

Efficient algorithms, architectures and implementations in internet of things and smart environments

Stéphane Kundig

stephane.kundig@unige.ch



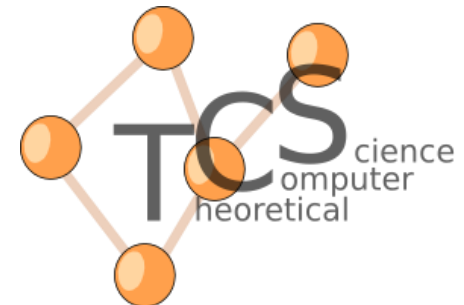
**UNIVERSITÉ
DE GENÈVE**

CENTRE UNIVERSITAIRE
D'INFORMATIQUE

TCS–Sensor Lab

University of Geneva

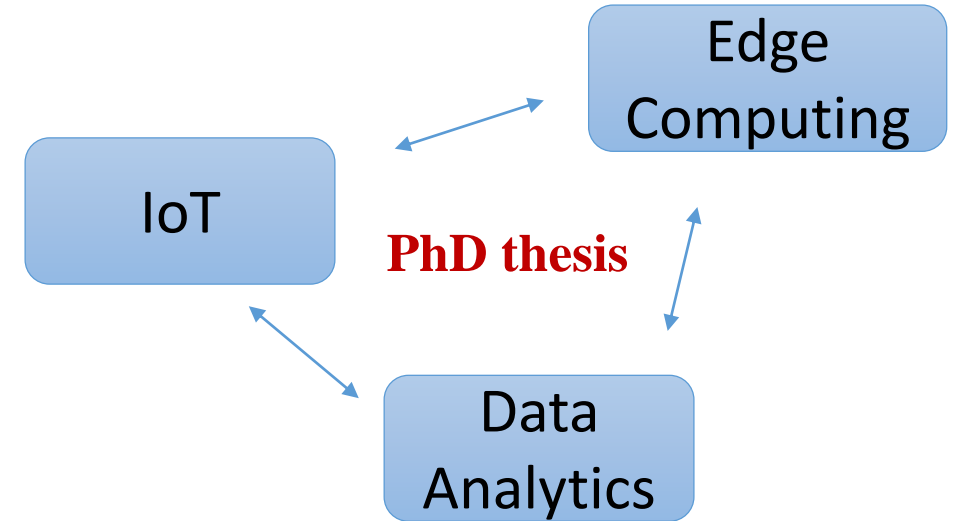
<http://tcs.unige.ch/doku.php>



Theoretical Computer Science & Sensor Lab

Presentation Outline

- The Syndesi Testbed
- Modelled Testbeds
- Efficient bidirectional search in large scale networks
- Office automation for Syndesi mobile users
- A Raspberry-Pi cluster for distributed edge computing (*ongoing work*)
- Summary



Syndesi Testbed

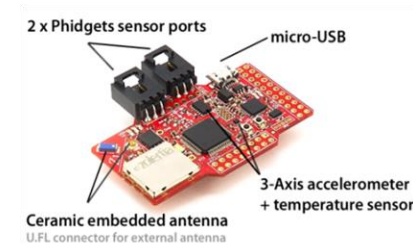
- Syndesi is an IoT framework and testbed located at the University of Geneva
- It includes WSN as well as crowdsensed resources exposing them as a service via a REST-ful architecture
- More than 30 IPv6-enabled sensor motes compose its backbone WSN



MEMSIC TelosB Mote

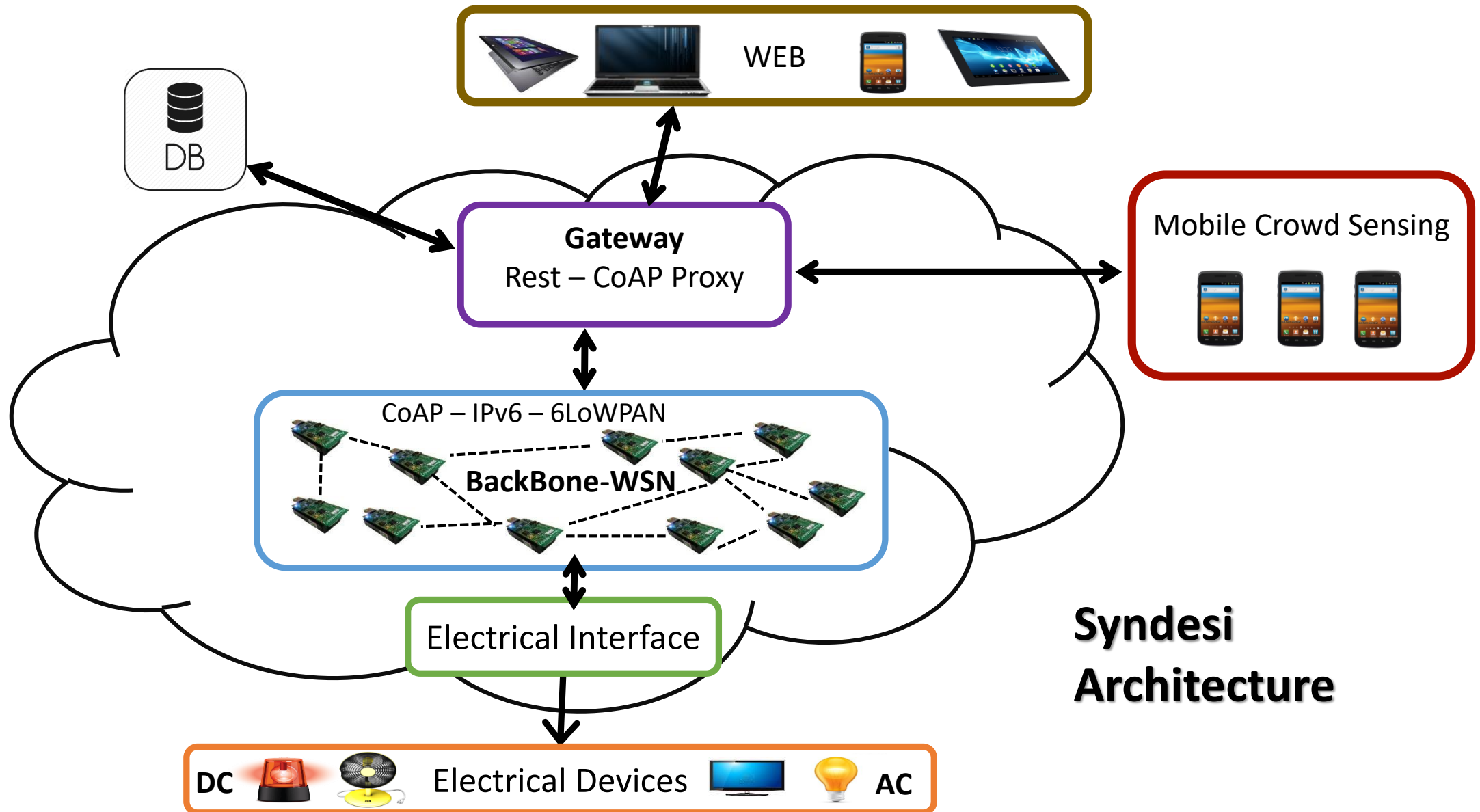


AS-XM1000 802.15.4 Mote



Zolertia's Z1 Mote

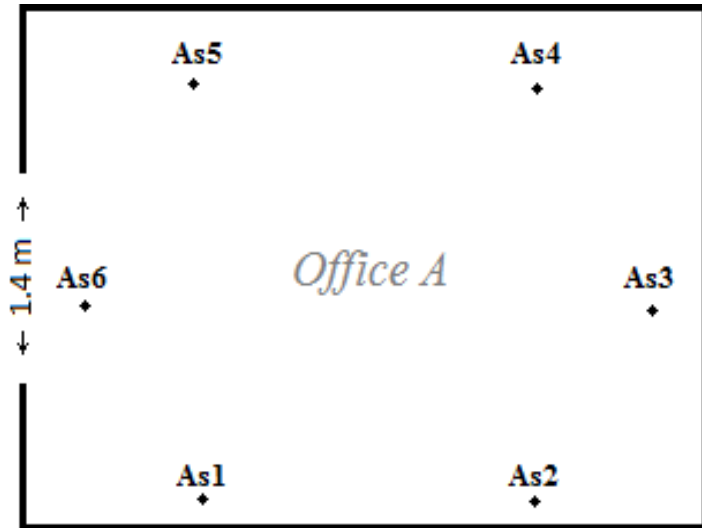
Syndesi Testbed



Creating a dataset

Data Collection

1. Illuminance
2. Temperature
3. Humidity



◆ : Physical Sensor

Automatic
query for
values every
~20min



	id	node_name	resource_name	value	unit	pos_x	pos_y	pos_z	timestamp
<input type="checkbox"/> Edit Copy Delete	22040	SGoAs6	illuminance at SGoAs6	270	lux	2.4	9.05	1.45	2016-03-18 11:20:22
<input type="checkbox"/> Edit Copy Delete	22041	SGoAs5	illuminance at SGoAs5	284	lux	2.4	11.55	3.9	2016-03-18 11:15:38
<input type="checkbox"/> Edit Copy Delete	22042	SGoAs4	illuminance at SGoAs4	315	lux	2.4	13.55	3.9	2016-03-18 11:20:10
<input type="checkbox"/> Edit Copy Delete	22043	SGoAs3	illuminance at SGoAs3	331	lux	2.4	17.6	1.45	2016-03-18 11:17:50
<input type="checkbox"/> Edit Copy Delete	22044	SGoAs2	illuminance at SGoAs2	368	lux	2.4	13.55	0	2016-03-18 11:15:03
<input type="checkbox"/> Edit Copy Delete	22045	SGoAs1	illuminance at SGoAs1	305	lux	2.4	11.55	0	2016-03-18 11:19:09



~300k measurements so far

Modelled Testbeds

- A modelled testbed (MT) is based on a physical testbed - same 3D space, connected sensors appearing in corresponding positions
- Virtual sensors can be inserted interactively in its GUI

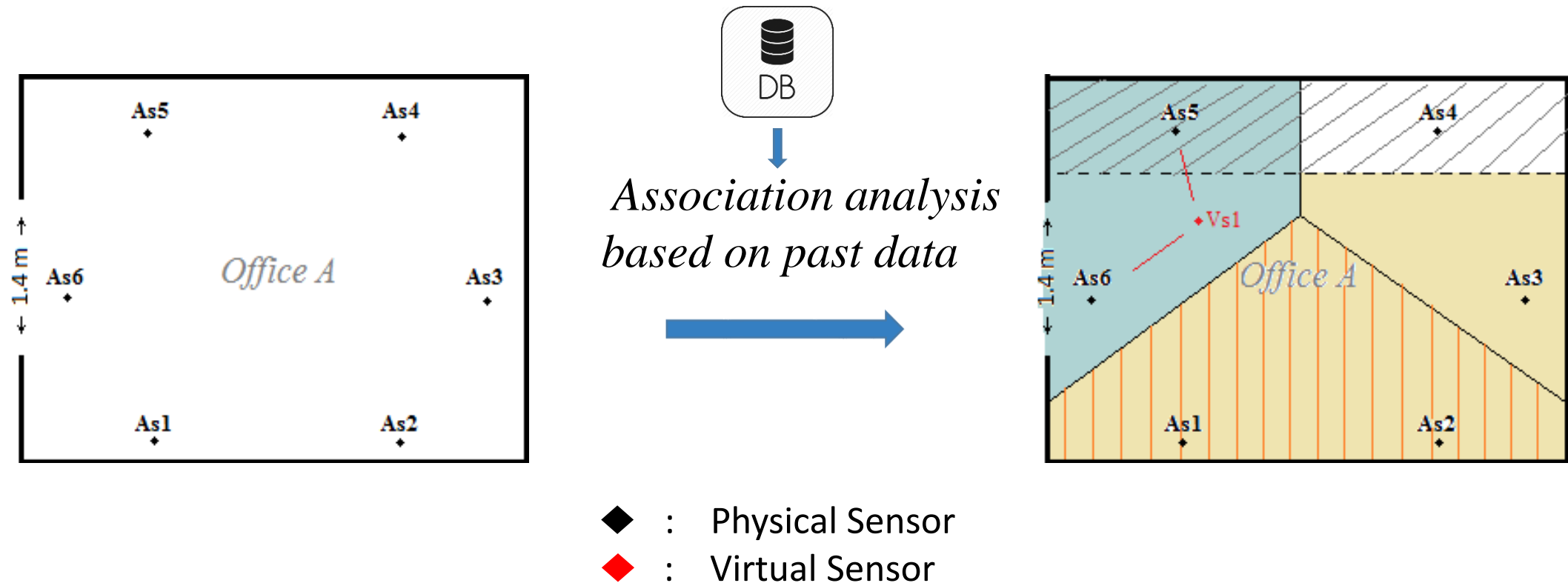
They provide:

- Very large experiment scale
- Unlimited number of simultaneous experiments



Experiment accuracy in Modelled Testbeds

- Physical sensors measurement values shown in MTs are close-to-real time.
- Virtual sensors get their values via weighted average on specific physical sensors subsets, derived from association analysis on past data



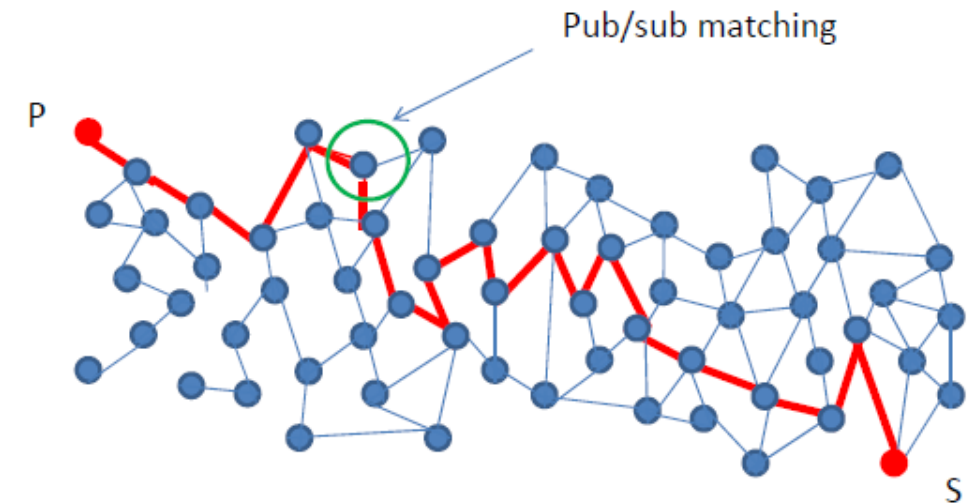
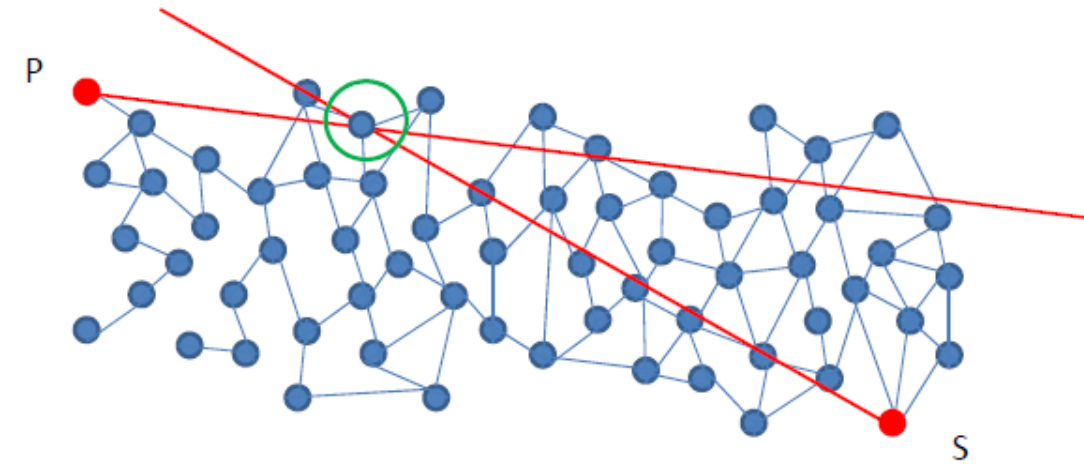
Evaluation

10-fold
Cross-validation

Weighted average over inverse distance						
Sensor:	Illuminance(lux)		Temperature($^{\circ}C$)		Humidity(%)	
Room	Average RMSE	Average MAPE	Average RMSE	Average MAPE	Average RMSE	Average MAPE
Office A	9.22 \pm 0.55	3.02 \pm 0.12%	0.33 \pm 0.01	1.07 \pm 0.02%	0.60 \pm 0.02	1.50 \pm 0.01%
Office B	44.4 \pm 3.21	6.58 \pm 0.20%	0.60 \pm 0.01	1.91 \pm 0.03%	1.17 \pm 0.10	2.61 \pm 0.05%
Weighted average over inverse distance squared						
Sensor:	Illuminance(lux)		Temperature($^{\circ}C$)		Humidity(%)	
Room	Average RMSE	Average MAPE	Average RMSE	Average MAPE	Average RMSE	Average MAPE
Office A	9.39 \pm 0.60	3.20 \pm 0.14%	0.30 \pm 0.01	0.98 \pm 0.01%	0.58 \pm 0.01	1.42 \pm 0.01%
Office B	43.69 \pm 3.41	6.57 \pm 0.19%	0.61 \pm 0.02	1.88 \pm 0.04%	1.18 \pm 0.10	2.62 \pm 0.06%

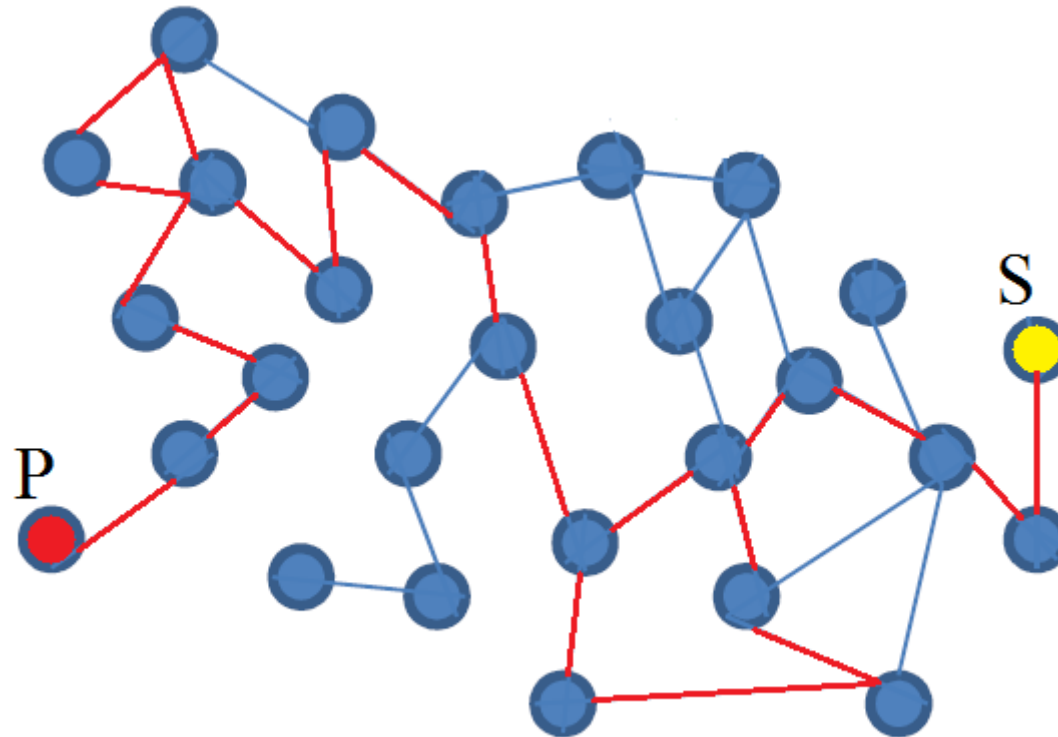
Efficient path dissemination

- Publish-Subscribe communication patterns
- No routing layer existence is assumed.
- Fully distributed solution



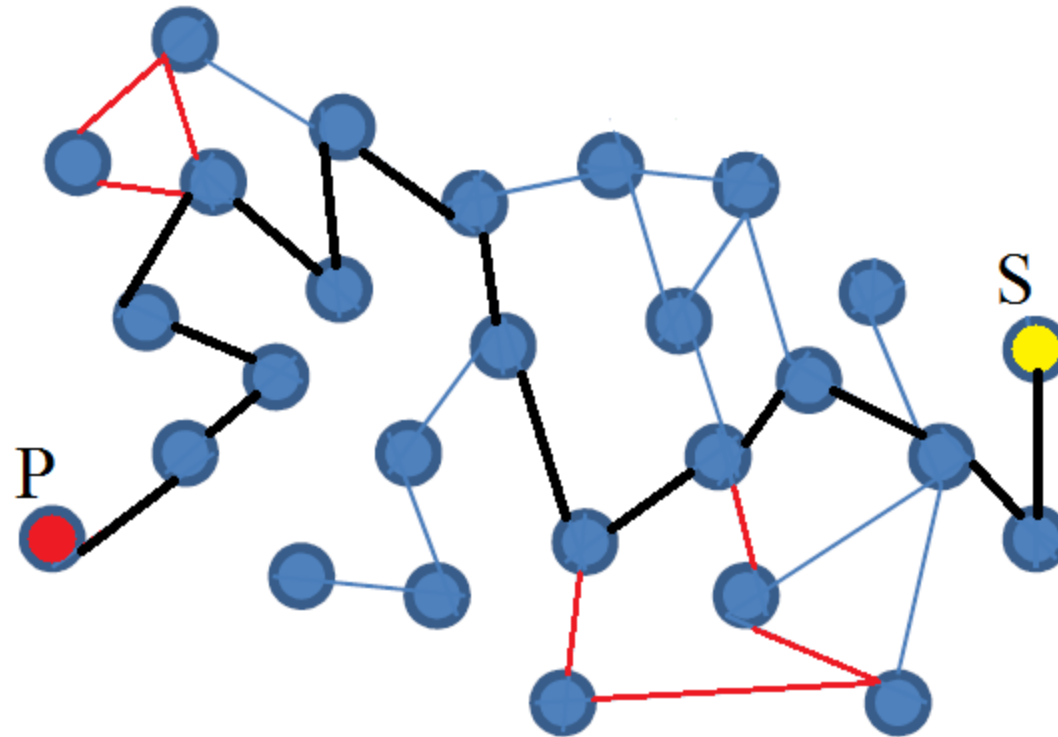
Efficient path dissemination

- A random walk (good at balancing the load)



Efficient path dissemination

- Loop-erased path



Efficient path dissemination

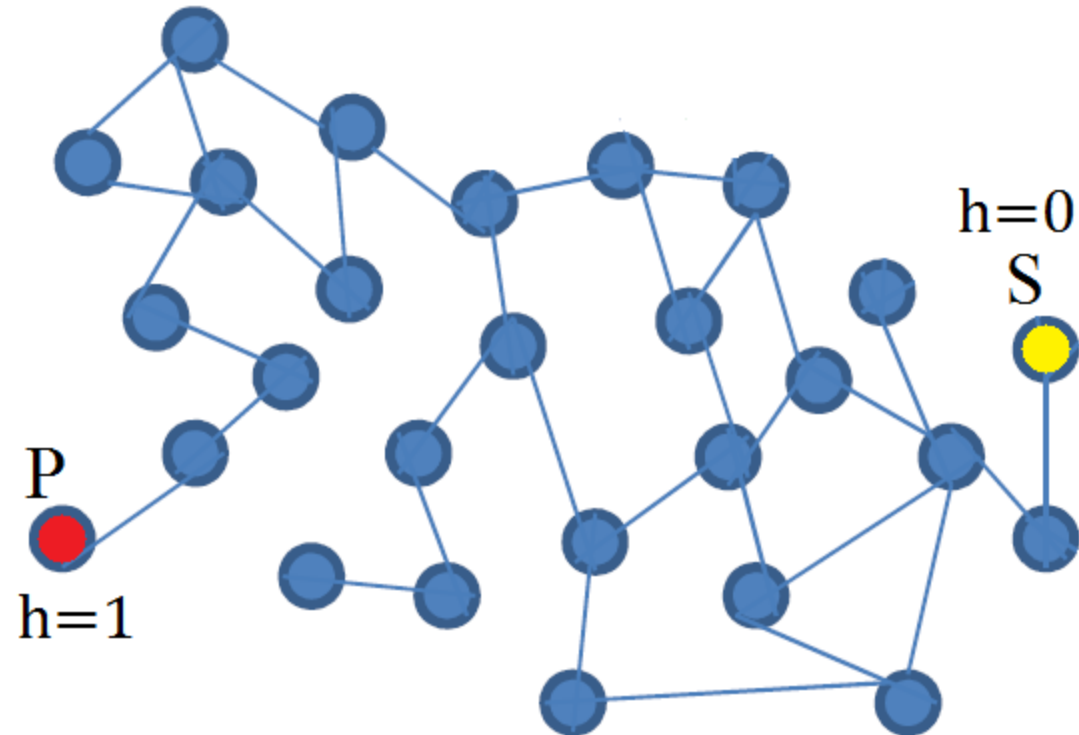
- The Laplacian Random walk

Harmonic function h :

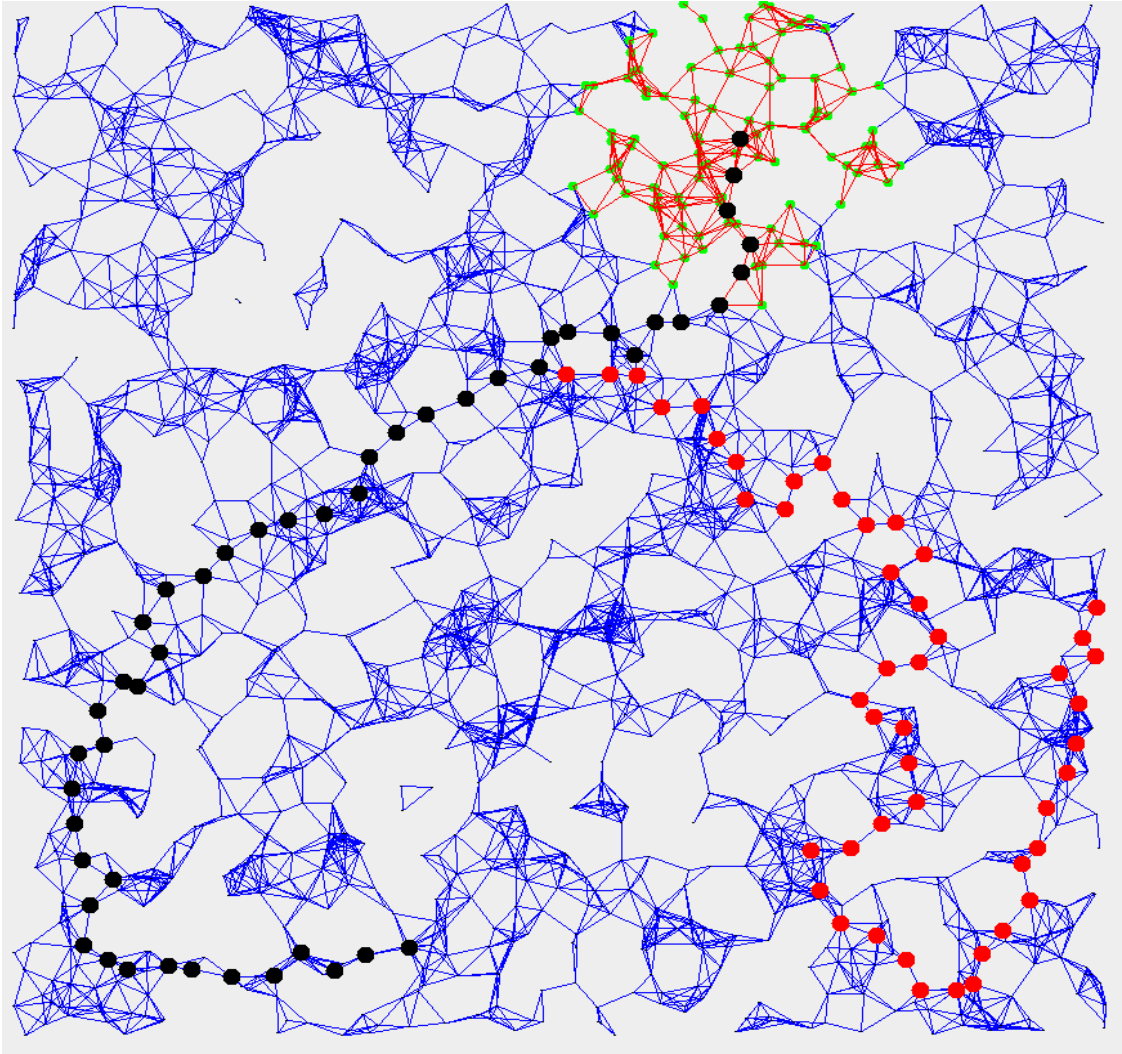
$$h(x_i) = \frac{\sum_{\text{neighbors}} h(x_j)}{\sum \text{neighbors}}$$

-choose min $h(x)$

-generates loop-erased path!



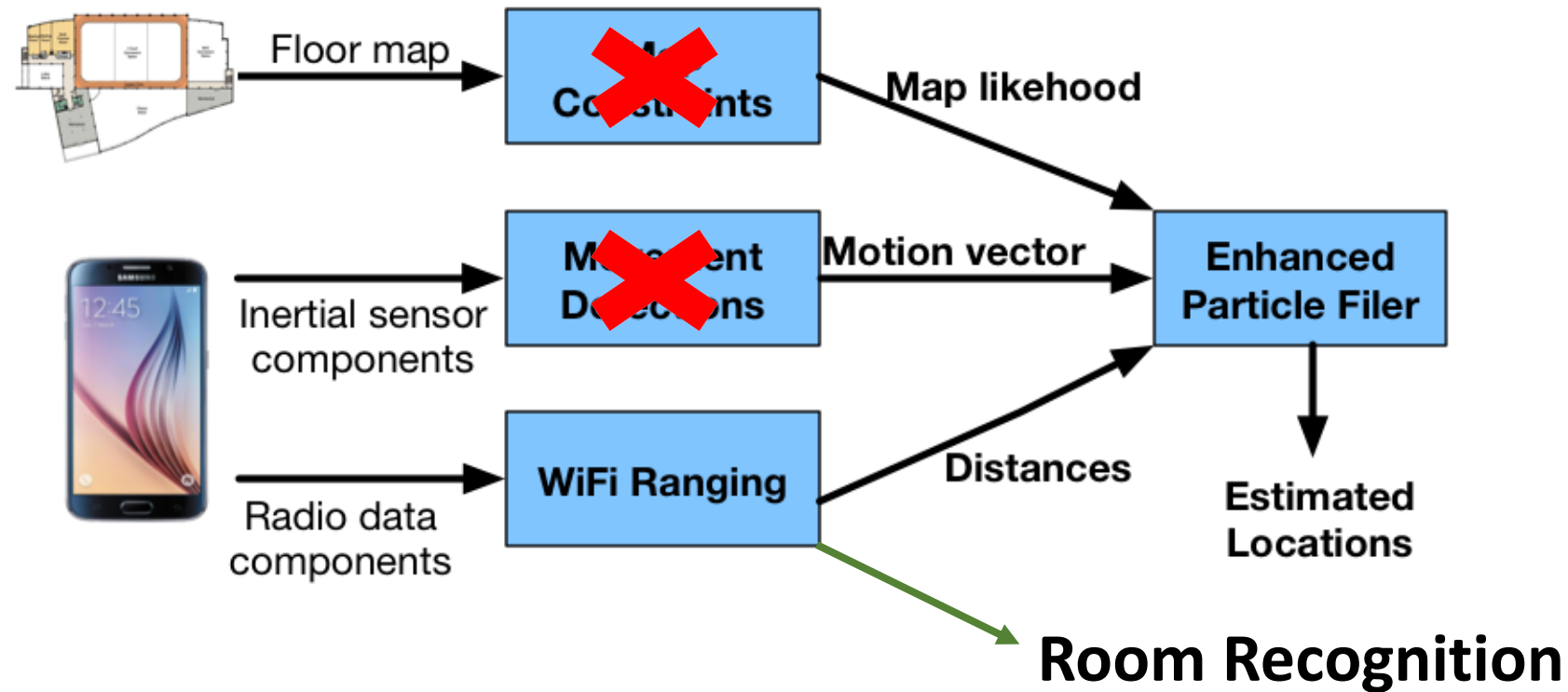
Simulation-Evaluation



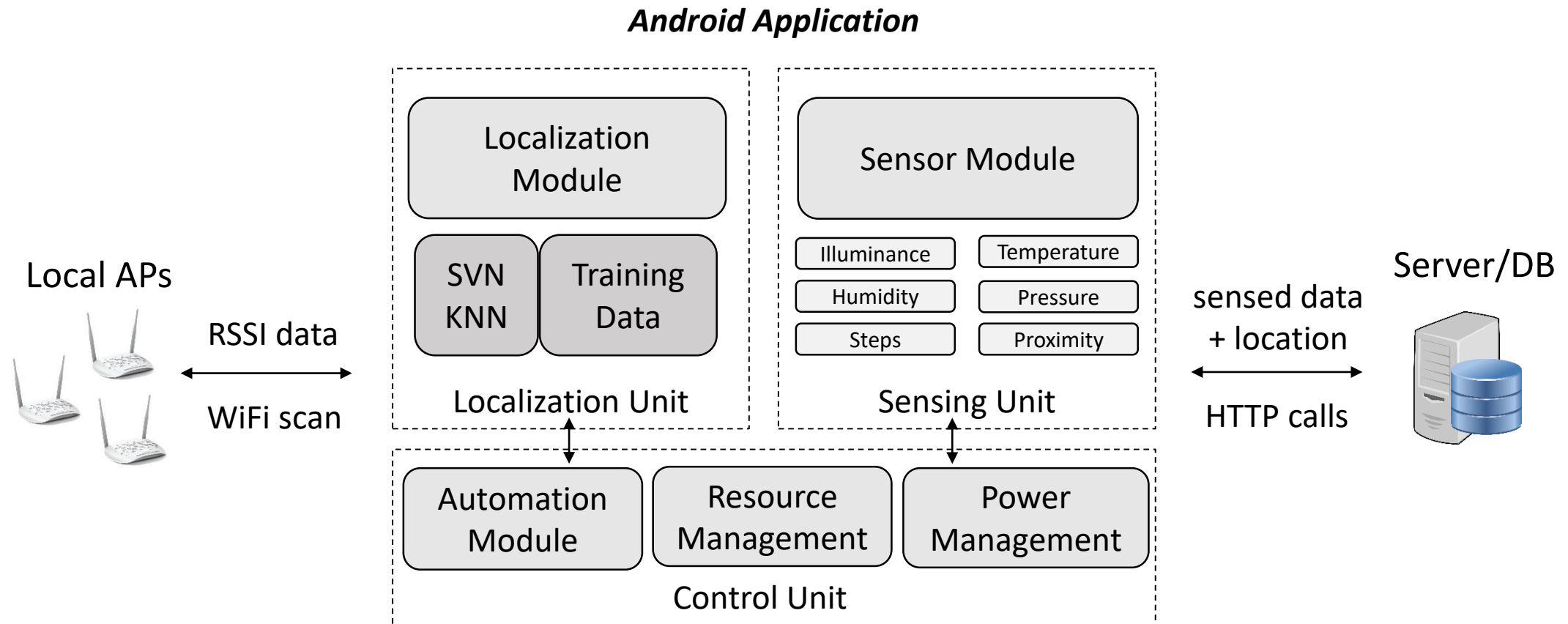
Key results:

- A minimal local knowledge of the network suffices. ($d = 3 \rightarrow 95\%$ success)
- Optimal local values are observed ($d = 3$, $St_b = 200$, $C_b = 200$).

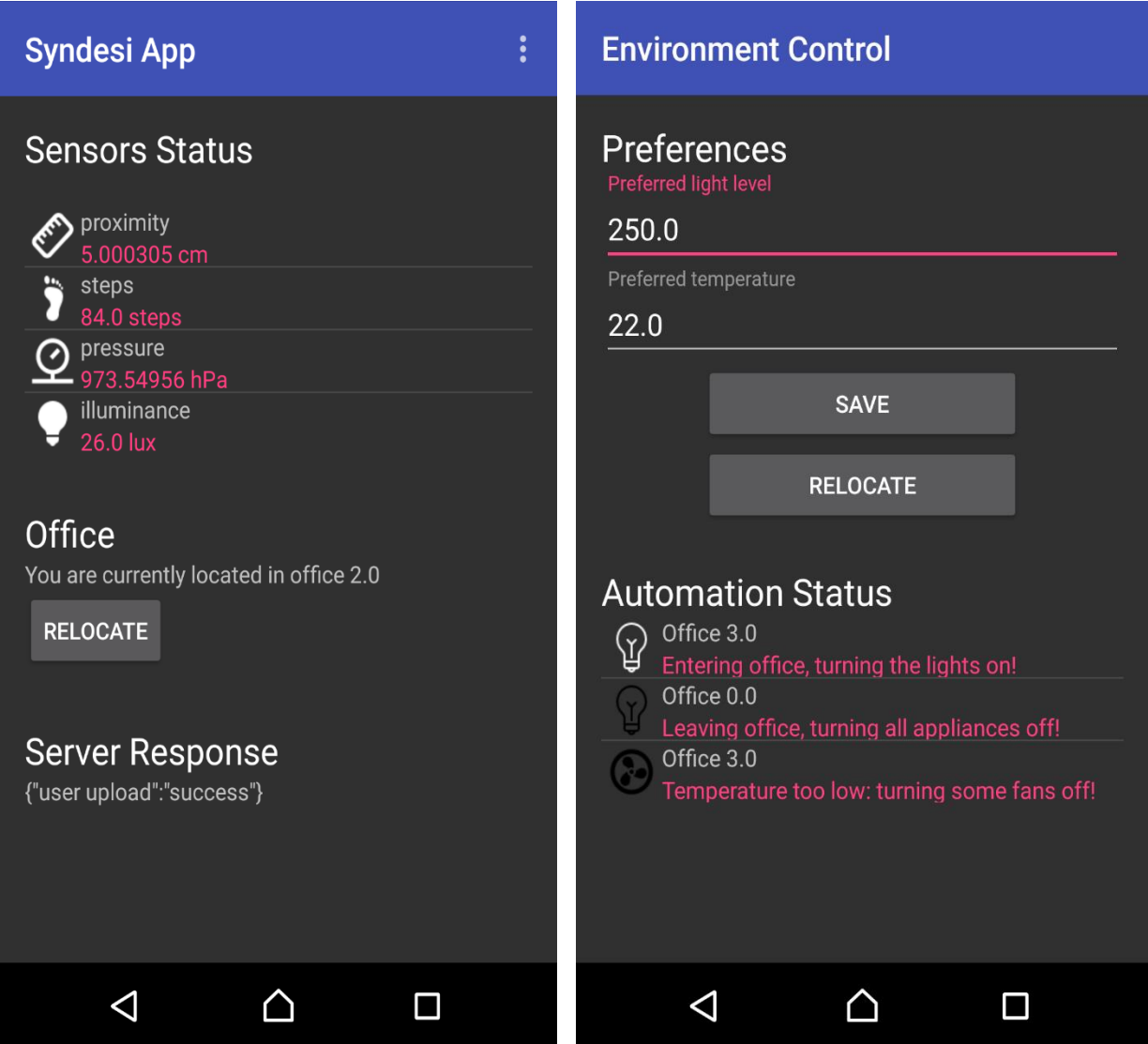
Office Automation – Indoor Location



Office Automation – Indoor Location



Office Automation

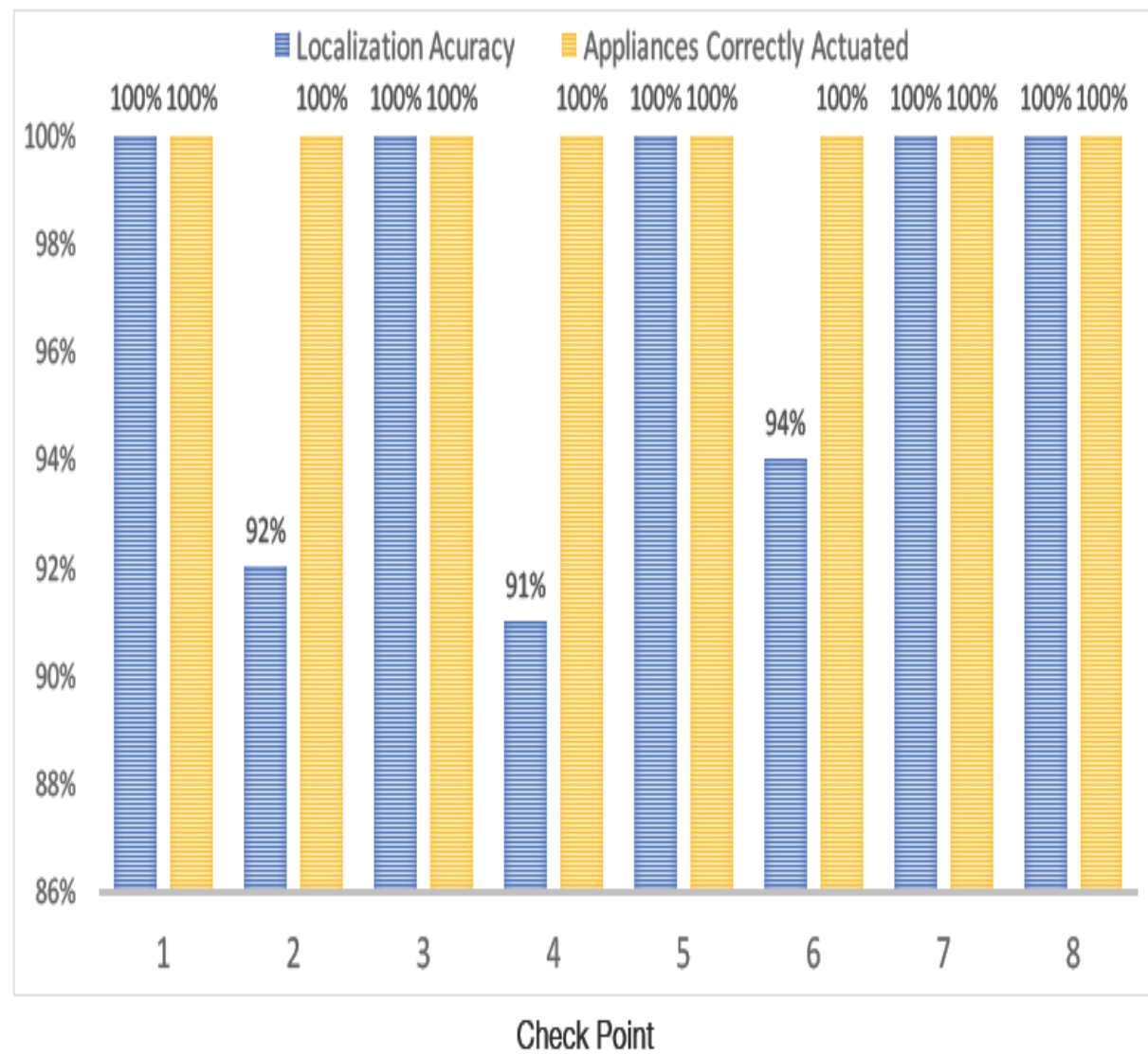
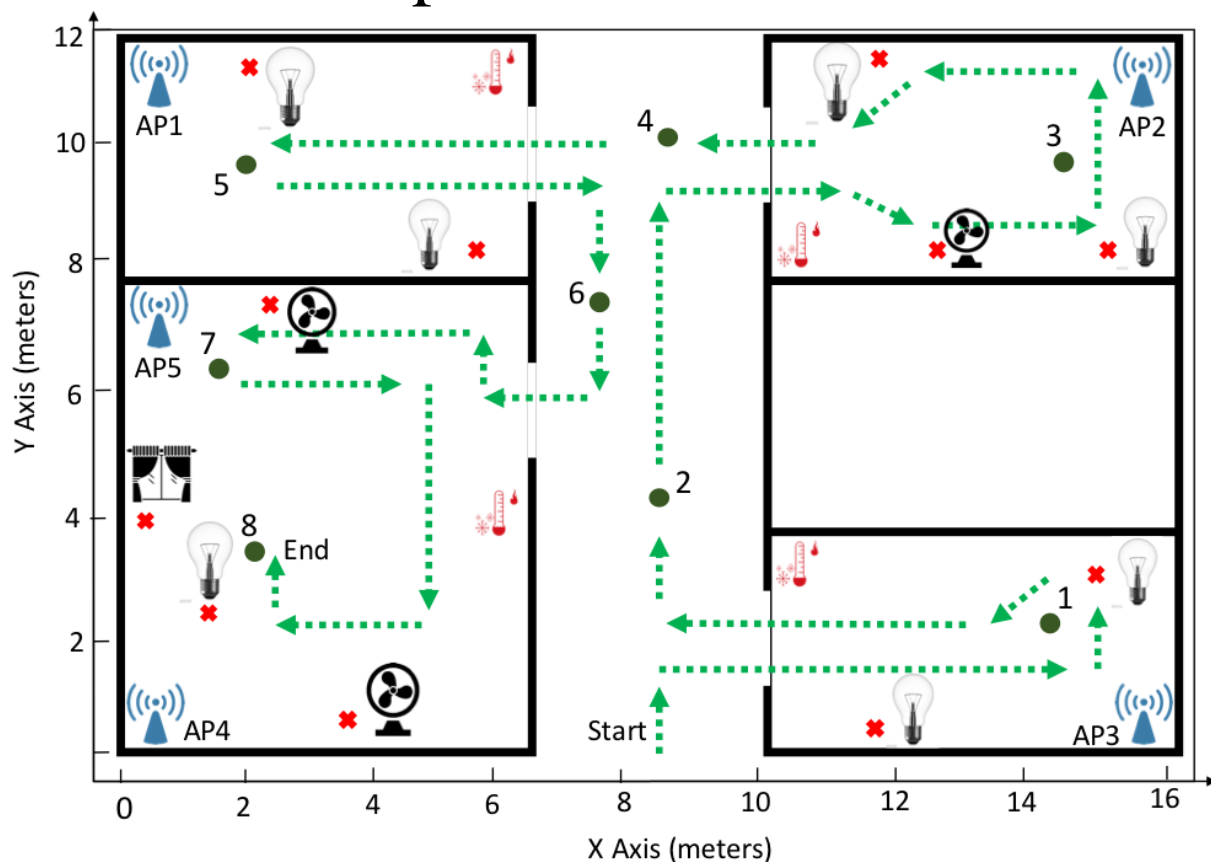


- ✕ Sensor
- ✕ Sensor-Actuator

Location-based automation

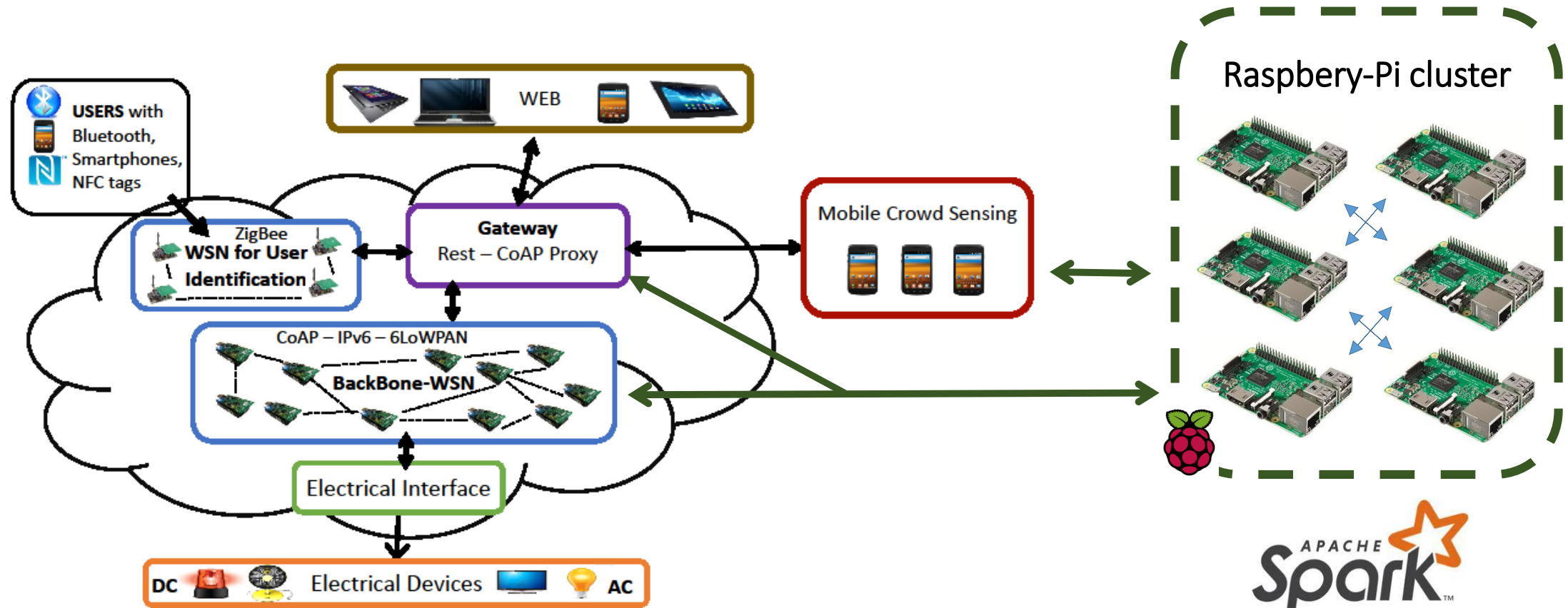
Evaluation

Experiment scenario



A distributed computing cluster on the edge

- Computationally demanding applications
- Low-latency demanding applications



Summary/Future work

- A WSN-based framework with diverse modules/utilities:
 - Environmental monitoring/crowdsensing
 - Location-based automation
 - Its modelled 3D-version with virtual resources of realistic values
- A distributed algorithm for bidirectional search in large scale networks

Future work:

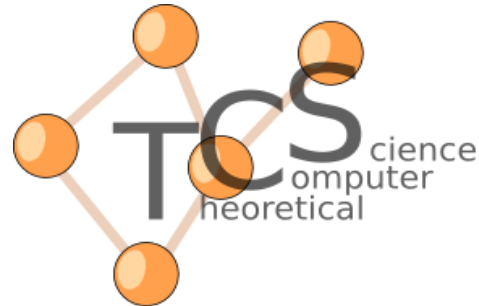
- Benchmark the Raspberry-Pi cluster
- Test it in some application!

Q&A



**UNIVERSITÉ
DE GENÈVE**

**CENTRE UNIVERSITAIRE
D'INFORMATIQUE**



Theoretical Computer Science & Sensor Lab