- 1. Consider a system of linear equations with augmented matrix  $\boldsymbol{A}$  and coefficient matrix  $\boldsymbol{C}$ . In each case explain why the statement is true or give an example showing that it is false.
- (a) If there is more than one solution,  $\boldsymbol{A}$  has a row of zeros.
- o If a row with all zeros occurs, then that row added no new information and was only a multiple of another row, i.e., the system is reduced rank.
- Matrix rank corresponds to the maximal number of linearly independent columns.
- Linear independence is when no vector in the matrix can be expressed as a linear combination, i.e.,

$$a_1 \mathbf{v}_1 + a_2 \mathbf{v}_2 + a_3 \mathbf{v}_3 + a_n \mathbf{v}_n$$

• For example, in a 3-D vector space  $\mathbb{R}^3$ , then any vector in the space is can be made by a linear combination of the following three vectors  $\mathbf{e}_1$ ,  $\mathbf{e}_2$ ,  $\mathbf{e}_3$  (unit vectors) multiplied by some scalar  $\lambda$ :

$$\lambda \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + \lambda \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + \lambda \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

o If the third column vector was all zeros (making the matrix have a row of all zeros) then it would just be describing a plane in  $\mathbb{R}^2$ , with the last row (or rather, third vector) contributing no information to the system,

$$\lambda \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + \lambda \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + \lambda \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

• That being said, the matrix above could be an augmented matrix with the constant matrix containing values for the first two vectors, indicating a single solution.

$$\begin{bmatrix} 1 & 0 & 0 & y \\ 0 & 1 & 0 & x \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

- And now I've realized I actually answered why the statement in (b) is false and not directly addressing the validity of (a).
- For (a) to be true, then there does have to be a row of zeros, given the original system of equations, as well as parameters in at least one of the other systems, as a row of all zeros puts no restriction on z.

$$\begin{bmatrix} 1 & 0 & 2 & x \\ 0 & 1 & 0 & y \\ 0 & 0 & 0 & 0(z) \end{bmatrix}$$

- (b) If **A** has a row of zeros, there is more than one solution.
- o Not necessarily, see above answer.
- (c) If there is no solution, the reduced row-echelon form of  $oldsymbol{\mathcal{C}}$  has a row of zeros.
- $\circ$  True, the rref form needs to have a row of zeros in the coefficient matrix and a non-zero in the same row in the constant matrix, i.e.,  $\begin{bmatrix} 0 & 0 & 0 & \cdots & a \neq 0 \end{bmatrix}$ , in order to have no solution.
- (d) If the row-echelon form of C has a row of zeros, there is no solution.
- Not necessarily, a row of zeros is more likely to indicate infinite solutions than no solution or a single solution, albeit, all are still possible.
- o For example, the following matrix is in ref and contains a row of all zeros.

$$\begin{bmatrix} 1 & 6 & 9 & 4 \\ 0 & 1 & 0 & 2 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

2.

Verify that 
$$\begin{cases} x_1 &= 2s+12t+13 \\ x_2 &= s \\ x_3 &= -s-3t-3 \end{cases}$$
 is a solution of 
$$\begin{cases} 2x_1+5x_2+9x_3+3x_4&=-1 \\ x_1+2x_2+4x_3&=1. \end{cases}$$

$$\begin{bmatrix} 2 & 5 & 9 & 3 & | & -1 \\ 1 & 2 & 4 & 0 & | & 1 \end{bmatrix} R_1 \updownarrow R_2 \begin{bmatrix} 1 & 2 & 4 & 0 & | & 1 \\ 2 & 5 & 9 & 3 & | & -1 \end{bmatrix}$$
$$-2R_1 + R_2 \begin{bmatrix} 1 & 2 & 4 & 0 & | & 1 \\ 0 & 1 & 1 & 3 & | & -3 \end{bmatrix}$$
$$-2R_2 + R_1 \begin{bmatrix} 1 & 0 & 2 & -6 & | & 7 \\ 0 & 1 & 1 & 3 & | & -3 \end{bmatrix}$$

Two parameters are left: s, t.

$$x_1 = 2s - 6t + 7$$

$$x_2 = s$$

$$x_3 = -s - 3t - 3$$

$$x_4 = t$$

I am confused.

Let's try something different:

$$2(2s + 12t + 13) + 5(s) + 9(-s - 3t - 3) + 3(t) = -1$$

$$4s + 24t + 26 + 5s - 9s - 27t - 27 + 3t = -1$$

$$24t - 27t + 3t + 26 - 27 = -1$$

$$26 - 27 = -1$$

$$-1 = -1$$

$$2s + 12t + 13 + 2(s) + 4(-s - 3t - 3) = 1$$

$$2s + 12t + 13 + 2s - 4s - 12t - 12 = 1$$

$$12t - 12t + 13 - 12 = 1$$

$$1 = 1$$

Hmmm...why doesn't rref work.

$$2(2s-6t+7)+5(s)+9(-s-3t-3)+3(t)=-1$$
 
$$4s-12t+14+5s-9s-27t-27+3t=-1$$
 
$$-12t+14-27t-27+3t=-1$$
 yeah, no

Did I do parameters wrong?

$$\begin{bmatrix} 1 & 0 & 2 & -6 & 7 \\ 0 & 1 & 1 & 3 & -3 \end{bmatrix}$$

$$x_1 = 2s + 6t + 7$$

$$x_2 = -s - 3t - 3$$

$$x_3 = s$$

$$x_4 = t$$

Idk, let's try it.

$$2(2s+6t+7) + 5(-s-3t-3) + 9(s) + 3(t) = -1$$
$$4s+12t+14-10s-15t-15+9s+3t=-1$$
$$3s-1=-1$$
$$s=0$$

Well, why doesn't that work? I guess rref removes information...or maybe I'm doing something wrong with parameters.