

Math 33A

Today:

- Topics: Solving Systems of Linear Eqns.

Matrix Algebra

Linear Transformations

- Office Hours: 1-2 pm, Zoom link on website

& syllabus

Topic : Solving Systems of Linear Eqns.
 & Gauss-Jordan elimination (Gaussian elimination, row reduction)

①

$$\begin{cases} x + 3y + 2z = 2 \\ 2x + 7y + 7z = -1 \\ 2x + 5y + 2z = 7 \end{cases}$$

Gauss-Jordan Elimination :

① Swap two rows

② Multiply / Divide a row by a scalar

③ Add a multiple of one row to another row

rows
coming
to eqns.

Augmented Matrix

x	y	z	
1	3	2	2
2	7	7	-1
2	5	2	7

coefficient matrix

RREF : (Row Reduced Echelon Form)

- ① First non-zero entry is a 1, called a leading 1
- ② Every other entry in same col. as a leading 1 is 0
- ③ All leading 1's above another leading 1 are to the left

$$\left[\begin{array}{ccc|c} 1 & 3 & 2 & 2 \\ 2 & 7 & 7 & -1 \\ 2 & 5 & 2 & 7 \end{array} \right] \xrightarrow{-2(I)} \left[\begin{array}{ccc|c} 1 & 3 & 2 & 2 \\ 0 & 1 & 3 & -5 \\ 2 & 5 & 2 & 7 \end{array} \right] \xrightarrow{-2(I)} \longrightarrow$$

$$\left[\begin{array}{ccc|c} 1 & 3 & 2 & 2 \\ 0 & 1 & 3 & -5 \\ 0 & -1 & -2 & 3 \end{array} \right] \xrightarrow{+ (II)} \left[\begin{array}{ccc|c} x & y & z & \\ 1 & 3 & 2 & 2 \\ 0 & 1 & 3 & -5 \\ 0 & 0 & 1 & -2 \end{array} \right]$$

① Read off matrix from here

$$z = -2$$

$$y + 3z = -5 \Rightarrow y - 6 = -5$$

$$y = 1$$

$$x + 3y + 2z = 2$$

$$x + 3 - 4 = 2 \Rightarrow x - 1 = 2$$

$$x = 3$$

② Reduce all the way to RREF

$$\left[\begin{array}{ccc|c} 1 & 3 & 2 & 2 \\ 0 & 1 & 0 & -5 \\ 0 & 0 & 1 & -2 \end{array} \right] \xrightarrow{-3(\text{III})}$$

$$\left[\begin{array}{ccc|c} 1 & 3 & 2 & 2 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & -2 \end{array} \right] \xrightarrow{-2(\text{III})}$$

$$\left[\begin{array}{ccc|c} 1 & 3 & 0 & 6 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & -2 \end{array} \right] \xrightarrow{-3(\text{II})}$$

$$\left[\begin{array}{ccc|c} 1 & 0 & 0 & 3 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & -2 \end{array} \right] \quad \boxed{\text{rank} = 3}$$

Def: The rank of a matrix is the number of leading 1's

- If my matrix has a row like $0 \dots 0 | 0$ & not all my cols have a leading 1
then I will have oo many solutions
- If there is a row like $0 \dots 0 | \text{non-zero}$
Then I have no solutions

Topic : Matrix Algebra

Matrix Multiplication : "row-by-col"

$$\begin{pmatrix} 2 & 1 \\ 3 & 1 \end{pmatrix} \begin{pmatrix} 3 & 1 \\ 2 & 1 \end{pmatrix} = \begin{pmatrix} 2 \cdot 3 + 1 \cdot 2 & 2 \cdot 1 + 1 \cdot 1 \\ 3 \cdot 3 + 1 \cdot 2 & 3 \cdot 1 + 1 \cdot 1 \end{pmatrix}$$

$2 \times 2 \qquad \qquad 2 \times 2$

$$= \begin{pmatrix} 8 & 3 \\ 11 & 4 \end{pmatrix}$$

2×3

$$\begin{pmatrix} 2 & 1 \\ 3 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \end{pmatrix} = \begin{pmatrix} 2 \cdot 1 + 1 \cdot 0 & 2 \cdot 0 + 1 \cdot 1 & 2 \cdot 1 + 1 \cdot 1 \\ 3 \cdot 1 + 1 \cdot 0 & 3 \cdot 0 + 1 \cdot 1 & 3 \cdot 1 + 1 \cdot 1 \end{pmatrix}$$

$2 \times 2 \qquad \qquad 2 \times 3$

$$= \begin{pmatrix} 2 & 1 & 3 \\ 3 & 1 & 4 \end{pmatrix}$$

Can only multiply matrices of different sizes when the

$$\left[\begin{array}{l} \text{number of cols of first matrix} \\ = \text{number of rows of second matrix} \end{array} \right]$$

- You can add matrices of the same size

A , $m \times n$ matrix,

$n \times 1$

$A \vec{v}$ where \vec{v} is a vector in \mathbb{R}^n ,

$m \times n$ $n \times 1$ \curvearrowright vector in \mathbb{R}^m

$$\begin{bmatrix} v_1 \\ \vdots \\ v_n \end{bmatrix}$$

(3.1)

$$\begin{pmatrix} 8 & 1 \\ 7 & 2 \end{pmatrix} \begin{pmatrix} 2 \\ -2 \end{pmatrix} = \begin{pmatrix} 8 \cdot 2 + 1 \cdot (-2) \\ 7 \cdot 2 + 2 \cdot (-2) \end{pmatrix} = \begin{pmatrix} 16 - 2 \\ 14 - 4 \end{pmatrix}$$
$$= \begin{pmatrix} 14 \\ 10 \end{pmatrix}$$

Linear Transformations:

$T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ is a linear transformation if:

$$\cdot T(\vec{x} + \vec{y}) = T(\vec{x}) + T(\vec{y})$$

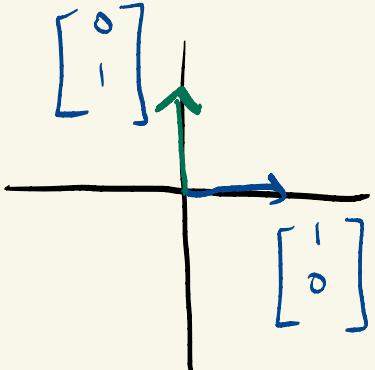
$$\cdot T(c\vec{x}) = cT(\vec{x}) \text{ for any scalar } c$$

$$T(\vec{x}) = A\vec{x}$$
, A $m \times n$ matrix

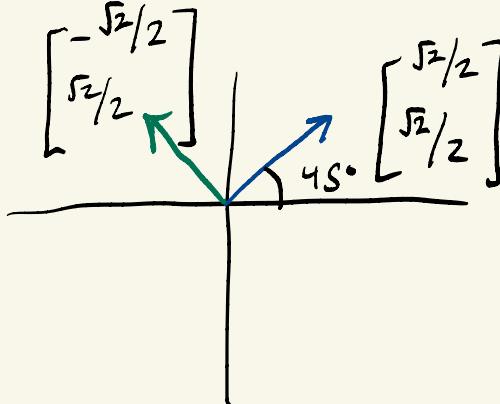
(5)

S.1 : Find a 2×2 matrix s.t. is rotates a vector \vec{v} by 45° counterclockwise

Key Idea : A linear transformation T is completely determined by where it sends the vectors $\begin{bmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix}, \dots, \begin{bmatrix} 0 \\ \vdots \\ 0 \\ 1 \end{bmatrix}$
(standard basis vectors)



rotate 45°
ccw



$$T(\vec{x}) = A \vec{x},$$

$$A = \begin{bmatrix} T[1] & T[0] \end{bmatrix}$$

$$= \begin{bmatrix} \sqrt{2}/2 & -\sqrt{2}/2 \\ \sqrt{2}/2 & \sqrt{2}/2 \end{bmatrix}$$