

崔屿杰

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教育背景

同济大学 自动化本科	2021 年 9 月-2026 年 6 月 (预计)
◦ GPA: 89.43, 综合排名: 1/68 , 雅思: 7.0	
◦ 技能: 嵌入式开发, ROS, SLAM, PyTorch, 点云处理, CV, python/C++	

荣誉奖励

全国特等奖: 第十八届“挑战杯”全国大学生课外学术科技作品“黑科技”专项赛 (第一作者)	2023 年 10 月
全国银奖: 中国国际大学生创新创业大赛 (2024) (第二作者)	2024 年 10 月
我最喜爱的项目 (20/250): 第十七届全国大学生创新年会 (第一作者)	2024 年 11 月
全国二等奖: 第七届全国大学生嵌入式芯片与系统设计竞赛	2024 年 8 月
全国一等奖: 2025 中国机器人大赛暨 RoboCup 机器人世界杯中国赛	2025 年 5 月
启迪奖学金 (电信学院最高荣誉), 同济大学一等奖奖学金, 优秀学生, 京川艺术奖学金	

项目经历

三指灵巧手通用操作学习框架	AIR/DISCOVER, 清华大学
◦ 设计同构三指灵巧手外骨骼与真机, 实现无需遥操的便携数据采集与训练框架。完成外骨骼采集设备的嵌入式开发设计, ORB3-SLAM 的 VIO 手腕定位以及从外骨骼到真机的 ACT 模仿学习框架, 同时搭建了 Mujoco 同构仿真平台, 满足外骨骼设备对虚拟灵巧手的运动迁移。	2025 年 1 月 - 至今
Dero——桥梁箱梁内部病害检测机器人 (DERO)	矩尺土木, 同济大学
◦ 技术: 使用 STM32 与树莓派完成了桥梁箱梁内部检测机器人全栈开发, 涵盖了建图、定位、数据采集、病害识别、网页展示与云台控制 APP 的开发, 并进行了实桥实验。针对箱梁内部建图问题, 设计退化环境检测算法, 自适应调节 Cartographer 算法点云匹配环节参数。 发表一篇桥梁领域顶会文章, 授权两项专利。	2022 年 4 月-2024 年 4 月
◦ 商业: 进行成果转化与商业实践, 包括市场调研、竞品分析、商业模式设计、产品路演与宣传以及意向投资与订单争取。 三大创新创业竞赛国奖。	
基于自监督的 2D 激光点云权重预测 (已被 IROS 2025 接收) LSW-Net	RAIL, 同济大学
◦ 设计了一种基于自监督学习的二维点云重要性感知网络, 使用融合对比损失提取点云权重, 提升了 ICP, CSM 等点云匹配算法的精度。	2024 年 9 月-2025 年 3 月
◦ 提出了一种使用类 U-Net 结构与重建损失, 联合时空编码的通用二维点云编码器, 可有效挖掘二维点云特征。	
智缘心声——基于 STM32H7 的失语症患者辅助设备 (STM32H7 Aphasia Helper)	同济大学
◦ 人机交互: 基于 STM32H7 的失语症患者辅助设备, 采用姿态传感选控 + 红外触控确认 + 多模态反馈的病患友好型交互方式。 获得嵌入式芯片与系统设计国赛二等奖。	2024 年 3 月-2024 年 7 月
◦ 边缘 AI: 使用 X-CUBE-AI 将图像识别模型 MCUNet 量化压缩, 并部署到 STM32H7, 实现了在内存 (1MB) 以及 Flash(2MB) 受限的微控制器上进行 ImageNet 类别的实时推理。	

文章发表

- Haojie Dai*, **Yujie Cui***, Bowen Shi, Mazeyu Ji, Chengju Liu, Qijun Chen “LSW-Net: A Spatio-temporal Self-Supervised Framework for 2D LiDAR-Based Environment Perception”, IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), 2025.
- Yujie Cui**, Yue Pan, Dalei Wang, Mazeyu Ji, Sugong Cao “A smart robotic system for autonomous inspection of large-scale concrete girder,” International Association for Bridge Maintenance And Safety(IABMAS), 2024.

Education

Tongji University *B.E in Automation*

Sep. 2021 – Jun. 2026(expected)

- GPA: 89.43, **overall rank: 1/68**, IELTS: 7.0
- Skills: Embedded Development, ROS, SLAM, PyTorch, Point Cloud Processing, Computer Vision, Python/C++

Selected Honors and Awards

National Grand Prize in Challenge Cup National College Student Curricular Academic Science and Technology Works Competition - Black Technology Track (First Author)	<i>Oct. 2023</i>
National Silver Award in China International College Students' Innovation Competition 2024(Second Author)	<i>Oct. 2024</i>
Most Popular Project (20/250) in National College Student Innovation Annual Conference 2024(First Author)	<i>Nov. 2024</i>
National Second Prize in National College Student Embedded System Design Competition	<i>Aug. 2024</i>
National First Prize in 2025 China Robotics Competition and RoboCup China Open	<i>May. 2025</i>
Qidi Scholarship (the highest honor of the School of EE), Tongji University First-Class Scholarship, Excellent Student, Jingchuan Art Scholarship	

Project Experience

Three-Fingered Dexterous Hand Universal Manipulation Interface	<i>AIR/DISCOVER, Tsinghua University Jan. 2024 - Current</i>
<ul style="list-style-type: none"> ◦ Designed a homomorphic three-finger exoskeleton and real robotic hand, enabling portable data collection and training without teleoperation. Developed embedded systems, ORB3-SLAM-based wrist VIO, ACT imitation learning from exoskeleton to robot, and a Mujoco simulation for motion transfer. 	
Dero—Bridge Box Girder Internal Detection Robot(DERO 🔗)	<i>Juchi Civil Engineer, Tongji University Apr. 2022 – Apr. 2024</i>
<ul style="list-style-type: none"> ◦ Technology: Developed a full-stack bridge box girder internal detection robot using STM32 and Raspberry Pi, including mapping, localization, data collection, defect detection, web display, and gimbal control, with real-bridge testing. A degradation environment detection algorithm was designed to adjust point cloud matching parameters in the Cartographer algorithm for internal mapping. Published a top-tier conference paper in the field of bridge engineering and granted two patents. ◦ Business: Handled business practice, including market research, competitor analysis, business model design, product roadshows, and securing investments and orders. Three National Innovation and Entrepreneurship Competition Awards. 	
Self-Supervised Laser Scan Weight Prediction(Accepted to IROS 2025)LSW-Net 🔗	<i>RAIL, Tongji University Sep. 2024 – Mar. 2025</i>
<ul style="list-style-type: none"> ◦ Designed a self-supervised learning-based 2D point cloud importance perception network, using fused contrastive loss to extract point cloud weights, which improved the accuracy of point cloud matching algorithms such as ICP and CSM. ◦ Proposed a universal 2D point cloud encoder using a U-Net-like structure with reconstruction loss and spatiotemporal encoding to effectively extract features. 	
STM32H7 based Aphasia Helper(STM32H7 Aphasia Helper 🔗)	<i>Tongji University Mar. 2024 – Jul. 2024</i>
<ul style="list-style-type: none"> ◦ Human-Computer Interaction: Developed an STM32H7-based assistive device for aphasia patients, featuring patient-friendly interaction via gesture-based selection, infrared touch confirmation, and multimodal feedback. ◦ Edge AI: The image recognition model MCUNet was compressed and deployed on the STM32H7 with X-CUBE-AI, enabling real-time inference for ImageNet categories on a microcontroller with memory (1MB) and Flash (2MB) constraints. 	

Publication

- Haojie Dai*, **Yujie Cui***, Bowen Shi, Mazeyu Ji, Chengju Liu, Qijun Chen “LSW-Net: A Spatio-temporal Self-Supervised Framework for 2D LiDAR-Based Environment Perception”, IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), 2025.
- Yujie Cui**, Yue Pan, Dalei Wang, Mazeyu Ji, Sugong Cao “A smart robotic system for autonomous inspection of large-scale concrete girder,” International Association for Bridge Maintenance And Safety(IABMAS), 2024.