

CS501 Project: The Maze

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Introduction

- In this project, our aim is to solve maze problems using both DFT & BFT techniques.
 - We will also implement the algorithms using Python with which we will test the test cases on Leetcode.
 - Finally, we will compare and contrast the two solution approaches (DFT & BFT) and infer which one is better in terms of time and space complexity
-

Design

- The problem involves navigating a maze represented as a 2D grid to determine if a path exists from the start to the destination.
 - We will discuss two approaches: Depth-First Search (DFS) and Breadth-First Search (BFS), each with its own advantages and trade-offs.
-

Design cont.

DFT

- Key Components:
 - Starting from the initial position, explore each possible path until reaching the destination or exhausting all options.
 - Backtrack when reaching dead ends to explore alternative paths.
- Implementation:
 - We'll implement DFS recursively to traverse the maze efficiently.

BFT

- Key Components:
 - Explore all possible paths level by level, starting from the initial position.
 - Ensures finding the shortest path first due to its nature of exploring closer nodes before moving farther.
 - Implementation:
 - We'll implement BFS using a queue data structure to manage the traversal of the maze.
-

Design cont.

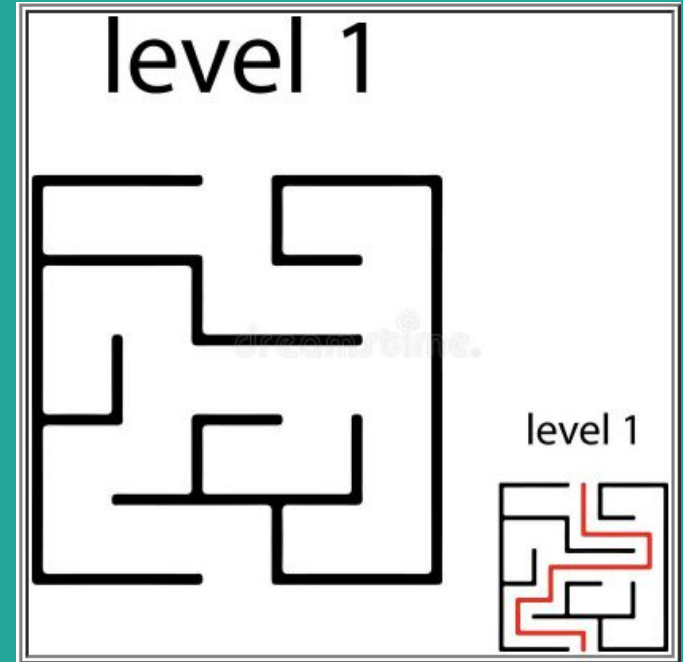
- Both DFS and BFS have a time complexity of $O(V + E)$, where V is the number of vertices (cells in the maze) and E is the number of edges (possible movements between cells).
- DFS uses less memory as it traverses deeper before backtracking, while BFS explores the maze level by level, potentially using more memory.
- Diagrams (sketches) illustrating how DFS and BFS algorithms traverse the maze will be provided to aid in understanding the traversal process and the solutions to the problems.
- Python code for both DFS and BFS solutions will be presented to clarify the algorithmic logic and implementation details.

Implementation & Testing

1. DFT

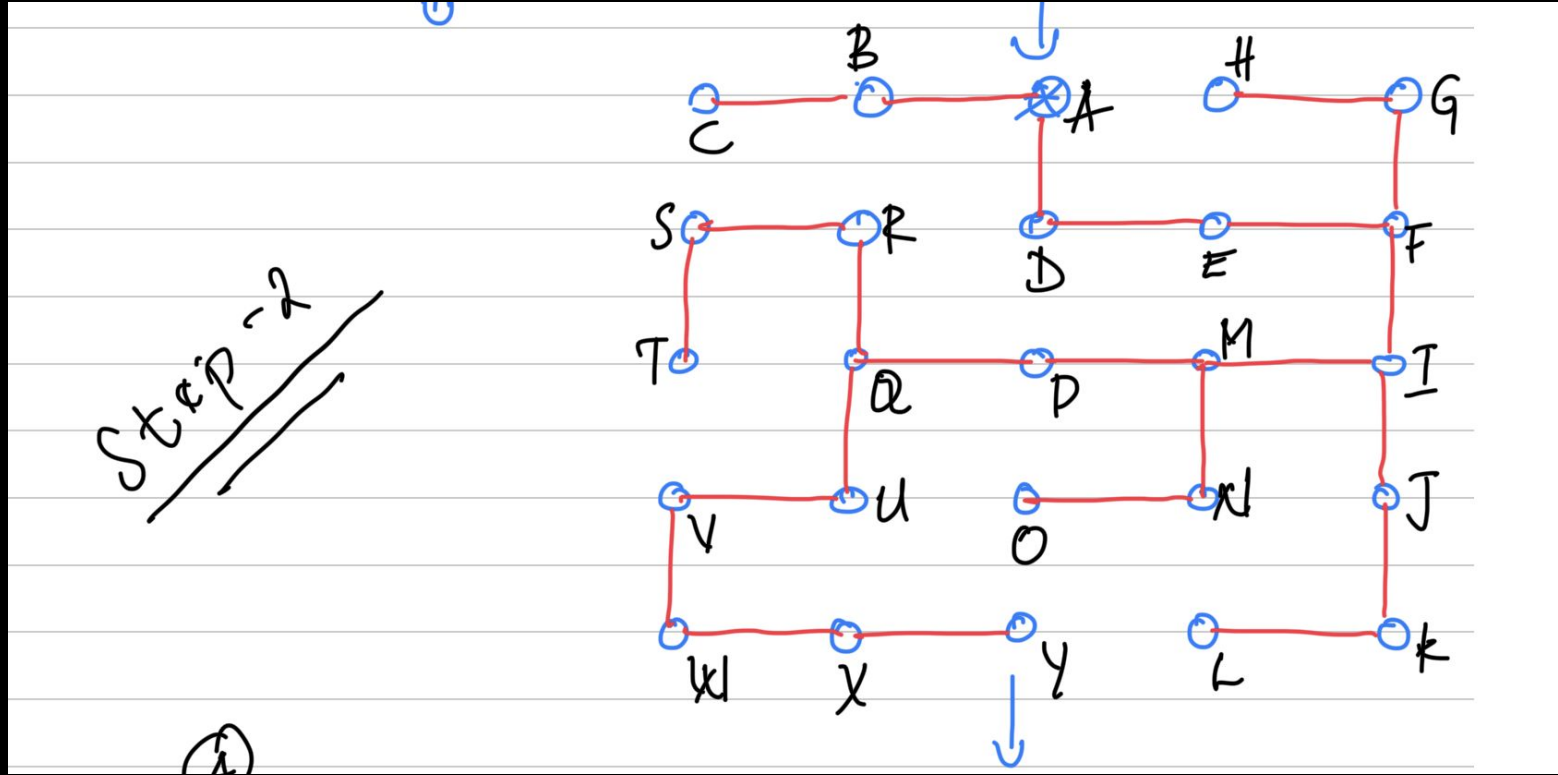
- Manual Solution for Problem 1
- Manual Solution for Problem 2
- LeetCode Solution - Python
- Test Cases Execution
Screenshot

1. Manually solve the following problem using DFT (Depth First Traversal):
 - Without Wheel

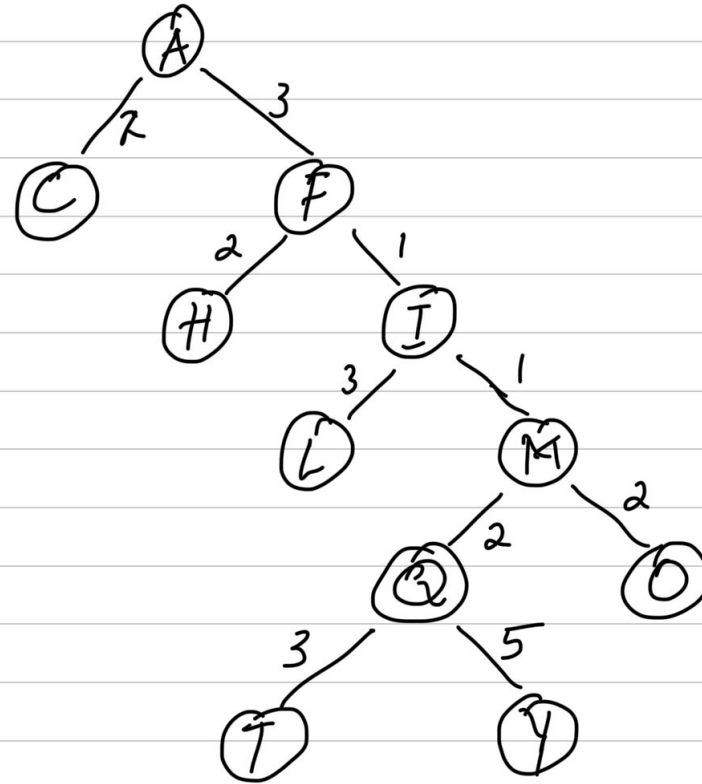




Build the tree first: cont.



Build the tree first: cont.

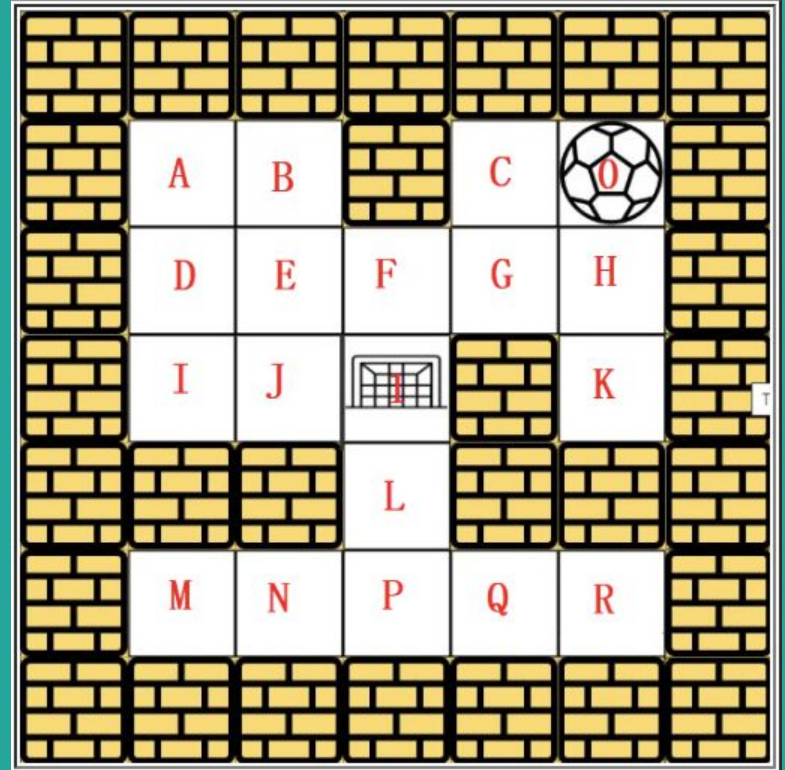


Now using DFT, the below table shows the traversed leaves added and popped from a stack.

[illegible]

2. Manually solve the following problem using DFT (Depth First Traversal):

- With Wheel



Using DFT, the following table shows the traversed leaves added and popped from a stack.

[illegible]

Python Code Solution for Leetcode Problem 490.

```
def hasPath(maze, start, destination) -> bool:
    if not maze:
        return False
    m, n = len(maze), len(maze[0])
    visited: set[tuple[int, int]] = set()
    def dfs(x: int, y: int):
        if [x, y] == destination:
            return True
        if (x, y) in visited:
            return False
        visited.add((x, y))
        # Try moving in all four directions
        directions = [(0, 1), (0, -1), (1, 0), (-1, 0)]
        for dx, dy in directions:
            newX: int = x + dx
            newY: int = y + dy
            # Keep moving until hitting a wall or the boundary
            while 0 <= newX < m and 0 <= newY < n and
                maze[newX][newY] == 0:
                newX += dx
                newY += dy
                # When hitting a wall or boundary,
                # perform DFS from the new position
                if dfs(newX - dx, newY - dy):
                    return True
            return False
    return dfs(start[0], start[1])
```


Execution/Output Screenshot

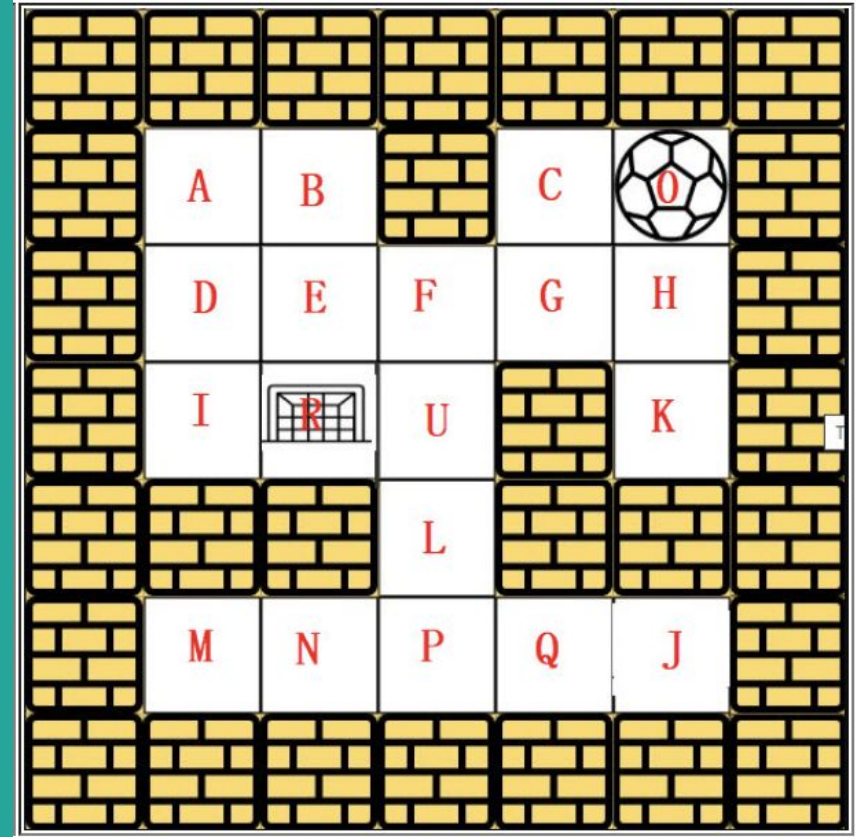
```
Welcome 501.py x
Users > nati > Documents > sfbu > CS501 > homeworks > project > 501.py > hasPath
1 def hasPath(maze: list[list[int]], start: list[int], destination: list[int]):
2     if not maze:
3         return False
4     m, n = len(maze), len(maze[0])
5     visited: set[tuple[int, int]] = set()
6     def dfs(x: int, y: int):
7         if [x, y] == destination:
8             return True
9         if (x, y) in visited:
10            return False
11        visited.add((x, y))
12        # Try moving in all four directions
13        directions = [(0, 1), (0, -1), (1, 0), (-1, 0)]
14        for dx, dy in directions:
15            newX: int = x + dx
16            newY: int = y + dy
17            # Keep moving until hitting a wall or the boundary
18            while 0 <= newX < m and 0 <= newY < n and maze[newX][newY] == 0:
19                newX += dx
20                newY += dy
21            # When hitting a wall or boundary, perform DFS from the new position
22            if dfs(newX - dx, newY - dy):
23                return True
24        return False
25    return dfs(start[0], start[1])
26    # Test the function
27    maze, start, destination = [[0,0,1,0,0], [0,0,0,0,0], [0,0,0,1,0], [1,1,0,1,1], [0,0,0,0,0]], [0, 4], [4, 4]
28    print(hasPath(maze, start, destination)) # Output: True
29    maze, start, destination = [[0,0,1,0,0], [0,0,0,0,0], [0,0,0,1,0], [1,1,0,1,1], [0,0,0,0,0]], [0, 4], [3, 2]
30    print(hasPath(maze, start, destination)) # Output: False
31    maze, start, destination = [[0,0,0,0,0], [1,1,0,0,1], [0,0,0,0,0], [0,1,0,0,1], [0,1,0,0,0]], [4, 3], [0, 1]
32    print(hasPath(maze, start, destination)) # Output: False

PROBLEMS OUTPUT TERMINAL PORTS SERIAL MONITOR DEBUG CONSOLE
cd /Users/nati/Documents/sfbu/CS501/homeworks/project
/usr/bin/python3 /Users/nati/Documents/sfbu/CS501/homeworks/project/501.py
nati@Natis-Macbook ~ % cd /Users/nati/Documents/sfbu/CS501/homeworks/project
nati@Natis-Macbook project % /usr/bin/python3 /Users/nati/Documents/sfbu/CS501/homeworks/project/501.py
True
False
False
nati@Natis-Macbook project %
```

2. BFT

- Manual Solution for Problem 1
- LeetCode Solution - Python
- Test Cases Execution
Screenshot

- Manually solve the following problem using BFT (Breadth First Traversal):
- With Wheel



Using BFT, the following table shows the traversed cells of the maze added and removed from a queue.

Visited: 0 0 Queue: <hr/> Visited: 0 1 Queue: 0 1. Add 0 to the queue 2. Mark 0 as visited <hr/> Visited: 0 1 Queue: 1. Remove 0 from the queue 2. Print 0 <hr/> Visited: 0 C K 1 1 1 Queue: C K 1. Add C and K to the queue 2. Mark C and K as visited <hr/> Visited: 0 C K 1 1 1 Queue: K 1. Remove C from the queue 2. Print 0 C <hr/> Visited: 0 C K G 1 1 1 1 Queue: K G 1. Add G to the queue 2. Mark G as visited	Visited: 0 C K G 1 1 1 1 Queue: G 1. Remove K from the queue 2. Print: 0 C K <hr/> Visited: 0 C K G 1 1 1 1 Queue: 1. Remove G from the queue 2. Print 0 C K G <hr/> Visited: 0 C K G D 1 1 1 1 1 Queue: D 1. Add D to the queue 2. Mark D as visited <hr/> Visited: 0 C K G D 1 1 1 1 1 Queue: 1. Remove D from the queue 2. Print: 0 C K G D <hr/> Visited: 0 C K G D A I 1 1 1 1 1 1 1 Queue: A I 1. Add A, I to the queue 2. Mark A, I as visited Visited: 0 C K G D A I 1 1 1 1 1 1 1 Queue: I 1. Remove A from the queue 2. Print: 0 C K G D A <hr/> Visited: 0 C K G D A I B 1 1 1 1 1 1 1 1 Queue: I B 1. Add B to the queue 2. Mark B as visited	Visited: 0 C K G D A I B 1 1 1 1 1 1 1 1 Queue: B 1. Remove I from the queue 2. Print: 0 C K G D A I <hr/> Visited: 0 C K G D A I B R 1 1 1 1 1 1 1 1 1 Queue: B R 1. Add R to the queue 2. Mark R as visited <hr/>
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Python Code Solution for Leetcode Problem 490.

```
from collections import deque
```

```
def hasPath(maze, start, destination) -> bool:
```

```
    if not maze or not maze[0]:
```

```
        return False
```

```
    rows, cols = len(maze), len(maze[0])
```

```
    visited: set[tuple[int, int]] = set()
```

```
    queue = deque([tuple(start)])
```

```
    directions: list[tuple[int, int]] = [(0, 1), (0, -1),
```

```
(1, 0), (-1, 0)]
```

```
    while queue:
```

```
        i, j = queue.popleft()
```

```
        if [i, j] == destination:
```

```
            return True
```

```
        if (i, j) in visited:
```

```
            continue
```

```
        visited.add((i, j))
```

```
    for dx, dy in directions:
```

```
        x, y = i, j
```

```
        while 0 <= x + dx < rows and 0 <= y + dy <
            cols and maze[x + dx][y + dy] == 0:
```

```
            x += dx
```

```
            y += dy
```

```
        if (x, y) not in visited:
```

```
            queue.append((x, y))
```

```
    return False
```

Execution/Output Screenshot

```
bft dft.py
bft > hasPath
1  from collections import deque
2
3  def hasPath(maze: list[list[int]], start: list[int], destination: list[int]) -> bool:
4      if not maze or not maze[0]:
5          return False
6      rows, cols = len(maze), len(maze[0])
7      visited: set[tuple[int, int]] = set()
8      queue = deque([tuple(start)])
9      directions: list[tuple[int, int]] = [(0, 1), (0, -1), (1, 0), (-1, 0)]
10     while queue:
11         i, j = queue.popleft()
12         if [i, j] == destination:
13             return True
14         if (i, j) in visited:
15             continue
16         visited.add((i, j))
17         for dx, dy in directions:
18             x, y = i, j
19             while 0 <= x + dx < rows and 0 <= y + dy < cols and maze[x + dx][y + dy] == 0:
20                 x += dx
21                 y += dy
22                 if (x, y) not in visited:
23                     queue.append((x, y))
24     return False
25
26 # Test the function
27 maze, start, destination = [[0,0,1,0,0], [0,0,0,0,0], [0,0,0,1,0], [1,1,0,1,1], [0,0,0,0,0]], [0, 4], [4, 4]
28 print(hasPath(maze, start, destination)) # Output: True
29 maze, start, destination = [[0,0,1,0,0], [0,0,0,0,0], [0,0,0,1,0], [1,1,0,1,1], [0,0,0,0,0]], [0, 4], [3, 2]
30 print(hasPath(maze, start, destination)) # Output: False
31 maze, start, destination = [[0,0,0,0,0], [1,1,0,0,1], [0,0,0,0,0], [0,1,0,0,1], [0,1,0,0,0]], [4, 3], [0, 1]
32 print(hasPath(maze, start, destination)) # Output: False
33
PROBLEMS OUTPUT TERMINAL PORTS SERIAL MONITOR DEBUG CONSOLE
cd /Users/nati/Documents/sfbu/CS501/homeworks/project
/usr/bin/python3 /Users/nati/Documents/sfbu/CS501/homeworks/project/bft
nati@Natis-Macbook project % cd /Users/nati/Documents/sfbu/CS501/homeworks/project
nati@Natis-Macbook project % /usr/bin/python3 /Users/nati/Documents/sfbu/CS501/homeworks/project/bft
True
False
False
nati@Natis-Macbook project %
```

Enhancement Ideas

- Implement optimization techniques such as memoization to improve the efficiency of DFS and BFS algorithms.
 - Explore parallelization strategies by dividing the maze into smaller sections to accelerate maze traversal.
 - Utilize dynamic programming techniques to optimize the computation of solutions.
-

Conclusion

- Our analysis of this project using DFS and BFS techniques reveals their distinct approaches to maze traversal.
 - DFS efficiently explores paths until a solution is found or a dead end is reached, while BFS systematically explores all possible paths level by level, prioritizing the shortest path.
-

Conclusion cont.

- We've outlined key components, implementation strategies, and complexities for both approaches.
- Visual aids and Python code enhance comprehension and implementation.
- With these approaches, we gain versatile tools for solving maze navigation problems efficiently, whether prioritizing simplicity and memory efficiency with DFS or guaranteeing the shortest path with BFS.
- Our exploration equips us with valuable problem-solving skills applicable to diverse scenarios.

References

- [robot path planning](#)
- [Robotic Path Planning](#)
- [Breadth-First and Depth-First Search for Path Planning](#)
- [A framework for robot path finding in unstructured environments](#)
- [A Comprehensive Study on Pathfinding Techniques for Robotics and Video Games](#)

Github Link

<https://github.com/cur10usityDrives/Algorithms/tree/main>

An aerial photograph of a large, intricate hedge maze made of green hedges. The maze features a complex pattern of rectangular and square paths. The text "THANK YOU" is written in a white, casual, handwritten-style font across the center of the image. The perspective is from a high angle, looking down into the maze.

THANK YOU