# Machine Learning 1.07: Logistic Regression & Polling

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- But so does a random forest.
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  - Faster, and can be trained incrementally/online
  - Really popular everywhere but computer science!
  - Simple (Invented in 1958!)

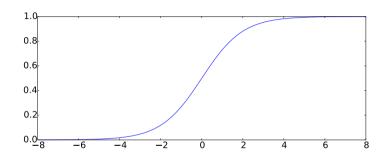


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  - Simple (Invented in 1958!)
  - Its good for understanding all the subtle details. . .



### The Logistic Function

(also called the sigmoid function)



$$y=rac{1}{1+e^{-x}}$$
 or  $y=rac{e^x}{1+e^x}$  or  $y=rac{1}{2}\left(1+ anh(x/2)
ight)$ 

Maps 
$$-\infty - +\infty$$
 to  $0-1$ 



### Fitting To Data I

- Binary classification: Output, y, is 0 or 1.
- For now assume single input feature, x.
- Probabilities go from 0 to 1, so lets assume

$$P(y=1|x) = \frac{1}{1+e^{-z}}, \qquad P(y=0|x) = 1 - \frac{1}{1+e^{-z}} = \frac{e^{-z}}{1+e^{-z}}, \qquad z=\beta_0 + \beta_1 x$$



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- This is a model.
- $\beta_0$  and  $\beta_1$  are parameters which we fit to data.
- Note the assumptions!



# Fitting To Data II

- We have a data set:  $y_i$  and  $x_i$  for  $i \in 1..N$
- We want to maximise the probability of the data set:

$$\operatorname*{argmax}_{\beta_0,\beta_1} \left\{ \prod_{i=1}^N P(y_i|x_i,\beta_0,\beta_1) \right\}$$

- No analytic solution.
- Gradient descent!



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- No analytic solution.
- Gradient descent!
- Note:
  - Historically, Logistic regression was optimised by minimising distance.
  - This has a closed form expression, but is idiotic: Output not probabilities.
  - Many implementations still use this approach however. Check!



# Simplifying I

• Swap P() for logistic equation:

$$\operatorname*{argmax}_{\beta_0,\beta_1} \left\{ \prod_{i=1}^N p_i^{y_i} (1-p_i)^{1-y_i} \right\}, \qquad \quad p_i = \frac{1}{1+e^{-z_i}}, \quad z_i = \beta_0 + \beta_1 x_i$$

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• Take the log – argmax doesn't care:

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• Rearrange:

$$\operatorname*{argmax}_{\beta_0,\beta_1} \left\{ \sum_{i=1}^N \log(1-p_i) + \sum_{i=1}^N y_i \log\left(\frac{p_i}{1-p_i}\right) \right\}$$



# Simplifying II

• What is  $\log(1-p_i)$ ?

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• So...

$$\operatorname*{argmax}_{\beta_0,\beta_1} \left\{ \sum_{i=1}^N y_i z_i - \sum_{i=1}^N \log(1 + e^{z_i}) \right\}$$



• For  $\beta_j$  (L = likelihood, i.e. term in argmax):

$$\frac{\delta L}{\beta_j} = \frac{\delta L}{\delta z} \frac{\delta z}{\beta_j} = \sum_{i=1}^{N} \left\{ \left( y_i - \frac{1}{1 + e^{-z_i}} \right) \frac{\delta z_i}{\delta \beta_j} \right\}$$





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β<sub>0</sub>:

$$\frac{\delta L}{\beta_1} = \sum_{i=1}^{N} \left\{ \left( y_i - \frac{1}{1 + e^{-z_i}} \right) \right\}$$

•  $\beta_1$ :

$$\frac{\delta L}{\beta_1} = \sum_{i=1}^{N} \left\{ \left( y_i - \frac{1}{1 + e^{-z_i}} \right) x_i \right\}$$



# Model Fitting - Gradient Ascent

- Initialise all  $\beta$  to 0;  $\beta_i^{(0)} = 0$ .
- Iterate updating each  $\beta_i$  with

$$\beta_j^{(t+1)} = \beta_j^{(t+1)} + \lambda \frac{\delta L}{\beta_j}$$

and  $\lambda$  set to a suitably small step size.

• Stop when the  $\beta$  values stop changing / L stops increasing.



# Multiple Features

• Replace  $z_i$  with:

$$z_i = \vec{\beta} \cdot \vec{x_i}$$

where

$$\vec{\beta} = [\beta_0, \beta_1, \beta_2, \ldots]^T$$
  $\vec{x_i} = [1, x_{i,1}, x_{i,2}, \ldots]^T$ 

• All of the above just works, exactly as you would expect!



• Why do we care about getting probability?



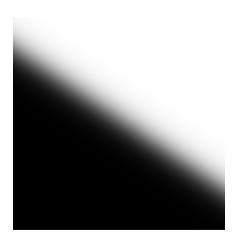
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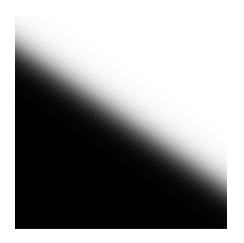


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  - Maybe...
  - Optimising a reasonable metric (maximum likelihood).
  - But assuming a very specific distribution.
  - Few data sets follow this.





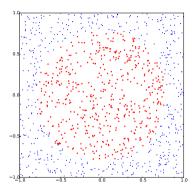
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  - Few data sets follow this.
- Are random forests better?





# Straight in Feature Space

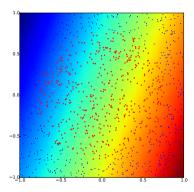
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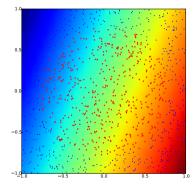
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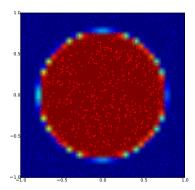




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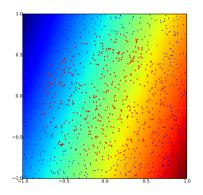
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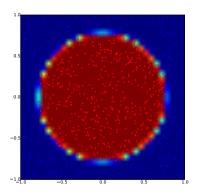




# Straight in Feature Space

#### Can't separate with a straight line:





- Added a third feature distance from centre of circle.
- A straight line in **feature space** can now separate the data.



# Feature Engineering I

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- In some cases you can't beat the fully automatic approach.
- But in many a simple algorithm with the right features will win!
- Compute time is cheaper than your time.
- Automatic feature design is taking over.



# Feature Engineering II

#### Examples:

- Convert a continuous variable into a set of discrete variables, marking which bin of a histogram that continuous variable has landed in.
- As above, but with triangular kernels this is equivalent to letting the algorithm choose an arbitrary piecewise linear function of a feature.
- Calculate random non-linear functions of the input features (Reservoir computing).



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  - Demographics (age, gender etc.)
  - Other useful stuff

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- Will not work as sample too small.
- Normal approach (most polling companies):
  - Re-weight sample members, e.g. if census says 10% of the country are managers, but it's only 5% in sample double the value of their vote (called raking).
  - · Simulate election with this correction.
  - Add fudge factors to ensure you would have got it right last time!



- Smart approach (used by YouGov and FiveThirtyEight):
  - Data set 1: Polling data.
  - Data set 2: Entire country: Last census plus anything else available!
  - Learn function using polling data:
    - Input: Questions shared between between two data sets.
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- "multilevel": Include terms to account for group biases (in this context).
- "poststratification" means running per-voting region with region demographics.
- Instead of fudge factors ask how people voted last time!



#### Related models

- Probit regression: Replace the logistic distribution with the Gaussian distribution.
- Whole family of these: Generalised Linear Model.
- Hidden and output nodes in a neural network may each be logistic regression.
- Used to be the dominant choice, these days linear rectified units are preferred to sigmoid functions.





- Logistic regression
- Probability not simple!
- Basic feature engineering



### Further Reading

- Guide to Mr P: http://www.princeton.edu/~jkastell/MRP\_primer/mrp\_primer.pdf
- Andrew Gelman, inventor of Mr P, has an excellent blog: http://andrewgelman.com/ (his take downs of bad research are particularly educational)