

# PGM-Assignment #4

1. The differences between Bayesian Networks (BNs, denoted by  $G$ ) and Markov Networks (MNs, denoted by  $H$ ):

(a) Please prove that no MN can PERFECTLY\* represent a v-structure in BN;

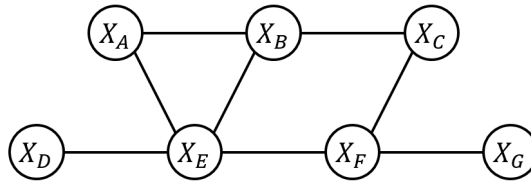
(b) Please prove that no BN can PERFECTLY represent a polygon (use quadrangle\*\* as the example) in MN;

**Hint:**

\* : PERFECTLY: refer to Perfect-Map:  $I(H) = I(G)$

\*\* : quadrangle: 四边形

2. For a Markov network as below (all the variables are 0/1 binary):



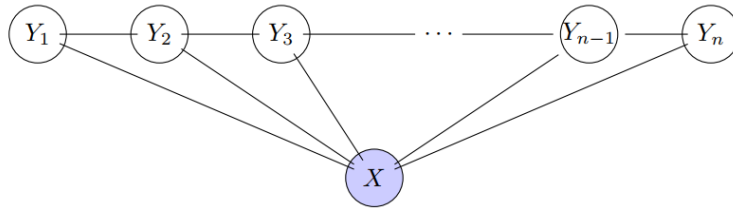
**Q:** Please write down the Gibbs distribution of this MN in **log-linear format** based on the constructive solution by Julian Beseg (1974).

(**Hint:** for each term, the coefficient has different values for the different configurations of the associated variables.)

3. In a simplified linear-chain like Markov network as below, all the variables are 0-1 binary

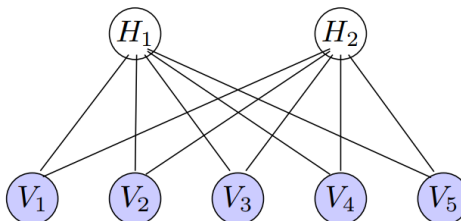
(1) Please write down its Gibbs distribution.

(2) If all  $X$  is always observed, please write down its conditional distribution (see the hint below).



**Hints for above conditional models:** because  $X$  is always observed, you do not need to model the marginal distribution over  $X$ .

4. An RBM (Restricted Boltzmann Machine) is a bipartite Markov network consisting of a visible (observed) layer and a hidden layer, where each node is a **binary** random variable. Consider the following RBM:



The joint distribution of a configuration is given by:

$$P(\mathbf{H} = \mathbf{h}, \mathbf{V} = \mathbf{v}) = \frac{1}{Z} e^{-E(\mathbf{h}, \mathbf{v})}, \quad \mathbf{h} = (h_1, h_2)^T, \quad \mathbf{v} = (v_1, \dots, v_5)^T$$

And:

$$E(\mathbf{h}, \mathbf{v}) = -\sum_{i=1}^2 a_i h_i - \sum_{j=1}^5 b_j v_j - \sum_{ij} w_{ij} h_i v_j$$

- (1) Using the above joint distribution form, **show that  $p(\mathbf{H}|\mathbf{V})$  could be factorized as:**

$$p(\mathbf{H}|\mathbf{V}) = \prod_{i=1}^2 p(H_i|\mathbf{V})$$

**And also:**

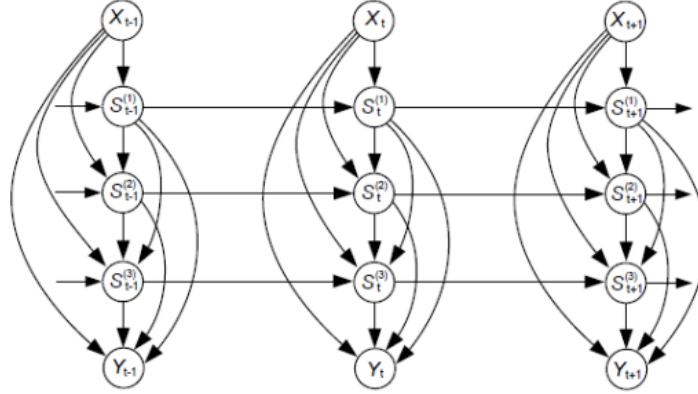
$$p(\mathbf{V}|\mathbf{H}) = \prod_{j=1}^5 p(V_j|\mathbf{H})$$

- (2) Can the marginal distribution over the hidden variables  $p(\mathbf{H})$  be factorized? Please give your reason according to the graph.

(Optional) Try derive  $p(\mathbf{H})$  to confirm your judgement.

- (3) (Optimal) Now let  $\mathbf{V}$  denotes the evaluations of users on some songs.  $V_j = 1/0$  means the user likes/dislikes this song. Suppose  $V_1$ : Hero(Mariah Carey song),  $V_2$ : Perfect(Ed Sheeran song),  $V_3$ : IDOL(BTS song),  $V_4$ : Horner: For The Love Of A Princess,  $V_5$ : Kung Fu Piano: Cello Ascends. After training, suppose  $H_1 = 1$  corresponds to the pop music, and  $H_2 = 1$  corresponds to the classical music. **Which  $w_{ij}$  do you expect to be positive?**

5. Consider a tree-structured HMM (simply treat it as a Bayesian network with a variable index for time!):



- (1) Please write down the factorization of the joint distribution  $P$  according to the figure.
- (2) (Optional) Suppose all variables are discrete random variables.  $|val(S)| = k, |val(X)| = r, |val(Y)| = l$ . (The number of possible values of all  $S$  is  $k$ , all  $X$  is  $r$ , and all  $Y$  is  $l$ .) This model could be parameterized by:
- a) Initial probability vector  $\mathbf{v} \in \mathbb{R}^r$ :  $\mathbf{v}_x = P(X = x)$
- b) State-state transmission tensor  $\mathbf{T}^{(1)} \in \mathbb{R}^{r \times k \times k}$ ,  $\mathbf{T}^{(2)} \in \mathbb{R}^{r \times k \times k \times k}$ ,  $\mathbf{T}^{(3)} \in \mathbb{R}^{r \times k \times k \times k \times k}$ :

$$\begin{aligned} \mathbf{T}_{x, i_1, i}^{(1)} &= P(S_t^{(1)} = i | X_t = x, S_{t-1}^{(1)} = i_1) \\ \mathbf{T}_{x, i_1, i_2, i}^{(2)} &= P(S_t^{(2)} = i | X_t = x, S_t^{(1)} = i_1, S_{t-1}^{(2)} = i_2) \\ \mathbf{T}_{x, i_1, i_2, i_3, i}^{(3)} &= P(S_t^{(3)} = i | X_t = x, S_t^{(1)} = i_1, S_t^{(2)} = i_2, S_{t-1}^{(3)} = i_3) \end{aligned}$$

c) State-observation emission tensor  $\mathbf{O} \in \mathbb{R}^{r \times k \times k \times k \times l}$ :  $\mathbf{O}_{x,i_1,i_2,i_3,y} = P(Y = y | X = x, S^{(m)} = i_m, m = 1, 2, 3)$

Q: Please derive the form of  $p(S_t^{(2)} | S^{(1)}, S_{-t}^{(2)}, S^{(3)}, X, Y)$  in terms of above parameters, where:

$$S^{(i)} = (\dots, S_{t-1}^{(i)}, S_t^{(i)}, S_{t+1}^{(i)}, \dots), i = 1, 3$$

$$S_{-t}^{(2)} = (\dots, S_{t-1}^{(2)}, S_{t+1}^{(2)}, \dots)$$

$$X = (\dots, X_{t-1}, X_t, X_{t+1}, \dots)$$

$$Y = (\dots, Y_{t-1}, Y_t, Y_{t+1}, \dots)$$