Multicore Performance #1 - CPU Scheduling -

Minsoo Ryu

Department of Computer Science and Engineering Hanyang University

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CPU Scheduling

- CPU scheduling is to decide when and which process to run among ready processes
- > Scheduling criteria
 - Performance objectives
 - Maximize CPU utilization or throughput
 - Minimize completion time, waiting time, or response time
 - Real-time constraints
 - Satisfy deadlines
 - Fairness
 - Provide CPU cycles proportional to weights

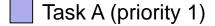
Classification of Scheduling Policies

- > Two paradigms
 - Priority-based scheduling
 - Proportional share scheduling
- > Number of processors
 - Uniprocessor scheduling
 - Multiprocessor scheduling

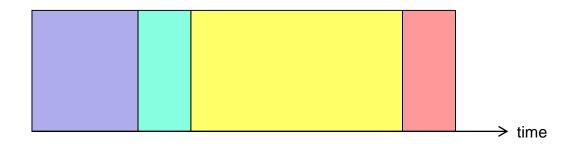
Priority-Based Scheduling

Priority-Based Scheduling

➤ A priority number (integer) is associated with each process



- Task B (priority 2)
- Task C (priority 3)
- Task D (priority 4)



- ➤ The CPU is allocated to the process with the highest priority (smallest integer = highest priority)
 - Preemptive
 - Nonpreemptive

Priority-Based Scheduling Policies

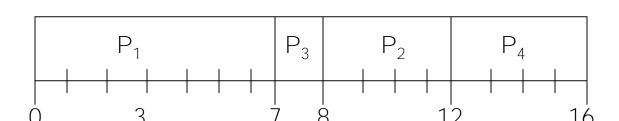
- **➤** Non-real-time policies
 - FCFS (First-Come, First-Served)
 - SJF (Shortest-Job-First)
 - SRTF (Shortest-Remaining-Time-First)
- > Real-time policies
 - RM (Rate Monotonic)
 - EDF (Earliest Deadline First)

SJF (Shortest-Job-First)

Process Arrival Time Execution Time

P_1	0.0	7
P_2	2.0	4
P_3	4.0	1

5.0



> Average waiting time = (0 + 6 + 3 + 7)/4 = 4

SRTF (Shortest-Remaining-Time-First)

<u>Process</u>	Arrival T	<u>ime</u> Execu	ution Time
P_1	0.0		7
P_2	2.0		4
P_3	4.0		1
P_4	5.0		4
P ₁ P ₂ 0 2	2 P ₃ P ₂	P ₄ + + + + + + + + + + + + + + + + + + +	P ₁ 16

- \triangleright Average waiting time = (9 + 1 + 0 + 2)/4 = 3
 - SRTF is optimal in that it achieves minimum average waiting time for a given set of processes

RM (Rate Monotonic)

빈도가 높은 일에 우선순위를 주는 방식.

Assumptions

Processes have periods, worst-case execution times (WCETs), and deadlines

Scheduling policy

- Give higher priorities to tasks with shorter periods
- Preemptive static priority scheduling

Optimality

 If a feasible static priority assignment exists for some process set, the RM priority assignment is feasible for that process set

RM (Rate Monotonic)

> Consider the following tasks

- Process X : period = 20, WCET = 10, deadline = 20
- Process Y □: period = 30, WCET = 8, deadline = 30
- Process Z : period = 40, WCET = 4, deadline = 40

period : 주기



> Schedulability test

m : CPU count U : CPU utilization cpu utilization이 69%를 넘지 않으면 rate monotonic을 할 수 있다.

- **CPU utilization:** $U = \sum_{i=1}^{m} e_i / p_i$
- A set of m processes is schedulable if $U \le m(2^{1/m} 1)$
 - For large m, $m(2^{1/m} 1) \approx \ln 2 \approx 0.69$

EDF (Earliest Deadline First)

Scheduling policy

- Give higher priorities to tasks with earlier absolute deadlines
- Preemptive dynamic priority scheduling

> Optimality

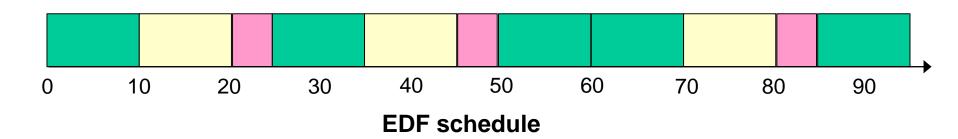
 If a feasible dynamic priority assignment exists for some process set, the EDF priority assignment is feasible for that process set

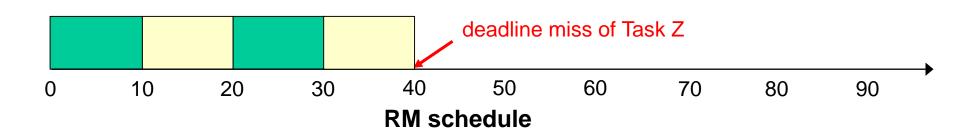
Schedulability test

■ A set of m processes is schedulable if and only if $U \le 1$

EDF (Earliest Deadline First)

- > Consider the following tasks
 - Process X : period = 20, WCET = 10, deadline = 20
 - Process Y □: period = 30, WCET = 10, deadline = 30
 - Process Z ■: period = 40, WCET = 5, deadline = 40

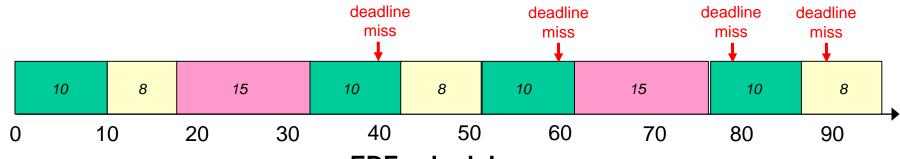




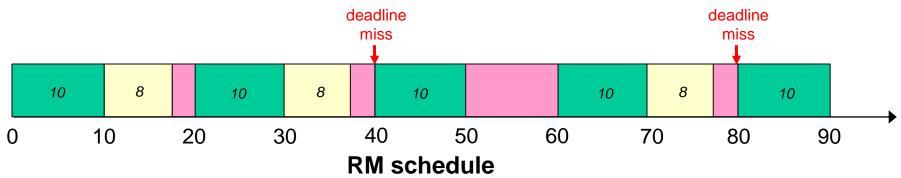
Non-schedulable Behavior



- > Consider the following tasks
 - Process X : period = 20, WCET = 10, deadline = 20
 - Process Y : period = 30, WCET = 8, deadline = 30
 - Process Z ■: period = 40, WCET = 15, deadline = 40



EDF schedule

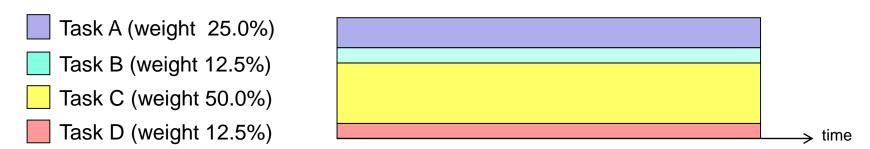


Proportional Share Scheduling

Proportional Share Scheduling

Basic concept

- A weight value is associated with each process
- The CPU is allocated to the process in proportion to its weight



> Two contexts

- Fair queueing (in the context of communication networks)
 - Packet scheduling
- Proportional share (in the context of operating systems)
 - Process scheduling

Scheduling Algorithms

Network scheduling

- PGPS (= WFQ), Demers *et al.*, 1989
- Virtual Clock, Lixia Zhang, 1990
- SCFQ, Golestani, 1994
- SFQ, Goyal et al., 1996
- WF²Q, Bennett *et al.*, 1996

CPU scheduling

- Lottery and Stride, Waldspurger, 1995
- Hierarchical SFQ, Goyal et al., 1996
- BVT, Duda et al., 1999
- VTRR, Nieh et al., 2001

GPS (Generalized Processor Sharing)

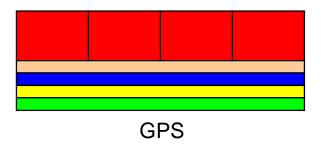
> A GPS server is defined by (Kleinrock, 1976)

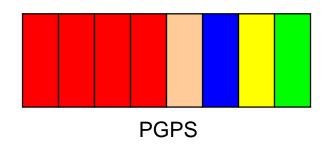
$$\frac{W_i(t_1, t_2)}{W_j(t_1, t_2)} \ge \frac{r_i}{r_j}, j = 1, 2, \dots, N$$

- $W_i(t_1,t_2)$: the amount of session i traffic served in an $(t_1,t_2]$ interval
- r_i: weight of session i
- > Packets of all sessions are served simultaneously
 - Idealized fluid-flow system or bit-by-bit weighted roundrobin

PGPS (Packet-by-Packet GPS)

- > PGPS is an approximation to GPS
 - Fair queueing on a packet-by-packet basis
 - Also known as WFQ (Weighted Fair Queueing)
- > Algorithm
 - F_p : the time at which packet p will depart (finish service) under GPS
 - Serve packets in increasing order of \boldsymbol{F}_p





Fairness Bounds of PGPS

Bound on lag

$$\hat{F}_{p} - F_{p} \leq \frac{L_{\text{max}}}{r}$$

- \hat{F}_p : the time at which packet p departs under PGPS
- F_p : the time at which packet p will depart under GPS
- $L_{\rm max}$: the maximum packet length
- If r = 1Gbps and $L_{max} = 1Kb$, then the lag is 1 ms

> Bound on difference of services received

•
$$W_i(0,\tau) - \hat{W}_i(0,\tau) \le L_{\text{max}}$$

Worst-case Fair WFQ

- **→ WF²Q only considers**
 - Packets that have started receiving service under GPS

GPS (fluid-flow)



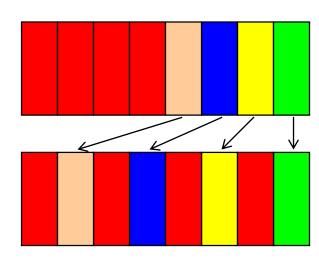
WFQ satisfies only

$$W_{p}(t_{1},t_{2}) - \hat{W_{p}}(t_{1},t_{2}) \leq L_{\max}$$
 not

$$|W_p(t_1, t_2) - \hat{W_p}(t_1, t_2)| \leq L_{\max}$$

WFQ

WF²Q



Lottery and Stride Scheduling

- > Tickets: relative resource rights
 - Task τ_i has m_i tickets
 - A total of M tickets
- > Lottery scheduling: probabilistic algorithm
 - Use random number generator to select a winning ticket
 - Task τ_i is probabilistically guaranteed a rate of $p = m_i / M$
- > Stride scheduling: deterministic algorithm
 - "Stride" is inversely proportional to tickets
 - Task with minimum "pass" value is selected and its pass is advanced by its stride

Stride Scheduling

```
\triangleright Task \tau_1: tickets = 3, stride = 2
```

$$\triangleright$$
 Task τ_2 : tickets = 2, stride = 3

$$\triangleright$$
 Task τ_3 : tickets = 1, stride = 6

Initial pass values are set to stride values															
time pass	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14
$ au_1$'s pass value	2	4	4	6	8	8	8	10	10	12	14	14	14	16	16
$ au_2$'s pass value	3	3_	> 6	6	6	9	9	9	12	12	12	15	15	15	18
$ au_3$'s pass value	6	6	6	6	6	6	12	12	12	12	12	12	18	18	18
Smallest value is shoop															

Smallest value is chosen
Pass is advanced by stride 3

Ties are broken arbitrarily

Multiprocessor Scheduling

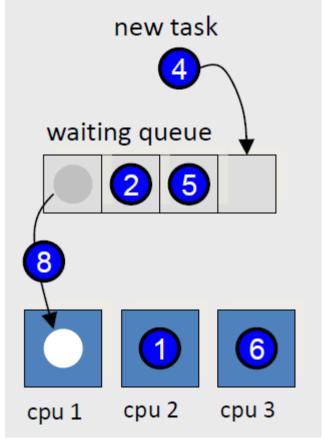
Uniprocessor vs. Multiprocessor Scheduling

- Uniprocessor scheduling
 - It is to decide when and which job will run
- Multiprocessor scheduling
 - It is to decide not only when but also where a job will run
 - Almost the same goals as those of uniprocessor scheduling
 - But it raises new issues
 - How to assign applications to multiple processors?
 - How to balance workload among processors?
 - How to define and exploit affinity?
 - How to manage processor heterogeneity?

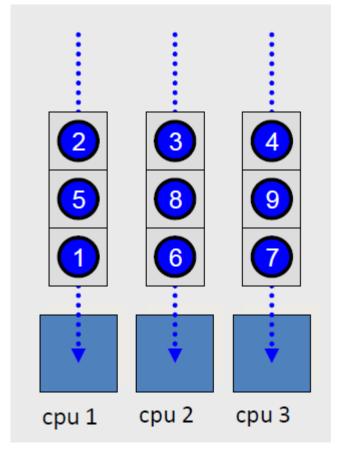
Multiprocessor Scheduling Policies

- > The same policies as uniprocessor policies
 - Priority-based scheduling: FCFS, SJF, SRTF, RM, EDF
 - Proportional share scheduling: PGPS, SFQ, WF²Q, Lottery and Stride, BVT, VTRR
- > Two approaches
 - Global scheduling
 - The system has a single global process queue
 - Processes are dispatched to any available processors
 - Partitioned scheduling
 - Each processor has a separate process queue
 - Each queue is scheduled by an independent scheduler
 - Process migration may be allowed or not

Global vs. Partitioned Scheduling



Global Scheduling



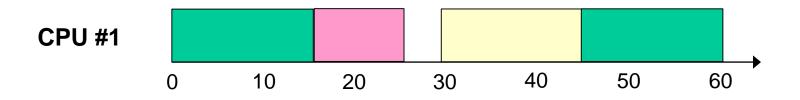
Partitioned Scheduling

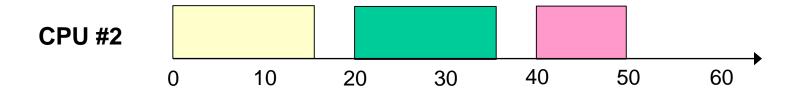
Global vs. Partitioned Scheduling

- ➤ Global scheduling migration issue, cache problem
 - It is generally believed that global scheduling can achieve better performance
 - However, it can be inefficient due to the contention at the single queue and increased cache misses
- ➤ Partitioned scheduling 실제로는 이 방식을 많이 사용한다. 그 이유는, RM scheduling 방식은 single core에서 증명된 스케줄링 방식이기 때문이다.
 - Performance can vary depending on the initial distribution of processes, i.e., a bin-packing problem
 - Different scheduling policies can be employed across processors
 - We can use the rich and extensive results from the uniprocessor scheduling theory

Global EDF

- Consider the following tasks
 - Process X : period = 20, WCET = 15, deadline = 20
 - Process Y □: period = 30, WCET = 15, deadline = 30
 - Process Z □: period = 40, WCET = 10, deadline = 40

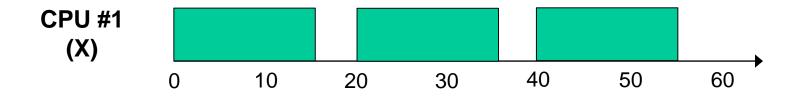




Partitioned EDF

Consider the following tasks

- Process X : period = 20, WCET = 15, deadline = 20
- Process Y : period = 30, WCET = 15, deadline = 30
- Process Z □: period = 40, WCET = 10, deadline = 40





Schedulability Analysis

Global EDF

- There is no single efficient test
- Most tests are very complex

Theorem 2 (*GFB*). A task set τ is schedulable with global EDF if

$$\lambda_{\text{tot}} \leqslant m(1 - \lambda_{\text{max}}) + \lambda_{\text{max}}.$$
 (1)

Theorem 3 (*BAK*, from [3]). A task set τ is schedulable with global EDF if, for all $\tau_k \in \tau$, there is a $\lambda \in \{\lambda_k\} \cup \{U_\ell | U_\ell \ge \lambda_k, \ell < k\}$ such that

$$\sum_{\tau_i \in \tau} \min(1, \beta_{i,k}(\lambda)) \leqslant m(1-\lambda) + \lambda, \tag{2}$$

where

$$eta_{i,k}(\lambda) = egin{cases} U_i\Big(1 + rac{\max(0,T_i - D_i)}{D_k}\Big) & ext{if} \quad U_i \leqslant \lambda \ U_i\Big(1 + rac{T_i}{D_k}\Big) - \lambda rac{D_i}{D_k} & ext{if} \quad U_i > \lambda. \end{cases}$$

Theorem 6 (*FFDBF* from [10]). A task set τ is schedulable with global EDF if $\exists \sigma | \lambda_{\max} \leqslant \sigma < \frac{m-U_{tot}}{m-1} - \epsilon$ (with an arbitrarily small ϵ), such that $\forall t \geqslant 0$,

$$ffdbf(t,\sigma) \leqslant (m-(m-1)\sigma)t$$
 (10)

It can be proved that it is sufficient to check only those values of t in $\{kT_i + D_i | k \in \mathbb{N}\}_{i=1}^n$ that are smaller than²

$$\frac{\sum_{\tau_i \in \tau} C_i \left(1 - \frac{D_i}{T_i}\right)}{m - (m - 1)\sigma - U_{\text{tot}}}.$$
(11)

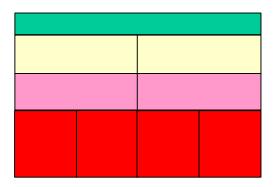
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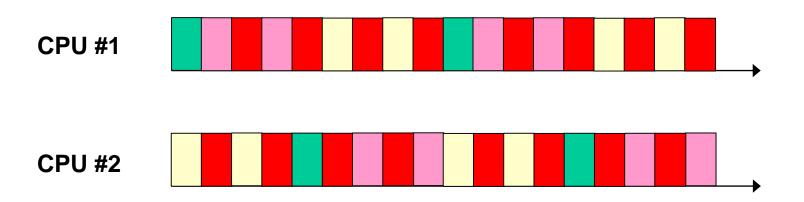
Partitioned EDF

 Sufficient to check if the CPU utilization does not exceed 100% for each processor

Global WFQ

- > Consider the following tasks
 - Process A : weight = 1
 - Process B : weight = 2
 - Process C : weight = 2
 - Process D■: weight = 4





Partitioned WFQ with Load Balancing

- Consider the following tasks
 - Process A : weight = 1
 - Process B : weight = 2
 - Process C : weight = 2
 - Process D : weight = 4

