

IT3280 –THỰC HÀNH KIẾN TRÚC MÁY TÍNH

Tuần 10:

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Assignment 3:

Code:

```
.eqv HEADING 0xffff8010      # integer: an angle between 0 and 359
                                # 0 : North (up)
                                # 90: East (right)
                                # 180: South (down)
                                # 270: West (left)

.eqv MOVING 0xffff8050        # boolean: whether or not to move

.eqv LEAVETRACK 0xffff8020    # boolean: (0 or non-0)
                                # whether or not to leave a track

.eqv WHEREX 0xffff8030        # integer: current x-location of Marsbot

.eqv WHEREY 0xffff8040        # integer: current y-location of marsbot

.text
#chuyển bot về nơi nhìn rõ được tam giác

main:  addi $a0, $0, 130 # Marsbot rotates 180 * running and start running
        jal ROTATE
        nop
        jal GO
        nop

sleep:  addi $v0, $0, 32 # keep running by sleeping in 1000ms
        li $a0, 1000
        syscall

#-----
        jal STOP

goline1: addi $a0, $0, 180 # Marsbot rotates 90 * running and start running
        jal ROTATE
        nop
        jal TRACK
```

```

        nop
        jal GO
        nop
sleep1: addi $v0, $0, 32 # keep running by sleeping in 3000ms
        li $a0, 3000
        syscall

#-----

        jal STOP
goline2: addi $a0, $0, 90 # Marsbot rotates 90 * running and start running
jal ROTATE
        nop
        jal UNTRACK
        nop
        jal TRACK
        nop
        jal GO
        nop
sleep2: addi $v0, $0, 32 # keep running by sleeping in 4000ms
        li $a0, 4000
        syscall

#-----

        jal STOP
goline3: addi $a0, $0, 310 # Marsbot rotates 90 * running and start running
        jal ROTATE
        nop
        jal UNTRACK
        nop
        jal TRACK
        nop
        jal GO
        nop
sleep3: addi $v0, $0, 32 # keep running by sleeping in 6100ms

```

```

        li $a0, 6100

        syscall

#-----

end_main: jal STOP

        nop

        j end

#-----

# GO procedure, to start running
# param[in] none
#-----

GO: li $at, MOVING # change MOVING port

    addi $k0, $zero, 1 # to logic 1,
    sb $k0, 0($at) # to start running

    nop

    jr $ra

    nop

#-----

# STOP procedure, to stop running
# param[in] none
#-----

STOP: li $at, MOVING # change MOVING port to 0

    sb $zero, 0($at) # to stop

    nop

    jr $ra

    nop

#-----

# TRACK procedure, to start drawing line
# param[in] none
#-----

TRACK: li $at, LEAVETRACK # change LEAVETRACK port

    addi $k0, $zero, 1 # to logic 1,
    sb $k0, 0($at) # to start tracking

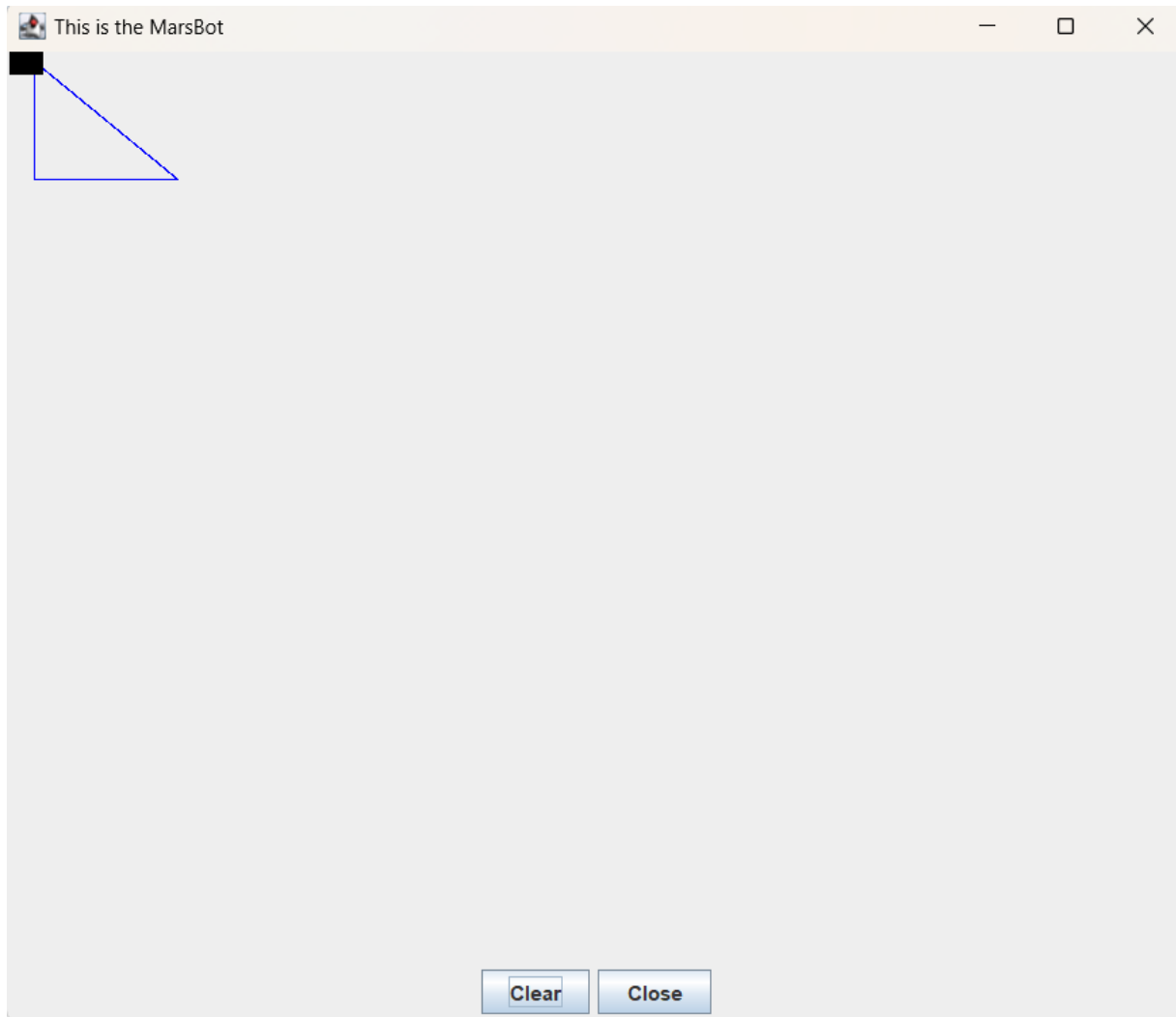
```

```

        nop
        jr $ra
        nop
#-----
# UNTRACK procedure, to stop drawing line
# param[in] none
#-----
UNTRACK:li $at, LEAVETRACK # change LEAVETRACK port to 0
        sb $zero, 0($at) # to stop drawing tail
        nop
        jr $ra
        nop
#-----
# ROTATE procedure, to rotate the robot
# param[in] $a0, An angle between 0 and 359
# 0 : North (up)
# 90: East (right)
# 180: South (down)
# 270: West (left)
#-----
ROTATE: li $at, HEADING # change HEADING port
        sw $a0, 0($at) # to rotate robot
        nop
        jr $ra
        nop
end:

```

Result:



Assignment 4:

Code:

```
.eqv KEY_CODE 0xFFFF0004 # ASCII code from keyboard, 1 byte
.eqv KEY_READY 0xFFFF0000 # =1 if has a new keycode ?
# Auto clear after lw

.eqv DISPLAY_CODE 0xFFFF000C # ASCII code to show, 1 byte
.eqv DISPLAY_READY 0xFFFF0008 # =1 if the display has already to do
# Auto clear after sw

.text

    li $k0, KEY_CODE
    li $k1, KEY_READY
    li $s0, DISPLAY_CODE
```

```

        li $s1, DISPLAY_READY

        li $t6, 0

        li $t5, 4

loop: nop

WaitForKey: lw $t1, 0($k1) # $t1 = [$k1] = KEY_READY

            nop

            beq $t1, $zero, WaitForKey # if $t1 == 0 then Polling

            nop

#-----

ReadKey: lw $t0, 0($k0) # $t0 = [$k0] = KEY_CODE

            nop

#-----

WaitForDis: lw $t2, 0($s1) # $t2 = [$s1] = DISPLAY_READY

            nop

            beq $t2, $zero, WaitForDis # if $t2 == 0 then Polling

            nop

#-----

ShowKey: sw $t0, 0($s0) # show key

            nop

#-----

#check exit

        beq $t0, 'e', continue_fake

        beq $t0, 'x', checkx

        beq $t0, 'i', checki

        beq $t0, 't', checkt

        j continue

continue_fake2: addi $t6, $t6, 1

                j continue

                continue_fake: addi $t6, $zero, 1

                continue: beq $t6, $t5, exit

                j loop

                nop

```

checkx:

```
li $t3, 1
beq $t6, $t3, continue_fake2
j continue
```

checki:

```
li $t3, 2
beq $t6, $t3, continue_fake2
j continue
```

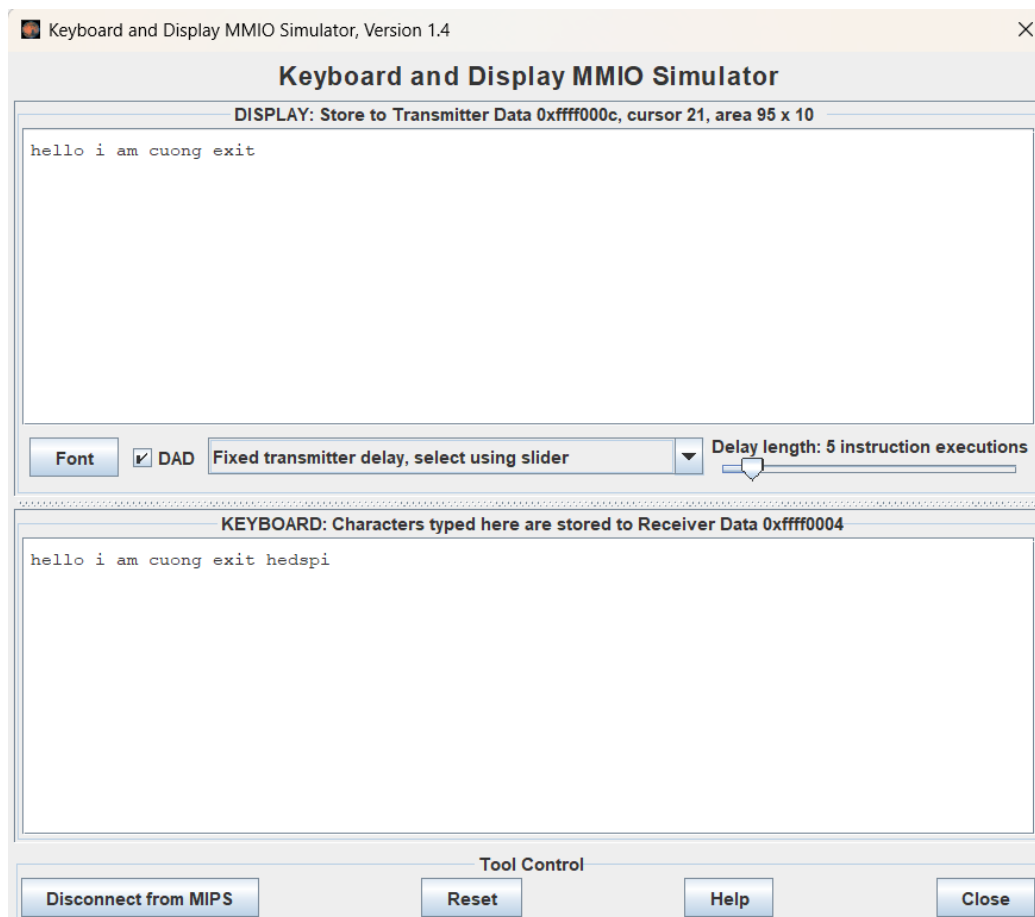
checkt:

```
li $t3, 3
beq $t6, $t3, continue_fake2
j continue
```

exit:

Result:

Chương trình chạy bình thường và đưa kết quả input từ bàn phím vào mục DISPLAY cho đến khi gặp exit chương trình tự động ngắt và không còn nhận input nữa.



Explain:

- Kiểm tra các kí tự nhập vào, mỗi lần đọc được kí tự 'e' thì bộ đếm \$t6 tăng thành 1 và tương tự sẽ tăng thêm 1 nếu gặp thêm các kí tự 'x', 'i', 't'.
- Nếu bộ đếm đạt đến 4, chỉ ra rằng chuỗi "exit" đã được nhập chính xác, chương trình nhảy tới nhãn exit. Nếu không nó tiếp tục đợi phím bấm tiếp theo.

```
#check exit
    beq $t0, 'e', continue_fake
    beq $t0, 'x', checkx
    beq $t0, 'i', checki
    beq $t0, 't', checkt
    j continue
continue_fake2: addi $t6, $t6, 1
                j continue
continue_fake: addi $t6, $zero, 1
continue: beq $t6, $t5, exit
           j loop
           nop
checkx:
    li $t3, 1
    beq $t6, $t3, continue_fake2
    j continue
checki:
    li $t3, 2
    beq $t6, $t3, continue_fake2
    j continue
checkt:
    li $t3, 3
    beq $t6, $t3, continue_fake2
    j continue
exit:
```