

Data Structures and Algorithms

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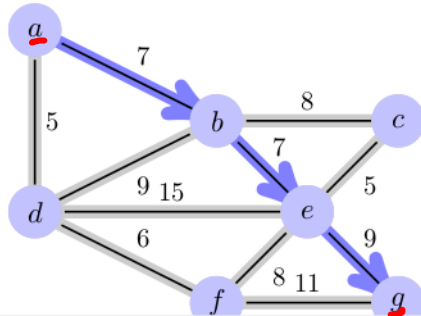
Session: Shortest Path Algorithm
(Dijkstra's Algorithm)

Finding Shortest Paths in Graphs

1. Shortest Path in Weighted Graphs
2. Shortest Path Properties in Weighted Graphs
3. Dijkstra's algorithm
4. Edge Relaxaton

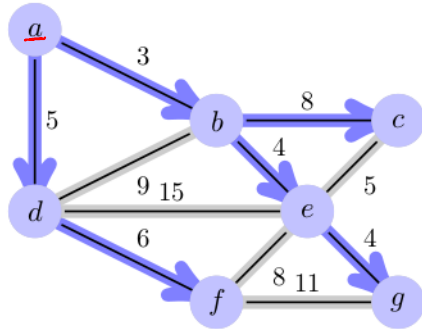
Shortest Path in Weighted Graphs

1. Given two vertices a and g in the weighted graph below, find a path of minimum total weight between them.
2. Length of path = sum of weight of constituent edges
3. Applications: Routing of vehicles, flights, internet packets



Shortest Path Properties in Weighted Graphs

1. **Optimal Substructure:** A subpath of a shortest path is also a shortest path
2. **Tree of shortest paths** exists¹ from a start vertex s to every other vertex



¹ Illustrated below is the tree of shortest paths from a

Dijkstra's Algorithm and Shortest Path Properties

1. **Optimal Substructure:** A subpath of a shortest path is also a shortest path
2. **Tree of shortest paths** exist from a start vertex s to every other vertex
3. Dijkstra's Algorithm combines the two:
 - ▶ Store for each v a label $d(v)$ = the distance of v from s
 - ▶ Successively computes $d(v)$, starting from the neighbors of s , assuming
 - ▶ graph is connected → H/w problem! To deal with graph containing
 - ▶ edges are undirected → H/w: deal with mixture of directed & undirected edges
 - ▶ edge weights are nonnegative

Dijkstra's Shortest Path Algorithm

Algorithm ComputeDijkstraSPs(G, s)

Output: Array $SP[.]$ with length of shortest path from s to v stored in $SP[v]$.

$P \leftarrow$ new Min-heap

for $v \in G.getVertices()$ do

if $v = s$ then

$SP[v] = 0$

else

$SP[v] = \infty$

end if

$P.insert(v, SP[v])$

end for

while $P.isNotEmpty()$ do

$u \leftarrow P.getMin()$

$P.removeMin()$ // Remove u

for $e \in G.incidentEdges(u)$ do

$w \leftarrow G.otherVertex(e, u)$

$r \leftarrow SP[u] + weight(e)$ // Relax e

if $r < SP[w]$ then

$SP[w] = r$

$P.update(w, r)$ // Update the value for key w

end if

end for

end while

P = interim state (distance) of every vertex from s that has been found to be shortest so far

u is the closest node in P from s



Loop invariant: For each $u \notin P$, shortest path to u is $SP[u]$

Figure: Computing Shortest Paths using Dijkstras Algorithm

Shortest Path (from d)

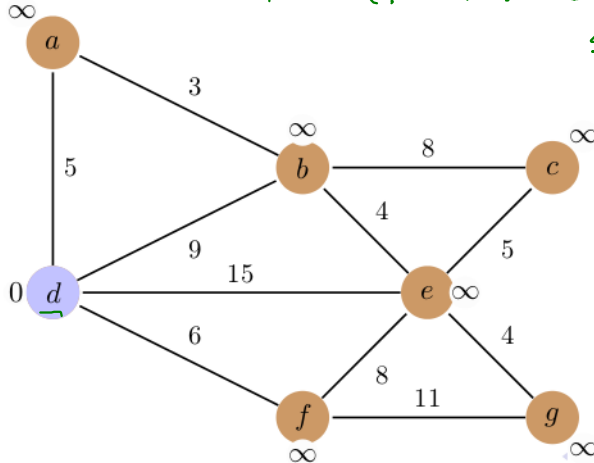
$$SP[d] = 0 \quad SP[a, b, \dots] = \infty$$

$$P.min() = d \quad \dots \quad SP[a] = 5$$

$$SP[b] = 9$$

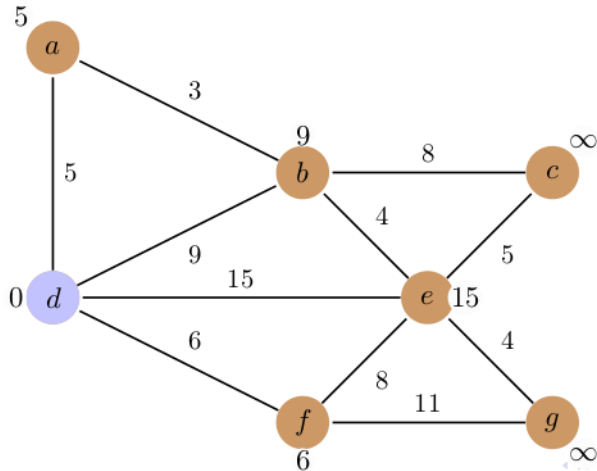
$$SP[f] = 6$$

$$SP[e] = 15$$

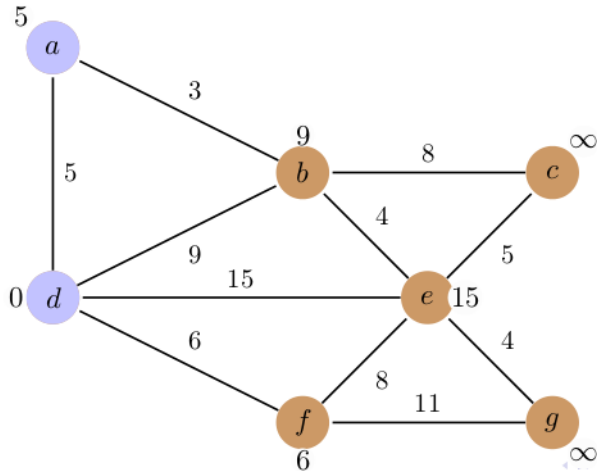


Next
 $P.min() = (a, 5)$

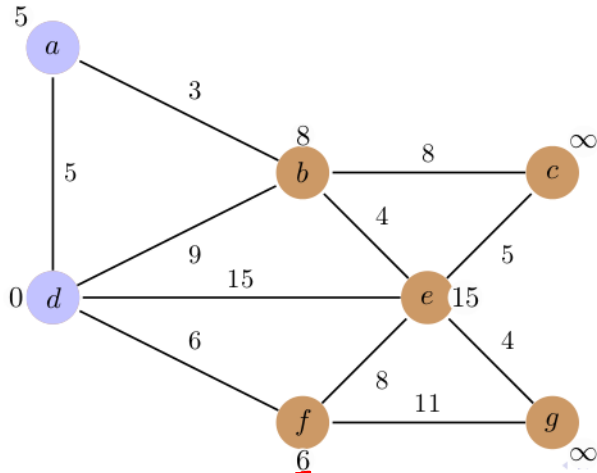
Shortest Path (from d) contd.



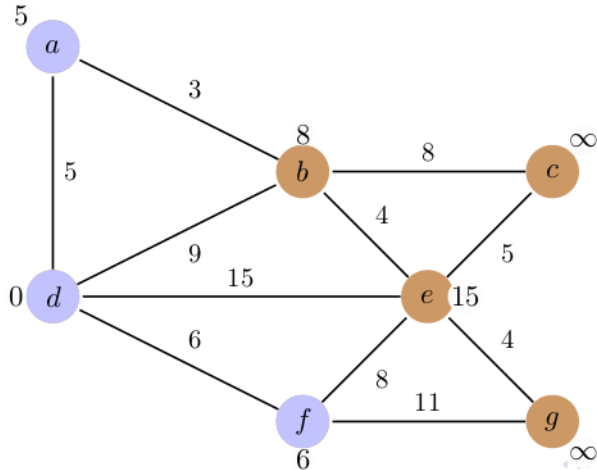
Shortest Path (from d) contd.



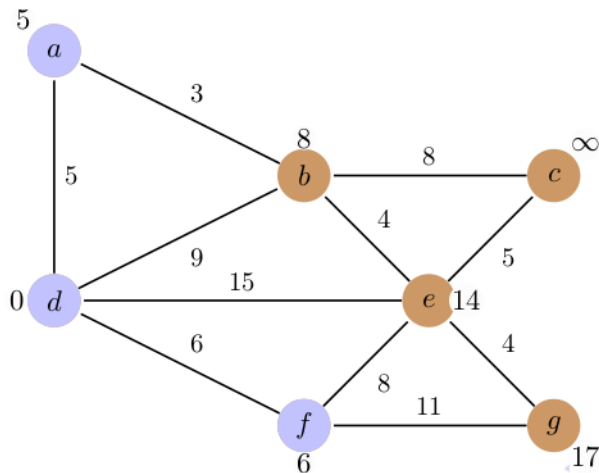
Shortest Path (from d) contd.



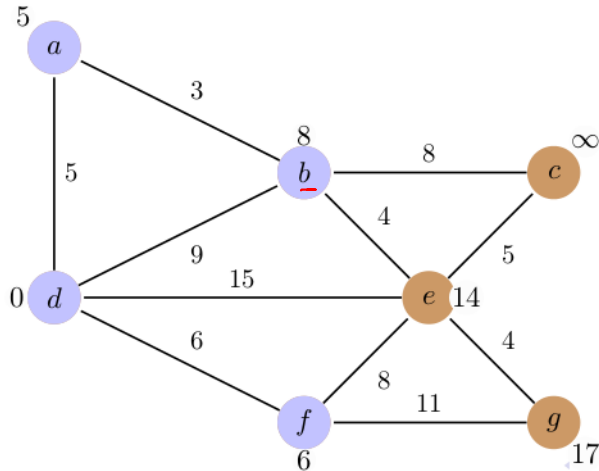
Shortest Path (from d) contd.



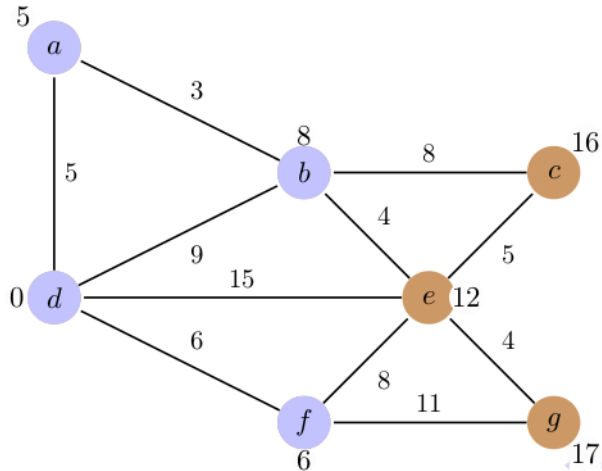
Shortest Path (from d) contd.



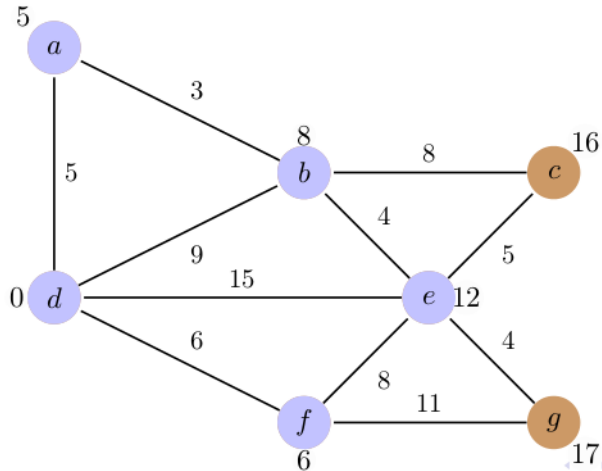
Shortest Path (from d) contd.



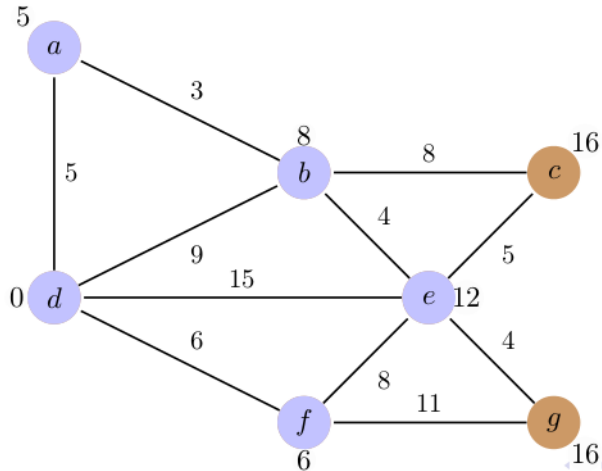
Shortest Path (from d) contd.



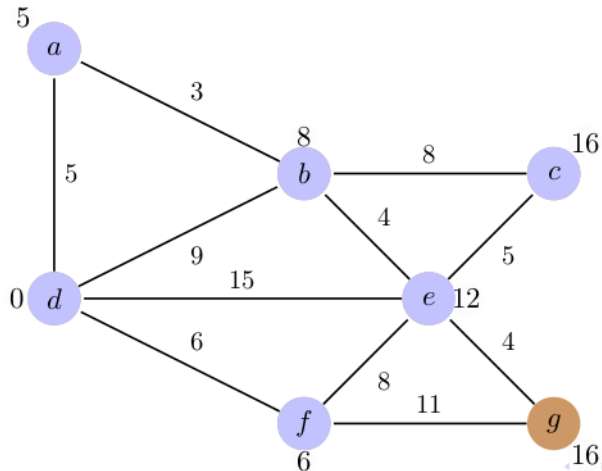
Shortest Path (from d) contd.



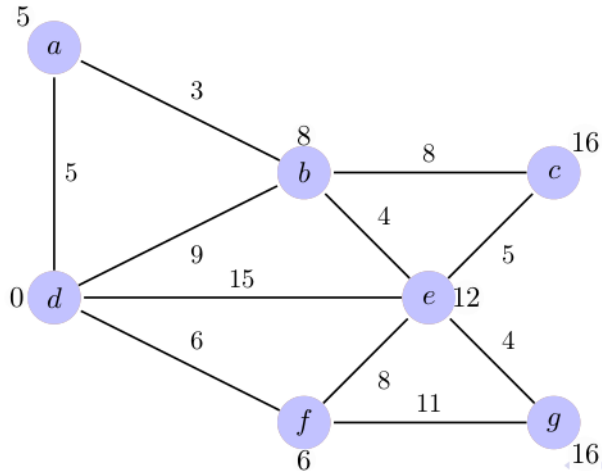
Shortest Path (from d) contd.



Shortest Path (from d) contd.



Shortest Path (from d) contd.



Analysis of Dijkstra's Algorithm

Algorithm ComputeDijkstraSPs(G, s)

Output: Array $SP[.]$ with length of shortest path from s to v stored in $SP[v]$.

$P \leftarrow$ new Min-heap

for $v \in G.getVertices()$ **do**

if $v = s$ **then**

$SP[v] = 0$

else

$SP[v] = \infty$

end if

$P.insert(v, SP[v])$

end for $\Rightarrow c_1 \times |V| \text{ times}$

while $P.isNotEmpty()$ **do**

$u \leftarrow P.getMin()$ $\Rightarrow c_2 \times \log |V| \text{ times}$

$P.removeMin()$ //Remove u

for $e \in G.incidentEdges(u)$ **do**

$w \leftarrow G.otherVertex(e, u)$

$r \leftarrow SP[u] + weight(e)$ //Relax e

if $r < SP[w]$ **then**

$SP[w] = r$

$P.update(w, r)$ //Update the value for key $w \Rightarrow c_3 \times \log |V| \text{ times}$

end if

end for $\Rightarrow c_4 \times deg(v) \text{ times}$

end while $\Rightarrow c_5 \times |V| \text{ times}$

$$T(n) = c_3 c_4 \log |V| \sum_{v \in V} deg(v) + c_2 c_5 |V| (\log |V|) + c_1 |V| = O((|E| + |V|) \log |V|)$$

Thank you