

# Weekly Report Week 15.5 - 21.5

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## Contributions

- Alexander Busch: Implement a version of numerical inverse kinematics and class structure for trajectory parts and kinematics parts of the project
- Yu Tung Tsai: Research on the usage of visual processing in ROS
- Berk & Can: Implement inverse kinematics and integrating the use of jitter
- Junaaid Ali: Working with the ROS tutorial and found the transformation matrices for forward kinematics. Started working with inverse kinematics.