

Mr.Chen Shangyu

Second year Ph.D Student
Nanyang Technological University
Computational Intelligence Lab, 639798, Singapore
Phone: 65-81165720
email: schen025@e.ntu.edu.sg
homepage: csyhhu.github.io
github: <https://github.com/csyhhu>

Research Area

Model Compression, Categorical Data Analysis

Education

2016 BS in Computer Science, Sun Yat-Sen University, Guangzhou, China
2020 (Expected) PhD in Computer Science, Nanyang Technological University, Singapore
Under supervision of [Nanyang Prof. Sinno Jialin Pan](#)

Publications

2017 Xin Dong, **Shangyu Chen**, Sinno Jialin Pan “Learning to Prune Deep Neural Networks via Layer-wise Optimal Brain Surgeon”, To appear in Annual Conference on Neural Information Processing Systems 2017 (NIPS-17). Long Beach, USA. Dec. 4-9, 2017. (Full paper)
2016 Eun-Young Kang, Jianda Chen, Liu Ke, and **Shangyu Chen**, “Statistical Analysis of Energy-aware Real-Time Automotive Systems in EAST-ADL/Stateflow”, *11th IEEE Conference on Industrial Electronics and Applications 2016*, IEEE Computer Society

Research Projections

2017 **Layer-Wise Model Compression by Prunning Unimportant Parameters**

- Formulated parameters prunning into an optimization problem by utilizing deep neural network layer output’s change before and after prunning.
- Proved theoretical bound for final error.
- This work was accepted by Annual Conference on Neural Information Processing Systems (NIPS) 2017. [[paper](#)] [[code](#)]

2016 **System Verification and Validation Using UPPAAL, Stateflow and EAST-ADL**

- Transferred vehicle system verification models in Matlab/Stateflow, EAST-ADL into UPPAAL for formal verification.
- This work was accepted by 11th IEEE Conference on Industrial Electronics and Applications [[Technical Paper](#)] [[Full Paper](#)].

Applied Project

2015

Image Recommendation System

- Performed image recommendation based on images' *SIFT-saliency* and user browsing history.
- [Project Homepage](#)

2015

Lane Detection and Inverse Perspective Mapping Generation

- Designed and implemented an innovative algorithm to perform automatic *Inverse Perspective Mapping* of road, which traditionally required camera to be calibrated manually in advance.
- Performed lane detection based on inverse perspective mapping images.
- [Project Homepage](#)

2016

Final Year Project: **Vehicle Box for Advanced Driver Assistance Systems**

- Embedded *Lane Detection*, *Traffic Sign Detection*, *Pedestrian Detection* into hardware board (Jetson tk1) to provide development APIs.

Grants, honors & awards

2016

Three times of Outstanding Students Scholarship, Sun Yat-Sen University. (Top 10%)

Programming Languages

Python (TensorFlow, PyTorch), C++