Dr. Taeyeong Choi Curriculum vitae

CONTACT

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**INTERESTS** 

Novel learning methods for real-world applications with limited resources—applied AI, robotics, AI for agriculture/biology, anomaly detection, active sensing, generative models, selfsupervised learning, Bayesian learning, and reinforcement learning

CURRENT ACADEMIC APPOINTMENTS

## University of California, Davis (UCD), Davis, CA, USA

Postdoctoral Scholar, Computer Science

Aug 2022 - Present

- Supervisor: Dr. Xin Liu
- · Affiliations:
  - Department of Computer Science AI Institute for Food Systems (AIFS)

# **PREVIOUS ACADEMIC** APPOINTMENTS

## University of Lincoln (UoL), Lincoln, UK

Postdoctoral Research Associate

Oct 2020 - Jul 2022

- Supervisor: Dr. Grzegorz Cielniak
- · Affiliations:
  - Lincoln Agri-Robotics (LAR)
  - Lincoln Institute for Agri-food Technology (LIAT)
  - Lincoln Centre for Autonomous Systems (L-CAS)

#### **EDUCATION**

## Arizona State University (ASU), Tempe, AZ, USA

M.S. & Ph.D., Computer Science

Dec 2020

- Advisor: Dr. Theodore (Ted) P. Pavlic
- Ph.D. Dissertation: "Deep Learning Approaches for Inferring Collective Macrostates from Individual Observations in Natural and Artificial Multi-Agent Systems Under Realistic Constraints". ISBN: 9798557031004

# Soongsil University (SSU), Seoul, South Korea

B.S.E., Computer Science and Engineering

Aug 2015

# Work EXPERIENCE

## Atlassian, Mountain View, CA

Data Scientist Intern

May 2018 - Aug 2018

- Jira Duplicate Ticket Detection
  - Designed a deep learning pipeline for human natural language to classify semantically similar tickets from customers.
  - Gathered >124K examples to implement, train, fine-tune, and validate specialized LSTM models.
  - Demonstrated 1) significantly higher accuracy than traditional machine learning models, 2) generalizability to the data from different sources of ticket, and 3) feasibility of similarity-based ranking scenarios.

#### **PUBLICATIONS**

## (Preprinted/Accepted)

[1] Choi T. and X. Liu. Exploiting Unlabeled Data to Improve Detection of Visual Anomalies in Soft Fruits. In: AAAI-23 Workshop on AI for Agriculture and Food Systems (AIAFS 2023).

- [2] Liu Y., **T. Choi**, and X. Liu. Constrained Reinforcement Learning for Autonomous Farming: Challenges and Opportunities. In: *AAAI-23 Workshop on AI for Agriculture and Food Systems (AIAFS 2023)*.
- [3] **Choi T.** and G. Cielniak. Channel Randomisation with Domain Control for Effective Representation Learning of Visual Anomalies in Strawberries. In: *AAAI-22 Workshop on AI for Agriculture and Food Systems (AIAFS 2022)*. OpenReview.net.

## (Published)

- [4] **Choi T.**, O. Would, A. Salazar-Gomez, and G. Cielniak. Self-supervised Representation Learning for Reliable Robotic Monitoring of Fruit Anomalies. In: 2022 IEEE International Conference on Robotics and Automation (ICRA 2022). May 23–27, 2022. Philadelphia, USA. doi:10.1109/ICRA46639.2022.9811954.
- [5] Choi T., Benjamin Pyenson, Juergen Liebig, and T. P. Pavlic. Beyond Tracking: Using Deep Learning to Discover Novel Interactions in Biological Swarms. *Journal of Artificial Life and Robotics (AROB)*, Mar 2022. doi:10.1007/s10015-022-00753-y
  Extension of the *Best Paper Award* winner at the 4th International Symposium on Swarm Behavior and Bio-Inspired Robotics 2021 (SWARM 2021), Jun 1–4, 2021. Kyoto, Japan. Virtual event.
- [6] Choi T. and G. Cielniak. Adaptive Selection of Informative Path Planning Strategies via Reinforcement Learning. In: *Proceedings of the 10th European Conference on Mobile Robots (ECMR 2021)*, Aug 31–Sep 3, 2021. Bonn, Germany. Virtual event. doi:10.1109/ECMR50962.2021.9568796
- [7] **Choi T.**, Benjamin Pyenson, Juergen Liebig, and T. P. Pavlic. Identification of Abnormal States in Videos of Ants Undergoing Social Phase Change. In: *Proceedings of the 35th AAAI Conference on Artificial Intelligence (AAAI-21)*, Feb 2–9, 2021. Virtual event.
- [8] Choi T. and T. P. Pavlic. Automatic Discovery of Motion Patterns that Improve Learning Rate in Communication-Limited Multi-Robot Systems. In: *Proceedings of the IEEE* 2020 International Conference on Multisensor Fusion and Integration (MFI 2020), Sep 14–16, 2020. Karlsruhe, Germany. Virtual event. doi:10.1109/MFI49285.2020.9235218
- [9] Kang, S., T. Choi and T. P. Pavlic. How Far Should I Watch? Quantifying the Effect of Various Observational Capabilities on Long-range Situational Awareness in Multi-robot Teams. In: Proceedings of the 1st IEEE International Conference on Autonomic Computing and Self-Organizing Systems (ACSOS 2020), Aug 17–21, 2020. Washington, DC, USA. Virtual event. doi:10.1109/ACSOS49614.2020.00036
- [10] Choi, T., S. Kang, and T. P. Pavlic. Learning Local Behavioral Sequences to Better Infer Non-local Properties in Real Multi-robot Systems. In: *Proceedings of the 2020 IEEE International Conference on Robotics and Automation (ICRA 2020)*, May 31–June 4, 2020. Paris, France. Virtual event. doi:10.1109/ICRA40945.2020.9196728
- [11] **Choi, T.**, T. P. Pavlic, and A. W. Richa. Automated Synthesis of Scalable Algorithms for Inferring Non-Local Properties to Assist in Multi-Robot Teaming. In: *Proceedings of the 2017 IEEE International Conference on Automation Science and Engineering (CASE 2017)*, Aug 20–23, 2017. Xi'an, China. doi:10.1109/COASE.2017.8256320
- [12] **Choi, T.** and H. Na. Stealthy Behavior Simulations based on Cognitive Data. *Journal of Korea Game Society (JKGS)*, 16(2):27–40, Apr 2016. doi:10.7583/JKGS.2016.16.2.27
- [13] **Choi, T.** and H. Na. Making Levels More Challenging with a Cooperative Strategy of Ghosts in Pac-Man. *Journal of Korea Game Society (JKGS)*, 15(5):89–98, Oct 2015. doi:10.7583/JKGS.2015.15.5.89

[14] Choi, T. and H. Na. Stealthy Behavior Simulations based on Cognitive Data. In: Proceedings of the 2015 IEEE International Conference on Machine Learning and Cybernetics (ICMLC 2015), 16(2):27–40, Jul 12–15 2015. Guangzhou, China. doi:10.1109/ICMLC.2015.7340900

# POSTER PRESENTATIONS

- [15] **Choi, T.**, T. P. Pavlic, and A. W. Richa. Automated Synthesis of Scalable Algorithms for Inferring Non-local Properties to Assist in Multi-Robot Teaming. In: Poster Session at *Southwest Robotics Symposium*, Jan 2018. Tempe, AZ, USA.
- [16] **Choi, T.**, T. P. Pavlic, and A. W. Richa. Automated Synthesis of Scalable Algorithms for Inferring Non-local Properties to Assist in Multi-Robot Teaming. In: Poster Session at *TEDxASU: Innovators Symposium*, Mar 2017. Tempe, AZ, USA.
- [17] **Choi, T.**, J. Lee, C. Soh, and J. Lee. Social Alarm: Smart mobile application helping people to get up together. In: Poster Session at *Seoul Accord ITem SHOW*, Dec 2012. Seoul, South Korea.

#### INVITED TALKS

- [18] Self-supervised Learning of Visual Anomalies in Strawberries. In: *International Conference on Digital Technologies for Sustainable Crop Production (DIGICROP)*, Mar 2022. Virtual event.
- [19] AI Research in Agriculture and Beyond Successful Machine Learning under Limited Resources. In: *Hankyong National University, School of Computer Engineering & Applied Mathematics Seminar*, Dec 2021. Anseong, South Korea.
- [20] Local Behavior Learning for Social Temperature Prediction without Individual Ant Tracking. In: Oral Session at *Collective Information Processing*, Mar 2020. Berlin, Germany.
- [21] Machine Learning Applications for Video Game Development. In: *Hankyong National University, School of Computer Engineering & Applied Mathematics Seminar*, Jul 2015. Anseong, South Korea.

## TEACHING EXPERIENCE

## UCD, Davis, CA, USA

## Guest Lecturer

- ECS 293A: Research in Computer Science
  - Graduate-level course in computer science
  - Instructor: Dr. Xin Liu
  - Lecture: "How to Read Academic Papers for You Now"

## UoL, Lincoln, UK

#### Guest Lecturer

• CMP 9766M: Frontiers of Robotics Research Seminar:

May 2021

Nov 2022

- Graduate-level course in robotics and autonomous systems
- Instructor: Dr. Grzegorz Cielniak
- Lecture: "Identifying Anomalies for Better Decision-Making"

# ASU, Tempe, AZ, USA

#### Teaching Assistant

- CSE 450/551: Design Analysis of Algorithms/Foundations of Algorithms: Jan 2018 May 2018
  - Instructor: Dr. Andréa Richa
  - Graded exams, and held office hours (2 hours/week) for tutoring students.

• CSE 310: Data Structures and Algorithms:

Aug 2017 - Dec 2017

- Instructor: Dr. Andréa Richa
- Taught recitation sessions (4 hours/week), graded exams, and provided instructions for C++ programming assignments.
- CSE 205: Object-Oriented Programming & Data Structures Jan 2016 May 2016
  - Instructor: Dr. Xuerong Feng
  - Graded exams, and tutored students for Java programming (4 hours/week).
- CSE 100: Prin. of Programming with C++

Jan 2016 - May 2016

- Instructor: Dr. Phillip Miller
- Supervised C++ programming laboratories (5 hours/week), and held tutoring hours (4 hours/week).
- CSE 424: Capstone Project II

Aug 2015 - Dec 2015

- Instructor: Dr. Debra Calliss
- Supervised each project group with their short-term and long-term goals, and graded IT ethics essays.

#### MENTORING

## UCD, Davis, CA, USA

• Avishai Halev (Ph.D. candidate in Applied Mathematics)

Sep 2022 - Present

Collaborating with food scientists on efficient parameter search to build a realistic oxidation model based on empirical datasets.

## UoL, Lincoln, UK

- Owen Would (M.Sc. in Robotics & Autonomous Systems)
  - Studied on deep neural network-based visual anomaly detection of strawberry images, and validated GAN-based approaches on challenging conditions such as occlusion.

## ASU, Tempe, AZ, USA

• Sehyeok Kang (M.S. in Computer Engineering)

Mar 2019 - May 2020

Mar 2021 - Sep 2021

- Researched on Remote Teammate Localization on the physical robot platform *Thymio*, and also analysed the correlation between the prediction accuracy and the amount of observation samples.
- Ricardo Weir (B.S. in Computer Science)

Mar 2018 - Dec 2018

Developed a YOLO-based deep learning pipeline—from data annotation to model validation—to perform automatic tracking of individual *Harpegnathos* ants from video recordings.

## RESEARCH PROJECTS

# ASU, Tempe, AZ

- NSF: "CRISP: Type 2/Collaborative Research: Design and Control of Coordinated Green and Gray Water Infrastructure to Improve Resiliency in Chemical and Agricultural Sectors" Aug 2018 – Dec 2019
  - PI: Dr. John Sabo
  - Combinatorial optimization for placement of green infrastructures (wetlands) along with gray infrastructures (reservoirs) to minimize risks of natural disasters in areas of interest.
- DARPA I20: "BioSwarm: Bio-Inspired Swarming"

Aug 2017 - Jul 2018

- Supervisor (co-PI): Dr. Theodore (Ted) P. Pavlic
- PI: Dr. Stephen C. Pratt
- Designed a deep neural network to identify informative behaviors of *Harpegnathos* ants for classification of colonial states.

#### SSU, Seoul, South Korea

• Reinforcement Learning for Video Game Design

Oct 2014 - Aug 2015

- Supervisor: Dr. Hyeon-Suk Na
- Designed a model-free reinforcement learning framework to predict the actions of human players at the stage of video game development.
- Proposed novel team strategies of enemies in the video game of Pac-Man using A\* algorithm to significantly increase the overall level of difficulty.
- Development of a Cognitive Planning and Learning Model for Mobile Platforms Dec 2012
   Sep 2014
  - Supervisor: Dr. Young-Tack Park
  - Contributed to refining noisy GPS data from Android phones and creating modules on Android for reliable communication with a remote server.
  - Implemented ontology-based temporal reasoning models integrated with SPAQL.

# GRANTS & AWARDS

#### **SWARM 2021**

· Best Paper Award

Jun 2021

## **ASU Graduate College**

• Completion Fellowship (\$8,550 plus tuition for 1 credit hour)

Aug 2020

## ASU Ira A. Fulton Schools of Engineering

• Engineering Graduate Fellowship (\$700)

May 2020

## ASU School of Computing, Informatics, and Decision Systems Engineering

• Doctoral Fellowship (\$4,000)

Mar 2020

## **ASU Social Insect Research Group**

• Student Research Grants (\$1,550)

Nov 2018

Project: Deep Features for Generalizable Insect-behavior Learning.

## SSU College of Information Technology

• Bronze Award at Software Development Competition

Oct 2012

- Social Alarm: Smart Android Alarm Application (Photos & Demo)

# PROFESSIONAL SERVICE

# **Workshop Organizer**

- (Under Review in ICRA2023) "Task-Informed Grasping IV: From Farm To Fork"
  - Full-day workshop on robotic innovations to improve food systems—from farming to postharvesting, consumption, and legislation

#### Conference/Journal Reviewer

• ICRA 2023, ICRA 2022, IROS 2022, RA-L, ICRA 2020

#### **Grant Reviewer**

· Research Grant at ASU GPSA

Aug 2017 – May 2018

· Travel Grant at ASU GPSA

Aug 2016 - Jul 2017

#### **Conference Session Chair**

• TAROS 2021 Sep 2021

• IEEE CASE 2017 Aug 2017

HARDWARE AND

**Data Science & Machine Learning:** 

SOFTWARE SKILLS • Tensorflow, PyTorch, Tensorboard, Weka, OpenCV, and Gephi

**Programming Languages:** 

• Python, Java, C, C++, UNIX shell scripting, GNU make, MySQL, and others

**Operating Systems:** 

• Microsoft Windows family, Apple OS X, Linux, and other UNIX variants

Others:

• Unity 3D, MATLAB, LATEX, GitHub, Android, and TCP/IP programming

SERVICE

**ASU International Students Club** 

Student President Aug 2016 – Dec 2017

Korea Food for the Hungry International (KFHI)

Math Tutor for Middle School Students Apr 2014 – Aug 2014

**Korea Campus Crusade for Christ** 

Student President for the Southern District of Seoul Mar 2011 – Aug 2012

**Republic of Korea Army** 

Military Service Feb 2009 – Dec 2010