

## **Computing Infrastructures**

System Dependability

Reliability and Availability

# The topics of the course: what are we going to see today?





#### **HW Infrastructures**:

**System-level**: Computing Infrastructures and Data Center Architectures, Rack/Structure;

Node-level: Server (computation, HW accelerators), Storage (Type, technology), Networking (architecture and technology);

**Building-level**: Cooling systems, power supply, failure recovery

#### **SW Infrastructures**:

#### Virtualization:

Process/System VM, Virtualization Mechanisms (Hypervisor, Para/Full virtualization)

#### **Computing Architectures:**

Cloud Computing (types, characteristics), Edge/Fog Computing, X-as-a service



#### Methods:

Reliability and availability of datacenters (definition, fundamental laws, RBDs)

**Disk performance** (Type, Performance, RAID)

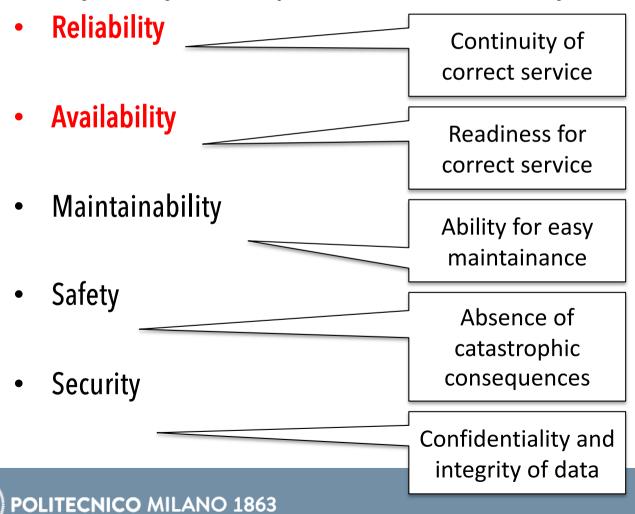
Scalability and performance of datacenters (definitions, fundamental laws, queuing network theory)

#### What dependability is? (SLIDE Form the OVERVIEW SET)

A measure of how much we trust a system...

...from a microwave oven up to an airplane and a large datacenter!

The ability of a system to perform its functionality while exposing:



#### Reliability

The ability of a system or component to perform its required functions under stated conditions for a specified period of time [IEEE610]

[IEEE610]: IEEE Standard Glossary of Software Engineering Terminology, IEEE Std 610.12-1990 (R2002).

R(t): probability that the system will operate correctly in a specified operating environment until time *t* 

R(t) = P(not failed during [0, t])assuming it was operating at time t = 0

- t is important!
- If a system needs to work for slots of ten hours at a time, then ten hours is the reliability target
- Often used to characterize systems in which even small periods of incorrect behavior are unacceptable (e.g. Impossibility to repair)

#### **Characteristics**

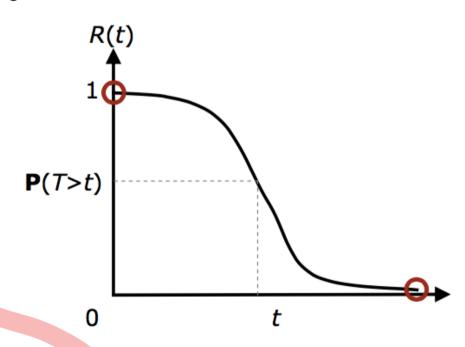
1 - R(t): unreliability, also denoted Q(t)

R(t) is a non-increasing function varying from 1 to 0 over  $[0, +\infty)$ 

$$R(0) = 1$$

$$\lim_{t \to +\infty} R(t) = 0$$

$$f(x) = -\frac{\mathrm{d}R(t)}{\mathrm{d}t}$$



probability density function of the failure

## **Availability**

The degree to which a system or component is operational and accessible when required for use [IEEE610]

 [IEEE610]: IEEE Standard Glossary of Software Engineering Terminology, IEEE Std 610.12-1990 (R2002).

Availability = Uptime / (Uptime + Downtime)

- Fundamentally different from reliability
  - "reliability: does not break down ..."
  - "availability: even if it breaks down, it is working when needed...
- Any examples of designs requiring high reliability/availability?

#### definition

A(t): probability that the system will be operational at time t

```
A(t) = P(\text{not failed at time } t)
```

- Literally, readiness for service
- Admits the possibility of brief outages
- When the system is not repairable: A(t) = R(t)
- In general (repairable systems):  $A(t) \ge R(t)$
- 1 A(t): unavailability

#### Some numbers

Availability as a function of the "number of 9's"

Number of 9's	Availability	Downtime (mins/year)	Practical meaning
1	90%	52596.00	~5 weeks per year
2	99%	5259.60	~4 days per year
3	99.9%	525.96	~9 hours per year
4	99.99%	52.60	~1 hour per year
5	99.999%	5.26	~5 minutes per year
6	99.9999%	0.53	~30 secs per year
7	99.99999%	0.05	~3 secs per year

# Some example

Number of 9's	Availability	Downtime/year	System
2	99%	~4 days	Generic web site
3	99.9%	~9 hours	Amazon.com
4	99.99%	~1 hour	Enterprise server
5	99.999%	~5 minutes	Telephone system
6	99.9999%	~30 seconds	Network switches

#### R(t) & A(t): Two points of view

#### Of course, they are related:

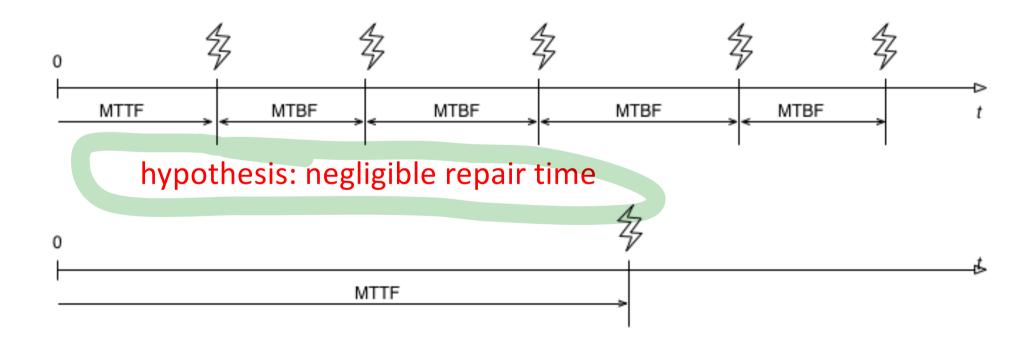
if a system is unavailable it is not delivering the specified system services

# It is possible to have systems with low reliability that must be available

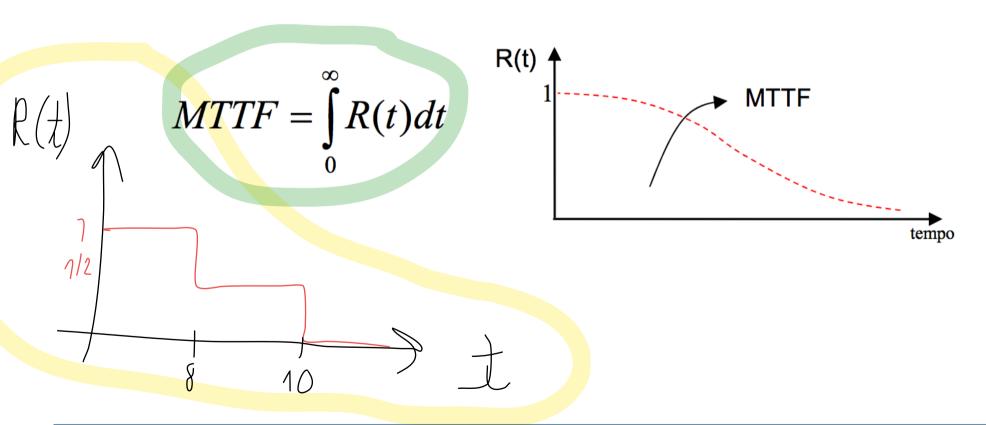
 system failures can be repaired quickly and do not damage data, low reliability may not be a problem (for example a database management system)

The opposite is generally more difficult...

MTTF (Mean Time To Failure): mean time before any failure will occur MTBF (Mean Time Between Failures): mean time between two failures



MTTF (Mean Time To Failure): mean time before any failure will occur



MTTF: mean time to (first) failure, the up time before the first failure

MTBF: mean time between failures

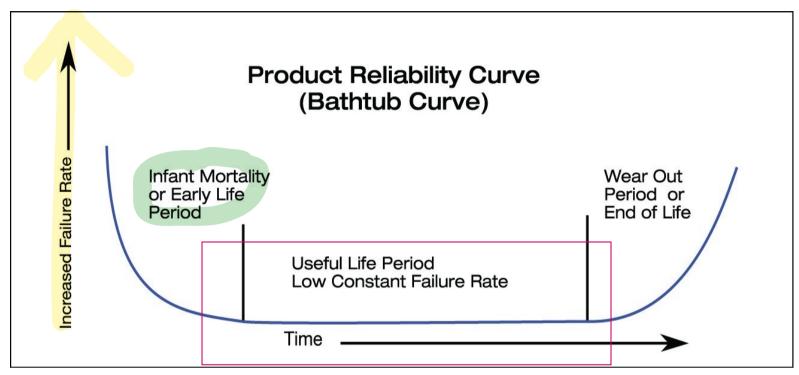
FIT: failures in time

Failure Rate  $\lambda = \frac{\text{number of failures}}{\text{total operating time}}$ 

another way of reporting MTBF

- the number of expected failures per one billion hours (109) of operation for a device
- MTBF (in h) =  $10^9/FIT$

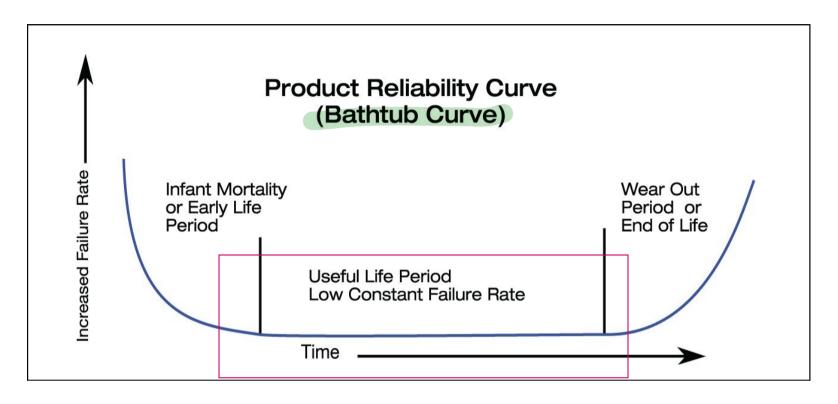
$$MTBF = \frac{1}{\lambda}$$



Infant Mortality: failures showing up in new systems. Usually this category is present during the testing phases, and not during production phases. Random Failures: showing up randomly during the entire life of a system.

Our main focus

Wear Out: at the end of its life, some components can cause the failure of a system. Predictive mainteinance can reduce the number of this type of failures.

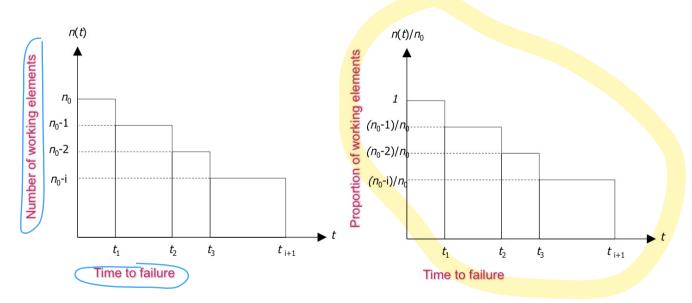


How to identify defective products and calculate MTTF?

Burn-in test: *stress* the system with excessive temperature, voltage, current, humidity so to accelerate wear out.

#### How to compute reliability? Empirical Evaluation

- Let's consider  $n_0$  independent and statistically identical elements deployed at time t = 0 in identical conditions  $n(0) = n_0$
- At time t, n(t) elements are not failed
- $t_1, t_2, ... t_{n0}$  are the times to failure of the  $n_0$  elements
  - times to failure are independent occurrences of the random quantity τ



• Function  $n(t)/n_0$  is the empirical function of reliability that as  $n_0 \to \infty$  converges to the value:  $n(t)/n_0 \to R(t)$ 

## **Different types of faults**

#### •Hardware faults:

- Electronic
- Mechanical

•Software faults:



```
split(" "); } $("#unique")

array_from_string($("#fin")

(), c = use_unique(array final)

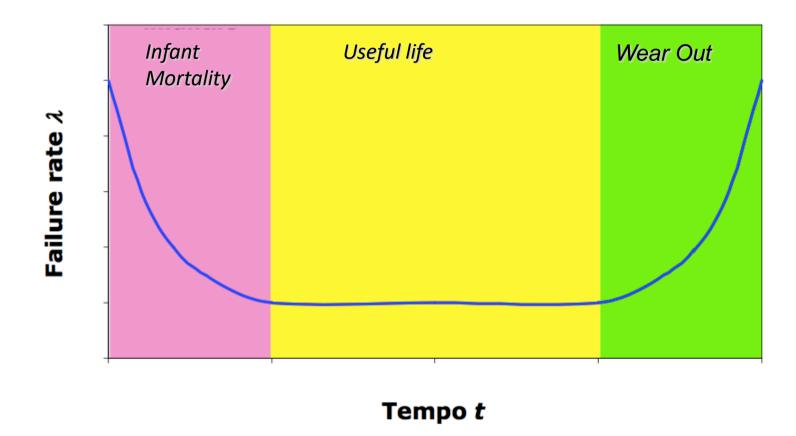
(i))); if (c < 2 * b - 1)

this.trigger("click")

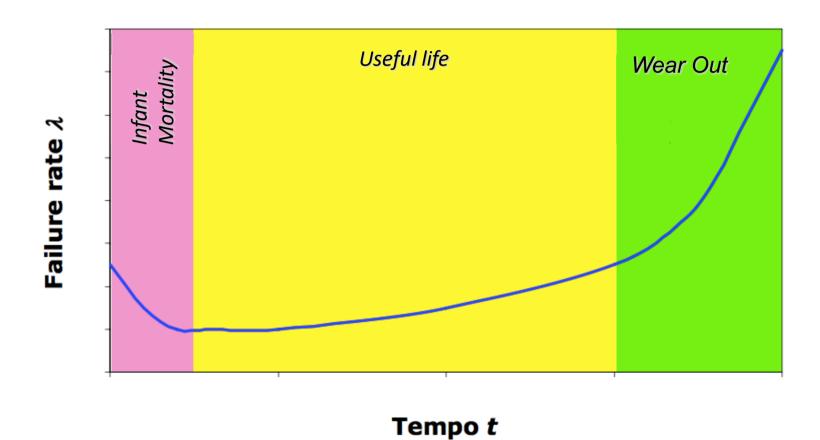
[b] && " " != a[b]

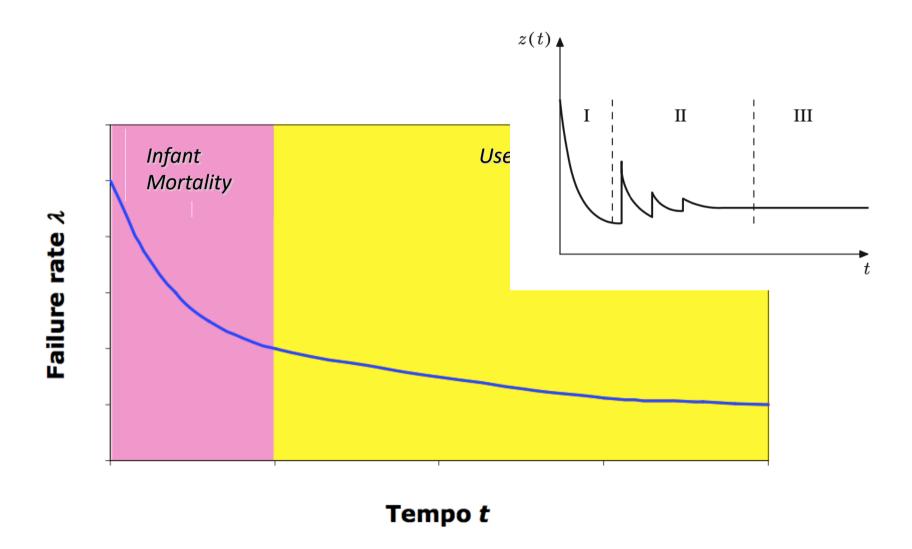
[c] &&
```

# Hardware: electronic components



# **Hardware: Mechanical components**





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#### R(t) ... what to do?

Exploitation of R(t) information is used to compute, for a complex system, its reliability in time, that is the expected lifetime

computation of the MTTF

Computation of the overall reliability starting from the components' one

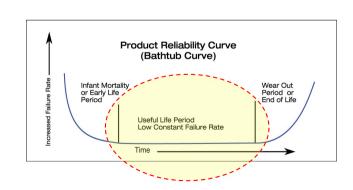
Within the course we consider only a reliability with an exponential distribution:

**Constant Failure rate** 

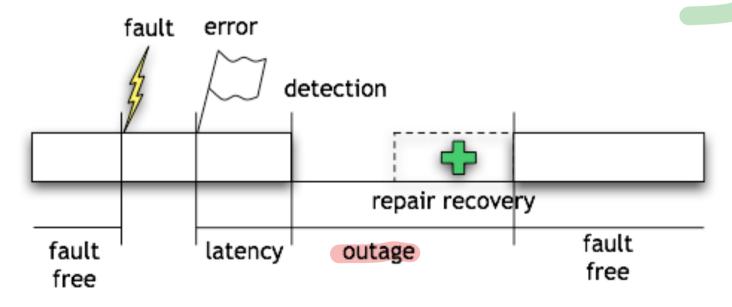
$$R(t) = e^{-\lambda t}$$

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$$MTTF = \int_{0}^{\infty} R(t) dt = \frac{1}{\lambda}$$



Term	Term Description	
Fault	A defect within the system	
Error	A deviation from the required operation of the system or subsystem	
Failure	The system fails to perform its required function	



An example: a flying drone with an automatic radar-guided landing system

Fault: electromagnetic disturbances interfere with a radar measurement

**Error**: the radar-guided landing system calculates a wrong trajectory

**Failure**: the drone crashes to the ground

Another example: a tele-surgery system

**Fault**: radioactive ions make some memory cells change value (bitflip)

**Error**: some frames of the video stream are corrupted

Failure: the surgeon kills the patient

Not always the fault – error – failure chain closes

example: a tele-surgery system

Fault: radioactive ions make some memory cells change value (bitflip) but the corrupted memory does not involve the video stream

**Error**: no frames are corrupted

Failure: the surgeon carries out the procedure

Not always the fault – error – failure chain closes

example: a tele-surgery system

Fault: radioactive ions make some memory cells change value (bitflip) but the corrupted memory does not involve the video stream

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Non activated fault

Not always the fault – error – failure chain closes

example: a flying drone with automatic radar-guided landing

**Fault**: electromagnetic disturbances interfere with a radar measurement

**Error**: the radar-guided landing system calculates a wrong trajectory, but then, based on subsequent correct radar measurements it is able to recover the right trajectory

Failure: the drone safely lands

Not always the fault – error – failure chain closes

example: a flying drone with automatic radar-guided landing

Fault: electromagnetic disturbances interfere with a radar measurement

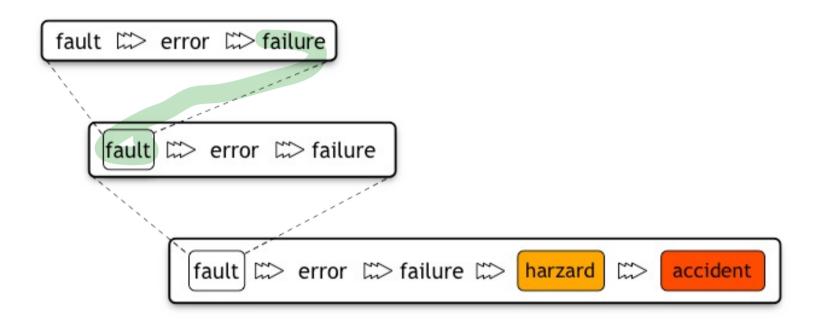
**Error**: the radar-guided landing system calculates a wrong trajectory, but then, based on

subsequent correct raua rements it is at

Failure: the drone safely lands

Non propagated (or absorbed) error

#### Fault hierarchy



Fault-error-failure cascades can lead to life-threatening hazards