Weekly Report Week 22.5 - 28.5

Summary

Finished and corrected numerical incremental kinematics calculation. Discussed project class structure and corrected the setup of the package structure.

Contributions

- Alexander Busch: Implemented and corrected numerical incremental kinematics; setup of the package structure
- Junaidali Surti: Setup and Installation of required files and packages. Studied ROS.
- Berk Cam: Made small changes to the package structure, started working on trajectory generation