



## Carroll Vance

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LinkedIn, Github & Portfolio: <https://csvance.github.io>

### Profile

I have professional experience working with embedded and real-time systems for a variety of applications including robotics, automation, networking, and storage. I am also passionate about machine learning, especially when it comes to inference optimization for embedded systems. After working in the oil & gas services industry for seven years I am currently pursuing higher education to develop a rigorous understanding of the theory and mathematics required for engineering related applications of computer science.

### Skills

Developed applications for microcontrollers and microprocessors such as ARM Cortex M0, M3, M4, A7, A15, A57, PIC, dsPIC, and more. Proficient in C and Python. Experience with embedded Linux ranging from board bringup to custom distribution creation. Trained, optimized, and deployed convolutional neural networks for object detection and classification on embedded systems.

### Education - CGPA 4.0

#### **UNIVERSITY OF HOUSTON – 2018-CURRENT**

Expected Graduation: Fall 2020 with B.S. in Computer Science & Minor in Mathematics

#### **HOUSTON COMMUNITY COLLEGE – 2016-2018**

Studied Computer Science

### Experience

#### **EMBEDDED SYSTEMS CONSULTANT, SELF-EMPLOYED; HOUSTON, TEXAS – 2019-CURRENT**

Providing IC selection for concept validation as well as expertise in embedded software

#### **SOFTWARE ENGINEER, WILDCAT DEVELOPMENT; SPRING, TEXAS – 2009-2016**

Designed, implemented, and tested embedded software for companies such as Baker Hughes, Hewlett Packard Enterprise, and National Oilwell Varco

#### **SYSTEMS VALIDATION TESTER, WAILUA TECHNOLOGY; HOUSTON, TEXAS – 2008-2009**

Executed test plan for flash memory technology created by Spansion and Virident Systems

### Extracurricular

#### **CULLEN COLLEGE OF ENGINEERING IEEE UH MAKERS – WORKSHOP COORDINATOR, 2018-CURRENT**

Coordinating educational workshops involving embedded systems, computer vision and machine learning. Working on group projects such as indoor autonomous drones and robotic arms. Community outreach events

## Projects

### **ARM A7 BOARD BRINGUP**

Conducted board bringup on a custom PCB based on NXP IMX6 reference design running embedded Linux. Changes to device tree to support custom hardware and sensors. Debugging many hardware and software issues. This resulted in patches to the kernel in the case of PCIe, cutting a trace that was grounding a clock signal for ethernet, and many other issues being addressed. Used kernel debugger along with logic analyzer to diagnose issues

### **JETSON TENSORRT**

Created a series of ROS nodes for executing optimized deep learning object detection and classification inferences on nVidia's Jetson platform. 100% GPU preprocessing pipeline for minimal inference latency. Utilized ImageNet and OpenImages datasets to train object detector. Currently being used to develop a system to keep squirrels from taking fresh produce from gardens using blasts of water

Github: [https://github.com/csvance/jetson\\_tensorrt](https://github.com/csvance/jetson_tensorrt)

### **SD CARD BACKUP DEVICE**

Created firmware for a small form factor file backup device with high speed USB and wireless capability. Implemented high speed file transfer between SD, eMMC, and USB 3.0 Mass Storage Mode. Ported Qualcomm QCA4002 driver and TCP/IP stack to ThreadX RTOS and implemented wireless file transfer. Due to memory constraints, a finite state machine design was implemented to exercise tight control over memory allocations and power consumption.

### **AIR POLLUTION TIME SERIES PREDICTION**

Exploratory data analysis with 50GB dataset of pollution data in Texas ranging from 2000 to 2017. Created preprocessing pipeline using OpenMPI / multiprocessing to handle missing data, windowing, and sequence creation on an HPC cluster. Testing various machine learning models including LSTM and Random Forests as well as different problem structures such as multiple regression and classification. Current focus is addressing nulls in data by utilizing spacial information to improve interpolation