4 Quantum Field Theory II – Exercise sheet 3 (2025-05-28)

4.1 Exercise 1 - Tree-level= Classical Field Theory

We want to understand the claim that tree-level diagrams correspond to classical field theory (which is equivalently stated by saying that \hbar is the loop counting parameter). We consider ϕ^3 theory with action:

$$S[\phi] = \int d^4x \left(-\frac{1}{2} \partial_\mu \phi \partial^\mu \phi - \frac{m^2}{2} \phi^2 - \frac{\lambda}{3!} \phi^3 + J\phi \right),\tag{1}$$

where J is a fixed (non-dynamical) external source. Our main goal is to solve the field equations as a perturbation theory in λ , making the power series ansatz:

$$\phi = \phi_0 + \lambda \phi_1 + \lambda^2 \phi_2 + \lambda^3 \phi_3 + \cdots$$

- 1) Determine the Euler-Lagrange equations of (1) and use this to write the field equations for ϕ_0 , ϕ_1 , and ϕ_2 .
- 2) Solve the above equations for ϕ_0 , ϕ_1 , and ϕ_2 in terms of J by use of a suitable Greens function like the Feynman propagator $D_F(x-y)$.
- 3) Find a graphical notation to represent the above solutions and use these Feynman diagrams to determine the solution to order λ^3 , i.e., to determine ϕ_3 . Convince yourself directly that the equations hold.

Hint: Nobody can stop you from reading section 3.5 of the book by Schwartz.

4) Consider now the 'on-shell action' obtained by substituting the solution $\phi(J)$ into (1):

$$S_{\text{on-shell}}[J] := S[\phi(J)]. \tag{2}$$

The claim is that the n-point tree-level amplitude can be obtained from the on-shell action via:

$$(2\pi)^4 \delta^{(4)}(k_1 + \dots + k_n) M_n^{\text{tree}}(k_1, \dots, k_n) = (-1)^n \prod_{i=1}^n \int d^4 x_i \, e^{ik_i \cdot x_i} \left(\Box_{x_i} - m^2 \right) \frac{\delta}{\delta J(x_i)} S_{\text{on-shell}}[J] \bigg|_{J=0}.$$
 (3)

Check this claim by looking at the $2 \rightarrow 2$ scattering.

1) From $\delta S=0$ we obtain the Euler-Lagrange equations - so we calculate the terms

$$\frac{\partial \mathcal{L}}{\partial(\partial_{\alpha}\phi)} = -\frac{1}{2} \frac{\partial g^{\mu\nu} \partial_{\mu}\phi \partial_{\nu}\phi}{\partial(\partial_{\alpha}\phi)} \tag{115}$$

$$= -\frac{1}{2} (g^{\mu\nu} \delta^{\alpha}_{\mu} \partial_{\nu} \phi + g^{\mu\nu} \partial_{\mu} \phi \delta^{\alpha}_{\nu}) \tag{116}$$

$$=-\partial^{\alpha}\phi$$
 (117)

$$\frac{\partial \mathcal{L}}{\partial \phi} = -m^2 \phi - \frac{\lambda}{2} \phi^2 + J \tag{118}$$

$$\rightarrow -\partial_{\alpha} \frac{\partial \mathcal{L}}{\partial(\partial_{\alpha} \phi)} + \frac{\partial \mathcal{L}}{\partial \phi} = 0 \tag{119}$$

$$\rightarrow (\Box - m^2)\phi - \frac{\lambda}{2}\phi^2 + J = 0 \tag{121}$$

As we are working in $g^{\mu\nu}=\mathrm{diag}(-1,1,1,1)$ (meaning $\square=-\partial_t^2+\triangle$) the signs of the KG equation are ok. The substituting in the series expansion

$$(\Box - m^2)(\phi_0 + \lambda \phi_1 + \lambda^2 \phi_2 + \cdots) - \frac{\lambda}{2}(\phi_0 + \lambda \phi_1 + \lambda^2 \phi_2 + \cdots)^2 + J = 0$$

$$(\Box - m^2)(\phi_0 + \lambda\phi_1 + \lambda^2\phi_2 + \cdots) - \frac{\lambda}{2}(\phi_0^2 + 2\phi_0\phi_1\lambda + (\phi_1^2 + 2\phi_0\phi_2)\lambda^2 + (2\phi_1\phi_2 + 2\phi_0\phi_3)\lambda^3 + \cdots) + J = 0$$

we obtain

$$\lambda^0: \qquad (\Box - m^2)\phi_0 = -J \tag{122}$$

$$\lambda^1: \qquad (\Box - m^2)\phi_1 = \frac{1}{2}\phi_0^2 \tag{123}$$

$$\lambda^2: (\Box - m^2)\phi_2 = \phi_0\phi_1$$
 (124)

$$\lambda^3: \qquad (\Box - m^2)\phi_3 = \frac{1}{2}(\phi_1^2 + 2\phi_0\phi_2)$$
 (125)

2) With the definition of the Feynman propagator D_F

$$D_F(x,y) = i \int \frac{d^4p}{(2\pi)^4} \frac{i}{p^2 + m^2 - i\epsilon} e^{ip(x-y)}$$
(126)

$$\rightarrow (\Box_x - m^2) D_F(x, y) = -\int \frac{d^4p}{(2\pi)^4} \frac{i}{p^2 + m^2 - i\epsilon} e^{ip(x-y)} [i^2(-(p_0)^2 + \vec{p}^2) - m^2]$$
(127)

$$=-i\int \frac{d^4p}{(2\pi)^4} \frac{-(p^2+m^2)}{p^2+m^2-i\epsilon} e^{ip(x-y)}$$
(128)

$$= +i \int \frac{d^4p}{(2\pi)^4} e^{ip(x-y)}$$
 (129)

$$=i\delta^{(4)}(x-y)\tag{130}$$

we find

$$\phi_0(x) = \int d^4y \, D_F(x - y)[iJ(y)] \tag{131}$$

$$= i \int d^4y \, D_F(x-y)J(y) \tag{132}$$

and

$$\phi_1(x) = (-i)\frac{1}{2} \int d^4y \, D_F(x-y) \left(\underbrace{i \int d^4z_1 \, D_F(y-z_1) J(z_1)}_{=\phi_0(y)} \cdot \underbrace{i \int d^4z_2 \, D_F(y-z_2) J(z_2)}_{=\phi_0(y)} \right)$$
(133)

$$= \frac{i}{2} \int d^4y \, D_F(x-y) \left(\int d^4z_1 \, D_F(y-z_1) J(z_1) \cdot \int d^4z_2 \, D_F(y-z_2) J(z_2) \right) \tag{134}$$

$$= \frac{i}{2} \iiint d^4y \, d^4z_1 \, d^4z_2 \, D_F(x-y) D_F(y-z_1) J(z_1) D_F(y-z_2) J(z_2)$$
(135)

and

$$\phi_{2}(x) = (-i) \int d^{4}u \, D_{F}(x-u)$$

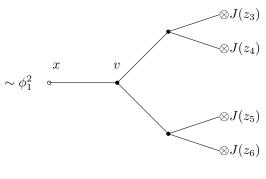
$$\left(\underbrace{i \int d^{4}w D_{F}(u-w)J(w)}_{=\phi_{0}(u)} \cdot \underbrace{\frac{i}{2} \iiint d^{4}y \, d^{4}z_{1} \, d^{4}z_{2} \, D_{F}(u-y)D_{F}(y-z_{1})J(z_{1})D_{F}(y-z_{2})J(z_{2})}_{=\phi_{1}(u)} \right)$$

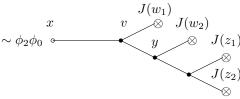
$$= \underbrace{i}{2} \iiint d^{4}u \, d^{4}w \, d^{4}y \, d^{4}z_{1} \, d^{4}z_{2} \, D_{F}(x-u)D_{F}(u-w)J(w)D_{F}(u-y)D_{F}(y-z_{1})J(z_{1})D_{F}(y-z_{2})J(z_{2})$$

$$(138)$$

3) Graphical representation

Now constructing the λ^3 term $\phi_3(x)$ (three black nodes)





We can also calculate - and obtain the same result

$$\phi_3(x) = (-i) \int dv \, D_F(x - v) \left(2 \underbrace{i \int dw_1 \, D_F(v - w_1) J(w_1)}_{=\phi_0(v)} \cdot \right)$$
(139)

$$\underbrace{\frac{i}{2}\iiint\iint du dw_2 dy dz_1 dz_2 D_F(v-u)D_F(u-w_2)J(w_2)D_F(u-y)D_F(y-z_1)J(z_1)D_F(y-z_2)J(z_2)}_{=\phi_2(v)} + \underbrace{\frac{i}{2}\iiint\iint du dw_2 dy dz_1 dz_2 D_F(v-u)D_F(u-w_2)J(w_2)D_F(u-y)$$

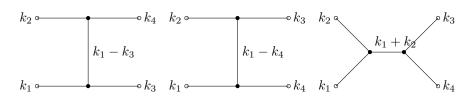
$$+\underbrace{\frac{i}{2}\iiint dy_1 dz_3 dz_4 D_F(v-y_1)D_F(y_1-z_3)J(z_3)D_F(y_1-z_4)J(z_4)}_{\phi_1(v)}.$$
(141)

$$\cdot \underbrace{\frac{i}{2} \iiint dy_2 dz_5 dz_6 D_F(v - y_2) D_F(y_2 - z_5) J(z_5) D_F(y_2 - z_6) J(z_6)}_{\phi_1(v)}$$
(142)

$$= i \int dv \, dw_1 \, du \, dw_2 \, dy \, dz_1 \, dz_2 \, D_{xv} D_{vw_1} J(w_1) D_{vu} D_{uw_2} J(w_2) D_{uy} D_{yz_1} J(z_1) D_{yz_2} J(z_2)$$
(143)

$$+\frac{i}{4}\int dv dy_1 dz_3 dz_4 dy_2 dz_5 dz_6 D_{xv} D_{vy_1} D_{y_1 z_3} J(z_3) D_{y_1 z_4} J(z_4) D_{vy_2} D_{y_2 z_5} J(z_5) D_{y_2 z_6} J(z_6)$$
(144)

4) Intuitively we expect only stuff to happen at λ^2 order because the only relevant (low order) tree level diagrams are. We calculate anyway - so substituting (shortening the notation $D_F(x-y) \equiv D_{xy}$)



$$S_{\text{on-shell}}[J] = S[\phi(J)]$$

$$= S[\phi_0 + \lambda \phi_1 + \lambda^2 \phi_2 + \dots]$$

$$= \int d^4x \left(-\frac{1}{2} (\Box - m^2) (\phi_0 + \lambda \phi_1 + \lambda^2 \phi_2 + \dots) - \frac{\lambda}{3!} (\phi_0 + \lambda \phi_1 + \lambda^2 \phi_2 + \dots)^3 + J(\phi_0 + \lambda \phi_1 + \lambda^2 \phi_2 + \dots) \right)$$

$$= \int d^4x \left(-\frac{1}{2} (-J + \lambda \frac{1}{2} \phi_0^2 + \lambda^2 \phi_0 \phi_1 + \dots) - \frac{\lambda}{3!} (\phi_0^3 + 3\phi_1 \phi_0^2 \lambda + 3\phi_0 (\phi_1^2 + \phi_0 \phi_2) \lambda^2 + \dots) + J(\phi_0 + \lambda \phi_1 + \lambda^2 \phi_2 + \dots) \right)$$

$$= \int d^4x J \left(\phi_0 + \frac{1}{4} \right) + \lambda \int d^4x \left(-\frac{1}{6} \phi_0^2 \left[\phi_0 + \frac{3}{2} \right] + J\phi_1 \right) + \lambda^2 \int d^4x \left(-\frac{1}{2} \phi_0 \phi_1 (\phi_0 + 1) + J\phi_2 \right) + \dots$$

$$(149)$$

Now we look at the individual contributions (shortening notation) - and doing to first functional integral in baby steps

$$S_0 = \int d^4x \, J\left(\phi_0 + \frac{1}{4}\right) \tag{150}$$

$$= \int dx J(x) \left(i \int dy D_F(x-y)J(y) + \frac{1}{4} \right)$$
(151)

$$=\frac{1}{4}\int dx\,J(x)+i\int dx\,dyJ(x)D_{xy}J(y) \tag{152}$$

$$\rightarrow \frac{\delta S_0[J]}{\delta J(x_i)} = \lim_{\epsilon \to 0} \frac{1}{\epsilon} \left[\frac{1}{4} \int dx \left[J(x) + \epsilon \delta(x - x_i) \right] - \frac{1}{4} \int dx J(x) \right]$$
 (153)

$$+ i \lim_{\epsilon \to 0} \frac{1}{\epsilon} \left[i \int dx \, dy (J(x) + \epsilon \delta(x - x_i)) D_{xy} (J(y) + \epsilon \delta(y - x_i)) - i \int dx \, dy J(x) D_{xy} J(y) \right] \quad (154)$$

$$= \frac{1}{4} \int dx \, \delta(x - x_j) + i \int dx \, dy \left[\delta(x - x_i) D_{xy} J(y) + J(x) D_{xy} \delta(y - x_i) \right] \tag{155}$$

$$= \frac{1}{4} + i \int dy \, D_{x_i y} J(y) + i \int dx \, D_{x x_i} J(x) \tag{156}$$

this terms contains only one J - performing the other three functional derivatives $\delta/\delta J(x_k)$ will result in a zero. Now we can calculate a bit faster

$$S_{1} = -\frac{1}{6} \int dx \, \phi_{0}^{3} - \frac{1}{4} \int dx \, \phi_{0}^{2} + \int dx \, J\phi_{1}$$

$$= -\frac{i^{3}}{6} \int dx \, dy_{1} \, dy_{2} \, dy_{3} \, D_{xy_{3}} J(y_{3}) D_{xy_{2}} J(y_{2}) D_{xy_{1}} J(y_{1}) - \frac{i^{2}}{4} \int dx \, dy_{1} \, dy_{2} D_{xy_{2}} J(y_{2}) D_{xy_{1}} J(y_{1})$$

$$\tag{158}$$

$$+\frac{i}{2}\int dx\,dy\,dz_1\,dz_2\,J(x)\,D_{xy}D_{yz_1}J(z_1)D_{yz_2}J(z_2)$$
(159)

$$\rightarrow \frac{\delta S_{1}[J]}{\delta J(x_{i})} = -\frac{i^{3}}{6} \int dx \, dy_{1} \, dy_{2} \, D_{xx_{i}} D_{xy_{2}} J(y_{2}) D_{xy_{1}} J(y_{1}) - \frac{i^{3}}{6} \int dx \, dy_{1} \, dy_{3} \, D_{xy_{3}} J(y_{3}) D_{xx_{i}} D_{xy_{1}} J(y_{1}) \quad \text{(160)}$$

$$-\frac{i^3}{6} \int dx \, dy_2 \, dy_3 \, D_{xy_3} J(y_3) D_{xy_2} J(y_2) D_{xx_1} \tag{161}$$

$$-\frac{i^2}{4} \int dx \, dy_1 \, D_{xx_i} D_{xy_1} J(y_1) - \frac{i^2}{4} \int dx \, dy_2 D_{xy_2} J(y_2) D_{xx_i}$$
 (162)

$$+\frac{i}{2}\int dy dz_1 dz_2 D_{x_1y}D_{yz_1}J(z_1)D_{yz_2}J(z_2) + \frac{i}{2}\int dx dy dz_2 J(x) D_{xy}D_{yx_1}D_{yz_2}J(z_2)$$
 (163)

$$+\frac{i}{2}\int dx\,dy\,dz_1\,J(x)\,D_{xy}D_{yz_1}J(z_1)D_{yx_i}$$
(164)

this terms contains only two J - performing the other three functional derivatives $\delta/\delta J(x_k)$ will result in a zero. And

$$S_2 = -\frac{1}{2} \int dx \,\phi_0^2 \phi_1 - \frac{1}{2} \int dx \,\phi_0 \phi_1 + \int dx \,J(x)\phi_2 \tag{165}$$

$$= -\frac{i^2}{2} \int dx \, dy_1 dy_2 \, D_{xy_2} J(y_2) D_{xy_1} J(y_1) \frac{i}{2} \iiint d^4 y \, d^4 z_1 \, d^4 z_2 \, D_{xy} D_{yz_1} J(z_1) D_{yz_2} J(z_2)$$
 (166)

$$-\frac{i^2}{2} \int dx \, dy_1 dD_{xy_2} J(y_2) \frac{i}{2} \iiint d^4y \, d^4z_1 \, d^4z_2 \, D_{xy} D_{yz_1} J(z_1) D_{yz_2} J(z_2)$$
(167)

$$+ \int dx J(x) \frac{i}{2} \int du \, dw \, dy \, dz_1 \, dz_2 \, D_{xu} D_{uw} J(w) D_{uy} D_{yz_1} J(z_1) D_{yz_2} J(z_2)$$
 (168)

$$= -\frac{i^3}{4} \int dx \, dy_1 dy_2 \, dy \, dz_1 \, dz_2 \, D_{xy_2} J(y_2) D_{xy_1} J(y_1) D_{xy} D_{yz_1} J(z_1) D_{yz_2} J(z_2)$$
(169)

$$+\frac{i}{2}\int dx\,du\,dw\,dy\,dz_1\,dz_2\,J(x)D_{xu}D_{uw}J(w)D_{uy}D_{yz_1}J(z_1)D_{yz_2}J(z_2)+\mathcal{O}(J^3)$$
(170)

Now first integral - one derivative

$$\frac{\delta}{\delta J(x_1)} \int dx \, dy_1 \, dy_2 \, dy \, dz_1 \, dz_2 \, D_{xy_2} J(y_2) D_{xy_1} J(y_1) D_{xy} D_{yz_1} J(z_1) D_{yz_2} J(z_2) \tag{171}$$

$$= \int dx \, dy_1 \, dy \, dz_1 \, dz_2 \, D_{xx_1} D_{xy_1} J(y_1) D_{xy} D_{yz_1} J(z_1) D_{yz_2} J(z_2)$$
(172)

$$+ \int dx \, dy_2 \, dy \, dz_1 \, dz_2 \, D_{xy_2} J(y_2) D_{xx_1} D_{xy} D_{yz_1} J(z_1) D_{yz_2} J(z_2)$$
(173)

$$+ \int dx \, dy_1 \, dy_2 \, dy \, dz_2 \, D_{xy_2} J(y_2) D_{xy_1} J(y_1) D_{xy} D_{yx_1} D_{yz_2} J(z_2)$$
 (174)

$$+ \int dx \, dy_1 \, dy_2 \, dy \, dz_1 \, D_{xy_2} J(y_2) D_{xy_1} J(y_1) D_{xy} D_{yz_1} J(z_1) D_{yz_1}$$
(175)

two derivatives

$$\frac{\delta}{\delta J(x_2)} \frac{\delta}{\delta J(x_1)} \int dx \, dy_1 \, dy_2 \, dy \, dz_1 \, dz_2 \, D_{xy_2} J(y_2) D_{xy_1} J(y_1) D_{xy} D_{yz_1} J(z_1) D_{yz_2} J(z_2) \tag{176}$$

$$= + \int dx \, dy \, dz_1 \, dz_2 \, D_{xx_1} D_{xx_2} D_{xy} D_{yz_1} J(z_1) D_{yz_2} J(z_2)$$
 (177)

$$+ \int dx \, dy_1 \, dy \, dz_2 \, D_{xx_1} D_{xy_1} J(y_1) D_{xy} D_{yx_2} D_{yz_2} J(z_2)$$
 (178)

$$+ \int dx \, dy_1 \, dy \, dz_1 \, D_{xx_1} D_{xy_1} J(y_1) D_{xy} D_{yz_1} J(z_1) D_{yx_2}$$
 (179)

$$+ \int dx \, dy_2 \, dy \, dz_2 \, D_{xy_2} J(y_2) D_{xx_1} D_{xy} D_{yx_2} D_{yz_2} J(z_2)$$
 (180)

$$+ \int dx \, dy \, dz_1 \, dz_2 \, D_{xx_2} D_{xx_1} D_{xy} D_{yz_1} J(z_1) D_{yz_2} J(z_2)$$
 (181)

$$+ \int dx \, dy_2 \, dy \, dz_1 \, D_{xy_2} J(y_2) D_{xx_1} D_{xy} D_{yz_1} J(z_1) D_{yx_2}$$
 (182)

$$+ \int dx \, dy_1 \, dy \, dz_2 \, D_{xx_2} D_{xy_1} J(y_1) D_{xy} D_{yx_1} D_{yz_2} J(z_2)$$
 (183)

$$+ \int dx \, dy_2 \, dy \, dz_2 \, D_{xy_2} J(y_2) D_{xx_2} D_{xy} D_{yx_1} D_{yz_2} J(z_2)$$
 (184)

$$+ \int dx \, dy_1 \, dy_2 \, dy \, D_{xy_2} J(y_2) D_{xy_1} J(y_1) D_{xy} D_{yx_1} D_{yx_2}$$
 (185)

$$+ \int dx \, dy_1 \, dy \, dz_1 \, D_{xx_2} D_{xy_1} J(y_1) D_{xy} D_{yz_1} J(z_1) D_{yz_1}$$
 (186)

$$+ \int dx \, dy_2 \, dy \, dz_1 \, D_{xy_2} J(y_2) D_{xx_2} D_{xy} D_{yz_1} J(z_1) D_{yz_1}$$
 (187)

$$+ \int dx \, dy_1 \, dy_2 \, dy \, D_{xy_2} J(y_2) D_{xy_1} J(y_1) D_{xy} D_{yx_2} D_{yz_1}$$
 (188)

three derivatives

$$\frac{\delta}{\delta J(x_3)} \frac{\delta}{\delta J(x_2)} \frac{\delta}{\delta J(x_1)} \int dx \, dy_1 \, dy_2 \, dy \, dz_1 \, dz_2 \, D_{xy_2} J(y_2) D_{xy_1} J(y_1) D_{xy} D_{yz_1} J(z_1) D_{yz_2} J(z_2) \qquad (189)$$

$$= + \int dx \, dy \, dz_2 \, D_{xx_1} D_{xx_2} D_{xy} D_{yx_3} D_{yz_2} J(z_2) + \int dx \, dy \, dz_1 \, D_{xx_1} D_{xx_2} D_{xy} D_{yz_1} J(z_1) D_{yx_3} \qquad (190)$$

$$+ \int dx \, dy \, dz_2 \, D_{xx_1} D_{xx_3} D_{xy} D_{yx_2} D_{yz_2} J(z_2) + \int dx \, dy_1 \, dy \, D_{xx_1} D_{xy_1} J(y_1) D_{xy} D_{yx_2} D_{yx_3} \qquad (191)$$

$$+ \int dx \, dy \, dz_1 \, D_{xx_1} D_{xx_3} D_{xy} D_{yz_1} J(z_1) D_{yx_2} + \int dx \, dy_1 \, dy \, D_{xx_1} D_{xy_1} J(y_1) D_{xy} D_{yx_3} D_{yx_2} \qquad (192)$$

$$+ \int dx \, dy \, dz_2 \, D_{xx_3} D_{xx_1} D_{xy} D_{yx_2} D_{yz_2} J(z_2) + \int dx \, dy_2 \, dy \, D_{xy_2} J(y_2) D_{xx_1} D_{xy} D_{yx_2} D_{yx_3} \qquad (193)$$

$$+ \int dx \, dy \, dz_2 \, D_{xx_2} D_{xx_1} D_{xy} D_{yx_3} D_{yz_2} J(z_2) + \int dx \, dy_2 \, dy \, D_{xy_2} J(y_2) D_{xx_1} D_{xy} D_{yx_3} D_{yx_2} \qquad (195)$$

$$+ \int dx \, dy \, dz_1 \, D_{xx_3} D_{xx_1} D_{xy} D_{yx_1} J(z_1) D_{yx_2} + \int dx \, dy_2 \, dy \, D_{xy_2} J(y_2) D_{xx_1} D_{xy} D_{yx_3} D_{yx_2} \qquad (195)$$

$$+ \int dx \, dy \, dz_2 \, D_{xx_3} D_{xy_2} D_{yx_1} D_{yz_2} J(z_2) + \int dx \, dy_1 \, dy \, D_{xx_2} J(y_2) D_{xx_2} D_{xy_1} D_{yx_3} \qquad (196)$$

$$+ \int dx \, dy \, dz_2 \, D_{xx_3} D_{xy_2} D_{yx_1} D_{yz_2} J(z_2) + \int dx \, dy_1 \, dy \, D_{xy_2} J(y_2) D_{xx_2} D_{xy_2} D_{yx_1} D_{yx_3} \qquad (197)$$

$$+ \int dx \, dy \, dz_2 \, D_{xx_3} D_{xy_2} D_{yx_1} D_{yz_2} J(z_2) + \int dx \, dy_2 \, dy \, D_{xy_2} J(y_2) D_{xx_2} D_{xy_2} D_{yx_1} D_{yx_2} \qquad (198)$$

$$+ \int dx \, dy_1 \, dy \, D_{xx_3} D_{xy_1} J(y_1) D_{xy_2} D_{yx_1} D_{yx_2} + \int dx \, dy_2 \, dy \, D_{xy_2} J(y_2) D_{xx_3} D_{xy_2} D_{yx_1} D_{yx_2} \qquad (198)$$

$$+ \int dx \, dy \, dz_1 \, D_{xx_2} D_{xx_3} D_{xy_2} D_{yz_1} J(z_1) D_{yz_1} + \int dx \, dy_1 \, dy \, D_{xx_2} D_{xy_1} J(y_1) D_{xy_2} D_{yx_3} D_{yz_1} \qquad (199)$$

$$+ \int dx \, dy \, dz_1 \, D_{xx_3} D_{xy_1} J(y_1) D_{xy_2} D_{yz_1} J(z_1) D_{yz_1} + \int dx \, dy_1 \, dy \, D_{xy_2} J(y_2) D_{xx_3} D_{xy_2} D_{yy_3} D_{yz_1} \qquad (200)$$

$$+ \int dx \, dy_2 \, dy \, D_{xx_3}$$

four derivatives

$$\frac{\delta}{\delta J(x_4)} \frac{\delta}{\delta J(x_3)} \frac{\delta}{\delta J(x_2)} \frac{\delta}{\delta J(x_1)} \int dx \, dy_1 \, dy_2 \, dy \, dz_1 \, dz_2 \, D_{xy_2} J(y_2) D_{xy_1} J(y_1) D_{xy} D_{yz_1} J(z_1) D_{yz_2} J(z_2) \qquad (202)$$

$$= + \int dx \, dy \, D_{xx_1} D_{xx_2} D_{xy} D_{yx_3} D_{yx_4} + \int dx \, dy \, D_{xx_1} D_{xx_2} D_{xy} D_{yx_4} D_{yx_3} \qquad (203)$$

$$+ \int dx \, dy \, D_{xx_1} D_{xx_3} D_{xy} D_{yx_2} D_{yx_4} + \int dx \, dy \, D_{xx_1} D_{xx_4} D_{xy} D_{yx_2} D_{yx_3} \qquad (204)$$

$$+ \int dx \, dy \, D_{xx_1} D_{xx_3} D_{xy} D_{yx_2} D_{yx_4} + \int dx \, dy \, D_{xx_1} D_{xx_4} D_{xy} D_{yx_2} D_{yx_3} \qquad (205)$$

$$+ \int dx \, dy \, D_{xx_3} D_{xx_1} D_{xy} D_{yx_2} D_{yx_4} + \int dx \, dy \, D_{xx_1} D_{xy} D_{yx_2} D_{yx_3} \qquad (207)$$

$$+ \int dx \, dy \, D_{xx_2} D_{xx_1} D_{xy} D_{yx_3} D_{yx_4} + \int dx \, dy \, D_{xx_2} D_{xx_1} D_{xy} D_{yx_3} D_{yx_2} \qquad (208)$$

$$+ \int dx \, dy \, D_{xx_2} D_{xx_3} D_{xy} D_{yx_1} D_{yx_4} + \int dx \, dy \, D_{xx_2} D_{xx_4} D_{xy} D_{yx_1} D_{yx_3} \qquad (209)$$

$$+ \int dx \, dy \, D_{xx_2} D_{xx_3} D_{xy} D_{yx_1} D_{yx_4} + \int dx \, dy \, D_{xx_2} D_{xx_4} D_{xy} D_{yx_1} D_{yx_3} \qquad (210)$$

$$+ \int dx \, dy \, D_{xx_3} D_{xx_4} D_{xy} D_{yx_1} D_{yx_2} + \int dx \, dy \, D_{xx_4} D_{xx_2} D_{xy} D_{yx_1} D_{yx_2} \qquad (211)$$

$$+ \int dx \, dy \, D_{xx_3} D_{xx_4} D_{xy} D_{yx_4} D_{yz_1} + \int dx \, dy \, D_{xx_4} D_{xy} D_{yx_3} D_{yz_1} \qquad (212)$$

$$+ \int dx \, dy \, D_{xx_3} D_{xx_4} D_{xy} D_{yx_4} D_{yz_1} + \int dx \, dy \, D_{xx_4} D_{xx_2} D_{xy} D_{yx_3} D_{yz_1} \qquad (212)$$

$$+ \int dx \, dy \, D_{xx_3} D_{xx_4} D_{xy} D_{yx_4} D_{yz_1} + \int dx \, dy \, D_{xx_4} D_{xx_2} D_{xy} D_{yx_3} D_{yz_1} \qquad (212)$$

$$+ \int dx \, dy \, D_{xx_3} D_{xx_4} D_{xy} D_{yx_4} D_{yz_1} + \int dx \, dy \, D_{xx_4} D_{xx_2} D_{xy} D_{yx_3} D_{yz_1} \qquad (213)$$

$$+ \int dx \, dy \, D_{xx_3} D_{xx_4} D_{xy} D_{yx_4} D_{yz_1} + \int dx \, dy \, D_{xx_4} D_{xx_2} D_{xy} D_{yx_3} D_{yz_1} \qquad (213)$$

$$\frac{\delta}{\delta J(x_4)} \frac{\delta}{\delta J(x_3)} \frac{\delta}{\delta J(x_2)} \frac{\delta}{\delta J(x_1)} \int dx \, dy_1 \, dy_2 \, dy \, dz_1 \, dz_2 \, D_{xy_2} J(y_2) D_{xy_1} J(y_1) D_{xy} D_{yz_1} J(z_1) D_{yz_2} J(z_2)$$

$$= 4 \int dx \, dy \, D_{xx_1} D_{xx_2} D_{xy} D_{yx_3} D_{yx_4} + 4 \int dx \, dy \, D_{xx_1} D_{xx_3} D_{xy} D_{yx_2} D_{yx_4} + 4 \int dx \, dy \, D_{xx_1} D_{xx_4} D_{xy} D_{yx_2} D_{yx_3}$$

$$+ 4 \int dx \, dy \, D_{xx_2} D_{xx_3} D_{xy} D_{yx_1} D_{yx_4} + 4 \int dx \, dy \, D_{xx_2} D_{xx_4} D_{xy} D_{yx_1} D_{yx_3} + 4 \int dx \, dy \, D_{xx_3} D_{xx_4} D_{xy} D_{yx_3} D_{yx_4}$$

Second integral - analog calculation

$$\frac{\delta}{\delta J(x_4)} \frac{\delta}{\delta J(x_3)} \frac{\delta}{\delta J(x_2)} \frac{\delta}{\delta J(x_2)} \frac{\delta}{\delta J(x_1)} \int dx \, du \, dw \, dy \, dz_1 \, dz_2 \, J(x) D_{xu} D_{uw} J(w) D_{uy} D_{yz_1} J(z_1) D_{yz_2} J(z_2)$$

$$(215)$$

$$= 2 \int du \, dy \, D_{x_1 u} D_{ux_2} D_{uy} D_{yx_3} D_{yx_4} + 2 \int du \, dy \, D_{x_2 u} D_{ux_2} D_{uy} D_{yx_3} D_{yx_4} + 2 \int du \, dy \, D_{x_1 u} D_{ux_3} D_{uy} D_{yx_2} D_{yx_4}$$

$$(216)$$

$$+ 2 \int du \, dy \, D_{x_3 u} D_{ux_1} D_{uy} D_{yx_2} D_{yx_4} + 2 \int du \, dy \, D_{x_1 u} D_{ux_4} D_{uy} D_{yx_2} D_{yx_3} + 2 \int du \, dy \, D_{x_4 u} D_{ux_1} D_{uy} D_{yx_2} D_{yx_3}$$

$$(217)$$

$$+ 2 \int du \, dy \, D_{x_2 u} D_{ux_3} D_{uy} D_{yx_1} D_{yx_4} + 2 \int du \, dy \, D_{x_3 u} D_{ux_2} D_{uy} D_{yx_1} D_{yx_4} + 2 \int du \, dy \, D_{x_2 u} D_{ux_4} D_{uy} D_{yx_1} D_{yx_3}$$

$$(218)$$

$$+ 2 \int du \, dy \, D_{x_4 u} D_{ux_2} D_{uy} D_{yx_1} D_{yx_3} + 2 \int du \, dy \, D_{x_3 u} D_{ux_4} D_{uy} D_{yx_1} D_{yx_2} + 2 \int du \, dy \, D_{x_4 u} D_{ux_3} D_{uy} D_{yx_1} D_{yx_2}$$

$$(218)$$

This last two expression is all that survives the funtional derivatives and setting $J \to 0$.

Now we can calculate one example term of the first integral using the Klein-Gordon Greens function property of the Feynman propagator $(\Box_x - m^2)D_F(x-y) = i\delta^{(4)}(x-y)$

$$\int d^4x_1 e^{i(k_1x_1)} (\Box_{x_1} - m^2) \int dx \, dy \, D_{xx_1} D_{xx_2} D_{xy} D_{yx_3} D_{yx_4} = \int dx \, dy \, e^{i(k_1x_1)} (-i) \delta^{(4)} (x - x_1) D_{xx_2} D_{xy} D_{yx_3} D_{yx_4}$$

$$= -i \int dx \, dy \, e^{i(k_1x)} D_{xx_2} D_{xy} D_{yx_3} D_{yx_4}$$
(221)

so we can generalize to the x_1, x_2, x_3, x_4 integration - and do the Fourier trafo of the Feynman propagator (via substitution u = x - y, v = y, meaning x = u + v, y = v, dxdy = dudv)

$$\int \prod_{i=1}^{4} d^{4}x_{i} e^{i(k_{i}x_{i})} (\Box_{x_{i}} - m^{2}) \int dx \, dy \, D_{xx_{1}} D_{xx_{2}} D_{xy} D_{yx_{3}} D_{yx_{4}} = (-i)^{4} \int dx \, dy \, e^{i(k_{1}x + k_{2}x + k_{3}y + k_{4}y)} D_{xy} \qquad (222)$$

$$= \int dx \, dy \, e^{i(k_{1} + k_{2})x + i(k_{3} + k_{4})y} D_{F}(x - y) \qquad (223)$$

$$= \int du \, dv \, e^{i(k_{1} + k_{2})(u + v) + i(k_{3} + k_{4})v} D_{F}(u) \qquad (224)$$

$$= \int dv \, e^{i(k_{1} + k_{2} + k_{3} + k_{4})v} \cdot \int du \, e^{i(k_{1} + k_{2})u} D_{F}(u) \qquad (225)$$

$$= (2\pi)^{4} \delta^{(4)}(k_{1} + k_{2} + k_{3} + k_{4}) \frac{i}{(k_{1} + k_{2})^{2} - m^{2} + i\epsilon}$$

we see that all the 6 different terms end up in the similar expression.

Now we can do one term of the second integral

$$\int \prod_{i=1}^{4} d^{4}x_{i} e^{i(k_{i}x_{i})} (\Box_{x_{i}} - m^{2}) \int du \, dy \, D_{x_{1}u} D_{ux_{2}} D_{uy} D_{yx_{3}} D_{yx_{4}} = (-i)^{4} \int du \, dy \, e^{i(k_{1}u + k_{2}u + k_{3}y + k_{4}y)} D_{F}(u - y)$$

$$= (-i)^{4} \int du \, dy \, e^{i(k_{1} + k_{2})u} e^{i(k_{3} + k_{4})y} D_{F}(u - y)$$

$$= (228)$$

$$= (2\pi)^{4} \delta^{(4)}(k_{1} + k_{2} + k_{3} + k_{4}) \frac{i}{(k_{1} + k_{2})^{2} - m^{2} + i\epsilon}$$

$$= (2\pi)^{4} \delta^{(4)}(k_{1} + k_{2} + k_{3} + k_{4}) \frac{i}{(k_{1} + k_{2})^{2} - m^{2} + i\epsilon}$$

$$= (2\pi)^{4} \delta^{(4)}(k_{1} + k_{2} + k_{3} + k_{4}) \frac{i}{(k_{1} + k_{2})^{2} - m^{2} + i\epsilon}$$

$$= (2\pi)^{4} \delta^{(4)}(k_{1} + k_{2} + k_{3} + k_{4}) \frac{i}{(k_{1} + k_{2})^{2} - m^{2} + i\epsilon}$$

$$= (2\pi)^{4} \delta^{(4)}(k_{1} + k_{2} + k_{3} + k_{4}) \frac{i}{(k_{1} + k_{2})^{2} - m^{2} + i\epsilon}$$

$$= (2\pi)^{4} \delta^{(4)}(k_{1} + k_{2} + k_{3} + k_{4}) \frac{i}{(k_{1} + k_{2})^{2} - m^{2} + i\epsilon}$$

$$= (2\pi)^{4} \delta^{(4)}(k_{1} + k_{2} + k_{3} + k_{4}) \frac{i}{(k_{1} + k_{2})^{2} - m^{2} + i\epsilon}$$

$$= (2\pi)^{4} \delta^{(4)}(k_{1} + k_{2} + k_{3} + k_{4}) \frac{i}{(k_{1} + k_{2})^{2} - m^{2} + i\epsilon}$$

So in total we should get three types of terms for the pairs (s, t, u-channels) k_1 , k_2 and k_1 , k_3 and k_1 , k_4 (I would need some more time to collect all prefactors)

$$\int \prod_{i=1}^{4} d^4 x_i \, e^{i(k_i x_i)} (\Box_{x_i} - m^2) \, \frac{\delta}{\delta J(x_i)} S[(J)] \bigg|_{J=0} = \lambda^2 \int \prod_{i=1}^{4} d^4 x_i \, e^{i(k_i x_i)} (\Box_{x_i} - m^2) \, \frac{\delta}{\delta J(x_i)} S_2[(J)] \bigg|_{J=0}$$

$$\sim \lambda^2 (2\pi)^4 \delta^{(4)} (k_1 + k_2 + k_3 + k_4) \left(\frac{1}{(k_1 + k_2)^2 - m^2} + \frac{1}{(k_1 + k_3)^2 - m^2} + \frac{1}{(k_1 + k_4)^2 - m^2} \right)$$
(230)