

# Set Family Decision Diagrams

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How to compute efficiently on sets ?

- ▶ represent sets in a compact way
- ▶ compute on a whole set instead on a single element
  - ▶ aka SIMD or *graphic card computing*
- ▶ respect union : set homomorphism

various approaches based on decision diagrams.

# Set Family Decision Diagrams

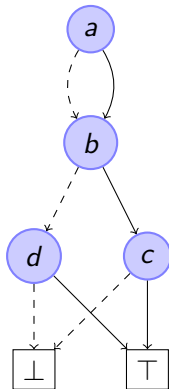
## Informal Definition

A SFDD is a **directed acyclic graph** where

- ▶ each node represent a term
- ▶ each node has two children, indicating whether or not the term is contained
- ▶ each path from the root to an accepting terminal represents a set of terms

# Set Family Decision Diagrams

## Example



Encodes the sets:

- ▶  $\{a, b, c\}$
- ▶  $\{a, d\}$
- ▶  $\{b, c\}$
- ▶  $\{d\}$

# Set Family Decision Diagrams

## Formal Definition

### Definition (Formal definition)

Let  $T$  be a set of terms. The set of SFDDs  $\mathbb{S}$  is inductively defined by:

- ▶  $\perp \in \mathbb{S}$  is the rejecting terminal
- ▶  $\top \in \mathbb{S}$  is the accepting terminal
- ▶  $\langle t, \tau, \sigma \rangle \in \mathbb{S}$  if and only if  $t \in T \wedge \tau, \sigma \in \mathbb{S}$

# Set Family Decision Diagrams

## Canonical Form

Let  $S \in \mathbb{S}$  be the SFDD  $\langle t, \tau, \sigma \rangle$ , we call  $\tau$  its **take** node and  $\sigma$  its **skip** node.

$S$  is **canonical** if for all its nodes, the skip node and take node represent greater terms or terminals, and no take node is the rejecting terminal.

# Set Family Decision Diagrams

## Canonical Form

### Definition (Canonical form)

Let  $T$  be a set of terms, and  $< \in T \times T$  a total ordering on  $T$ . A SFDD  $S \in \mathbb{S}$  is canonical if and only if

- ▶  $S$  is the rejecting terminal  $\perp$
- ▶  $S$  is the accepting terminal  $\top$
- ▶  $S = \langle t, \tau, \sigma \rangle$  where
  - ▶  $\tau = \langle t_\tau, \tau_\tau, \sigma_\tau \rangle \implies t < t_\tau$  and  $\tau \neq \perp$
  - ▶  $\sigma = \langle t_\sigma, \tau_\sigma, \sigma_\sigma \rangle \implies t < t_\sigma$
  - ▶  $\tau$  and  $\sigma$  are canonical

# Set Family Decision Diagrams

## Union

The union of two SFDDs is given by:

$$A \cup B = B \cup A$$

$$A \cup A = A$$

$$\perp \cup A = A$$

$$\top \cup \langle t, \tau, \sigma \rangle = \langle t, \top \cup \tau, \top \cup \sigma \rangle$$

$$\langle t, \tau, \sigma \rangle \cup \langle t', \tau', \sigma' \rangle = \begin{cases} \langle t, \tau, \sigma \cup \langle t', \tau', \sigma' \rangle \rangle & \text{if } t < t' \\ \langle t, \tau \cup \tau', \sigma \cup \sigma' \rangle & \text{if } t = t' \\ \langle t', \tau', \sigma' \cup \langle t, \tau, \sigma \rangle \rangle & \text{if } t > t' \end{cases}$$



# Set Family Decision Diagrams

## Intersection

The intersection of two SFDDs is given by:

$$A \cap B = B \cap A$$

$$A \cap A = A$$

$$\perp \cap A = \perp$$

$$\top \cap \langle t, \tau, \sigma \rangle = \top \cap \sigma$$

$$\langle t, \tau, \sigma \rangle \cap \langle t', \tau', \sigma' \rangle = \begin{cases} \sigma \cap \langle t', \tau', \sigma' \rangle & \text{if } t < t' \\ \langle t, \tau \cap \tau', \sigma \cap \sigma' \rangle & \text{if } t = t' \\ \langle t, \tau, \sigma \rangle \cap \sigma' & \text{if } t > t' \end{cases}$$

# Set Family Decision Diagrams

## Encoding

The encoding of a set into a SFDD is given by:

$$\text{enc}(\emptyset) = \perp$$

$$\text{enc}(\{\emptyset\}) = \top$$

$$\text{enc}(S \cup \{s\}) = \text{enc}(S) \cup \text{enc}(\{s\})$$

$$t < \min(s) \implies \text{enc}(\{s \cup \{t\}\}) = \langle t, \text{enc}(\{s\}), \perp \rangle$$

# Set Family Decision Diagrams

## Decoding

The decoding of one SFDD is given by:

$$\text{dec}(\perp) = \emptyset$$

$$\text{dec}(\top) = \{\emptyset\}$$

$$\text{dec}(\langle t, \tau, \sigma \rangle) = (\text{dec}(\tau) \oplus t) \cup \text{dec}(\sigma)$$

Where  $\oplus$  is defined as follows:

$$\bigcup_{s \in S} \{s\} \oplus t = \bigcup_{s \in S} \{s \cup \{t\}\}$$

# Set Family Decision Diagrams

## Correctness

The decoding/encoding of one set is the identity (and the reverse):

$$\forall S \subseteq \mathcal{P}(T), \text{dec}(\text{enc}(S)) = S$$

$$\forall S \in \mathbb{S}, \text{enc}(\text{dec}(S)) = S$$

# Set Family Decision Diagrams

## Homomorphisms

Homomorphisms are operations that preserve union:

$$\phi(S \cup S') = \phi(S) \cup \phi(S')$$

They also support operations that are themselves homomorphisms:

$$\forall S, (\phi_1 + \phi_2)(S) = \phi_1(S) \cup \phi_2(S)$$

$$\forall S, (\phi_1 \times \phi_2)(S) = \phi_1(S) \cap \phi_2(S)$$

$$\forall S, (\phi_1 \circ \phi_2)(S) = \phi_1(\phi_2(S))$$

# Set Family Decision Diagrams

## Insertion

$\oplus : \mathbb{S}, T \rightarrow \mathbb{S}$  inserts a term  $t \in T$  into all sets of a SFDD:

$$\perp \oplus a = \perp$$

$$\top \oplus a = \langle a, \top, \perp \rangle$$

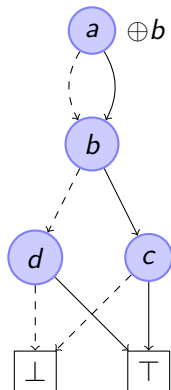
$$\langle t, \tau, \sigma \rangle \oplus a = \begin{cases} \langle t, \tau \oplus a, \sigma \oplus a \rangle & \text{if } t < a \\ \langle t, \tau \cup \sigma, \perp \rangle & \text{if } t = a \\ \langle a, \langle t, \tau, \sigma \rangle, \perp \rangle & \text{if } t > a \end{cases}$$

NB:  $\oplus$  is an homomorphism.

# Set Family Decision Diagrams

## Insertion

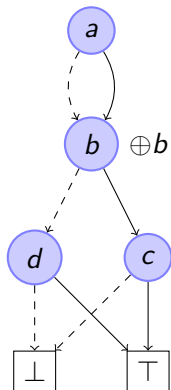
Example:  $\text{enc}(\{\{a, b, c\}, \{a, d\}, \{b, c\}, \{d\}\}) \oplus b$



# Set Family Decision Diagrams

## Insertion

Example:  $\text{enc}(\{\{a, b, c\}, \{a, d\}, \{b, c\}, \{d\}\}) \oplus b$

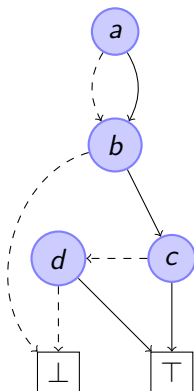




# Set Family Decision Diagrams

## Insertion

Example:  $\text{enc}(\{\{a, b, c\}, \{a, d\}, \{b, c\}, \{d\}\}) \oplus b$



Encodes the sets:

- ▶  $\{a, b, c\}$
- ▶  $\{a, b, d\}$
- ▶  $\{b, c\}$
- ▶  $\{b, d\}$

# Set Family Decision Diagrams

## Removal

$\ominus : \mathbb{S}, T \rightarrow \mathbb{S}$  removes a term  $t \in T$  from all sets that contain it:

$$\perp \ominus a = \perp$$

$$\top \ominus a = \top$$

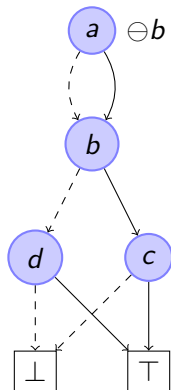
$$\langle t, \tau, \sigma \rangle \ominus a = \begin{cases} \langle t, \tau \ominus a, \sigma \ominus a \rangle & \text{if } t < a \\ \sigma \cup \tau & \text{if } t = a \\ \langle t, \tau, \sigma \rangle & \text{if } t > a \end{cases}$$

NB:  $\ominus$  is an homomorphism.

# Set Family Decision Diagrams

## Removal

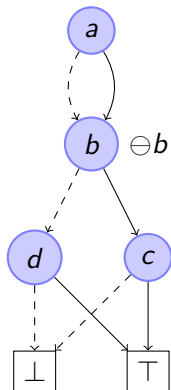
Example:  $\text{enc}(\{\{a, b, c\}, \{a, d\}, \{b, c\}, \{d\}\}) \ominus b$



# Set Family Decision Diagrams

## Removal

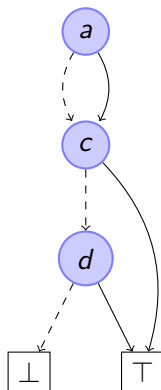
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# Set Family Decision Diagrams

## Removal

Example:  $\text{enc}(\{\{a, b, c\}, \{a, d\}, \{b, c\}, \{d\}\}) \ominus b$



Encodes the sets:

- ▶  $\{a, c\}$
- ▶  $\{a, d\}$
- ▶  $\{c\}$
- ▶  $\{d\}$

# Set Family Decision Diagrams

## Filtering

$\text{filter} : \mathbb{S}, T \rightarrow \mathbb{S}$  filters out the sets that don't contain a term  $t \in T$ :

$$\text{filter}(\perp, a) = \perp$$

$$\text{filter}(\top, a) = \perp$$

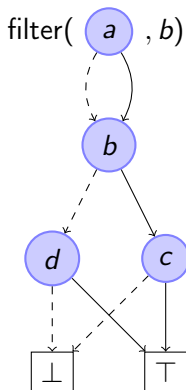
$$\text{filter}(\langle t, \tau, \sigma \rangle, a) = \begin{cases} \langle t, \text{filter}(\tau, a), \text{filter}(\sigma, a) \rangle & \text{if } t < a \\ \langle t, \tau, \perp \rangle & \text{if } t = a \\ \perp & \text{if } t > a \end{cases}$$

NB1: filter is an homomorphism.

# Set Family Decision Diagrams

## Filtering

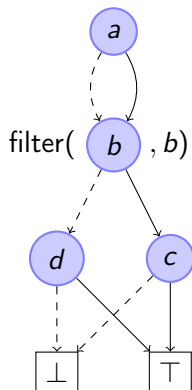
Example:  $\text{filter}(\text{enc}(\{\{a, b, c\}, \{a, d\}, \{b, c\}, \{d\}\}), b)$



# Set Family Decision Diagrams

## Filtering

Example:  $\text{filter}(\text{enc}(\{\{a, b, c\}, \{a, d\}, \{b, c\}, \{d\}\}), b)$

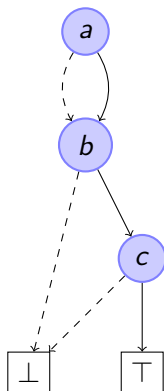




# Set Family Decision Diagrams

## Filtering

Example:  $\text{filter}(\text{enc}(\{\{a, b, c\}, \{a, d\}, \{b, c\}, \{d\}\}), b)$



Encodes the sets:

- ▶  $\{a, b, c\}$
- ▶  $\{b, c\}$

# Set Family Decision Diagrams

## Inductive Homomorphisms

An inductive homomorphism is a tuple  $\phi = \langle S, i \rangle$  where:

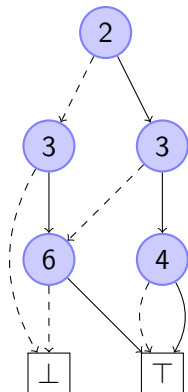
- ▶  $S \in \mathbb{S}$
- ▶  $i(A) = \langle \phi_\tau, \phi_\sigma \rangle$  where  $\phi_\tau, \phi_\sigma$  are homomorphisms and  $A \in \mathbb{S} \setminus \{\perp, \top\}$

Let  $\phi = \langle S, i \rangle$ , its application on  $A \in \mathbb{S}$  is given by:

$$\phi(A) = \begin{cases} \perp & \text{if } A = \perp \\ S & \text{if } A = \top \\ \langle t, \phi_\tau(\tau), \phi_\sigma(\sigma) \rangle & \text{if } A = \langle t, \tau, \sigma \rangle, i(A) = \langle \phi_\tau, \phi_\sigma \rangle \end{cases}$$

# Set Family Decision Diagrams

## Inductive Homomorphisms



Example: removing values smaller than of 4

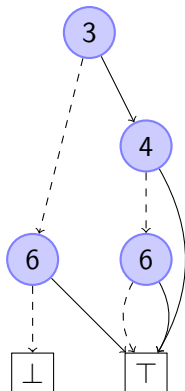
$$\phi = \langle \top, i \rangle$$

$$i(\langle t, \tau, \sigma \rangle) = \begin{cases} \langle h[\perp], \phi \circ (h[\tau] + \text{id}) \rangle & \text{if } t < 4 \\ \langle \text{id}, \text{id} \rangle & \text{otherwise} \end{cases}$$

where  $\forall S, \text{id}(S) = S$  and  $\forall S, h[K](S) = K$ .

# Set Family Decision Diagrams

## Inductive Homomorphisms



Example: removing values smaller than of 4

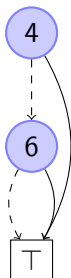
$$\phi = \langle \top, i \rangle$$

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# Set Family Decision Diagrams

## Inductive Homomorphisms



Example: removing values smaller than of 4

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where  $\forall S, \text{id}(S) = S$  and  $\forall S, h[K](S) = K$ .

# Set Family Decision Diagrams

## Global Computation on SFDDs

The count of members in a family is the homomorphism `size`:

$$\text{size}(S) = \begin{cases} 0 & \text{if } S = \perp \\ 1 & \text{if } S = \top \\ \text{size}(\tau) + \text{size}(\sigma) & \text{if } S = \langle t, \tau, \sigma \rangle \end{cases}$$

NB1: `size` is an homomorphism.

# Set Family Decision Diagrams

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## Algorithm 1: State space computation on individual states

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**Input:**  $s_0$  : initial state.

**Input:**  $T$  : set of transition.

**Result:** set of reachable states

**begin**

$s_{rem}, s$  : set of states ;

$m, mt$  : states ;

$s_{rem} \leftarrow \{s_0\}$  ;  $s \leftarrow \{\}$  ;

**repeat**

$m \leftarrow \text{choose}(s)$  ;

$s_{rem} \leftarrow s_{rem} / \{m\}$  ;

**foreach**  $t \in T$  **do**

**if**  $\text{fireable}(t, m)$  **then**

$mt \leftarrow t(m)$  ;

**if**  $m \notin s$  **then**  $s \leftarrow s \cup \{mt\}$  ;  $s_{rem} \leftarrow s_{rem} \cup \{mt\}$  ;

**until**  $s_{rem} = \emptyset$  ;

**return**  $s$  ;

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# Set Family Decision Diagrams

## Global computation of state space

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### Algorithm 2: Global state space computation

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**Input:**  $s_0$  : initial state.

**Input:**  $\Phi$  : set of transition homomorphisms.

**Result:** set of reachable states

**begin**

$s, s_{old}, temp$  : set of states ;

$s \leftarrow \{s_0\}$  ;

**repeat**

$s_{old} \leftarrow s$  ;

**foreach**  $t \in \Phi$  **do**

$temp \leftarrow t(s)$  ;

$s \leftarrow s \cup temp$  ;

**until**  $s = s_{old}$ ;

**return**  $s$ ;

---



# Set Family Decision Diagrams

Global computation of state space

What about  $t(s)$ ?

$$t(m) = m + post(t) - pre(t)$$

If  $pre$  and  $post$  are functions on transition and markings.

$$t(m) = post(t, pre(t, m))$$

Extended to set of states:

$$t(s \cup \{m\}) = t(t(s) \cup \{post(t, pre(t, m))\})$$

$$t(\emptyset) = \emptyset$$

# Set Family Decision Diagrams

## Petri nets

Petri nets are defined as  $\langle P, T, Pre, Post \rangle$  where:

- ▶  $P$  and  $T$  are finite disjoint sets.
- ▶  $Pre$  and  $Post$  are functions  $P \times T \rightarrow \mathbb{N}$

The state of a Petri net is the **marking**  $M : P \rightarrow \mathbb{N}$ .

A transition  $t \in T$  is **fireable** if and only if

$$\forall p \in P, Pre(p, t) \leq M(p)$$

The firing of a transition modifies the marking (i.e. state):

$$\forall p \in P, M'(p) = M(p) + Post(p, t) - Pre(p, t)$$

# Set Family Decision Diagrams

## Encoding safe PN marking in sets

Encoding a safe Petri net marking  $M$  with  $S_M$  can be done with sets using simply  $P$  as terms:

$$S_M = \bigcup_{p \in P, M(p)=1} \{p\}$$

which is encoded directly in SFDD as:  $enc(\bigcup_{p \in P, M(p)=1} \{p\})$  with the total order  $P = \{p_1, p_2, \dots, p_k\}$  and  $p_1 < p_2 < \dots < p_k$

# Set Family Decision Diagrams

Encoding safe PN pre and post conditions

$$t = post(t) \circ pre(t)$$

$$pre(t) = pre(t, p_1) \circ pre(t, p_2) \circ \cdots \circ pre(t, p_n)$$

$$post(t) = post(t, p_1) \circ post(t, p_2) \circ \cdots \circ post(t, p_1)$$

$$pre(t, p_i) = \begin{cases} \ominus(p_i) \circ \text{filter}(p_i) & \text{if } Pre(t, p_i) \neq 0 \\ (id) & \text{otherwise} \end{cases}$$

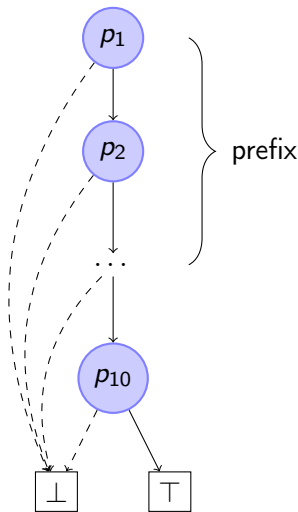
$$post(t, p_i) = \begin{cases} \oplus(p_i) & \text{if } Post(t, p_i) \neq 0 \\ (id) & \text{otherwise} \end{cases}$$

# Set Family Decision Diagrams

## Optimizations

Homomorphisms may involve unnecessary operations on large prefixes:

$$\text{filter}(p_{10})(\text{enc}(\bigcup_{1 \leq i \leq 10} p_i))$$



# Set Family Decision Diagrams

## Optimizations

The idea is to **dive** as deep as possible before applying an homomorphism:

$$\text{dive}(k, \phi)(\perp) = \perp$$

$$\text{dive}(k, \phi)(\top) = \top$$

$$\text{dive}(k, \phi)(\langle t, \tau, \sigma \rangle) = \begin{cases} \langle t, \text{dive}(k, \phi)(\tau), \text{dive}(k, \phi)(\sigma) \rangle & \text{if } t < k \\ \phi(\langle t, \tau, \sigma \rangle) & \text{if } t = k \\ \langle t, \tau, \sigma \rangle & \text{if } t > k \end{cases}$$

# Set Family Decision Diagrams

## Optimizations

Grouping homomorphisms that work on close variables can avoid processing long prefixes multiple times:

$$\text{filter}(p_8) \circ \text{filter}(p_{10}) \equiv \text{dive}(p_8, \text{filter}(p_8) \circ \text{filter}(p_{10}))$$

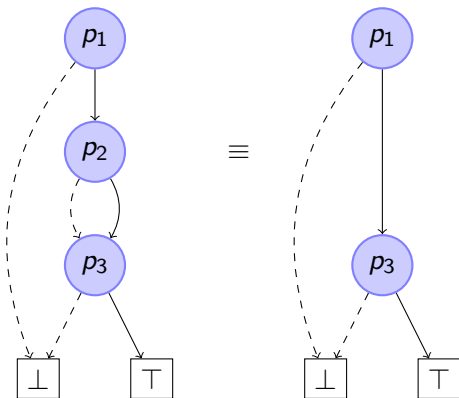
Some homomorphism may be reordered so they can be grouped:

$$\text{filter}(p_i) \circ \text{filter}(p_j) \equiv \text{filter}(p_j) \circ \text{filter}(p_i)$$

# Set Family Decision Diagrams

## Optimizations

If set of terms is sparse and has a minimum value  $t \in T$  such that  $\forall u \in T, t \neq u \implies t < u$ , some nodes can be omitted:





# Set Family Decision Diagrams

## Conclusion

- ▶ SFDD encoding of sets
- ▶ SFDD properties such as canonization
- ▶ Homomorphic operations on SFDD
- ▶ Inductive homomorphisms as pattern of computation
- ▶ Encoding of markings and set of markings
- ▶ Encoding of fire functions
- ▶ Computation of PN state space
- ▶ *don't care* can be defined for particular constraint on  $T$