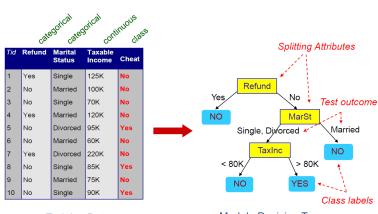
Machine learning with Python Decision Trees



Decision Trees

- Decision trees are a classification methodology, wherein the classification process is modeled with the use of a set of hierarchical decisions on the feature variables, arranged in a tree-like structure.
- The decision at a particular node of the tree is typically a condition on one or more feature variables(split criterion)
- The split criterion divides the training data into two or more parts
- Tree structure:
 - Root node the topmost decision node
 - Internal node- consecutive decision node denote a test on an attribute
 - Branch represents an outcome of the test
 - Leaf node represents a classification label or decision

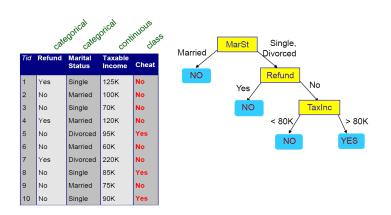
Decision Tree



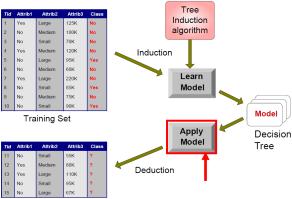
Training Data

Model: Decision Tree

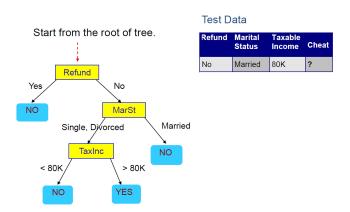
Decision Tree

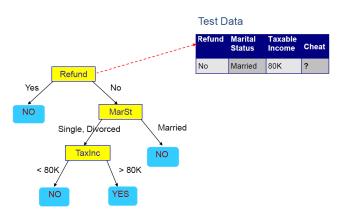


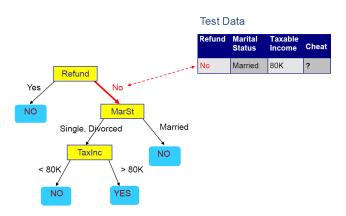
There could be more than one tree trained on the same dataset

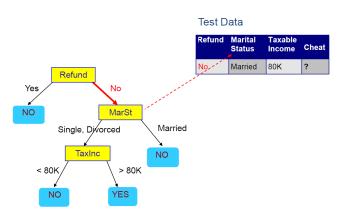


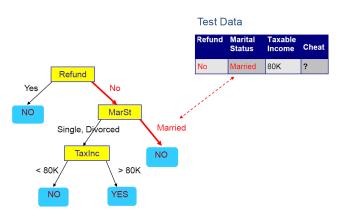
Test Set

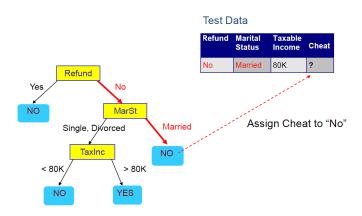








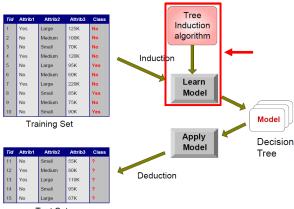




Divide and Conquer

- Decision trees are built using a heuristic called recursive partitioning.
- This approach splits the data into subsets, which are then split repeatedly into even smaller subsets
- The process stops when the algorithm determines the data within the subsets are sufficiently homogenous, or another stopping criterion has been met.
 - Start with bare root node that will grow into a mature tree
 - The decision tree algorithm must choose a feature to split upon
 - The examples are then partitioned into groups according to the distinct values forming branches
 - The algorithm continues to divide and conquer the data, choosing the best candidate feature each time to create another decision node
 - Algorithm stops when stopping criterion is reached

Tree Induction algorithm



Test Set

Generic algorithm

DecisionTree(Data Set: D)

begin

Create root node containing D;

repeat

- Select an eligible node in the tree;
- Split the selected node into two or more nodes based on a pre-defined split criterion;

until no more eligible nodes for split;

- Prune overfitting nodes from tree;
- Label each leaf node with its dominant class;

end

Tree Induction Algorithms

- Hunt's Algorithm one of the earliest
- CART
- ID3, C4.5 C5.0
- SLIQ
- SPRINT

Issues

- How to split the records?
 - How to specify the attribute test condition?
 - How to choose the best split?
- When to stop splitting?
- How to classify a leaf node?

Test Condition

- Depends on two factors:
- Feature data type:
 - Nominal
 - Ordinal
 - Continuous
- Split pattern
 - 2-way split
 - multi-way split

Nominal features split

 Multi-way split- Number of partitions equal to the number of distinct values

 Binary split - distinct values gruped in two partitions (optimize)



Ordinal features split

 Multi-way split - Number of partitions equal to the number of distinct values

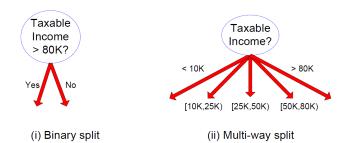


 Binary split - divides values into two subsets, order is maintained(optimize)



Continuous features split

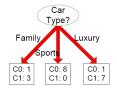
- Multi-way split discretization to ordinal categorical attribute
 - Static intervals set at the beginning
 - Dynamic interval bucketing, clustering
- \bullet Binary all possibles splits are taken into account to find (A < v) or (A > v)

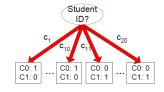


How to determine the best split

• Which test condition is the best?







• We need to measure impurity

C0: 5 C1: 5

Non-homogeneous,

High degree of impurity



Homogeneous,

Low degree of impurity

Choosing the best split

- The first challenge that a decision tree will face is to identify which feature to split
- The degree to which a subset of examples contains only a single class is known as purity
- There are various measurements of purity that can be used to identify the best decision tree splitting candidate:
- Entropy used in C5.0
- Gini used in ID3 and C4.5
- Classification error used in CART, SLIQ, SPRINT

The C5.0 algorithm

- One of the most well-known implementations is the C5.0 algorithm
- Developed by computer scientist J. Ross Quinlan as an improved version of his prior algorithm, C4.5
- C5.0 is a commercial algorithm but the source code for a single-threaded version of the algorithm was made publically available, and has been incorporated into programs such as R
- The C5.0 algorithm has become the industry standard to produce decision trees, because it does well for most types of problems directly out of the box.
- Performs nearly as well as Neural networks and SVM's but trees are much easier to understand and deploy

C5.0 - Strengths

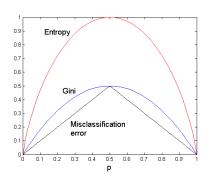
- An all-purpose classifier that does well on most problems
- Highly automatic learning process, which can handle numeric or nominal features, as well as missing data
- Excludes unimportant features
- Can be used on both small and large datasets
- Results in a model that can be interpreted without a mathematical background (for relatively small trees)
- More efficient than other complex models

C5.0 - Weaknesses

- Decision tree models are often biased toward splits on features having a large number of levels
- It is easy to overfit or underfit the model
- Can have trouble modeling some relationships due to reliance on axis-parallel splits
- Small changes in the training data can result in large changes to decision logic
- Large trees can be difficult to interpret and the decisions they make may seem counterintuitive

Splitting measures comparison

- All of the impurity measures take value zero (minimum) for the case of a pure node where a single value has probability 1
- A 50-50 split in a 2-class problem results in a maximum value of measures indicating maximum impurity.



Purity measures

$$Entropy(t) = -\sum_{i=1}^{c} p_i log_2 p_i \tag{1}$$

- For n classes, entropy ranges from 0 to log2(n)
- The minimum value indicates that the sample is completely homogenous, while the maximum value indicates that the data are as diverse as possible
- For a given segment of data (t), the term c refers to the number of class levels and pi refers to the proportion of values falling into class level i.

$$Gini(t) = 1 - \sum_{i=1}^{c} [p_i]^2$$
 (2)

$$Classerror(t) = 1 - max_i[p_i] \tag{3}$$

Example

C1	0
C2	6

$$P(C1) = 0/6 = 0$$
 $P(C2) = 6/6 = 1$
 $Gini = 1 - P(C1)^2 - P(C2)^2 = 1 - 0 - 1 = 0$
 $Entropy = -0 log 0 - 1 log 1 = -0 - 0 = 0$
 $Error = 1 - max (0, 1) = 1 - 1 = 0$

P(C1) = 1/6 P(C2) = 5/6
Gini = 1 - (1/6)² - (5/6)² = 0.278
Entropy = - (1/6)
$$\log_2 (1/6) - (5/6) \log_2 (1/6) = 0.65$$

Error = 1 - max (1/6, 5/6) = 1 - 5/6 = 1/6

P(C1) =
$$2/6$$
 P(C2) = $4/6$
Gini = $1 - (2/6)^2 - (4/6)^2 = 0.444$
Entropy = $-(2/6) \log_2 (2/6) - (4/6) \log_2 (4/6) = 0.92$
Error = $1 - \max (2/6, 4/6) = 1 - 4/6 = 1/3$

Splitting issues

- Impurity measures favor attributes with large number of values
- A test condition with large number of outcomes may not be desirable
- To avoid that problem Information gain is adjusted by the entropy of the partition.
- Large number of partitions is penalized

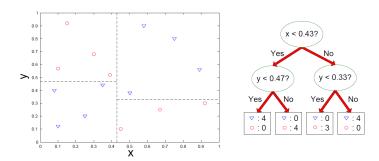
Stopping Criteria

- Algorithm stop expanding a node when all the records belong to the same class
- Algorithm stop expanding a node when all the records have similar feature values
- Early termination pruning

Data fragmentation

- Data fragmentation is a problem in creating decision trees
- Number of instances gets smaller down the tree
- It may cause a problem to make any statistically significant decision if number of instances at the leaf nodes would be too small
- Solution to that problem is a lower bound on the number of items per leaf node in the stopping criterion

Axis-parallel splits



- Decision boundary is a border line between two neighboring regions of different classes
- It is parallel to axes because test condition involves a single attribute at-a-time

Pruning the decision tree

- A decision tree can continue to grow indefinitely until each example is perfectly classified or the algorithm runs out of features to split on
- If the tree grows overly large, will be overly specific and the model will be overfitted to the training data.
- The process of pruning a decision tree involves reducing its size such that it generalizes better to unseen data
- Two types of pruning:
 - pre-pruning
 - post-pruning

Pre-pruning

- Stop the tree from growing once it reaches a certain number of decisions or when the decision nodes contain only a small number of examples.
- Typical rules
 - Stop if all instances belong to the same class
 - Stop if all the attribute values are the same
- Restructive rules
 - Stop if number of instances is less than user-specified threshold
 - Stop if expanding the current node does not improve impurity measures

Post-pruning

- Involves growing a tree that is intentionally too large and pruning leaf nodes to reduce the size of the tree to a more appropriate level.
- The nodes are trimmed in a bottom-up fashion
- If tree improves after trimming, replace sub-tree by a leaf node
- Class label of leaf node is determined from majority class of instances in the sub-tree
- This is often a more effective approach than pre-pruning