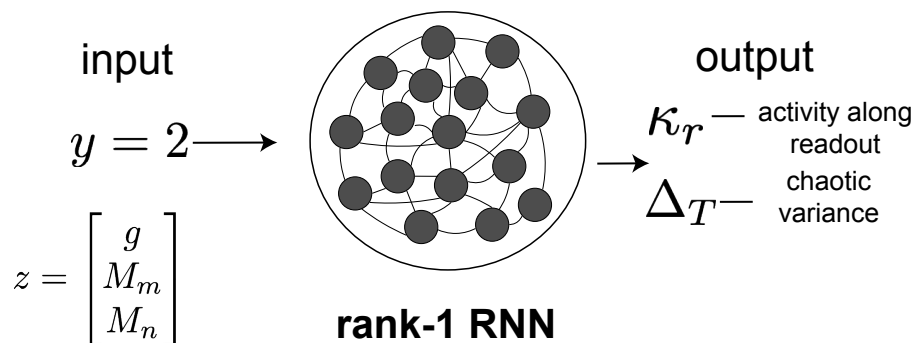
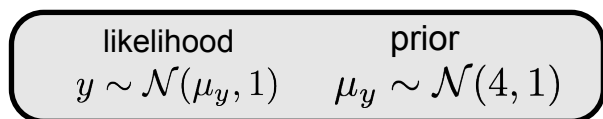


A

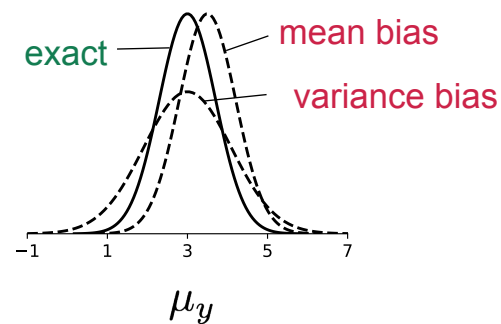
# Gaussian posterior conditioning

RNN assumes

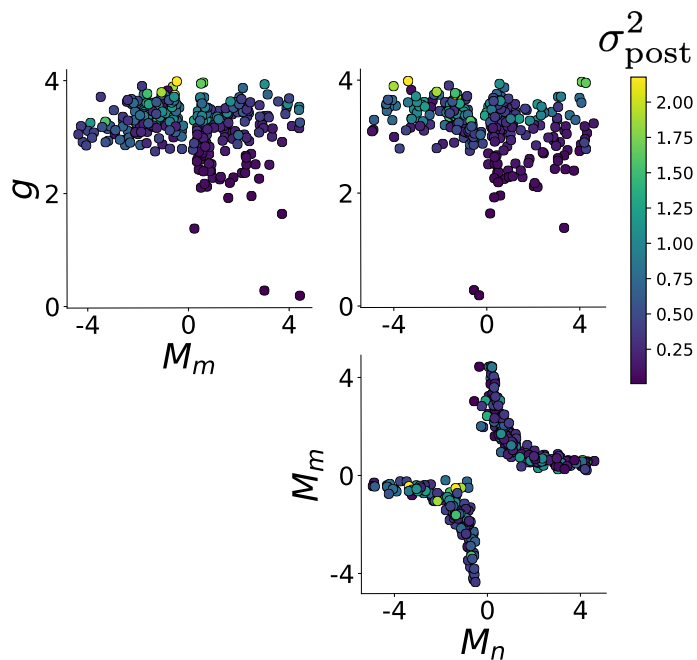
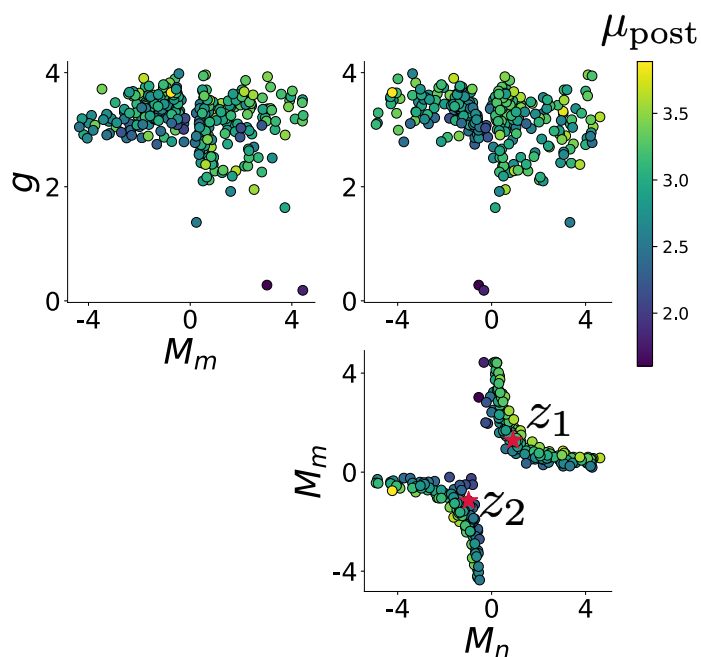


estimated posterior

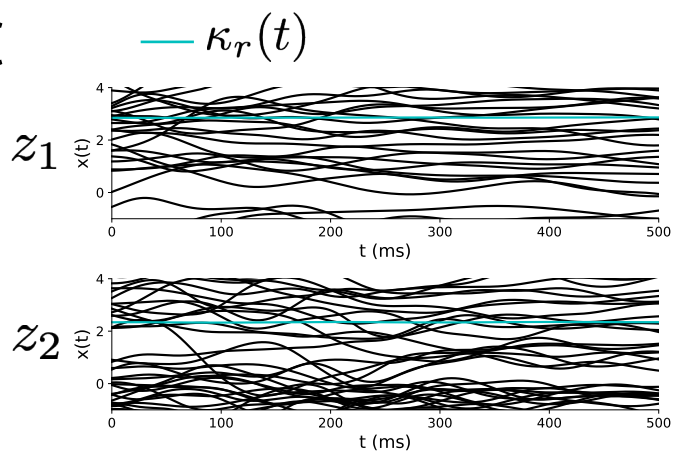
$$p(\mu_y | y) = \mathcal{N}(\mu_{\text{post}} = \kappa_r, \sigma_{\text{post}}^2 = \Delta_T)$$



B



C



D

