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Artificial Neural Networks
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Two-layer perceptron (2020)

```
clear all
M1 = 8;
M2 = 4;
step = .02;
numRuns = 5000;

% training variables
train = readmatrix('training_set.csv');
X = train(:,1:2);
t = train(:,3);
pVal = length(X);
w{1} = -.2 + .4.*rand(M1,2);
w{2} = -.2 + .4.*rand(M2,M1);
w{3} = -.2 + .4.*rand(1,M2);
theta{1} = zeros(M1,1);
theta{2} = zeros(M2,1);
theta{3} = 0;
B{1} = zeros(M1,pVal);
B{2} = zeros(M2,pVal);
B{3} = zeros(1,pVal);
V{1} = zeros(M1,pVal);
V{2} = zeros(M2,pVal);
V{3} = zeros(1,pVal);
sigO = zeros(1,pVal);
err{1} = zeros(M1);
err{2} = zeros(M2);
err{3} = zeros(1);
C = zeros(1,numRuns);

% testing variables
test = readmatrix('validation_set.csv');
testInput = test(:,1:2);
testTarget = test(:,3);
pValTest = length(testInput);
wGood{1} = zeros(M1,2);
wGood{2} = zeros(M2,M1);
wGood{3} = zeros(1,M2);
thetaGood{1} = theta{1};
thetaGood{2} = theta{2};
thetaGOod{3} = theta{3};
BTest{1} = B{1};
BTest{2} = B{2};
BTest{3} = B{3};
VTest{1} = V{1};
VTest{2} = V{2};
VTest{3} = V{3};
sigOTest = sigO;
CTest = zeros(1,numRuns);

numIter = 0;
for iRun=1:numRuns
    % calc Bs, Vs, and final output sigO
    for mu=1:pVal
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    B{1}(:,mu) = w{1} * X(mu,:)' - theta{1};
    V{1}(:,mu) = tanh(B{1}(:,mu));
    for L=2:3
        B{L}(:,mu) = w{L} * V{L-1}(:,mu) - theta{L};
        V{L}(:,mu) = tanh(B{L}(:,mu));
    end
    if V{3}(:,mu) >= 0
        sigO(:,mu) = 1;
    else
        sigO(:,mu) = -1;
    end
    C(iRun) = C(iRun) + abs(sigO(:,mu) - t(mu));
end
C(iRun) = C(iRun)/(2*pVal);

for numFed=1:pVal
    numIter = numIter + 1;
    iRand = randi(pVal,1);
    % calc local fields, Vs
    B{1}(:,iRand) = w{1} * X(iRand,:)' - theta{1};
    V{1}(:,iRand) = tanh(B{1}(:,iRand));
    for L=2:3
        B{L}(:,iRand) = w{L} * V{L-1}(:,iRand) - theta{L};
        V{L}(:,iRand) = tanh(B{L}(:,iRand));
    end
    % calc errors
    err{3} = (t(iRand)-V{3}(:,iRand)) * (1 - tanh(B{3}(:,iRand))^2);
    for L=flip(1:2)
        err{L} = w{L+1}' * err{L+1} .* (1 - tanh(B{L}(:,iRand)).^2);
    end
    % update weights and biases
    w{1} = w{1} + step * err{1} * X(iRand,:);
    w{2} = w{2} + step * err{2} * V{1}(:,iRand)';
    w{3} = w{3} + step * err{3} * V{2}(:,iRand)';
    theta{1} = theta{1} - step * err{1};
    theta{2} = theta{2} - step * err{2};
    theta{3} = theta{3} - step * err{3};
end

% calc C for test data
for i=1:pValTest
    BTest{1}(:,i) = w{1} * testInput(i,:)' - theta{1};
    VTest{1}(:,i) = tanh(BTest{1}(:,i));
    for L=2:3
        BTest{L}(:,i) = w{L} * VTest{L-1}(:,i) - theta{L};
        VTest{L}(:,i) = tanh(BTest{L}(:,i));
    end
    if VTest{3}(:,i) >= 0
        sigOTest(:,i) = 1;
    else
        sigOTest(:,i) = -1;
    end
    CTest(iRun) = CTest(iRun) + abs(sigOTest(:,i) - testTarget(i));
end
CTest(iRun) = CTest(iRun)/(2*pValTest);
```

```
    if mod(iRun,10) == 0
        plot(CTest)
        drawnow
    end
    if CTest(iRun) < .12 % store good weights and biases
        for L=1:3
            wGood{L} = w{L};
            thetaGood{L} = theta{L};
        end
    end
    if CTest(iRun) < .115 % stopping criteria
        break
    end
end
```