# Multicore Performance #2 - Load Balancing -

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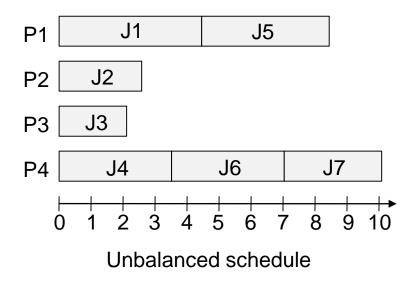
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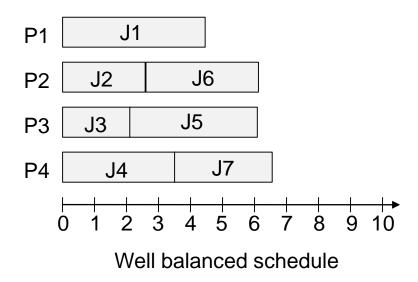
## **Outline**

- Concepts of Load Balancing
  - 2 Load Balancing Algorithms
- Overhead of Load Balancing

# **Goal of Load Balancing**

- > Distribute workload evenly across processors
  - To get optimal resource utilization, maximize throughput, and minimize response time





# Static Balancing vs. Dynamic Balancing

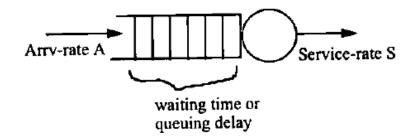
- > Static balancing (partitioned sched. w/o migration)
  - Processes are statically assigned to processors during program compilation or loading
  - Works well when there is not much variation in the workload
- > Dynamic balancing (partitioned sched. with migration)
  - Running processes are moved to remote processors
  - Works well when loads may vary significantly during runtime
  - But the cost of collecting and maintaining load information and process migration is high
- > Adaptive balancing
  - Special type of dynamic load balancing
  - The algorithm may change depending on the system state
  - e.g.) If the system load is very high, it may not even attempt to collect load information

## **Load Balancing Policies**

- > Transfer policy
  - Decides whether a processor is eligible for load balancing
  - Usually based on a threshold such as queue length
- > Selection policy
  - Decides which task should be moved
- > Location policy
  - Decides where to send or receive the task
  - Typical approaches are polling, guessing, or random
- > Information policy
  - Decide when (how often) trigger collection of system load information and where to collect them
  - On demand, periodic, or state change driven

# **Stability Condition**

- Without load balancing
  - If A < S, the system is stable</p>
  - Otherwise, it is unstable



- With load balancing
  - If A+LB < S, the system is stable</p>
    - LB is the overhead due to load balancing
  - Otherwise, it is unstable
  - If the algorithm leads to thrashing, the system is unstable
    - When a task arrives at a processor 1, it gets transferred to processor 2
    - The task may get transferred to another processor 3
    - It may keep getting transferred from processor to processor

## **Sender-Initiated Algorithms**

- Can be viewed as "work sharing"
- > Transfer policy
  - Use a threshold policy on the ready queue length |Q|
  - If a task arrives and makes |Q| > T, the processor becomes a sender
- Selection policy
  - Consider only newly arrived tasks
- Location policy
  - Different algorithms (described on the next slide)
- Information policy
  - Demand driven

## **Location Policies**

#### > Random LP

- Choose a remote processor randomly
- No overhead of collecting information
- Still, better than no load balancing

#### > Threshold LP

- Select remote processors randomly
- But check if |Q| < T</li>

### Shortest queue LP

- Select k processors at random
- Send to the processor with smallest |Q|
- More overhead than threshold LP, but marginal improvement

## **Receiver-Initiated Algorithms**

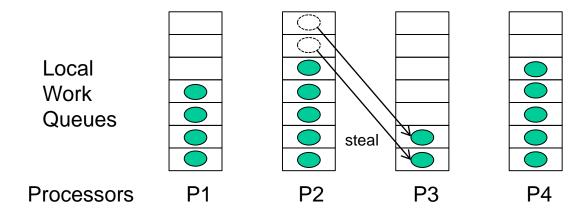
- > Can be viewed as "work stealing"
- > Transfer policy
  - Use a threshold policy on the ready queue length |Q|
  - If a task departs and makes |Q| < T, the processor becomes a receiver
- Selection policy
  - Consider only newly arrived tasks
- Location policy
  - Can choose randomly or based on the queue length |Q|
- Information policy
  - Demand driven

# **Symmetrically-Initiated Algorithms**

- > Combine the previous two algorithms
- > Transfer policy
  - Use a double threshold <Lower, Upper>
  - If |Q| > Upper, the processor becomes a sender
  - If |Q| < Lower, the processor becomes a receiver
- > Location policy
  - Sender-initiated: broadcasts a "too high" message, and waits for a reply from a receiver
  - Receiver-initiated: broadcasts a "too low" message, and waits for a reply from a sender
  - If no reply has been received within timeout, send a "system load is high/low" message and change the threshold

## **Work Stealing**

- ➤ Work stealing is known to be a simple but very effective approach to load balancing
  - Each processor maintains a local work queue
  - If a processor runs out of jobs, it steals from other processor



Work stealing is a receiver-initiated approach

## **Variations of Work Stealing**

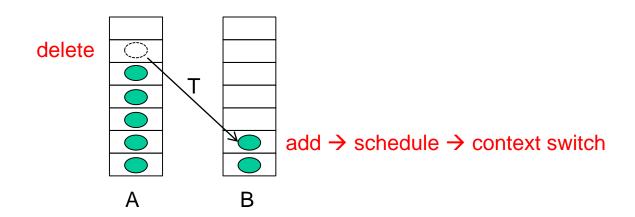
- > Threshold-based work stealing
  - When a processor becomes idle, it randomly chooses another processor and steals a job only if the victim's queue contains more than a threshold number of tasks
- Probabilistic work stealing
  - Whenever a processor accesses its local work queue, it performs a balancing operation with probability inversely proportional to the size of its work queue (with probability 1/m where m is the length of the work queue)

# Overhead of Load Balancing

- > Information collection
  - Can be done via either shared memory access or interprocessor communication
  - This causes minor overhead when compared to the task migration overhead
- > Task migration
  - Scheduling
  - Cold cache effect

# **Scheduling for Thread Migration**

- > To move thread T from core A to core B
  - W need to access and update the kernel's scheduling data structures
    - Deleting T from A's ready queue
    - Adding T to B's ready queue
  - The scheduler on B needs to perform scheduling
    - This would also involve context switching



## **Cold Cache Effect**

- > Thread migration requires transferring program states
  - Register state, TLB state, and branch predictor state
- > The largest overhead is caused by cache states
  - A primary mechanism is demand-fetching
    - Executing the thread on the new core causes demand misses
    - This fills caches slowly (cold cache effect)

