

Variance of Discrete Random Variables; Continuous Random Variables

Class 5, 18.05

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1 Learning Goals

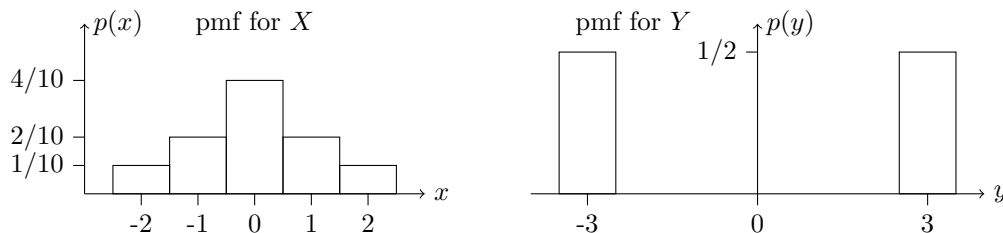
1. Be able to compute the variance and standard deviation of a random variable.
2. Understand that standard deviation is a measure of scale or spread.
3. Be able to compute variance using the properties of scaling and linearity.
4. Know the definition of a continuous random variable.
5. Know the definition of the probability density function (pdf) and cumulative distribution function (cdf).
6. Be able to explain why we use probability density for continuous random variables.

2 Spread

The expected value (mean) of a random variable is a measure of location. If you had to summarize a random variable with a single number, the mean would be a good choice. Still, the mean leaves out a good deal of information. For example, the random variables X and Y below both have mean 0, but their probability mass is spread out about the mean quite differently.

values X	-2	-1	0	1	2	values Y	-3	3
pmf $p(x)$	1/10	2/10	4/10	2/10	1/10	pmf $p(y)$	1/2	1/2

It's probably a little easier to see the different spreads in plots of the probability mass functions. We use bars instead of dots to give a better sense of the mass.



pmf's for two different distributions both with mean 0

In the next section, we will learn how to quantify this spread.

3 Variance and standard deviation

Taking the mean as the center of a random variable's probability distribution, the **variance** is a measure of how much the probability mass is **spread** out around this center. We'll start with the formal definition of variance and then unpack its meaning.

Definition: If X is a random variable with mean $E(X) = \mu$, then the **variance** of X is defined by

$$\text{Var}(X) = E((X - \mu)^2).$$

The **standard deviation** σ of X is defined by

$$\sigma = \sqrt{\text{Var}(X)}.$$

If the relevant random variable is clear from context, then the variance and standard deviation are often denoted by σ^2 and σ ('sigma'), just as the mean is μ ('mu').

What does this mean? First, let's rewrite the definition explicitly as a sum. If X takes values x_1, x_2, \dots, x_n with probability mass function $p(x_i)$ then

$$\text{Var}(X) = E((X - \mu)^2) = \sum_{i=1}^n p(x_i)(x_i - \mu)^2.$$

In words, the formula for $\text{Var}(X)$ says to take a weighted average of the squared distance to the mean. By squaring, we make sure we are averaging only non-negative values, so that the spread to the right of the mean won't cancel that to the left. By using expectation, we are weighting high probability values more than low probability values. (See Example 2 below.)

Note on units:

1. σ has the same units as X .
2. $\text{Var}(X)$ has the same units as the square of X . So if X is in meters, then $\text{Var}(X)$ is in meters squared.

Because σ and X have the same units, the standard deviation is a natural measure of spread.

Let's work some examples to make the notion of variance clear.

Example 1. Compute the mean, variance and standard deviation of the random variable X with the following table of values and probabilities.

value x	1	3	5
pmf $p(x)$	1/4	1/4	1/2

answer: First we compute $E(X) = 7/2$. Then we extend the table to include $(X - 7/2)^2$.

value x	1	3	5
$p(x)$	1/4	1/4	1/2
$(x - 7/2)^2$	25/4	1/4	9/4

Now the computation of the variance is similar to that of expectation:

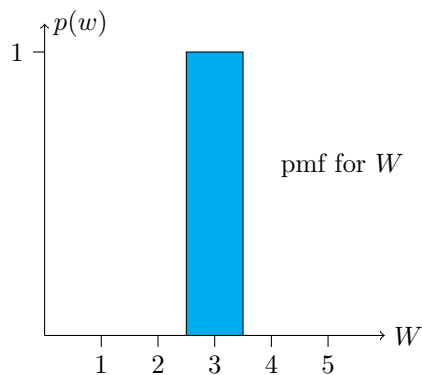
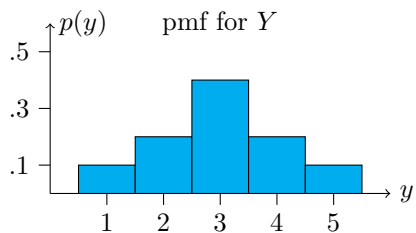
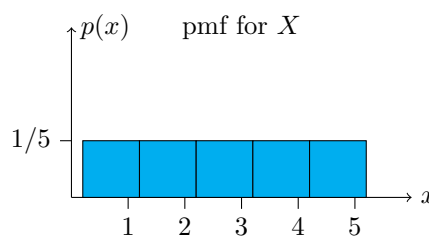
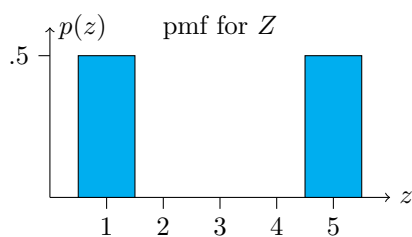
$$\text{Var}(X) = \frac{25}{4} \cdot \frac{1}{4} + \frac{1}{4} \cdot \frac{1}{4} + \frac{9}{4} \cdot \frac{1}{2} = \frac{11}{4}.$$

Taking the square root we have the standard deviation $\sigma = \sqrt{11/4}$.

Example 2. For each random variable X , Y , Z , and W plot the pmf and compute the mean and variance.

(i)	value x	1	2	3	4	5
	pmf $p(x)$	1/5	1/5	1/5	1/5	1/5
(ii)	value y	1	2	3	4	5
	pmf $p(y)$	1/10	2/10	4/10	2/10	1/10
(iii)	value z	1	2	3	4	5
	pmf $p(z)$	5/10	0	0	0	5/10
(iv)	value w	1	2	3	4	5
	pmf $p(w)$	0	0	1	0	0

answer: Each random variable has the same mean 3, but the probability is spread out differently. In the plots below, we order the pmf's from largest to smallest variance: Z , X , Y , W .



Next we'll verify our visual intuition by computing the variance of each of the variables. All of them have mean $\mu = 3$. Since the variance is defined as an expected value, we can compute it using the tables.

(i)	value x	1	2	3	4	5
	pmf $p(x)$	1/5	1/5	1/5	1/5	1/5
	$(X - \mu)^2$	4	1	0	1	4

$$\text{Var}(X) = E((X - \mu)^2) = \frac{4}{5} + \frac{1}{5} + \frac{0}{5} + \frac{1}{5} + \frac{4}{5} = \boxed{2}.$$

(ii)	value y	1	2	3	4	5
	$p(y)$	1/10	2/10	4/10	2/10	1/10
	$(Y - \mu)^2$	4	1	0	1	4

$$\text{Var}(Y) = E((Y - \mu)^2) = \frac{4}{10} + \frac{2}{10} + \frac{0}{10} + \frac{2}{10} + \frac{4}{10} = \boxed{1.2}.$$

(iii)	value z	1	2	3	4	5
	pmf $p(z)$	5/10	0	0	0	5/10
	$(Z - \mu)^2$	4	1	0	1	4

$$\text{Var}(Z) = E((Z - \mu)^2) = \frac{20}{10} + \frac{20}{10} = \boxed{4}.$$

(iv)	value w	1	2	3	4	5
	pmf $p(w)$	0	0	1	0	0
	$(W - \mu)^2$	4	1	0	1	4

$$\text{Var}(W) = \boxed{0}. \text{ Note that } W \text{ doesn't vary, so it has variance 0!}$$

3.1 The variance of a Bernoulli(p) random variable.

Bernoulli random variables are fundamental, so we should know their variance.

If $X \sim \text{Bernoulli}(p)$ then

$$\text{Var}(X) = p(1 - p).$$

Proof: We know that $E(X) = p$. We compute $\text{Var}(X)$ using a table.

values X	0	1
pmf $p(x)$	$1 - p$	p
$(X - \mu)^2$	$(0 - p)^2$	$(1 - p)^2$

$$\text{Var}(X) = (1 - p)p^2 + p(1 - p)^2 = (1 - p)p(1 - p + p) = \boxed{(1 - p)p}.$$

As with all things Bernoulli, you should remember this formula.

Think: For what value of p does Bernoulli(p) have the highest variance? Try to answer this by plotting the PMF for various p .

3.2 A word about independence

So far we have been using the notion of independent random variable without ever carefully defining it. For example, a binomial distribution is the sum of **independent** Bernoulli trials. This may (should?) have bothered you. Of course, we have an intuitive sense of what independence means for experimental trials. We also have the probabilistic sense that random variables X and Y are independent if knowing the value of X gives you no information about the value of Y .

In a few classes we will work with continuous random variables and joint probability functions. After that we will be ready for a full definition of independence. For now we can use the following definition, which is exactly what you expect and is valid for discrete random variables.

Definition: The discrete random variables X and Y are independent if

$$P(X = a, Y = b) = P(X = a)P(Y = b)$$

for any values a, b . That is, the probabilities multiply.

3.3 Properties of variance

The three most useful properties for computing variance are:

1. If X and Y are independent then $\text{Var}(X + Y) = \text{Var}(X) + \text{Var}(Y)$.
2. For constants a and b , $\text{Var}(aX + b) = a^2 \text{Var}(X)$.
3. $\text{Var}(X) = E(X^2) - E(X)^2$.

For Property 1, note carefully the requirement that X and Y are independent. We will return to the proof of Property 1 in a later class.

Property 3 gives a formula for $\text{Var}(X)$ that is often easier to use in hand calculations. The computer is happy to use the definition! We'll prove Properties 2 and 3 after some examples.

Example 3. Suppose X and Y are independent and $\text{Var}(X) = 3$ and $\text{Var}(Y) = 5$. Find:

- (i) $\text{Var}(X + Y)$, (ii) $\text{Var}(3X + 4)$, (iii) $\text{Var}(X + X)$, (iv) $\text{Var}(X + 3Y)$.

answer: To compute these variances we make use of Properties 1 and 2.

- (i) Since X and Y are independent, $\text{Var}(X + Y) = \text{Var}(X) + \text{Var}(Y) = 8$.

- (ii) Using Property 2, $\text{Var}(3X + 4) = 9 \cdot \text{Var}(X) = 27$.

(iii) Don't be fooled! Property 1 fails since X is certainly not independent of itself. We can use Property 2: $\text{Var}(X + X) = \text{Var}(2X) = 4 \cdot \text{Var}(X) = 12$. (Note: if we mistakenly used Property 1, we would the wrong answer of 6.)

- (iv) We use both Properties 1 and 2.

$$\text{Var}(X + 3Y) = \text{Var}(X) + \text{Var}(3Y) = 3 + 9 \cdot 5 = 48.$$

Example 4. Use Property 3 to compute the variance of $X \sim \text{Bernoulli}(p)$.

answer: From the table

X	0	1
$p(x)$	$1 - p$	p
X^2	0	1

we have $E(X^2) = p$. So Property 3 gives

$$\text{Var}(X) = E(X^2) - E(X)^2 = p - p^2 = p(1 - p).$$

This agrees with our earlier calculation.

Example 5. Redo Example 1 using Property 3.

answer: From the table

X	1	3	5
$p(x)$	$1/4$	$1/4$	$1/2$
X^2	1	9	25

we have $E(X) = 7/2$ and

$$E(X^2) = 1^2 \cdot \frac{1}{4} + 3^2 \cdot \frac{1}{4} + 5^2 \cdot \frac{1}{2} = \frac{60}{4} = 15.$$

So $\text{Var}(X) = 15 - (7/2)^2 = 11/4$ –as before in Example 1.

3.4 Variance of binomial(n, p)

Suppose $X \sim \text{binomial}(n, p)$. Since X is the sum of *independent* Bernoulli(p) variables and each Bernoulli variable has variance $p(1 - p)$ we have

$$X \sim \text{binomial}(n, p) \Rightarrow \text{Var}(X) = np(1 - p).$$

3.5 Proof of properties 2 and 3

Proof of Property 2: This follows from the properties of $E(X)$ and some algebra.

Let $\mu = E(X)$. Then $E(aX + b) = a\mu + b$ and

$$\text{Var}(aX + b) = E((aX + b - (a\mu + b))^2) = E((aX - a\mu)^2) = E(a^2(X - \mu)^2) = a^2 E((X - \mu)^2) = a^2 \text{Var}(X).$$

Proof of Property 3: We use the properties of $E(X)$ and a bit of algebra. Remember that μ is a constant and that $E(X) = \mu$.

$$\begin{aligned} E((X - \mu)^2) &= E(X^2 - 2\mu X + \mu^2) \\ &= E(X^2) - 2\mu E(X) + \mu^2 \\ &= E(X^2) - 2\mu^2 + \mu^2 \\ &= E(X^2) - \mu^2 \\ &= E(X^2) - E(X)^2. \quad \text{QED} \end{aligned}$$

4 Tables of Distributions and Properties

Distribution	range X	pmf $p(x)$	mean $E(X)$	variance $\text{Var}(X)$
Bernoulli(p)	0, 1	$p(0) = 1 - p, \quad p(1) = p$	p	$p(1 - p)$
Binomial(n, p)	0, 1, ..., n	$p(k) = \binom{n}{k} p^k (1 - p)^{n-k}$	np	$np(1 - p)$
Uniform(n)	1, 2, ..., n	$p(k) = \frac{1}{n}$	$\frac{n+1}{2}$	$\frac{n^2 - 1}{12}$
Geometric(p)	0, 1, 2, ...	$p(k) = p(1 - p)^k$	$\frac{1-p}{p}$	$\frac{1-p}{p^2}$

Let X be a discrete random variable with range x_1, x_2, \dots and pmf $p(x_j)$.

Expected Value:	Variance:
Synonyms: mean, average	
Notation: $E(X), \mu$	$\text{Var}(X), \sigma^2$
Definition: $E(X) = \sum_j p(x_j)x_j$	$E((X - \mu)^2) = \sum_j p(x_j)(x_j - \mu)^2$
Scale and shift: $E(aX + b) = aE(X) + b$	$\text{Var}(aX + b) = a^2\text{Var}(X)$
Linearity: (for any X, Y) $E(X + Y) = E(X) + E(Y)$	(for X, Y independent) $\text{Var}(X + Y) = \text{Var}(X) + \text{Var}(Y)$
Functions of X : $E(h(X)) = \sum p(x_j)h(x_j)$	
Alternative formula:	$\text{Var}(X) = E(X^2) - E(X)^2 = E(X^2) - \mu^2$

5 Introduction

We now turn to [continuous random variables](#). All random variables assign a number to each outcome in a sample space. Whereas discrete random variables take on a discrete set of possible values, continuous random variables have a continuous set of values.

Computationally, to go from discrete to continuous we simply replace sums by integrals. It will help you to keep in mind that (informally) an integral is just a continuous sum.

Example 6. Since time is continuous, the amount of time Jon is early (or late) for class is a continuous random variable. Let's go over this example in some detail.

Suppose you measure how early Jon arrives to class each day (in units of minutes). That is, the outcome of one trial in our experiment is a time in minutes. We'll assume there are random fluctuations in the exact time he shows up. Since in principle Jon could arrive, say, 3.43 minutes early, or 2.7 minutes late (corresponding to the outcome -2.7), or at any other time, the sample space consists of all real numbers. So the random variable which gives the outcome itself has a [continuous range](#) of possible values.

It is too cumbersome to keep writing 'the random variable', so in future examples we might write: Let T = "time in minutes that Jon is early for class on any given day."

6 Calculus Warmup

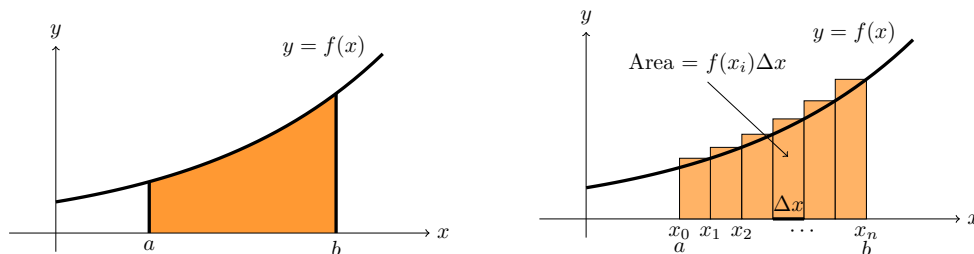
While we will assume you can compute the most familiar forms of derivatives and integrals by hand, we do not expect you to be calculus whizzes. For tricky expressions, we'll let the computer do most of the calculating. Conceptually, you should be comfortable with two views of a definite integral.

1. $\int_a^b f(x) dx$ = area under the curve $y = f(x)$.
2. $\int_a^b f(x) dx$ = 'sum of $f(x) dx$ '.

The connection between the two is:

$$\text{area} \approx \text{sum of rectangle areas} = f(x_1)\Delta x + f(x_2)\Delta x + \dots + f(x_n)\Delta x = \sum_{i=1}^n f(x_i)\Delta x.$$

As the width Δx of the intervals gets smaller the approximation becomes better.



Area is approximately the sum of rectangles

Note: In calculus you learned to compute integrals by finding antiderivatives. This is important for calculations, but don't confuse this method for the reason we use integrals. Our interest in integrals comes primarily from its interpretation as a 'sum' and to a much lesser extent its interpretation as area.

7 Continuous Random Variables and Probability Density Functions

A continuous random variable takes a **range of values**, which may be finite or infinite in extent. Here are a few examples of ranges: $[0, 1]$, $[0, \infty)$, $(-\infty, \infty)$, $[a, b]$.

Definition: A random variable X is **continuous** if there is a function $f(x)$ such that for any $c \leq d$ we have

$$P(c \leq X \leq d) = \int_c^d f(x) dx. \quad (1)$$

The function $f(x)$ is called the **probability density function (pdf)**.

The pdf always satisfies the following properties:

1. $f(x) \geq 0$ (f is nonnegative).
2. $\int_{-\infty}^{\infty} f(x) dx = 1$ (This is equivalent to: $P(-\infty < X < \infty) = 1$).

The probability density function $f(x)$ of a continuous random variable is the analogue of the probability mass function $p(x)$ of a discrete random variable. Here are two important differences:

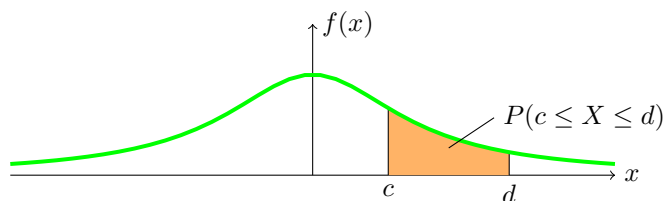
1. Unlike $p(x)$, the pdf $f(x)$ is *not* a probability. You have to integrate it to get probability. (See section 7.2 below.)
2. Since $f(x)$ is not a probability, there is no restriction that $f(x)$ be less than or equal to 1.

Note: In Property 2, we integrated over $(-\infty, \infty)$ since we did not know the range of values taken by X . Formally, this makes sense because we just define $f(x)$ to be 0 outside of the range of X . In practice, we would integrate between bounds given by the range of X .

7.1 Graphical View of Probability

If you graph the probability density function of a continuous random variable X then

$$P(c \leq X \leq d) = \text{area under the graph between } c \text{ and } d.$$



Think: What is the total area under the pdf $f(x)$?

7.2 The terms ‘probability mass’ and ‘probability density’

Why do we use the terms mass and density to describe the pmf and pdf? What is the difference between the two? The simple answer is that these terms are completely analogous to the mass and density you saw in physics and calculus. We’ll review this first for the probability mass function and then discuss the probability density function.

Mass as a sum:

If masses m_1, m_2, m_3 , and m_4 are set in a row at positions x_1, x_2, x_3 , and x_4 , then the total mass is $m_1 + m_2 + m_3 + m_4$.

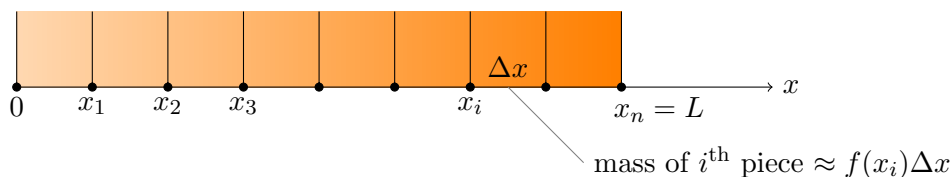


We can define a ‘mass function’ $p(x)$ with $p(x_j) = m_j$ for $j = 1, 2, 3, 4$, and $p(x) = 0$ otherwise. In this notation the total mass is $p(x_1) + p(x_2) + p(x_3) + p(x_4)$.

The **probability mass function** behaves in exactly the same way, except it has the dimension of probability instead of mass.

Mass as an integral of density:

Suppose you have a rod of length L meters with varying density $f(x)$ kg/m. (Note the units are mass/length.)



If the density varies continuously, we must find the total mass of the rod by integration:

$$\text{total mass} = \int_0^L f(x) dx.$$

This formula comes from dividing the rod into small pieces and 'summing' up the mass of each piece. That is:

$$\text{total mass} \approx \sum_{i=1}^n f(x_i) \Delta x$$

In the limit as Δx goes to zero the sum becomes the integral.

The **probability density function** behaves exactly the same way, except it has units of probability/(unit x) instead of kg/m. Indeed, equation (1) is exactly analogous to the above integral for total mass.

While we're on a physics kick, note that for both discrete and continuous random variables, the expected value is simply the **center of mass** or balance point.

Example 7. Suppose X has pdf $f(x) = 3$ on $[0, 1/3]$ (this means $f(x) = 0$ outside of $[0, 1/3]$). Graph the pdf and compute $P(.1 \leq X \leq .2)$ and $P(.1 \leq X \leq 1)$.

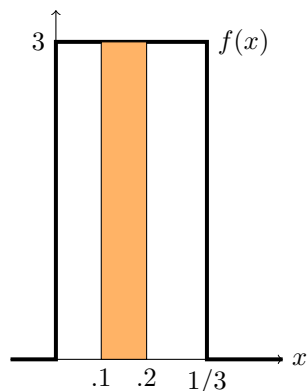
answer: $P(.1 \leq X \leq .2)$ is shown below at left. We can compute the integral:

$$P(.1 \leq X \leq .2) = \int_{.1}^{.2} f(x) dx = \int_{.1}^{.2} 3 dx = .3.$$

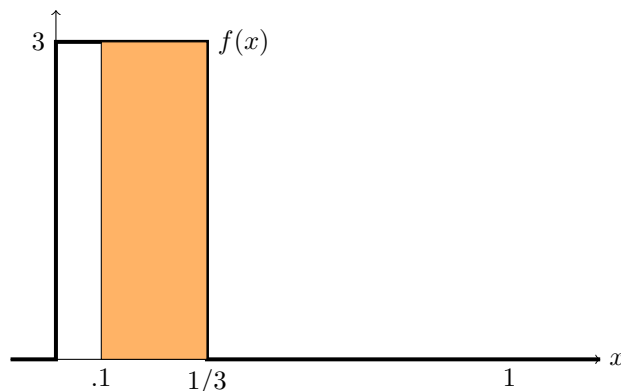
Or we can find the area geometrically:

$$\text{area of rectangle} = 3 \cdot .1 = .3.$$

$P(.1 \leq X \leq 1)$ is shown below at right. Since there is only area under $f(x)$ up to $1/3$, we have $P(.1 \leq X \leq 1) = 3 \cdot (1/3 - .1) = .7$.



$P(.1 \leq X \leq .2)$



$P(.1 \leq X \leq 1)$

Think: In the previous example $f(x)$ takes values greater than 1. Why does this not violate the rule that probabilities are always between 0 and 1?

Note on notation. We can define a random variable by giving its range and probability density function. For example we might say, let X be a random variable with range $[0, 1]$

and pdf $f(x) = x/2$. Implicitly, this means that X has no probability density outside of the given range. If we wanted to be absolutely rigorous, we would say explicitly that $f(x) = 0$ outside of $[0,1]$, but in practice this won't be necessary.

Example 8. Let X be a random variable with range $[0,1]$ and pdf $f(x) = Cx^2$. What is the value of C ?

answer: Since the total probability must be 1, we have

$$\int_0^1 f(x) dx = 1 \quad \Leftrightarrow \quad \int_0^1 Cx^2 dx = 1.$$

By evaluating the integral, the equation at right becomes

$$C/3 = 1 \Rightarrow \boxed{C = 3}.$$

Note: We say the constant C above is needed to **normalize** the density so that the total probability is 1.

Example 9. Let X be the random variable in the Example 8. Find $P(X \leq 1/2)$.

answer: $P(X \leq 1/2) = \int_0^{1/2} 3x^2 dx = x^3 \Big|_0^{1/2} = \boxed{\frac{1}{8}}.$

Think: For this X (or any continuous random variable):

- What is $P(a \leq X \leq a)$?
- What is $P(X = 0)$?
- Does $P(X = a) = 0$ mean that X can never equal a ?

In words the above questions get at the fact that the probability that a random person's height is exactly 5'9" (to infinite precision, i.e. no rounding!) is 0. Yet it is still possible that someone's height is exactly 5'9". So the answers to the thinking questions are 0, 0, and No.

p=0 doesn't mean impossible

7.3 Cumulative Distribution Function

The **cumulative distribution function** (**cdf**) of a continuous random variable X is defined in exactly the same way as the cdf of a discrete random variable.

$$F(b) = P(X \leq b).$$

Note well that the definition is about probability. When using the cdf you should first think of it as a probability. Then when you go **to calculate** it you can use

$$F(b) = P(X \leq b) = \int_{-\infty}^b f(x) dx, \quad \text{where } f(x) \text{ is the pdf of } X.$$

Notes:

1. For discrete random variables, we defined the cumulative distribution function but did

not have much occasion to use it. The cdf plays a far more prominent role for continuous random variables.

2. As before, we started the integral at $-\infty$ because we did not know the precise range of X . Formally, this still makes sense since $f(x) = 0$ outside the range of X . In practice, we'll know the range and start the integral at the start of the range.

3. In practice we often say ' X has distribution $F(x)$ ' rather than ' X has cumulative distribution function $F(x)$.'

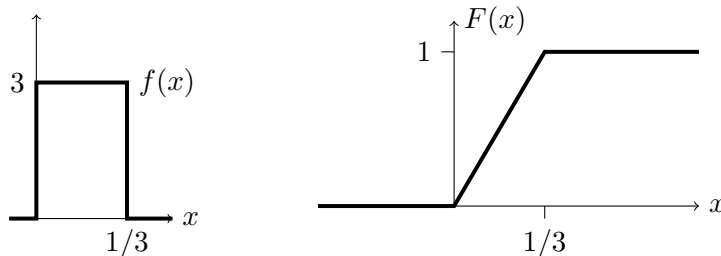
Example 10. Find the cumulative distribution function for the density in Example 7.

answer: For a in $[0, 1/3]$ we have $F(a) = \int_0^a f(x) dx = \int_0^a 3 dx = 3a$.

Since $f(x)$ is 0 outside of $[0, 1/3]$ we know $F(a) = P(X \leq a) = 0$ for $a < 0$ and $F(a) = 1$ for $a > 1/3$. Putting this all together we have

$$F(a) = \begin{cases} 0 & \text{if } a < 0 \\ 3a & \text{if } 0 \leq a \leq 1/3 \\ 1 & \text{if } 1/3 < a. \end{cases}$$

Here are the graphs of $f(x)$ and $F(x)$.



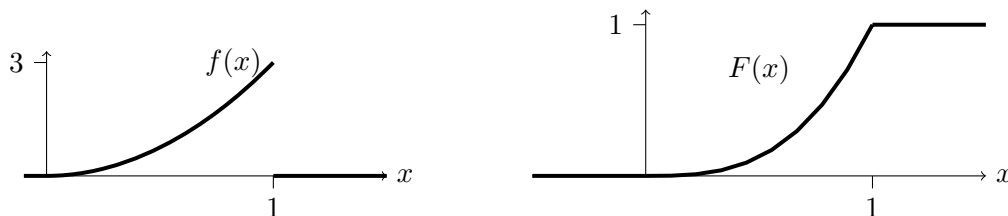
Note the different scales on the vertical axes. Remember that the vertical axis for the pdf represents probability density and that of the cdf represents probability.

Example 11. Find the cdf for the pdf in Example 8, $f(x) = 3x^2$ on $[0, 1]$. Suppose X is a random variable with this distribution. Find $P(X < 1/2)$.

answer: $f(x) = 3x^2$ on $[0, 1] \Rightarrow F(a) = \int_0^a 3x^2 dx = a^3$ on $[0, 1]$. Therefore,

$$F(a) = \begin{cases} 0 & \text{if } a < 0 \\ a^3 & \text{if } 0 \leq a \leq 1 \\ 1 & \text{if } 1 < a \end{cases}$$

Thus, $P(X < 1/2) = F(1/2) = 1/8$. Here are the graphs of $f(x)$ and $F(x)$:



7.4 Properties of cumulative distribution functions

Here is a summary of the most important properties of cumulative distribution functions (cdf)

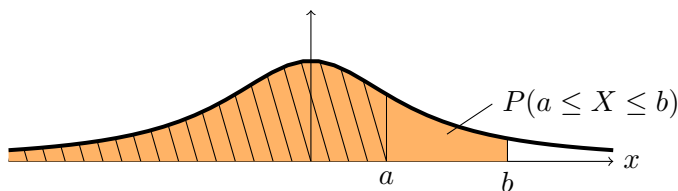
1. (Definition) $F(x) = P(X \leq x)$
2. $0 \leq F(x) \leq 1$
3. $F(x)$ is non-decreasing, i.e. if $a \leq b$ then $F(a) \leq F(b)$.
4. $\lim_{x \rightarrow \infty} F(x) = 1$ and $\lim_{x \rightarrow -\infty} F(x) = 0$
5. $P(a \leq X \leq b) = F(b) - F(a)$
6. $F'(x) = f(x)$.

Properties 2, 3, 4 are identical to those for discrete distributions. The graphs in the previous examples illustrate them.

Property 5 can be seen algebraically:

$$\begin{aligned} \int_{-\infty}^b f(x) dx &= \int_{-\infty}^a f(x) dx + \int_a^b f(x) dx \\ \Leftrightarrow \int_a^b f(x) dx &= \int_{-\infty}^b f(x) dx - \int_{-\infty}^a f(x) dx \\ \Leftrightarrow P(a \leq X \leq b) &= F(b) - F(a). \end{aligned}$$

Property 5 can also be seen geometrically. The orange region below represents $F(b)$ and the striped region represents $F(a)$. Their difference is $P(a \leq X \leq b)$.



Property 6 is the fundamental theorem of calculus.

7.5 Probability density as a dartboard

We find it helpful to think of sampling values from a continuous random variable as throwing darts at a funny dartboard. Consider the region underneath the graph of a pdf as a dartboard. Divide the board into small equal size squares and suppose that when you throw a dart you are equally likely to land in any of the squares. The probability the dart lands in a given region is the fraction of the total area under the curve taken up by the region. Since the total area equals 1, this fraction is just the area of the region. If X represents the x -coordinate of the dart, then the probability that the dart lands with x -coordinate between a and b is just

$$P(a \leq X \leq b) = \text{area under } f(x) \text{ between } a \text{ and } b = \int_a^b f(x) dx.$$