```
In [ ]: # 6.34
        from math import erfc, sqrt
        Max Err Prob = 10e-5
        Es N0 = 1
        def compute probability(Es No):
            """Gives the probability of error for a given Es/No"""
            sum = 48/16 * erfc(sqrt(4 * Es_N0 / 20))
            sum += 36/16 * erfc(sqrt(8 * Es N0 / 20))
            sum += 32/16 * erfc(sqrt(16 * Es_N0 / 20))
            sum += 48/16 * erfc(sqrt(20 * Es N0 / 20))
            sum += 16/16 * erfc(sqrt(32 * Es N0 / 20))
            sum += 16/16 * erfc(sqrt(36 * Es N0 / 20))
            sum += 24/16 * erfc(sqrt(40 * Es_N0 / 20))
            sum += 16/16 * erfc(sqrt(52 * Es_N0 / 20))
            sum += 4/16 * erfc(sqrt(72 * Es N0 / 20))
            return sum
        probability = compute probability(Es N0)
        while abs(probability - Max Err Prob) > 0.0001:
            half way = Es N0 / 2
            if probability > Max Err Prob:
                Es N0 += half way
            else:
                Es NO -+ half way
            probability = compute_probability(Es_N0)
        print(Es N0)
        57.6650390625
In [ ]: # Problem 3 reproduce K1 and K2
        def compute K1 K2(BnT, Z, K0, Kp):
            K0_{Kp_K1} = (4 * Z * BnT / (Z + 1 / (4 * Z))) / (1 + 2 * Z * BnT / (Z + 1 / (4 * Z)))
            K0_{Kp_K2} = (4 * (BnT / (Z + 1 / (4 * Z)))**2) / (1 + 2 * Z * BnT / (Z + 1 / (4 * Z)))
```

```
def compute_K1_K2(BnT, Z, K0, Kp):
    K0 Kp_K1 = (4 * Z * BnT / (Z + 1 / (4 * Z))) / (1 + 2 * Z * BnT / (Z + 1 / (4 * Z)))
    K0_Kp_K2 = (4 * (BnT / (Z + 1 / (4 * Z)))**2) / (1 + 2 * Z * BnT / (Z + 1 / (4 * Z)))
    K1 = K0_Kp_K1 / (K0 * Kp)
    K2 = K0_Kp_K2 / (K0 * Kp)
    return K1, K2

BnT = 0.5
Z = 1 / sqrt(2)
Kp = 1
K0 = 5.66
K1, K2 = compute_K1_K2(BnT, Z, K0, Kp)

print(f"C.2.1: K1 = {K1}; K2 = {K2}")

BnT = 0.05
K0 = 0.5
K1, K2 = compute_K1_K2(BnT, Z, K0, Kp)

print(f"C.2.3: K1 = {K1}; K2 = {K2}")
```

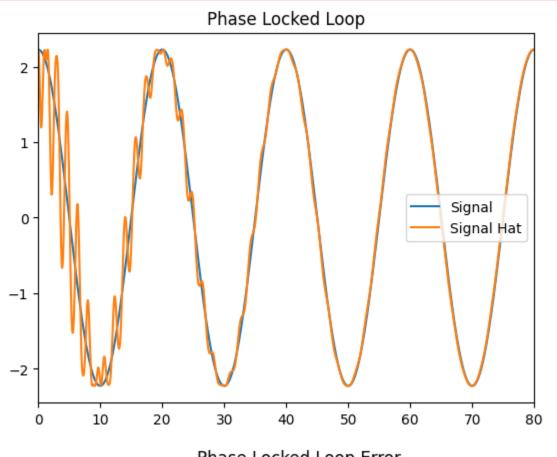
```
C.2.1: K1 = 0.12471419663271667; K2 = 0.08314279775514448 C.2.3: K1 = 0.2494802494802495; K2 = 0.016632016632016636
```

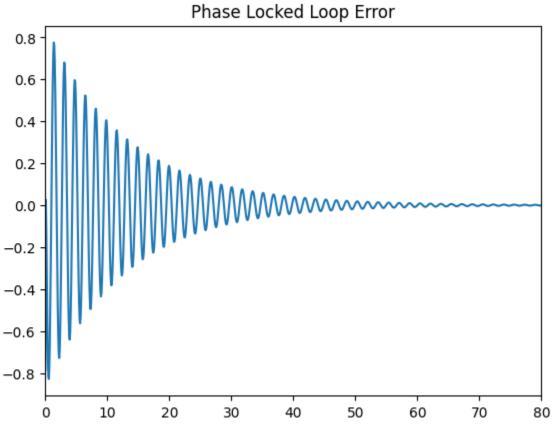
```
In [ ]: # C.2.4
        from math import pi, atan, e
        from numpy import linspace
        import matplotlib.pyplot as plt
        N = linspace(0, 80, 1000)
        0mega0 = 2 * pi / 20
        BnT = 1
        Z = 1
        Theta n = BnT / (Z + 1/(4 * Z))
        Kp = 1
        K0 = 10
        K1, K2 = compute K1 K2(BnT, Z, K0, Kp)
        print(f"K1 {K1} K2 {K2}")
        signal = []
        signal hat = [complex(1,1)]
        theta error = []
        V = []
        z1 = 0
        z2 = 0
        omegas = []
        z2s = []
        for n in N:
            # Phase Detector
            signal.append(e**(complex(Theta_n, OmegaO*n)))
            omegas.append(OmegaO*n)
            added_signal = signal[-1] * signal_hat[-1].conjugate()
            theta_error.append(atan(added_signal.imag/added signal.real))
            # print(theta error[-1])
            # Loop Filter
            first = K1 * theta_error[-1]
            second = (K2 * theta error[-1]) + z1
            z1 = second
            v.append(first + second)
            # DDS
            signal hat.append(e**(complex(Theta n,z2)))
            z2 = v[-1] + z2 + 0mega0
            z2s.append(z2)
        plt.figure()
        plt.plot(N,signal)
        signal_hat.pop(0)
        plt.plot(N,signal hat)
        plt.legend(["Signal", "Signal Hat"])
        plt.title("Phase Locked Loop")
        plt.xlim([0, max(N)])
        # plt.ylim([-2.5, 2.5])
        plt.show()
        plt.figure()
        plt.xlim([0, max(N)])
        plt.plot(N, theta error)
        plt.title("Phase Locked Loop Error")
        plt.show()
```

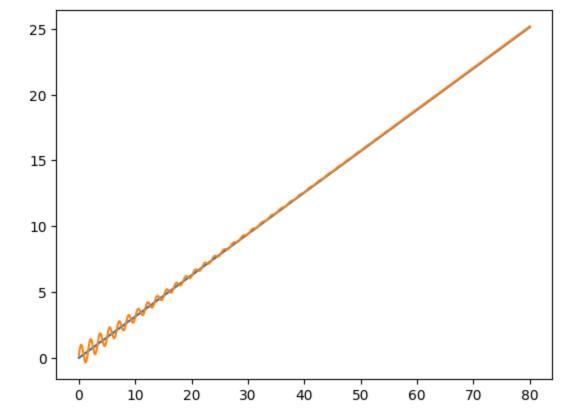
```
plt.figure()
plt.plot(N, omegas)
plt.plot(N, z2s)
plt.show()
```

K1 0.09876543209876543 K2 0.07901234567901236

/home/calvin/.local/lib/python3.10/site-packages/matplotlib/cbook/__init__.py:1369: Comp
lexWarning: Casting complex values to real discards the imaginary part
 return np.asarray(x, float)





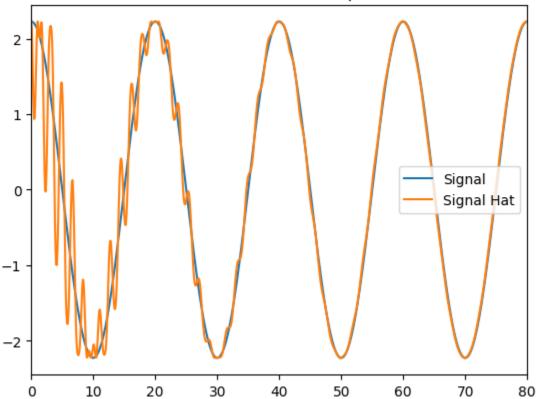


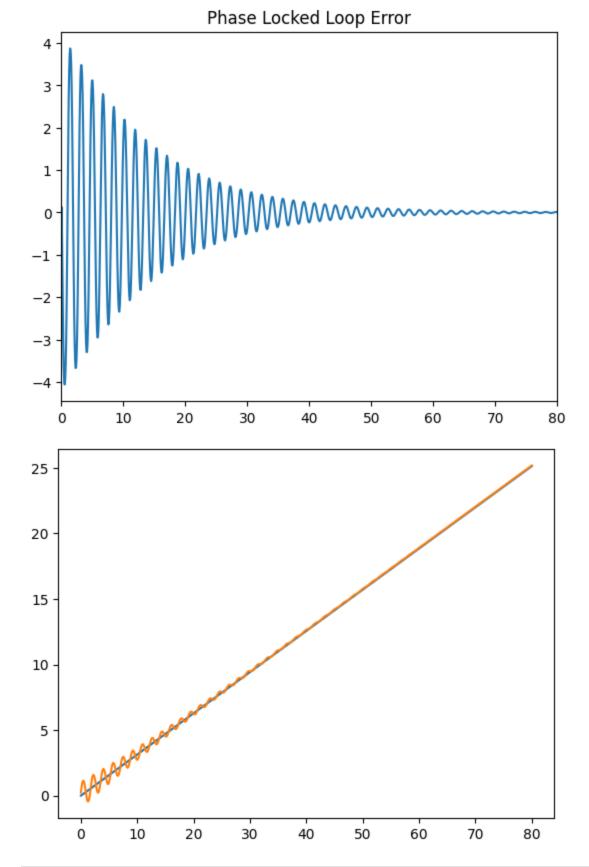
```
In [ ]: # C.2.5
        from math import cos, sin, pi, e
        from numpy import linspace
        import matplotlib.pyplot as plt
        N = linspace(0, 80, 1000)
        0mega0 = 2 * pi / 20
        BnT = 1
        Z = 1
        Theta n = BnT / (Z + 1/(4 * Z))
        Kp = 1
        K0 = 50
        K1, K2 = compute K1 K2(BnT, Z, K0, Kp)
        print(f"K1 {K1} K2 {K2}")
        signal = []
        signal hat = [complex(1,1)]
        theta error = []
        V = []
        z1 = 0
        z2 = 0
        omegas = []
        z2s = []
        for n in N:
            # Phase Detector
            signal.append(e**(complex(Theta_n, OmegaO*n)))
            omegas.append(Omega0*n)
            added signal = signal[-1] * signal hat[-1].conjugate()
            theta_error.append(added_signal.imag)
            # print(theta error[-1])
            # Loop Filter
            first = K1 * theta error[-1]
            second = (K2 * theta error[-1]) + z1
```

```
z1 = second
    v.append(first + second)
    # DDS
    signal_hat.append(e**(complex(Theta_n,z2)))
    z2 = v[-1] + z2 + 0mega0
    z2s.append(z2)
plt.figure()
plt.plot(N,signal)
signal hat.pop(0)
plt.plot(N,signal_hat)
plt.legend(["Signal", "Signal Hat"])
plt.title("Phase Locked Loop")
plt.xlim([0, max(N)])
# plt.ylim([-2.5, 2.5])
plt.show()
plt.figure()
plt.xlim([0, max(N)])
plt.plot(N, theta_error)
plt.title("Phase Locked Loop Error")
plt.show()
plt.figure()
plt.plot(N, omegas)
plt.plot(N, z2s)
plt.show()
```

K1 0.019753086419753086 K2 0.01580246913580247

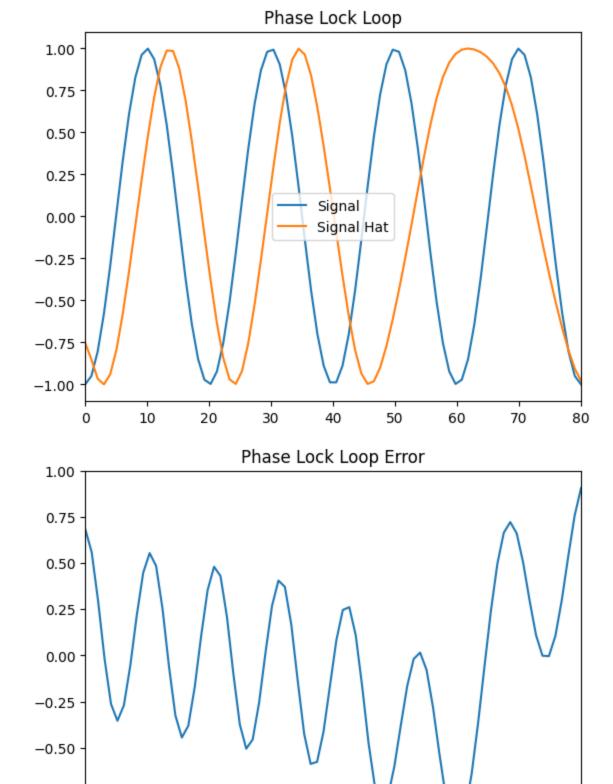
Phase Locked Loop





```
In []: #C.2.8
    from math import pi, e, sqrt
A = 1
    Omega0 = 2 * pi / 20
BnT = 0.5
Z = 0.75 #1 / sqrt(2)
Theta_n = pi#BnT / (Z + 1/(4 * Z))
Kp = 1
K0 = 25
K1, K2 = compute_K1_K2(BnT, Z, K0, Kp)
```

```
print(f"K1 {K1} K2 {K2}")
N = linspace(0,80,80)
signal = []
signal hat = [pi]
signal error = []
z1 = 0
z2 = 0.85
V = []
out = []
omegas = []
z2s = []
for n in N:
    #Phase Detector
    signal.append(A * cos((Omega0 * n) + Theta_n))
    omegas.append(OmegaO*n)
    signal error.append(signal[-1] * signal hat[-1])
    # Loop Filter
   first = K1 * signal_error[-1]
    second = (K2 * signal\_error[-1]) + z1
    z1 = second
    v.append(first + second)
    # DDS
    out.append(cos(z2))
    signal hat.append(-sin(z2))
    z2 = 0mega0 + v[-1] + z2
    z2s.append(z2)
signal hat.pop(0)
# plt.figure()
# plt.plot(N, temp)
# plt.show()
plt.figure()
plt.clf()
plt.plot(N, signal)
plt.plot(N, signal hat)
plt.title("Phase Lock Loop")
plt.xlim([0,max(N)])
plt.legend(["Signal", "Signal Hat"])
plt.show()
plt.figure()
plt.title("Phase Lock Loop Error")
plt.plot(N, signal error)
plt.xlim([2,max(N)])
plt.ylim([-1,1])
plt.show()
plt.figure()
plt.plot(N, omegas)
plt.plot(N, z2s)
plt.title("Sinusoidal Arguments")
plt.show()
```



-0.75

-1.00

