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INTERESTS	Real-world AI Applications ; Robot/Computer Vision; (Inter)Active Sensing; Food Safety/Security; Anomaly Detection; Representation Learning	
CURRENT ACADEMIC APPOINTMENTS	Kennesaw State University (KSU) , Marietta, GA, USA Assistant Professor	Aug 2023 – Present
	<ul style="list-style-type: none"> Affiliations: <ul style="list-style-type: none"> Department of Information Technology 	
PREVIOUS ACADEMIC APPOINTMENTS	University of California, Davis (UCD) , Davis, CA, USA Postdoctoral Scholar	Aug 2022 – Jul 2023
	<ul style="list-style-type: none"> Supervisor: Dr. Xin Liu Affiliations: <ul style="list-style-type: none"> Department of Computer Science AI Institute for Food Systems (AIFS) 	
	University of Lincoln (UoL) , Lincoln, UK Postdoctoral Research Associate	Oct 2020 – Jul 2022
	<ul style="list-style-type: none"> Supervisor: Dr. Grzegorz Cielniak Affiliations: <ul style="list-style-type: none"> Lincoln Agri-Robotics (LAR) Lincoln Institute for Agri-food Technology (LIAT) Lincoln Centre for Autonomous Systems (L-CAS) 	
EDUCATION	Arizona State University (ASU) , Tempe, AZ, USA M.S. & Ph.D., Computer Science	Dec 2020
	<ul style="list-style-type: none"> Advisor: Dr. Theodore (Ted) P. Pavlic Ph.D. Dissertation: "Deep Learning Approaches for Inferring Collective Macrostates from Individual Observations in Natural and Artificial Multi-Agent Systems Under Realistic Constraints". ISBN: 9798557031004 	
	Soongsil University (SSU) , Seoul, South Korea B.S.E., Computer Science and Engineering	Aug 2015
PUBLICATIONS	[1] Mamo, R. and T. Choi . CA-Cut: Crop-Aligned Cutout for Data Augmentation to Learn More Robust Under-Canopy Navigation. In: <i>Proceedings of Proceedings of the 14th European Conference on Mobile Robots (ECMR 2025)</i> , Sep 2–Sep 5, 2025. Padua, Italy. — To appear.	
	[2] Choi, T. , O. Would, A. Salazar-Gomez, X. Liu, and G. Cielniak. Channel Randomisation: Self-Supervised Representation Learning for Reliable Visual Anomaly Detection in Specialty Crops. In: <i>Journal of Computers and Electronics in Agriculture</i> , Nov 2024. doi:10.1016/j.compag.2024.109416.	
	[3] Choi T. , D. Guevara, Z. Cheng, G. Bandodkar, C. Wang, B. N. Bailey, M. Earles, and X. Liu. DAVIS-Ag: A Synthetic Plant Dataset for Prototyping Domain-Inspired Active Vision in Agricultural Robots. In: <i>Proceedings of the 2024 IEEE International Conference on Automation Science and Engineering (CASE 2024)</i> , Aug 28–Sep 1, 2024. Bari, Italy. doi:10.1109/CASE59546.2024.10711368	

- [4] Goyal, S., K. Sasikumar, R. Sheth, A. Seelam, **T. Choi**, and X. Liu. EnColor: Improving Visual Accessibility with a Deep Encoder-Decoder Image Corrector for Color Vision Deficient Individuals. In: *Proceedings of the 38th AAAI Conference on Artificial Intelligence (AAAI-24)*, Feb 20–27, 2024. Vancouver, Canada. doi:10.1609/aaai.v38i21.30382
- [5] Bandodkar, G., S. Agarwal, A. K. Sugghosh, S. Singh, and **T. Choi**. “Allot?” Is “A Lot!” Towards Developing More Generalized Speech Recognition System for Accessible Communication. In: *Proceedings of the 38th AAAI Conference on Artificial Intelligence (AAAI-24)*, Feb 20–27, 2024. Vancouver, Canada. doi:10.1609/aaai.v38i21.30381
- [6] **Choi, T.**, O. Would, A. Salazar-Gomez, and G. Cielniak. Self-supervised Representation Learning for Reliable Robotic Monitoring of Fruit Anomalies. In: *Proceedings of the 2022 IEEE International Conference on Robotics and Automation (ICRA 2022)*. May 23–27, 2022. Philadelphia, USA. doi:10.1109/ICRA46639.2022.9811954.
- [7] **Choi, T.**, B. Pyenson, J. Liebig, and T. P. Pavlic. Beyond Tracking: Using Deep Learning to Discover Novel Interactions in Biological Swarms. *Journal of Artificial Life and Robotics (AROB)*, Mar 2022. doi:10.1007/s10015-022-00753-y
— Extension of the *Best Paper Award* winner at the *4th International Symposium on Swarm Behavior and Bio-Inspired Robotics 2021 (SWARM 2021)*, Jun 1–4, 2021. Kyoto, Japan. Virtual event.
- [8] **Choi, T.** and G. Cielniak. Adaptive Selection of Informative Path Planning Strategies via Reinforcement Learning. In: *Proceedings of the 10th European Conference on Mobile Robots (ECMR 2021)*, Aug 31–Sep 3, 2021. Bonn, Germany. Virtual event. doi:10.1109/ECMR50962.2021.9568796
- [9] **Choi, T.**, B. Pyenson, J. Liebig, and T. P. Pavlic. Identification of Abnormal States in Videos of Ants Undergoing Social Phase Change. In: *Proceedings of the 35th AAAI Conference on Artificial Intelligence (AAAI-21)*, Feb 2–9, 2021. Virtual event. doi:10.1609/aaai.v35i17.17794
- [10] **Choi, T.** and T. P. Pavlic. Automatic Discovery of Motion Patterns that Improve Learning Rate in Communication-Limited Multi-Robot Systems. In: *Proceedings of the 2020 IEEE International Conference on Multisensor Fusion and Integration (MFI 2020)*, Sep 14–16, 2020. Karlsruhe, Germany. Virtual event. doi:10.1109/MFI49285.2020.9235218
- [11] Kang, S., **T. Choi** and T. P. Pavlic. How Far Should I Watch? Quantifying the Effect of Various Observational Capabilities on Long-range Situational Awareness in Multi-robot Teams. In: *Proceedings of the 1st IEEE International Conference on Autonomic Computing and Self-Organizing Systems (ACSOS 2020)*, Aug 17–21, 2020. Washington, DC, USA. Virtual event. doi:10.1109/ACSOS49614.2020.00036
- [12] **Choi, T.**, S. Kang, and T. P. Pavlic. Learning Local Behavioral Sequences to Better Infer Non-local Properties in Real Multi-robot Systems. In: *Proceedings of the 2020 IEEE International Conference on Robotics and Automation (ICRA 2020)*, May 31–June 4, 2020. Paris, France. Virtual event. doi:10.1109/ICRA40945.2020.9196728
- [13] **Choi, T.**, T. P. Pavlic, and A. W. Richa. Automated Synthesis of Scalable Algorithms for Inferring Non-Local Properties to Assist in Multi-Robot Teaming. In: *Proceedings of the 2017 IEEE International Conference on Automation Science and Engineering (CASE 2017)*, Aug 20–23, 2017. Xi’an, China. doi:10.1109/COASE.2017.8256320
- [14] **Choi, T.** and H. Na. Stealthy Behavior Simulations based on Cognitive Data. *Journal of Korea Game Society (JKGS)*, 16(2):27–40, Apr 2016. doi:10.7583/JKGS.2016.16.2.27
- [15] **Choi, T.** and H. Na. Making Levels More Challenging with a Cooperative Strategy of Ghosts in Pac-Man. *Journal of Korea Game Society (JKGS)*, 15(5):89–98, Oct 2015. doi:10.7583/JKGS.2015.15.5.89

- [16] **Choi, T.** and H. Na. Stealthy Behavior Simulations based on Cognitive Data. In: *Proceedings of the 2015 IEEE International Conference on Machine Learning and Cybernetics (ICMLC 2015)*, 16(2):27–40, Jul 12–15 2015. Guangzhou, China. doi:10.1109/ICMLC.2015.7340900
- INVITED TALKS [17] Self-supervised Learning of Visual Anomalies in Strawberries. In: *International Conference on Digital Technologies for Sustainable Crop Production (DIGICROP)*, Mar 2022. Virtual event.
- [18] AI Research in Agriculture and Beyond – Successful Machine Learning under Limited Resources. In: *Hankyong National University, School of Computer Engineering & Applied Mathematics Seminar*, Dec 2021. Anseong, South Korea.
- [19] Local Behavior Learning for Social Temperature Prediction without Individual Ant Tracking. In: Oral Session at *Collective Information Processing*, Mar 2020. Berlin, Germany.
- [20] Machine Learning Applications for Video Game Development. In: *Hankyong National University, School of Computer Engineering & Applied Mathematics Seminar*, Jul 2015. Anseong, South Korea.
- TEACHING EXPERIENCE **KSU, Marietta, GA, USA**
- Instructor*
- IT 7143: Cloud Analytics **Spring 2024, Spring 2025**
 - IT 7133: Enterprise AI Applications **Summer 2025**
 - IT 7103: Practical Data Analytics **Fall 2023, Fall 2024**
 - IT 4773: Machine Learning for Enterprise **Fall 2023, Fall 2024**
- UCD, Davis, CA, USA**
- Guest Lecturer*
- ECS 293A: Research in Computer Science **Nov 2022**
 - Graduate-level course in computer science
 - Instructor: Dr. Xin Liu
 - Lecture: “How to Read Academic Papers for You Now”
- UoL, Lincoln, UK**
- Guest Lecturer*
- CMP 9766M: Frontiers of Robotics Research Seminar: **May 2021**
 - Graduate-level course in robotics and autonomous systems
 - Instructor: Dr. Grzegorz Cielniak
 - Lecture: “Identifying Anomalies for Better Decision-Making”
- ASU, Tempe, AZ, USA**
- Teaching Assistant*
- CSE 450/551: Design Analysis of Algorithms/Foundations of Algorithms: **Jan 2018 – May 2018**
 - Instructor: Dr. Andréa Richa
 - Graded exams, and held office hours (2 hours/week) for tutoring students.
 - CSE 310: Data Structures and Algorithms: **Aug 2017 – Dec 2017**
 - Instructor: Dr. Andréa Richa
 - Taught recitation sessions (4 hours/week), graded exams, and provided instructions for C++ programming assignments.

- CSE 205: Object-Oriented Programming & Data Structures **Jan 2016 – May 2016**
 - Instructor: Dr. Xuerong Feng
 - Graded exams, and tutored students for Java programming (4 hours/week).
- CSE 100: Prin. of Programming with C ++ **Jan 2016 – May 2016**
 - Instructor: Dr. Phillip Miller
 - Supervised C++ programming laboratories (5 hours/week), and held tutoring hours (4 hours/week).
- CSE 424: Capstone Project II **Aug 2015 – Dec 2015**
 - Instructor: Dr. Debra Calliss
 - Supervised each project group with their short-term and long-term goals, and graded IT ethics essays.

MENTORING

KSU, Marietta, GA, USA

- Sahith Vardhan Reddy Vancha (M.S. in Information Technology) **Aug 2023 – Present**
 - Directing to extend the DAVIS-Ag dataset with novel features and labels
- Nafisa Anjum (M.S. in Information Technology) **Aug 2023 – Present**
 - Serving on the Master's thesis committee

UCD, Davis, CA, USA

- (Team 1) Satyam Goyal, Rohan Sheth, Akash Seelam, and Kavya Sasikumar
(Team 2) Grisha Bandodkar, Athul Krishna Sugghosh, Sahil Singh, and Shyam Agarwal (B.S. in Computer Science) **Jun 2023 – Present**
 - Serving as a mentor for the EAAI-24 Mentored Undergraduate Research Challenge
 - Advising in designing a problem, producing a solution and evaluation results, and writing a paper to submit.
- Grisha Bandodkar, Zifei Cheng, Chonghan Wang, and Satyam Goyal (B.S. in Computer Science) **Jan 2023 – Aug 2022**
 - Directing to generate and extend DAVIS-Ag—a public image dataset of simulated plants—with labels, such as instance segmentation, bounding box, camera pose, etc., in a desirable format.
 - Advising in designing reasonable heuristic methods for active vision in agricultural environments and in training a fruit detector for validation of the DAVIS-Ag dataset.
 - Guiding while exploring embedded AI platforms like AI Habitat and AI2-THOR
- Avishai Halev (Ph.D. in Applied Mathematics) **Sep 2022 – Dec 2022**
 - Working with food scientists on efficient parameter search to build a realistic oxidation model fitting empirical datasets.

UoL, Lincoln, UK

- Owen Would (M.Sc. in Robotics & Autonomous Systems) **Mar 2021 – Sep 2021**
 - Advised in studying on deep neural network-based visual anomaly detection of strawberry images particularly while designing a GAN-based method for occluding environments.

ASU, Tempe, AZ, USA

- Sehyeok Kang (M.S. in Computer Engineering) **Mar 2019 – May 2020**
 - Mentored to implement Remote Teammate Localization on a physical robot platform, *Thymio*, while he was working on his thesis on correlation between prediction accuracy and observational information.
- Ricardo Weir (B.S. in Computer Science) **Mar 2018 – Dec 2018**
 - Guided to develop a YOLO-based object-detection pipeline—from data annotation to model validation—to perform automated tracking of individual *Harpegnathos* ants from high-quality video recordings.

**PROFESSIONAL
SERVICE**

Workshop Organizer

- ICRA2023: “TIG-IV: Agri-Food Robotics From Farm To Fork” Jun 2023
 - Full-day workshop on robotic innovations for agri-food systems—from farming to post-harvest processing, cooking, delivery, serving, and legislation

Conference/Journal Reviewer

- IJRR, RAM, RA-L, Biosystm. Eng., Comput. Electron Agric., IROS 2025 (AE), IROS 2023, ICRA 2023, ICRA 2022, IROS 2022, ICRA 2020

Grant Reviewer

- Research Grant at ASU GPSA Aug 2017 – May 2018
- Travel Grant at ASU GPSA Aug 2016 – Jul 2017

Conference Session Chair

- TAROS 2021 Sep 2021
- CASE 2017 Aug 2017

**RESEARCH
PROJECTS**

ASU, Tempe, AZ

- NSF: “CRISP: Type 2/Collaborative Research: Design and Control of Coordinated Green and Gray Water Infrastructure to Improve Resiliency in Chemical and Agricultural Sectors” **Aug 2018 – Dec 2019**
 - PI: Dr. John Sabo
 - Combinatorial optimization for placement of green infrastructures (wetlands) along with gray infrastructures (reservoirs) to minimize risks of natural disasters in areas of interest.
- DARPA I20: “BioSwarm: Bio-Inspired Swarming” **Aug 2017 – Jul 2018**
 - Supervisor (co-PI): Dr. Theodore (Ted) P. Pavlic
 - PI: Dr. Stephen C. Pratt
 - Designed a deep neural network to identify informative behaviors of *Harpegnathos* ants for classification of colonial states.

SSU, Seoul, South Korea

- Reinforcement Learning for Video Game Design **Oct 2014 – Aug 2015**
 - Supervisor: Dr. Hyeon-Suk Na
 - Designed a model-free reinforcement learning framework to predict the actions of human players at the stage of video game development.
 - Proposed novel team strategies of enemies in the video game of Pac-Man using A* algorithm to significantly increase the overall level of difficulty.
- Development of a Cognitive Planning and Learning Model for Mobile Platforms **Dec 2012 – Sep 2014**
 - Supervisor: Dr. Young-Tack Park
 - Contributed to refining noisy GPS data from Android phones and creating modules on Android for reliable communication with a remote server.
 - Implemented ontology-based temporal reasoning models integrated with SPAQL.

GRANTS & AWARDS

NSF

- PI, “ERI: Odor Representation Learning for Robust Detection of Co-present Foods and Pathogen Contamination Using an Electronic Nose”, \$199,995, Jul 2025–Jun 2027.

Georgia Peanut Commission

- PI, “Night Owl: A Low-Cost Smart Drone System for Defending Peanut Farms from Night-time Wildlife Intrusion”, \$25,000, Jul 2025–Jun 2026.

Southern Sustainable Agriculture Research and Education

- PI, “MoCoBot: Developing a Low-Cost Night-time Mollusk Control Robot for Strawberry Growers”, Graduate Student Grants, \$21,964, Sep 2024–Aug 2026.

KSU Office of Research

- Co-PI, “Enhancing Student Engagement with Peer Questioning in Immersive Virtual Classroom Using Large Language Models”, Interdisciplinary Initiatives Seed Grants, \$10,000, May 2024–Apr 2025.

SWARM 2021

- Best Paper Award Jun 2021

ASU Graduate College

- Completion Fellowship (\$8,550 plus tuition for 1 credit hour) Aug 2020

ASU Ira A. Fulton Schools of Engineering

- Engineering Graduate Fellowship (\$700) May 2020

ASU School of Computing, Informatics, and Decision Systems Engineering

- Doctoral Fellowship (\$4,000) Mar 2020

ASU Social Insect Research Group

- Student Research Grants (\$1,550) Nov 2018
 - Project: Deep Features for Generalizable Insect-behavior Learning.

SSU College of Information Technology

- Bronze Award at Software Development Competition Oct 2012
 - Social Alarm: Smart Android Alarm Application (Photos & Demo)

**WORK
EXPERIENCE**

Atlassian, Mountain View, CA

Data Scientist Intern

May 2018 – Aug 2018

- Jira Duplicate Ticket Detection
 - Designed a deep learning pipeline for human natural language to classify semantically similar tickets from customers.
 - Gathered >124K examples to implement, train, fine-tune, and validate specialized LSTM models.
 - Demonstrated 1) significantly higher accuracy than traditional machine learning models, 2) generalizability to the data from different sources of ticket, and 3) feasibility of similarity-based ranking scenarios.

**HARDWARE AND
SOFTWARE SKILLS**

Data Science & Machine Learning:

- PyTorch, TensorFlow, TensorBoard, OpenAI Gym, OpenCV, Scikit-learn, SciPy, NumPy, Pandas, Matplotlib, etc.

Programming Languages:

- Python, Java, C, C++, UNIX shell scripting, GNU make, MySQL, etc.

Operating Systems:

- Microsoft Windows family, Apple OS X, Linux, and other UNIX variants

Others:

- Unity 3D, MATLAB, L^AT_EX, Git, Android, and TCP/IP programming