Stevens Institute of Technology Department of Electrical and Computer Engineering

CpE 462 Introduction to Image Processing and Coding

Spring Semester 2022 Midterm Exam, Mar. 10, 6:30 – 10:30 PM

Instructions:

- Please provide necessary intermediate steps in your work. You will get zero credit if you only provide the final result without necessary steps.
- All calculations are to be done by hand, with the help of a calculator. Computer is only allowed for viewing lecture notes and course materials.
- Sign the following statement

I pledge on my honor that I have abided by the Stevens honor code

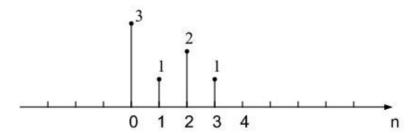
Aly Baskins

Name (print): Alex Gustins

Last four digits of your Student ID: 5143

Problem 1. (10 points) A discrete time signal can be expressed in many forms. Given the following signals:

- (Analytic form) $x_1[n] = 0.2^n$ for $n = \{0, 1, 2, 3\}$
- $(\delta[n] \text{ sequence}) x_2[n] = \delta[n] 2\delta[n-1] \delta[n-2] + 3\delta[n-3]$
- (Graphic form) $x_3[n]$ as shown



a) Express $x_1[n]$ in the form of $\delta[n]$ sequence.

$$0.2^n for n = \{0, 1, 2, 3\}$$

$$0.2^0 = 1$$

$$0.2^1 = 0.2$$

$$0.2^2 = 0.04$$

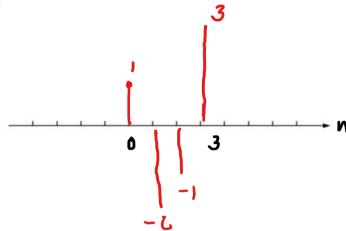
$$0.2^3 = 0.008$$

$$x_1[n] = \delta[n] + (0.2)\delta[n-1] + (0.04)\delta[n-2] + (0.008)\delta[n-3]$$

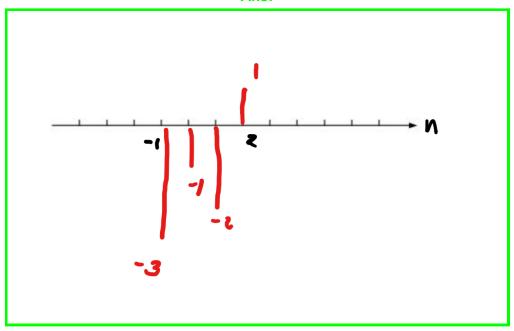
b) Express $x_3[n]$ in the form of $\delta[n]$ sequence.

$$x_{3}[n] = 3\delta[n] + \delta[n-1] + 2\delta[n-2] + \delta[n-3]$$

c) Plot $x_2[-n-2]$



Ans:



Problem 2 (20 points) Determine if the system $y[n] = \frac{1}{3}(x[n] + x[n-1] + x[n-2]) + 1$ is

a) Additive

$$y_{1}[n] = \frac{1}{3} (x_{1}[n] + x_{1}[n-1] + x_{1}[n-2]) + 1$$

$$y_{2}[n] = \frac{1}{3} (x_{2}[n] + x_{2}[n-1] + x_{2}[n-2]) + 1$$

$$T\{ax_{1}[n] + bx_{2}[n]\} = \frac{1}{3} \left((ax_{1}[n] + bx_{2}[n]) + (ax_{1}[n-1] + bx_{2}[n-1]) + (ax_{1}[n-2] + bx_{2}[n-2]) \right) + T\{ax_{1}[n]\} + T\{bx_{1}[n]\} = \left(\frac{1}{3} (ax_{1}[n] + ax_{1}[n-1] + ax_{1}[n-2]) \right) + T\{ax_{1}[n]\} = \left(\frac{1}{3} (ax_{1}[n] + ax_{1}[n-1] + ax_{1}[n-2]) \right) + T\{ax_{1}[n]\} = \left(\frac{1}{3} (ax_{1}[n] + ax_{1}[n-1] + ax_{1}[n-2]) \right) + T\{ax_{1}[n]\} = \left(\frac{1}{3} (ax_{1}[n] + ax_{1}[n-1] + ax_{1}[n-2]) \right) + T\{ax_{1}[n]\} = \left(\frac{1}{3} (ax_{1}[n] + ax_{1}[n-1] + ax_{1}[n-2]) \right) + T\{ax_{1}[n]\} = \left(\frac{1}{3} (ax_{1}[n] + ax_{1}[n-1] + ax_{1}[n-2]) \right) + T\{ax_{1}[n]\} = \left(\frac{1}{3} (ax_{1}[n] + ax_{1}[n-1] + ax_{1}[n-2]) \right) + T\{ax_{1}[n]\} = \left(\frac{1}{3} (ax_{1}[n] + ax_{1}[n-1] + ax_{1}[n-2]) \right) + T\{ax_{1}[n]\} = \left(\frac{1}{3} (ax_{1}[n] + ax_{1}[n-1] + ax_{1}[n-2]) \right) + T\{ax_{1}[n]\} = \left(\frac{1}{3} (ax_{1}[n] + ax_{1}[n-1] + ax_{1}[n-2]) \right) + T\{ax_{1}[n]\} = \left(\frac{1}{3} (ax_{1}[n] + ax_{1}[n-1] + ax_{1}[n-2]) \right) + T\{ax_{1}[n]\} = \left(\frac{1}{3} (ax_{1}[n] + ax_{1}[n] + ax$$

$$T\{ax_{1}[n]\} + T\{bx_{2}[n]\} = (\frac{1}{3}(ax_{1}[n] + ax_{1}[n-1] + ax_{1}[n-2])) + (\frac{1}{3}(ax_{1}[n] + ax_{1}[n-1] + ax_{1}[n-2])) + 2$$

$$T\{ax_{_{1}}[n] \ + \ bx_{_{2}}[n]\} \ \neq \ T\{ax_{_{1}}[n]\} \ + \ T\{bx_{_{2}}[n]\}$$

... Not Additive

b) Homogeneous

$$\begin{split} T\{ax_1[n]\} &= \frac{1}{3} \left(ax_1[n] + ax_1[n-1] + ax_1[n-2]\right) + 1 \\ aT\{x_1[n]\} &= \frac{1}{3} \left(ax_1[n] + ax_1[n-1] + ax_1[n-2]\right) + a \\ T\{ax_1[n]\} &\neq aT\{x_1[n]\} \end{split}$$

∴ Not Homogeneous

c) Time-invariant

$$\begin{split} T\{x[n-n_0]\} &= \frac{1}{3} \left(x_1[n-n_0] + x_1[n-n_0-1] + x_1[n-n_0-2]\right) + 1 \\ y[n-n_0] &= \frac{1}{3} \left(x_1[n-n_0] + x_1[n-n_0-1] + x_1[n-n_0-2]\right) + 1 \\ T\{x[n-n_0]\} &= y[n-n_0] \end{split}$$

... Time Invariant

Problem 3 (20 points) Given $x_1[n] = 2\delta[n] + \delta[n-1] - \delta[n-2]$, $x_2[n] = \delta[n] - 2\delta[n-1]$,

a) Calculate the 1-D convolution $y[n] = x_1[n] * x_2[n]$

$$x_1[n] = [1; n = 0], [-2; n = 1] \text{ where } L_1 = 2$$

 $x_2[n] = [2; n = 0], [1; n = 1], [-1; n = 2] \text{ where } L_2 = 3$
 $y[k] = h[n] * x[n] = \sum_{i=-k}^{L} x[i]h[k-i]$

$$L = [2 - 1] + [3 - 1] = 3$$

$$y[0] = x_2[n] \cdot x_1[4 - n]$$
:

$$(x_{2}[0] \bullet x_{1}[0]) + (x_{2}[1] \bullet x_{1}[3]) + (x_{2}[2] \bullet x_{1}[2]) + (x_{2}[3] \bullet x_{1}[1]) = 2 \bullet 1 + 1 \bullet 0 + - 1 \bullet 0 + 0 \bullet - 2 = 2$$

$$y[1] = x_2[n] \cdot x_1[1 - n]$$
:

$$(x_{2}[0] \bullet x_{1}[1]) + (x_{2}[1] \bullet x_{1}[0]) + (x_{2}[2] \bullet x_{1}[3]) + (x_{2}[3] \bullet x_{1}[2]) = 2 \bullet -2 + 1 \bullet 1 + -1 \bullet 0 + 0 \bullet 0 = -3$$

$$y[2] = x_2[n] \cdot x_1[2 - n]$$
:

$$(x_2[0] \bullet x_1[2]) + (x_2[1] \bullet x_1[1]) + (x_2[2] \bullet x_1[0]) + (x_2[3] \bullet x_1[3]) = 2 \bullet 0 + 1 \bullet - 2 + -1 \bullet 1 + 0 \bullet 0 = -3$$

$$y[3] = x_2[n] \cdot x_1[3 - n]$$
:

$$(x_{2}[0] \bullet x_{1}[3]) + (x_{2}[1] \bullet x_{1}[2]) + (x_{2}[2] \bullet x_{1}[1]) + (x_{2}[3] \bullet x_{1}[0]) = 2 \bullet 0 + 1 \bullet 0 + -1 \bullet -2 + 0 \bullet 1 = 2$$

$$y[n] = \{2, -3, -3, 2\}$$

b) Calculate the 4-point DFT of the output y[n], i.e. Y[k] for k=0, 1, 2, 3. (Show your steps)

$$y[n] = \{2, -3, -3, 2\}$$

$$y[k] = \sum_{n=0}^{3} y[n] \cdot W_{4}^{k_{n}} = \sum_{n=0}^{3} y[n] \cdot e^{-j\frac{2\pi}{N}kn}$$

$$y[0] = 2 - 3 - 3 + 2 = -2$$

$$y[1] = 2 - 3e^{-j\frac{2\pi}{4}} - 3e^{-j\pi} + 2e^{-j\frac{2\pi}{4}3} = 2 + 3j + 3 + 2j = 5 + 5j$$

$$y[2] = 2 - 3e^{-j\pi} - 3e^{-j\frac{2\pi}{4}4} + 2e^{-j\frac{2\pi}{4}6} = 2 + 3 - 3 - 2 = 0$$

$$y[3] = 2 - 3e^{-j\frac{2\pi}{4}3} - 3e^{-j\frac{2\pi}{4}6} + 2e^{-j\frac{2\pi}{4}9} = 2 - 3j + 3 - 2j = 5 - 5j$$

$$y[k] = \{-2, 5 + 5j, 0, 5 - 5j\}$$

Problem 4 (20 points) Calculate the 2×2 DCT of the following 2-D signal

$$x[n_1,n_2] = \begin{bmatrix} 1 & -2 \\ 1 & a \end{bmatrix}$$

where a is a constant. (Your answer will contain a in it.)

$$| \frac{1}{\sqrt{N}}, k = 0, 0 \le n \le N - 1$$

$$c(k, n) = \left\{ \sqrt{\frac{2}{N}} cos \frac{\pi(2n+1)k}{2N}, 1 \le k \le N - 1, 0 \le n \le N - 1 \right.$$

$$c(0, 0) = c(0, 1) = \frac{1}{\sqrt{N}} = \frac{1}{\sqrt{2}}$$

$$c(1, 0) = \sqrt{\frac{2}{2}} cos \left[\frac{-(2(0)+1)n(1)}{2(2)} \right] = \frac{1}{\sqrt{2}}$$

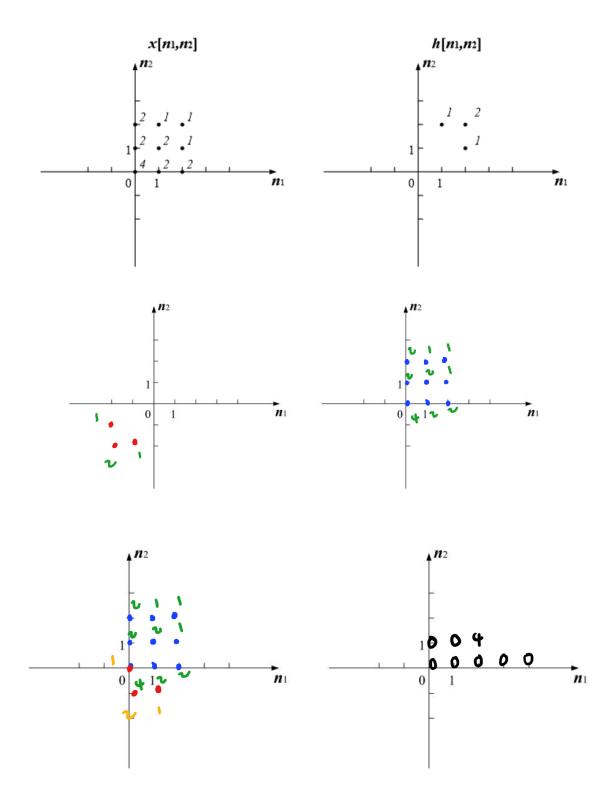
$$c(1, 1) = \sqrt{\frac{2}{2}} cos \left[\frac{(2(1)+1)n(1)}{2(2)} \right] = \frac{-1}{\sqrt{2}}$$

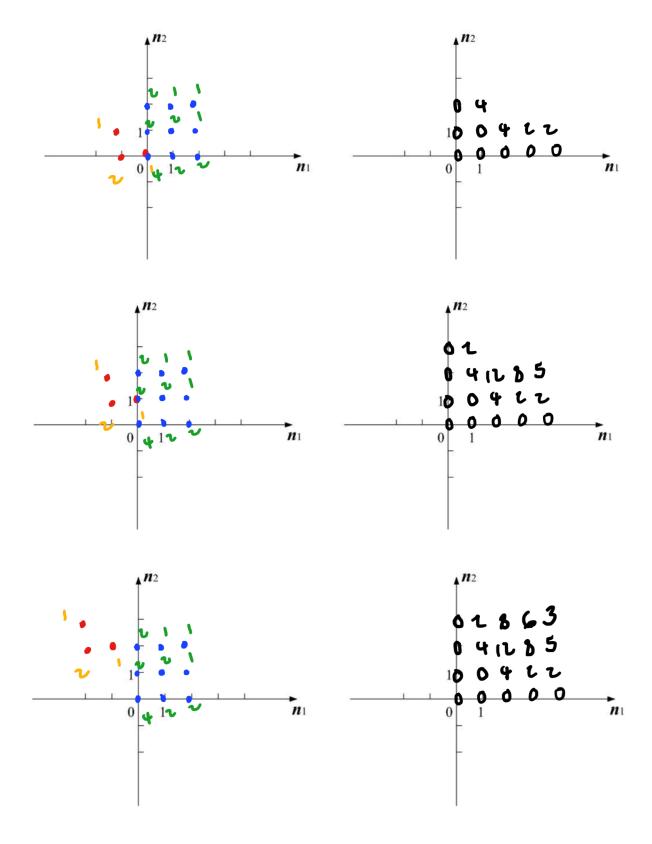
$$dct = \left[\frac{1}{\sqrt{2}} \frac{1}{\sqrt{2}} \right] \left[1 - 2 \right] \left[\frac{1}{\sqrt{2}} \frac{1}{\sqrt{2}} \right]$$

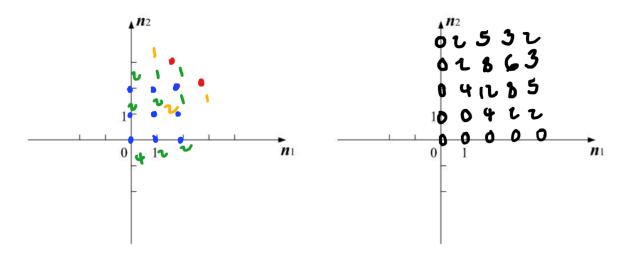
$$\left[\frac{1}{\sqrt{2}} \frac{1}{\sqrt{2}} \right] \left[1 - a \right] \left[\frac{1}{\sqrt{2}} \frac{1}{\sqrt{2}} \right]$$

$$dct = \begin{bmatrix} \frac{a}{2} & \frac{-a+4}{2} \\ \left\lfloor \frac{-a-2}{2} & -\frac{-a-2}{2} \right\rfloor \end{bmatrix}$$

Problem 5 (20 points) Given a 2-D signal $x[n_1, n_2]$ and a 2-D system $h[n_1, n_2]$ as shown, calculate the 2-D convolution of $y[n_1, n_2] = x[n_1, n_2]$ ** $h[n_1, n_2]$. (Show some steps)







 $y[n, n] = \{0, 0, 0, 0, 0, 0, 0, 4, 2, 2, 4, 12, 8, 5, 0, 2, 8, 6, 3, 0, 2, 5, 3, 2\}$

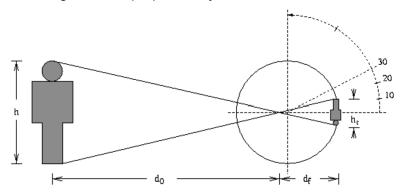
Problem 6 (10 points) Consider the human visual system

a) Discuss if our eyes are more sensitive to small amplitude noise in dark regions or bright regions of an image. Please provide explanation.

Brightness is closely related to intensity, but it is not proportional to intensity, but rather, a logarithmic function of intensity. According to Weber's ratio, $\frac{\Delta l}{l} \approx const \approx 0.02$ for a large range of values I, it is suggested that our brightness perception is closely related to contrast. Thus, it is implied that we are better able to notice differences in intensity when the image is **dark** than when it is light.

b) Describe the procedure to calculate the optimal viewing distance of an image. (You answers should be no longer than 5 short sentences.)

When viewing an object with a specific height (h), the distance (d_f) between the focal center of the lens and the retina is typically between 14 and 17 mm. Assuming these values are known, the next step is to recall that the viewing distance (d₀) is inversely proportional to the perceived height in the retina (h_r). We can use the expression $d_0 = \frac{d_f h}{h_r}$, where h_r increases with viewing angle. With a known viewing angle θ , h_r can be calculated as $d_f[2tan\theta]$, thus resulting in the optimal viewing distance being equal to $\frac{1}{2} \left[\frac{h}{d_f tan\theta} \right]$. It must be noted that there is a cutoff point where the distance is too big/small for proper clarity.



• The distance between the focal center of the lens and the retina $d_f=14 \sim 17 \text{ mm}$

• The size of the object at retina is $h_r = \frac{d_f h}{d_0}$