

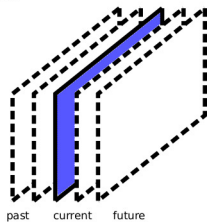
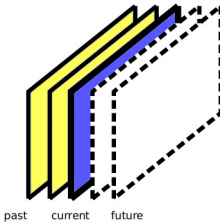
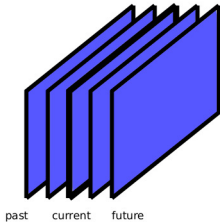
frames

All frames are known

Past frames  
are known

Future frames  
are unknown

Only current frame is considered



temporal  
kernel

