**Exercise 2.20:** Design a 1-bit synchronous adder <code>lBitAdder</code> by composing instances of And, Or, Not, and Xor gates. The component <code>lBitAdder</code> has three input variables x, y, and carry-in and two output variables z and carry-out. In each round, the value encoded by the two output bits z and carry-out, where z is the least significant bit, should equal the sum of the values of three input variables. Then, design a 3-bit synchronous adder <code>3BitAdder</code> by composing three instances of the component <code>1BitAdder</code>. The component <code>3BitAdder</code> has input variables  $x_0$ ,  $x_1$ ,  $x_2$ ,  $y_0$ ,  $y_1$ ,  $y_2$ , and carry-in and has output variables  $z_0$ ,  $z_1$ ,  $z_2$ , and carry-out. In each round, the 4-bit number encoded by the output variables  $z_0$ ,  $z_1$ ,  $z_2$ , and carry-out should equal the sum of the 3-bit number encoded by the input variables  $x_0$ ,  $x_1$ , and  $x_2$ , the 3-bit number encoded by the input variables  $y_0$ ,  $y_1$ , and  $y_2$ , and the input value of carry-in.

**Exercise 2.22:** Consider the leader election algorithm in synchronous networks (<u>figure 2.35</u>). Argue that if the value of *id* does not change in a given round, then there is no need to send it in the following round (that is, the output *out* can be absent in the next round). This can reduce the number of messages sent. Modify the description of the component SyncleNode to implement this change. ■

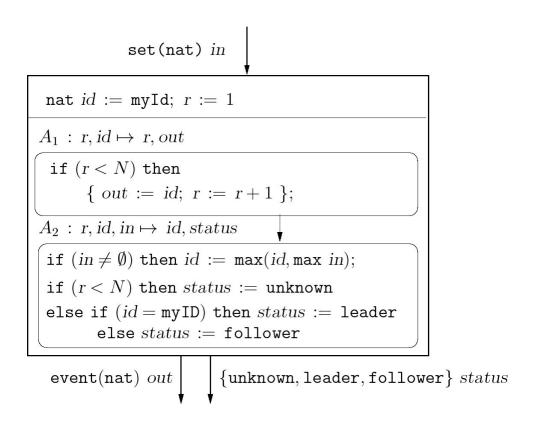


Figure 2.35: Component SyncLENode for Synchronous Leader Election

**Exercise 3.6:** Consider a transition system T with two integer variables x and y and a Boolean variable z. All the variables are initially 0. The transitions of the system correspond to executing the conditional statement

if 
$$(z = 0)$$
 then  $\{x := x + 1; z := 1\}$  else  $\{y := y + 1; z := 0\}$ .

Consider the property  $\phi$  given by  $(x = y) \lor (x = y + 1)$ . Is  $\phi$  an invariant of the transition system T? Is  $\phi$  an inductive invariant of the transition system T? Find a formula  $\psi$  such that  $\psi$  is stronger than  $\phi$  and is an inductive invariant of the transition system T. Justify your answers.

**Exercise 3.7:** Recall the transition system Mult(m, n) from exercise 3.1. First, show that the invariant property  $(mode = stop) \rightarrow (y = m \cdot n)$  is not an inductive invariant. Then find a stronger property that is an inductive invariant. Justify your answers.

**Exercise 3.1:** Given two natural numbers m and n, consider the program Mult that multiplies the input numbers using two variables x and y, of type nat, as shown in figure 3.2. Describe the transition system Mult(m, n) that captures the behavior of this program on input numbers m and n, that is, describe the states, initial states, and transitions. Argue that when the value of the variable x is 0, the value of the variable y must equal the product of the input numbers m and n, that is, the following property is an invariant of this transition system:

$$(mode = stop) \rightarrow (y = m \cdot n)$$

 $(x>0) \rightarrow \{x:=x-1; \ y:=y+n\}$  nat x:=m; y:=0 (x=0)? stop

Figure 3.2: Program for Multiplication

**Exercise 3.3:** The reaction description for the controller Controller2 consists of three tasks as shown in figure 3.8. Split the task  $A_3$  into four tasks, each of which writes exactly one of the state variables *east*, *west*, *near*<sub>W</sub>, and *near*<sub>E</sub>. Each task should be described by its read-set, write-set, and update code, along with the necessary precedence constraints. The revised description should have the same set of reactions as the original description. Does this splitting impact output/ input await dependencies? If not, what would be the potential benefits and/ or drawbacks of the revised description compared to the original description?

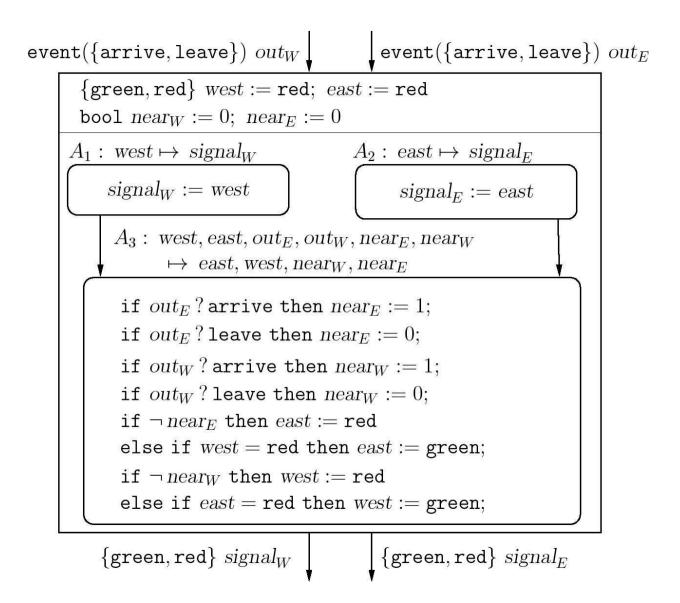


Figure 3.8: A Safe Controller for the Railroad Problem

**Exercise 3.4:** Consider a component C with an output variable x of type int. Design a safety monitor to capture the requirement that the sequence of values output by the component C is strictly increasing (that is, the output in each round should be strictly greater than the output in the preceding round).