

Wiring a button and LED

And connecting to Adafruit IO

IOT Oct 31, 2023

Our data transmission is slow!!!

- Our cloud computers on **Adafruit IO** limit our data to 60 per minute
- We are only going to transmit small packets of information

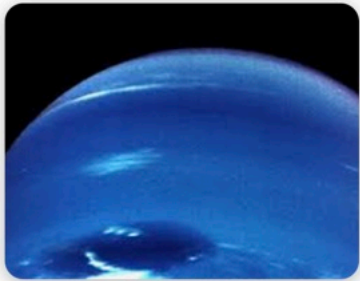
Nano 1 State

```
"time": 01:27:03  
"date": 2023-10-31  
"buttonpresses": 7  
"now": 1577838715  
"wifiConnected": True  
"buttonstate": False  
"rgbled": 0
```

Voyager 1 and 2 (NASA) 1977

Voyager 1 and 2 (NASA) 1977

Primary mission: Collect data including pictures



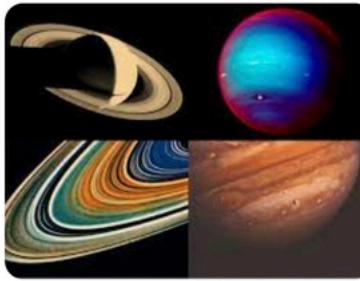
Voyager - NASA

Voyager - Galleries of Images Vo...



Voyager - NASA

Voyager - Galleries of Images...



Business Insider

NASA Voyager Probes: 18 Best Pic...



Voyager - NASA

Voyager - Galleries of Images Vo...



PBS

Voyager: A History in Photos



NASA

Voyager Image Gallery



Business Insider

NASA Voyager Probes: 18 Best Pict...



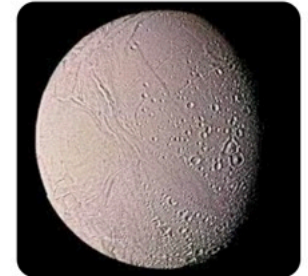
YouTube

Voyager Images from the Odysseys (NASA ...



Voyager - NASA

Voyager - Images Voyager t...



Business Insider

NASA Voyager Probes: 18...

Just Google It!

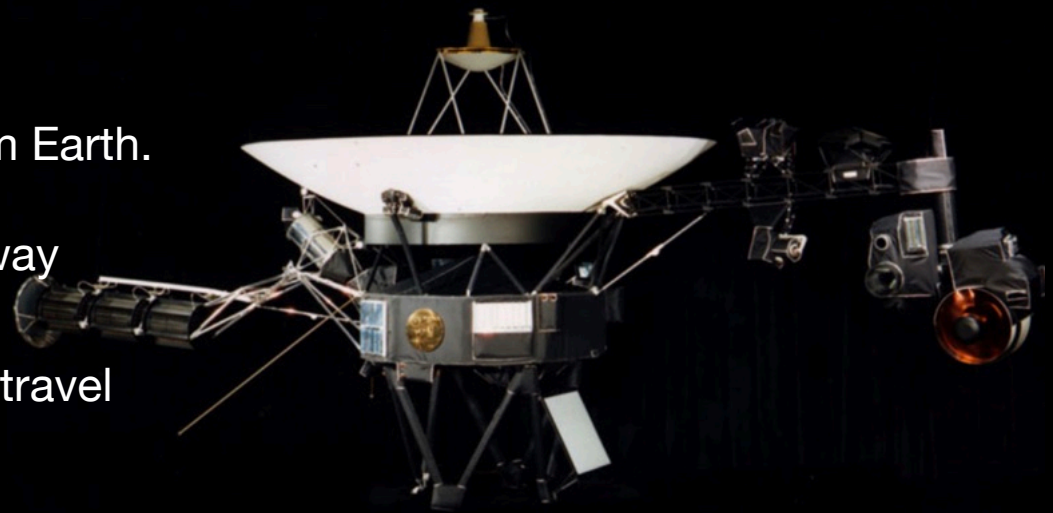
Voyager 1 and 2 (NASA) 1977

Voyager 1 is currently **15 billion miles** from Earth.

This morning was 15,079,868,948 miles away

It takes light >20 hours and 33 minutes to travel that distance

That means it takes roughly **two days to send a message to Voyager 1 and get a response**



A 45 year old IOT
Very far away
Lots of thing collecting data
Transmitting data back to earth

<https://voyager.jpl.nasa.gov/mission/status/>

Voyager 1 and 2 (NASA) 1977

Very slow computers and data transmission

The computers aboard the Voyager probes each have 69.63 kilobytes of memory, total. That's about enough to store one average internet jpeg image file.

~3,000,000 times less memory than your phone

The probes' scientific data is encoded on old-fashioned digital 8-track tapes rather than whatever solid state drive your laptop or phone is currently using.

Transmits data at 160 bits per second, 38,000 times slower than a 5G connection

The Voyager computers can execute about 81,000 instructions per second. A modern graphic card can compute at 10 Tera-flops, 10 Trillion per second. That is 123,456,790 times faster than Voyager

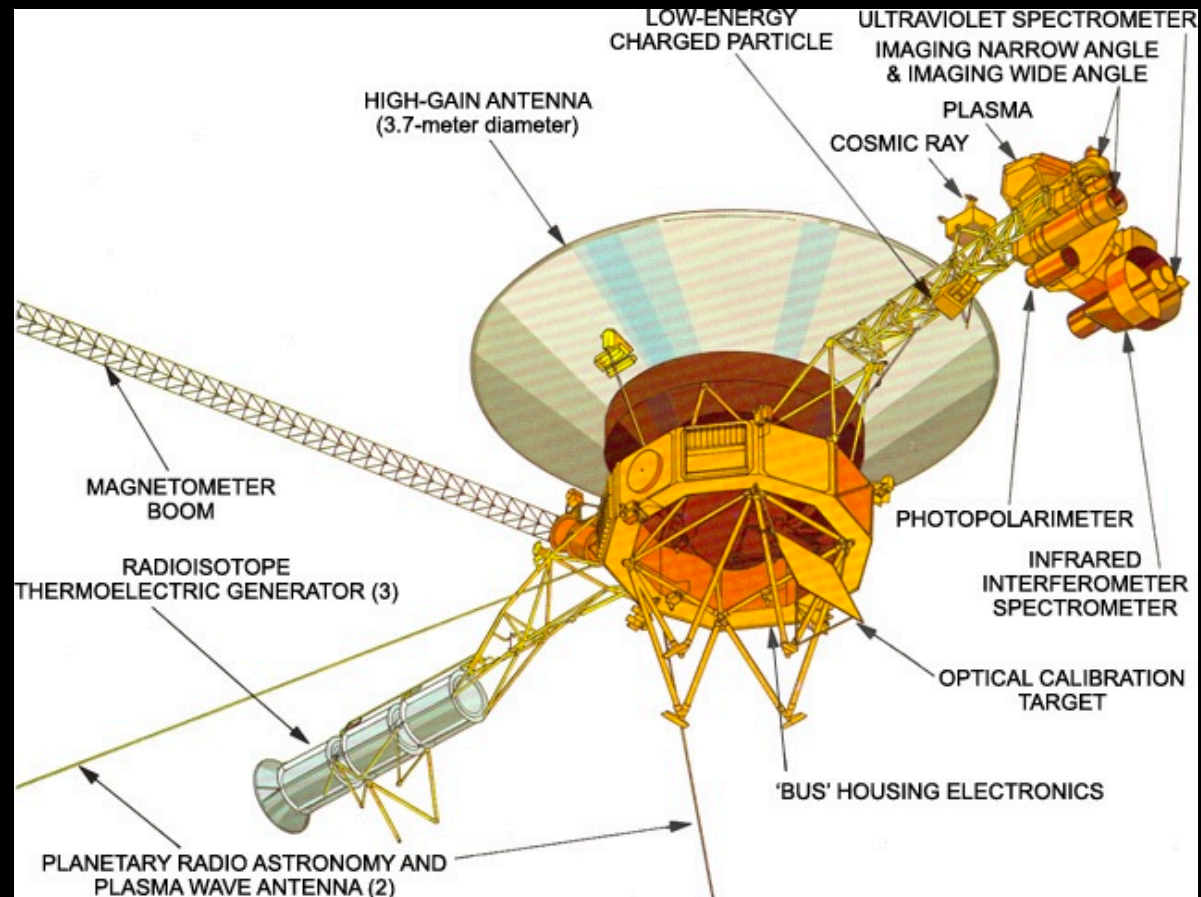
The Voyager probes are always sending out a signal. Voyager 1 has a 22.4-Watt transmitter – something equivalent to a refrigerator light bulb – but by the time its beacon reaches us, the power has been reduced to roughly 0.1 billion-billionth of a Watt. NASA has to use its largest antenna, a 70-meter dish, or combine two 34-meter antennas, just to hear Voyager.



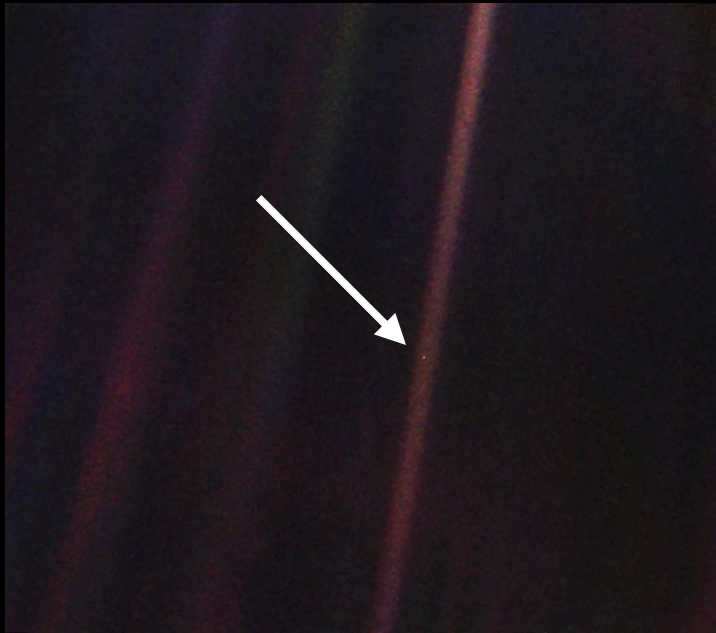
<https://voyager.jpl.nasa.gov/mission/status/>

Voyager 1 and 2 (NASA) 1977

PACKED WITH
LOTS OF
THINGS



The “Pale Blue Dot” 1990



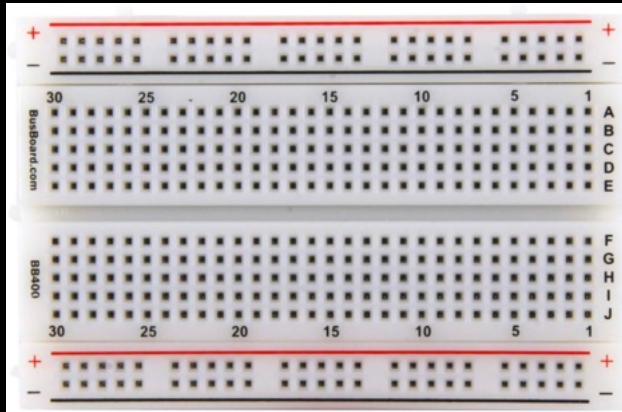
Before turning off the cameras to save power, Voyager turned toward the earth to take this photo

The “Pale Blue Dot” 1990

From this distant vantage point, the Earth might not seem of any particular interest. But for us, it's different. Consider again that dot. That's here. That's home. That's us. On it everyone you love, everyone you know, everyone you ever heard of, every human being who ever was, lived out their lives. The aggregate of our joy and suffering, thousands of confident religions, ideologies, and economic doctrines, every hunter and forager, every hero and coward, every creator and destroyer of civilization, every king and peasant, every young couple in love, every mother and father, hopeful child, inventor and explorer, every teacher of morals, every corrupt politician, every "superstar," every "supreme leader," every saint and sinner in the history of our species lived there – **on a mote of dust suspended in a sunbeam.**

- Carl Sagan

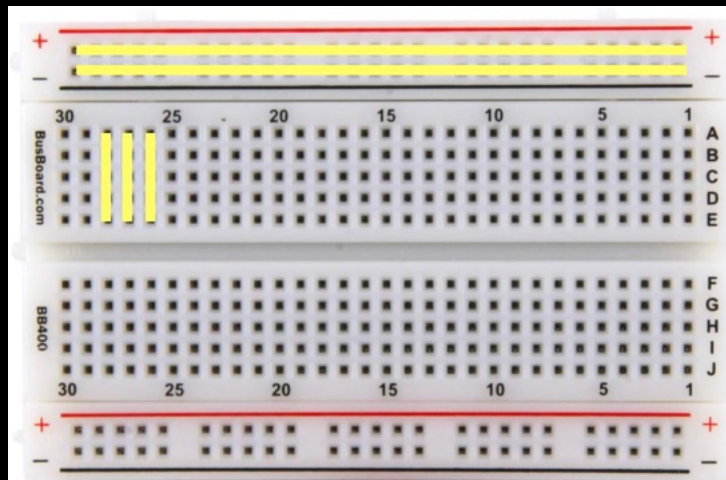
Breadboard basics



A breadboard is what we use to wire all our things together including the Arduino.

We have marked the pin holes that are electrically connected (**yellow**).

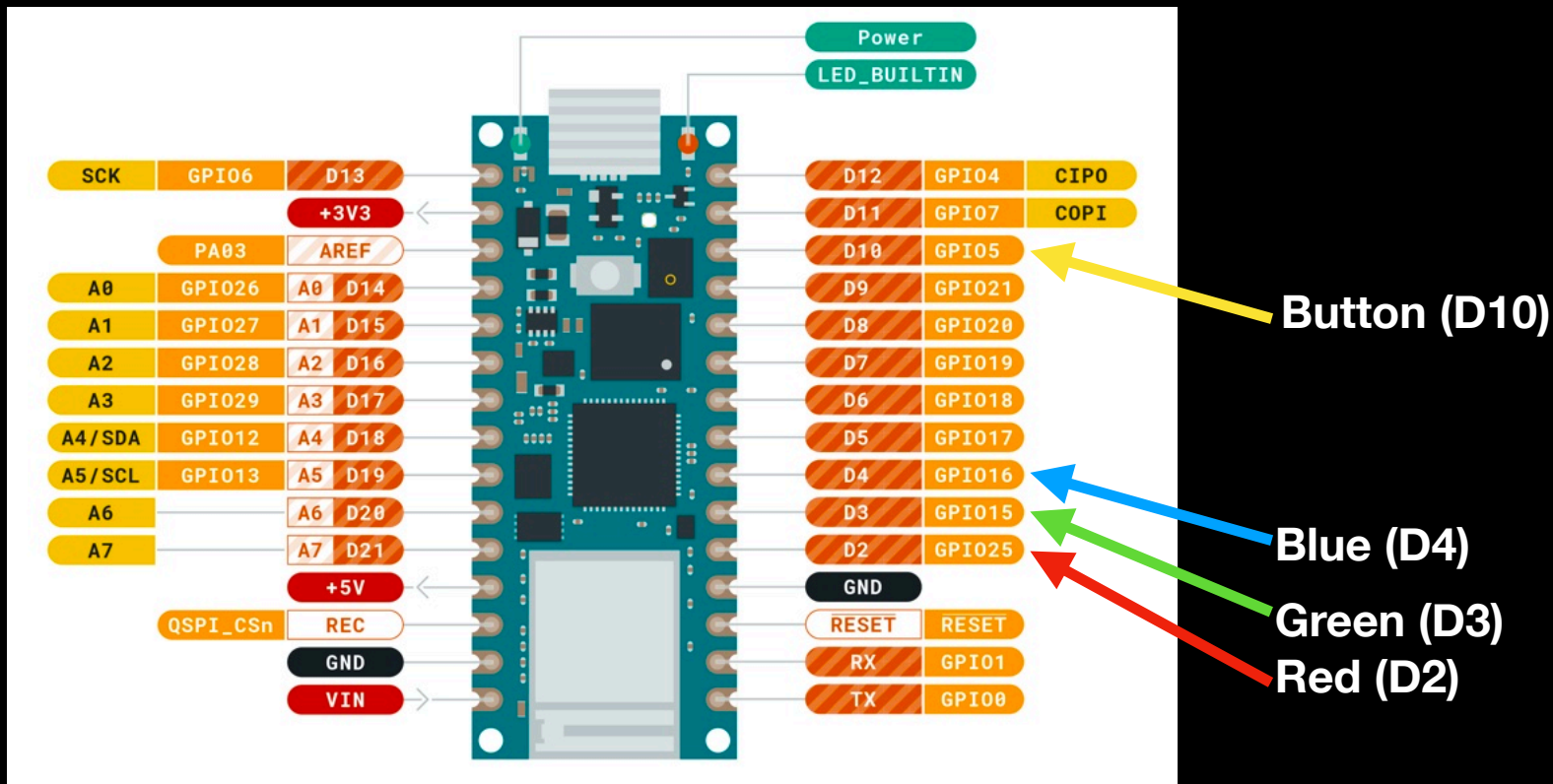
The top row is all connected together. We use this for voltage to power our things. Notice the red '+'.
The bottom row is all connected together. We use this for ground to power our things. Notice the blue '-'.



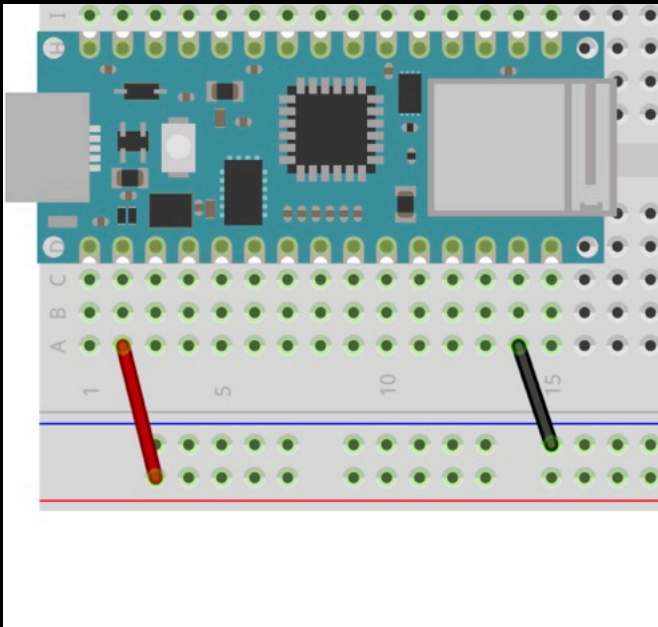
The second row is all connected together. We use this for ground of each of our things. Notice the blue '-'. Remember: All things need to be connected to ground!

Each vertical row is connected together (with a break in the middle).

Arduino Nano rp2040 connect



My code on the Arduino specifies these pins



We will start with the arduino inserted into the breadboard.

Note, the top pins are electrically isolated (not connected) to the bottom row of pins

I have connected power (red) to the bottom row

I have also connected ground (black) to the next row

I have written code that is loaded on the Arduino

- 1) On power up will eventually connect to wifi (on my phone) and RGB led will turn green.**
- 2) Once you wire the button, pressing it will trasmit the data to the Adafruit IO cloud**



It is important what they are connected to!

Connecting to Adafruit IO

Each of your Arduino's has a "Thing ID"

You can access each dashboard on the web


1) <https://io.adafruit.com/rhcudmore/dashboards/nano1>


2) <https://io.adafruit.com/rhcudmore/dashboards/nano2>

3) <https://io.adafruit.com/cudmore/dashboards/nano3>

4) <https://io.adafruit.com/cudmore/dashboards/nano4>

rhcuDmore / Dashboards / nano1

rgbled

#302a3a

Other Red LED


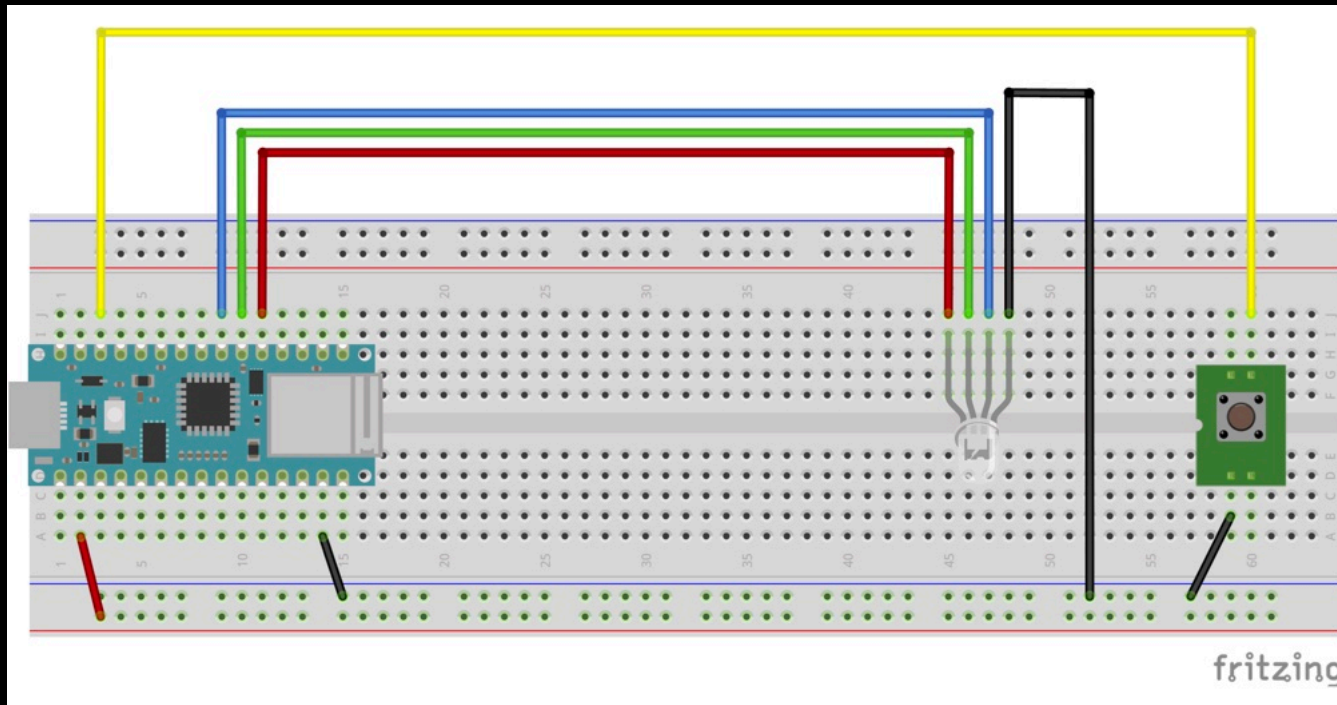
Nano 1 State

```
"time": 01:27:03  
"date": 2023-10-31  
"buttonpresses": 7  
"now": 1577838715  
"wifiConnected": True  
"buttonstate": False  
"rgbled": 0
```

Hold down the button and eventually, the switch in the middle will turn on

You can get feedback in the “Nano State”, look for changes in “buttonState”

You can also see the time update if your Arduino is connected (and its onboard RGB led is green)



Wiring a RGB LED

The RGB LED has four pins corresponding to:

Ground (-)
 Red (R) to D2
 Green (G) to D3
 Blue (B) to D4

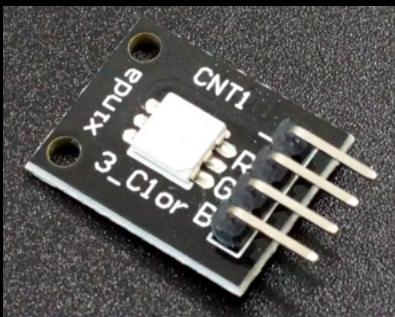
Why red, green, and blue? The RGB color model is an additive color model where different levels of red, green, and blue can create any color in the visible spectrum. This is used for displaying colors on a screen like you phone.

If each of R/G/B have equal amount the produced light is white. If all are off, there is no light.

There is another color space that specifies cyan/magenta/yellow and is used for printing a document. There are also the three primary colors for painting which are red, blue, yellow.

Once the RGB LED is wired

- 1) Holding your button will change its color
- 2) The color will be updated on Adafruit IO
- 3) I can then control your RGB LED thing from my dashboard



Things communicating with things

- Arduino 1 is connected to Arduino 2 through the internet
- Hold the button on Arduino 1 and see the red LED light up on Arduino 2
- Try the same for Arduino 2 to light the red LED on Arduino 1

1 -> 2

2 -> 1

- Arduino 3 is connected to Arduino 4 through the internet
- Hold the button on Arduino 3 and see the red LED light up on Arduino 4
- Try the same for Arduino 4 to light the red LED on Arduino 3

• 3 -> 4

• 4 -> 3