


Approximating exponential family models (not single distributions) with a two-network architecture

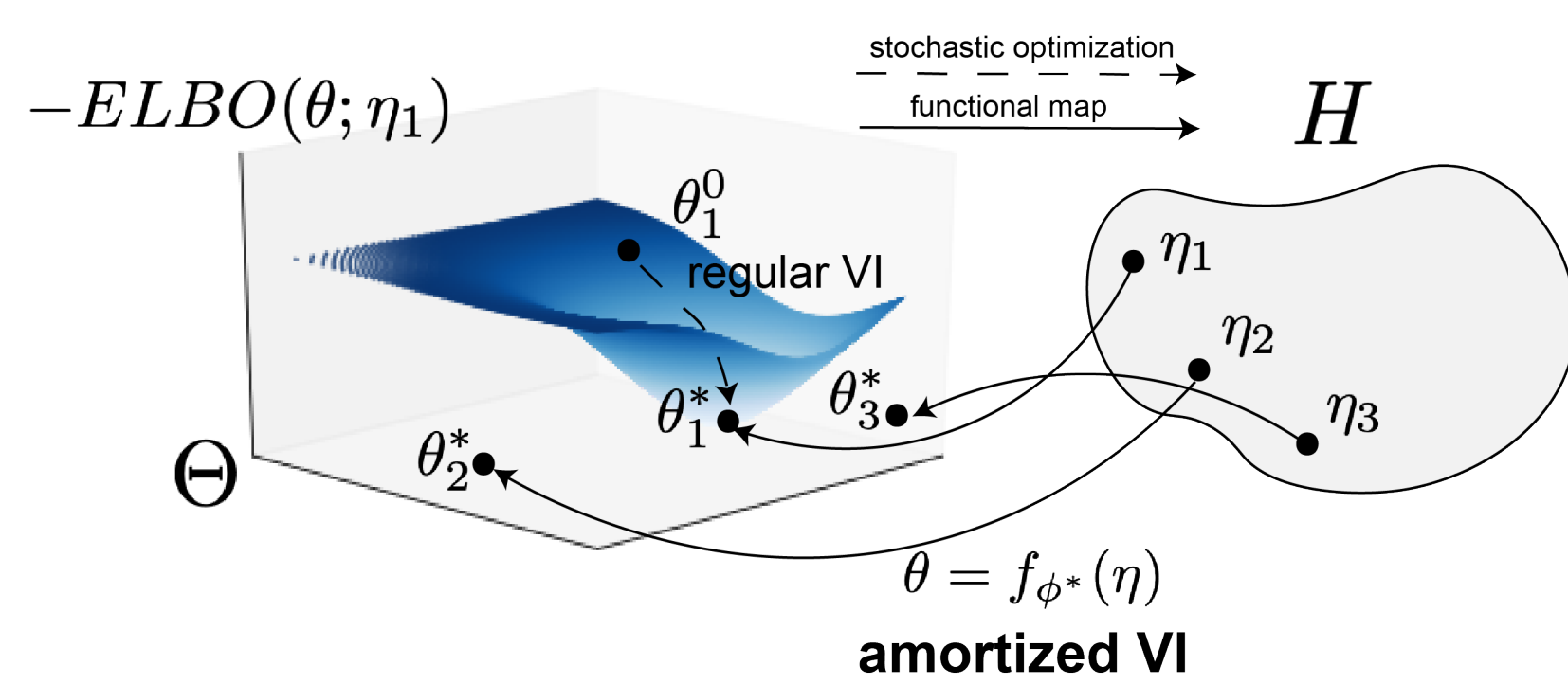
Sean R. Bittner¹, John P. Cunningham²

¹Department of Neuroscience and ²Department of Statistics, Columbia University Medical Center



Motivation

- Many models used in machine learning are intractable exponential families.
- Variational inference (VI) on intractable exponential families incurs a cost of optimization.
- We introduce a deep generative two-network architecture called exponential family networks (EFNs) for learning intractable exponential family *models* (not single distributions).
- EFNs learn a smooth function $f_{\phi^*} : H \rightarrow \Theta$ mapping natty p's η (i.e. ) to optimal variational parameters θ^* .



- EFNs afford substantial computational savings through amortized VI.

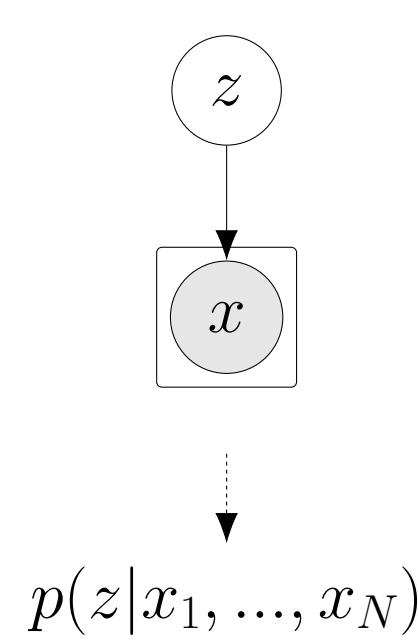
Exp fams as target models \mathcal{P}

- Exponential family models \mathcal{P} have the form

$$\mathcal{P} = \left\{ \frac{h(\cdot)}{A(\eta)} \exp \{ \eta^\top t(\cdot) \} : \eta \in H \right\}$$

with natural parameter η , sufficient statistics $t(\cdot)$, base measure $h(\cdot)$, and log normalizer $A(\eta)$.

- We focus on the fundamental problem setup of probabilistic inference: N conditionally independent observations x_i given latent variable z .



- With exponential family prior and likelihood,

$$p_0(z) = \frac{1}{A_0(\alpha)} \exp \{ \alpha^\top t_0(z) \}$$

$$p(x_i|z) = \frac{1}{A(z)} \exp \{ \nu(z)^\top t(x_i) \}$$

our posterior is the following exp fam

$$p(z|x_1, \dots, x_N) \propto \exp \left\{ \left[\begin{array}{c} \alpha \\ \sum_i t(x_i) \\ -N \end{array} \right]^\top \left[\begin{array}{c} t_0(z) \\ \nu(z) \\ \log A(z) \end{array} \right] \right\}$$

which is intractable for nonconjugate priors, requiring computation for inference.

Deep approximating families \mathcal{M}

- Deep generative models are commonly used as approximating families to single distributions.
- The density network (vertical) of our two-network architecture is a cascade of normalizing flows, which maps a base random variable ω to sample $z = g_\theta(\omega)$ with variational parameters θ .
- Bijjective normalizing flows allow us to calculate the density for each sample.

$$\omega \sim q_0(\omega), z = g_\theta(\omega) = g_L \circ \dots \circ g_1(\omega)$$

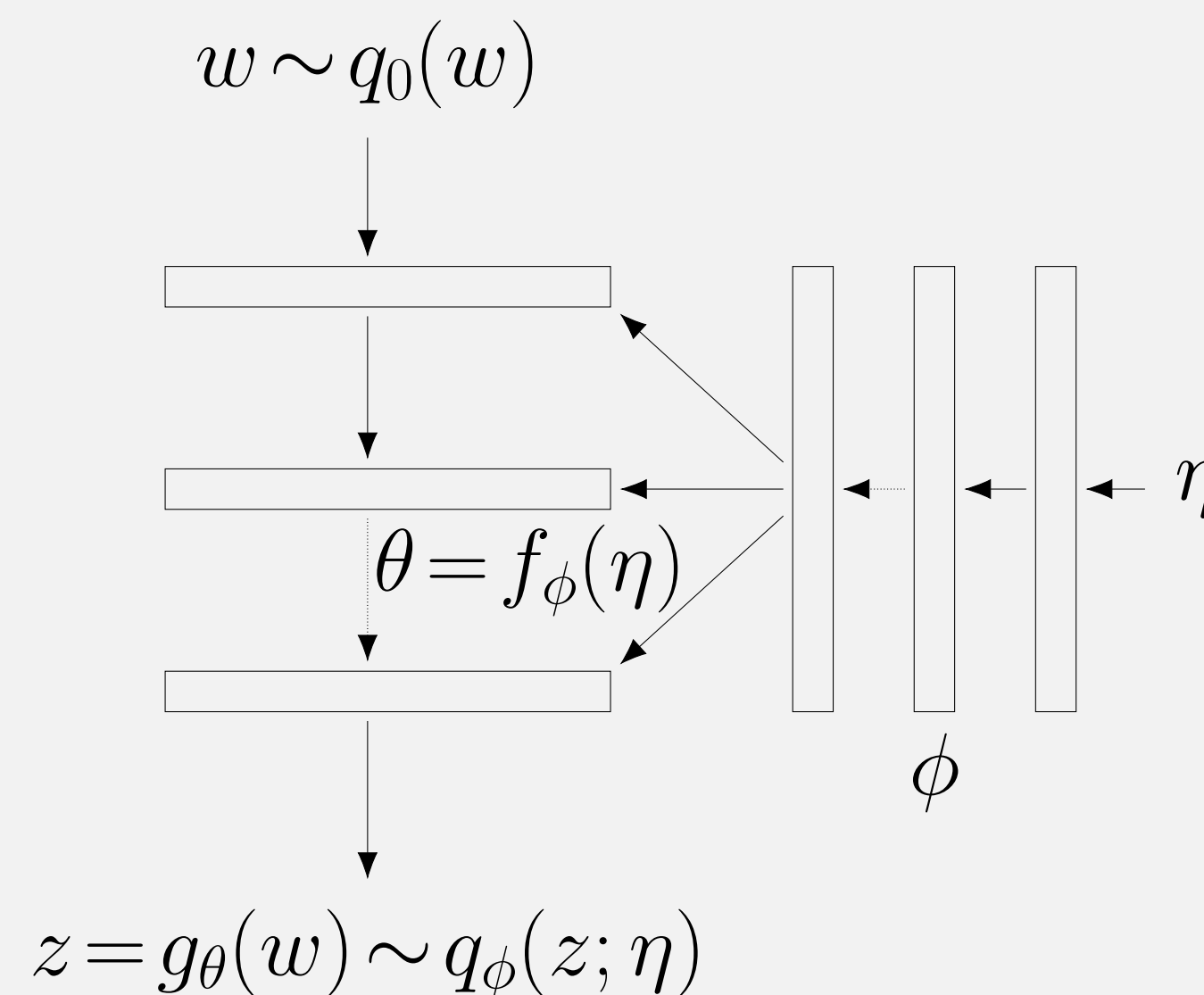
$$q_\theta(z) = q_0(g_1^{-1} \circ \dots \circ g_L^{-1}(z)) \prod_{\ell=1}^L \frac{1}{|J_{g_\ell}(z)|}$$

- The density network induces a model

$$\mathcal{M} = \{q(g_\theta(\omega)) : \theta \in \Theta\}$$

Exponential family networks (EFNs)

- EFNs are comprised of two networks :
 - density network: $z = g_\theta(\omega)$
 - parameter network: $\theta = f_\phi(\eta)$
- The parameter network (horizontal) is a fully connected neural network mapping $f_\phi : H \rightarrow \Theta$.
- EFNs learn approximations $\mathcal{Q}_\phi \subset \mathcal{M}$ of exponential family models \mathcal{P} , so that $\mathcal{Q}_\phi \approx \mathcal{P}$, where $\mathcal{Q}_\phi = \{q_{f_\phi}(z; \eta) : \eta \in H\}$.



- For a given η , we minimize the KL divergence \mathcal{D} between the indexed distribution of \mathcal{P} and \mathcal{Q}_ϕ .

$$\mathcal{D}(q_\phi(z; \eta) || p(z; \eta)) = \mathbb{E}_{q_\phi} \left(\log q_\phi(z; \eta) - \eta^\top t(z) + \log(A(\eta)) \right)$$

We do this over a desired prior distribution $p(\eta)$,

$$\argmin_{\phi} \mathbb{E}_{p(\eta)} (\mathcal{D}(q_\phi(z; \eta) || p(z; \eta))) = \argmin_{\phi} \mathcal{D}(q_\phi(z; \eta)p(\eta) || p(z; \eta)p(\eta))$$

which corresponds to the loss below.

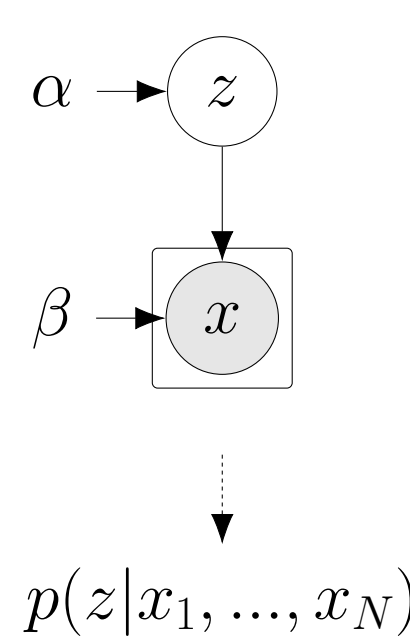
$$\mathbb{L}(\phi) = \frac{1}{K} \frac{1}{M} \sum_{k=1}^K \sum_{m=1}^M \left(\log q_0(g_{\theta_k}^{-1}(z^m)) + \sum_{\ell=1}^L \log |J_{g_\ell}^\ell(z^m)| - \eta_k^\top t(z^m) \right)$$

Intractable exponential families

- Nonconjugate priors yield intractable exponential families requiring computation for inference.

Example: Hierarchical Dirichlet

- Dirichlet prior: $z \sim \text{Dir}(\alpha)$

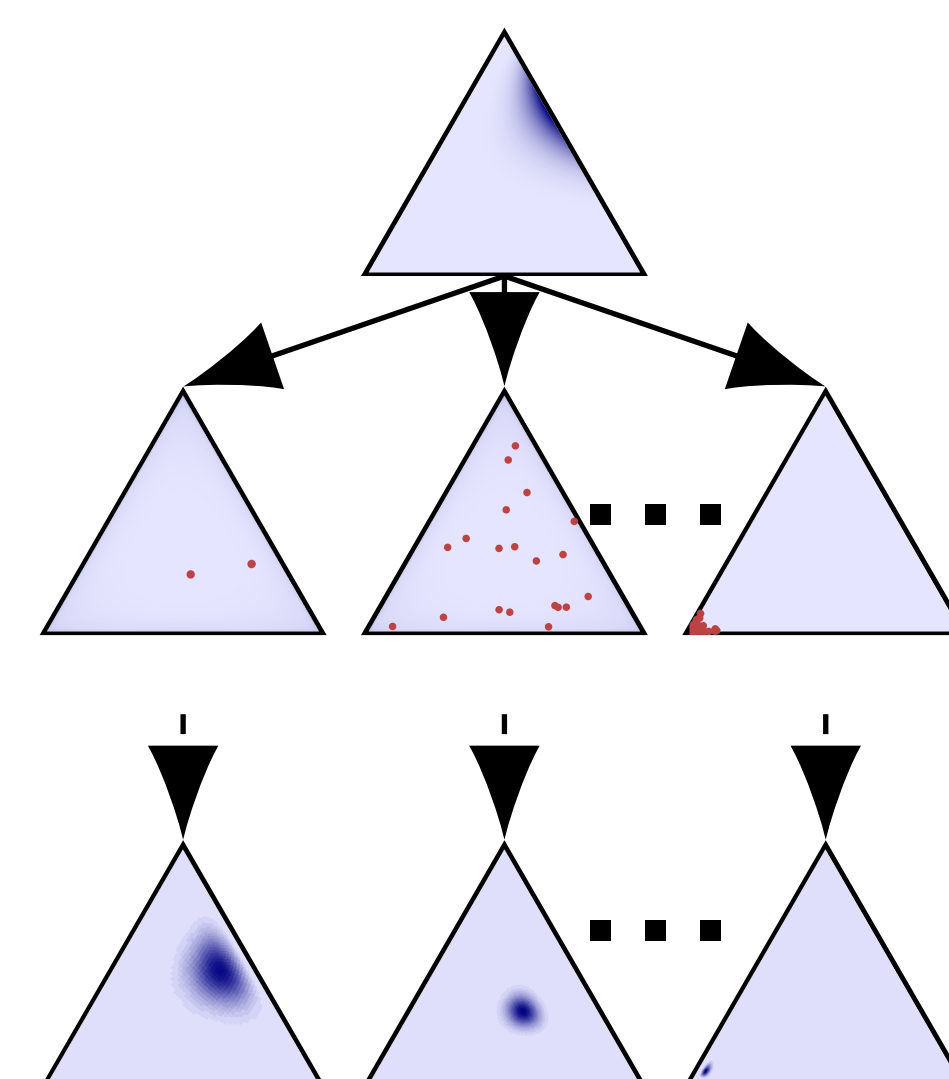


- iid Dirichlet draws: $x_i | z \sim \text{Dir}(\beta z)$

$$p(z | X) \propto \exp \{ \eta^\top t(z) \}$$

$$= \exp \left\{ \left[\begin{array}{c} \alpha - 1 \\ \sum_i \log(x_i) \\ -N \end{array} \right]^\top \left[\begin{array}{c} \log(z) \\ \beta z \\ \log(B(\beta a)) \end{array} \right] \right\}$$

- Consider a situation in which we want to do inference on the hierarchical Dirichlet model for three separate data sets (red dots, middle triangles) given a constant prior (top triangle).



- Rather than running variational inference independently for each dataset, with an EFN, we can

1. Compute $\eta = \left[\begin{array}{c} \alpha - 1 \\ \sum_i \log(x_i) \\ -N \end{array} \right]$ for each dataset.

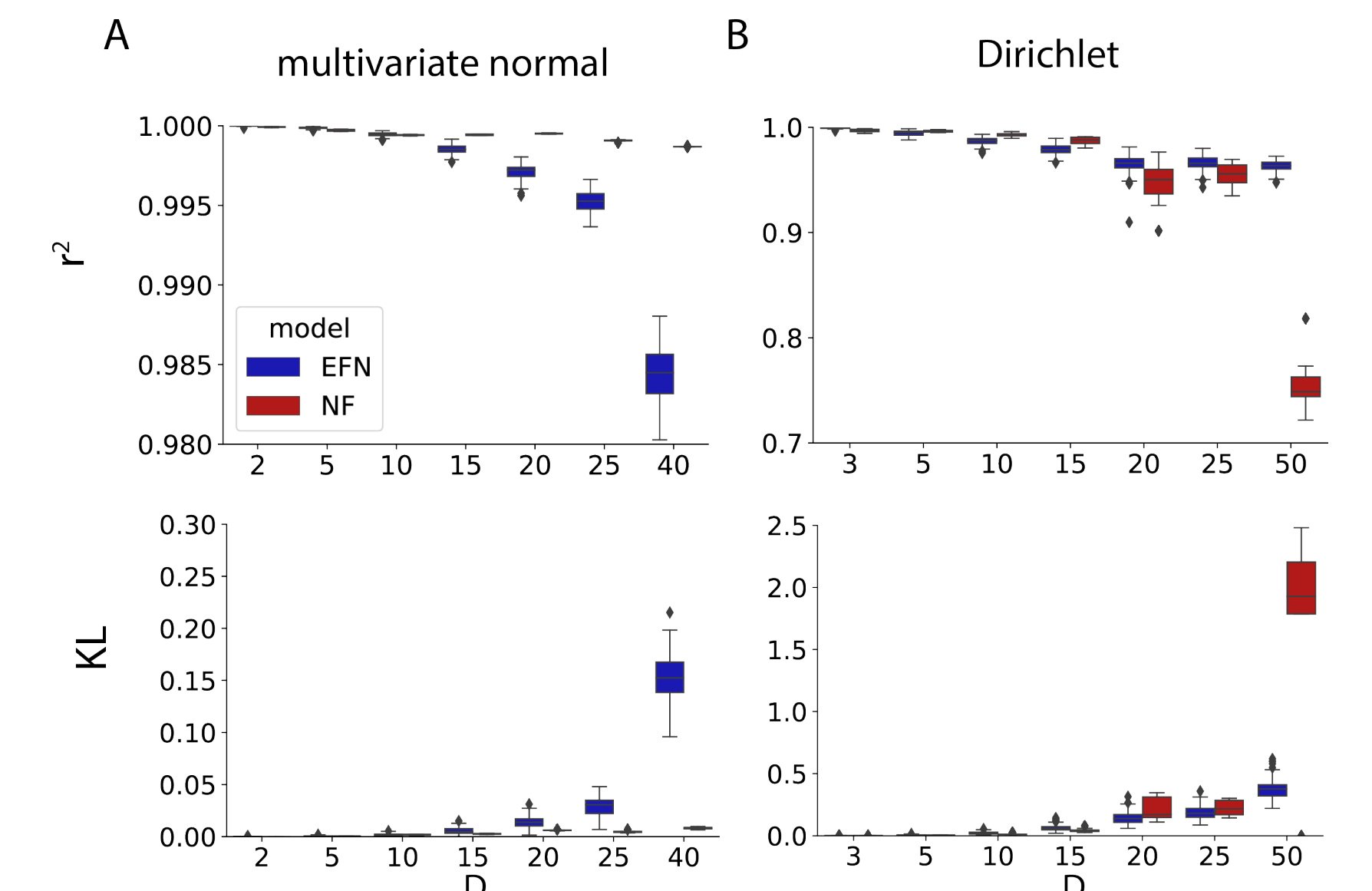
2. Compute $\theta = f_{\phi^*}(\eta)$ using the parameter network.

3. Sample from the posterior using density network $z = g_{f_{\phi^*}(\eta)}(\omega)$ (bottom triangles).

- By training an EFN for the hierarchical Dirichlet intractable exponential family, we are amortizing variational inference.

Scaling dimensionality

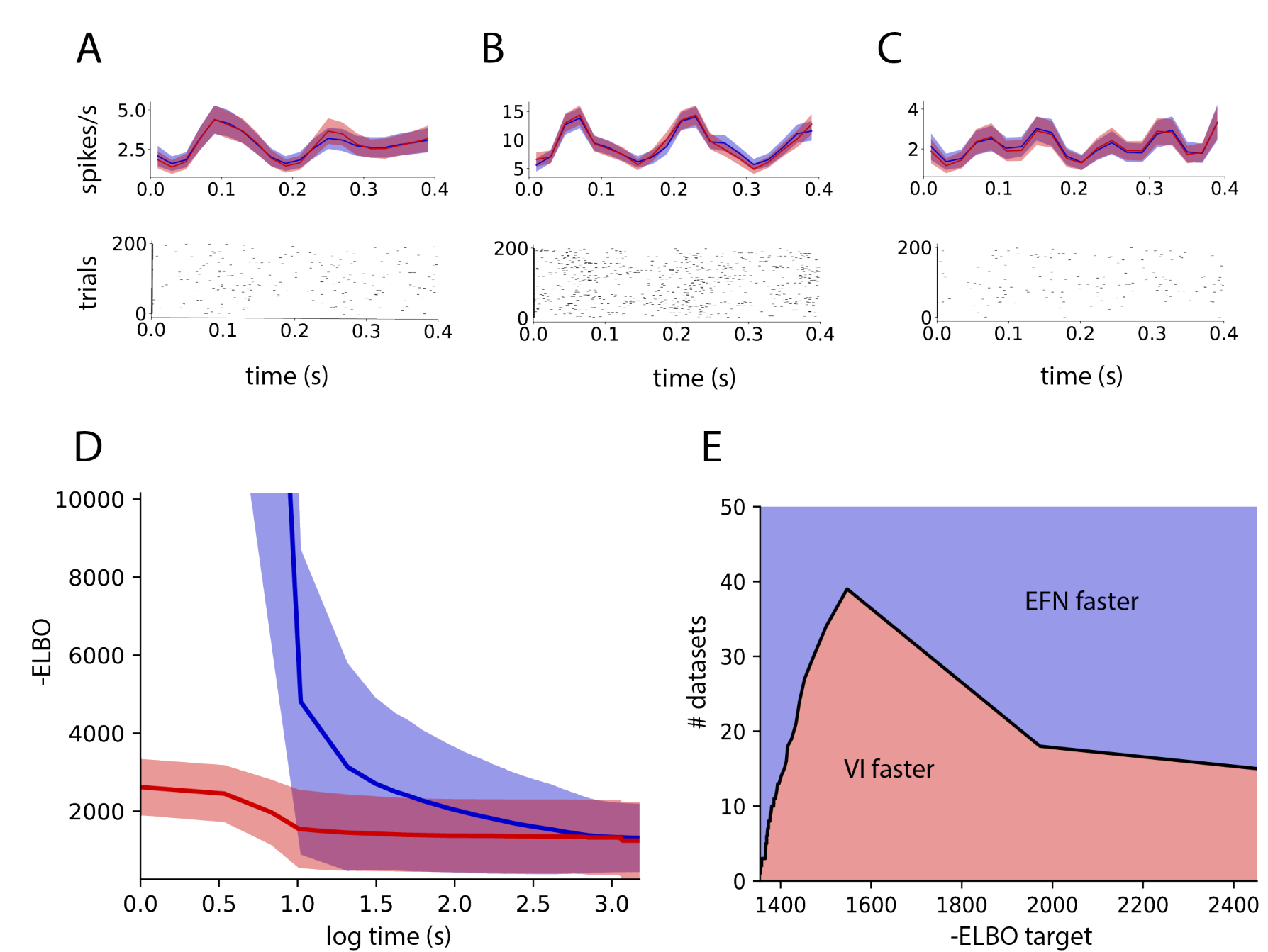
- EFN scales to 40-50 dimensions for ground truth exponential families.



- The regularization afforded by learning in a restricted model class \mathcal{Q}_ϕ results in better Dirichlet approximations in high dimensions.

Lookup posterior inference with neural data

- The log-Gaussian Poisson model is a popular intractable exponential family model used in neuroscience to represent neural spike emissions over a trial.
- If we want to run inference on the 2,964 datasets of 6.25Hz drift grating responses from [1], we can save a tremendous amount of computation using EFN (red) compared to independent runs of VI (blue).



Summary

- We learn exponential family models using a deep generative network, the parameters of which are the image of the natural parameters under another deep neural network.
- We demonstrated high quality empirical performance across a range of dimensionalities with the potential for better approximations when learning in a restricted model space.
- Finally, we show computational savings afforded by immediate posterior inference lookup.

References 1. Smith, Matthew A., and Adam Kohn. "Spatial and temporal scales of neuronal correlation in primary visual cortex." *Journal of Neuroscience* 28.48 (2008): 12591-12603.

Acknowledgements

NSF Graduate Research Fellowship, DGE-1644869, McKnight Endowment Fund, NIH NINDS 5R01NS100066, Simons Foundation 542963, NSF 1707398, The Gatsby Charitable Foundation