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# Learning Exponential Families

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## Abstract

[SLOPPY NOTES STAGE JUST TO GET THOUGHTS DOWN]

Recently much attention has been paid to probabilistic models defined by a deep neural network transformation of a simpler random variable; these implicit generative models have been used to great success across variational inference, generative modeling of complex data types, and more. In essentially all of these settings, the model is specified by the network architecture, and a particular member of that model is chosen to minimize some loss (be it adversarial or information divergence)

We treat the problem of learning an exponential family – the model itself, rather than the typical setting of learning a particular member of that model.

Many intractable distributions encountered in machine learning belong to exponential families. In rare cases these distributions are tractable due to either known conjugacy in the problem setup (such as the normal-inverse-Wishart), or due to careful numerical work historically that has made these distributions computationally indistinguishable from tractable (eg the Dirichlet).

## 1 Introduction

*People use lots of implicit generative models:*

Across machine learning, including ABC [?], GANs [1], VAEs [2, 3], and their many follow-ons (too numerous to cite in any detail), models that specify a distribution via the nonlinear transformation of latent random variable. We prefer and use the terminology of [4], calling such a distribution an *implicit generative model*, defined as:

something like eq 1 and 2 in Mohamed:2016aa, defining  $q_{\theta}(z)$

Also use the proper notation of the density implied by the pushforward measure of the function  $f_{\theta\#}$  if useful. Also reference to this being super standard and widespread [5]. The two central uses are at present generative distributions of interesting data types (as in GANs), and for variational inference. Regardless, all of these use cases specify a *model* (or variational family)  $\mathcal{Q} = \{q_{\theta} : \theta \in \Theta\}$ , and then minimize a suitable loss  $\mathcal{L}(q, p)$  over  $q \in \mathcal{Q}$ . In the case of VI  $p$  is the posterior (or the unnormalized log joint) and  $\mathcal{L}$  is the *KL* divergence (or so called ELBO), in GAN  $p$  is the sample density of a (large) dataset and  $\mathcal{L}$  is the adversarial objective whose details do not matter here.

*All these learn a single member of a family*

Inherent in all the above approaches is an algorithmic procedure to select a *single* distribution  $q_{\theta}(z)$  from among the *model*  $\mathcal{Q}$ . Implicit in this effort is the belief that  $\mathcal{Q}$  is suitably general to contain the true distribution of interest, or at least an adequately close approximation.

*Here we learn the family*

We leverage the natural parameterization of exponential families to derive a novel objective that is amenable to stochastic optimization.

### 31 *A note on amortization*

32 Several have pointed out that these IGMs are in fact strictly less expressive than a mean field, at  
33 least in the conventional VI setting. See for example [http://dustintran.com/blog/variational-auto-](http://dustintran.com/blog/variational-auto-encoders-do-not-train-complex-generative-models)  
34 [encoders-do-not-train-complex-generative-models](http://dustintran.com/blog/variational-auto-encoders-do-not-train-complex-generative-models) (here I like the line “The neural network used in  
35 the encoder (variational distribution) does not lead to any richer approximating distribution. It is a  
36 way to amortize inference such that the number of parameters does not grow with the size of the data  
37 (an incredible feat, but not one for expressivity!) (Stuhlmüller et al., 2013)”). You have to optimize  
38 for every data point individually, or instead you get to do so in aggregate once in advance (at a much  
39 higher cost) and then recover that cost over future data points within that distribution (and hence the  
40 term amortization, though perhaps there is shared statistical power as well) Etc etc what we are doing  
41 here is *amortized* amortized inference, in the sense that we are amortizing not the data points, but the  
42 distribution itself.

43 REparameterization trick (Kingma and Welling (2013), Rezende et al. (2014) and Titsias and  
44 Lazaro-Gredilla 2014).. See also Archer 2015 / Gao 2016 for clean explanation.

45 Key for obvious norm flow connection but also a good bibliography and some good historical views  
46 to Dayan and Gershman and other people who did norm flows. <https://arxiv.org/pdf/1505.05770.pdf>

47 *Our contributions include:*

48 ...

49 This should not be confused with "Learning to learn by gradient descent by gradient descent"  
50 (Andrychowicz et. al. 2016) and similar works.

51 ...

52 Important to distinguish carefully from VI. In a sense VI does parameterize a family: given data,  
53 you get local variational parameters and that parameterizes a density (like a regular VAE). Inference  
54 networks are exclusively used to data to amortize with a global set of parameters a variational  
55 distribution, not a model. Of course it is in a sense a model, but that's a bunch of normals. The  
56 sampling mechanism is easy (Gaussian).

57 *Our results demonstrate*

58 ...

## 59 **2 Learning exponential families**

60 *Why this is important*

61 Exp fams are awesome and fundamental []. Also [?] rightly point out that many many inference  
62 problems can be cast as exponential families. Can we cast the VAE encoder network as a suitable  
63 exp fam... sure I think that's right; the network parameters of  $z$  form the statistics, and then the  
64 observations are  $\eta$ 's.

65 *Why this is coherent*

66  $\Theta$  defines quite a big  $\mathcal{Q}$ , and indeed the subject of compressibility, generalization, etc is of keen  
67 interest to many [?]. So actually the space of distributions is quite large, and in many cases certainly  
68 larger than it needs be. Why? Well, we know precisely the parameter space of the exponential family;  
69 it is defined by the *natural* parameters  $\eta \in \mathbb{R}^p$  (or whatever we choose there).

70 Note somewhere that the natural parameter space needs to be considered in general. That is, not all  $\eta$   
71 lead to a valid distribution (standard fact, see for example Wainwright and Jordan 08). In practice  
72 that's not often a problem, as the space is known for most distributions one uses, and when one  
73 composes them in a posterior scheme (for example), this is inherited (eg the normal covariance...).

74 So we skip that here. But yes in general that needs to be considered.

75 *Figure 1*

76 Figure of model space. Yeah that's good. Then graphical model. Note that perhaps  $\mathcal{Q}$  is too big,  
77 and a simpler model space (the  $\|\eta\|$  dimensional subspace of  $\Theta$ ) would be better for the usual  
78 robustness/generalization reasons.

79 *Aside*

80 A neat idea is to ask if learning the  $\theta(\eta)$  network leads to better VI in terms of inference networks,  
81 since it is apparently appropriately regularized and can just take suff stats. That's testable if we have  
82 time.

83 *Why Flow Networks*

84 We choose flow networks [] and [] because duh. And "implicit generative models aka density  
85 networks" (or rather, density networks are the instantiation of an IGM with deep nets, which is  
86 effectively synonymous these days. Gibbs and MacKay Density Networks 1997! And invertible  
87 networks In that vein probably definitely cite invertible deep nets in general: Baird et al IJCAI 2005,  
88 Ripple and Adams 2013 . Note that what norm flows (the Rezende/Mohamed stuff specifically)  
89 did is make it tractable and scalable and in the modern VAE style. That makes these comparisons  
90 legitimate and apples to apples. Any generalization of this is also dandy though, so could use a mean  
91 field approach (standard) or any of the things that go beyond mean field, either classically (*Saul*  
92 *and Jordan, 1996; Barber and Wiergerinck, 1999*); *this is called structured variational inference.*  
93 *Another way to expand the family is to consider mixtures of variational densities, i.e., additional*  
94 *latent variables within the variational family (Bishop et al., 1998).* or newer stuff [] [Tran Copula  
95 VI, Hoffman and Blei 2015].

96 As noted in norm flows paper: "The true posterior distribution will be more com- plex than this  
97 assumption allows for, and defining multi- modal and constrained posterior approximations in a scal-  
98 able manner remains a significant open problem in varia- tional inference."

99 Couch this in terms of normalizing flows though point out this is not strictly necessary. Note in  
100 particular Tabak, E. G. and Turner, C. V. A family of nonparametric density estimation algorithms.  
101 Communications on Pure and Applied Mathematics, 66(2):145?164, 2013. Tabak, E. G and Vanden-  
102 Eijnden, E. Density estimation by dual ascent of the log-likelihood. Communications in Mathematical  
103 Sciences, 8(1):217?233, 2010. A nice line from Rezende and Mohamed is: Thus, an ideal family of  
104 variational distributions  $q(z|x)$  is one that is highly flexible, preferably flexible enough to contain the  
105 true posterior as one solution. One path towards this ideal is based on the principle of nor- malizing  
106 flows (Tabak Turner, 2013; Tabak VandenEijnden, 2010).

107 *Related work / How close is this to norm flows or VAE*

108 In a restricted technical sense, rather close: VAE and other black box VI that uses reparameterization  
109 results in a conditional density  $q_\phi(z|x)$ . If we consider  $\eta$  as  $x$ , then sure yes the previous stuff specifies  
110 a model  $Q_{VAE} = \{q_\phi(z|x) : x \in X\}$ . But that's a little silly, and any way that is very often a normal  
111 family with variational parameters specified by (a deep function of)  $x$ . Much closer is Figure 2 in  
112 Rezende and Mohamed, where like here they use a network to index the *parameters* of the normalizing  
113 flow. In that case it's a function of  $x$  the observation, and as such that network is an inference network;  
114 here it's a function of  $\eta$  and as such is a parameter network. That's just nomenclature, so naturally  
115 the next question is do they differ at some other level. Yes, distinctly. The other term implied in a  
116 VI (or norm flow VAE style as they use) is the expected log joint  $E_{q_\phi(x)}(\log p_\theta(x, z))$ . Now sure  
117 that's a loss function on  $x, z$ , so then when we look at that same term in EFN we see  $E_{q_\phi(\eta)}(\eta^\top t(z))$ ,  
118 which sure also looks like a loss function on  $\eta, z$ . And yes, they are both unnormalized (in the sense  
119 that VI is an ELBO / joint  $p(x, z)$  and EFN lacks the normalizer because it's constant, so we're  
120 not getting a KL estimate). A picky difference is that the exp family doesn't really correspond to a  
121 proper unnormalized log joint (though I suppose it could), as there is not a prior on  $\eta$  in the objective  
122 (but is that just ignoring  $p(\eta)$  in our sampling scheme?). But yes if we want to be reductionist and  
123 pedantic [use nicer words] in general we could see this as a specific case where  $x = \eta$  and thus we  
124 are learning a family just as in the inference case. And for example we are giving in the bayesian  
125 logistic regression example full datasets for inference instead of single data points. To make this  
126 as close as possible, we write  $p(\eta|z) = \frac{1}{A(t(z))} \exp \{\eta^\top t(z)\}$ . That's the "likelihood" of an EFN in  
127 some wonky sense. So this reveals the mechanical differences: first,  $t(z)$  is not a deep generative  
128 model with parameters  $\theta$ , but rather it is a fixed set of sufficient statistics that define the exp fam.  
129 Next, there is no clear prior  $p(z)$ , which is critical to understanding how VI behaves (see Hoffman  
130 and Johnson ELBO surgery paper, also Duvenaud's <https://arxiv.org/pdf/1801.03558.pdf>). So yes  
131 there is a hand wavy sense in which EFN is a specific case of norm flow, but of course it is. And  
132 anyway norm flow is a specific case of a DNN architecture or Helmholtz machine or deep density  
133 network (Ripple and Adams). This is just rambling but good to have all perspective here. Ok so what

134 to do? First, then we need to produce really compelling results focusing on when learning an exp fam  
 135 is key. Second we need some very tight language to draw this distinction without seeming a small  
 136 tweak on normalizing flows. One way to do this is the restricted model class argument, a la Fig 7.2 in  
 137 Hastie and Tibshirani. Another is to actually produce a conditional exp fam, as in something indexed  
 138 on both  $x$  and  $\eta$ . Third, possible novelties in norm flows, like triple spinners or other better choices  
 139 than planar flows (yuck).

140 Another related work is that this is somehow the dual of MEFN, or a generalization of the dual  
 141 problem. In the wainwright and jordan sense of forward and backward mappings.

### 142 3 Results

#### 143 Chapter 1, Fig 1

144 Toy figure that demonstrates what we are doing and a simple example. Note this should probably not  
 145 be in Results but in the EFN section or similar. Ideas:

- 146 • value of a restricted model, see hastie tibshirani fig 7.2, or porbanz's batman version from  
 147 4400 slides. ... well that's a bit off topic. At least worth a mention in motivation.
- 148 • graphical model. yeah probably needed.
- 149 • network model. yeah probably needed.
- 150 • cartoon example three sets of natural parameters in, three dirichlet distributions out. Or  
 151 similar.

#### 152 Chapter 2: Fig 2 and 3 and 4 Ground truth toy examples, etc.

153 Fig 2. This says, it works in a sensible case (maybe Dirichlet 25 or NIW 10x10):

- 154 • training and test curves (probably both of these are needless since by def train equals test  
 155 here).
- 156 • both in  $r^2$  and in  $KL$  to ground truth.
- 157 •  $MMD$  p values? Can this help give specifics?

158 Fig 3. This says, it works across a range of Dirichlet and NIW (and perhaps not Gaussian). Sensitivi-  
 159 ties

- 160 • dimensionality of dir and NIW
- 161 • choices of  $K, M$  (is this really needed)
- 162 • key comparison to baseline of VI (doing this specifically for  $K=1$  but a fixed  $K$ , possibly  
 163 with no parameter network because it's unnecessary). The key is to show that it works  
 164 almost as well as VI in the specific case, but of course VI can't generalize. And when I say  
 165 VI I don't really mean VI, I mean just learning a specific member of the exp fam.

166 Fig 4. [This idea was Fig 5 in disguise; see below. Currently no need for this figure].

#### 167 Chapter 3: Fig 5 and 6

168 Fig 5. The intractable posterior inference example. **Key real data result.** Learn the full posterior  
 169 family for some problem (see ideas below). Then get some data  $X$ . Then find the posterior distribution  
 170 for that data by indexing the natural parameters (as in, just plugging in the correct choice of  $\eta$ , which  
 171 is after all some function of the prior and  $X$ ). That gives the EFN posterior  $q(z|X)$ . (Possible  
 172 preceding figure: show its properties, show a low-d picture, show its non-Gaussianity). Now, as  
 173 Alternative 1 do full norm flow variational inference (explore all of  $\phi$  space with the full flow network  
 174 model  $\mathcal{Q}$ ), which is to say  $\arg \min_{\phi} KL(q_{\phi}||p)$ : the key difference here is that, while you have the  
 175 *same exact* flow network architecture, now you have to optimize over  $\phi$  with a limited single dataset.  
 176 As Alternative 2, be literal to Figure 2 of the Norm Flow VI paper, give the sufficient statistics of  
 177 that  $K=1$  dataset, and learn an EFN from scratch. This alternative is important because it is the most  
 178 specific (but kind of annoying, hence alternative 1) interpretation of norm flow VI paper.

179 Now, PANEL A of this figure shows performance as a size of the dataset. This will likely show  
 180 that when the dataset gets small, this "traditional VI" will get arbitrarily bad (can't learn a network);

eventually, there will be so much data that the VI will match or outperform the EFN... outperform because VI can focus specifically on this distribution rather than over the whole family, so the EFN has less effective data for this  $\eta$  (but not because it has a broader range of models, since we believe the EFN contains the closest member). Alternative 2 should do shittier across the board than alt 1, I think? Performance metric should be ELBO on some held out data or something like that (it's a posterior, so log likelihood doesn't really make sense). Test data anyway. Check VI papers for usual metrics. PANEL B of this figure shows performance as dimension of the problem grows. Pick some middle dataset size, then repeat same performance metric as in Panel A for a range of dimensionalities of the exponential family. VI will generalize to test data worse and worse as dimensionality grows, but EFN will learn the family less well on its computational budget. This could go either way but will be interesting regardless. I suppose we should also have those panels for training data. A key point to make here is that one great virtue of EFNs is is learning a restricted model, which should demonstrate the usual bias-variance tradeoff (see for example Hastie and Tibshirani book, Fig 7.2). Maybe that's Panel A. Or Figure 4 is bias-variance and some sample posteriors in 2-d (showing how nicely it works), and then Fig 5 is the above performance, with both train and test. Notice one pain here is that Panel B requires training a new EFN at every dimensionality. Sorry.

This will be for one real example  $X$ . As such, to get error bars, just take a big dataset and randomly subsample. Then the posterior performance is really for that very dataset, so the sem is coherent and the right thing to calculate/show. Important to clarify that doing so *does not* test how well this does across the entire exp fam, but just this one posterior. To test that, we do it in simulation: generate *many datasets*  $X$ , then do the above for every one of them. Same computation for EFN (since its just plugging in a dataset), but VI alternatives 1 and 2 now need to be rerun for every dataset. And it's still simulated data, not really offering something fundamentally more than Fig 3 (well ok it's an intractable model, but I'm not sure that offers so much).

Fig 5. Heaps of examples with conditional iid exp fams. Math details of that pending. Some cool examples:

- Censored data. normal prior, censored normal observations, what is posterior distribution on mean? Lots of work in that.
- Truncated data. truncated mvn prior, with some observations thereafter, what is posterior? (Does this work?...)
- Poisson/Bern "process" data. Phony process like in neuro, normal prior on log intensity (ooh maybe that's not an exp fam prior), then a "spike train" of bern or poisson count observations
- multivariate t with inverse wishart prior or something like that. That's neat but doesn't have great "oh yeah people do care about that problem" recognition. Seems contrived.
- check MKB book for other cool MV distributions. (Marshall-Olkin)... seems contrived.
- Elliptically contoured prior with some conditionally iid exp fam observations. People in ML like elliptical distributions.
- von Mises-Fisher distribution, eg <http://www.jmlr.org/papers/volume6/banerjee05a/banerjee05a.pdf> or <https://arxiv.org/pdf/1605.00316.pdf>, but again not clustering (see below), since it's a local latent variable problem then.s
- Note: a whole heap of models don't quite fit comfortably here.
  - Bayesian Logistic Regression. This is an intractable exp fam in the desired sense, but the natural parameter (when parameterized) depends on  $x_i$ . Thus, it grows with every datapoint, or put differently it's a diff exp fam for every dataset. No bueno. This is then true of GLMs, so those are out too.
  - Latent Dirichlet Allocation. Local variational parameters mean that the exp fam grows with datasize. That means that the posterior is already too big for uninteresting sizes of LDA. This is then true of hierarchical models with local latent variables in general.

Fig 6. The Killer real data. Perhaps Gibbs or Markov Random Field. Learn it, then pick some  $\eta$ , then show samples from it. Can this look interesting? Some thoughts...

Criteria:

- Needs to be an exp fam.

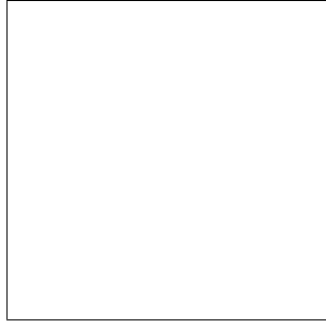


Figure 1: possibly Fig 7.2 bias-variance tradeoff and then benefit of a restricted model from Hastie Book, or similar from W4400 (ask PO for batman permission).

Table 1: Sample table title

Part		
Name	Description	Size ( $\mu\text{m}$ )
Dendrite	Input terminal	$\sim 100$
Axon	Output terminal	$\sim 10$
Soma	Cell body	up to $10^6$

- Needs to be a forward exp fam. As in, not fit to data, because we don't have  $\mu$  parameters, we have  $\eta$  parameters.
- "real data" is a misnomer, since we are not doing VI or similar. Really we want an exp fam that is real and somehow useful in its own right, and that people want to sample from.
- Reminder: we will *always* be comparing to "well normally you can do this with learning a *single* distribution in the min  $KL(q||p)$  sense. That's fine. The point is we can learn the whole family, then choose and sample, vs just one by one.
- something hard to sample will be key, since the "toy" results will have used things we already "know" how to sample, like NIW or Dirichlet.

Ideas:

- Fancy Exp Fam like Marshall-Olkin. Yeah but who really cares about this esoteric distribution? It doesn't look cool visually either.
- Ising models: classic, bw images, but gross NP-Hard Cooper 1990.
- Potts model: great because failure of MCMC (Gibbs sampling) here is at least locally well known from Geman and Geman 1984 through Sudderth correcting this (see Gibbs sampler slides from Advanced ML, Peter's part). But that is kind of a failure example, not an interesting one (MRFs are smoothness prior, not segmentation prior). Also both Potts and Ising are NP-hard Cooper 1990 The Computational Complexity of Probabilistic Inference Using Bayesian Belief Networks
- Markov Random Fields / Gibbs Random Fields (same, by Hammersley Clifford theorem). Yes this is cool: image distributions, texture distributions. Can show wild diff sets of textures, none of which require any sampling or any such thing. Can we make this super intractable from an MCMC perspective? Need to read on how sampling is done there. Erik Sudderth and his phd thesis are likely good resources.
- Gatys and Simoncelli texture stuff (see for example MEFN paper for refs); those are interesting distributions on textures, or specified moments. Can then just sample from this family.

```
\usepackage[pdftex]{graphicx} ...
\includegraphics[width=0.8\linewidth]{myfile.pdf}
```

## Acknowledgments

Use unnumbered third level headings for the acknowledgments. All acknowledgments go at the end of the paper. Do not include acknowledgments in the anonymized submission, only in the final paper.

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- Stuff on sampling from Gibbs distributions (max ent models), and sampling from exp fams generally, with MCMC and such.
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- Hoffman et al 2013 SVI
- From Blei review on VI. The development of variational techniques for Bayesian inference followed two parallel, yet separate, tracks. Peterson and Anderson (1987) is arguably the first variational procedure for a particular model: a neural network. This paper, along with insights from statistical mechanics (Parisi, 1988), led to a flurry of variational inference procedures for a wide class of models (Saul et al., 1996; Jaakkola and Jordan, 1996, 1997; Ghahramani and Jordan, 1997; Jordan et al., 1999). In parallel, Hinton and Van Camp (1993) proposed a variational algorithm for a similar neural network model. Neal and Hinton (1999) (first published in 1993) made important connections to the expectation maximization (EM) algorithm (Dempster et al., 1977), which then led to a variety of variational inference algorithms for other types of models (Waterhouse et al., 1996; MacKay, 1997).
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