

MATRIX ALGEBRA

BY

TANUJIT CHAKRABORTY

Indian Statistical Institute

Mail : tanujitisi@gmail.com

MATRICES

Definition:- A collection of numbers arranged in rows and columns is said to be an array. A matrix is a rectangular array of numbers closed in addition, subtraction, multiplication, and division.

We represent a matrix by $A = [a_{ij}]_{m \times n}$, $i=1(1)m$, $j=1(1)n$.

$$\text{i.e., } A = \begin{bmatrix} a_{11} & a_{12} & a_{13} & \dots & a_{1n} \\ a_{21} & a_{22} & a_{23} & \dots & a_{2n} \\ \vdots & \vdots & \vdots & & \vdots \\ a_{m1} & a_{m2} & a_{m3} & \dots & a_{mn} \end{bmatrix}$$

Diagonal matrix:-

$A = [a_{ij}]$ is such that $a_{ij} = 0 \forall i \neq j$

i.e. $A = \text{diag}[d_1, d_2, \dots, d_n]$

Eg. $A = \begin{bmatrix} a_{11} & 0 & 0 \\ 0 & a_{22} & 0 \\ 0 & 0 & a_{33} \end{bmatrix}$ is a 3×3 diagonal mtx.

Scalar matrix:-

$A = [a_{ij}] \Rightarrow a_{ij} = 0 \forall i \neq j$
 $a_{ij} = k \forall i=j, k \in \mathbb{N}$.

Eg. $A = \begin{bmatrix} a & 0 & 0 \\ 0 & a & 0 \\ 0 & 0 & a \end{bmatrix}$

Triangular mtx:- If every element above or below the leading diagonal of a square matrix is zero, then the matrix is called a triangular matrix.

Upper triangular mtx:-

$$\begin{bmatrix} a_{11} & a_{12} & a_{13} \\ 0 & a_{22} & a_{23} \\ 0 & 0 & a_{33} \end{bmatrix}$$

Lower Triangular mtx:-

$$\begin{bmatrix} a_{11} & 0 & 0 \\ a_{21} & a_{22} & 0 \\ a_{31} & a_{32} & a_{33} \end{bmatrix}$$

Equality of matrices:- Two matrices A and B of the same order are said to be equal, if and only if the corresponding elements are equal.

Multiplication of matrix by a scalar:- Matrix multiplication is associative and distributive but not commutative.

$$A = [a_{ij}]_{m \times n}$$

$$KA = \begin{bmatrix} ka_{11} & ka_{12} & \cdots & ka_{1n} \\ ka_{21} & ka_{22} & \cdots & ka_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ ka_{m1} & ka_{m2} & \cdots & ka_{mn} \end{bmatrix} = [ka_{ij}]_{m \times n}$$

Addition of Matrices:-

$$A = [a_{ij}]_{m \times n} \quad B = [b_{ij}]_{m \times n}$$

$$A + B = [a_{ij} + b_{ij}]$$

Matrix addition is commutative, associative and distributive.

Note:- Only a square matrix can have a determinant.

Transpose of a matrix:-

$$A = [a_{ij}]_{m \times n}$$

$$A^T = [a_{ji}]_{n \times m}$$

$$(1) (A')' = A.$$

$$(2) (A+B)' = A'+B'.$$

$$(3) (AB)' = B'A'.$$

Symmetric and Skew-symmetric matrices:-

For a symmetric mtx. A , $a_{ij} = a_{ji} \forall i, j$.

For a skew-symmetric mtx A , $a_{ij} = -a_{ji} \forall i \neq j$
 $= 0 \quad \forall i = j$.

Ex.1. If A be any matrix, S.T. AA' and $A'A$ are symmetric.

$$\text{Sol. } (AA')' = (A')'(A)' = AA'$$

$$(A'A)' = (A)'(A')' = A'A$$

Hence AA' and $A'A$ both are symmetric.

Ex.2. If A and B are both symmetric, then AB is symmetric iff A and B commute.

Sol.

$$A' = A, \quad B' = B$$

$$(AB)' = B'A'$$

$$= BA$$

$= AB$ iff A and B commute.

This shows $(AB)'$ is symmetric.

Ex.3. S.T. A^2 is symmetric, if A is either symmetric or skew-symmetric.

Sol. A^2 exists only if A is square mtx.

Let $A = [a_{ij}]$, $i, j = 1, 2, \dots, n$. Then

$$A^2 = [c_{ij}]$$

$$c_{ij} = \sum_{k=1}^n a_{ik}a_{kj}$$

Case I :- When A is symmetric, then $a_{kj} = a_{jk}$.

$$\therefore c_{ij} = \sum_{k=1}^n a_{ik} a_{jk}$$

$$\therefore c_{ji} = \sum a_{jk} a_{ik}; \text{ on interchanging } i \text{ and } j.$$

\therefore Clearly, $c_{ij} = c_{ji}$, $\therefore A^2$ is symmetric.

Case II :- When A is skew-symmetric, then $a_{kj} = -a_{jk}$.

$$\therefore c_{ij} = \sum_{k=1}^n a_{ik} (-a_{jk}) = -\sum_{k=1}^n a_{ik} a_{jk}$$

$$\text{so that } c_{ji} = \sum a_{jk} a_{ik}, \text{ on interchanging } i \text{ and } j.$$

$$\text{Clearly, } c_{ij} = c_{ji}$$

Hence A^2 is again symmetric.

$\therefore A^2$ is symmetric if A is either symmetric or skew-symmetric.

Ex. 4. S.T. all positive integral powers of a symmetric matrix are symmetric.

Sol.

$$A' = A$$

$$(A^n)' = (AA \dots n \text{ times})', n \text{ be a positive integer}$$
$$= A'A' \dots n \text{ times}$$
$$= AA \dots n \text{ times} \text{ as } A' = A$$
$$= A^n; \text{ hence } A^n \text{ is symmetric.}$$

Ex. 5. S.T. all positive odd (even) integral powers of a skew-symmetric matrix are skew-symmetric (symmetric).

Sol.

$$A' = -A$$

$$(A^n)' = (AA \dots n \text{ times})'$$
$$= A'A' \dots n \text{ times}$$
$$= (-A)(-A) \dots n \text{ times. as } A' = -A.$$
$$= (-1)^n A^n$$
$$= \begin{cases} A^n, & n = \text{even} \quad \therefore A^n \text{ is symmetric.} \\ -A^n, & n = \text{odd} \quad \therefore A^n \text{ is skew-symmetric.} \end{cases}$$

Ex. 6. If A is symmetric (skew-symmetric), show that $B'AB$ is symmetric (skew-symmetric).

Sol.

Case I :- $A^T = A$ $(B'AB)' = (B)'A'(B')'$
 $= B'A'B$

Case II :- $A^T = -A$, $(B'AB)' = -B'AB$

Ex.7. If A and B are symmetric (skew-symmetric), s.t. A+B is symmetric (skew-symmetric).

Ex.8. If A be any ^{sq.} matrix, s.t. A+A' is symmetric and A-A' is skew-symmetric.

$$(A+A')' = (A') + (A)' = A' + A = (A+A')$$

$$(A-A')' = (A') - (A)' = A' - A = -(A-A').$$

Ex.9. If A, B are symmetric, s.t. AB+BA is symmetric and AB-BA is skew-symmetric.

Ex.10. Show that every square matrix can be uniquely expressed as the sum of a symmetric and a skew-symmetric matrix.

Sol.

$$A = \frac{1}{2}(A+A') + \frac{1}{2}(A-A')$$

$$(A+A')' = A' + (A)' = A' + A$$

$$(A-A')' = A' - A = -(A-A')$$

∴ A+A' is symmetric and A-A' is skew-symmetric.

Conjugate and Triangulated of matrix:-

A matrix obtained by replacing each element of a mtx A by its complex conjugate is called the conjugate mtx of A and is denoted by \bar{A} .

A matrix is said to be real iff $\bar{A} = A$.

$(\bar{A})'$ is called triangulated matrix of A.

Hermitian and Skew-Hermitian matrices:-

$A^* = [a_{ij}]$ is Hermitian iff $a_{ij} = \bar{a}_{ij} \forall i, j$
 $= \bar{a}_{ji} \forall i = j$

i.e. every diagonal element of a Hermitian mtx is real.

e.g. $\begin{bmatrix} 0 & i \\ -i & 0 \end{bmatrix}, \begin{bmatrix} 4 & 1-i \\ 1+i & 2 \end{bmatrix}$ are the examples of Hermitian mtx.

$A = [a_{ij}]$ is skew-Hermitian iff $a_{ij} = -\bar{a}_{ji} \forall i, j$.

i.e. Every diagonal element of a skew-Hermitian mtx is either a purely imaginary or zero.

e.g. $\begin{bmatrix} 0 & i \\ i & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1-i \\ -1-i & 0 \\ 2i & \end{bmatrix}$

Q. Show that $A = \begin{bmatrix} 3 & 1+2i \\ 1-2i & 2 \end{bmatrix}$ is Hermitian.

Sol. \bar{A} = conjugate of A = $\begin{bmatrix} 3 & 1-2i \\ 1+2i & 2 \end{bmatrix}$

and $A^* = (\bar{A})'$ transpose of $\bar{A} = \begin{bmatrix} 3 & 1+2i \\ 1-2i & 2 \end{bmatrix}$

Clearly, $A^* = A$; hence A is Hermitian.

Note:- The above all results of symmetric and skew-symmetric matrices are true if we replace symmetric mtx by

Hermitian matrix and skew-symmetric mtx by skew-Hermitian mtx.

Note:- Every square mtx. can be uniquely represented as the sum of a hermitian and a skew-hermitian matrix.

2. Every square mtx. can be uniquely expressed as $P + iQ$, where P and Q are hermitian.

3. If A is Hermitian (skew-hermitian) mtx, then iA is a skew-hermitian (Hermitian) mtx.

Polynomials in square matrix with scalar coefficients:

The algebra of polynomials in one square mtx A with scalar coefficients is the same as the algebra of ordinary polynomials.

For example, two parallel identities are:

$$x^2 - (\alpha + \beta)x + \alpha\beta \equiv (x - \alpha)(x - \beta)$$

$$A^2 - (\alpha + \beta)A + \alpha\beta I \equiv (A - \alpha I)(A - \beta I)$$

More generally, if

$$x^n + p_1 x^{n-1} + \dots + p_{n-1} x + p_n \equiv (x - \alpha_1)(x - \alpha_2) \dots (x - \alpha_n)$$

$$\text{then } A^n + p_1 A^{n-1} + \dots + p_{n-1} A + p_n I \equiv (A - \alpha_1 I)(A - \alpha_2 I) \dots (A - \alpha_n I).$$

Ex.1. Find the scalar solutions of the mtx equation $A^2 - 5A + 7I = 0$, and show that $\begin{bmatrix} 3 & 1 \\ -2 & 2 \end{bmatrix}$ is a non-scalar solution.

Sol. Consider the algebraic equation

$$x^2 - 5x + 7 = 0;$$

$$x = \frac{5 \pm i\sqrt{3}}{2}$$

Hence the scalar solution are $A = \frac{1}{2}(5 \pm i\sqrt{3})I$, where $I = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$

$$\text{i.e. } A = \begin{bmatrix} \frac{1}{2}(5+i\sqrt{3}) & 0 \\ 0 & \frac{1}{2}(5+i\sqrt{3}) \end{bmatrix}$$

2nd part:-

$$\text{If } A = \begin{bmatrix} 3 & 1 \\ -1 & 2 \end{bmatrix}, \text{ then } A^2 = \begin{bmatrix} 8 & 5 \\ -5 & 3 \end{bmatrix}$$

$$A^2 - 5A = \begin{bmatrix} 8 & 5 \\ -5 & 3 \end{bmatrix} - 5 \begin{bmatrix} 3 & 1 \\ -1 & 2 \end{bmatrix}$$

$$= -7 \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$= -7I$$

Hence $\begin{bmatrix} 3 & 1 \\ -1 & 2 \end{bmatrix}$ is a non-scalar solution.

Idempotent Matrix:-

Definition:- A square matrix A such that $A^2 = A$ is called idempotent. If $A^T = A$ and $A^2 = A$, then the square matrix A is called symmetric idempotent.

Theorem:- Every non-singular idempotent mtx is an identity mtx.

Proof:- A matrix A is said to be non-singular or regular if $|A| \neq 0$.

As A is idempotent so $A^2 = A$ or $AA = A$.

Now, a square mtx B of the same order as A , such that $AB = BA = I$, is called the inverse mtx of A and

is denoted by A^{-1} and exists as A is non-singular.

$$A^{-1}(AA) = A^{-1}A$$

$$\Rightarrow IA = I$$

$$\Rightarrow A = I.$$

Theorem:- If A and B are idempotent matrices, then AB is idempotent

Proof:- if A and B commute.

$$A^2 = A, B^2 = B$$

$$(AB)^2 = (AB)(AB)$$

$$= A(BA)B$$

$$= A(AB)B$$

$$= (AA)(BB)$$

$$= A^2B^2 = AB \text{ as } A \text{ and } B \text{ commute, i.e., } AB = BA.$$

Theorem:- $\therefore AB$ is idempotent.

If A is idempotent and $A+B = I$, then B is idempotent and $AB = BA = 0$.

Proof:- since $A+B = I$, $\therefore B = (I-A)$

$$B^2 = (I-A)(I-A)$$

$$= I - A + A - A^2$$

$$= I - A \quad [\because A^2 = A]$$

$$= B.$$

$\therefore B$ is an idempotent matrix.

2nd Part:-

$$A+B = I$$

$$A(A+B) = AI$$

$$A^2 + AB = A$$

$$A + AB = A$$

$$\therefore AB = 0$$

similarly $BA = 0$.

Theorem:- Show that the mtx A defined as

$$A = I_n - X(X'X)^{-1}X'$$
 is a symmetric and idempotent mtx.

$$\text{Sol.} \quad A = I_n - X(X^{-1}(X')^{-1})X'$$

$$= I_n - \{(XX^{-1})\} \{(X')^{-1}X'\}$$

$$= I_n - (I_n)(I_n)$$

$$= I_n - I_n = 0$$

Therefore $A' = A$ and $A^2 = A$.

Nilpotent Matrix:-

Definition:- If A be a nilpotent mtx such that $A^m=0$, where m is positive integer, then A is called a nilpotent matrix.

If m be the least positive integer for which $A^m=0$, then A is said to be a nilpotent matrix of index m . Thus a square mtx $A \ni A^m=0$, but $A^{m-1} \neq 0$ is a nilpotent mtx of order m , m being a positive integer.

Involutory Matrix:-

Definition:- A square mtx A is such that

$$A^2 = I \text{ or, } (I+A)(I-A) = 0$$

is called involutory. Clearly I is involutory.

Ex. Show that $A = \begin{bmatrix} ab & b \\ -a & -ab \end{bmatrix}$ is nilpotent.

Sol.

$$A^2 = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

Orthogonal matrix:-

Definition:- A square mtx A is said to be orthogonal if

$$A'A = I = AA'$$

Note:- When A is orthogonal $|A|^2 = 1$, $|A| = \pm 1$. If $|A|$ is equal to 1, then A is called a proper mtx.

Theorem:- If A and B are n -square orthogonal matrices, then AB and BA are orthogonal matrices.

Proof:- Since A and B are orthogonal matrices, we have

$$AA' = I \text{ and } BB' = I$$

$$\begin{aligned} (AB)(AB') &= (AB)(B'A') \\ &= A(BB')A' \\ &= AA' \\ &= I \end{aligned}$$

$\therefore AB$ is orthogonal, similarly BA is also orthogonal.

Ex.1. S.T. the mtx $A = \begin{bmatrix} \cos\theta & \sin\theta \\ -\sin\theta & \cos\theta \end{bmatrix}$ is orthogonal.

Sol.

$$AA' = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}; \text{ hence } A \text{ is orthogonal.}$$

Ex.2. If A is real skew-symmetric matrix such that $A^2 + I = 0$. Show that A is orthogonal.

Sol.

$$A = -A'$$

$$AA = -AA'$$

$$A^2 = -AA'$$

$$-I = -AA'$$

$$\therefore AA' = I$$

$\therefore A$ is orthogonal.

Unitary matrix:-

Definition:- A square matrix A is called unitary if $A^*A = I = AA^*$.

If A is real then $A^* = A'$, so that A is unitary if $A'A = AA' = I$.

Ex. Show that $A = \begin{bmatrix} \frac{1}{2}(1+i) & -\frac{1}{2}(1-i) \\ \frac{1}{2}(1+i) & \frac{1}{2}(1-i) \end{bmatrix}$ is unitary mtx.

$$\text{Sol. } A = \frac{1}{2} \begin{bmatrix} 1+i & 1-i \\ 1+i & 1-i \end{bmatrix}$$

$$A^* = \frac{1}{2} \begin{bmatrix} 1+i & 1-i \\ -1-i & 1+i \end{bmatrix}$$

$$AA^* = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = I$$

$\therefore A$ is unitary.

Trace (or spw) of a square matrix:-

Definition:- The sum of the elements of the principal diagonal of a square matrix is called the trace (or, spw, a german word) of the matrix.

Thus if $A = [a_{ij}]$ be a square matrix of order n , then

$$\text{trace } A = a_{11} + a_{22} + a_{33} + \dots + a_{nn} = \sum_{i=1}^n a_{ii}$$

Remark:- For the identity mtx I_n , $\text{trace } I_n = n$.

Ex. 1. Show that for any sq. mtx A, B :-

$$(i) \text{trace } (kA) = k \text{trace } (A), k \text{ being a scalar.}$$

$$(ii) \text{trace } (KA + B) = k \text{trace } (A) + \text{trace } (B).$$

Sol. (i) $A = [a_{ij}]_{n \times n}$, Then $kA = [ka_{ij}]_{n \times n}$

$$\begin{aligned} \text{trace } (kA) &= \sum_{i=1}^n k a_{ii} \\ &= k \text{trace } (A). \end{aligned}$$

(ii) $A = [a_{ij}]_{n \times n}, B = [b_{ij}]_{n \times n}$

$$KA + B = [ka_{ij} + b_{ij}]_{n \times n}$$

$$\begin{aligned} \text{trace } (KA + B) &= \sum_{i=1}^n (ka_{ii} + b_{ii}) \\ &= k \sum_{i=1}^n a_{ii} + \sum_{i=1}^n b_{ii} \end{aligned}$$

$$= k \text{trace } (A) + \text{trace } (B)$$

e.g. If $\text{trace } (A) = 20$, $\text{trace } (B) = -8$, then $\text{trace } (A + B) = 12$.

Ex.2. Show that $\text{trace } A' = \text{trace } A$.

Sol. Let $A = [a_{ij}]_{n \times n}$, $A' = [a'_{ij}]_{n \times n} = [a_{ji}]_{n \times n}$

therefore when $i=j$, we have $\text{trace}(A) = \text{trace}(A')$.

Ex.3. Show that $\text{trace}(AB) = \text{trace}(BA)$, if AB and BA co-exist.

Sol.

$$A = [a_{ij}]_{m \times n} \quad B = [b_{ij}]_{n \times m}$$

$$AB = [c_{ij}]_{m \times m} \quad ; \quad c_{ij} = \sum_{k=1}^n a_{ik} b_{kj}$$

$$\begin{aligned} \therefore \text{trace}(AB) &= \sum_{i=1}^m c_{ii} \\ &= \sum_{i=1}^m \sum_{k=1}^n a_{ik} b_{ki} \end{aligned}$$

$$BA = [d_{ij}]_{n \times n}$$

$$d_{ij} = \sum_{k=1}^m b_{ik} a_{kj}$$

$$\begin{aligned} \therefore \text{trace}(BA) &= \sum_{i=1}^n d_{ii} \\ &= \sum_{i=1}^n \sum_{k=1}^m b_{ik} a_{ki} \\ &= \sum_{k=1}^m \sum_{i=1}^n b_{ki} a_{ik}, \text{ interchanging } i \text{ and } k. \\ &= \sum_{i=1}^n \sum_{k=1}^m a_{ik} b_{ki} \end{aligned}$$

$\therefore \text{trace}(AB) = \text{trace}(BA)$.

Ex.4. S.T. $\text{trace}(AA') \geq 0$.

Sol. $A = [a_{ij}]_{m \times n}$, $A' = [a'_{ij}]_{n \times m}$

$$AA' = [c_{ij}]_{m \times m} \quad ; \quad c_{ij} = \sum_{k=1}^n a_{ik} a'_{kj}$$

$$\begin{aligned} \therefore \text{trace}(AA') &= \sum_{i=1}^m c_{ii} \\ &= \sum_{i=1}^m \sum_{k=1}^n a_{ik} a'_{ki} \\ &= \sum_{i=1}^m \sum_{k=1}^n (a_{ik})^2 \quad \text{as } a_{ik} = a'_{ki} \end{aligned}$$

Ex.5. S.T. $\text{trace}(C'AC) \stackrel{> 0}{=} \text{trace}(A)$, if C is an orthogonal mtx.

$$\text{trace}(C'AC) = \text{trace}\{C'(AC)\}$$

$$= \text{trace}\{(AC)C'\}, \text{ as } \text{trace } AB = \text{trace } BA.$$

$$= \text{trace}\{A(CC')\}, \text{ as } C \text{ is orthogonal mtx.}$$

$$= \text{trace}(A).$$

The adjoint of a square matrix:-

$$A = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{bmatrix}, \text{ Adj } A = \begin{bmatrix} A_{11} & A_{12} & \cdots & A_{1n} \\ A_{21} & A_{22} & \cdots & A_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ A_{n1} & A_{n2} & \cdots & A_{nn} \end{bmatrix}$$

Theorem:- If A is a square matrix, then

$$A(\text{adj } A) = (\text{adj } A) \cdot A = |A| \cdot I.$$

Sol. We have

The (i, j) th element of the product $A \cdot (\text{adj } A)$

= Product of the i th row of A and j th column of $\text{adj } A$

$$= a_{11} A_{j1} + a_{12} A_{j2} + \cdots + a_{1n} A_{jn}$$

$$= \begin{cases} 0 & \text{if } i \neq j \\ |A| & \text{if } i = j \end{cases}$$

Thus in the product, only the diagonal elements exist and each is equal to $|A|$ while all other elements are zero, so that

$$A \cdot (\text{adj } A) = \begin{bmatrix} |A| & 0 & 0 & \cdots & 0 \\ 0 & |A| & 0 & \cdots & 0 \\ 0 & 0 & |A| & \cdots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \cdots & |A| \end{bmatrix}$$

$$= |A| \begin{bmatrix} 1 & 0 & 0 & \cdots & 0 \\ 0 & 1 & 0 & \cdots & 0 \\ 0 & 0 & 1 & \cdots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \cdots & 1 \end{bmatrix}$$

$$= |A| \cdot I.$$

similarly, $(\text{adj } A) \cdot A = |A| \cdot I.$

Corollary 1:- If $|A| \neq 0$, we have

$$|A| \cdot |\text{adj } A| = \begin{bmatrix} |A| & 0 & \cdots & 0 \\ 0 & |A| & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & |A| \end{bmatrix} = |A|^n$$

$$\therefore |\text{adj } A| = |A|^{n-1}.$$

Corollary 2:- If $|A| \neq 0$, then

$$A \left(\frac{1}{|A|} \text{adj } A \right) = I = \left(\frac{1}{|A|} \text{adj } A \right) A.$$

Singular matrix:- A sq. matrix is said to be singular if its determinant is zero.

Theorem:- If A and B are n-square matrices, then

$$\text{Adj } AB = \text{Adj } A \cdot \text{Adj } B .$$

Sol. We have $AB \cdot (\text{Adj } AB) = |AB| \cdot I = (\text{Adj } AB) \cdot AB$

$$\begin{aligned} \text{Now, } AB \cdot (\text{Adj } B) \cdot (\text{Adj } A) &= A \cdot (B \cdot \text{Adj } B) \cdot (\text{Adj } A) \\ &= A \cdot (|B| \cdot I) \cdot (\text{Adj } A) \\ &= |B| \cdot (A \cdot \text{Adj } A) \\ &= |B| \cdot |A| \cdot I \\ &= |AB| \cdot I \end{aligned}$$

$$\begin{aligned} \text{Also, } (\text{Adj } B) \cdot (\text{Adj } A) \cdot AB &= (\text{Adj } B) [\text{Adj}(A) \cdot A] B \\ &= (\text{Adj } B) |A| \cdot IB \\ &= |A| [(\text{Adj } B) \cdot B] \\ &= |A| \cdot |B| \cdot I \\ &= |AB| \cdot I . \end{aligned}$$

$$\therefore \text{Adj}(AB) = \text{Adj}(A) \text{Adj}(B) .$$

Ex.1. Show that $\text{Adj } A' = (\text{Adj } A)'$.

Sol. Obviously, the matrices $\text{Adj } A'$ and $(\text{Adj } A)'$ both will be of the same order as A. Now,

$$\begin{aligned} \text{The } (i,j)\text{th element of } \text{Adj } A' &= \text{the co-factor of } (j,i)\text{th element of } A' \text{ in} \\ &\quad \text{the determinant } |A'| . \\ &= \text{the co-factor of } (i,j)\text{th element of } A \text{ in} \\ &\quad \text{the determinant } |A| \\ &= (j,i)\text{th element of } \text{Adj } A . \\ \therefore \text{Adj } A' &= (\text{Adj } A)' . \end{aligned}$$

Ex.2. Show that every skew-symmetric matrix of odd order is singular.

Solution:- Let A be a skew-symmetric matrix of order n, where n is odd. Since A is skew-symmetric, we have

$$A' = -A .$$

$$\begin{aligned} |A'| &= |-A| \\ &= (-1)^n |A| \\ &= -|A| , \text{ where } n \text{ is odd and } |A'| = |A| \end{aligned}$$

$$\therefore |A| = -|A|$$

$$\therefore 2|A| = 0$$

$$\Rightarrow |A| = 0 .$$

Hence a skew-symmetric matrix of odd order is singular.

WORKED EXAMPLES:-

1. Let A be a non-singular sq. mtx of order 3. If B is the mtx obtained from A by adding 3-multiple of its first row to its second row, then the value of $\det(2A^{-1}B)$ is

(A) 8 (B) 3 (C) 6 (D) 2

Sol. (D) $A = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix}$

$$|A| \neq 0,$$

$$A \sim B = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ 3a_{11} + a_{21} & 3a_{12} + a_{22} & 3a_{13} + a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix}$$

Since A and B are equivalent so $|A|=|B|$

$$\begin{aligned} \therefore \det(2A^{-1}B) &= 2|A^{-1}| |B| \\ &= 2 \cdot \frac{1}{|A|} \cdot |B| \\ &= 2. \end{aligned}$$

2. Let u be a unit column vector and $A = I - 2uu^T$. Then A^{-1} is

(A) $I - 2uu^T$ (B) $I + 2uu^T$ (C) $2uu^T - I$ (D) $4uu^T$.

Sol.

$$\begin{aligned} A &= \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} - 2 \cdot [1 \ 1 \ 1] \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \\ &= \begin{bmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix} \end{aligned}$$

$$A^{-1} = \begin{bmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix} = I - 2uu^T.$$

3. Let P, Q, R be matrices of order $3 \times 5, 5 \times 7, 7 \times 3$ respectively. The number of scalar additions required to compute $P(QR)$ is

(A) 114 (B) 126 (C) 128 (D) 138.

Sol. We have to calculate $P(QR)$.

Q and R is of order 5×7 and 7×3 respectively. When we multiply it we have to make 6 scalar addition for each entry so 5 column in Q and 3 rows in R then we multiply Q and R .

We do $6 \times 5 \times 3 = 90$ addition further QR is of 5×3 matrix.

Similarly when we multiply P to QR we perform $4 \times 3 \times 3$ addition

\therefore Total no. of additions $= 90 + 36 = 126$.

4. If A is a square matrix and $A - \frac{1}{2}I$ and $A + \frac{1}{2}I$ are orthogonal, prove that A is skew-symmetric & $A^2 = -\frac{3}{4}I$.

Sol. Since $A - \frac{1}{2}I$ is orthogonal,

$$\text{so, } (A - \frac{1}{2}I)(A - \frac{1}{2}I)^T = I$$

$$\text{or, } (A - \frac{1}{2}I)(A' - \frac{1}{2}I) = I$$

$$\text{or, } AA' - \frac{1}{2}IA' - \frac{1}{2}AI + \frac{1}{4}I^2 = I$$

$$\text{or, } AA' - \frac{1}{2}A' - \frac{1}{2}A = \frac{3}{4}I \quad \text{--- (1)}$$

Similarly since $A + \frac{1}{2}I$ is orthogonal, we have

$$AA' + \frac{1}{2}A' + \frac{1}{2}A = \frac{3}{4}I. \quad \text{--- (2)}$$

\therefore (1) & (2) gives $A' + A = 0$

$$(1) - (2) \Rightarrow A' = -A$$

$\therefore A$ is skew-symmetric.

$$(1) + (2) \text{ gives } 2AA' = \frac{3}{2}I$$

$$\therefore 2A(-A) = \frac{3}{2}I$$

$$\therefore A^2 = -\frac{3}{4}I.$$

5. If $A = \begin{bmatrix} 1+i & 2-3i & 2 \\ 3-4i & 4+5i & 1 \\ 5 & 3 & 3-i \end{bmatrix}$, find the conjugate of matrix A ?

Sol. $\bar{A} = \begin{bmatrix} 1-i & 2+3i & 2 \\ 3+4i & 4-5i & 1 \\ 5 & 3 & 3+i \end{bmatrix}$

6. Let P and Q be two $n \times n$ non-zero matrices $\exists P+Q=0$, then show that, (i) P is non-singular

(ii) $P = Q^T$

(iii) $P = Q^{-1}$

(iv) $\text{Rank}(P) = \text{Rank}(Q)$.

Sol. Given that P and Q are two $n \times n$ matrices such that $P+Q=0$.

$$\therefore P+Q=0 \Rightarrow P=-Q$$

$$\Rightarrow |P|=|Q|$$

$$\Rightarrow |P| \neq 0 \text{ iff } |Q| \neq 0$$

i.e. P is non-singular iff Q is non-singular.

If Q is non-singular then Q^{-1} exists. $|Q^{-1}| = |Q^T| = |Q|$

$$\therefore P = Q^T = Q^{-1}.$$

But if $P+Q=0$ then $\text{Rank}(P) = \text{Rank}(Q)$.

Example 1- $P = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \Rightarrow Q = \begin{bmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix}$

Then $P+Q=0$ and $\text{Rank}(P) = \text{Rank}(Q)$.

7. Show that all $n \times n$ symmetric matrices over \mathbb{F} form a vector space of dimension $\frac{n(n+1)}{2}$ over \mathbb{F} . What is the dimension of the space of skew-symmetric matrices?

Sol.

Let $A = (a_{ij})$ be an $n \times n$ symmetric matrix.
 Then $a_{ij} = a_{ji} \forall i \neq j$. Thus the number of independent entries are a_{ij} ($i < j$) and a_{ij} ($1 \leq i \leq n$) and there are $\frac{n(n-1)}{2} + n = \frac{n(n+1)}{2}$ in number.

Hence the space has dimension $\frac{n(n+1)}{2}$.

For a skew-symmetric matrix, $a_{ij} = 0, 1 \leq i \leq n, \forall i = j$ and $a_{ij} = -a_{ji}$.
 Then the number of LIN entries are $\frac{n(n-1)}{2}$ which is also the dimension of the space of skew-symmetric matrices.

8. (a) If A is a real skew-symmetric matrix and $A^2 + I = 0$, then S.T. A is orthogonal.

(b) If H is Hermitian matrix, what kind of matrix is e^{iH} ?

Sol. (a) Let A be the real skew-symmetric matrix.

then $A^T = -A$.

Also we have $A^2 + I = 0$.

We have $A^T A = (-A)(A) = I$.

$\therefore A$ is orthogonal.

(b) Let H is Hermitian matrix. $H^* = H$.

for any matrix M , $(e^M)^* = e^{M^*}$

Let $e^{iH} = A$

Then $A^* A = (e^{iH})^* \cdot e^{iH}$
 $= I$.

Hence e^{iH} is unitary matrix.

Inverse or Reciprocal of a matrix:-

Let A be a square matrix of order n . Then the mtx B of order n , if it exists, such that

$$AB = BA = I_n,$$

is called the inverse or reciprocal of A and is denoted by A^{-1} .

$$A^{-1} = \left(\frac{\text{Adj } A}{|A|} \right) * I, \text{ provided } |A| \neq 0.$$

Corollary! We have $|A| |A^{-1}| = |AA^{-1}| = |I| = 1$

$$\therefore |A^{-1}| = |A|^{-1}.$$

Theorem! - the inverse of a matrix is unique.

Sol. If possible let B and C be two inverses of the same mtx A , then by definition

$$AB = BA = I$$

$$AC = CA = I$$

$$1. C(AB) = CI = C$$

$$\therefore (CA)B = IB = B$$

$\therefore C = B$, \therefore the inverse is unique.

Theorem! - A square matrix A has an inverse if and only if $|A| \neq 0$, i.e. only a non-singular matrix has an inverse.

Proof! - the condition is necessary. Let B be the inverse of the mtx A .

$$\text{then } AB = I$$

$$\text{so, that } |A||B| = |I| = 1$$

$$\therefore |A| \neq 0.$$

2. the condition is sufficient.

Let $|A| \neq 0$, we assume that $B = \frac{\text{Adj } A}{|A|}$

$$\therefore AB = A \left(\frac{\text{Adj } A}{|A|} \right)$$

$$= \frac{1}{|A|} \cdot (A \cdot \text{Adj } A)$$

$$= \frac{|A| \cdot I}{|A|} = I$$

Similarly $BA = I$.

$\therefore AB = BA = I$, \therefore Hence A has an inverse.

Ex. 1 Find A^{-1} when $A = \begin{bmatrix} 1 & 0 & -1 \\ 3 & 4 & 5 \\ 0 & 6 & -7 \end{bmatrix}$.

Sol. $|A| = 20$; $\text{Adj } A = \begin{bmatrix} 6 & 4 \\ -7 & -8 \\ -18 & 6 \end{bmatrix}$

Hence $A^{-1} = \frac{\text{Adj } A}{|A|} = \begin{bmatrix} \frac{6}{20} & \frac{4}{20} & \frac{-1}{20} \\ \frac{-7}{20} & \frac{-8}{20} & \frac{-8}{20} \\ \frac{-18}{20} & \frac{6}{20} & \frac{4}{20} \end{bmatrix}$

Ex. 2. Show that the inverse of a regular symmetric (hermitian) matrix is symmetric (hermitian).

Sol. Let A be symmetric, so that $A' = A$

$$\& AA^{-1} = I = A^{-1}A$$

$$\text{since } I = I', \text{ so, } A^{-1}A = (A^{-1}A)'$$

$$\begin{aligned} AA^{-1} &= (A^{-1}A)' \\ &= A' \cdot (A^{-1})' \\ &= A(A^{-1})' \end{aligned}$$

$$\therefore A^{-1} = (A^{-1})'$$

$\therefore A^{-1}$ is symmetric.

2nd Part:- Let A be hermitian, so that

$$A^* = A$$

$$A^{-1}A = AA^{-1} = I$$

$$\therefore (A^{-1}A)^* = I^* = I = (AA^{-1})$$

$$\& A^*(A^{-1})^* = AA^{-1}$$

$$\therefore A(A^{-1})^* = AA^{-1}$$

$$\therefore (A^{-1})^* = A^{-1}$$

$\therefore A^{-1}$ is hermitian.

Ex. 3. find the inverse of $A = \begin{bmatrix} 0 & 1 & 2 & 2 \\ -1 & 1 & 2 & 3 \\ 2 & 2 & 2 & 3 \\ 2 & 3 & 3 & 3 \end{bmatrix}$.

Sol.

$$\boxed{A = I \times A}$$

$$\begin{bmatrix} 0 & 1 & 2 & 2 \\ 1 & 1 & 2 & 3 \\ 2 & 2 & 2 & 3 \\ 2 & 3 & 3 & 3 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} A$$

$$\begin{bmatrix} 1 & 1 & 0 & 2 \\ 0 & 1 & 1 & 3 \\ 0 & 2 & 1 & 3 \\ 1 & 3 & 0 & 3 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} A \quad \left[\begin{array}{l} c_1' \leftrightarrow c_2 - c_1 \\ c_3' \leftrightarrow c_4 - c_3 \end{array} \right]$$

$$\begin{bmatrix} 1 & 1 & 0 & 2 \\ 0 & 1 & 0 & 0 \\ 0 & 2 & 1 & 3 \\ 1 & 1 & -1 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ -1 & -1 & 1 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} A \quad \left[\begin{array}{l} R_2' \leftrightarrow R_3 - R_2 \\ R_4' \leftrightarrow R_4 - R_3 \end{array} \right]$$

$$\begin{bmatrix} 1 & 1 & 0 & 2 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 3 \\ 0 & 0 & -1 & -2 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ -1 & -1 & 1 & 0 \\ 2 & 2 & -1 & 0 \\ -1 & 0 & 0 & 1 \end{bmatrix} A \quad \left[\begin{array}{l} R_4' \leftrightarrow R_4 - R_1 \\ R_3' \leftrightarrow R_3 - 2R_2 \end{array} \right]$$

$$\begin{bmatrix} 1 & 0 & 0 & 2 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 3 \\ 0 & 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 2 & 1 & -1 & 0 \\ -1 & -1 & 1 & 0 \\ 2 & 2 & -1 & 0 \\ 1 & 2 & -1 & 1 \end{bmatrix} A \quad \left[\begin{array}{l} R_4' = R_4 + R_3 \\ R_1' = R_1 - R_2 \end{array} \right]$$

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 0 & -3 & 1 & -2 \\ -1 & -1 & 1 & 0 \\ -1 & -4 & 2 & -3 \\ 1 & 2 & -1 & 1 \end{bmatrix} A \quad \left[\begin{array}{l} R_1' = R_1 - 2R_4 \\ R_3' = R_3 - 3R_4 \end{array} \right]$$

$$I = A^{-1} A$$

$$\therefore A^{-1} = \begin{bmatrix} 0 & -3 & 1 & -2 \\ -1 & -1 & 1 & 0 \\ -1 & -4 & 2 & -3 \\ 1 & 2 & -1 & 1 \end{bmatrix}$$

Rank and Nullity of a matrix:-

The maximum order of the non-singular square sub-matrix of A is called the rank of A. The mtx A is said to be of rank n, if and only if it has at least one nonsingular square sub-mtx of order n and all square submatrices of (n+1) and higher orders are singular. The rank of a mtx A is denoted by rank(A).

If A is a square mtx of order n, then n - rank(A) is called the nullity of the mtx A and denoted by N(A).

Remarks:-

1. If I is a unit mtx of order n, rank(I)=n.

2. If A is of order mxn, then rank(A) ≤ m and ≤ n.

3. If A' is the transpose of A, rank(A')=rank(A).

Ex. S.T. the rank of a skew-symmetric mtx can't be 1.

Sol. For a skew-symmetric mtx, the elements of the leading diagonal are all zero. If one element is non-zero, say x, then we have a minor of the form $\begin{vmatrix} 0 & x \\ -x & 0 \end{vmatrix} \neq 0$

Therefore rank of the mtx is ≥ 2. If all entries are zero then rank is 0.

Ex. 2. Find the rank of the mtrix A, where $A = \begin{bmatrix} 2 & 1 & -1 \\ 0 & 3 & -2 \\ 2 & 4 & -3 \end{bmatrix}$.

Sol.

$$|A| = 2(-9+8) + 2(-3+4) = 0$$

But $\begin{vmatrix} 2 & 1 \\ 0 & 3 \end{vmatrix} \neq 0$, so $\text{rank}(A) = 2$.

Normal form of a matrix:-

Theorem:- By means of elementary transformations every mtrix A of order $m \times n$ and rank $r (> 0)$ can be reduced to the following form:

- (i) $\left[\begin{array}{c|c} I_n & 0 \\ \hline 0 & 0 \end{array} \right]$
- (ii) $\left[\begin{array}{c|c} I_n & 0 \\ \hline 0 & 0 \end{array} \right]$
- (iii) $\left[\begin{array}{c|c} I_n & 0 \\ \hline 0 & 0 \end{array} \right]$
- (iv) $\left[\begin{array}{c|c} I_n & 0 \\ \hline 0 & 0 \end{array} \right]$

Ex. Reduce the mtrix A to its normal form, where $A = \begin{bmatrix} 1 & 1 & 1 & -1 \\ 1 & 2 & 3 & 4 \\ 3 & 4 & 5 & 2 \end{bmatrix}$ and hence determine its rank.

Solution:-

$$\begin{aligned} & \left[\begin{array}{cccc} 1 & 1 & 1 & -1 \\ 1 & 2 & 3 & 4 \\ 3 & 4 & 5 & 2 \end{array} \right] \\ & \sim \left[\begin{array}{cccc} 1 & 1 & 1 & -1 \\ 0 & 1 & 2 & 5 \\ 0 & 1 & 2 & 5 \end{array} \right] \quad R_2' \leftrightarrow R_2 - R_1 \\ & \sim \left[\begin{array}{cccc} 1 & 1 & 1 & -1 \\ 0 & 1 & 2 & 5 \\ 0 & 0 & 0 & 0 \end{array} \right] \quad R_3' \leftrightarrow R_3 - 3R_1 \\ & \sim \left[\begin{array}{cccc} 1 & 0 & -1 & -6 \\ 0 & 1 & 2 & 5 \\ 0 & 0 & 0 & 0 \end{array} \right] \quad R_1' \leftrightarrow R_1 - R_2 \\ & \sim \left[\begin{array}{cccc} 1 & 0 & 0 & -6 \\ 0 & 1 & 0 & 5 \\ 0 & 0 & 0 & 0 \end{array} \right] \quad C_3' \leftrightarrow C_3 + C_1 \\ & \sim \left[\begin{array}{cccc} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right] \quad C_3' \leftrightarrow C_3 - 2C_2 \\ & \sim \left[\begin{array}{cccc} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right] \quad C_4' \leftrightarrow C_4 + 6C_1 \\ & \sim \left[\begin{array}{cccc} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right] \quad C_4' \leftrightarrow C_4 - 5C_2 \end{aligned}$$

Hence the normal form of A is
and $\text{rank}(A) = 2$.

$$\left[\begin{array}{c|c} I_2 & 0 \\ \hline 0 & 0 \end{array} \right]$$

WORKED EXAMPLES:-

1. If $r(A)$ denotes rank of a mtx A, then $r(AB)$ is
 (a) $r(A)$ (b) $r(B)$ (c) $\leq \min[r(A), r(B)]$ (d) $> \min[r(A), r(B)]$

Sol: $\text{rank}(AB) \leq \min[r(A), r(B)]$

e.g. $A = \begin{bmatrix} 1 & 2 \\ 1 & 2 \end{bmatrix}, B = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$
 $AB = \begin{bmatrix} 7 & 10 \\ 7 & 10 \end{bmatrix} \quad \text{rank}(A) = 1, \text{rank}(B) = 2,$
 $\text{rank}(AB) = 1 \leq \min[r(A), r(B)]$.

2. Show that $\text{rank}(A') = \text{rank}(A^*) = \text{rank}(A)$.

Sol. The transpose of a mtx is obtained by interchanging rows into columns into rows, and clearly this change does not alter the values of the determinants of minors. Hence

$$\text{rank}(A') = \text{rank}(A).$$

Now assume that the value of a minor of A with complex elements be $a+ib$. Then the value of the corresponding minor of the conjugate mtx of A be $a-ib$.

In case $a+ib=0$ then $a-ib=0$.

In case $a+ib \neq 0$ then $a-ib \neq 0$.

$$\text{Hence } \text{rank}(A^*) = \text{rank}(A) = \text{rank}(A').$$

3. If A is an $(n \times 1)$ non-zero mtx and B is a $(1 \times n)$ non-zero mtx, then show that $\text{rank}(AB)=1$.

Sol. Let $A = \begin{bmatrix} a_{11} \\ a_{21} \\ \vdots \\ a_{n1} \end{bmatrix}$, and $B = [b_{11} \ b_{12} \ \dots \ b_{1n}]$.

$$\text{Then } AB = \begin{bmatrix} a_{11}b_{11} & a_{11}b_{12} \dots a_{11}b_{1n} \\ a_{21}b_{11} & a_{21}b_{12} \dots a_{21}b_{1n} \\ \vdots & \vdots \\ a_{n1}b_{11} & a_{n1}b_{12} \dots a_{n1}b_{1n} \end{bmatrix}$$

AB is non-zero and there will be at least one non-zero minor of order 1.

Hence, $\text{rank}(AB)=1$ because all 2nd and higher order minors are all zero here.

4. Find the rank of the matrix $A = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 3 & -2 & 1 \\ 2 & 0 & -3 & 2 \\ 3 & 3 & 0 & 3 \end{bmatrix}$

Solution:-

$$A = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 3 & -2 & 1 \\ 2 & 0 & -3 & 2 \\ 3 & 3 & 0 & 3 \end{bmatrix}$$

$$\sim \begin{bmatrix} 1 & 1 & 1 & 0 \\ 1 & 3 & -2 & 0 \\ 2 & 0 & -3 & 0 \\ 3 & 3 & 0 & 0 \end{bmatrix} \quad c_4' \leftrightarrow c_4 - c_1$$

$\therefore \text{rank}(A) = \text{No. of LIN columns in } A$

$\therefore 3.$

5. Reduce the mtx/A to its normal form where
and hence find the rank of the mtx.

$$A = \begin{bmatrix} 0 & 1 & -3 & -1 \\ 1 & 0 & 1 & 1 \\ 3 & 1 & 0 & 2 \\ 1 & 1 & -2 & 0 \end{bmatrix}$$

Solution:-

$$A = \begin{bmatrix} 0 & 1 & -3 & -1 \\ 1 & 0 & 1 & 1 \\ 3 & 1 & 0 & 2 \\ 1 & 1 & -2 & 0 \end{bmatrix}$$

$$\sim \begin{bmatrix} 0 & 1 & -3 & -1 \\ 1 & 0 & 1 & 1 \\ 3 & 1 & 0 & 2 \\ 0 & 0 & 0 & 0 \end{bmatrix} \quad R_4' \leftrightarrow R_4 - (R_1 + R_2)$$

$$\sim \begin{bmatrix} 0 & 1 & -3 & -1 \\ 0 & 0 & 1 & 1 \\ 0 & 1 & 0 & 2 \\ 0 & 0 & 0 & 0 \end{bmatrix} \quad C_1' \leftrightarrow C_1 - (C_2 + C_4)$$

$$\sim \begin{bmatrix} 1 & -1 & -3 & 0 \\ 0 & 1 & 1 & 0 \\ 1 & 2 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\sim \begin{bmatrix} 1 & 0 & -3 & 0 \\ 0 & 1 & 1 & 0 \\ 1 & 3 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \quad C_2' = C_1 + C_2$$

5. Reduce the matrix A to its normal form, where

$$A = \begin{bmatrix} 1 & 1 & 1 & -1 \\ 1 & 2 & 3 & 4 \\ 3 & 4 & 5 & 2 \end{bmatrix}$$

and hence determine its rank.

Sol. To reduce a mtx into its normal form, let us use congruent row and column operations.

$$A \sim \begin{bmatrix} 1 & 1 & 1 & -1 \\ 0 & 2 & 2 & 5 \\ 3 & 4 & 5 & 2 \end{bmatrix} \quad \text{By } R_{21}(-1)$$

$$\sim \begin{bmatrix} 1 & 1 & 1 & -1 \\ 0 & 1 & 2 & 5 \\ 0 & 1 & 2 & 5 \end{bmatrix} \quad \text{By } R_{31}(-3)$$

$$\sim \begin{bmatrix} 1 & 0 & 1 & -1 \\ 0 & 1 & 2 & 5 \\ 0 & 1 & 2 & 5 \end{bmatrix} \quad \text{By } C_{21}(-1)$$

$$\sim \begin{bmatrix} 1 & 0 & 0 & -1 \\ 0 & 1 & 2 & 5 \\ 0 & 1 & 2 & 5 \end{bmatrix} \quad \text{By } C_{31}(-1)$$

$$\sim \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 2 & 5 \\ 0 & 1 & 2 & 5 \end{bmatrix} \quad \text{By } C_{41}(1)$$

$$\sim \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 2 & 5 \\ 0 & 0 & 0 & 0 \end{bmatrix} \quad \text{By } R_{32}(-1)$$

$$\sim \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 5 \\ 0 & 0 & 0 & 0 \end{bmatrix} \quad \text{By } C_{32}(-1)$$

$$\sim \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \quad \text{By } C_{42}(5)$$

Hence the normal form of A is $\left[\begin{array}{c|c} I_2 & 0 \\ \hline 0 & 0 \end{array} \right]$ and $\text{rank}(A) = 2$.

6. Reduce the matrix A to its normal form, where

$$A = \begin{bmatrix} 0 & 1 & -3 & -1 \\ 1 & 0 & 1 & 1 \\ 3 & 1 & 0 & 2 \\ 1 & 1 & -2 & 0 \end{bmatrix}$$

and hence find the rank of the matrix.

Solution:- By performing the operation R_{12} , we have

$$A \sim \begin{bmatrix} 1 & 0 & 1 & 1 \\ 0 & 1 & -3 & -1 \\ 3 & 1 & 0 & 2 \\ 1 & 1 & -2 & 0 \end{bmatrix}$$

By $R_{31}(-3)$, $R_{41}(-1)$ $A \sim \begin{bmatrix} 1 & 0 & 1 & 1 \\ 0 & 1 & -3 & -1 \\ 0 & 1 & -3 & -1 \\ 0 & 1 & -3 & -1 \end{bmatrix}$

By $C_{31}(-1)$, $C_{41}(-1)$ $A \sim \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & -3 & -1 \\ 0 & 1 & -3 & -1 \\ 0 & 1 & -3 & -1 \end{bmatrix}$

By $R_{32}(-1)$, $\cancel{R_{42}(-1)}$ $A \sim \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & -3 & -1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$

By $C_{32}(3)$, $C_{42}(1)$, $A \sim \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$

which is of the form $\left[\begin{array}{c|cc} I_2 & 0 \\ \hline 0 & 0 \end{array} \right]$; hence $\text{rank}(A) = 2$.

~~~~~ . ~~~~~

# System of Linear Equations

1. The equations

$$x - y + 2z = 4$$

$$3x + y + 4z = 6$$

$$x + y + z = 1 \quad \text{have}$$

- (A) Unique solution    (B) Infinite solutions    (C) No solution    (D) None.

Sol. →

$$(B) [A|b] = \left[ \begin{array}{ccc|c} 1 & -1 & 2 & 4 \\ 3 & 1 & 4 & 6 \\ 1 & 1 & 1 & 1 \end{array} \right]$$

$$\sim \left[ \begin{array}{ccc|c} 1 & -1 & 2 & 4 \\ 0 & 4 & -2 & -6 \\ 0 & 2 & -1 & -3 \end{array} \right]$$

$$\sim \left[ \begin{array}{ccc|c} 1 & -1 & 2 & 4 \\ 0 & 4 & -2 & -6 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

$$\therefore \text{rank } [A|b] = \text{rank } (A) = 2 < 3$$

∴ it has infinite solutions.

2. The system of linear equations  $x + y + z = 2$ ,  $2x + y - z = 3$ ,  $3x + 2y + kz = 4$  has a unique solution if

- (A)  $k=0$     (B)  $k \neq 1$     (C)  $k=1$     (D)  $k \neq 0$ .

Sol.

$$[A|b] = \left[ \begin{array}{ccc|c} 1 & 1 & 1 & 2 \\ 2 & 1 & -1 & 3 \\ 3 & 2 & k & 4 \end{array} \right] \sim \left[ \begin{array}{ccc|c} 1 & 1 & 1 & 2 \\ 0 & -1 & -3 & -1 \\ 0 & -1 & k-3 & -2 \end{array} \right]$$

$$\sim \left[ \begin{array}{ccc|c} 1 & 1 & 1 & 2 \\ 0 & -1 & -3 & -1 \\ 0 & 0 & k-3 & -1 \end{array} \right]$$

$$\therefore k \neq 0$$

AH. method:-

Given system has a unique solution if

$$\left| \begin{array}{ccc} 1 & 1 & 1 \\ 2 & 1 & -1 \\ 3 & 2 & k \end{array} \right| \neq 0$$

$$\Rightarrow k \neq 0$$

### 3. The system of equations

$$2x + y = 5$$

$$x - 3y = -1$$

$$3x + 4y = k$$

is consistent, when  $k$  is

$$(A) 1$$

$$(B) 2$$

$$(C) 5$$

$$(D) 10$$

Sol.

$$(D) [A|B] = \left[ \begin{array}{cc|c} 2 & 1 & 5 \\ 1 & -3 & -1 \\ 3 & 4 & k \end{array} \right]$$

$$A = \left[ \begin{array}{cc} 2 & 1 \\ 1 & -3 \\ 3 & 4 \end{array} \right] \sim \left[ \begin{array}{cc} 2 & 1 \\ 1 & -3 \\ 3 & 4 \end{array} \right]$$

$$\text{rank}(A) = 2$$

$$\text{Det}[A|B] = -7k + 70$$

$\therefore$  the system is consistent if  $\text{Det}[A|B] = 0$

$$\Rightarrow -7k = 70$$

$$\Rightarrow k = 10.$$

4. S.T. the S.O.E.s  $\left. \begin{array}{l} x_1 - 2x_2 + x_3 - x_4 + 1 = 0 \\ 3x_1 - 2x_3 + 3x_4 + 4 = 0 \\ 5x_1 - 4x_2 + x_4 + 3 = 0 \end{array} \right\}$  is inconsistent.

Sol. Here, we have

$$A = \left[ \begin{array}{cccc} 1 & -2 & 1 & -1 \\ 3 & 0 & -2 & 3 \\ 5 & -4 & 0 & 1 \end{array} \right], [A:b] = \left[ \begin{array}{cccc|c} 1 & -2 & 1 & -1 & 1 \\ 3 & 0 & -2 & 2 & -1 \\ 5 & -4 & 0 & 1 & -3 \end{array} \right]$$

By elementary transformations,  $A$  and  $[A:b]$  can be reduced in the following forms:

$$A \sim \left[ \begin{array}{cccc} 1 & 0 & \frac{1}{6} & 1 \\ 0 & 1 & -\frac{5}{6} & 1 \\ 0 & 0 & 0 & 0 \end{array} \right], [A:b] \sim \left[ \begin{array}{cccc|c} 1 & 0 & \frac{1}{6} & 1 & -4/3 \\ 0 & 1 & -\frac{5}{6} & 1 & -1/6 \\ 0 & 0 & 0 & 0 & 3 \end{array} \right]$$

$$\therefore \text{rank}(A) = 2 \text{ but } \text{rank}(A:b) = 3$$

so, the equations are inconsistent.

5. Find the rank of the matrix  $A = \left[ \begin{array}{cccc} 1 & a & b & 0 \\ 0 & c & d & 1 \\ 1 & a & b & 0 \\ 0 & c & d & 1 \end{array} \right]$ .

Sol.

$$A \sim \left[ \begin{array}{cccc} 1 & a & b & 0 \\ 0 & c & d & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

$$\therefore \text{rank}(A) = 2.$$

6. Find the inverse of the matrix

$$\begin{bmatrix} 1 & 2 & 1 \\ 3 & 2 & 3 \\ 1 & 1 & 2 \end{bmatrix}$$

Sol.  $A = I_3 A$

Applying E-norm transformation to the matrix applying  $R_2 \rightarrow R_2 - 3R_1$ ,  
 $R_3 \rightarrow R_3 - R_1$ .

$$\begin{bmatrix} 1 & 2 & 1 \\ 0 & 2 & 0 \\ 0 & -1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ -3 & 1 & 0 \\ -1 & 0 & 1 \end{bmatrix} A$$

$$R_2 \rightarrow -\frac{1}{4}R_2$$

$$\begin{bmatrix} 1 & 2 & 1 \\ 0 & 1 & 0 \\ 0 & -1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ \frac{3}{4} & \frac{1}{4} & 0 \\ -1 & 0 & 1 \end{bmatrix} A$$

$$R_1 \rightarrow R_1 - 2R_2, R_3 \rightarrow R_3 + R_2$$

$$\begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} -\frac{1}{2} & \frac{1}{2} & 0 \\ \frac{3}{4} & -\frac{1}{4} & 0 \\ -\frac{1}{4} & -\frac{1}{4} & 1 \end{bmatrix} A$$

$$R_1 \rightarrow R_1 - R_3$$

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} -\frac{1}{4} & \frac{3}{4} & -1 \\ \frac{3}{4} & -\frac{1}{4} & 0 \\ -\frac{1}{4} & -\frac{1}{4} & 1 \end{bmatrix} A$$

$$\therefore I_3 = BA$$

$$\therefore A^{-1} = B.$$

$$\therefore A^{-1} = B = \begin{bmatrix} -\frac{1}{4} & \frac{3}{4} & -1 \\ \frac{3}{4} & -\frac{1}{4} & 0 \\ -\frac{1}{4} & -\frac{1}{4} & 1 \end{bmatrix}$$

$$\begin{aligned}
 7. \quad & \text{Solve: } x_1 - x_2 + x_3 = 2 \\
 & 3x_1 - x_2 + 2x_3 = -6 \\
 & 3x_1 + x_2 + x_3 = -18
 \end{aligned}$$

Sol. Here, we have  $A = \begin{bmatrix} 1 & -1 & 1 \\ 3 & -1 & 2 \\ 3 & 1 & 1 \end{bmatrix}$  and  $B = \begin{bmatrix} 1 & -1 & 1 & 2 \\ 3 & -1 & 2 & -6 \\ 3 & 1 & 1 & -18 \end{bmatrix}$

$$\text{Now, } |A| = 1(-1-2) + 1(3-6) + 1(3+3) = 0.$$

$$\text{Also, } \begin{vmatrix} 1 & -1 \\ 3 & -1 \end{vmatrix} \neq 0; \text{ hence rank}(A) = 2.$$

We now proceed to reduce matrix B to its Echelon form

$$\text{by } R_{21}(-3), R_{31}(-3),$$

$$B \sim \begin{bmatrix} 1 & -1 & 1 & 2 \\ 0 & 2 & -1 & -12 \\ 0 & 4 & -2 & -24 \end{bmatrix}$$

$$\text{By } R_{32}(-2),$$

$$B \sim \begin{bmatrix} 1 & -1 & 1 & 2 \\ 0 & 2 & -1 & -12 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\text{By } R_1(1/2)$$

$$B \sim \begin{bmatrix} 1 & -1 & 1 & 2 \\ 0 & 1 & -1/2 & -6 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\therefore \text{rank}(B) = 2 = \text{rank}(A).$$

Hence the given equations are consistent.

Also the mtix equation becomes

$$\begin{bmatrix} 1 & -1 & 1 \\ 0 & 1 & -1/2 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 2 \\ -6 \\ 0 \end{bmatrix}$$

$$\therefore \begin{cases} x_1 - x_2 + x_3 = 2 \\ x_2 - 1/2 x_3 = -6 \end{cases} \quad \begin{array}{l} \therefore x_1 = -1/2 x_3 - 4, \\ x_2 = 1/2 x_3 - 6. \end{array}$$

and  $x_1, x_2$  can be expressed in terms of  $x_3$  which is arbitrary. Since the rank is 2, two unknowns  $x_1, x_2$  are expressed in terms of  $x_3$ , the system has ~~finite~~ infinite number of solutions.

8. Find two non-singular matrices P and Q such that  $PAQ$  is in the normal form where

$$A = \begin{bmatrix} 1 & 1 & 1 \\ 1 & -1 & -1 \\ 3 & 1 & 1 \end{bmatrix}. \text{ Also find the rank of the matrix A.}$$

Solution:-

$$A = I_3 A I_3$$

$$\begin{bmatrix} 1 & 1 & 1 \\ 1 & -1 & -1 \\ 3 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} A \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

E-operations on the matrix A (left hand equation) until it is reduced to the normal form.  
 Every E-type operation will also be applied to the pre-factors  $I_3$  of the product on the right hand member of the above equation and every column operation to the factors  $I_3$ .

Applying  $R_2 \rightarrow R_2 - R_1, R_3 \rightarrow R_3 - 3R_1$

$$\begin{bmatrix} 1 & 1 & 1 \\ 0 & -2 & -2 \\ 0 & -2 & -2 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ -3 & 0 & 1 \end{bmatrix} A \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Performing  $C_2 \rightarrow C_2 - C_1, C_3 \rightarrow C_3 - C_1$

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & -2 & -2 \\ 0 & -2 & -2 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ -3 & 0 & 1 \end{bmatrix} A \begin{bmatrix} 1 & -1 & -1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Performing  $R_2 \rightarrow -\frac{1}{2}R_2$

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & -2 & -2 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ \frac{1}{2} & -\frac{1}{2} & 0 \\ -3 & 0 & 1 \end{bmatrix} A \begin{bmatrix} 1 & -1 & -1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Performing  $R_3 \rightarrow R_3 + 2R_2$

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ \frac{1}{2} & -\frac{1}{2} & 0 \\ -2 & -1 & 1 \end{bmatrix} A \begin{bmatrix} 1 & -1 & -1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Performing  $C_3 \rightarrow C_3 - C_2$

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ \frac{1}{2} & -\frac{1}{2} & 0 \\ -2 & -1 & 1 \end{bmatrix} A \begin{bmatrix} 1 & -1 & 0 \\ 0 & 1 & -1 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix} I_2 & 1 & 0 \\ 0 & 1 & 0 \end{bmatrix} = P A Q, \text{ where }$$

$$P = \begin{bmatrix} \frac{1}{2} & 0 & 0 \\ -2 & -1 & 1 \end{bmatrix}, Q = \begin{bmatrix} 1 & -1 & 0 \\ 0 & 1 & -1 \\ 0 & 0 & 1 \end{bmatrix}$$

$\therefore \text{Rank}(A) = 2.$

## EIGEN VALUES & VECTORS

---

### Eigen Values:-

Let  $A = [a_{ij}]_{n \times n}$  be any square matrix of order  $n$  and  $\lambda$  be an indeterminate.

$[A - \lambda I]$  is called characteristic matrix and

$|A - \lambda I| = 0$  is called characteristic equation and roots of this equation is called the characteristic roots or characteristic values or eigen values or latent roots or proper values of the matrix  $A$ .

Note:- The set of the eigen values of  $A$  is called the spectrum of  $A$ .

### Eigen Vectors:- If $\lambda$ is a characteristic root of an $n \times n$ matrix $A$ , then a non-zero vector $x$ such that

$Ax = \lambda x$  is called a characteristic vector or eigen vector of  $A$  corresponding to the characteristic root  $\lambda$ .

Remark:- 1.  $\lambda$  is a characteristic root of a matrix  $A$  if and only if there exists a non-zero vector  $x$  such that  $Ax = \lambda x$ .

2. If  $x$  is a characteristic vector of a matrix  $A$  corresponding to the characteristic value  $\lambda$ . Here  $k$  is any non-zero scalar, then  $kx$  is also a characteristic vector of  $A$  corresponding to the same characteristic value  $\lambda$ .

3. The characteristic vectors corresponding to distinct characteristic roots of a matrix are linearly independent.

### Nature of an eigen value of the special types of matrices :-

1. The eigen values of a Hermitian matrix are all real.
2. The eigen values of a real symmetric matrix are all real.
3. The eigen values of a skew-Hermitian matrix are either pure imaginary or zero.
4. The eigen values of a skew symmetric matrix are either pure imaginary or zero.
5. The eigen values of a unitary matrices & an orthogonal matrix are of unit modulus.

Ex. S.T. the eigen values of a triangular matrix are just the diagonal elements of the matrix.

Sol. Let,  $A = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ 0 & a_{22} & a_{23} \\ 0 & 0 & a_{33} \end{bmatrix}$  be a triangular matrix of order 3.

$$|A - \lambda I| = \begin{vmatrix} a_{11} - \lambda & a_{12} & a_{13} \\ 0 & a_{22} - \lambda & a_{23} \\ 0 & 0 & a_{33} - \lambda \end{vmatrix} = 0$$

$$\Rightarrow (a_{11} - \lambda)(a_{22} - \lambda)(a_{33} - \lambda) = 0$$

$$\Rightarrow \lambda = a_{11}, a_{22}, a_{33}.$$

Ex.2. Determine the eigen values and eigen vectors of the matrix

$$A = \begin{bmatrix} 5 & 4 \\ 1 & 2 \end{bmatrix}$$

Sol.

$$|A - \lambda I| = 0$$

$$\Rightarrow \begin{vmatrix} 5-\lambda & 4 \\ 1 & 2-\lambda \end{vmatrix} = 0$$

$$\Rightarrow (5-\lambda)(2-\lambda) - 4 = 0$$

$$\Rightarrow (\lambda - 6)(\lambda - 1) = 0$$

$$\therefore \lambda_1 = 6, \lambda_2 = 1$$

Eigen vectors  $\tilde{x}_1 = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$  of A corresponding to the eigen value 6.

$$(A - 6I)\tilde{x} = 0$$

$$\Rightarrow \begin{bmatrix} 5-6 & 4 \\ 1 & 2-6 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} -1 & 4 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \text{ by } R_2 \leftrightarrow R_2 + R_1$$

rank of the coefficient matrix = 1, there are  $(2-1)=1$  L.I. solution.

$$4x_2 = x_1$$

$$\therefore x_2 = 4, x_1 = 1$$

$\therefore \begin{bmatrix} 4 \\ 1 \end{bmatrix}$  is an eigen vector of A corresponding to the eigen value 6.

The eigen vectors  $\tilde{x}_2 = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$  corresponding to the eigen value 1.

$$(A - 1I)\tilde{x} = 0$$

$$\Rightarrow \begin{bmatrix} 4 & 4 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\Rightarrow \begin{cases} 4x_1 + 4x_2 = 0 \\ x_1 + x_2 = 0 \end{cases}$$

$$\therefore x_1 = -x_2$$

$$\text{if } x_2 = 1, x_1 = -1.$$

$\therefore \tilde{x}_2 = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$  is the eigen vector of A corresponding to the eigen value 1.

So,  $\tilde{x}_1 = k \begin{bmatrix} 4 \\ 1 \end{bmatrix}, \tilde{x}_2 = h \begin{bmatrix} 1 \\ -1 \end{bmatrix}$  are the eigen vectors

corresponding to the eigen values 6, 1, respectively, where  $k, h$  are any non-zero scalars.

## The Cayley-Hamilton theorem:

Every square matrix satisfies its characteristic equation.  
i.e. if for a square matrix  $A$  of order  $n$ ,

$$|A - \lambda I| = (-1)^n [\lambda^n + a_1 \lambda^{n-1} + a_2 \lambda^{n-2} + \dots + a_n]$$

then the matrix equation

$$\lambda^n + a_1 \lambda^{n-1} + a_2 \lambda^{n-2} + \dots + a_n I = 0$$

is satisfied by  $\lambda = A$ ,

$$\text{i.e. } A^n + a_1 A^{n-1} + a_2 A^{n-2} + \dots + a_n I = 0.$$

Corollary 1: If  $A$  be a non-singular matrix,  $|A| \neq 0$ .

Premultiplying by  $A^{-1}$

$$A^{n-1} + a_1 A^{n-2} + a_2 A^{n-3} + \dots + a_{n-1} I + a_n A^{-1} = 0$$

$$\text{or, } A^{-1} = -\left(\frac{1}{a_n}\right)(A^{n-1} + a_1 A^{n-2} + \dots + a_{n-1} I)$$

Corollary 2: If  $m$  be a positive integer such that  $m \geq n$ , then multiplying the results by  $A^{m-n}$ ,

$$A^m + a_1 A^{m-1} + \dots + a_n A^{m-n} = 0.$$

## Eigenvalues and Eigen Vectors:

If  $V$  is a vector space over the field  $F$  and  $T$  is a linear operator on  $V$ . An eigenvalue of  $T$  is a scalar  $c$  in  $F$  such that there is a non-zero vector,  $\alpha \in V$  with  $T\alpha = c\alpha$ .

If  $c$  is an eigenvalue of  $T$ , then

(a) Any  $\alpha$  such that  $T\alpha = c\alpha$  is called eigen vector of  $T$  associated with the eigen value  $c$ ;

(b) The collection of all  $\alpha$  such that  $T\alpha = c\alpha$  is called the eigen space associated with  $c$ .

Eigen value of matrix  $A$  over  $F$ : If  $A$  is an  $n \times n$  matrix over the field  $F$ , an eigen value of  $A$  over  $F$  is a scalar  $c$  in  $F$  such that the matrix  $(A - cI)$  is singular (not invertible).

Diagonalisable: If  $T$  is a linear operator on the finite dimensional space  $V$ , then  $T$  is diagonalizable if there is a basis for  $V$  each vector of which is an eigen vector of  $T$ .

## Eigen polynomial:

$$f(c) = |A - cI|.$$

### Some Important Theorem:-

1. If  $T$  is a linear operation on a finite dimensional space  $V$  and  $c$  is any scalar, then followings are equivalent:
  - $c$  is an eigen value of  $T$
  - The operator  $(T - cI)$  is singular (not invertible)
  - $\det(T - cI) = 0$ .
2. Similar matrices have the same eigen ~~poly~~ polynomial.
3. If  $T\alpha = c\alpha$  and  $F$  is any polynomial, then  $F(T)\alpha = F(c)\alpha$
4. Suppose  $T$  is a linear operator on the finite dimensional space  $V$ ;  $c_1, \dots, c_k$  are  $k$ -distinct eigen values of  $T$  and  $W$  is the space of the eigen vectors associated with the eigen values  $c_i$ . If  $W = W_1 + W_2 + \dots + W_k$ , then
 
$$\dim(W) = \dim(W_1) + \dim(W_2) + \dots + \dim(W_k).$$
 In fact, if  $B_i$  is an ordered basis for  $W_i$ , then  $B = (B_1, \dots, B_k)$  is an ordered basis for  $W$ .
5. If  $T$  is a linear operator on a finite dimensional space of  $T$  and  $W_i$  is a null space of  $(T - c_i I)$ . The followings are equivalent:
  - $T$  is diagonalizable
  - The eigen polynomial for  $T$  is  $F = (x - c_1)^{d_1} (x - c_2)^{d_2} \dots (x - c_k)^{d_k}$ , with  $\dim(W_i) = d_i$ ,  $i=1(1)k$ .
  - $\dim V = \dim(W_1) + \dim(W_2) + \dots + \dim(W_k)$ .

Theorem: If  $\tilde{\alpha}$  is a characteristic ~~poly~~ vector of  $T$  corresponding to the eigen value  $\lambda$ , then  $k\tilde{\alpha}$  is also a ch. vector of  $T$  corresponding to the same ch. value  $\lambda$ . Here  $k$  is any non-zero scalar.

Proof: Since  $\tilde{\alpha}$  is a characteristic vector of  $T$  corresponding to the ch. value  $\lambda$ , therefore, ~~poly~~  $\tilde{\alpha} \neq 0$  and

$$T(\tilde{\alpha}) = \lambda \tilde{\alpha}; \text{ let, } k \text{ be any non-zero scalar.}$$

$$\begin{aligned} T(k\tilde{\alpha}) &= kT(\tilde{\alpha}) = k(\lambda \tilde{\alpha}) \\ &= \lambda(k\tilde{\alpha}). \end{aligned}$$

$\therefore k\tilde{\alpha}$  is a characteristic vector of  $T$  corresponding to the characteristic value  $\lambda$ .

Thus, corresponding to a ch. value  $\lambda$ , there may correspond more than one characteristic vectors.

Theorem: If  $\tilde{\alpha}$  is a ch. vector of  $T$ , then  $\tilde{\alpha}$  can't correspond to more than one ch. value of  $T$ .

Proof:  $T\tilde{\alpha} = c_1 \tilde{\alpha}$  and  $T\tilde{\alpha} = c_2 \tilde{\alpha}$ ; where  $c_1, c_2$  are two distinct ch. values of  $T$ .

$$c_1 \tilde{\alpha} = c_2 \tilde{\alpha}$$

$$\Rightarrow (c_1 - c_2) \tilde{\alpha} = 0 \quad [\because \tilde{\alpha} \neq 0]$$

$$\Rightarrow c_1 - c_2 = 0$$

$$\Rightarrow c_1 = c_2.$$

So, a ch. vector of a matrix, can't correspond to more than one characteristic value of that mtx.

Theorem: Let  $T$  be a linear operator on an  $n$ -dimensional vector space  $V$  and  $A$  be the matrix of  $T$  relative to any ordered basis  $B$ . Then a vector in  $V$  is an eigenvector of  $T$  corresponding to its eigenvalue  $c$  if and only if its coordinate vector  $\underline{x}$  relative to the basis  $B$  is an eigenvector of  $A$  corresponding to its eigenvalue  $c$ .

Proof: We have  $[T - cI]_B = [T]_B - c[I]_B$

$$= A - cI.$$

If  $\alpha \neq 0$ , then the coordinate vector  $\underline{x}$  of  $\alpha$  is also non-zero.

Now,  $[(T - cI)(\alpha)]_B = [T - cI]_B [\alpha]_B$

$$= (A - cI) \underline{x}$$

$$\therefore (T - cI)(\alpha) = 0 \text{ iff } (A - cI) \underline{x} = 0$$

or,  $T(\alpha) = c\alpha$  iff  $A\underline{x} = c\underline{x}$ .

or,  $\alpha$  is an eigenvector of  $T$  iff  $\underline{x}$  is an eigenvector of  $A$ .

Ex.1. Let  $V$  be an  $n$ -dimensional vectors space over  $F$ . What is the ch. polynomial of (i) the identity operators on  $V$ ,  
(ii) the zero operator on  $V$ .

Sol. Let  $B$  be any ordered basis for  $V$ .

(i) If  $I$  is the identity operators on  $V$ , then  $[I]_B = I$ .

The characteristic polynomial of  $I$ ;  $\det(I - xI)$

$$= \begin{vmatrix} 1-x & 0 & \cdots & 0 \\ 0 & 1-x & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & 1-x \end{vmatrix} = (1-x)^n.$$

(ii) If  $\hat{0}$  is the zero operator on  $V$ , then  $[\hat{0}]_B = 0$ , i.e. the null matrix of order  $n$ , then the ch. polynomial of  $\hat{0}$  is

$$\det(\hat{0} - xI) = \begin{vmatrix} -x & 0 & \cdots & 0 \\ 0 & -x & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & -x \end{vmatrix} = (-1)^n x^n.$$

Ex.2. If  $c \in F$  is a ch. value of a linear operator  $T$  on a vector space  $V(F)$ , then for any polynomial  $P(x)$  over  $F$ ,  $P(c)$  is a ch. value of  $P(T)$ .

Sol. Since  $c$  is a ch. value of  $T$ , therefore  $\exists$  a non-zero vector  $\alpha$  in  $V$  such that

$$\begin{aligned} T\alpha &= c\alpha \\ \Rightarrow T(T\alpha) &= T(c\alpha) \\ \Rightarrow T^2\alpha &= cT(\alpha) = c^2\alpha \\ \therefore c^2 &\text{ is a ch. value of } T^2. \end{aligned}$$

Repeating this process  $k$  times, we get

$$T^k\alpha = c^k\alpha.$$

$\therefore c^k$  is a ch. value of  $T^k$ , where  $k$  be any positive integer.

Let  $p(x) = a_0 + a_1x + a_2x^2 + \dots + a_m x^m$ , where  $a_i \in F$ .

Then  $p(T) = a_0I + a_1T + a_2T^2 + \dots + a_m T^m$ .

$$\begin{aligned} \text{We have } [P(T)](\alpha) &= (a_0I + a_1T + \dots + a_m T^m)(\alpha) \\ &= a_0 I \alpha + a_1 T(\alpha) + \dots + a_m T^m(\alpha) \\ &= a_0 \alpha + a_1(c\alpha) + \dots + a_m (c^m \alpha) \\ &= (a_0 + c a_1 + \dots + c^{m-1} a_m) \alpha. \end{aligned}$$

$\therefore P(c) = a_0 + c a_1 + \dots + c^{m-1} a_m$  is a ch. value of  $P(T)$ .

Ex.3. Find all (complex) ch. values and ch. vectors of the following matrix  $A = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$ .

Sol.

$$|A - xI| = \begin{vmatrix} -x & 1 \\ 0 & -x \end{vmatrix} = 0$$
$$\Rightarrow x^2 = 0 \Rightarrow x = 0$$

$\therefore 0$  is the only ch. value of  $A$ .

Let  $x_1, x_2$  be the components of the ch. vector corresponding to this ch. value 0.

$$\text{Let } \tilde{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

$$\text{Now, } [A - 0 \cdot I] \tilde{x} = 0$$

$$\Rightarrow \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\text{i.e. } x_2 = 0$$

Let  $x_1 = k$ ; where  $k$  is any non-zero complex number.

$\therefore \tilde{x} = \begin{bmatrix} k \\ 0 \end{bmatrix}$  is the ch. vector corresponding to the eigen value  $\lambda = 0$ , where  $k$  is any non-zero complex no.

WORKED EXAMPLES:-

1. The eigen values of the matrix  $\begin{bmatrix} 1 & 1 & 3 \\ 1 & 5 & 1 \\ 3 & 1 & 1 \end{bmatrix}$  is  
 (A) 2, 3, 6    (B) 2, 6, 7    (C) -2, 3, 6    (D) None.

Sol. (C)  $|A - \lambda I| = 0$

$$\Leftrightarrow \begin{vmatrix} 1-\lambda & 1 & 3 \\ 1 & 5-\lambda & 1 \\ 3 & 1 & 1-\lambda \end{vmatrix} = (1-\lambda) \begin{vmatrix} 5-\lambda & 1 & -1 \\ 1 & 1-\lambda & 3 \\ 3 & 1 & 1 \end{vmatrix} + 3 \begin{vmatrix} 1 & 1 & 1 \\ 3 & 5-\lambda & 1 \\ 1 & 1 & 1 \end{vmatrix} = (\lambda+2)(\lambda-3)(\lambda-6) = 0$$

$$\Rightarrow \lambda = -2, 3, 6.$$

2. Find the eigen values of  $(A^4 + 3A - 2I)$ , where

$$A = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 2 & 1 \\ 0 & 0 & 1 \end{bmatrix} \text{ are}$$

- (A) 2, 3, 20    (B) 2, 2, 2    (C) 2, 2, 20    (D) 20, 20, 2

Sol. (C)  $A^2 = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 2 & 1 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 & 1 \\ 0 & 2 & 1 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 3 & 3 \\ 0 & 4 & 3 \\ 0 & 0 & 1 \end{bmatrix}$

$$A^4 = \begin{bmatrix} 1 & 3 & 3 \\ 0 & 4 & 3 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 3 & 3 \\ 0 & 4 & 3 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 15 & 15 \\ 0 & 16 & 15 \\ 0 & 0 & 1 \end{bmatrix}$$

Now,  $B = A^4 + 3A - 2I$

$$= \begin{bmatrix} 1 & 15 & 15 \\ 0 & 16 & 15 \\ 0 & 0 & 1 \end{bmatrix} + \begin{bmatrix} 3 & 3 & 3 \\ 0 & 6 & 3 \\ 0 & 0 & 3 \end{bmatrix} - \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix}$$

$$= \begin{bmatrix} 2 & 18 & 18 \\ 0 & 20 & 18 \\ 0 & 0 & 2 \end{bmatrix}$$

Then the eigen values of  $|B - \lambda I| = 0$

$$\Leftrightarrow \begin{vmatrix} 2-\lambda & 18 & 18 \\ 0 & 20-\lambda & 18 \\ 0 & 0 & 2-\lambda \end{vmatrix} = 0$$

$$\Rightarrow \lambda = 2, 20, 2.$$

3. Find the eigen values of  $A^4$ , where  $A = \begin{pmatrix} 1 & 0 & -1 \\ 9 & 4 & 1 \\ 3 & 1 & 1 \end{pmatrix}$ .

Sol.

$$A = \begin{pmatrix} 1 & 0 & -1 \\ 9 & 4 & 1 \\ 3 & 1 & 1 \end{pmatrix}$$

then the eigen values of the matrix can be determined from the ch. equation

$$|A - \lambda I| = 0$$

$$\Rightarrow \begin{vmatrix} 1-\lambda & 0 & -1 \\ 9 & 4-\lambda & 1 \\ 0 & 1 & 1-\lambda \end{vmatrix} = 0$$

$$\Rightarrow (1-\lambda)(\lambda-2)(\lambda-3) = 0$$

$$\Rightarrow \lambda = 1, 2, 3.$$

$\therefore$  the eigen values of  $A$  are: 1, 2, 3.

$\therefore$  the eigen values of  $A^4$  are:  $1^4, 2^4, 3^4$ , i.e. 1, 16, 81.

So, the eigen values of  $A^4$  are: 1, 16, 81.

4. Use Cayley Hamilton theorem, find the inverse of  $A = \begin{bmatrix} -1 & 1 & 1 \\ 3 & 1 & -1 \\ 2 & 2 & 1 \end{bmatrix}$

Sol.

$$|A - \lambda I| = 0$$

$$\Rightarrow \begin{vmatrix} -1-\lambda & 1 & 1 \\ 3 & 1-\lambda & -1 \\ 2 & 2 & 1-\lambda \end{vmatrix} = 0$$

$$\Rightarrow -\lambda^3 + \lambda^2 - 4\lambda - 4 = 0$$

$$\Rightarrow A^3 - A^2 + 4A + 4I = 0$$

$$\Rightarrow A^{-1} = \frac{-A^2 + A + 4I}{4}$$

$$= \frac{1}{4} \left[ - \begin{bmatrix} 6 & 2 & -1 \\ -2 & 2 & 1 \\ 6 & 6 & 1 \end{bmatrix} + \begin{bmatrix} -1 & 1 & 1 \\ 3 & 1 & -1 \\ 2 & 2 & 1 \end{bmatrix} + \begin{bmatrix} 4 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & 4 \end{bmatrix} \right]$$

$$= \frac{1}{4} \cdot \begin{bmatrix} -3 & -1 & 2 \\ 5 & 3 & -2 \\ 4 & -4 & 4 \end{bmatrix}$$

5. If  $\lambda_1$  and  $\lambda_2$  are the values of  $\lambda$  for which  $|1-\lambda \ 2 \ 0 \ \lambda \ 2 \ 1 \ 0 \ 1 \ 1| = 0$ , then  $\lambda_1 + \lambda_2$  equals (A) -1 (B) 0 (C) 1 (D) 2.

Sol. (B)  $\begin{vmatrix} 1 & 2 & 0 \\ \lambda & 2 & 1 \\ 0 & 1 & 1 \end{vmatrix} = 0$

$$\Rightarrow 1(2-1) - \lambda(2) = 0$$

$$\Rightarrow \lambda^2 = 1 \quad \text{i.e. } \lambda_1 + \lambda_2 = 1 - 1 = 0.$$

$$\Rightarrow \lambda = \pm 1$$

6. Find the characteristic roots and corresponding characteristic vectors for each of the following matrix

$$A = \begin{bmatrix} 8 & -6 & 2 \\ -6 & 7 & -4 \\ 2 & -4 & 3 \end{bmatrix}$$

Sol. The characteristic equation is

$$|A - \lambda I| = \begin{vmatrix} 8-\lambda & -6 & 2 \\ -6 & 7-\lambda & -4 \\ 2 & -4 & 3-\lambda \end{vmatrix} = -\lambda^3 + 18\lambda^2 - 45\lambda = 0$$

$$\Rightarrow \lambda(\lambda-3)(\lambda-15) = 0$$

$\Rightarrow \lambda = 0, 3, 15$  are the 3 ch. roots of the mtx A.

If  $\tilde{x}$  is a characteristic vector corresponding to the ch. root 0, then we have

$$A\tilde{x} = \lambda\tilde{x}$$

$$\Rightarrow [A - \lambda I]\tilde{x} = 0$$

$$\Rightarrow \begin{bmatrix} 8 & -6 & 2 \\ -6 & 7 & -4 \\ 2 & -4 & 3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\Rightarrow 8x_1 - 6x_2 + 2x_3 = 0, -6x_1 + 7x_2 - 4x_3 = 0, 2x_1 - 4x_2 + 3x_3 = 0$$

$$\text{Let } x_1 = 1, \text{ then } x_2 = 2, x_3 = 2.$$

$\therefore \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix}$  is a ch. vector corresponding to the

It may similarly be shown by considering the equation

$$(A - 3I)\tilde{x} = 0,$$

$$(A - 15I)\tilde{x} = 0,$$

that the ch. vectors corresponding to the ch. roots 3 and 15 are arbitrary non-zero multiples of the vectors

$$\begin{bmatrix} 2 \\ 1 \\ -2 \end{bmatrix}, \begin{bmatrix} 2 \\ 2 \\ 1 \end{bmatrix}$$

7. Find the eigen value of the mtx

$$\begin{bmatrix} 1 & 0 & 0 & -\alpha/2 \\ 0 & 1 & 0 & -\alpha/2 \\ 0 & 0 & 1 & -\alpha/2 \\ 0 & 0 & 0 & \alpha \end{bmatrix}.$$

Sol.

$$\det [A - \lambda I] = 0$$

$$\Rightarrow (1-\lambda)(1-\lambda)(1-\lambda)(\alpha-\lambda) = 0$$

$$\Rightarrow \lambda = 1, 1, 1, \alpha \text{ are the eigen values.}$$

8. Let  $M = \begin{pmatrix} 1 & 1+i & 2-i \\ 1-i & 2 & 8+i \\ 2+i & 3-i & 3 \end{pmatrix}$ . If  $B = \begin{pmatrix} x_1 & y_1 & z_1 \\ x_2 & y_2 & z_2 \\ x_3 & y_3 & z_3 \end{pmatrix}$ , where  $\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}, \begin{pmatrix} y_1 \\ y_2 \\ y_3 \end{pmatrix}$  and  $\begin{pmatrix} z_1 \\ z_2 \\ z_3 \end{pmatrix}$  are LIN eigen vectors of  $M$ , then the main diagonal of the matrix  $B^{-1}MB$  has

- (A) exactly one real entry      (B) exactly two real entries  
 (C) exactly 3 real entries      (D) no real entries

Sol.

$$M^T = M^*$$

$\Rightarrow M$  is a Hermitian matrix

since  $B$  is invertible mtx.

$\Rightarrow B^{-1}MB$  is a diagonal mtx whose diagonal entries are eigenvalues of  $M$ .

We know the eigen values of Hermitian mtx are real.  
 $\Rightarrow$  all three eigen values are real.

9. Let  $P$  be a  $3 \times 3$  mtx  $\exists$  for some  $c$ , the linear system  $P=c$  has infinite number of solutions. Which one of the following is TRUE?

- (A) The linear system  $Px=b$  has infinite no. of solutions  $\forall b$ .  
 (B)  $\text{Rank}(P)=3$       (C)  $\text{Rank}(P) \neq 1$       (D)  $\text{Rank}(P) \leq 2$ .

Sol. (D)  $\text{rank}(P) < n \Rightarrow Px=b$  has infinite no. of solutions  
 $\therefore \text{Rank}(P) \leq 2$ .

10. Let  $P$  be a  $2 \times 2$  mtx  $\Rightarrow P^{102}=0$ . Then  
 (A)  $P^2=0$       (B)  $(1-P)^2=0$       (C)  $(1+P)^2=0$       (D)  $P=0$

Sol. (A) Since  $P$  is mtx of order 2 so its ch. equation is of order 2.  
 So  $P^{102}$  is equal to 0 iff  $P^2=0$ .

11. Let  $A$  be an  $n \times n$  matrix  $\Rightarrow P^{-1}AP > 0$  for every non-zero invertible mtx  $P$  where  $P$  is also an  $n \times n$  mtx. Which of the following is TRUE?

- (A) All eigen values of  $A$  are negative      (B) All eigen values of  $A$  are positive.

Sol. (B) Since given that for mtx  $A$ ,  $P^{-1}AP > 0$ .

Here  $P^{-1}AP$  is a diagonal mtx whose diagonal elements are eigen values of matrix  $A$ . But  $P^{-1}AP > 0$  shows the eigen values of  $A$  are all positive.

- 12) Let  $P = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$ , the eigenvectors corresponding to the eigenvalues  $i$  and  $-i$  are respectively  
 (A)  $\begin{pmatrix} 1 \\ i \end{pmatrix}$  and  $\begin{pmatrix} -1 \\ i \end{pmatrix}$  (B)  $\begin{pmatrix} 1 \\ i \end{pmatrix}$  and  $\begin{pmatrix} -1 \\ -i \end{pmatrix}$  (C)  $\begin{pmatrix} -1 \\ i \end{pmatrix}$  and  $\begin{pmatrix} i \\ -i \end{pmatrix}$  (D)  $\begin{pmatrix} i \\ i \end{pmatrix}$  and  $\begin{pmatrix} i \\ -i \end{pmatrix}$

Sol.  $\lambda_1 = i, \lambda_2 = -i$

$$(P - \lambda_1 I) \underline{x} = 0$$

$$\Rightarrow \begin{bmatrix} 0-i & 1 \\ -1 & -i \end{bmatrix} \underline{x} = 0$$

$$\Rightarrow \begin{bmatrix} -i & 1 \\ -1 & -i \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\Rightarrow \begin{cases} -x_1 i + x_2 = 0 \\ -x_1 - ix_2 = 0 \end{cases}$$

$$\therefore x_1 = 1, x_2 = i$$

$\therefore \begin{bmatrix} 1 \\ i \end{bmatrix}$  is the eigenvector corresponding to the eigenvalue  $i$ .

$$(P - \lambda_2 I) \underline{x}' = 0$$

$$\Rightarrow \begin{bmatrix} i & 1 \\ -1 & i \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\Rightarrow \begin{cases} ix_1 + x_2 = 0 \\ -x_1 + ix_2 = 0 \end{cases}$$

$$\therefore x_1 = -1, x_2 = i$$

$\therefore \begin{bmatrix} -1 \\ i \end{bmatrix}$  is the eigenvector corresponding to the eigenvalue  $-i$ .

- 13) Let  $P, M, N$  be  $n \times n$  matrices  $\Rightarrow M$  and  $N$  are non-singular.  
 If  $\underline{x}$  is an eigenvector of  $P$  corresponding to the eigenvalue  $\lambda$ ,  
 then an eigenvector of  $N^{-1} M P M^{-1} N$  corresponding to the eigenvalue  $\lambda$  is

- (A)  $MN^{-1}\underline{x}$  (B)  $M^{-1}N\underline{x}$  (C)  $NM^{-1}\underline{x}$  (D)  $N^{-1}M\underline{x}$

Sol. (C) Since  $\lambda$  is eigenvalue of  $P$  and  $\underline{x}$  be the eigenvector corresponding to it.

$$\Rightarrow P\underline{x} = \lambda \underline{x}$$

$$N^{-1}M P M^{-1}N (N^{-1}M\underline{x}) = N^{-1}MPM^{-1}(NN^{-1})M\underline{x}$$

$$= N^{-1}MPM^{-1}M\underline{x}$$

$$= N^{-1}MP(M^{-1}M)\underline{x}$$

$$= N^{-1}MP\underline{x}$$

$$= N^{-1}M\underline{x}$$

$$= \lambda N^{-1}M\underline{x}$$

$\therefore N^{-1}M\underline{x}$  is eigenvector corresponding to  $\lambda$ .

13) Let  $P = \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$ , then

- (A)  $P$  has two linearly independent eigenvectors    (B)  $P$  has an eigen vector  
 (C)  $P$  is non-singular    (D)  $\exists$  a non-singular  $S \ni S^{-1}PS$  is a diagonal matrix

Sol.

(D)

14) Let  $P$  be an  $n \times n$  idempotent matrix, that is  $P^2 = P$ , which of the following is FALSE?

- (A)  $P^T$  is idempotent  
 (B) The possible eigenvalues of  $P$  are 0 and 1.  
 (C) The non-diagonal entries of  $P$  can be zero.  
 (D) There are infinite no. of  $n \times n$  non-singular matrices that are idempotent

Solution:

(A) Since  $P$  is idempotent matrix, i.e.,  $P^2 = P$ , then  $P^T$  is also idempotent, as  $(P^T)^T = P^T \Rightarrow (P^T)^2 = P^T$ .

$P^2 = P \Rightarrow P(P-I) = 0 \Rightarrow$  eigen values of  $P$  are 0 and 1.  
 → the non-diagonal entries of an idempotent matrix can be zero,  
 e.g.  $P = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}, P^2 = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} = P$ .

So, (D) is FALSE.

15) Let  $A$  and  $B$  are any arbitrary square matrices of order 2. Then show that  $AB$  and  $BA$  have some eigen values but ~~may~~ may have different eigen vectors.

Solution: — Let us take an example.

$$A = \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix}, B = \begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix}$$

$$\begin{aligned} AB &= \begin{bmatrix} 1 & 1 \\ 2 & 2 \end{bmatrix} \\ |AB - \lambda I| &= 0 \Rightarrow (1-\lambda)(2-\lambda) = 0 \\ &\Rightarrow \boxed{\lambda_1 = 1, \lambda_2 = 2} \\ &\Rightarrow \lambda^2 - 3\lambda = 0 \\ &\Rightarrow \lambda(\lambda-3) = 0 \\ &\Rightarrow \lambda = 0, \lambda = 3. \end{aligned}$$

For  $\lambda = 0$ ,

$$[AB - 0 \cdot I] \mathbf{x} = \mathbf{0}$$

$$\Rightarrow \begin{bmatrix} 1 & 1 \\ 2 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\therefore x_1 + x_2 = 0$$

$$\therefore x_1 = 1, x_2 = -1$$

$\therefore \begin{bmatrix} 1 \\ -1 \end{bmatrix}$  be an eigen vector corresponding to  $\lambda = 0$ .

For  $\lambda = 3$ ,

$$[AB - 3 \cdot I] \mathbf{x} = \mathbf{0}$$

$$\Rightarrow \begin{bmatrix} 1-3 & 1 \\ 2 & 2-3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\Rightarrow -2x_1 + x_2 = 0, 2x_1 - x_2 = 0$$

$$\therefore x_2 = 2, x_1 = 1$$

$\therefore \begin{bmatrix} 1 \\ 2 \end{bmatrix}$  is the eigen vector.

$$\text{Here } BA = \begin{bmatrix} 1 & 2 \\ 1 & 2 \end{bmatrix}$$

$$\therefore |BA - \lambda I| = 0$$

$$\Rightarrow \begin{vmatrix} 1-\lambda & 2 \\ 1 & 2-\lambda \end{vmatrix} = 0$$

$$\Rightarrow \lambda = 0, 3.$$

$$\text{For } \lambda = 0, [BA - 0 \cdot I] \vec{x} = \vec{0}$$

$$\Rightarrow \begin{bmatrix} 1 & 2 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\Rightarrow x_1 + 2x_2 = 0$$

$$\Rightarrow x_1 = -2x_2$$

$$\therefore x_2 = -\frac{1}{2}, x_1 = 1$$

$\therefore \begin{bmatrix} 1 \\ -\frac{1}{2} \end{bmatrix}$  be the eigenvectors corresponding to  $\lambda = 0$ .

For  $\lambda = 3$ ,  $\begin{bmatrix} 1 \\ 1 \end{bmatrix}$  be the eigenvectors corresponding to  $\lambda = 3$ .

$\therefore AB \text{ & } BA$  have same eigen values but not same eigenvectors.

A real  $3 \times 3$  mtx  $M$  has eigen values  $\pm 1$  and  $2$ . S.T.

- 16) A real  $3 \times 3$  mtx  $M$  has eigen values  $\pm 1$  and  $2$ . S.T.  
 (i)  $M$  is invertible (ii)  $M^3 - 2M^2$  is singular (iii)  $M$  is diagonalisable.

Sol. We have a mtx  $M$  whose eigenvalues are  $+1, -1$  and  $2$ .

(i) ch. equation can be given as

$$(M+I)(M-I)(M-2I) = 0$$

$$\Rightarrow (M^2 - I)(M - 2I) = 0$$

$$\Rightarrow M^3 - 2M^2 = M - 2I$$

(ii) By the properties of eigenvalues:  
 determinant of mtx = multiplication of eigenvalues

$$|M| = (-1) \times (1) \times (2)$$

$$|M| = -2$$

here  $|M| \neq 0 \Rightarrow M$  is invertible.

$$|M^3 - 2M^2| = |M - 2I|$$

$$\text{since } |M| = -2$$

$$|M - 2I| = 0$$

$$\Rightarrow |M^3 - 2M^2| = 0$$

$$\Rightarrow M^3 - 2M^2 \text{ is singular.}$$

(iii) Since  $M$  having 3 distinct eigenvalues, then the ch. vectors corresponding to distinct characteristic roots of a mtx are L.I.N.

And an  $n \times n$  mtx is diagonalisable if and only if it possesses  $n$  linearly independent eigenvectors.

$\Rightarrow M$  is diagonalisable.