IMPLEMENTING AN OBJECTIVE FUNCTION AND REPORTING THE EFFECTS OF REGULARISATION ON GENERATIVE MODELS

Chad Kakau

Victoria University, Wellington

ABSTRACT

this paper revises the concept of objective functions as applied in machine learning and identifies the SELECTED OBJECTIVE FUNCTION used by the authors in the implementation of a generative neural network. The generative model maps a gaussian distribution to a uniform distribution, then maps the uniform distribution to a gaussian distribution, for a concatenated gaussian to gaussian network. This paper lists the three main objective functions used in neural networks and SOMETHING TO SAY GOES THROUGH THE MATH of the selected function: . The results of the implemented neural network show that

Index Terms— One, two, three, four, five

1. INTRODUCTION

Neural networks have become a mainstay of image processing over the last two decades (compare [1] and [2])

2. OBJECTIVE FUNCTION

We train a neural network using stochastic gradient descent so that it can iteratively learn and adjust from the prediction (based on each instance, or input vector) and distance from the actual target (output vector). One of the main decisions for the design of the network is the selection of an objective function to drive the model predictions toward the target. Although numerous objective functions are possible, this implementation uses the Maximum Mean Discrepancy which measures the distance between two distributions. For optimisation the model aims to minimise MMD. Before working through the theory of the MMD, we need to first briefly discuss the kernel - a concept which has taken several days of bashing my head against the internet wall, for me to finally come to grips with.

2.1. The kernel function reduces the complexity of calculation without sacrificing detail

After several lectures, reviews of lecturs, scanning of the internet and multiple re-visits to the wikipedia, I think the ker-

nel, is a matrix that transforms our input vector in a lower dimensional space to the dot product output vector in a higher dimensional space [3] [4]. I struggled alot with the concept of the kernel, because I didn't take the time to look up what an inner product means... it turns out, an inner product is the result of multiplying two vectors and resolves to a scalar value.

For instance, for the function $h(\cdot)$, in a reproducing kernel Hilbert space (I can't, so here is a link to an accessible explanation...), with kernel k:, then $h(x) = \langle k(x, \cdot), h(\cdot) \rangle$.

2.2. Maximum Mean Distribution as the objective function

With the distribution p_Y as:

$$\frac{1}{n(n-1)} \sum_{i \neq j} k(y^{(i)}, y^{(j)})$$
and p_X as:
$$\frac{1}{m(m-1)} \sum_{i \neq j} k(x^{(i)}, x^{(j)}),$$

where $k(\boldsymbol{x}, \boldsymbol{y})$ is a positive definite kernel (in this case, the Gaussian kernel

$$MMD(\{x^{(i)}\}_{i=1,...,m}, \{y^{(j)}\}_{j=1,...,n})$$
=
+
$$-2\frac{1}{mn}\sum_{i,j}k(x^{(i)}, y^{(j)})$$

The theory: Why obective functions? - machine learning applies models to iteratively improve performance at generating a desired output (ref) - improves by 'moving' actual outputs closer to desired outputs, using an objective function tht calculates the difference or similarity between the actual output an the desired output - can be applied at the level of individual instances or across the distribution of input and output sets why regularisation? - list the options and distinguish between the options (method, output, application) - link the selected option with this problem - which will be the best for low/high outliers - which will be the best for which objective function?

- map the math -

AIML425

3. RESULTS

3.1. Subheadings

3.1.1. Sub-subheadings

4. ILLUSTRATIONS, GRAPHS, AND PHOTOGRAPHS

Since there are many ways, often incompatible, of including images (e.g., with experimental results) in a LaTeX document, below is an example of how to do this.

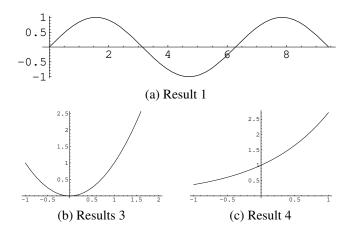


Fig. 1. Example of placing a figure with experimental results.

5. CONCLUSION

Write a conclusion.

6. REFERENCES

- [1] Raffaele Parisi, Elio D Di Claudio, G Lucarelli, and G Orlandi, "Car plate recognition by neural networks and image processing," in 1998 IEEE International Symposium on Circuits and Systems (ISCAS). IEEE, 1998, vol. 3, pp. 195–198.
- [2] Jose Naranjo-Torres, Marco Mora, Ruber Hernandez-Garcia, Ricardo J Barrientos, Claudio Fredes, and Andres Valenzuela, "A review of convolutional neural network applied to fruit image processing," *Applied Sciences*, vol. 10, no. 10, pp. 3443, 2020.
- [3] Drew Wilimitis, "The kernel trick," Feb 2019.
- [4] Thomas Hofmann, Bernhard Scholkopf, and Alexander J Smola, "Kernel methods in machine learning," *The annals of statistics*, vol. 36, no. 3, pp. 1171–1220, 2008.