Topics: Early systems and OS overview
Skim Chapters 1-2 of SGG
Read Chapter 1 of USP

CS 3733 Operating Systems

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Lecture Outline

- Evolution of Computer Systems and OS Concepts
- Operating System: what is it?
- Different types/variations of Systems/OS
 - Parallel/distributed/real-time/embedded OS etc.
- OS as a resource manager
 - How does OS provide service? interrupt/system calls
- OS Structures and basic components
 - Process/memory/IO device managers



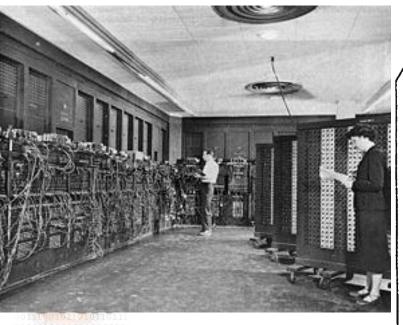
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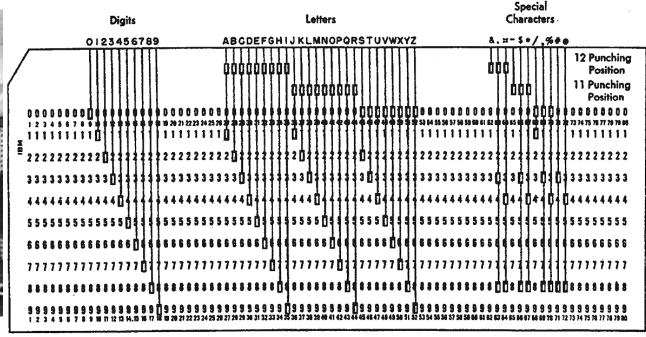
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First Computer: ENIAC in 1940s

- □ Big: 27 tons, 680 ft^2, and use 150kW
- Slow: tens instructions/s
- Limited functions: addition / multiplication
- Hard to use: Button switch or Punch card I/O





First Computer: ENIAC (cont.)

- Got problem with the program?! → you are in trouble ☺
- Process one job at a time
 - > Human is slow
 - CPU time is precious
- Batch systems
 - Read in more jobs
 - Process one by one
 - I/O devices are still slow?





Debug your program!

Multiprogrammed Systems

A single program cannot keep busy for CPU and IO, thus wasting resources

512M

- Several jobs run "concurrently resources
 - \rightarrow Job: computing \rightarrow input \rightarrow computing $\rightarrow ... \rightarrow$ output
 - Take turns to use CPU and I/O devices

- But which job uses what and when?
 - ➤ Need a manager/supervisor → OS
- How to use the hardware (e.g., I/O devices)?
 - ➤ Resource manager/interface → OS

job 2

operating system

job 1

job 3

job 4



Time Sharing Systems

- Extension to multi-programmed systems
- Multiple interactive users
 - > Allow on-line interaction with users;
 - Response time for each user should be short
- CPU is multiplexed among several jobs of several users that are kept in memory
 - > CPU is allocated to jobs in Round-Robin manner
 - All active users must have a *fair* share of the CPU time: e.g. with 100 ms time quantum
- Example systems: IBM 704 and 7090



Justification for Time Sharing Systems

Table 1.1. Typical times for components of a computer system. One nanosecond (ns) is 10^{-9} seconds, one microsecond (μ s) is 10^{-6} seconds, and one millisecond (ms) is 10^{-3} seconds.

item	time		scaled time in human terms (2 billion times slower)	
processor cycle	0.5 ns	(2 GHz)	1	second
cache access	1 ns	(1 GHz)	2	seconds
memory access	15 ns		30	seconds
context switch	5,000 ns	(5 μs)	167	minutes
disk access	7,000,000 ns	(7 ms)	162	days
quantum	100,000,000 ns	(100 ms)	6.3	years

Desktop Systems: 1980s

- Personal computers dedicated to a single user;
- Objective: User convenience and responsiveness.
 - Individuals have sole use of computers
 - A single user may not need advanced features of mainframe OS (maximize utilization, protection).
- □ I/O devices display, keyboard, mouse and printers
- □ Today, may run several different types of operating systems (Windows, MacOS, Linux)

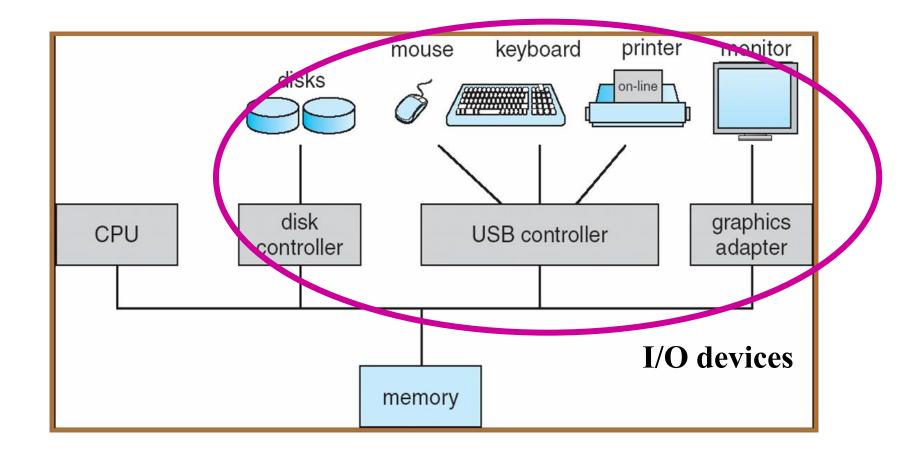




Parallel High-Performance Systems

- Goals:
 - Increased performance/throughput
 - Increased reliability: fault tolerance
- Multiprocessor systems: more than one CPUs
 - Tightly coupled system processors share memory, bus, IO, and a clock; communication usually takes place through the shared memory
- □ Symmetric multiprocessing (SMP) vs. asymmetric
 - SMP: each processor runs an identical copy of the operating system; all processors are peers
 - Asymmetric: master-slave

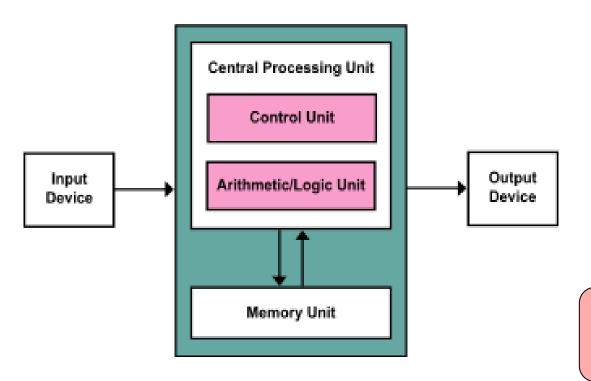
Modern Computer Hardware Organization





von Neumann Architecture: store and computation

Von Neumann Architecture



Before, computers have fixed uses

This describes a design architecture:

- A processing unit containing an ALU and processor registers
- A control unit containing an instruction register or program counter.
- A memory to store both data and instructions (Stored-program computer)
- External mass storage, and input and output mechanisms.

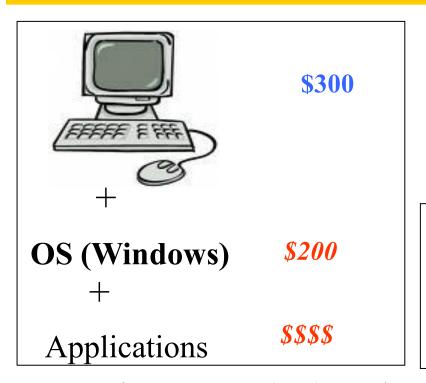


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What Operating Systems do?





Do I have to?!

Yes!
Otherwise, a set of silicon circuits
doing nothing good
for you!

Operating system (OS) goals:

- Execute user programs and make solving user problems easier
- Make the computer system convenient to use
- Use the computer hardware in an efficient manner

What is an Operating System (OS)?

User View

User interface, ease of use vs. performance (windows vs. command line; terminal vs. minicomputer; networked workstations; handheld; embedded)

System View

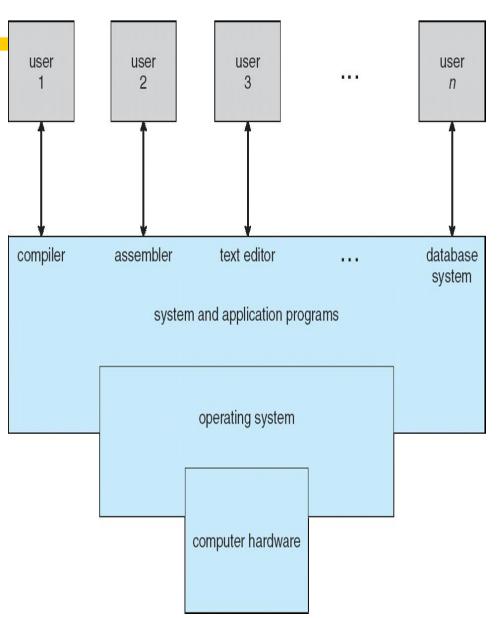
OS is a resource allocator

Manages all resources (CPU, memory, file-storage, I/O devices etc.)

Decides between conflicting requests for efficient and fair resource use

OS is a control program

Controls execution of programs to prevent errors and improper use of the computer



Operating System Definition(s)

Based on the discussion so far, can you define Operating System?

☐ Here is a good approximation

"Everything a vendor ships when you order an operating system"

- "The one program running at all times on the computer" is the kernel. Everything else is either a system program (ships with the operating system) or an application program
- □ So we may say: OS is a program (or programs) that
 - manages computer hardware and resources,
 - provides user friendly interface for applications and users
- No universally accepted or completely adequate definition
- □ Instead of a definition, we should focus on the tasks that are necessary to accomplish the OS goals:



- Execute user programs and make solving user problems easier (user/programmer view)
- Make the computer system convenient to use... (user view)
- Use the computer hardware in an efficient manner... (system view)

HOW?

- The amazing aspect of Operating Systems is how varied they are in performing their tasks
 - Different needs, capabilities, etc
 - Ease of use vs. performance vs. cost



Retrieval practice...

- What is Operating System (OS)?
 - A program (kernel) that runs at all times and acts as an *intermediary* between the user/programs and hardware.
 - ✓ manages computer hardware and resources,
 - ✓ provides user friendly interface for applications and users
- What are the Goals of Operating System
 - ➤ Convenience: Make the computer convenient to use for general user and programmers..
 - ➤ Efficiency: Manage system resources in an efficient manner

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Computer-System Operation

CPU (Processor/ALU)

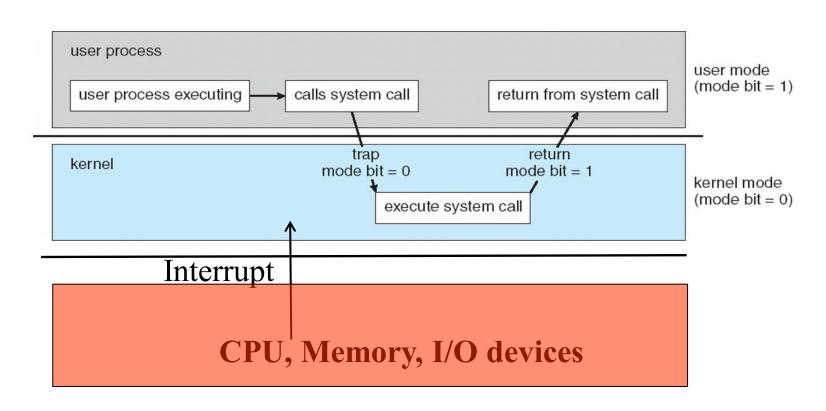
Internal Memory

Computer Startup: bootstrap
program is loaded at power-up
or reboot: Typically stored in
ROM or EPROM, generally
known as firmware. It
initializes all aspects of system
and loads operating system
kernel and starts execution

- load instructions from main memory,
- load/store data from/to memory system
- controls I/O devices to perform certain tasks

- User process or kernel process
- □ I/O devices and the CPU can execute concurrently
 - > Each device controller is in charge of a particular device type
 - Each device controller has a local buffer
 - CPU moves data from/to main memory to/from local buffers
- Device controller informs CPU that it has finished its operation by causing an *interrupt*

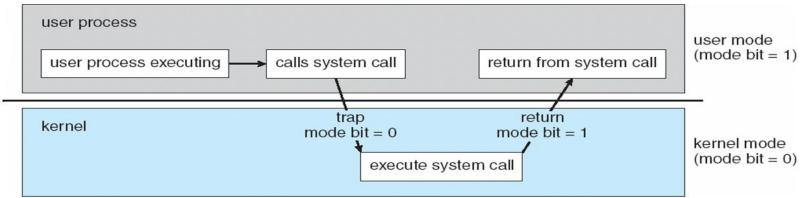
Computer-System Operation (cont'd)





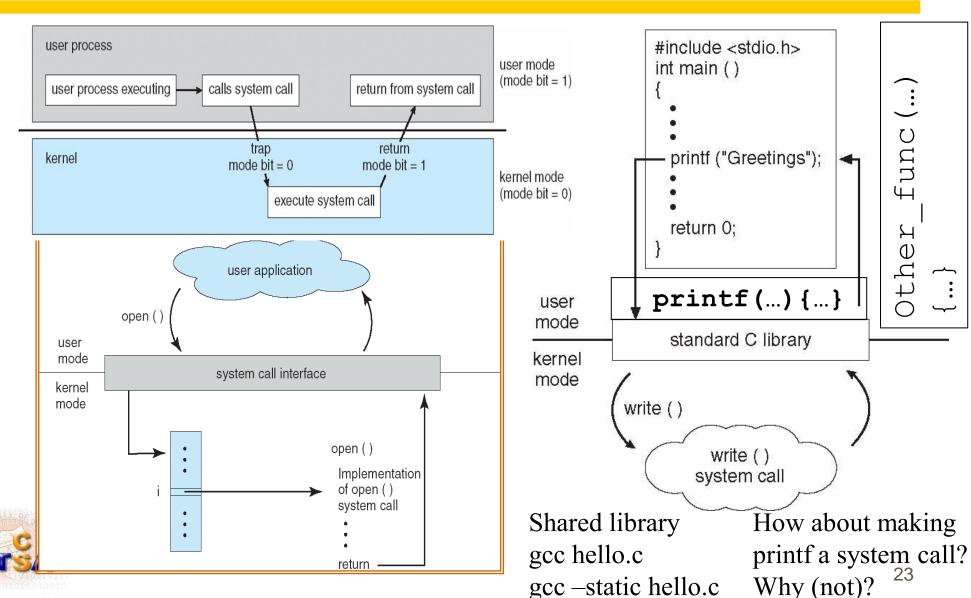
OS Interface: APIs and System Calls

- For application programmers
- Application programming interface (API)
 - The run-time support system (run-time libraries) provides a system-call interface, that intercepts function calls in the API and invokes the necessary system call within the operating system
- System calls provide the interface between a running program and the operating system.
 - Generally available in routines written in C and C++
 - Certain low-level tasks may have to be written using assembly language



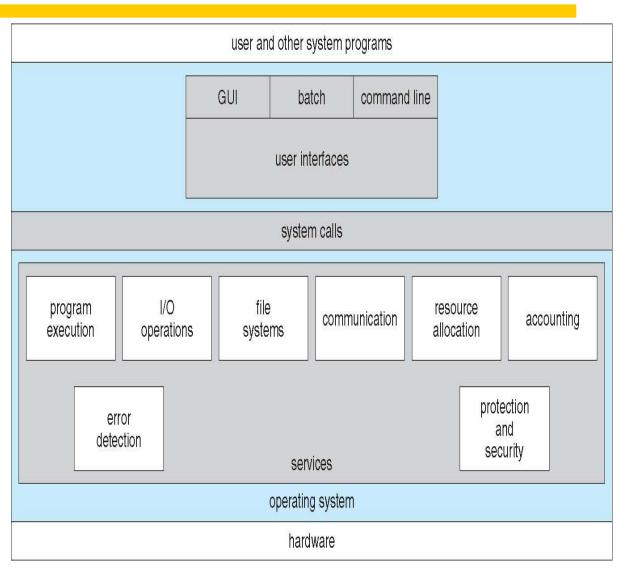


System Call vs. User/Library Function Call write(...) vs. printf(....)



Types of System Calls

- Process control
- □ File management
- □ I/O management
- Communications
- Accounting
- Protection





Examples: Major System Calls in Unix

Process management

Call	Description	
pid = fork()	Create a child process identical to the parent	
pid = waitpid(pid, &statloc, options)	Wait for a child to terminate	
s = execve(name, argv, environp)	Replace a process' core image	
exit(status)	Terminate process execution and return status	

File management

Call	Description	
fd = open(file, how,)	Open a file for reading, writing or both	
s = close(fd)	Close an open file	
n = read(fd, buffer, nbytes)	Read data from a file into a buffer	
n = write(fd, buffer, nbytes)	Write data from a buffer into a file	
position = lseek(fd, offset, whence)	Move the file pointer	
s = stat(name, &buf)	Get a file's status information	



Examples of Windows and Unix System Calls

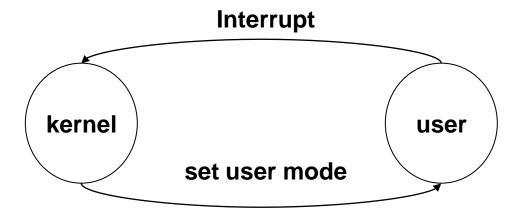
	Windows	Unix
Process Control	<pre>CreateProcess() ExitProcess() WaitForSingleObject()</pre>	<pre>fork() exit() wait()</pre>
File Manipulation	<pre>CreateFile() ReadFile() WriteFile() CloseHandle()</pre>	<pre>open() read() write() close()</pre>
Device Manipulation	SetConsoleMode() ReadConsole() WriteConsole()	ioctl() read() write()
Information Maintenance	<pre>GetCurrentProcessID() SetTimer() Sleep()</pre>	<pre>getpid() alarm() sleep()</pre>
Communication	<pre>CreatePipe() CreateFileMapping() MapViewOfFile()</pre>	<pre>pipe() shmget() mmap()</pre>
Protection	<pre>SetFileSecurity() InitlializeSecurityDescriptor() SetSecurityDescriptorGroup()</pre>	<pre>chmod() umask() chown()</pre>



Operation Modes

- Hardware support (mode bit) to differentiate between at least two modes of operations
 - User mode execution done on behalf of a user
 - Kernel mode (also monitor mode or system mode or privileged mode) executing on behalf of operating system
- □ E.g., interrupts: → switches to monitor mode.

Privileged instructions can be issued only in kernel mode.





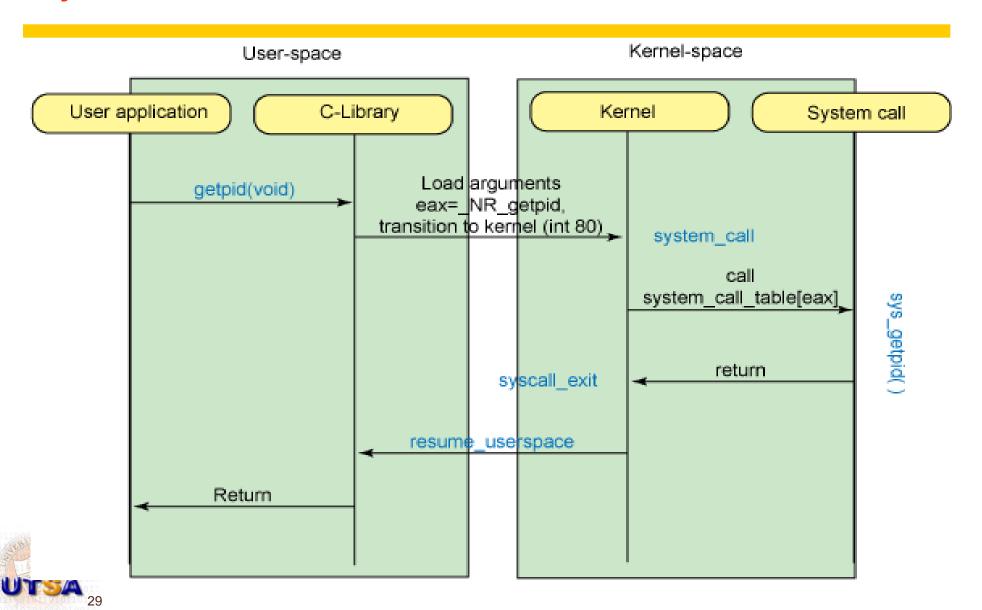
System call control flow - Linux

- User application calls a user-level library routine
 (gettimeofday(), read(), exec(), etc.)
- Invokes system call through stub, which specifies the system call number. From unistd.h:

```
#define __NR_getpid 172
__SYSCALL(__NR_getpid, sys_getpid)
```

- This generally causes a software interrupt, trapping to kernel
- Kernel looks up system call number in syscall table, calls appropriate function
- Function executes and returns to interrupt handler, which returns the result to the user space process

System call control flow - Linux



Interrupt Mechanisms

CPU (Processor/ALU)

I/O devices

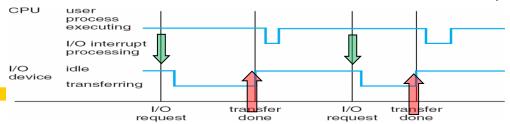
Internal Memory

Device controller informs CPU that

it has finished its operation by causing an interrupt

- Save the current "process state"
- Interrupt transfers control to the interrupt service routine (ISR) generally through interrupt vector containing the addresses of all the service routines.
- ISR: Separate segments of code determine what action should be taken for each type of interrupt.
- Once the interrupt has been serviced by the ISR, the control is returned to the interrupted program.

Interrupt Handling



- The interrupt is issued
- 2. Processor finishes execution of current instruction
- 3. Processor signals acknowledgement of interrupt
- Processor pushes PSW(Program Status Word) and PC to control stack
- 5. Processor loads new PC value through the interrupt vector
- 6. ISR saves remainder of the process state information
- ISR executes
- 8. ISR restores process state information
- 9. Old PSW and PC values are restored from the control stack

What if another interrupt occurs during interrupt processing?

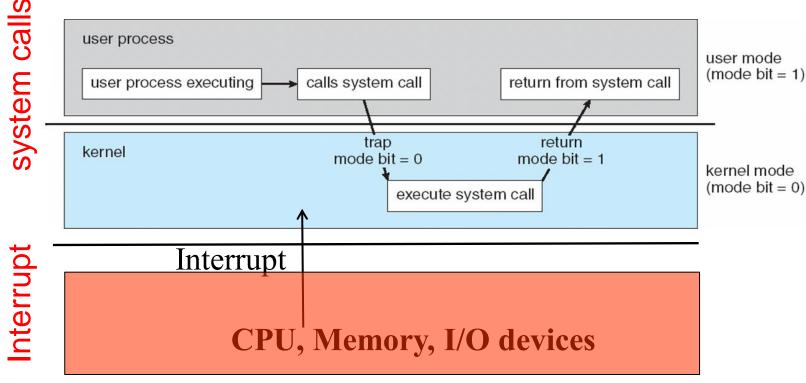
Classes of Interrupts

- I/O Interrupts: Generated by an I/O controller, to signal normal completion of an operation or to signal a variety of error conditions
- Timer Interrupts: Generated by a timer within the processor. This allows the operating system to perform certain functions on a regular basis, like scheduling
- Hardware Failure Interrupts: Generated by a failure (e.g. power failure or memory parity error).
- □ Traps (Software Interrupts): Generated by some condition that occurs as a result of an instruction execution
 - User request for an operating system service (e.g., system calls)
 - Runtime errors



Retrieval Practice

What are the two key mechanisms to interact with the kernel, and how do they work?





Retrieval Practice

What are the two key differences between system calls and user/library function calls?

e.g., write vs. printf



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Components in Operating System

- Process/thread Management
 - > CPU (processors): most precious resource
- Memory Management
 - Main memory
- □ File Management → data /program
- □ Secondary-Storage Management → disk
- □ I/O System Management → I/O devices
- □ Protection and Security → access management





Process Management



- □ A process is a program in execution (active),
 - Dynamic concept, represented by process control block
- □ A process needs resources: execution environment
 - including CPU time, registers, memory, files, and I/O devices to accomplish its task
- OS provides mechanism to
 - Create/delete processes
 - Run/Suspend/resume processes (scheduling/signal)
 - Process communication and synchronization
 - Deadlock handling



Main Memory Management



- The main memory is
 - > a large array of words/bytes, each with its own address
 - > a volatile storage device: content lost when power off
- The operating system will
 - Keep track of which parts of memory are currently being used and by whom
 - Decide which processes to load when memory becomes available
 - Allocate and de-allocate memory space as needed



File Management



- A file is a collection of related information (logic unit)
 - Format is defined by its creator.
- Represent programs (source/object forms) and data
- Operating system responsibilities
 - File creation and deletion
 - Directory creation and deletion
 - > Support of primitives for manipulating files and directories
 - Mapping files onto secondary storage
 - > File backup on stable (non-volatile) storage media



Secondary-Storage Management

- The secondary storage backs up main memory and provides additional storage.
- Most common secondary storage type: disks
- The operating system is responsible for
 - > Free space management
 - Storage allocation
 - Disk scheduling



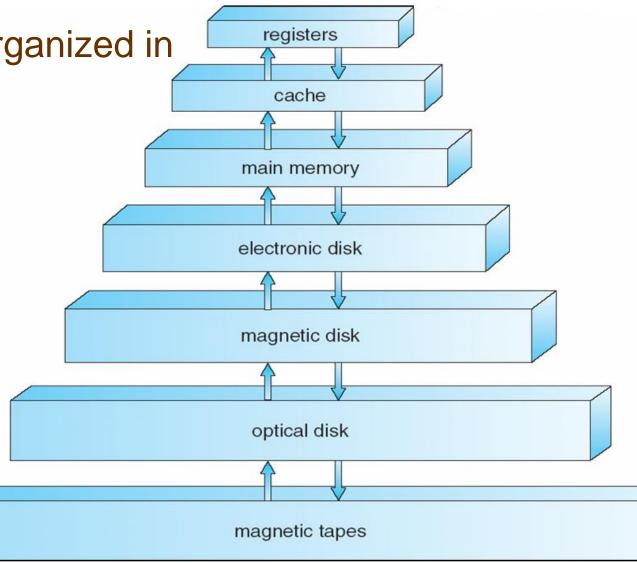
Storage Hierarchy

Storage systems organized in hierarchy

- Speed
- > Cost

storage

Caching – copying information into faster storage system; main memory can be viewed as a last *cache* for secondary.



Caching

- Important principle, performed at many levels in a computer (in hardware, operating system, software)
- Information in use copied from slower to faster storage temporarily
- Faster storage (cache) checked first to determine if information is there
 - > If it is, information used directly from the cache (fast)
 - If not, data copied to cache and used there
- Cache smaller than storage being cached
 - Cache management important design problem
 - Cache size and replacement policy

I/O System Management

- □ The Operating System will hide the peculiarities of specific I/O hardware from the user.
- □ In Unix, the I/O subsystem consists of:
 - >A buffering, caching and spooling system
 - >A general device-driver interface
 - Drivers for specific hardware devices
- Interrupt handlers and device drivers are crucial in the design of efficient I/O subsystems



Linux kernel map functionalities human interface system networking processing storage memory layers interfaces core processes memory access HI char devices sockets access files & directories sys_fork user sys_brk access System Call Interface sys kill sys_vfork cdev add sys open sys_socketcall sys_mmap shm vm ops sys execve sys_signal linux/syscalls.h sys clone sys_socket space /proc /sysfs /dev do sigaction sys_shmctl sys connect svs svsinfo linux/uaccess.h sys_shmat sys accept sys_pipe sys_select do_path_loc sysfs_ops copy_from_user sys bind /proc/net/ interfaces linux hinfmt sys_splice sys_sendfile sys_listen input_fops register_chrdev si_meminfo sys mprotect tcp4 seq show sys gettimeofday sys_sendmsg sys_mincore cdev_add sys time sg_proc_seq_show_dev sys recvms system calls rt cache seq show and system files cdev_map sys_epoll_create mem fops fb_fops sys capset /proc/meminfo cdev sys msync /proc/self/maps sys init module Virtual File System threads virtual memory protocol families inet_init __sock_create __socket **Device Model** vfs_fsync security security INIT_WORK/ queue work find_vma_prepare vfs_write workqueue struct vfs getattr inet family ops security capset may open kobject virtual kset fanotify tech tack see inet create inode vmalloc unix family ops kthread create inode permission vfree bus_type kernel thread security inode create device create proto_ops security_ops vm_struct file system type current inet_dgram_ops inet_stream_ops thread info virt to page device_type generic file aid read socket file ops driver_register debugging synchronization device driver memory page cache networking socket mapping address_space bdi_writeback_thread do_writepages bridges sys_ptrace log_buf storage splice sock_sendpage nfs file operations register knrobe printk add_timer timer_list run_timer_softirq do_mmap_pgoff si swapinto SWap cross-functional load module top sendpage kmem_cache_alloc smb_fs_type modules handle sysra oprofile start module kobject_uevent_init vma link swap_info kswapd cifs file ops module param sock splice read kobject uevent mm_struct do_swap_page iscsi tcp transport tcp_splice_read vm_area_struct kernel param HI subsystems Scheduler logical memory logical protocols system run /proc/net/protocols boot shutdown kernel/sched.c file systems power management tcp_prot task struct logical init/main alsa mm_init tcp_v4_rcv ext4 file operations functions implementations schedule timeout kmalloc tcp_transmit_sk do initcalls schedule ext4_get_sb NE HOOK video_device kfree ip_queue_xmit pgd_t pmd_t pte_t nt hooks ext4 readdir run init process mousedev_handler kernel_power_off ip push pending frames ip route input alloc_skb tty machine ops ip_rcv sk_buff Page Allocator abstract devices generic HW access interrupts core block devices network interface and request ira gendisk pci driver **HID class drivers** dev_queue_xmit _free_pages netif receive skb device block device operations pci_register_driver request mem region kmem cache drivers/input/ drivers/media register_netdev kmem_cache_init kmem_cache_alloc pci request regions do_timer net_device control scsi device console tick_periodic get free pages scsi driver usb submit urb alloc netdev mg alloc pages fb_ops do_softirq ether_setup ieee80211_rx do_IRQ_irq_desc usb hcd netif_carrier_on ieee80211_xmit drm_driver ioremap try_to_free_pages HI peripherals device access CPU specific physical memory disk controller network setup_arch device drivers and bus drivers operations device drivers drivers hardware arch/x86/mm/ get page from freelist usbnet_probe native init IRQ switch to interfaces ipw2100_pci_init_one ehci urb enqueue set_intr_gate atkbd dry zd1201_probe system call drivers, registers and interrupts e1000 xmit frame i8042 driver out of memory ahci pci driver show reas pci read e1000 intr psmouse aic94xx init num_physpages do page fault pci_write user peripherals 1/O mem 1/O CPU disk controllers network controllers memory PCI electronics mouse graphics card © 2007, 2010 Constantine Shulyupin www.MakeLinux.net/kernel map

Retrieval exercise: What are the Key Components/ modules in Operating System?

- Process/thread Management
 - > CPU (processors): most precious resource
- Memory Management
 - Main memory
- □ File Management → data /program
- □ Secondary-Storage Management → disk
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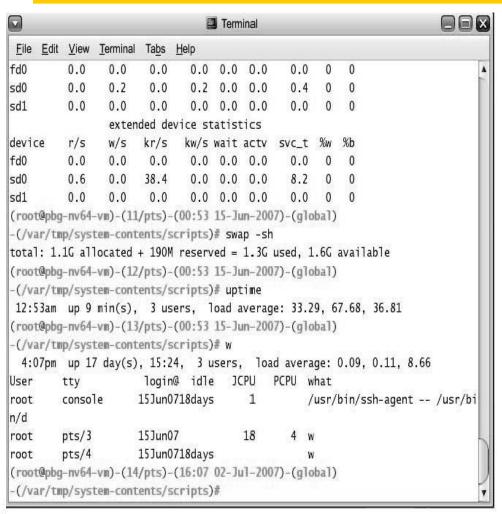


OS Interface: Shell and GUI

- For both programmers and end-users
- Two main approaches for both
 - Command-line interpreter (or shell)
 - Graphical User Interfaces (GUI)
- The shell
 - allows users to directly enter commands that are to be performed by the operating system
 - Is usually a system program (not part of the kernel)
- GUI allows a mouse-based window-and-menu system: click-and-play
- Some systems allow both (e.g. X-Windows in Unix)



OS Interfaces







Command Line

The Mac OS X GUI

System Programs

- System programs provide a convenient environment for program development and execution. They can be divided into:
 - File manipulation
 - Status information
 - > File modification
 - Programming language support
 - Program loading and execution
 - Communications
 - Application programs

Most users' view of the operating system is defined by system programs, not the actual system calls

System Programs

- Provide a convenient environment for program development and execution
 - Some of them are simply user interfaces to system calls; others are considerably more complex
- File management Create, delete, copy, rename, print, dump, list, and generally manipulate files and directories
- Status information
 - > Some ask the system for info date, time, amount of available memory, disk space, number of users
 - Others provide detailed performance, logging, and debugging information
 - Typically, these programs format and print the output to the terminal or other output devices
 - Some systems implement a registry used to store and retrieve configuration information

System Programs (Cont.)

- ☐ File modification
 - Text editors to create and modify files
 - Special commands to search contents of files or perform transformations of the text
- Programming-language support Compilers, assemblers, debuggers and interpreters sometimes provided
- Program loading and execution- Absolute loaders, relocatable loaders, linkage editors, and overlay-loaders, debugging systems for higher-level and machine language
- Communications Provide the mechanism for creating virtual connections among processes, users, and computer systems
 - Allow users to send messages to one another's screens, browse web pages, send electronic-mail messages, log in remotely, transfer files from one machine to another



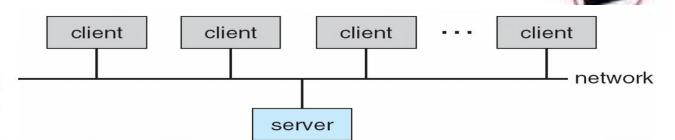
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Distributed Systems

- Loosely coupled system each processor has its own local memory; processors communicate with one another through various communications lines
- Advantages of distributed systems.
 - Resource Sharing
 - Computation speed up
 - load sharing
 - Reliability
 - Communications





Peer-to-Peer Computing Systems

- Another model of distributed system
- P2P does not distinguish clients and servers
 - Instead all nodes are considered peers
 - May each act as client, server or both
 - Node must join P2P network
 - ✓ Registers its service with central lookup service on network, or
 - ✓ Broadcast request for service and respond to requests for service via discovery protocol
 - Examples include Napster and Gnutella

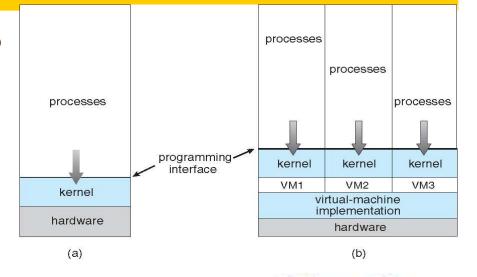


Special Purpose Systems

- A real-time system is used when strict time requirements have been placed on the operation of a processor or the flow of data
 - > Hard real-time: critical tasks must be completed on time
 - Soft real-time: no absolute timing guarantees (e.g. "best-effort scheduling"); multimedia applications;
- An embedded system is a component of a more complex system
 - Control of a nuclear plant or Missile guidance
 - Control of home and car appliances (microwave oven, DVD players, car engines, ...)
- Example: VxWorks and eCos; Android and iOS

Virtualization and Cloud Computing

- Virtualization: Run an OS as Application in another OS
- Emulation, Interpretation
- Cloud Computing
 - ➤ SaaS, PaaS, IaaS, XaaS...







Along the way...