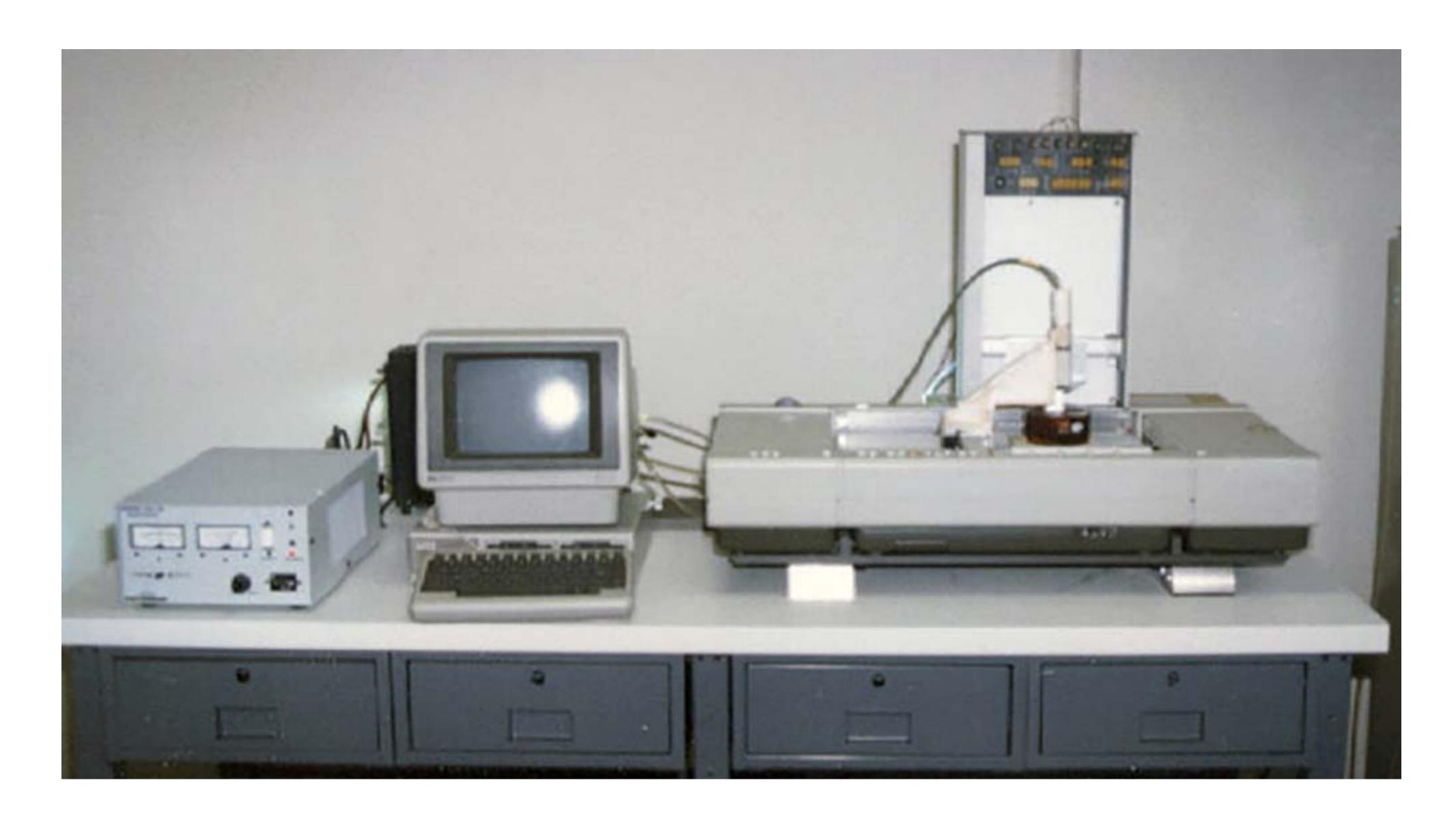
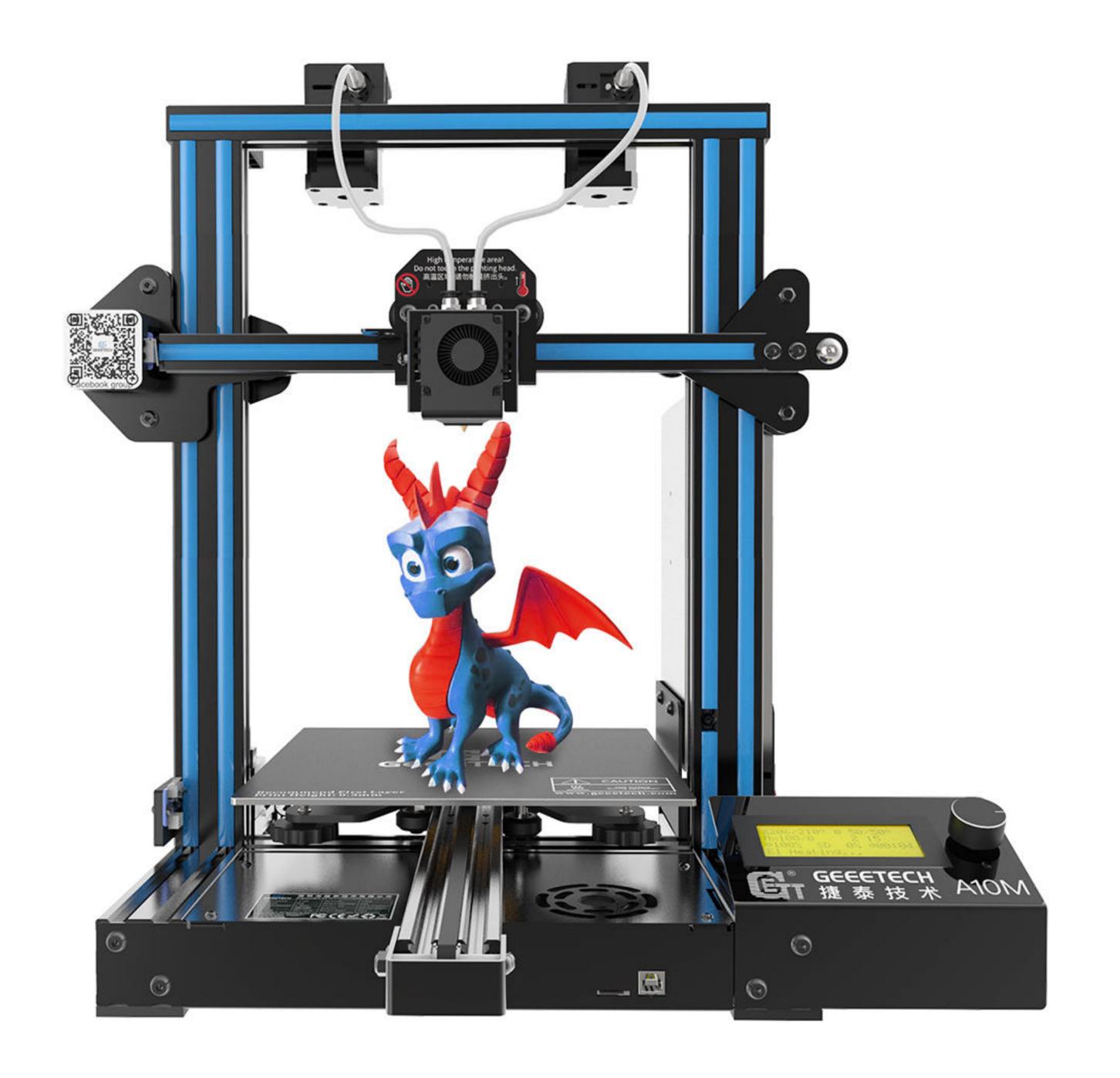
3D-printed Interactive Objects Without Assembly or Calibration

Carlos Tejada

University of Copenhagen



The first 3D printer: The SLA-1 from 3D Systems







#### Passive

#### Can't be interacted with

#### Previous Work

#### Previous Work

Requires engineering expertise:

Assembly of parts

Assembly of circuits

Calibration of models

Printed, not assembled.

Lowering the difficulty.

o Increase adoption.

No assembly of parts or circuits.

No calibration.

Minimal disruption of original geometry.

• Well-studied concepts (e.g. acoustic resonance, fluid dynamics).

• Structures that leverage these concepts.

• Benefits:

Only internal structures are modified.

• Mathematical equations, or pre-trained models.





Blowhole Gl'18

AirTouch CHI '20

#### Blowhole

#### Blowing-Activated Tags for Interactive 3D-Printed Models

• Resonant, spherical cavities, with tubular openings.

• Variations in tube length, and cavity volume, vary the resonant frequency.



Printed as a single structure.

• Use mathematical equation to identify interactions.

Blowhole Gl'18

#### Blowhole

Blowing-Activated Tags for Interactive 3D-Printed Models

• Susceptible to external, acoustic interference.



Only 6 locations.

Blowhole Gl'18

#### AirTouch

3D-printed Touch-Sensitive Objects Using Pneumatic Sensing

Pneumatic sensing.

• Flow distribution structure.

• From compressed air source to outlets in the surface.

• Outlets from 0.65 to 1.5mm in diameter.



AirTouch CHI '20

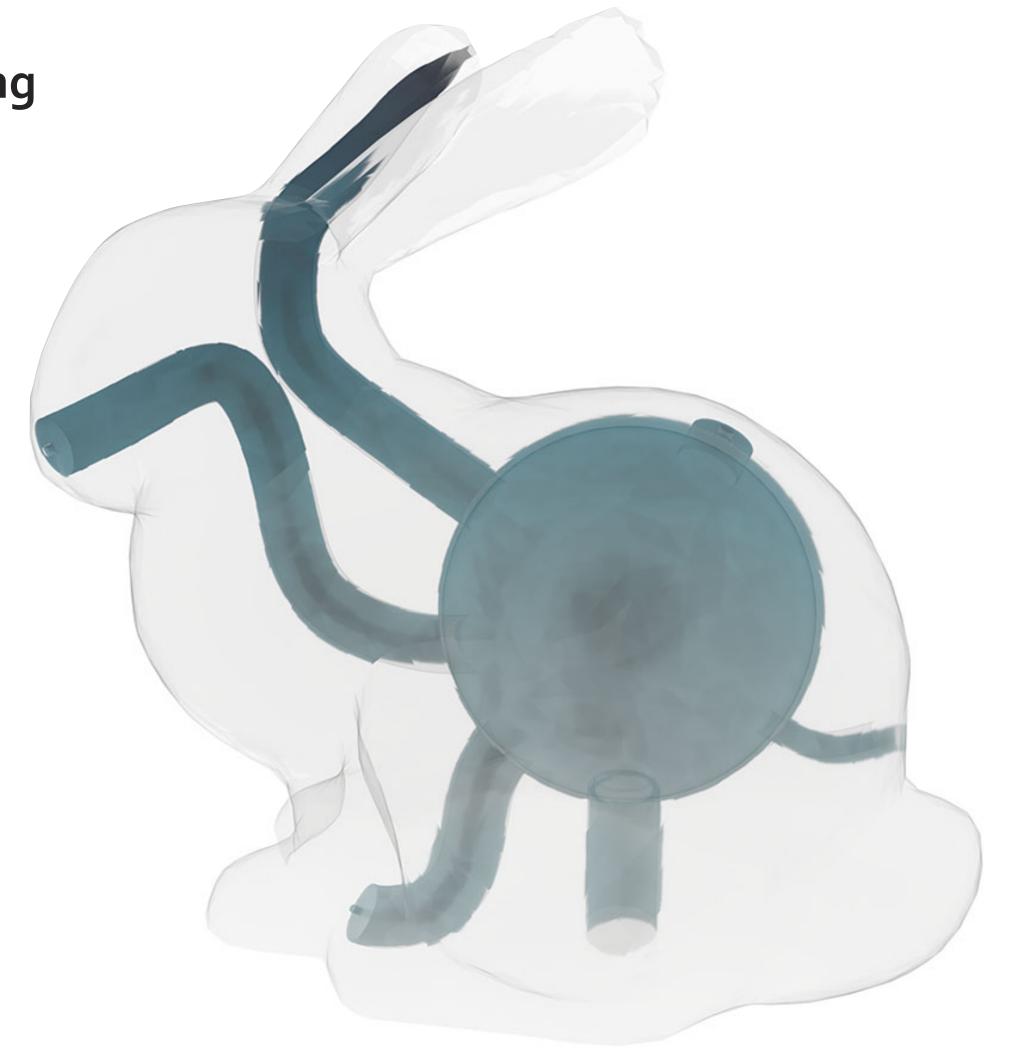
#### AirTouch

3D-printed Touch-Sensitive Objects Using Pneumatic Sensing

• Covering each causes an identifiable pressure increase.

Printed as a single structure.

 Uses pre-trained machine learning models to identify interactions.



AirTouch CHI '20

#### Ongoing Work

#### Ongoing Work

- Embed computation on fabricated objects.
  - o Reduce the need for assembling circuits.
- First steps: Logic gates.
- Physical toolkit for experimenting.
- Embed resulting design inside a 3D-model.

3D-printed Interactive Objects Without Assembly or Calibration

#### Carlos Tejada

University of Copenhagen carlosetejada.com