

Krylov Linear Solvers and Quasi Monte Carlo Methods for Transport Simulations

Sam Pasmann,^a C. T. Kelley,^b and Ryan McClarren^{*,a}

*^aDepartment of Aerospace and Mechanical Engineering
University of Notre Dame
Fitzpatrick Hall, Notre Dame, IN 46556*

*^bNorth Carolina State University, Department of Mathematics
3234 SAS Hall, Box 8205
Raleigh NC 27695-8205*

*Email: rmcclarr@nd.edu

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Abstract

QMC + Krylov

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I. INTRODUCTION

II. COMPUTATIONAL RESULTS

In this section we consider an example from [1]. The formulation of the transport problem is taken from [2]. The equation for the angular flux ψ is

$$\mu \frac{\partial \psi}{\partial x}(x, \mu) + \Sigma_t(x) \psi(x, \mu) = \frac{1}{2} \left[\Sigma_s(x) \int_{-1}^1 \psi(x, \mu') d\mu' + q(x) \right] \text{ for } 0 \leq x \leq \tau \quad (1)$$

The boundary conditions are

$$\psi(0, \mu) = \psi_l(\mu), \mu > 0; \psi(\tau, \mu) = \psi_r(\mu), \mu < 0.$$

II.A. Multigroup Equations

In general geometry the multigroup equations are

$$\mu \frac{\partial \psi_g}{\partial x}(x, \mu) + \Sigma_{t,g}(x) \psi_g(x, \mu) = \frac{1}{2} \sum_{g'=1}^G \Sigma_{s,g' \rightarrow g}(x) \int_{-1}^1 \psi_{g'}(x, \mu') d\mu' + \frac{q_g(x)}{2} \quad g = 1, \dots, G. \quad (2)$$

The boundary conditions are

$$\psi_g(0, \mu) = \psi_{l,g}(\mu), \mu > 0; \psi_g(\tau, \mu) = \psi_{r,g}(\mu), \mu < 0.$$

In matrix form, these equations are

$$\mu \frac{\partial \vec{\psi}}{\partial x}(x, \mu) + \underline{\Sigma}_t(x) \vec{\psi}(x, \mu) = \frac{1}{2} \underline{\Sigma}_s(x) \int_{-1}^1 \vec{\psi}(x, \mu') d\mu' + \frac{\vec{q}(x)}{2}, \quad (3)$$

where

$$\vec{\psi} = (\psi_1, \psi_2, \dots, \psi_G)^T, \quad \vec{q} = (q_1, q_2, \dots, q_G)^T, \quad (4)$$

$$\underline{\Sigma}_t(x) = \begin{pmatrix} \Sigma_{t,1}(x) & 0 & \dots \\ 0 & \Sigma_{t,2}(x) & 0 \dots \\ \vdots & & \ddots \\ 0 & \dots & 0 & \Sigma_{t,G}(x) \end{pmatrix}, \quad (5)$$

and

$$\underline{\Sigma}_s(x) = \begin{pmatrix} \Sigma_{s,1 \rightarrow 1}(x) & \Sigma_{s,2 \rightarrow 1}(x) & \dots & \Sigma_{s,G \rightarrow 1}(x) \\ \Sigma_{s,2 \rightarrow 1}(x) & \Sigma_{s,2 \rightarrow 1}(x) & \dots & \Sigma_{s,G \rightarrow 2}(x) \\ \vdots & \vdots & & \vdots \\ \Sigma_{s,G \rightarrow 1}(x) & \Sigma_{s,G \rightarrow 1}(x) & \dots & \Sigma_{s,G \rightarrow G}(x) \end{pmatrix}, \quad (6)$$

II.B. Source Iteration and Linear Solvers

Source iteration is Picard iteration for the fixed point problem

$$\phi = \mathcal{S}(\phi, q, \psi_l, \psi_r)$$

To use other solvers we must convert to a linear system via

$$\mathcal{K}(\phi) = \mathcal{S}(\phi, 0, 0, 0) \text{ and } f = \mathcal{S}(0, q, \psi_l, \psi_r)$$

to get

$$A\phi \equiv (I - \mathcal{K})\phi = f,$$

which we can send to a linear solver.

In the computations we use the problem from [1]

$$\tau = 5, \Sigma_s(x) = \omega_0 e^{-x/s}, \Sigma_t(x) = 1, q(x) = 0, \psi_l(\mu) = 1, \psi_r(\mu) = 0,$$

and consider two cases $s = 1$ and $s = \infty$

II.C. QMC and Krylov Linear Solvers

The linear and nonlinear solvers come from the Julia package [SIAMFANLEQ.jl](#) [3]. The documentation for these codes is in the [Juila notebooks](#) [4] and the book [5] that accompany the package.

We solve the QMC linear problem with $N=2048$ and $N_x=100$. We use two krylov methods [6], GMRES [7] and Bi-CGSTAB [8]. Figures 1 and 2 show that the Krylov iterations take fewer than half of the number of transport sweeps that Picard iteration required.

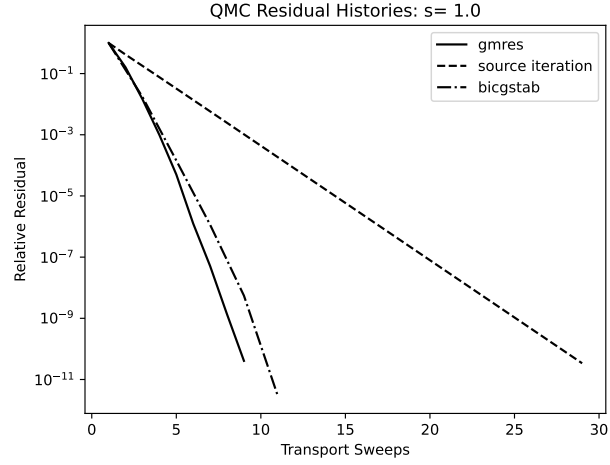


Fig. 1. $s = 1$

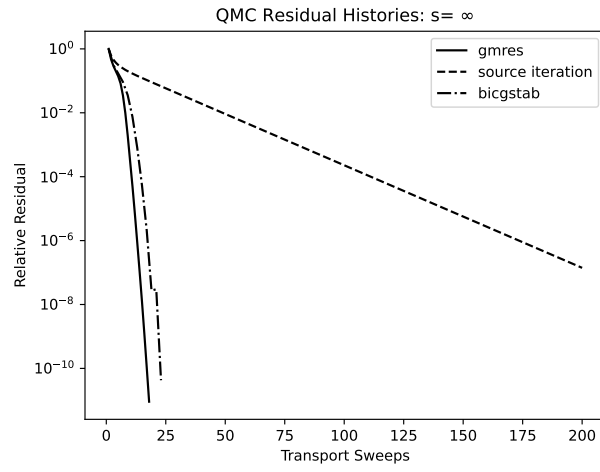


Fig. 2. $s = \infty$

II.D. Validation and calibration study

We conclude this section with a validation study. We compare the QMC results with the results from [1]. The results in [1] are exit distributions and are accurate to six figures. We have duplicated those results with an Sn computation on a fine angular and spatial mesh.

Sam, Ryan, should we use more or different values of N and Nx ?

For $N = 1000$ and $Nx = 100$ we obtain the cell-average fluxes from the QMC approximation. We then use a single Sn transport sweep to recover the exit distributions from the QMC cell-average fluxes. We report the results and the corresponding results from [1] in Tables I and II.

The exit distributions, as is clear from Table I can vary by five orders of magnitude. Even so, the results from QMC agree with the benchmarks to roughly two figures.

TABLE I
Exit Distributions: $s = 1$

| Garcia/Siewert | | | QMC | |
|----------------|-----------------|-------------------|-----------------|-------------------|
| μ | $\psi(0, -\mu)$ | $\psi(\tau, \mu)$ | $\psi(0, -\mu)$ | $\psi(\tau, \mu)$ |
| 5.00e-02 | 5.89664e-01 | 6.07488e-06 | 5.71197e-01 | 5.85487e-06 |
| 1.00e-01 | 5.31120e-01 | 6.92516e-06 | 5.22137e-01 | 6.66741e-06 |
| 2.00e-01 | 4.43280e-01 | 9.64232e-06 | 4.41567e-01 | 9.25261e-06 |
| 3.00e-01 | 3.80306e-01 | 1.62339e-05 | 3.81029e-01 | 1.54416e-05 |
| 4.00e-01 | 3.32964e-01 | 4.38580e-05 | 3.34673e-01 | 4.09691e-05 |
| 5.00e-01 | 2.96090e-01 | 1.69372e-04 | 2.98224e-01 | 1.57373e-04 |
| 6.00e-01 | 2.66563e-01 | 5.73465e-04 | 2.68871e-01 | 5.35989e-04 |
| 7.00e-01 | 2.42390e-01 | 1.51282e-03 | 2.44749e-01 | 1.42448e-03 |
| 8.00e-01 | 2.22235e-01 | 3.24369e-03 | 2.24583e-01 | 3.07431e-03 |
| 9.00e-01 | 2.05174e-01 | 5.96036e-03 | 2.07478e-01 | 5.67991e-03 |
| 1.00e+00 | 1.90546e-01 | 9.77123e-03 | 1.92789e-01 | 9.35351e-03 |

In Tables III and IV we look at the relative errors in the QMC exit distributions as compared to a highly accurate SN result. We compensate for the widely varying scales by tabulating, for each value of N and Nx

$$R = \max(R^0, R^\tau)$$

where

$$R^0 = \max_{\mu} \frac{|\psi^{SN}(0, -\mu) - \psi^{QMC}(0, -\mu)|}{\psi^{SN}(0, -\mu)}$$

and

$$R^\tau = \max_{\mu} \frac{|\psi^{SN}(\tau, \mu) - \psi^{QMC}(\tau, \mu)|}{\psi^{SN}(\tau, \mu)}.$$

TABLE II
Exit Distributions: $s = \infty$

| μ | Garcia/Siewert | | QMC | |
|----------|-----------------|-------------------|-----------------|-------------------|
| | $\psi(0, -\mu)$ | $\psi(\tau, \mu)$ | $\psi(0, -\mu)$ | $\psi(\tau, \mu)$ |
| 5.00e-02 | 8.97798e-01 | 1.02202e-01 | 8.47454e-01 | 1.00663e-01 |
| 1.00e-01 | 8.87836e-01 | 1.12164e-01 | 8.52822e-01 | 1.10325e-01 |
| 2.00e-01 | 8.69581e-01 | 1.30419e-01 | 8.47710e-01 | 1.29064e-01 |
| 3.00e-01 | 8.52299e-01 | 1.47701e-01 | 8.35879e-01 | 1.46849e-01 |
| 4.00e-01 | 8.35503e-01 | 1.64497e-01 | 8.22291e-01 | 1.64034e-01 |
| 5.00e-01 | 8.18996e-01 | 1.81004e-01 | 8.08044e-01 | 1.80827e-01 |
| 6.00e-01 | 8.02676e-01 | 1.97324e-01 | 7.93459e-01 | 1.97336e-01 |
| 7.00e-01 | 7.86493e-01 | 2.13507e-01 | 7.78672e-01 | 2.13625e-01 |
| 8.00e-01 | 7.70429e-01 | 2.29571e-01 | 7.63768e-01 | 2.29725e-01 |
| 9.00e-01 | 7.54496e-01 | 2.45504e-01 | 7.48818e-01 | 2.45642e-01 |
| 1.00e+00 | 7.38721e-01 | 2.61279e-01 | 7.33889e-01 | 2.61361e-01 |

Ryan, for large N_x I see convergence as N increases. Is it clearly $1/N$? Am I missing something? Am I tabulating the wrong thing?

TABLE III
Exit Distributions Errors: $s = 1.0$

| $N_x \setminus N$ | 1000 | 2000 | 4000 | 8000 | 16000 |
|-------------------|-------------|-------------|-------------|-------------|-------------|
| 50 | 1.41162e-01 | 1.36428e-01 | 1.34747e-01 | 1.35736e-01 | 1.35577e-01 |
| 100 | 7.08438e-02 | 6.60744e-02 | 6.52017e-02 | 6.51605e-02 | 6.49914e-02 |
| 200 | 4.17171e-02 | 3.30480e-02 | 3.23088e-02 | 3.21432e-02 | 3.17467e-02 |
| 400 | 4.55590e-02 | 1.73115e-02 | 1.63072e-02 | 1.61542e-02 | 1.58469e-02 |
| 800 | 4.83754e-02 | 1.93087e-02 | 1.29178e-02 | 8.30117e-03 | 7.96562e-03 |
| 1600 | 5.07584e-02 | 2.03691e-02 | 1.44681e-02 | 4.52388e-03 | 4.11350e-03 |
| 3200 | 5.09694e-02 | 2.13418e-02 | 1.48086e-02 | 2.88667e-03 | 2.18194e-03 |

TABLE IV
Exit Distributions Errors: $s = \infty$

| $N_x \setminus N$ | 1000 | 2000 | 4000 | 8000 | 16000 |
|-------------------|-------------|-------------|-------------|-------------|-------------|
| 50 | 5.95648e-02 | 2.42755e-02 | 1.36521e-02 | 1.29509e-02 | 1.22769e-02 |
| 100 | 5.60749e-02 | 2.31030e-02 | 1.31680e-02 | 6.45949e-03 | 6.59550e-03 |
| 200 | 5.62864e-02 | 2.32524e-02 | 1.42149e-02 | 4.77319e-03 | 3.55246e-03 |
| 400 | 5.30954e-02 | 2.17854e-02 | 1.48225e-02 | 4.73260e-03 | 2.05558e-03 |
| 800 | 7.66264e-02 | 1.88155e-02 | 1.60082e-02 | 4.34610e-03 | 1.41402e-03 |
| 1600 | 5.99376e-02 | 2.15675e-02 | 1.56784e-02 | 4.21636e-03 | 1.29138e-03 |
| 3200 | 5.74319e-02 | 1.89482e-02 | 2.00195e-02 | 3.26688e-03 | 1.49649e-03 |

III. CONCLUSION

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