

DSA switches: domesticating a savage beast

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Abstract

The DSA subsystem was originally built around Marvell devices, but has since been extended to cover a wide variety of hardware with even wider views of their management model. This paper uses the DSA architecture overview [1] as a primary source and discusses the changes in DSA that took place in the last years for this wide variety of switches to offer more services, and in a more uniform way, to the larger network stack. Summarized, these changes are:

- Acknowledging switches which only have DSA tags for control plane packets, and modifying the bridge driver to accept termination of data plane packets from these switches.
- Support for unoffloaded upper interfaces.
- Support for more cross-chip topologies than the basic daisy chain, while maintaining the basic principle that network interfaces under the same bridge can forward from one to another, and interfaces under different bridges don't.

Keywords

DSA, bridge, switchdev, offloading, cross-chip bridging, imprecise RX, TX forwarding offload, RX filtering.

The data plane and the control plane

The original DSA architecture, seen in figure 1, has remained unchanged to this day. It stipulates that one virtual network interface should be exposed for each front-facing switch port, and no virtual network interface should be exposed for the ports facing inwards (CPU ports, DSA/cascade ports). DSA network interfaces should not only be conduit interfaces for retrieving ethtool statistics and registering with the PHY library, but they should be fully capable of sending and receiving packets. This is accomplished via the DSA tagging protocol drivers, which are hooks in the RX and TX path of the host Ethernet controller (the DSA master) which multiplex and demultiplex packets to/from the correct virtual switch interface based on switch-specific metadata that is placed in the packets.

In this model, the basic function of a network switch from a hardware designer's perspective, which is to switch packets, is an optional feature from the Linux network stack's perspective, and was added years after the original design had been established. This is one of the first major hurdle software engineers need to get over when starting development in this

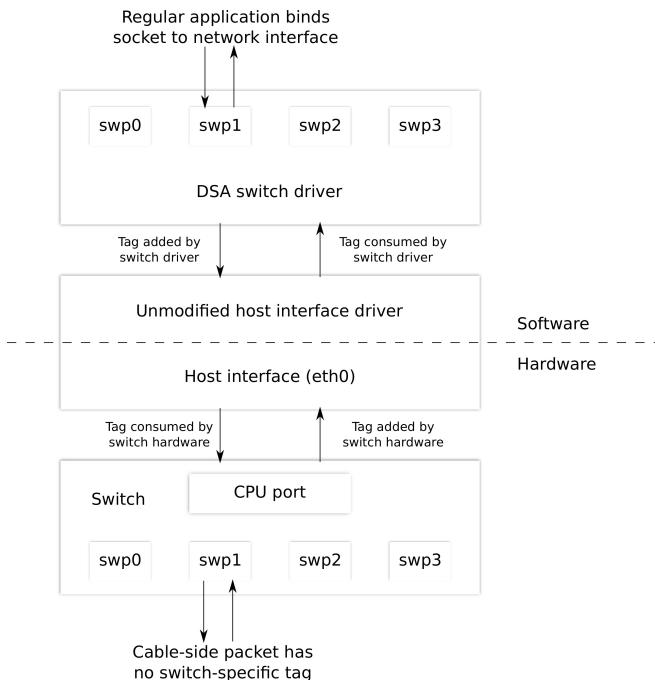


Figure 1: Overview of packet flow with DSA switches

area: DSA is not simply a switch driver, it is a networking driver framework, which first and foremost needs to cater to the most basic network connectivity needs, and which has optional hardware acceleration features.

Behind the seemingly uniform implementation of DSA tagging protocols and switch drivers, which are tightly managed by the DSA framework, lie many differences and subtleties that make the feature set exposed by two different DSA switches to the network stack very different.

The majority of network switches capable of management have some sort of distinction between the data plane packets and the control packets. These different flows, detailed in figure 2 as well as below, are superimposed on top of the same hardware ports. For this reason, even if control and data packets travel through the same Ethernet ports, it may be helpful to visualize them three dimensionally to understand the key differences.

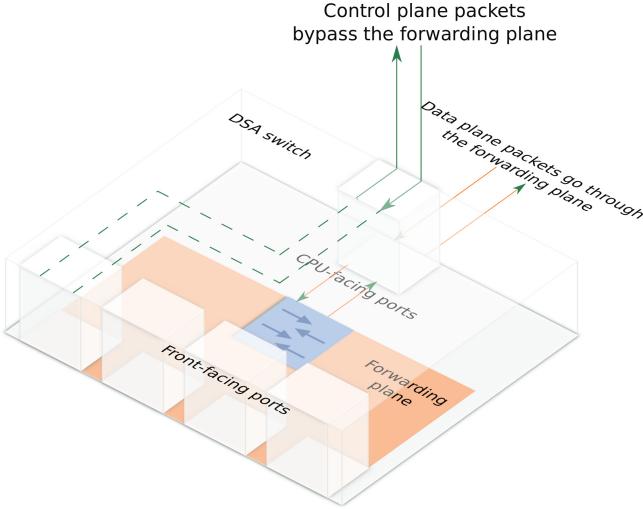


Figure 2: DSA control plane vs data plane

At the most basic level, control packets, which must be used for link-layer control protocols like STP, PTP, EAP, have the ability to target a specific egress port and to override its STP state (inject into a BLOCKING port). These packets typically bypass the forwarding layer of the switch and the frame analysis stage of the ingress (CPU) port and are injected directly into the egress port. The implications are that metadata such as QoS class and VLAN ID must be specified by the operating system driver directly as part of the DSA tag, and that hardware address learning is not performed on the CPU port.

On the opposite side of the spectrum, data plane packets do not perform STP state override, are subject to hardware address learning on the CPU port, but also cannot be steered towards a precise destination port, since they are also subject to the forwarding rules of the switch. The format of these packets might vary from a special bit in the DSA tag which marks them as subject to forwarding, to the complete absence of a DSA tag. For these packets, the CPU port acts like any other bridge port.

At the extreme, there exists a `DSA_TAG_PROTO_NONE` tagging protocol, which admits defeat and does not attempt to multiplex/demultiplex virtual switch interfaces from the DSA tag, and all network I/O through such a switch takes place through the DSA master which is seen as a switched endpoint. The network interfaces registered for the switches are only used for control operations (`ethtool`, PHY library) and are "dead" to the network stack both for control plane and for data plane packets. These are the "unmanaged" switches.

Finally, in some switch designs, injecting a control packet is an expensive operation which cannot be sustained at line rate, and the bulk of the traffic (the data plane packets) should be injected, from the hardware designer's perspective, directly through the DSA master interface, with no DSA tag. These are the "lightly managed" switches, and their virtual DSA interfaces are similarly "dead" to the network stack except for link-local packets.

The most basic and common approach with this type of

hardware is to simply set up a user space configuration to perform the traffic termination from the switching domain on the DSA master itself. For some packets to target a single switch port, the user is required to install a bridge VLAN on the switch port which is egress-tagged towards the CPU port, then create an 802.1q upper with the same VLAN ID on top of the DSA master, and send/receive traffic through the 802.1q upper of the DSA master. This approach is, however, undesirable for two reasons. First, `DSA_TAG_PROTO_NONE` is the only tagging protocol which needs special treatment from user space, which hurts the DSA framework's goal in exposing a uniform set of commands for user interaction. Second, it is inherently impossible to run control protocols for this switch - that would fundamentally require a tagging protocol which is not `DSA_TAG_PROTO_NONE`. Attempting to fix that, and making the switch network interfaces be capable of traffic but only for control protocols, by creating a specific tagging protocol which behaves as `DSA_TAG_PROTO_NONE` for data packets, creates yet another road block: bridging DSA interfaces with non-DSA (foreign) interfaces is impossible, which is an important use case for boards with a switch and a Wi-Fi AP (home routers). Interfaces that are DSA masters cannot be added to a bridge either (they can only as long as they use `DSA_TAG_PROTO_NONE` [2]).

A slightly better integrated way of achieving the same result is the relatively new software-defined DSA tagging protocol named `tag_8021q`, which can bring both the lightly managed and unmanaged switches closer to the user model exposed by DSA switches with hardware support for a DSA tagging protocol.

The `tag_8021q` protocol is fundamentally still sending data plane packets from the perspective of the hardware, so there are things it cannot accomplish, like STP state override. Therefore, `tag_8021q` must always be augmented by switch-specific methods of injecting and extracting control packets in order to offer full functionality, and for this reason, this tagging protocol is offered as library code and not a full drop-in solution. Additionally, the DSA framework has traditionally not enforced any meaningful distinction between data plane and control plane packets, since originally, the assumption was that all packets injected by the software network stack should be control packets.

To unify the hardware and the software notions, and to use these chips in the way they were meant to, the network stack must be taught about data plane packets. The `tag_8021q` model breaks down when DSA switch interfaces offload a VLAN-aware bridge, which is in fact their primary use cases. This is because the source port of the switch cannot be retrieved based on the VLAN ID by the tagging protocol driver on RX, because the VLANs are under the control of the bridge driver, not DSA, and there is no guarantee that a VLAN is uniquely installed on a single switch port. So bridging with foreign interfaces becomes equally impossible.

The decisive changes which made these switches correctly offload a VLAN-aware bridge come in the form of not attempting to report a precise source port on RX for data plane packets, just a plausible/imprecise one. As long as some requirements inside the software bridge's ingress path are sat-

isfied (valid STP state, VLAN ID from the packet is in the port’s membership list), the bridge is happy to accept the packet as valid, and process it on behalf of the imprecise DSA interface that was reported.

Complications arise due to the fact that the software bridge might learn the MAC SA of these packets on a potentially wrong port, and deliver those packets on the return path towards the wrong port. Additionally, due to bandwidth constraints, DSA interfaces do not synchronize their hardware FDB with the FDB of the software bridge, so the software bridge does not have an opportunity to figure out the real source port of imprecise packets.

To give DSA the chance to right a wrong, the bridge driver was modified to support TX forwarding offload [8]. With this feature, the software bridge avoids cloning an skb which needs to be flooded to multiple ports, and sends only one copy of the packet towards a single network interface from each “hardware domain” that the flooded packet must reach. The port driver is responsible with looking up its hardware FDB for that packet and replicate the packet as needed. This is a useful feature in itself, because with switches with a large port count, multicast traffic on the bottlenecked link between the DSA master and the CPU port is reduced, and packets are replicated inside the hardware. But with the lightly-managed and unmanaged switches, it makes the imprecise RX work correctly, since the TX is also imprecise. So even though the software bridge did learn the MAC SA of the packets on the wrong source port, that source port is in the same hardware domain with the right port, and even though the software FDB is incorrect, the hardware FDB isn’t. So DSA drivers for lightly-managed and unmanaged switches have a chance to properly terminate traffic on behalf of a VLAN-aware bridge, in a way that is compatible with bridging with foreign interfaces, and with a user space interaction procedure that is much more uniform with DSA drivers that always send and receive packets with a DSA tag.

Unoffloaded software upper interfaces

Support for unoffloaded upper interfaces running on top of DSA switch ports, such as the bridge, VLAN, macvlan, bonding interfaces, has always been baked into DSA’s core architecture. Surely, it came at a high cost, which is to not use the hardware to its full potential. However, this feature got broken when switchdev was created and DSA was integrated with it in order to offer hardware offload for the Linux bridge. This section details the changes made to switchdev in order for DSA to regain this functionality.

Recently, DSA has also gained support for offloading other virtual network interfaces than the Linux bridge. These are the hsr driver (which supports the HSR and PRP industrial redundancy protocols) [5] and the bonding/team drivers (which support the link aggregation protocol) [6].

Not all switches are capable of offloading hsr and team/bonding, and DSA’s policy is to fall back to a software implementation when hardware offload cannot be achieved: the bandwidth to/from the CPU is often times good enough that this is not impractical.

However, DSA’s policy could not be enforced right away with the expected results, due to two roadblocks that led to

further changes in the kernel code base.

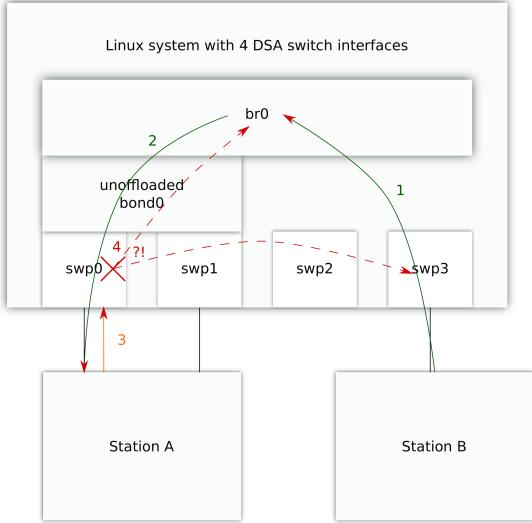
To not offload an upper interface means for DSA that the physical port should behave exactly as it would if it was a standalone interface with no switching to the others except the CPU port, and which is capable of IP termination.

But when the unoffloaded upper interface (the software LAG) is part of a bridge, the bridge driver makes the incorrect assumption that it is capable of hardware forwarding towards all other ports which report the same physical switch ID. Instead, forwarding to/from a software LAG should take place in software. This has led to a redesign of the switchdev API, in that drivers must now explicitly mark to the bridge the network interfaces that are capable of autonomous forwarding [7]; the new default being that they aren’t. In the new model, even if two interfaces report the same physical switch ID, they might yet not be part of the same hardware domain for autonomous forwarding as far as the bridge is concerned.

The second roadblock, even after the bridge was taught to allow software forwarding between some interfaces which have the same physical switch ID, was FDB isolation in DSA switches. Up until this point, the vast majority of DSA drivers, as well as the DSA core, have considered that it is enough to offload multiple bridges by enforcing a separation between the ports of one bridge and the ports of another at the forwarding level. This works as long as the same MAC address (or MAC+VLAN pair, in VLAN-aware bridges) is not present in more than one bridging domain at the same time. This is an apparently reasonable restriction that should never be seen in real life, so no precautions have been taken against it in drivers or the core.

The issue, described in figure 3, is that a DSA switch is still a switch, and for every packet it forwards, regardless of whether it is received on a standalone port, a port under a VLAN-unaware bridge or under a VLAN-aware one, it will attempt to look up the FDB to find the destination. With unoffloaded LAGs on top of a standalone DSA port, where forwarding between the switched domain and the standalone port takes place in software, the expectation that a MAC address is only present in one bridging domain is no longer true. From the perspective of the ports under the hardware bridge, a MAC address might come from the outside world, whereas from the perspective of the standalone ports, the same MAC address might come from the CPU port. So without FDB isolation (which is a hardware-specific mechanism by which FDB lookups performed on a source port are made to not match on FDB entries pointing towards a port that is not in the same hardware forwarding domain), the standalone port might look up the FDB for a MAC address and see that it could forward the packet directly to the port in the hardware bridge domain, where that packet was learned by the bridge port, shortcircuiting the CPU. But the forwarding isolation rules put in place will prevent this from happening, so packets will be dropped instead of being forwarded in software.

Individual drivers have started receiving patches for FDB isolation between standalone ports and bridged ports, but it is possible to conceive real life situations where even FDB isolation between one bridge and another must be maintained. Since the DSA core, at the time of writing, does not enforce FDB isolation through its API and many drivers already have



1. Station B sends an ICMP Echo request to Station A. Station A is behind an unoffloaded bridge port (bond0), so swp3 must forward it towards the CPU. swp3 is an offloaded bridge port, so Station B's MAC address is learned on this source port.
2. The bridge reinjects it towards bond0 which will send towards either swp0 or swp1 according to the xmit hash policy.
3. Station A generates an ICMP echo reply towards Station B's MAC address.
4. In lack of FDB isolation, swp0 will look up Station B's destination MAC address and will find the entry pointing towards swp3, so it will attempt to shortcircuit the CPU and forward towards that port directly. But forwarding is blocked from swp0 towards that port => packet is dropped.

Figure 3: Pinging between two stations connected by DSA using software forwarding

been written without it in mind, it is to be expected that many years pass until DSA drivers offer a uniform set of services to upper layers in this regard. Even with the core DSA framework in place, driver writers still are responsible for finding (sometimes creative) ways of isolating FDB lookups between ports that are standalone and ports that are members of a bridge, as well as between ports that are members of different bridges. The solutions can vary between cropping a range of VLAN IDs to be used for isolating VLAN-unaware bridges, and restricting the user to only create a single VLAN-aware bridge if VLANs of one bridge cannot be isolated from VLANs of another, to using hardware specific Filtering Identifiers (FID) which remap the same VLAN IDs from packets to different internal VLAN structures from the 4K space, depending on the bridging domain they belong to, to remapping VLANs to an internal space larger than 4K.

RX filtering

In the context of DSA, RX filtering refers to the technique of teaching switches which addresses must be filtered towards the host and delivered to the CPU ports. There are multiple possible ways to force a certain {MAC DA, VLAN ID} pair to be sent towards the CPU, either by installing an FDB entry in hardware, or by installing an ACL rule if the switch has a programmable TCAM.

Even if no such thing as a MAC address for a switch port exists, DSA network interfaces have MAC addresses of their own, since they are also capable of termination, not just for-

warding. By default, that MAC address is inherited from the DSA master's MAC address, with an option to override the address of each port from other sources like the device tree. Traditionally, DSA has not configured the switches in any way so as to make sure that packets destined towards the switch ports' addresses, or the DSA master's address, or a bridge upper interface's address, are really filtered only towards the host.

The end result varies depending on the exact hardware switch implementation, but the typical case is that of a fully managed switch, whose tagging driver sends only control packets. If the switch is configured to not perform hardware address learning for the MAC SA from those control packets, or if it outright cannot do it, then rules that match on host addresses are simply absent from hardware. Therefore, the packets destined for the host are reaching it via flooding. The host is not the only flooding destination however, however, these packets are flooded towards all other ports that are in the same bridging domain with the ingress port. There was a desire to change this behavior.

It turns out that addresses corresponding to interfaces on the host are not the only addresses that the switch must send to the CPU via a non-flooding based mechanism. There are many kinds of use cases where DSA switch ports are in a bridging domain with "foreign" (non-DSA) interfaces. A typical example is a Wi-Fi AP interface, which is in the same bridging domain with a DSA switch that handles the LAN ports. This topology can be seen in many home Wi-Fi routers running OpenWRT. Here, the effects of not having hardware address learning on the CPU port can be much more disastrous [9]. The root of the Wi-Fi roaming issue can be summarized as follows: if a station used to be learned by the switch on a certain port, but then migrates to another port which is in the switch's blind spot (such as behind the CPU, where no hardware address learning takes place), then the stale address will cause packet loss until it expires, and it may take many minutes until it does age out. There was also a desire to change this behavior.

Furthermore, taking FDB isolation into consideration, standalone ports (ports not offloading any interface) should be placed by drivers in a hardware FDB partition where no learning takes place, and packets are flooded towards their only possible destination (the CPU port). So there is no immediate need to implement `IFF_UNICAST_FLT` for standalone ports in DSA, it is only bridge ports that have a problem.

After gathering all requirements, the conclusion was that the problem needs to be addressed at the bridge level, and DSA became much tighter integrated with the software FDB of the bridge, by sniffing for two classes of FDB entries and offloading them as FDB entries towards its CPU ports:

- FDB entries learned on foreign interfaces in the same bridging domain as a DSA switch interface. This solves the Wi-Fi roaming issue by introducing an opt-in "assisted learning on the CPU port" feature which replaces the hardware alternative [10].
- FDB entries that are local/permanent. The bridge marks the MAC address of each bridge port as a local address, and the same goes for the bridge's own MAC address. By of-

flooding these entries, packets targeted towards the bridge itself are no longer flooded in the entire bridging domain [11].

The ultimate goal of RX filtering in DSA is to mark the CPU port as not being part of the flooding domain of the switch. Ideally, all packets that reach the host should reach it with a good reason, and not rely on software to drop them if they are not needed, since this wastes precious CPU cycles. Disabling flooding towards the CPU (neither unicast nor multicast) is not something possible today due to several reasons.

A limitation that is still present is the case where the bridge network interface has upper interfaces of its own (for example an 8021q upper), and these interfaces do not have the same MAC address as the bridge itself. Since the bridge driver does not implement `IFF_UNICAST_FLT`, the network stack will make this interface promiscuous. Packets coming from the hardware DSA side will still reach this interface via flooding, but with the same limitations as before. To address this limitation, the `dev_uc_add` API must be extended to include a VLAN ID as well, then the bridge driver must be modified to implement `IFF_UNICAST_FLT` and add the MAC addresses of its upper interfaces as FDB entries that are local/permanent (point towards the bridge). This way, DSA and other switchdev drivers will receive the information they need to have a known destination for these virtual interfaces.

Another case in which flooding towards the CPU cannot simply be disabled is when DSA ports are in a bridge with foreign interfaces. Even if no local interface needs the packets, a station associated with the Wi-Fi AP might.

Switch topology changes

Traditionally, the cross-chip setups supported by DSA have been daisy chains, where all switches except the top-most one lack a dedicated CPU port, and are simply cascaded towards an upstream switch. There are two new switch topologies supported by DSA now.

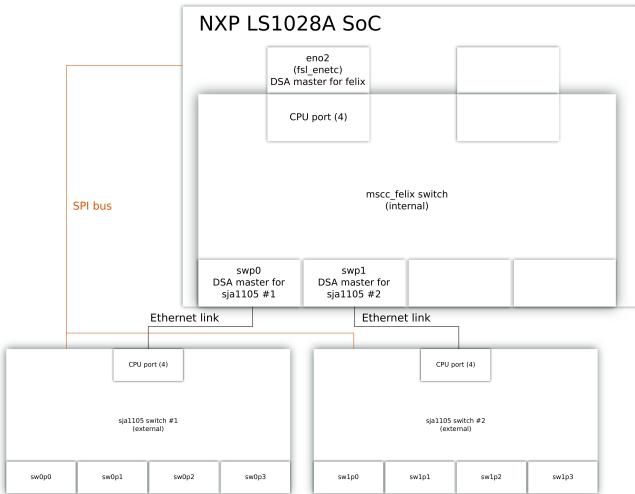


Figure 4: A disjoint tree setup consisting of NXP LS1028A internal switch ports acting as DSA masters for SPI-connected external switches

The first is the disjoint tree topology from figure 4. A DSA tree is comprised of all switches directly connected to each other which use a compatible tagging protocol (one switch understands the packets from the other one, and can push/pop them as needed). Disjoint trees are used when DSA switches are connected to each other, but their tagging protocols are not compatible. As opposed to one switch understanding another's, tag stacking takes place, so in software, more than one DSA tagging protocol driver needs to be invoked for the same packet. In such a system, each switch forms its own tree. Disjoint trees were already supported, but the new changes also permit some hardware forwarding to take place between switches belonging to different trees. For example, be there an embedded 5 port DSA switch that has 2 external DSA switches connected to 2 of its ports. Each embedded DSA switch interface is a DSA master for the external DSA switch beneath it, and there are 3 DSA disjoint trees in this system. For a packet to be sent from external switch 1 to external switch 2, it must be forwarded towards the CPU port. In the most basic configuration, forwarding between the two external switches can take place in software. However, it is desirable that the embedded DSA switch that is a master of external switches 1 and 2 can accelerate the forwarding between the two (because the external switches are tagger-compatible, they are just separated by a switch which isn't tagger-compatible with them). Under some conditions, this is possible as long as the embedded DSA switch still has some elementary understanding of the packets, and can still forward them by MAC DA and optionally VLAN ID, even though they are DSA-tagged. With the vast majority of DSA tagging protocols, the MAC DA of the packets is not altered even when a DSA tag is inserted, so the embedded DSA master can sanely forward packets between one external switch and another. This is one of the only special cases where DSA master interfaces can be bridged (they are part of a separate bridge compared to the external switch ports), because in this case, the DSA masters are part of a bridge with no software data plane, just a hardware data plane. The second requirement is for both the embedded and the external switches to have the same understanding of what constitutes a data plane packet, and what constitutes a control plane packet: STP packets received by the external switch should not be flooded by the embedded switch. Due to the same reason that the embedded switch must still preserve an elementary understanding of the MAC DA of packets tagged with the external switch's tagging protocol, this will also be the case, since typical link-layer protocols have unique link-local multicast MAC addresses.

For this topology, the necessary changes were to permit cross-chip bridging between ports belonging to different DSA trees, and to allow certain DSA masters to be bridge ports as long as no software forwarding is required [3].

The second is the H tree topology [4], described by figure 5. In such a system, there are multiple switches laterally interconnected through cascade ports, but to reach the CPU, each switch has its own dedicated CPU port. It turns out that to support such a system, there are two distinct issues.

First, with regard to RX filtering, an H tree topology is very similar in challenges to a single switch with multiple CPU

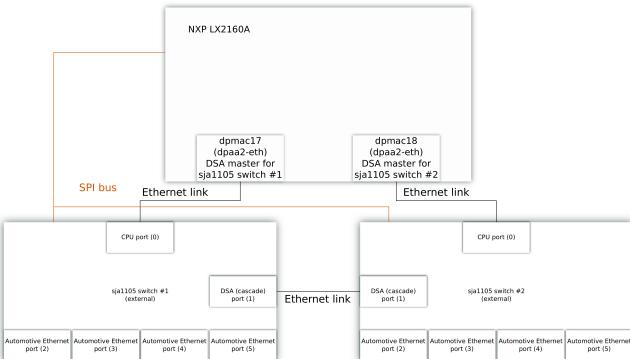


Figure 5: A H-tree topology consisting of two switches, each having its own CPU port, but also a cascade port for autonomous forwarding towards the other switch

ports. Hardware address learning on the CPU port, if at all available, is of no use and leads to addresses bouncing and packet drops. All MAC addresses which need to be filtered to the host need to be installed on all CPU ports as static FDB entries. This has led to the extension of the bridge switchdev FDB notifiers to cover FDB entries that are local to the bridge, and which should not be forwarded.

Secondly, in an H topology it is actually possible to have packet loops with the TX forwarding offload feature enabled, because TX data plane packets sent by the stack to one switch might also be flooded through the cascade port to the other switch, where they might be again flooded to the second switch's CPU port, where they will be processed as RX packets. Currently, drivers which support this topology need to be individually patched to cut RX from cascade ports that go towards switches that have their own CPU port, because the DSA driver API does not have the necessary insight into driver internals as to be able to cut forwarding between two ports only in a specific direction.

Future changes

One of the most important features still absent from DSA is the support for multiple CPU ports. However, with many roadblocks such as basic RX filtering support now out of the way, this functionality will arrive sooner rather than later. A possible implementation of multiple CPU ports should follow several requirements.

First of all, when there are multiple CPU ports there are multiple DSA masters, and DSA has gained the ability for the tagging protocol to be changed at runtime, by writing the new tagging protocol's name into the `dsa/tagging` sysfs file of the DSA master. But since both DSA masters attach to the same DSA tree, asymmetric DSA tagging protocols should not be permitted; all DSA masters should use the same protocol, since this might have undesirable effects for other switches in the same tree.

DSA should preserve its current default configuration, meaning that it should not use multiple CPU ports by default, but pick the first CPU port and keep the other one as inactive.

At the very least, user space should be able to create a static

assignment between a user port and the DSA master interface that services it, using a `rtnetlink` attribute. Device tree descriptions are not welcome since they should only describe the hardware ability, not the configuration. Furthermore, the kernel should provide the means but not enforce the policy.

Configuring the CPU ports in a link aggregation group is also a common use case which should be permitted by the design. While the network is down, the DSA masters can be added by user space to a bonding or team interface, and DSA ports can be statically assigned to use that bonding interface as the DSA master. Transmission from software towards the switch is balanced in software, while transmission from the switch towards the CPU is balanced by a hardware LAG that is the mirror image of the bonding interface.

There is also the emerging topic of Ethernet controllers as DSA masters that are aware of the DSA switches beneath them, which is typical when both the switch and the Ethernet controller are made by the same silicon vendor. Right now DSA can freely inherit all `master->vlan_features`, such as TX checksumming offloads, but this does not work for all switch and DSA master combinations, so it must be refined and only the known-working master and switch combinations inherit the extra features.

On the same topic of DSA-aware masters, SR-IOV capable masters are expected to still work when attached to a DSA switch, but the network stack's model of this use case is unclear. VFs on top of a DSA master should be treated as switched endpoints, but the VF driver's transmit and receive procedures do not go through the DSA tagging protocol hooks, and these packets are therefore DSA-untagged. So hardware manufacturers have the option of inserting DSA tags in hardware for packets sent through a VF that goes through a DSA switch. It is unclear, however, according to which bridging domain are these VFs being forwarded. An effort should be made to standardize the way in which the network stack treats these interfaces. It appears reasonable that DSA switches might have to register virtual network interfaces that are facing each VF of the master, in order to enforce their bridging domain, but this makes the DSA master and switch drivers closely coupled.

On the other hand, letting other code paths than the DSA tagging protocol driver inject packets into the switch risks compromising the integrity of the hardware, which is an issue that currently exists and needs to be addressed.

The case for network interfaces for the CPU ports

The DSA architecture mandates that ports which are unable of terminating traffic in a meaningful way do not get network interfaces associated with them. One example is the CPU port: attempting to ping on the interface associated with that would mean that a packet is sent towards the inside of the system, in a loopback of sorts.

On the other hand, there has always been the argument of needing network interfaces associated with the shared (CPU and DSA) ports for the ability to retrieve statistics counters, which are a very useful debugging tool. The latter argument could not win over the former, and other techniques for de-

bugging the DSA shared ports have been developed: devlink port regions, devlink resources, as well as overlaying the eth-tool statistics counters of the CPU port on top of the statistics counters of the DSA master.

Additionally, the PHY library needed a network interface attached to the PHY, and while the link between the DSA master and the switch is typically a fixed set of traces on a PCB, that is not always the case. For example, a Raspberry Pi might connect using a plain RJ45 cable to a switch evaluation board. In that case, there are two Ethernet PHYs involved between the DSA master and the switch, and the PHY library must manage them. To solve that scenario, the PHY library and phylink have been modified to be able to instantiate the state machines in lack of an attached network interface, and still present the same API towards the MAC side [13].

There have also been attempts to register network interfaces for the CPU ports in order to offload tc shapers on them, to limit the amount of traffic sent to the host [14]. These attempts have been shot down due to the impracticality of installing an egress shaper as opposed to an ingress policer on the front-facing ports directly. With an egress shaper, packets would be eventually dropped due to congestion. With an ingress policer, they would be dropped early when the bandwidth quota is exceeded.

So the architecture has remained unchanged despite the temptations. However, there might be use cases where network interfaces for the CPU port make the most amount of sense. Detailed below is one such example, which is provided for the purpose of contemplating the idea, the usage model for this new interface, and other consequences. Note that creating a network interface for the CPU port does not imply that interfaces are created for cascade ports too, so the aforementioned use cases for a network interface for hidden ports should still search for an alternative.

The Time Sensitive Networking (TSN) enhancements to IEEE 802.1Q and IEEE 802.3 are aiming to transform Ethernet into a viable replacement for the existing buses in automotive and industrial networking, and are seeing hardware implementations in a number of recently added DSA switch drivers. In TSN, the real-time guarantees are obtained by enforcing bandwidth reservations and saying "no" when those reservations are exceeded. Packets with real-time guarantees must be able to be transported by the same network that transports best-effort traffic, and time division based access to the network is therefore a common approach. To minimize the latency, the real-time aware endpoints must be synchronized to the network time via the Precision Time Protocol (PTP), in order to always send and receive packets in band with their allotted time interval, and not have switches delay their packets until that interval comes.

One of the existing paradigms in TSN is the "switched endpoint", a mix between an application terminating some data in a time-synchronized manner, and a control stack for the on-board switch, which forwards the data that must not be terminated locally. At the bare minimum, the switch control stack must manage a port redundancy protocol and the synchronization protocol.

Such use cases are well suited for a DSA hardware design, since the endpoint can be a real-time application which opens

a socket on the DSA master, and the switch can be managed by DSA itself.

There are multiple reasons why a TSN endpoint application might want to run on the bare DSA master. First, the switch might simply have a "lightly managed" design, and it might accept DSA-untagged packets just fine.

Second, opening the socket on top of the bridge interface, or on top of the switch interfaces, would add the extra processing overhead of several virtual network interfaces in the kernel, which would cost a few precious tens of extra microseconds per packet. DSA and the Linux bridge are simply not optimized for packet latency.

Third, the DSA master might be well prepared for TSN offloads itself, not relying on the TSN offloads of the switch. The DSA master might itself be synchronized to the PTP time, it might have a time-aware packet scheduler configured (standardized as clause "8.6.8.4 Enhancements for scheduled traffic" of IEEE 802.1Q-2018, but widely known as IEEE 802.1Qbv). Also, the endpoint application might want to be as oblivious to the network topology as possible, it should not need to know which switch port interface to bind its socket to, binding to the DSA master should be sufficiently agnostic if the CPU port is viewed as a regular bridged port.

In this model, it would make perfect sense for the CPU port to have a network interface associated with it. This interface would be capable of traffic, and pinging on the CPU port would talk to an application doing the same thing but running on the DSA master. Putting the CPU port interface in a bridge would decide what happens to DSA-untagged packets sent by the bare DSA master. It would not affect in any way what happens with control or data packets injected by DSA on behalf of the switch network interfaces or on behalf of a bridge, and packets belonging to those flows would still reach the CPU port even if that port was not under a bridge, or the same bridge. In this model, the DSA master could also be an endpoint (a DSA-unaware one), and the CPU port interface would be the bridge port that services it.

Nonetheless, there are many reasons why the switched endpoint use case cannot be realized with the existing DSA infrastructure today.

- Having the DSA master synchronized to the PTP time means running two instances of the PTP state machine on the same system: one for the DSA master, as an endpoint (Ordinary Clock), and one for the switch interfaces, as a bridge (Boundary Clock). Since the DSA master and the DSA switch have independent PTP Hardware Clocks (PHC), the DSA master's PHC will synchronize itself to the switch's PHC. Due to limitations in the PTP user API, DSA disables PTP timestamping on the master interface [12]. The PTP user space API would need to be extended, and timestamps to be annotated with the interface/PHC that took them, before the DSA master and the switch could synchronize themselves.
- On TX, it has been established in the sections above that letting DSA unaware code paths simply inject packets at will into the switch can be a harmful operation. If crafted correctly, packets sent from outside DSA-controlled code paths can even modify state inside the switch (access regis-

ters, etc). It would be desirable that if switch drivers create a path for DSA-untagged packet flows coming from the DSA master, those paths are safe.

- On RX, DSA traps all packets received by the DSA master by default. But allowing a packet reception flow outside of DSA's control would mean that the tagging protocol driver needs to filter out the packets that must be processed by the DSA master itself, and not by the DSA switch interfaces. As opposed to the TX flow, where packets coming from the DSA code paths will be DSA-tagged and packets coming from DSA-unaware code paths will be DSA-untagged, the same expectation is unreasonable for RX, unless the switch knows beforehand somehow that some packets sent towards the CPU must be tagged, and some must not. So the filtering, as well as tag stripping decision, must take place in software, inside the DSA tagging protocol driver. The criterion by which the tagging protocol decides what packets should be stripped and then left in the hands of the DSA master is TBD, but could possibly be derived from the source and destination MAC addresses of the packet (the DSA master as a switched endpoint would need to have a different MAC address than the virtual switch interfaces).

While the above might sound like fiction, the NXP LS1028A SoC targets the above use cases, but the DSA framework's restrictions were avoided by using a special hardware design. Namely, the internal switch present inside this SoC has two CPU ports, but they are asymmetric in role. One internal switch port can act as a control port (and the associated ENETC port is the DSA master), while the other port is a plain data port, for which DSA registers a user port with a network interface, and for which the associated ENETC port is not a DSA master. This can be seen in figure 6.

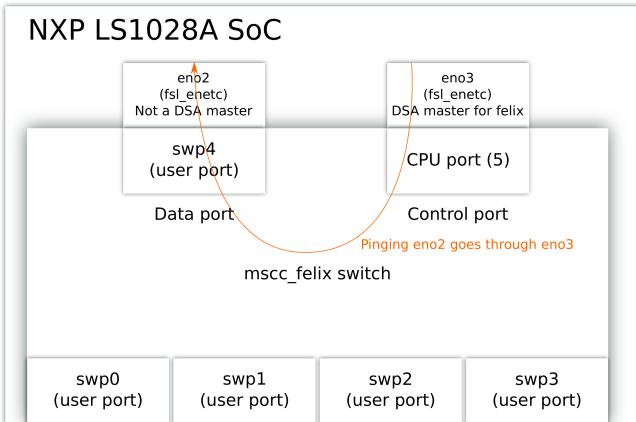


Figure 6: NXP LS1028A control port and data port

Both switch ports 4 and 5 are CPU ports in the truest sense of the word: they are inwards-facing ports that lead to the CPU. However, from DSA's perspective they play very different roles. The ENETC has its own PHC, and the Felix switch has its own PHC, and when the control port is physically separate from the data port, synchronizing the two is not any more complicated than running:

```
# ptp41 -i eno2 -2 -P -m &
# ptp41 -i swp4 -2 -P -m &
```

Since switch port 4 can be configured by software to act as either as a control or a data port, and the same goes for switch port 5, the device tree description becomes challenging. It is desirable in many use cases that the device tree is no more than a description of the hardware, since it may be set in stone with no way of updating it in the field. But when port roles are customizable, it is tempting to make that customization in the device tree description itself.

In mainline Linux, the NXP LS1028A has only one internal switch port described as a CPU port (has an ethernet phandle to its ENETC pair). The other internal switch port is declared as a simple data port, or disabled.

But the ethernet phandle might have been just as well between `mscc_felix_port5` and `enetc_port3`. Additionally, the felix driver might gain support for multiple CPU ports when using the `ocelot-8021q` tagging protocol, and it is desirable that both ports are described as CPU ports in the device tree when that happens, but also that this does not break existing use cases when using the normal `ocelot` DSA tagging protocol.

It would therefore appear natural for the device tree to describe a port's capability of acting as a control interface, and the definitive device tree description for the LS1028A switch to have the `ethernet` properties on both CPU ports. But the DSA framework could also ask the driver if it wants to opt in to registering a network interface for CPU ports. In the case of the Ocelot switch family, which the LS1028A Felix switch is a part of, DSA-untagged packets received on the control port are not accepted, so this driver would refuse that feature. However, in the presence of multiple `ethernet` OF properties, DSA currently picks the first one as the CPU port, and leaves the other ports with this property as CPU ports too, but they are "inactive" CPU ports (no `dp->cpu_dp` pointer points to them). It would be for this "inactive" CPU port that the DSA framework can register a network interface, and this would effectively yield the same result as the current description where one of the internal switch ports is declared as a user port.

Moreover, the data port opt-in might have uses beyond the LS1028A. Fundamentally, the aforementioned "switched endpoint" use case is the same as the LS1028A's use of two internal ports, except that the packet flows for the control and data ports are overlaid on top of a single pair of hardware ports. When the DSA switch is external, it might be wasteful to connect two Ethernet ports to the system in this way just for them to play different roles.

Even with a dedicated control port and a dedicated control port, the NXP LS1028A workaround still has some limitations. It creates a separate hardware path for DSA untagged packets to exit the system, but this path does not scale. To explain this, we can return to the example switch topology with disjoint trees, only this time, inside the LS1028A, both `eno2` and `eno3` ports are enabled. This is shown in figure 7.

DSA-untagged packets can exit the internal Felix switch, but attached to the Felix switch are other DSA switches that expect packets to be tagged with their own switch-specific

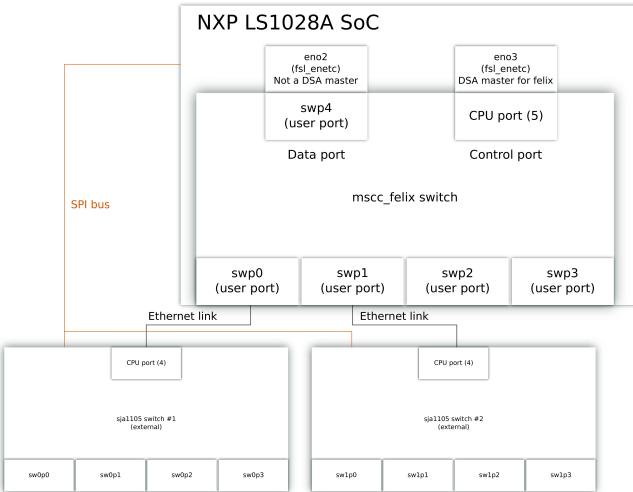


Figure 7: The same disjoint tree setup with felix and sja1105, but with eno2 as a data port

DSA tag. So these packets will be going nowhere, unless we accept one of the following:

- Similar to SR-IOV network interfaces which are DSA-aware and can be configured to insert a certain programmable DSA header in hardware, it is sane for DSA switch hardware designs to be themselves DSA-aware, and to insert other switch's tag formats on egress. In this case, the Felix switch would need to insert a DSA tag compatible with the sja1105's expectations, to allow DSA-untagged packets coming from eno2 to exit.
- The need for a path for DSA-untagged packets coming from inside the system to exit the switch is acknowledged at the DSA framework level, and does not need workarounds such as multiple CPU ports with different roles. Such a path for DSA-untagged packets can then be added to the drivers of the downstream switches too, and packets coming from eno2 can be treated as DSA-untagged all the way down.

At a minimum, exposing a network interface for the switch CPU port would allow the PTP protocol to run between the switch and the DSA master, and would allow the user to control the forwarding path for DSA-untagged traffic coming from the master or other upstream interfaces. And the reverse: any attempt to expose interfaces for the hidden ports needs to answer what are their semantics in terms of packet I/O, considering that "no packet I/O" is not a viable option.

Conclusion

This paper attempts to describe the considerations and angles that should be taken into account when writing DSA switch drivers, or when modifying the DSA framework. In some cases the requirements are contradictory, and writing a DSA driver can be more of a creative process than an objective one with a clear goal.

Taming DSA switches and making them behave completely in accordance with the network stack's expectations

proves to be a much more ambitious challenge than initially foreseen, thus the fight continues.

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