

Computer Animation and Games I

CM50244

Skeletal Motion Capture

Some slides from Prof. Christian Theobalt, MPII

Overview

- **Recap pre-knowledge of skeletal motion capture**
 - Motion capture
 - Skeleton structure and motion
- Skeletal Motion Capture and Main Technologies
- Marker based Skeletal Motion Capture

Recap: Motion Capture

- Record live action
- Transform to virtual character



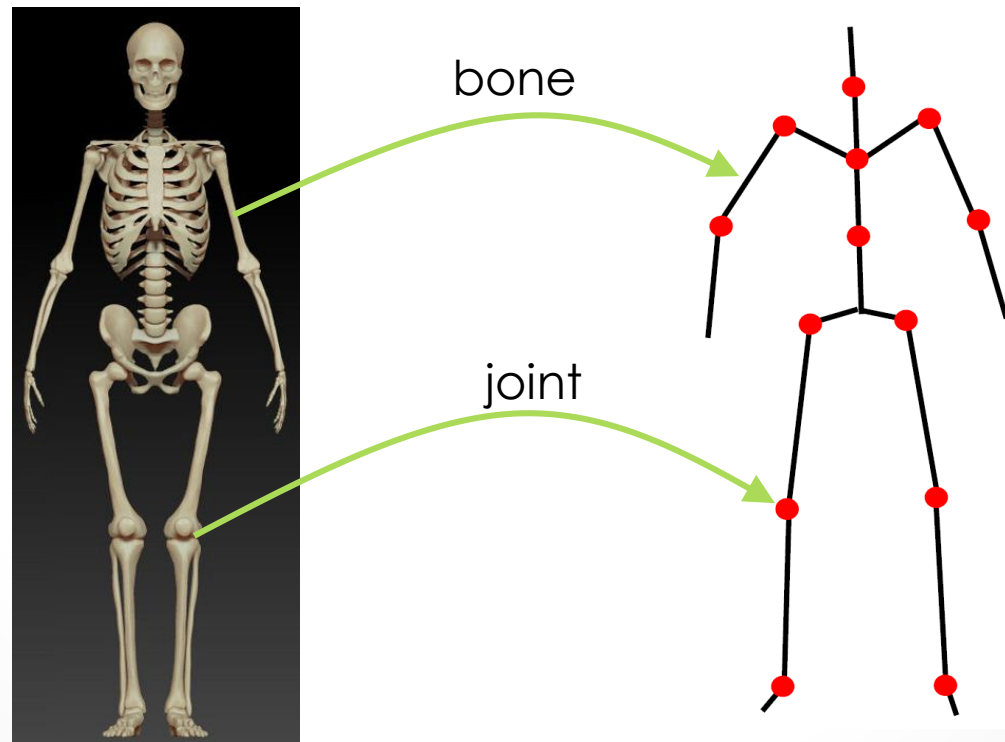
Motion Capture in Movies



[Avatar - Making of]

Recap: Skeleton Structure

- Animation/kinematic skeleton: inspired by anatomic skeleton

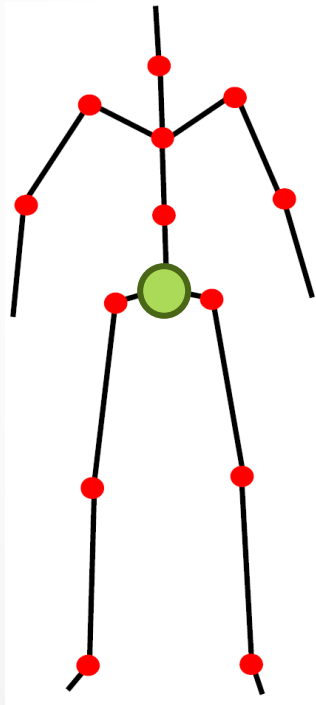


Anatomic skeleton

Kinematic skeleton

Recap: Skeleton Structure

- Skeleton = tree.



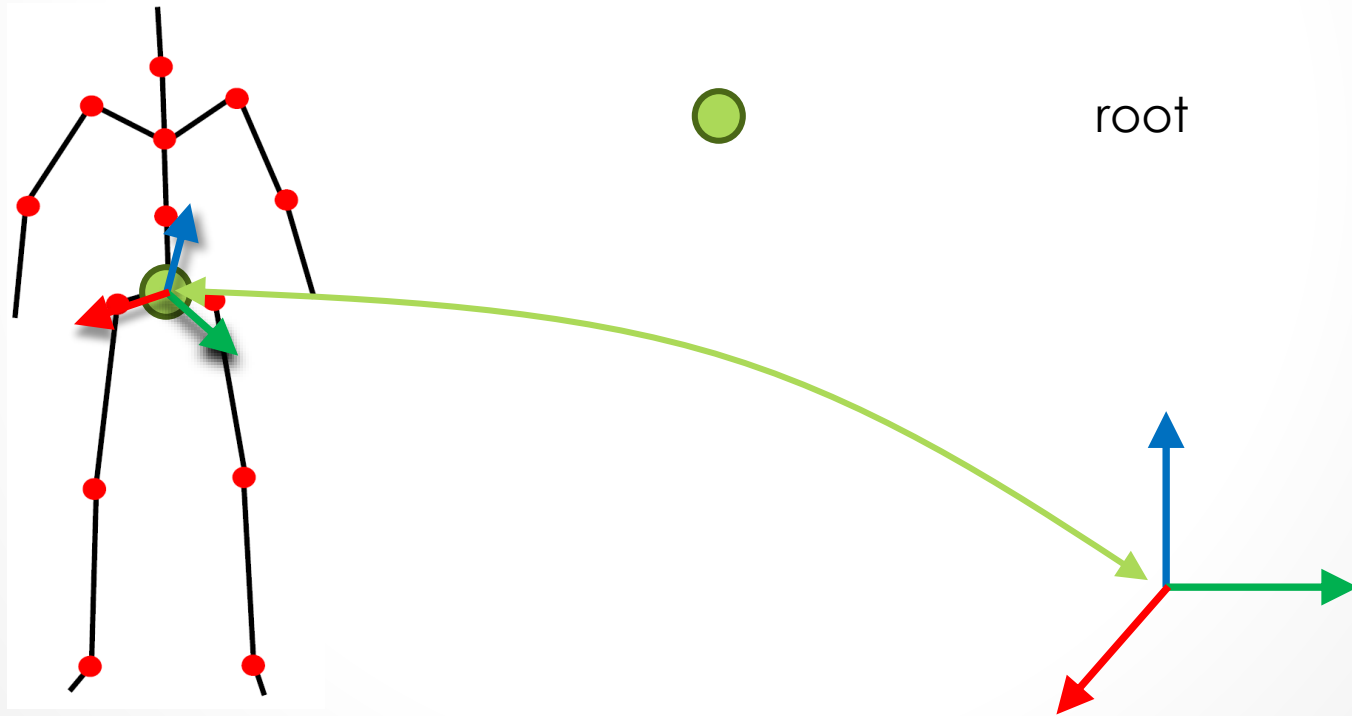
Kinematic skeleton



root

Recap: Skeleton Motion

- Skeleton = tree.
- Joints = predefined transformations in an coord. frame

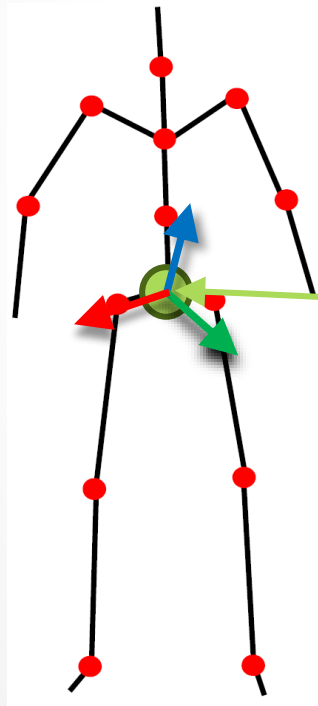


Kinematic skeleton

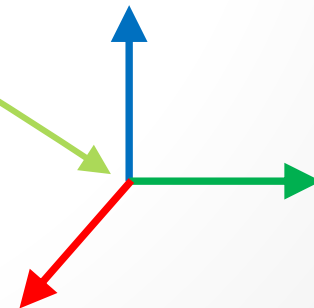
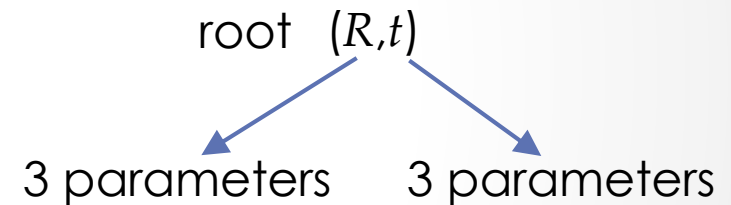
World coordinate frame

Recap: Skeleton Motion

- Skeleton = tree.
- Joints = predefined transformations in an coord. frame



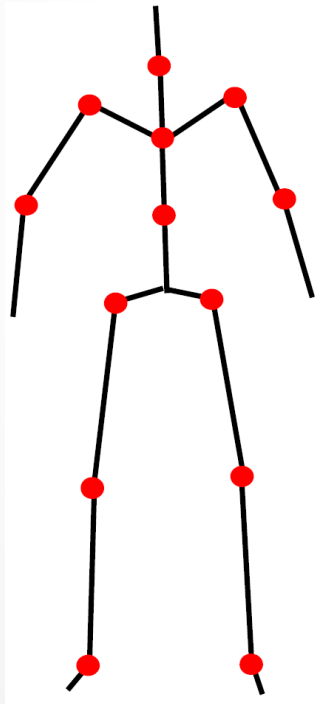
Kinematic skeleton



World coordinate frame

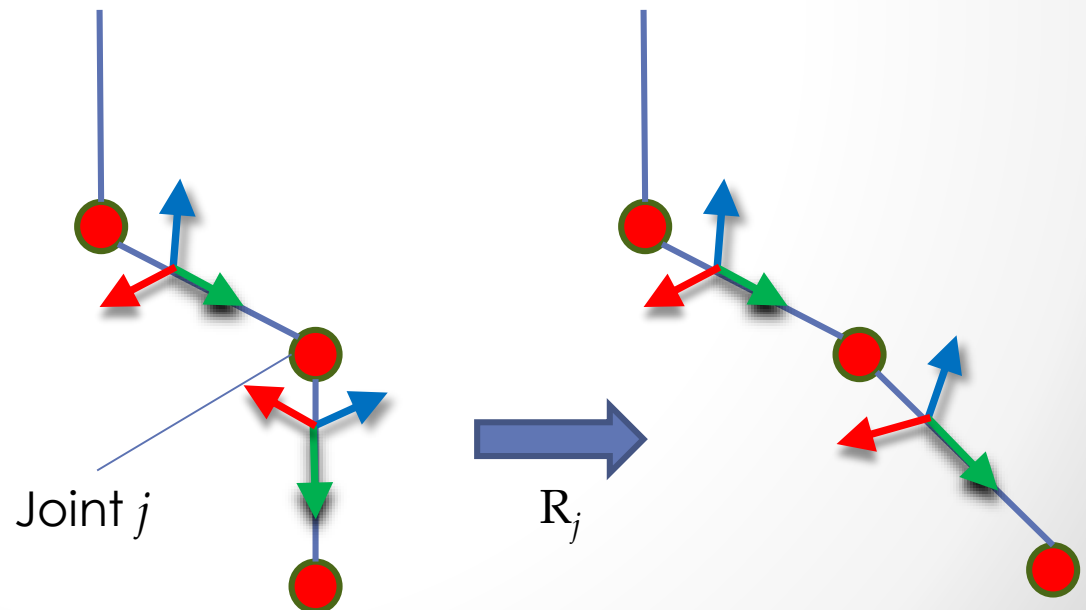
Recap: Skeleton Motion

- Skeleton = tree.
- Joints = predefined transformations in an coord. frame
- Hierarchy of transformations (usually rigid body)



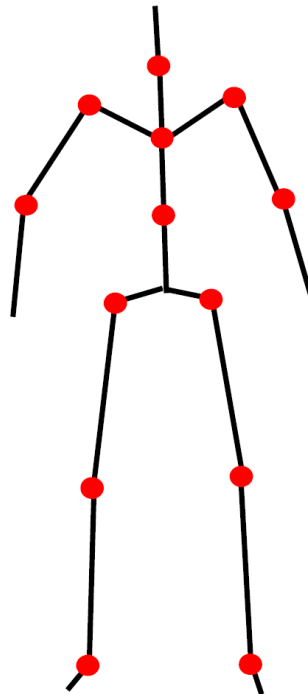
Kinematic skeleton

Other joints – relative transformation,
bone length fixed



Recap: Forward Kinematics

- Find joint parameters: $(R_{\text{root}}, t_{\text{root}}), (R_1, t_1), \dots, (R_n, t_n)$.
- Around 40+ parameters (degrees of freedom).
- For every time step of a motion.

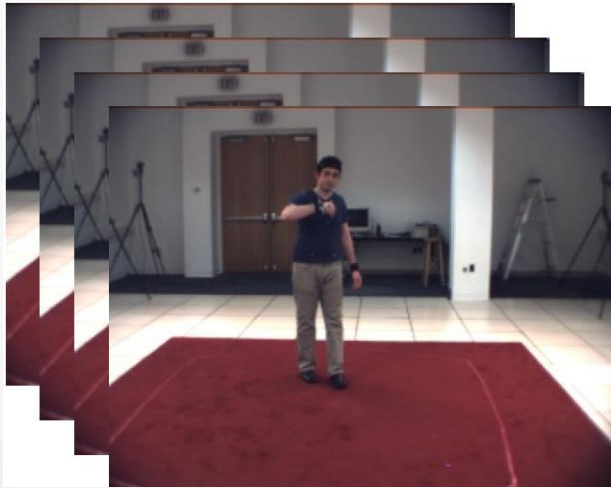


Kinematic skeleton

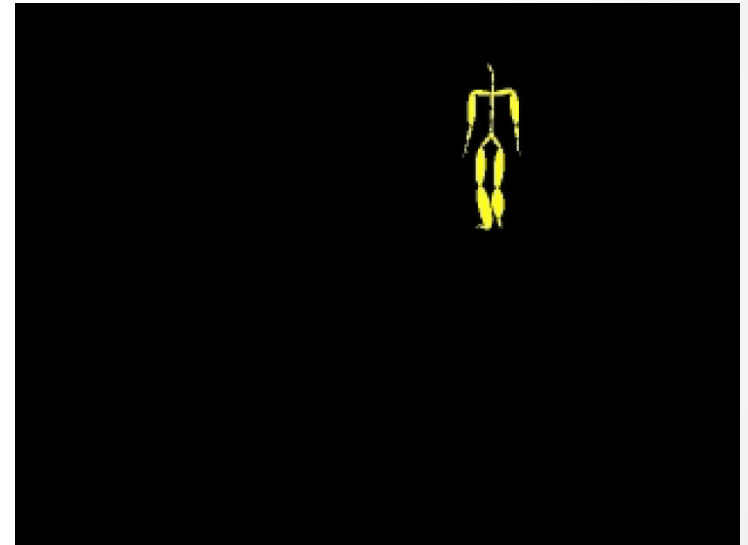
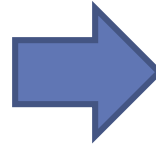
Overview

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- **Skeletal Motion Capture and Main Technologies**
- Marker based Skeletal Motion Capture

Skeletal Motion Capture



Sensor data



Model: Kinematic skeleton

Motion Capture Technology (1)

- Sensor (active sensing) based systems
 - accelerometer, gyroscope, etc.



[Metamotion]



[Xsens]

Motion Capture Technology (2)

- Marker-based optical systems



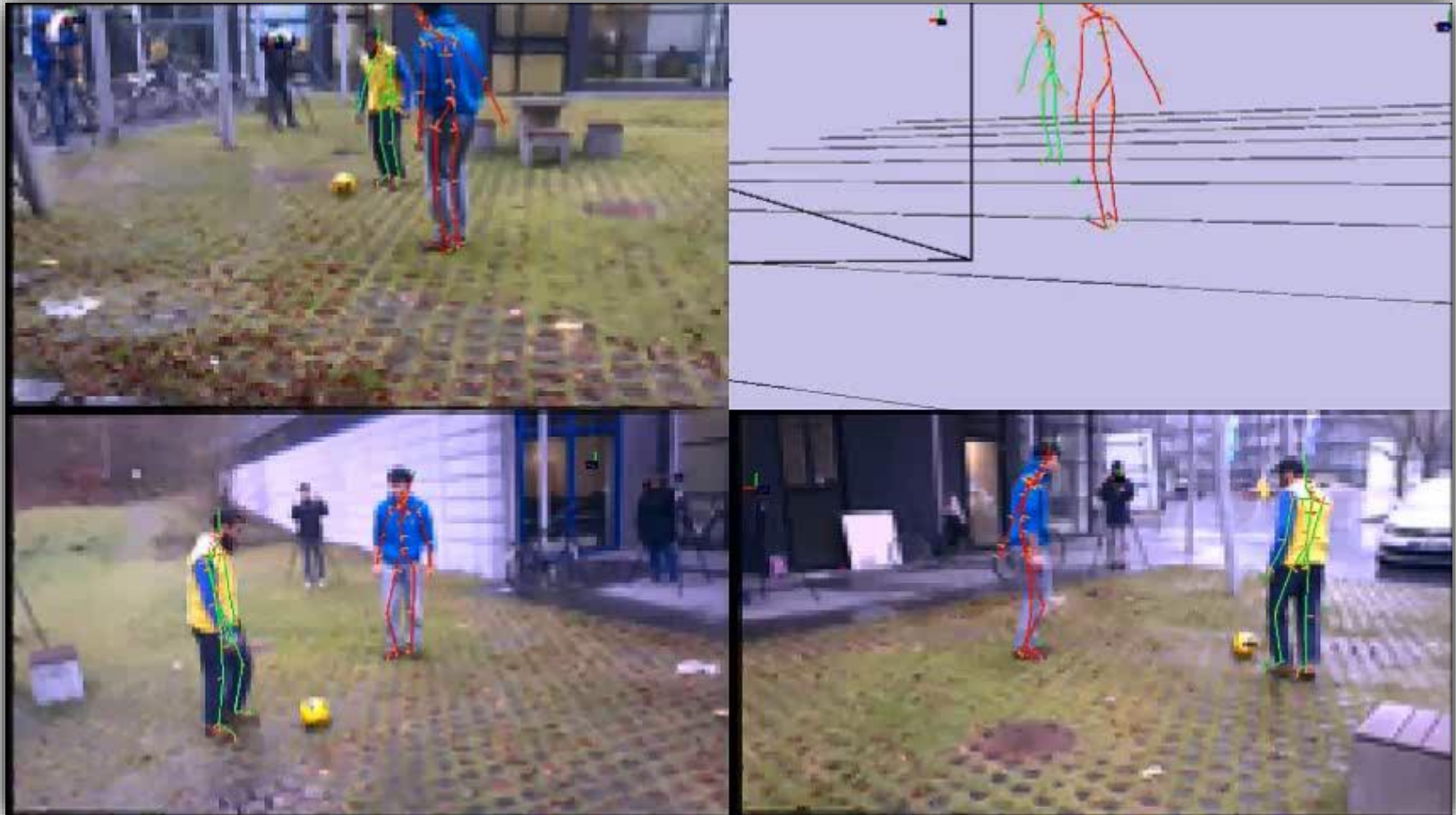
Passive retroreflective markers



Active markers

Motion Capture Technology (3)

- Marker-less motion capture

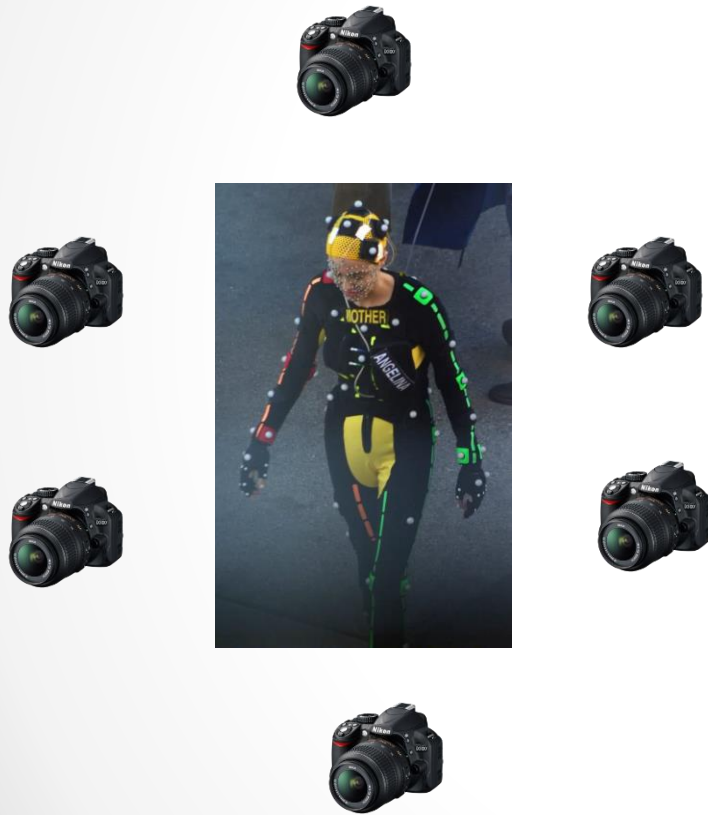


[Elhayek et al., Outdoor human motion capture by simultaneous optimization of pose and camera parameters, Computer Graphics Forum, 2014]

Overview

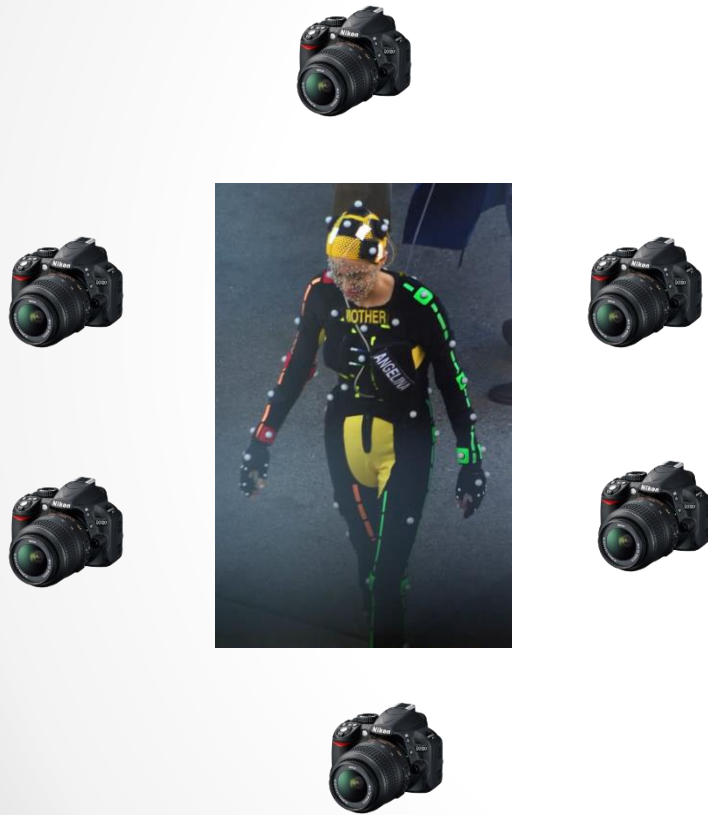
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- **Marker based Skeletal Motion Capture**

Marker-based Motion Capture

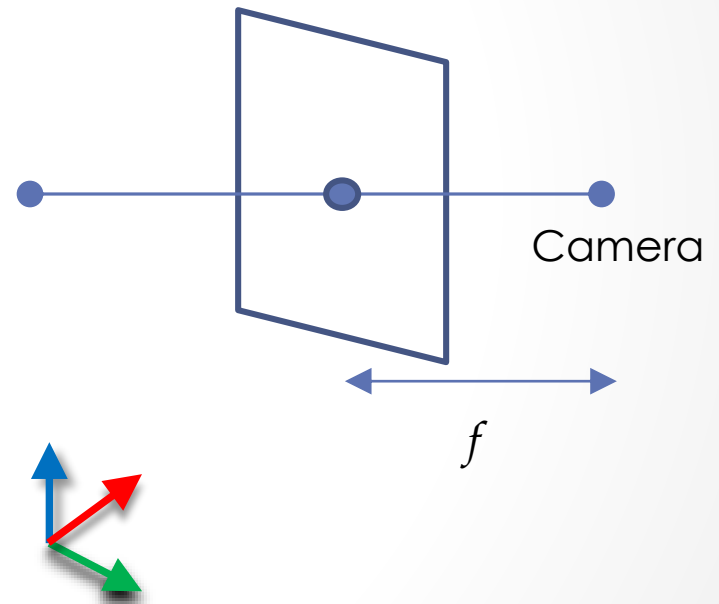


Calibration

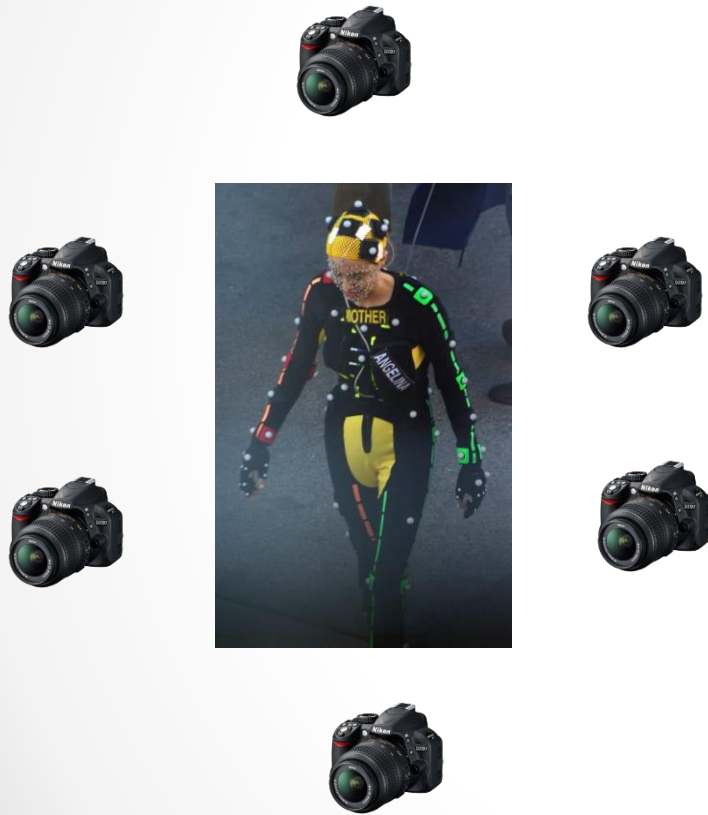
Marker-based Motion Capture



Calibration



Marker-based Motion Capture



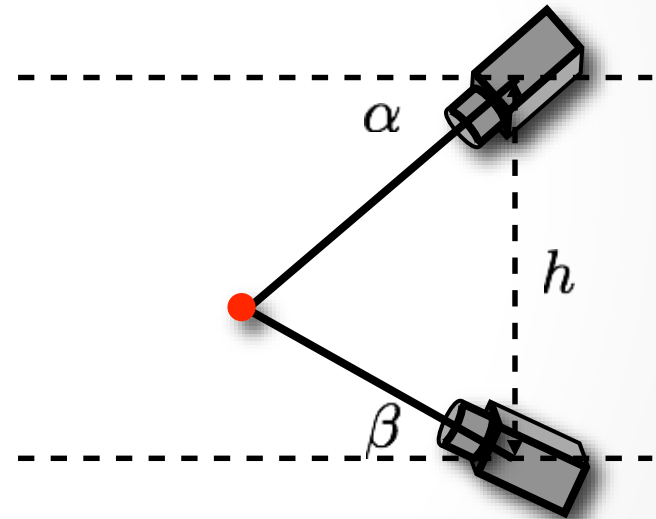
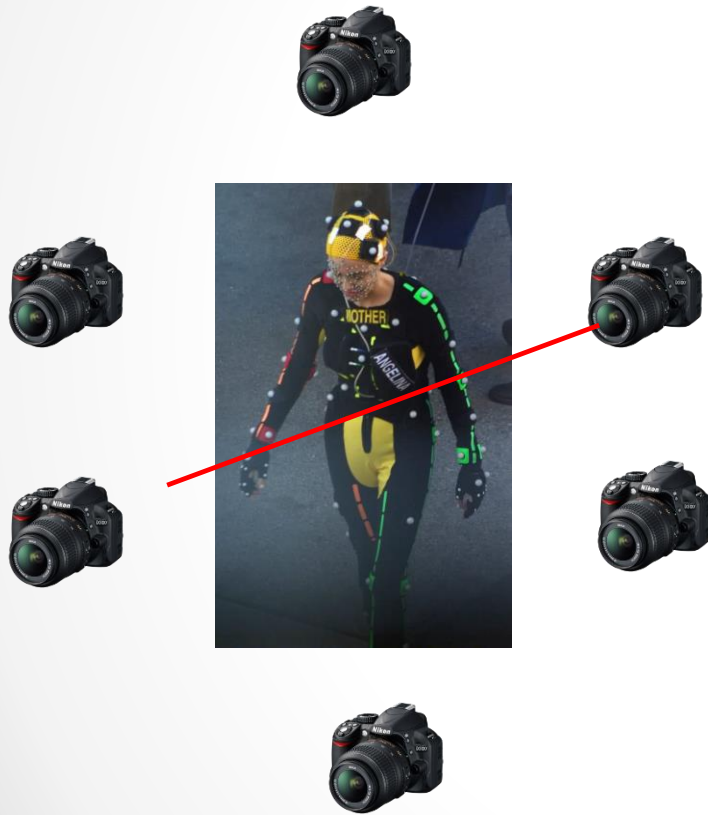
Calibration



Passive markers:
IR filters + IR light on camera

Marker-based Motion Capture

- Triangulation and tracking.



Triangulation \rightarrow 3D position

Marker-based Motion Capture

- Triangulation and tracking.



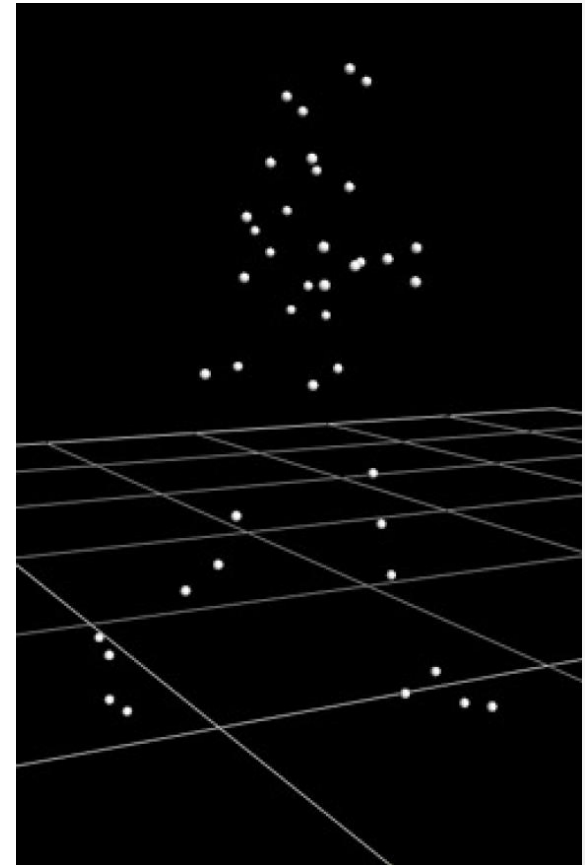
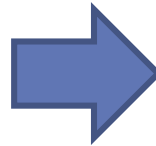
Triangulation → 3D position

Marker-based Motion Capture

- Triangulation and tracking.

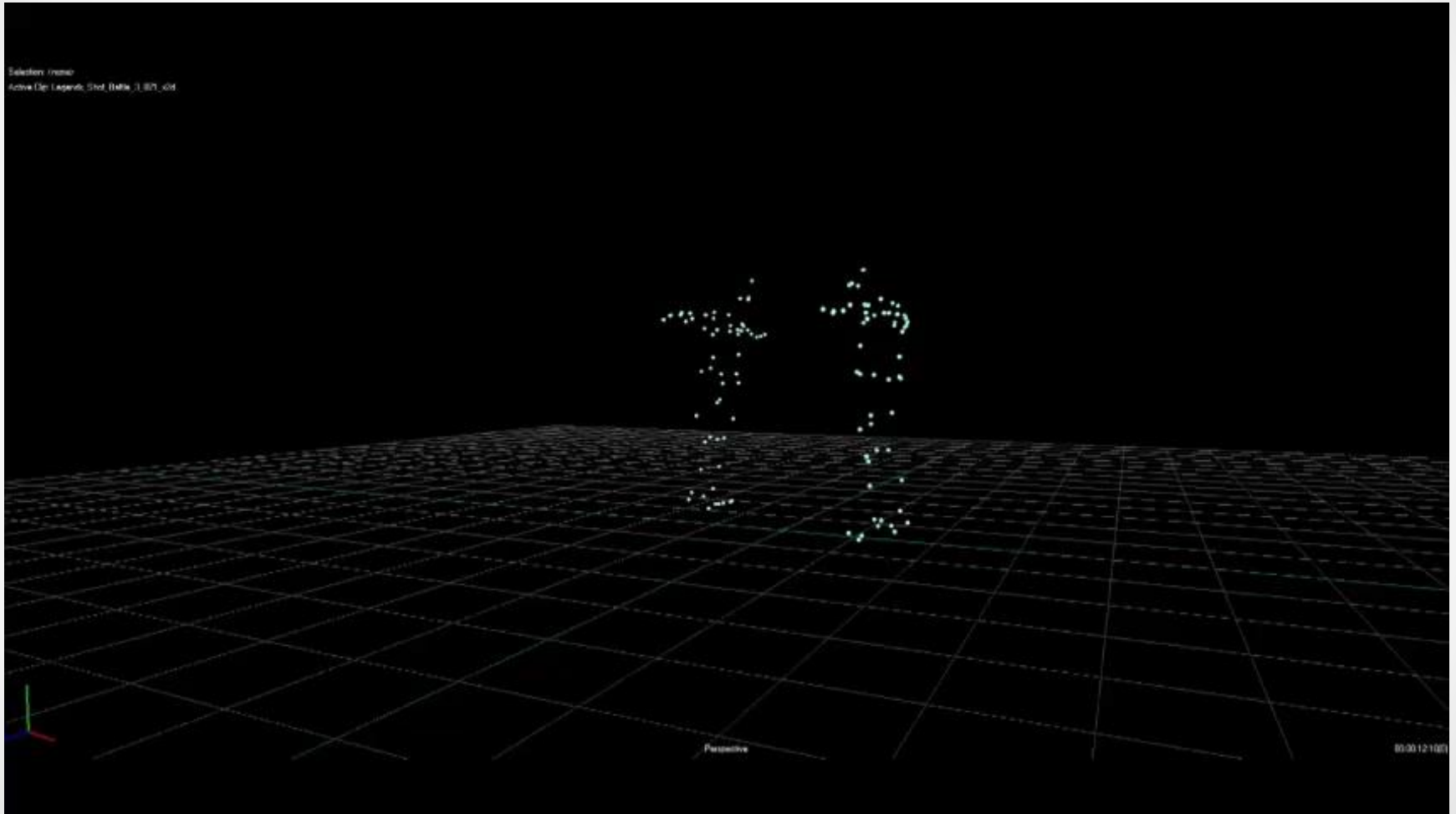


Triangulation → 3D position



[Carleton University]

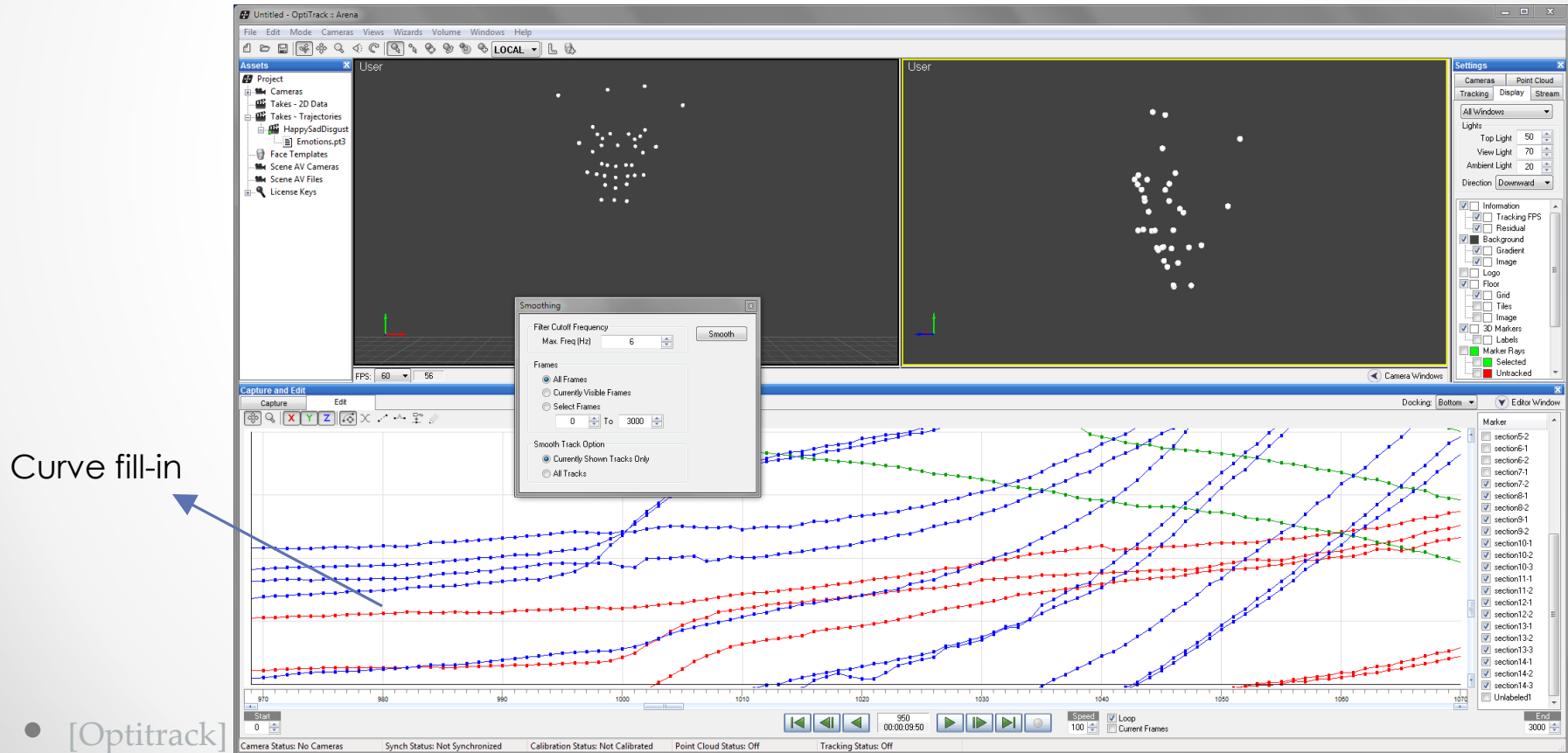
Marker-based Motion Capture: Step 1



[Motion Capture Processing 102 - Youtube]

Marker-based Motion Capture: Step 2

- Marker cleanup
 - Repair broken trajectories.
 - Semi-automatic – vendor specific tools.

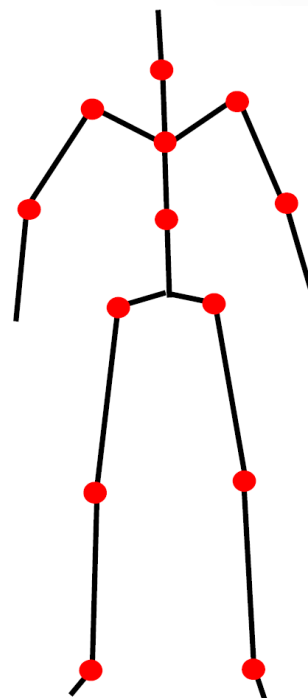


Marker-based Motion Capture: Step 3



[O'Brien,
UC Berkeley]

Initialization motion

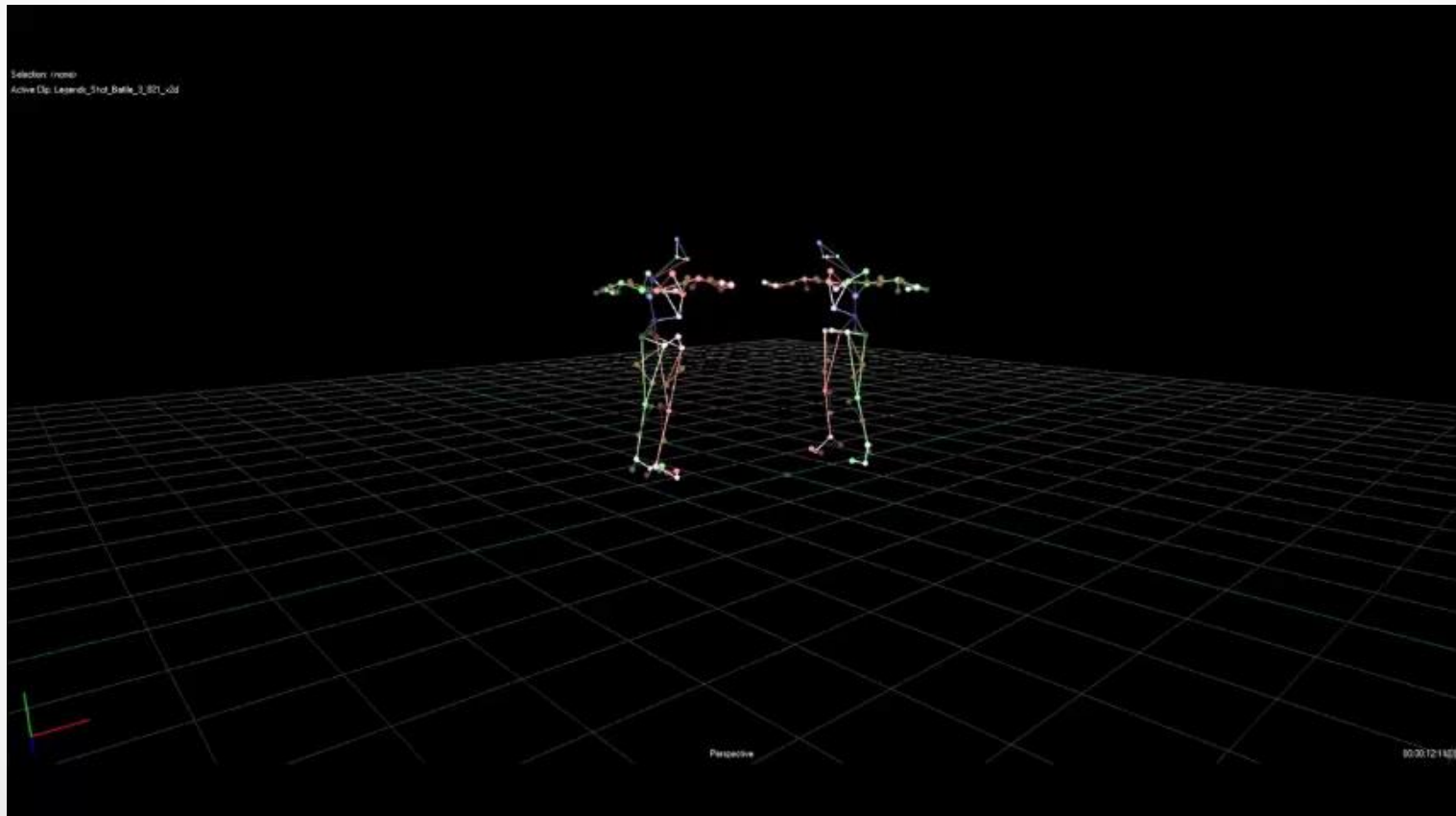


- Rigid segments with IDs of attached markers.
- Bone lengths.
- Joint locations

Adam G. Kirk, James F. O'Brien, and David A. Forsyth. 2005. Skeletal Parameter Estimation from Optical Motion Capture Data. CVPR 2005.

Marker-based Motion Capture: Step 3

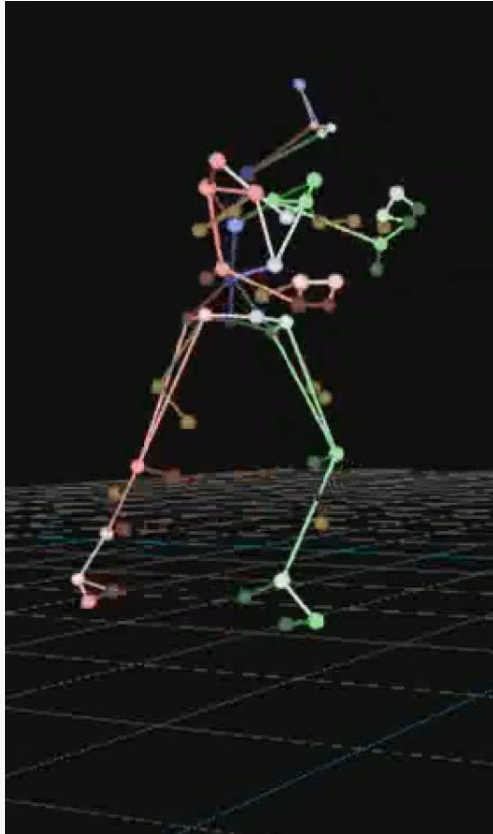
- Labeled marker sets (body segments).
- Most software – joint locations over time.



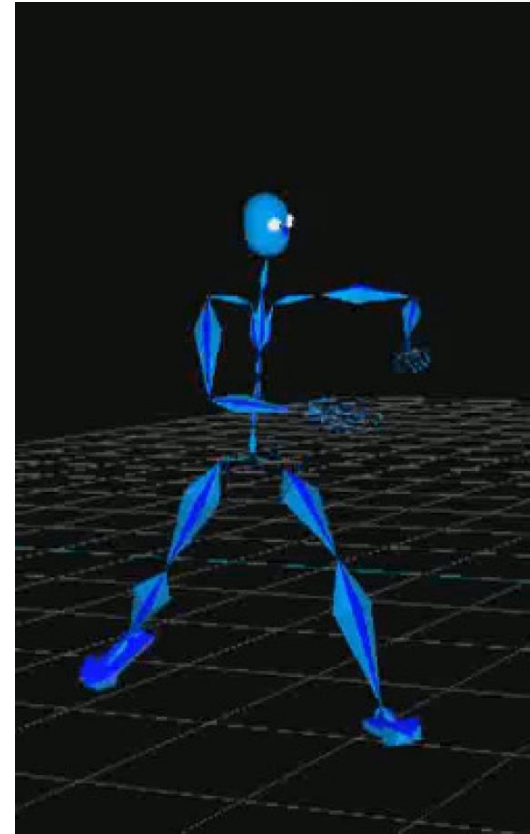
[Motion Capture Processing 103 - Youtube]

Marker-based Motion Capture: Step 4

- Inverse kinematics / skeleton solve

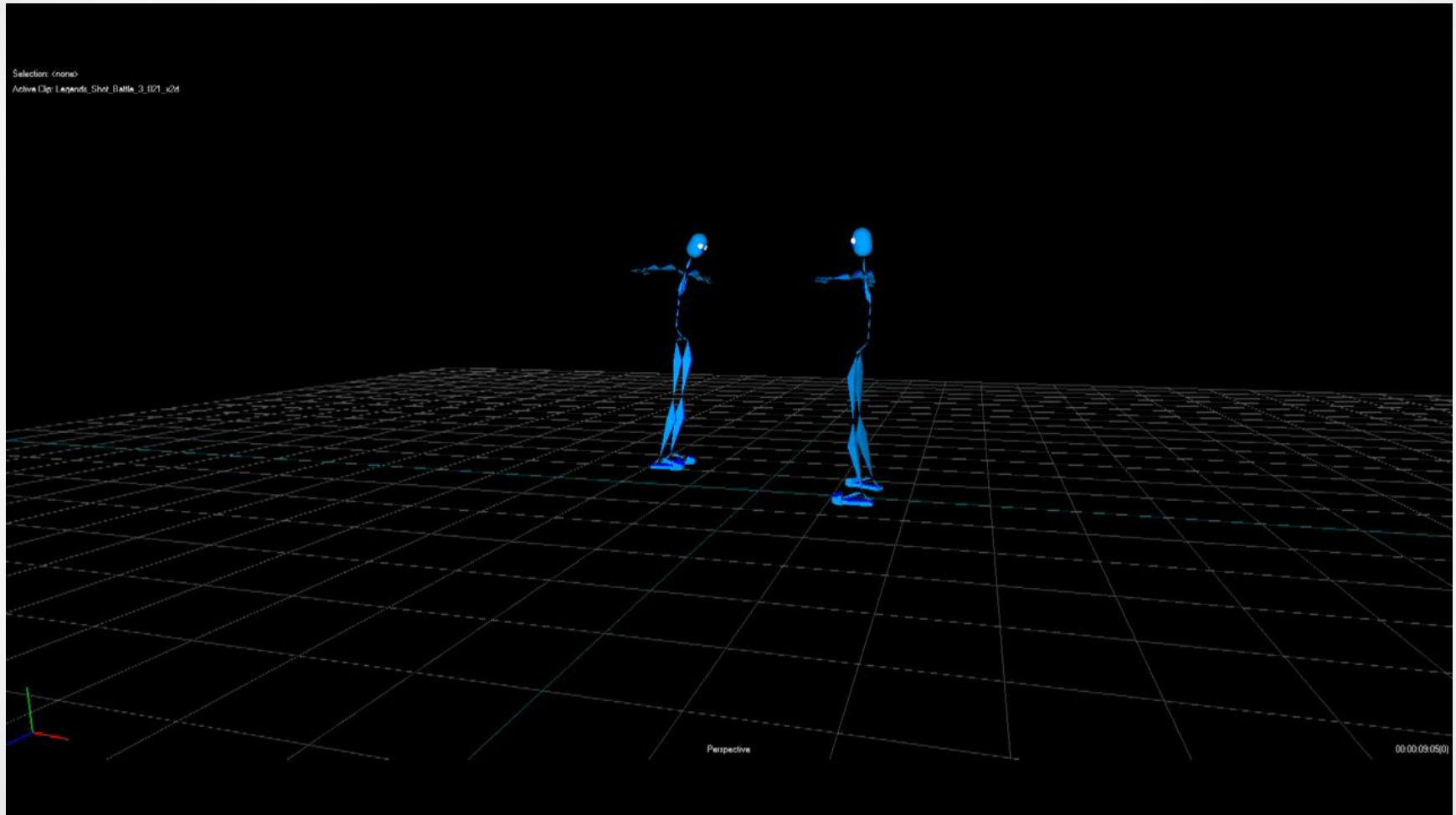


- (labeled) marker trajectories.
- Joint positions.



- Bones.
- Parameters for all joints $(R_{\text{root}}, t_{\text{root}}), (R_1, t_1), \dots, (R_n, t_n)$.

Marker-based Motion Capture: Step 4



[Motion Capture Processing 105 - Youtube]



[Rise of the tomb raider]