

CONTACT INFORMATION	University of California, Davis Department of Computer Science Room 3062, One Shields Ave. Davis, CA 95616-5270 USA	✉: taechoi@ucdavis.edu 🌐: taeyeongchoi.com 🐦: ssuty
INTERESTS	Novel learning methods for real-world applications with limited resources —applied AI, robotics, AI for agriculture/biology, anomaly detection, active sensing, generative models, self-supervised learning, Bayesian learning, and reinforcement learning	
CURRENT ACADEMIC APPOINTMENTS	University of California, Davis (UCD) , Davis, CA, USA Postdoctoral Scholar, Computer Science	Aug 2022 – Present
	<ul style="list-style-type: none"> • Supervisor: Dr. Xin Liu • Affiliations: <ul style="list-style-type: none"> – Department of Computer Science – AI Institute for Food Systems (AIFS) 	
PREVIOUS ACADEMIC APPOINTMENTS	University of Lincoln (UoL) , Lincoln, UK Postdoctoral Research Associate	Oct 2020 – Jul 2022
	<ul style="list-style-type: none"> • Supervisor: Dr. Grzegorz Cielniak • Affiliations: <ul style="list-style-type: none"> – Lincoln Agri-Robotics (LAR) – Lincoln Institute for Agri-food Technology (LIAT) – Lincoln Centre for Autonomous Systems (L-CAS) 	
EDUCATION	Arizona State University (ASU) , Tempe, AZ, USA M.S. & Ph.D., Computer Science	Dec 2020
	<ul style="list-style-type: none"> • Advisor: Dr. Theodore (Ted) P. Pavlic • Ph.D. Dissertation: "Deep Learning Approaches for Inferring Collective Macrostates from Individual Observations in Natural and Artificial Multi-Agent Systems Under Realistic Constraints". ISBN: 9798557031004 	
	Soongsil University (SSU) , Seoul, South Korea B.S.E., Computer Science and Engineering	Aug 2015
WORK EXPERIENCE	Atlassian , Mountain View, CA <i>Data Scientist Intern</i>	May 2018 – Aug 2018
	<ul style="list-style-type: none"> • Jira Duplicate Ticket Detection <ul style="list-style-type: none"> – Designed a deep learning pipeline for human natural language to classify semantically similar tickets from customers. – Gathered >124K examples to implement, train, fine-tune, and validate specialized LSTM models. – Demonstrated 1) significantly higher accuracy than traditional machine learning models, 2) generalizability to the data from different sources of ticket, and 3) feasibility of similarity-based ranking scenarios. 	
PUBLICATIONS	(Preprinted) [1] Choi T. and G. Cielniak. Channel Randomisation with Domain Control for Effective Representation Learning of Visual Anomalies in Strawberries. In: <i>AAAI-22 Workshop on AI for Agriculture and Food Systems (AIAFS 2022)</i> . OpenReview.net.	

(Published)

- [2] **Choi T.**, O. Would, A. Salazar-Gomez, and G. Cielniak. Self-supervised Representation Learning for Reliable Robotic Monitoring of Fruit Anomalies. In: *2022 IEEE International Conference on Robotics and Automation (ICRA 2022)*. May 23–27, 2022. Philadelphia, USA. doi:10.1109/ICRA46639.2022.9811954.
- [3] **Choi T.**, Benjamin Pyenson, Juergen Liebig, and T. P. Pavlic. Beyond Tracking: Using Deep Learning to Discover Novel Interactions in Biological Swarms. *Journal of Artificial Life and Robotics (AROB)*, Mar 2022. doi:10.1007/s10015-022-00753-y
— Extension of the *Best Paper Award* winner at the *4th International Symposium on Swarm Behavior and Bio-Inspired Robotics 2021 (SWARM 2021)*, Jun 1–4, 2021. Kyoto, Japan. Virtual event.
- [4] **Choi T.** and G. Cielniak. Adaptive Selection of Informative Path Planning Strategies via Reinforcement Learning. In: *Proceedings of the 10th European Conference on Mobile Robots (ECMR 2021)*, Aug 31–Sep 3, 2021. Bonn, Germany. Virtual event. doi:10.1109/ECMR50962.2021.9568796
- [5] **Choi T.**, Benjamin Pyenson, Juergen Liebig, and T. P. Pavlic. Identification of Abnormal States in Videos of Ants Undergoing Social Phase Change. In: *Proceedings of the 35th AAAI Conference on Artificial Intelligence (AAAI-21)*, Feb 2–9, 2021. Virtual event.
- [6] **Choi T.** and T. P. Pavlic. Automatic Discovery of Motion Patterns that Improve Learning Rate in Communication-Limited Multi-Robot Systems. In: *Proceedings of the IEEE 2020 International Conference on Multisensor Fusion and Integration (MFI 2020)*, Sep 14–16, 2020. Karlsruhe, Germany. Virtual event. doi:10.1109/MFI49285.2020.9235218
- [7] Kang, S., **T. Choi** and T. P. Pavlic. How Far Should I Watch? Quantifying the Effect of Various Observational Capabilities on Long-range Situational Awareness in Multi-robot Teams. In: *Proceedings of the 1st IEEE International Conference on Autonomic Computing and Self-Organizing Systems (ACSOS 2020)*, Aug 17–21, 2020. Washington, DC, USA. Virtual event. doi:10.1109/ACSOS49614.2020.00036
- [8] **Choi, T.**, S. Kang, and T. P. Pavlic. Learning Local Behavioral Sequences to Better Infer Non-local Properties in Real Multi-robot Systems. In: *Proceedings of the 2020 IEEE International Conference on Robotics and Automation (ICRA 2020)*, May 31–June 4, 2020. Paris, France. Virtual event. doi:10.1109/ICRA40945.2020.9196728
- [9] **Choi, T.**, T. P. Pavlic, and A. W. Richa. Automated Synthesis of Scalable Algorithms for Inferring Non-Local Properties to Assist in Multi-Robot Teaming. In: *Proceedings of the 2017 IEEE International Conference on Automation Science and Engineering (CASE 2017)*, Aug 20–23, 2017. Xi'an, China. doi:10.1109/COASE.2017.8256320
- [10] **Choi, T.** and H. Na. Stealthy Behavior Simulations based on Cognitive Data. *Journal of Korea Game Society (JKGS)*, 16(2):27–40, Apr 2016. doi:10.7583/JKGS.2016.16.2.27
- [11] **Choi, T.** and H. Na. Making Levels More Challenging with a Cooperative Strategy of Ghosts in Pac-Man. *Journal of Korea Game Society (JKGS)*, 15(5):89–98, Oct 2015. doi:10.7583/JKGS.2015.15.5.89
- [12] **Choi, T.** and H. Na. Stealthy Behavior Simulations based on Cognitive Data. In: *Proceedings of the 2015 IEEE International Conference on Machine Learning and Cybernetics (ICMLC 2015)*, 16(2):27–40, Jul 12–15 2015. Guangzhou, China. doi:10.1109/ICMLC.2015.7340900

POSTER
PRESENTATIONS

- [13] **Choi, T.**, T. P. Pavlic, and A. W. Richa. Automated Synthesis of Scalable Algorithms for Inferring Non-local Properties to Assist in Multi-Robot Teaming. In: Poster Session at *Southwest Robotics Symposium*, Jan 2018. Tempe, AZ, USA.
- [14] **Choi, T.**, T. P. Pavlic, and A. W. Richa. Automated Synthesis of Scalable Algorithms for Inferring Non-local Properties to Assist in Multi-Robot Teaming. In: Poster Session at *TEDxASU: Innovators Symposium*, Mar 2017. Tempe, AZ, USA.
- [15] **Choi, T.**, J. Lee, C. Soh, and J. Lee. Social Alarm: Smart mobile application helping people to get up together. In: Poster Session at *Seoul Accord Item SHOW*, Dec 2012. Seoul, South Korea.

INVITED TALKS

- [16] Self-supervised Learning of Visual Anomalies in Strawberries. In: *International Conference on Digital Technologies for Sustainable Crop Production (DIGICROP)*, Mar 2022. Virtual event.
- [17] AI Research in Agriculture and Beyond – Successful Machine Learning under Limited Resources. In: *Hankyong National University, School of Computer Engineering & Applied Mathematics Seminar*, Dec 2021. Anseong, South Korea.
- [18] Local Behavior Learning for Social Temperature Prediction without Individual Ant Tracking. In: Oral Session at *Collective Information Processing*, Mar 2020. Berlin, Germany.
- [19] Machine Learning Applications for Video Game Development. In: *Hankyong National University, School of Computer Engineering & Applied Mathematics Seminar*, Jul 2015. Anseong, South Korea.

TEACHING
EXPERIENCE

UCD, Davis, CA, USA

Guest Lecturer

- ECS 293A: Research in Computer Science **Nov 2022**
 - Graduate-level course in computer science
 - Instructor: Dr. Xin Liu
 - Lecture: “How to Read Academic Papers for You Now”

UoL, Lincoln, UK

Guest Lecturer

- CMP 9766M: Frontiers of Robotics Research Seminar: **May 2021**
 - Graduate-level course in robotics and autonomous systems
 - Instructor: Dr. Grzegorz Cielniak
 - Lecture: “Identifying Anomalies for Better Decision-Making”

ASU, Tempe, AZ, USA

Teaching Assistant

- CSE 450/551: Design Analysis of Algorithms/Foundations of Algorithms: **Jan 2018 – May 2018**
 - Instructor: Dr. Andréa Richa
 - Graded exams, and held office hours (2 hours/week) for tutoring students.
- CSE 310: Data Structures and Algorithms: **Aug 2017 – Dec 2017**
 - Instructor: Dr. Andréa Richa
 - Taught recitation sessions (4 hours/week), graded exams, and provided instructions for C++ programming assignments.

- CSE 205: Object-Oriented Programming & Data Structures **Jan 2016 – May 2016**
 - Instructor: Dr. Xuerong Feng
 - Graded exams, and tutored students for Java programming (4 hours/week).
- CSE 100: Prin. of Programming with C ++ **Jan 2016 – May 2016**
 - Instructor: Dr. Phillip Miller
 - Supervised C++ programming laboratories (5 hours/week), and held tutoring hours (4 hours/week).
- CSE 424: Capstone Project II **Aug 2015 – Dec 2015**
 - Instructor: Dr. Debra Calliss
 - Supervised each project group with their short-term and long-term goals, and graded IT ethics essays.

MENTORING

UCD, Davis, CA, USA

- Avishai Halev (Ph.D. candidate in Applied Mathematics) **Sep 2022 – Present**
 - Collaborating with food scientists on efficient parameter search to build a realistic oxidation model based on empirical datasets.

UoL, Lincoln, UK

- Owen Would (M.Sc. in Robotics & Autonomous Systems) **Mar 2021 – Sep 2021**
 - Studied on deep neural network-based visual anomaly detection of strawberry images, and validated GAN-based approaches on challenging conditions such as occlusion.

ASU, Tempe, AZ, USA

- Sehyeok Kang (M.S. in Computer Engineering) **Mar 2019 – May 2020**
 - Researched on Remote Teammate Localization on the physical robot platform *Thymio*, and also analysed the correlation between the prediction accuracy and the amount of observation samples.
- Ricardo Weir (B.S. in Computer Science) **Mar 2018 – Dec 2018**
 - Developed a YOLO-based deep learning pipeline—from data annotation to model validation—to perform automatic tracking of individual *Harpegnathos* ants from video recordings.

RESEARCH PROJECTS

ASU, Tempe, AZ

- NSF: “CRISP: Type 2/Collaborative Research: Design and Control of Coordinated Green and Gray Water Infrastructure to Improve Resiliency in Chemical and Agricultural Sectors” **Aug 2018 – Dec 2019**
 - PI: Dr. John Sabo
 - Combinatorial optimization for placement of green infrastructures (wetlands) along with gray infrastructures (reservoirs) to minimize risks of natural disasters in areas of interest.
- DARPA I20: “BioSwarm: Bio-Inspired Swarming” **Aug 2017 – Jul 2018**
 - Supervisor (co-PI): Dr. Theodore (Ted) P. Pavlic
 - PI: Dr. Stephen C. Pratt
 - Designed a deep neural network to identify informative behaviors of *Harpegnathos* ants for classification of colonial states.

SSU, Seoul, South Korea

- Reinforcement Learning for Video Game Design **Oct 2014 – Aug 2015**
 - Supervisor: Dr. Hyeon-Suk Na
 - Designed a model-free reinforcement learning framework to predict the actions of human players at the stage of video game development.
 - Proposed novel team strategies of enemies in the video game of Pac-Man using A* algorithm to significantly increase the overall level of difficulty.
- Development of a Cognitive Planning and Learning Model for Mobile Platforms **Dec 2012 – Sep 2014**
 - Supervisor: Dr. Young-Tack Park
 - Contributed to refining noisy GPS data from Android phones and creating modules on Android for reliable communication with a remote server.
 - Implemented ontology-based temporal reasoning models integrated with SPAQL.

GRANTS & AWARDS

SWARM 2021

- Best Paper Award Jun 2021

ASU Graduate College

- Completion Fellowship (\$8,550 plus tuition for 1 credit hour) Aug 2020

ASU Ira A. Fulton Schools of Engineering

- Engineering Graduate Fellowship (\$700) May 2020

ASU School of Computing, Informatics, and Decision Systems Engineering

- Doctoral Fellowship (\$4,000) Mar 2020

ASU Social Insect Research Group

- Student Research Grants (\$1,550) Nov 2018
 - Project: Deep Features for Generalizable Insect-behavior Learning.

SSU College of Information Technology

- Bronze Award at Software Development Competition Oct 2012
 - Social Alarm: Smart Android Alarm Application (Photos & Demo)

PROFESSIONAL SERVICE

Workshop Organizer

- (*Under Review in ICRA2023*) “Task-Informed Grasping IV: From Farm To Fork”
 - Full-day workshop on robotic innovations to improve food systems—from farming to postharvesting, consumption, and legislation

Conference/Journal Reviewer

- ICRA 2023, ICRA 2022, IROS 2022, RA-L, ICRA 2020

Grant Reviewer

- Research Grant at ASU GPSA Aug 2017 – May 2018
- Travel Grant at ASU GPSA Aug 2016 – Jul 2017

Conference Session Chair

- TAROS 2021 Sep 2021
- IEEE CASE 2017 Aug 2017

**HARDWARE AND
SOFTWARE SKILLS**

Data Science & Machine Learning:

- Tensorflow, PyTorch, Tensorboard, Weka, OpenCV, and Gephi

Programming Languages:

- Python, Java, C, C++, UNIX shell scripting, GNU make, MySQL, and others

Operating Systems:

- Microsoft Windows family, Apple OS X, Linux, and other UNIX variants

Others:

- Unity 3D, MATLAB, L^AT_EX, GitHub, Android, and TCP/IP programming

SERVICE

ASU International Students Club

Student President

Aug 2016 – Dec 2017

Korea Food for the Hungry International (KFHI)

Math Tutor for Middle School Students

Apr 2014 – Aug 2014

Korea Campus Crusade for Christ

Student President for the Southern District of Seoul

Mar 2011 – Aug 2012

Republic of Korea Army

Military Service

Feb 2009 – Dec 2010