Last update: May 2025

Duc-Cuong VU, BcS.

Email	vdcuong2002 [at] gmail.com
Phone	+84 865 280 802
Address	Giao Thuy, Nam Dinh, Vietnam
Sites	https://cuong-vd.github.io

Education

Master of Science in Automation and Control *(Jul 2024 - present)*
School of Electrical - Electronics Engineering,
Hanoi University of Science and Technology (HUST), Hanoi, Vietnam

- **Research project:** *Design control structures for Parallel Platforms in Maritime applications*
- **Funded by:** *Master, PhD Scholarship Programme of Vingroup Innovation Foundation (VINIF)*

Bachelor of Science in Automation and Control *(Oct 2020 - Mar 2024)*
School of Electrical - Electronics Engineering,
Hanoi University of Science and Technology (HUST), Hanoi, Vietnam

- **Excellent degree**, GPA: 3.71/4. Finished the 4-year BSc program in **just 3.5 years**.
- **Ranking:** 27/499 in the same cohort.
- **Bachelor Thesis:** *Balancing, motion planning, and tracking control for ballbot systems.*
  Thesis score: 9.9/10 - The best thesis defense

Work Experience

Research Assistant *(Oct 2021 - present)*

The Mechatronics Engineering Group,
School of Electrical - Electronic Engineering,
Hanoi University of Science and Technology (HUST), Hanoi, Vietnam

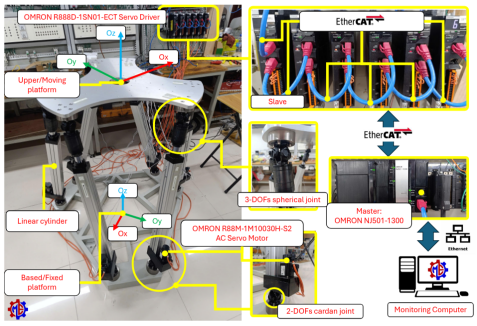
- **Research topics:** Automation, Control Design, Robotics, Multi-agent Systems, Modeling and Simulation, Experiment systems.
- **Supervisor:** Assoc.Prof.PhD. Tung Lam Nguyen (lam.nguyentung [at] hust.edu.com).
- **Skills acquired:** hardware design, numerical simulation and modeling, analysis, and interpretation of results, study conception, and design, draft manuscript preparation, ...

Projects

Member/Researcher *(Mar 2025 - Dec 2025)*

Advanced Control of a Ship-Mounted Stewart Platform for Marine Applications

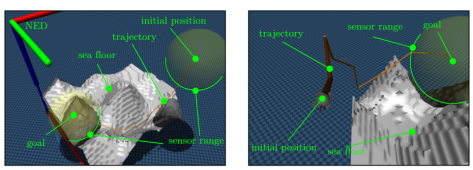
- Field: Marine Robotics and Control Systems.
- International Collaboration of Korea Institute of Science and Technology (KIST) and Institute for Control Engineering and Automation (ICEA, HUST).
- Supervisors: PhD. Minh Nhat Vu and Assoc.Prof.PhD. Tung Lam Nguyen



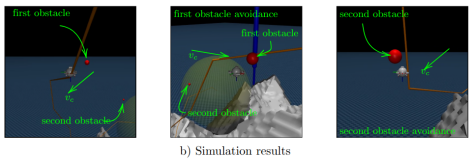
Member/Researcher *(Jan 2025 - Dec 2027)*

Robot navigation system integrating sensor network and wireless communication

- Field: Robotics and Control systems.
- Funded by Hanoi University of Science and Technology.
- Supervisors: PhD. Duc Chinh Hoang and Assoc.Prof.PhD. Tung Lam Nguyen.

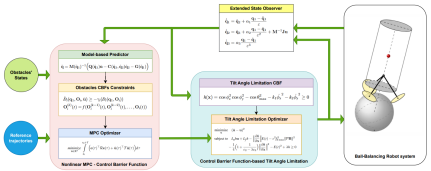


a) Simulation setup



b) Simulation results

Highlighted Publications

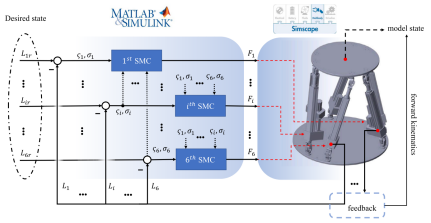


Journal IEEE Acess (ISI-Q2) (2025)

CBFs-based Model Predictive Control for Obstacle Avoidance with Tilt Angle Limitation for Ball-Balancing Robots

Minh Duc Pham, Duc Cuong Vu, Thi Thuy Hang Nguyen, Thi Van Anh Nguyen, Minh Nhat Vu, and Tung Lam Nguyen

DOI: 10.1109/ACCESS.2025.3567474

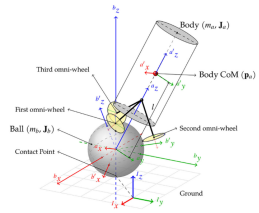


Journal Results in Engineering (ISI-Q1) (2025)

A novel approach of Consensus-based Finite-time Distributed Sliding Mode Control for Stewart platform manipulators motion tracking

Duc Cuong Vu, Danh Huy Nguyen, and Tung Lam Nguyen

DOI: 10.1016/j.rineng.2024.103872



Journal International Journal of Robust and Nonlinear Control (ISI-Q1) (2024)

Time-optimal trajectory generation and observer-based hierarchical sliding mode control for ballbots with system constraints

Duc Cuong Vu, Minh Duc Pham, Thi Thuy Hang Nguyen, Thi Van Anh Nguyen, and Tung Lam Nguyen

DOI: 10.1002/rnc.7358

Conferences

IEEE 12th International Conference on Control, Automation and Information Sciences (IEEE ICCAIS 2023)

Hanoi, Vietnam

2024 International Conference on Advanced Technologies for Communications (ATC2024)

Hanoi, Vietnam

International Conference on Intelligent Systems and Networks (Springer ICISN 2023)

Hanoi, Vietnam

Honours & awards

Master, PhD Scholarship Programme

Vingroup Innovation Foundation (VINIF)

Best Thesis Defense Award

Hanoi University of Science and Technology