

In [17]: #Q3

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In [30]: # Expectation Calculation
# It is assuming that only the first non solved task will be attempted again. after
def expectedReturnFirstNonSolvedTask(policy, attempts, first_task_nonsolved):
    if len(policy) > 0 and attempts <= 8 : # Max number of attempts is 8
        # we take the next task and increase attempts
        task = policy[0]
        if first_task_nonsolved == False:
            second_attempt_pass = task[1] + expectedReturnFirstNonSolvedTask(policy, attempts+1, first_task_nonsolved)
            second_attempt_fail = 0 + expectedReturnFirstNonSolvedTask(policy, attempts+1, first_task_nonsolved)
            first_attempt_pass = task[2] * ( task[1] + expectedReturnFirstNonSolvedTask(policy, attempts+1, first_task_nonsolved) )
            first_attempt_fail = (1-task[2]) * ( 0 + expectedReturnFirstNonSolvedTask(policy, attempts+1, first_task_nonsolved) )
            return first_attempt_pass + first_attempt_fail
        if first_task_nonsolved == True : #This means that once task has already been attempted
            first_attempt_pass = task[2] * ( task[1] + expectedReturnFirstNonSolvedTask(policy, attempts+1, first_task_nonsolved) )
            first_attempt_fail = (1-task[2]) * ( 0 + expectedReturnFirstNonSolvedTask(policy, attempts+1, first_task_nonsolved) )
            return first_attempt_pass + first_attempt_fail
    else:
        return 0
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In [31]: # Find expectations of Policy A and B
tasks = [(1, 12, 0.25), (2, 4, 0.4), (3, 10, 0.35), (4, 5, 0.6), (5, 7, 0.45), (6, 3, 0.5), (7, 50, 0.15)]
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In [32]: policyA = tasks #Policy A, sequential order
policyB = sorted(tasks, key=lambda task: task[2], reverse=True) # Policy B, order of decreasing probability
print("Policy A: ", policyA)
print("Expected return of policy A: ", expectedReturnFirstNonSolvedTask(policyA, 0, 0))

print("Policy B: ", policyB)
print("Expected return of policy B: ", expectedReturnFirstNonSolvedTask(policyB, 0, 0))
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Policy A: [(1, 12, 0.25), (2, 4, 0.4), (3, 10, 0.35), (4, 5, 0.6), (5, 7, 0.45), (6, 3, 0.5), (7, 50, 0.15)]
Expected return of policy A: 24.6665459375
Policy B: [(4, 5, 0.6), (6, 3, 0.5), (5, 7, 0.45), (2, 4, 0.4), (3, 10, 0.35), (1, 12, 0.25), (7, 50, 0.15)]
Expected return of policy B: 24.497423437500004
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In [33]: #Q4

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In [34]: # Randomly shuffle the order of tasks to generate all policies. Check the expected return of each policy.  
# Simulation of the iteration algorithms . Generating a shuffle of all policies  
import itertools  
maxer = 0  
for policy in list(itertools.permutations(tasks)) :  
    #print("Current Policy :",policy)  
    er = expectedReturnFirstNonSolvedTask(policy,0,False)  
    if er > maxer :  
        maxer = er  
        policyC = policy
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In [35]: print("Improved policy C: ",policyC)  
print("Expected Return of policy C: ",maxer)
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Improved policy C: ((7, 50, 0.15), (3, 10, 0.35), (5, 7, 0.45), (1, 12, 0.25),  
(4, 5, 0.6), (2, 4, 0.4), (6, 3, 0.5))  
Expected Return of policy C: 26.6859575625
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In [ ]:
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