

CONTACT INFORMATION	Lincoln Agri-Robotics Centre University of Lincoln Room 2003, Riseholme Hall Lincoln LN2 2LG, UK	✉: tchoi@lincoln.ac.uk 🌐: taeyeongchoi.com 🐦: ssuty
INTERESTS	<b>Novel learning algorithms for real applications with limited resources</b> — agricultural AI, robotics, deep neural networks, anomaly detection, data/controller synthesis, Bayesian learning, active planning/navigation, information-theoretic decision-making, decentralised systems, and reinforcement learning	
CURRENT ACADEMIC APPOINTMENTS	<b>University of Lincoln (UoL)</b> , Lincoln, UK Postdoctoral Research Associate	<b>Oct 2020 – Present</b>
	<ul style="list-style-type: none"> <li>• Supervisor: Dr. Grzegorz Cielniak</li> <li>• Affiliations: <ul style="list-style-type: none"> <li>– Lincoln Agri-Robotics (LAR)</li> <li>– Lincoln Institute for Agri-food Technology (LIAT)</li> <li>– Lincoln Centre for Autonomous Systems (L-CAS)</li> </ul> </li> </ul>	
EDUCATION	<b>Arizona State University (ASU)</b> , Tempe, AZ, USA M.S. & Ph.D., Computer Science	<b>Dec 2020</b>
	<ul style="list-style-type: none"> <li>• Advisor: Dr. Theodore (Ted) P. Pavlic</li> <li>• Ph.D. Dissertation: "Deep Learning Approaches for Inferring Collective Macrostates from Individual Observations in Natural and Artificial Multi-Agent Systems Under Realistic Constraints". ISBN: 9798557031004</li> </ul>	
	<b>Soongsil University (SSU)</b> , Seoul, South Korea B.S.E., Computer Science and Engineering	<b>Aug 2015</b>
WORK EXPERIENCE	<b>Atlassian</b> , Mountain View, CA <i>Data Scientist Intern</i>	<b>May 2018 – Aug 2018</b>
	<ul style="list-style-type: none"> <li>• Jira Duplicate Ticket Detection <ul style="list-style-type: none"> <li>– Designed a deep learning pipeline for human natural language to classify semantically similar tickets from customers.</li> <li>– Gathered &gt;124K examples to implement, train, fine-tune, and validate specialized LSTM models.</li> <li>– Demonstrated 1) significantly higher accuracy than traditional machine learning models, 2) generalizability to the data from different sources of ticket, and 3) feasibility of similarity-based ranking scenarios.</li> </ul> </li> </ul>	
PUBLICATIONS	<b>(Accepted / Preprinted)</b> [1] <b>Choi T.</b> , O. Would, A. Salazar-Gomez, and G. Cielniak. Self-supervised Representation Learning for Reliable Robotic Monitoring of Fruit Anomalies. In: <i>2022 IEEE International Conference on Robotics and Automation (ICRA 2022)</i> . arXiv:2109.10135. [2] <b>Choi T.</b> and G. Cielniak. Channel Randomisation with Domain Control for Effective Representation Learning of Visual Anomalies in Strawberries. In: <i>AAAI-22 Workshop on AI for Agriculture and Food Systems (AIAFS 2022)</i> . OpenReview.net. <b>(Published)</b> [3] <b>Choi T.</b> , Benjamin Pyenson, Juergen Liebig, and T. P. Pavlic. Beyond Tracking: Using Deep Learning to Discover Novel Interactions in Biological Swarms. <i>Journal of Artificial Life and Robotics (AROB)</i> , Mar 2022. doi:10.1007/s10015-022-00753-y	

— Extension of the *Best Paper Award* winner at the *4th International Symposium on Swarm Behavior and Bio-Inspired Robotics 2021 (SWARM 2021)*, Jun 1–4, 2021. Kyoto, Japan. Virtual event.

- [4] **Choi T.** and G. Cielniak. Adaptive Selection of Informative Path Planning Strategies via Reinforcement Learning. In: *Proceedings of the 10th European Conference on Mobile Robots (ECMR 2021)*, Aug 31–Sep 3, 2021. Bonn, Germany. Virtual event. doi:10.1109/ECMR50962.2021.9568796
- [5] **Choi T.**, Benjamin Pyenson, Juergen Liebig, and T. P. Pavlic. Identification of Abnormal States in Videos of Ants Undergoing Social Phase Change. In: *Proceedings of the 35th AAAI Conference on Artificial Intelligence (AAAI-21)*, Feb 2–9, 2021. Virtual event.
- [6] **Choi T.** and T. P. Pavlic. Automatic Discovery of Motion Patterns that Improve Learning Rate in Communication-Limited Multi-Robot Systems. In: *Proceedings of the IEEE 2020 International Conference on Multisensor Fusion and Integration (MFI 2020)*, Sep 14–16, 2020. Karlsruhe, Germany. Virtual event. doi:10.1109/MFI49285.2020.9235218
- [7] Kang, S., **T. Choi** and T. P. Pavlic. How Far Should I Watch? Quantifying the Effect of Various Observational Capabilities on Long-range Situational Awareness in Multi-robot Teams. In: *Proceedings of the 1st IEEE International Conference on Autonomic Computing and Self-Organizing Systems (ACSOS 2020)*, Aug 17–21, 2020. Washington, DC, USA. Virtual event. doi:10.1109/ACSOS49614.2020.00036
- [8] **Choi, T.**, S. Kang, and T. P. Pavlic. Learning Local Behavioral Sequences to Better Infer Non-local Properties in Real Multi-robot Systems. In: *Proceedings of the 2020 IEEE International Conference on Robotics and Automation (ICRA 2020)*, May 31–June 4, 2020. Paris, France. Virtual event. doi:10.1109/ICRA40945.2020.9196728
- [9] **Choi, T.**, T. P. Pavlic, and A. W. Richa. Automated Synthesis of Scalable Algorithms for Inferring Non-Local Properties to Assist in Multi-Robot Teaming. In: *Proceedings of the 2017 IEEE International Conference on Automation Science and Engineering (CASE 2017)*, Aug 20–23, 2017. Xi'an, China. doi:10.1109/COASE.2017.8256320
- [10] **Choi, T.** and H. Na. Stealthy Behavior Simulations based on Cognitive Data. *Journal of Korea Game Society (JKGS)*, 16(2):27–40, Apr 2016. doi:10.7583/JKGS.2016.16.2.27
- [11] **Choi, T.** and H. Na. Making Levels More Challenging with a Cooperative Strategy of Ghosts in Pac-Man. *Journal of Korea Game Society (JKGS)*, 15(5):89–98, Oct 2015. doi:10.7583/JKGS.2015.15.5.89
- [12] **Choi, T.** and H. Na. Stealthy Behavior Simulations based on Cognitive Data. In: *Proceedings of the 2015 IEEE International Conference on Machine Learning and Cybernetics (ICMLC 2015)*, 16(2):27–40, Jul 12–15 2015. Guangzhou, China. doi:10.1109/ICMLC.2015.7340900
- POSTER  
PRESENTATIONS [13] **Choi, T.**, T. P. Pavlic, and A. W. Richa. Automated Synthesis of Scalable Algorithms for Inferring Non-local Properties to Assist in Multi-Robot Teaming. In: Poster Session at *Southwest Robotics Symposium*, Jan 2018. Tempe, AZ, USA.
- [14] **Choi, T.**, T. P. Pavlic, and A. W. Richa. Automated Synthesis of Scalable Algorithms for Inferring Non-local Properties to Assist in Multi-Robot Teaming. In: Poster Session at *TEDxASU: Innovators Symposium*, Mar 2017. Tempe, AZ, USA.
- [15] **Choi, T.**, J. Lee, C. Soh, and J. Lee. Social Alarm: Smart mobile application helping people to get up together. In: Poster Session at *Seoul Accord ITeM SHOW*, Dec 2012. Seoul, South Korea.

- INVITED TALKS
- [16] Self-supervised Learning of Visual Anomalies in Strawberries. In: *International Conference on Digital Technologies for Sustainable Crop Production (DIGICROP)*, Mar 2022. Virtual event.
  - [17] AI Research in Agriculture and Beyond – Successful Machine Learning under Limited Resources. In: *Hankyong National University, School of Computer Engineering & Applied Mathematics Seminar*, Dec 2021. Anseong, South Korea.
  - [18] Identifying Anomalies for Better Decision-Making. In: *University of Lincoln, CMP9766M: Frontiers of Robotics Research Seminar*, May 2021. Lincoln, UK. Virtual event.
  - [19] Local Behavior Learning for Social Temperature Prediction without Individual Ant Tracking. In: Oral Session at *Collective Information Processing*, Mar 2020. Berlin, Germany.
  - [20] Machine Learning Applications for Video Game Development. In: *Hankyong National University, School of Computer Engineering & Applied Mathematics Seminar*, Jul 2015. Anseong, South Korea.

RESEARCH  
PROJECTS

ASU, Tempe, AZ

- NSF: "CRISP: Type 2/Collaborative Research: Design and Control of Coordinated Green and Gray Water Infrastructure to Improve Resiliency in Chemical and Agricultural Sectors" **Aug 2018 – Dec 2019**
  - PI: Dr. John Sabo
  - Combinatorial optimization for the placement of green infrastructures (wetlands) along with gray infrastructures (reservoirs) to minimize risks of natural disasters in an area of interest.
- DARPA I20: "BioSwarm: Bio-Inspired Swarming" **Aug 2017 – Jul 2018**
  - Supervisor (co-PI): Dr. Theodore (Ted) P. Pavlic
  - PI: Dr. Stephen C. Pratt
  - Designed deep neural networks to identify informative behaviors of *Harpegnathos* ants for classification of colonial states.

SSU, Seoul, South Korea

- Reinforcement Learning for Video Game Design **Oct 2014 – Aug 2015**
  - Supervisor: Dr. Hyeon-Suk Na
  - Designed a model-free reinforcement learning framework to predict the actions of human players at the stage of video game development.
  - Proposed team strategies of enemies using A\* algorithm to highly increase the level in the games of Pac-Man.
- Development of a Cognitive Planning and Learning Model for Mobile Platforms **Dec 2012 – Sep 2014**
  - Supervisor: Dr. Young-Tack Park
  - Contributed to refining noisy GPS data from Android phones and creating modules on Android OS for reliable communication with a remote server computer.
  - Implemented ontology-based temporal reasoning models integrated with SPAQL.

TEACHING  
EXPERIENCE

ASU, Tempe, AZ

*Teaching Assistant*

- CSE 450/551: Design Analysis of Algorithms/Foundations of Algorithms: **Jan 2018 – May 2018**
  - Instructor: Dr. Andréa Richa
  - Graded exams, and held office hours (2 hours/week) for tutoring students.

- CSE 310: Data Structures and Algorithms: **Aug 2017 – Dec 2017**
  - Instructor: Dr. Andréa Richa
  - Taught recitation sessions (4 hours/week), graded exams, and provided instructions for C++ programming assignments.
- CSE 205: Object-Oriented Programming & Data Structures **Jan 2016 – May 2016**
  - Instructor: Dr. Xuerong Feng
  - Graded exams, and tutored students for Java programming (4 hours/week).
- CSE 100: Prin. of Programming with C ++ **Jan 2016 – May 2016**
  - Instructor: Dr. Phillip Miller
  - Supervised C++ programming laboratories (5 hours/week), and held tutoring hours (4 hours/week).
- CSE 424: Capstone Project II **Aug 2015 – Dec 2015**
  - Instructor: Dr. Debra Calliss
  - Supervised each project group with their short-term and long-term goals, and graded IT ethics essays.

## MENTORING

**UoL, Lincoln, UK**

- Owen Would (MSc in Robotics & Autonomous Systems) **Mar 2021 – Sep 2021**
  - Studied on deep network-based visual anomaly detection of strawberry images, and validated GAN-based approaches on challenging conditions such as occlusion.

**ASU, Tempe, AZ, USA**

- Sehyeok Kang (MS in Computer Engineering) **Mar 2019 – May 2020**
  - Researched on Remote Teammate Localization on the physical robot platform *Thymio*, and also analysed the correlation between the prediction accuracy and the amount of observation samples.
- Ricardo Weir (BS in Computer Science) **Mar 2018 – Dec 2018**
  - Built a YOLO-based deep learning pipeline from data annotation to model validation to perform automatic tracking of individual *Harpegnathos* ants from video recordings.

GRANTS  
& AWARDS**SWARM 2021**

- Best Paper Award Jun 2021

**ASU Graduate College**

- Completion Fellowship (\$8,550 plus tuition for 1 credit hour) Aug 2020

**ASU Ira A. Fulton Schools of Engineering**

- Engineering Graduate Fellowship (\$700) May 2020

**ASU School of Computing, Informatics, and Decision Systems Engineering**

- Doctoral Fellowship (\$4,000) Mar 2020

**ASU Social Insect Research Group**

- Student Research Grants (\$1,550) Nov 2018
  - Project: Deep features for generalizable insect behavior learning.

	<b>SSU College of Information Technology</b>	
	<ul style="list-style-type: none"> <li>• Bronze Award at Software Development Competition – Social Alarm: Smart Android Alarm Application (Photos &amp; Demo)</li> </ul>	Oct 2012
PROFESSIONAL SERVICE	<b>TAROS 2021</b>	
	<ul style="list-style-type: none"> <li>• <i>Session Chair: "Oral Session 3"</i></li> </ul>	Sep 2021
	<b>ASU Graduate and Professional Student Association</b>	
	<ul style="list-style-type: none"> <li>• <i>Research Grants Reviewer</i></li> </ul>	Aug 2017 – May 2018
	<ul style="list-style-type: none"> <li>• <i>Travel Grants Reviewer</i></li> </ul>	Aug 2016 – Jul 2017
	<b>IEEE CASE 2017</b>	
	<ul style="list-style-type: none"> <li>• <i>Session Co-chair: "Big Data for Automation II"</i></li> </ul>	Aug 2017
HARDWARE AND SOFTWARE SKILLS	<b>Data Science &amp; Machine Learning:</b>	
	<ul style="list-style-type: none"> <li>• Tensorflow, PyTorch, Tensorboard, Weka, OpenCV, and Gephi.</li> </ul>	
	<b>Robotics:</b>	
	<ul style="list-style-type: none"> <li>• Thymio: A two-wheeled mobile robotic platform with a small diameter of about 12cm.</li> <li>• Robotarium: Mobile multi-robot system simulator, designed by <i>GRITSLab</i> in <i>Georgia Institute of Technology</i>, enabling to remotely access the physical robotic resources.</li> <li>• Webots: An open-sourced robot simulator to visualise operation of various commercialised platforms in 3D with Python scripts.</li> </ul>	
	<b>Programming Languages:</b>	
	<ul style="list-style-type: none"> <li>• Python, Java, C, C++, UNIX shell scripting, GNU make, MySQL, and others.</li> </ul>	
	<b>Operating Systems:</b>	
	<ul style="list-style-type: none"> <li>• Microsoft Windows family, Apple OS X, Linux, and other UNIX variants.</li> </ul>	
	<b>Others:</b>	
	<ul style="list-style-type: none"> <li>• Unity 3D, MATLAB, L<sup>A</sup>T<sub>E</sub>X, GitHub, Android, and TCP/IP programming.</li> </ul>	
SERVICE	<b>ASU International Students Club</b>	
	<i>Student President</i>	Aug 2016 – Dec 2017
	<b>Korea Food for the Hungry International (KFHI)</b>	
	<i>Math Tutor for Middle School Students</i>	Apr 2014 – Aug 2014
	<b>Campus Crusade for Christ at Seoul South District</b>	
	<i>Student President</i>	Mar 2011 – Aug 2012
	<b>Republic of Korea Army</b>	
	<i>Military Service</i>	Feb 2009 – Dec 2010