

Kernel Tricks.

SVM with linear boundary.

$$\max_d \left(\sum d_i - \frac{1}{2} \sum d_i d_j y^{(i)} y^{(j)} x^{(i)T} x^{(j)} \right)$$

$$\text{s.t. } \sum d_i y^{(i)} = 0, \quad d_i \in [0, \frac{\lambda}{m}]$$

But linear features have their limits,

for more effective hypothesis/decision boundary

we need non-linear feature space, $x \rightarrow \phi(x)$

$$\text{e.g.) } x = (1, x_1, x_2, \dots, x_n) \in \mathbb{R}^{n+1}$$

$$\phi(x) = (1, x_1, x_2, x_2 x_2, \dots, x_i x_j, \dots, x_n^2,$$

$$x_1 x_2 x_3, \dots, x_i x_j x_k, \dots, x_n^3,$$

$$\vdots$$

$$x_1 x_2 \dots x_p, \dots, x_n^p)$$

$$(p < n)$$

$\Rightarrow p + nP_p$ features, very large

With large enough feature space $(\phi(x))$, it is almost impossible to solve

$$\max_{\alpha} \left(\sum d_i - \frac{1}{2} \sum d_i d_j y^{(i)} y^{(j)} \underbrace{\phi(x^{(i)})^T \phi(x^{(j)})}_{O(d^2)} \right)$$

$O(d^2)$ where $\phi(x) \in \mathbb{R}^d$

• Kernel function

a function $K(x^{(i)}, x^{(j)})$ that
can replace $\phi(x^{(i)})^T \phi(x^{(j)})$

e.g.)

$$X = (x_1, x_2, x_3), \quad u, v \in X$$

$$\phi(x) = (x_1^2, x_2^2, x_3^2, \sqrt{2}x_1x_2, \sqrt{2}x_2x_3, \sqrt{2}x_1x_3)$$

$$\text{then } \phi^T(u)\phi(v) = (u_1^2v_1^2 + u_2^2v_2^2 + u_3^2v_3^2 + 2u_1u_2v_1v_2 + 2u_2u_3v_2v_3 + 2u_1u_3v_1v_3)$$

$$u^T v = (u_1v_1 + u_2v_2 + u_3v_3)$$

We define a polynomial kernel function $K(x^{(i)}, x^{(j)})$,

$K(x^{(i)}, x^{(j)}) = (x^{(i)T} x^{(j)})^p$ where p is the ^{highest} degree of the polynomial feature,

then $\underbrace{\phi^T(u)}_{O((n+np_2)^2)} \underbrace{\phi(v)}_{O(n^2)} = \underbrace{(u^T v)^2}_{O(n^2)} = K(u, v)$

the kernel function safely replaces $\phi^T \phi$
and saves us the trouble of calculating
complex features.

* There are other kernel functions as well.