

# Signal Management

**Advanced Embedded Linux  
Development  
with Dan Walkes**



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**Learning objectives:**  
Writing Signal Handlers  
Signal Handlers and Reentrancy



# Signal Management

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SIGNAL(2)

Linux Programmer's Manual

NAME

signal - ANSI C signal handling

SYNOPSIS

```
#include <signal.h>

typedef void (*sighandler_t)(int);

sighandler_t signal(int signum, sighandler_t handler);
```

DESCRIPTION

The behavior of `signal()` varies across UNIX versions, and has also varied historically across different versions of Linux.

Avoid its use: use `sigaction(2)` instead.

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SIGACTION(2)

NAME

`sigaction`, `rt_sigaction` - examine and change a signal action

SYNOPSIS

```
#include <signal.h>

int sigaction(int signum, const struct sigaction *act,
              struct sigaction *oldact);
```

# sigaction signal handling

- POSIX alternative (not part of the original std C library)
- Better signal management capabilities

NAME  
sigaction, rt\_sigaction - examine and change a signal action  
  
SYNOPSIS  
#include <signal.h>  
  
int sigaction(int signum, const struct sigaction \*act,  
              struct sigaction \*oldact);

The sigaction structure is defined as something like:

```
struct sigaction {  
    void (*sa_handler)(int);  
    void (*sa_sigaction)(int, siginfo_t *, void *);  
    sigset_t sa_mask;  
    int sa_flags;  
    void (*sa_restorer)(void);  
};
```

# sigaction signal handling

- Better signal management capabilities
  - Block new signals during handler
  - Retrieve state information
  - Only need to setup `sa_handler` in `sigaction` in simple cases

The `sigaction` structure is defined as something like:

```
struct sigaction {  
    void    (*sa_handler)(int);  
    void    (*sa_sigaction)(int, siginfo_t *, void *);  
    sigset_t sa_mask;  
    int     sa_flags;  
    void    (*sa_restorer)(void);  
};
```

**NAME**  
`sigaction, rt_sigaction` - examine and change a signal action

**SYNOPSIS**  
`#include <signal.h>`  
`int sigaction(int signum, const struct sigaction *act,`  
 `struct sigaction *oldact);`

# Waiting for signals

- `pause()` waits for a signal

```
PAUSE(2)          Linux Programmer's Manual      PAUSE(2)

NAME
    pause - wait for signal

SYNOPSIS
    #include <unistd.h>
    int pause(void);

DESCRIPTION
    pause() causes the calling process (or thread) to sleep until a signal is
    delivered that either terminates the process or causes the invocation of
    a signal-catching function.
```

# Sending signals

- `kill()` sends a signal to a process
  - Sends any signal, not just SIGKILL
- Available as system call or user command

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## KILL(1)

### NAME

`kill` - send a signal to a process

### SYNOPSIS

`kill [options] <pid> [...]`

`-<signal>`

`-s <signal>`

`--signal <signal>`

Specify the signal to be sent. The signal can be specified by using name or number. The behavior of signals is explained in `signal(7)` manual page.

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## KILL(2)

### NAME

`kill` - send signal to a process

### SYNOPSIS

```
#include <sys/types.h>
#include <signal.h>
```

```
int kill(pid_t pid, int sig);
```

### NAME

`sigqueue` - queue a signal and data to a process

### SYNOPSIS

```
#include <signal.h>
```

```
int sigqueue(pid_t pid, int sig, const union sigval value);
```

# sigaction signal handling

```
int main ( int argc, char **argv )
{
    struct sigaction new_action;
    bool success = true;
    memset(&new_action,0,sizeof(struct sigaction));
    new_action.sa_handler=signal_handler;
    if( sigaction(SIGTERM, &new_action, NULL) != 0 ) {
        printf("Error %d (%s) registering for SIGTERM",errno,strerror(errno))
        success = false;
    }
    if( sigaction(SIGINT, &new_action, NULL) ) {
        printf("Error %d (%s) registering for SIGINT",errno,strerror(errno));
        success = false;
    }

    if( success ) {
        printf("Waiting forever for a signal\n");
        pause();
        if( caught_sigint ) {
            printf("\nCaught SIGINT!\n");
        }
        if( caught_sigterm ) {
            printf("\nCaught SIGTERM!\n");
        }
    }
}
```

```
bool caught_sigint = false;
bool caught_sigterm = false;

static void signal_handler ( int signal_number )
{
    if ( signal_number == SIGINT ) {
        caught_sigint = true;
    } else if ( signal_number == SIGTERM ) {
        caught_sigterm = true;
    }
}
```

# signal handling

```
aesd@aesd-VirtualBox:~/aesd-lectures/lecture9$ ./signal_handler
Waiting forever for a signal
^C
Caught SIGINT!
```

```
aesd@aesd-VirtualBox:~/aesd-lectures/lecture9$ ./signal_handler
Waiting forever for a signal
```

```
aesd@aesd-VirtualBox:~/aesd-lectures/lecture9$ ps aux | grep signal_handler
aesd    31236  103  0.0  4504   732 pts/1    R+   14:07   0:16 ./signal_handler
aesd    31246  0.0  0.0  21532   996 pts/8    S+   14:07   0:00 grep --color=auto signal_handler
```

```
aesd@aesd-VirtualBox:~/aesd-lectures/lecture9$ kill -TERM 31236
```

```
Caught SIGTERM!
aesd@aesd-VirtualBox:~/aesd-lectures/lecture9$
```

- Ctrl->C sends SIGINT
- Restart
- Find process PID
- Send TERM

- Process exits with TERM

# Sending signals

- `sigqueue()` can send a payload with a signal
  - Rudimentary form of IPC

## NAME

`sigqueue` - queue a signal and data to a process

## SYNOPSIS

```
#include <signal.h>

int sigqueue(pid_t pid, int sig, const union sigval value);
```

```
union sigval {
    int sival_int;
    void *sival_ptr;
};
```

If the receiving process has installed a handler for this signal using the `SA_SIGINFO` flag to `sigaction(2)`, then it can obtain this data via the `si_value` field of the `siginfo_t` structure passed as the second argument to the handler. Furthermore, the `si_code` field of that structure will be set to `SI_QUEUE`.

```
struct sigaction {
    void (*sa_handler)(int);
    void (*sa_sigaction)(int, siginfo_t *, void *);
    sigset_t sa_mask;
    int sa_flags;
    void (*sa_restorer)(void);
};

siginfo_t {
    int si_signo; /* Signal number */
    int si_errno; /* An errno value */
    int si_code; /* Signal code */

    . . .

    clock_t si_utime; /* User time consumed */
    clock_t si_stime; /* System time consumed */
    sigval_t si_value; /* Signal value */
    int si_int; /* POSIX.1b signal */
    void *si_ptr; /* POSIX.1b signal */
    . . .
}
```

# Additional Signal Concepts

- Child inherits signal actions of the parent on fork
- Starting a processes with exec() resets all signals to default actions (other than those ignored by the parent).



# Signal Handlers and Safety

- Signal handlers:
  - Suspend execution of a process
  - Jump to our signal handler function
  - Not a thread switch or new thread - re-uses the existing thread



# Signal Handlers and Safety

- What does this mean about the functions you can call in the signal handler?
  - Must be “async-signal-safe” in Single Unix Specification parlance.
  - Must be reentrant \*and\* block signals during any points which could cause inconsistencies



# Signal Handlers and Safety

- How do I know if a POSIX function I'm calling is signal safe?
  - Table of allowed functions - one in your book, more complete in link below
  - malloc, free, (or any function which may call these) stdio library functions (printf for instance) are generally **not safe to call**.

# Signal Handlers and Reentrancy

- Must not manipulate static data also used outside the signal handler (`strsignal()` or similar functions)
- Should manipulate only stack-allocated data or data provided by the caller
  - Setting global flag is acceptable
- Must not invoke any non- async-signal-safe function



# Signal Handler Best practices

- Minimize global data access
  - Confirm any access is async signal safe
- Save/restore errno
- Call an absolute minimum set of functions,
  - Call only functions on an approved list of signal handler functions.



# Why Use/Not Use Signals?

- “old, antiquated mechanism for kernel to user communication”
- However, we are forced to use them for many important notifications (especially termination).
- Signal safety problems are easy to introduce and difficult to track down.
  - Handlers must be implemented carefully.