### **Calculus**



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## **Limits and Continuity**



#### Limits

- **Limit**  $\lim_{x\to c}$ : the value of a function (or sequence) approaches as the input (or index) approaches some value (informal definition)
  - Limits are used to define continuity<sup>↓</sup>, derivatives<sup>↓</sup>, and integrals<sup>↓</sup>

### **Limits of a Functions and Sequences**

- Limit of a function % | Limit of a sequence %
- **Limit of a function**: a fundament concept in calculus and analysis concerning the behavior *L* of a function near a particular input *c*, i.e.,

$$\lim_{x \to c} f(x) = L$$

- Reads as "f of x tends to L as x tends to c"
- $\circ$   $\mathcal{E}$ ,  $\delta$  **Limit of function**: a formalized definition, wherein f(x) is defined on an open interval I, except possibly at c itself, leading to above definition, if and only if:
  - For every real measure of closeness  $\mathcal{E} > 0$ , there exists a real corresponding  $\delta > 0$ , such that for all existing further approaches there exist a smaller  $\mathcal{E}$ , i.e.,

$$f: \mathbb{R} \to \mathbb{R}, \ c, L \in \mathbb{R} \Rightarrow \lim_{x \to c} f(x) = L$$

$$\updownarrow$$

$$\forall \varepsilon > 0 \ (\exists \delta > 0 : \forall x \in I \ (0 < |x - c| < \delta \Rightarrow |f(x) - L| < \varepsilon))$$

- Functions do not have a limit when the function:
  - has a unit step, i.e., it "jumps" at a point;
  - is not bounded, i.e., it tends towards infinity;
  - or does not stay close to any single number, i.e., it oscillates too much.
- **Limit of a sequence**: the value that the terms of a sequence  $(x_n)$  "tends to" (and not to any other) as n approaches infinity (or some point), i.e.,

$$\lim_{n\to\infty} x_n = x$$

 $\circ$   $\mathcal{E}$  Limit of sequence: for every measure of closeness  $\mathcal{E}$ , the sequence's term eventually converge to the limit, i.e.,

$$\forall \varepsilon > 0 \ (\exists N \in \mathbb{N} \ (\forall n \in \mathbb{N} \ (n \geq N \Rightarrow |x_n - x| < \varepsilon)))$$

- Convergent: when a limit of a sequence exists.
- Divergent: a sequence that does not converge.

### **Properties of Limits**

- S List of limits 1 Squeeze theorem 3
- Operations on a single known limit: if  $\lim_{x\to c} f(x) = L$  then:
  - $\cdot \lim_{x \to c} [f(x) \pm \alpha] = L \pm \alpha$
  - $\overline{\cdot \lim_{x \to c} \alpha f(x)} = \alpha L$
  - $\frac{1}{1+1} \lim_{x \to 0} f(x)^{-1} = L^{-1}, L \neq 0$
  - $\overline{\cdot \lim_{x \to c} f(x)^n = L^n}, n \in \mathbb{N}$
  - $\overline{\cdot \lim_{x \to c} f(x)^{n-1}} = L^{n-1}, n \in \mathbb{N}, \text{ if } n \in \mathbb{N}_e \Rightarrow L > 0$
- Operations on two known limits: if  $\lim_{x\to c} f(x) = L_1$  and  $\lim_{x\to c} g(x) = L_2$ 
  - $\cdot \overline{\lim_{x \to c} [f(x) \pm g(x)]} = L_1 \pm L_2$
  - $\cdot \lim_{x \to c} [f(x)g(x)] = L_1 L_2$
  - $\lim_{x \to c} f(x)g(x)^{-1} = L_1 L_2^{-1}$
- **Squeeze theorem**: used to confirm the limit of a function via comparison with two other functions whose limits are easily known or computed.
  - Let / be an interval having the point a as a limit point.
  - Let g, f, and h, be functions defined on I, except possibly at a itself.
  - Suppose that  $\forall x \in I \land \neq a \Rightarrow g(x) \leq f(x) \leq h(x)$
  - And suppose that  $\lim_{x \to a} g(x) = \lim_{x \to a} h(x) = L$
  - Then,  $\lim_{x \to a} f(x) = L$
  - Essentially, the hard to compute limit of the "middle function" is found by finding two other easy functions that "squeeze" the middle function at that point.

#### **One-Sided Limit**

- One-Sided Limit %
- One-sided limit: one of two limits of f(x) as x approaches a specified point from either the left or from the right.
  - From the left:  $\lim_{x\to c^-} = L$  From the right:  $\lim_{x\to c^+} = L$
- o If the left and right limits exist and are equal, then

$$\lim_{x \to c} f(x) = L \Leftrightarrow \lim_{x \to c^{-}} f(x) = L \land \lim_{x \to c^{+}} f(x) = L$$

 Limits can still exist, even if the function is defined at a different point, as long as both one-sided limits approach the same value near the given input.

### **Continuity**

- Continuity of functions is one of the core concepts of topology, however, there are definitions in terms of limits that prove useful; the following is only a primer.

#### **Continuous Functions**

- o Continuous function: a function that does not have any abrupt changes in value.
  - I.e., a function is continuous if and only if arbitrarily small changes in its output can be assured by restricting to sufficiently small changes in its input.
- **Discontinuous**: when a function is not continuous at a point in its domain, leading to a discontinuity; there are three classifications:
  - **Removable**: when both one-sided limits  $^{\uparrow}$  exist, are finite, and are equal, but the actual value of f(x) is not equal to the limit and equal to some other value.
    - · The discontinuity can be removed to regain continuity.
    - · Sometimes the term *removable discontinuity* is mistaken for *removable singularity*, or a "whole" in the function (the point is not defined elsewhere).
  - **Jump**: when a single limit does not exist because the one-sided limits exist and are finite, but not equal; points can be defined at the discontinuity, but the function can not be made continuous.
  - **Essential**: when at least one of two one-sided limits doesn't exist; can be the result of oscillating or unbounded functions.

#### Intermediate Value Theorem

Intermediate Value Theorem %

0

#### Extreme Value Theorem

Intermediate Value Theorem %

0

## **Limits Involving Infinity**

• Sources:

### **Limits at Infinity**

0

### Infinite Limits

0

## **Derivatives**



# **Applications of Derivatives**



# Integrals



# **Applications of Integrals**



## **Transcendental Functions**



# **Techniques of Integration**



# **Infinite Sequences and Series**



## **First-Order Differential Equations**



# **Parametric Equations and Polar Coordinates**



## **Vectors and Vector-Valued Functions**



# **Partial Derivatives**



# **Multiple Integrals**



## **Vector Calculus**



## **Second-Order Differential Equations**

