



# Bayesian Machine Learning

May 2024 - François HU  
<https://curiousml.github.io/>

# Outline

1

## Bayesian statistics

- Bayesian statistics and probabilistic model
- Analytical inference
- Conjugate priors

2

## Latent Variable Models

3

## Variational Inference

4

## Causal Inference

5

## Extensions and oral presentations

## PREREQUISITE

## THEORY

1. Notions of **probability & statistics**
2. **Statistical Learning :**  
supervised & unsupervised learning
3. **Information theory :**  
Entropy, KL-divergence, ...

## APPLICATION

Python

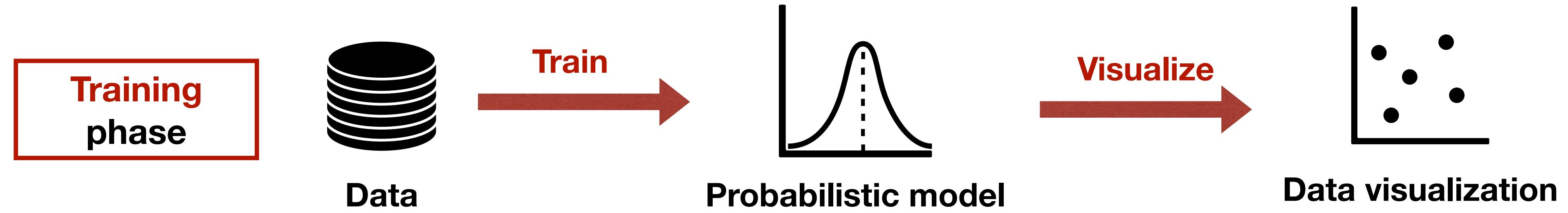
## ALGORITHM

Some « classical » supervised & unsupervised models

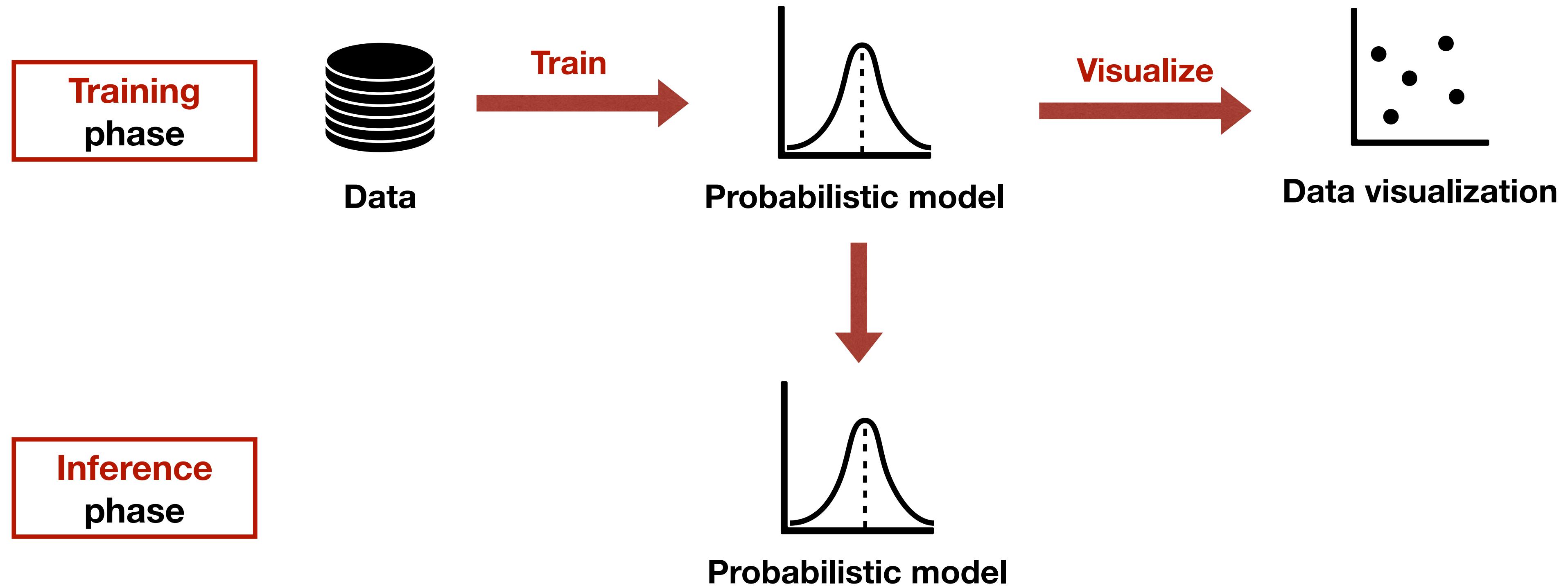
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# Gentle introduction to statistical learning

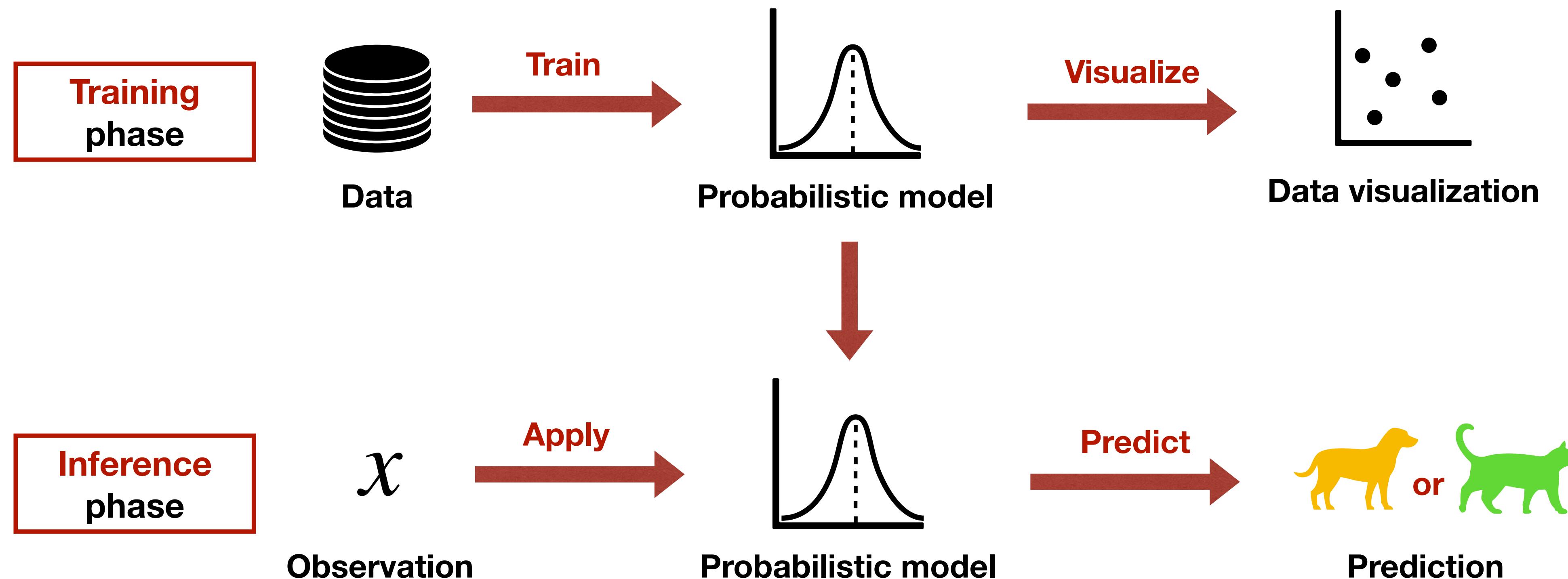
# Simplified statistical learning process



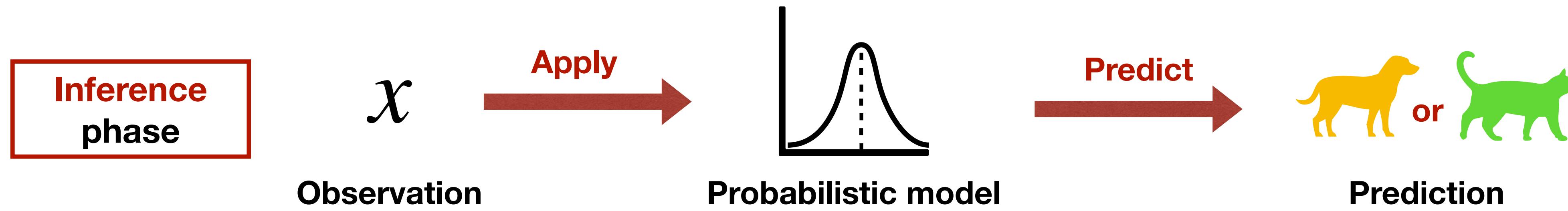
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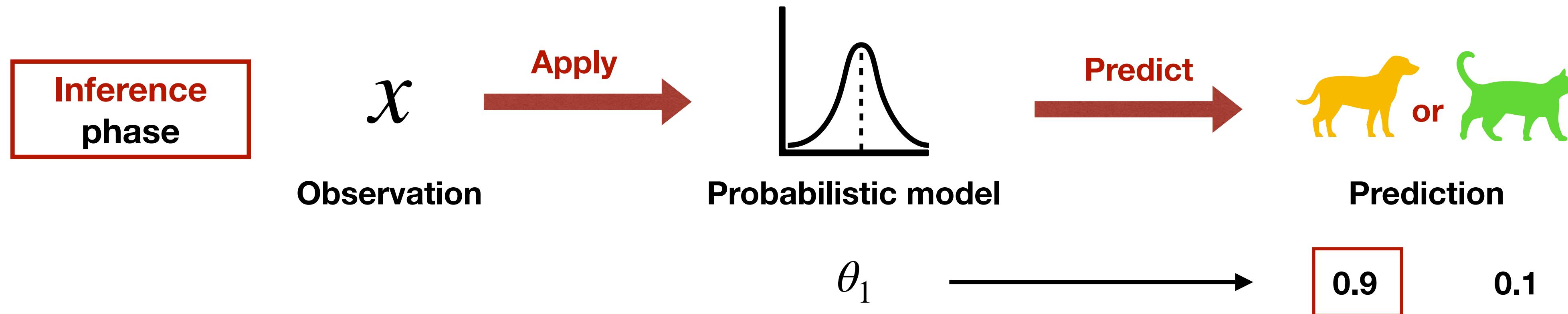
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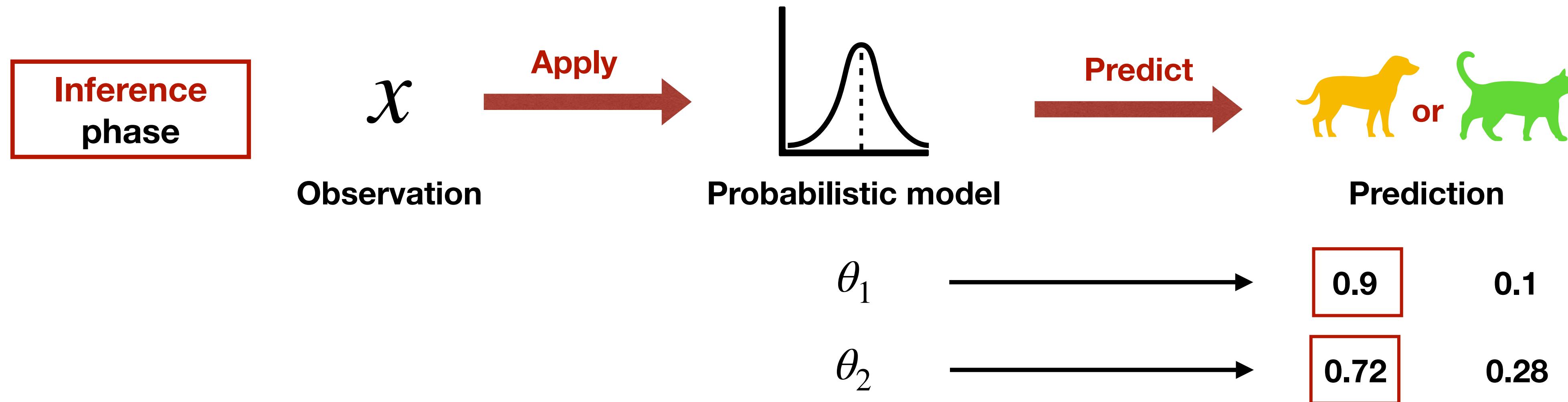
# Inference phase



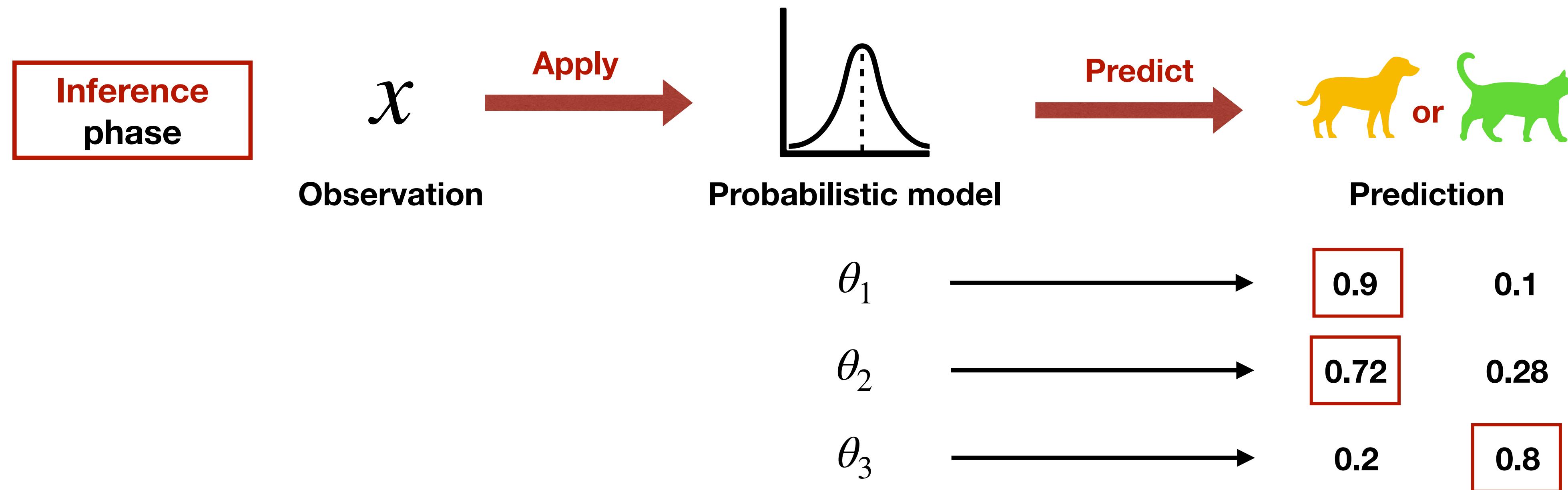
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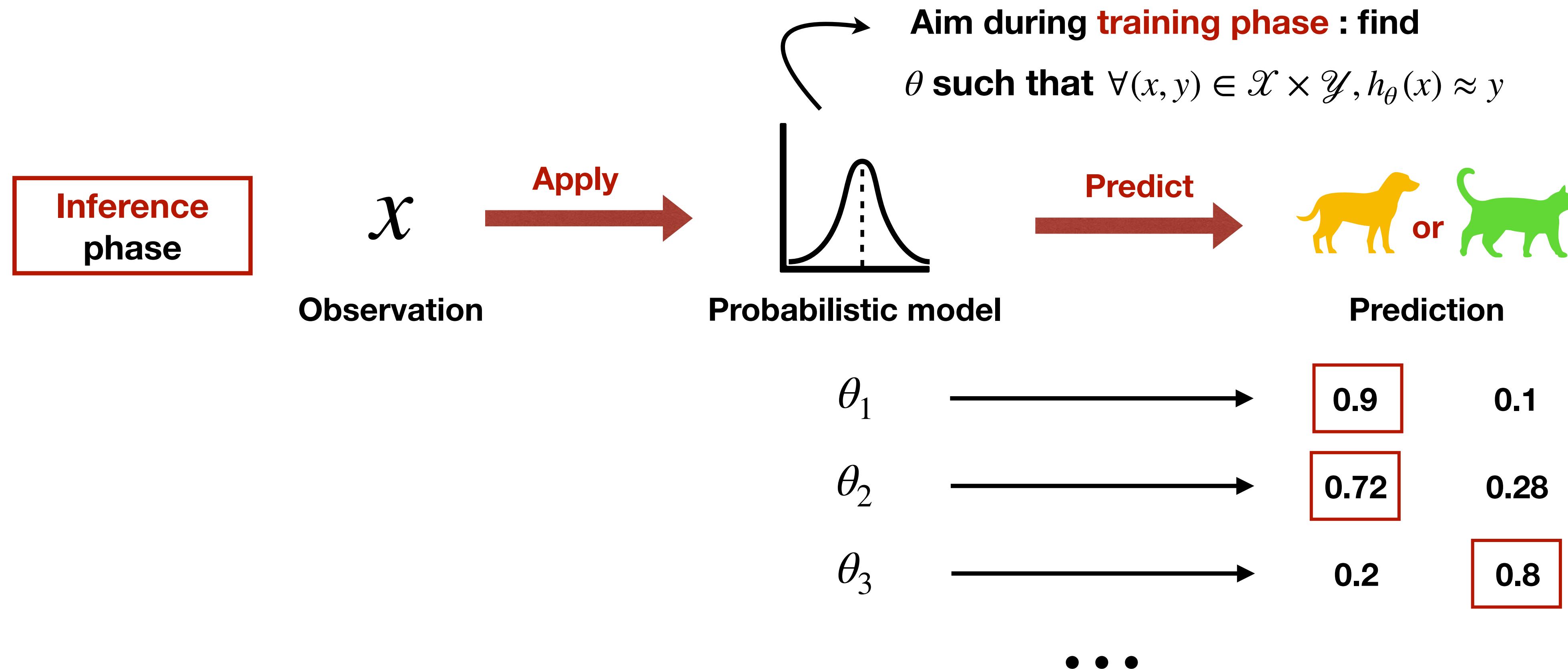
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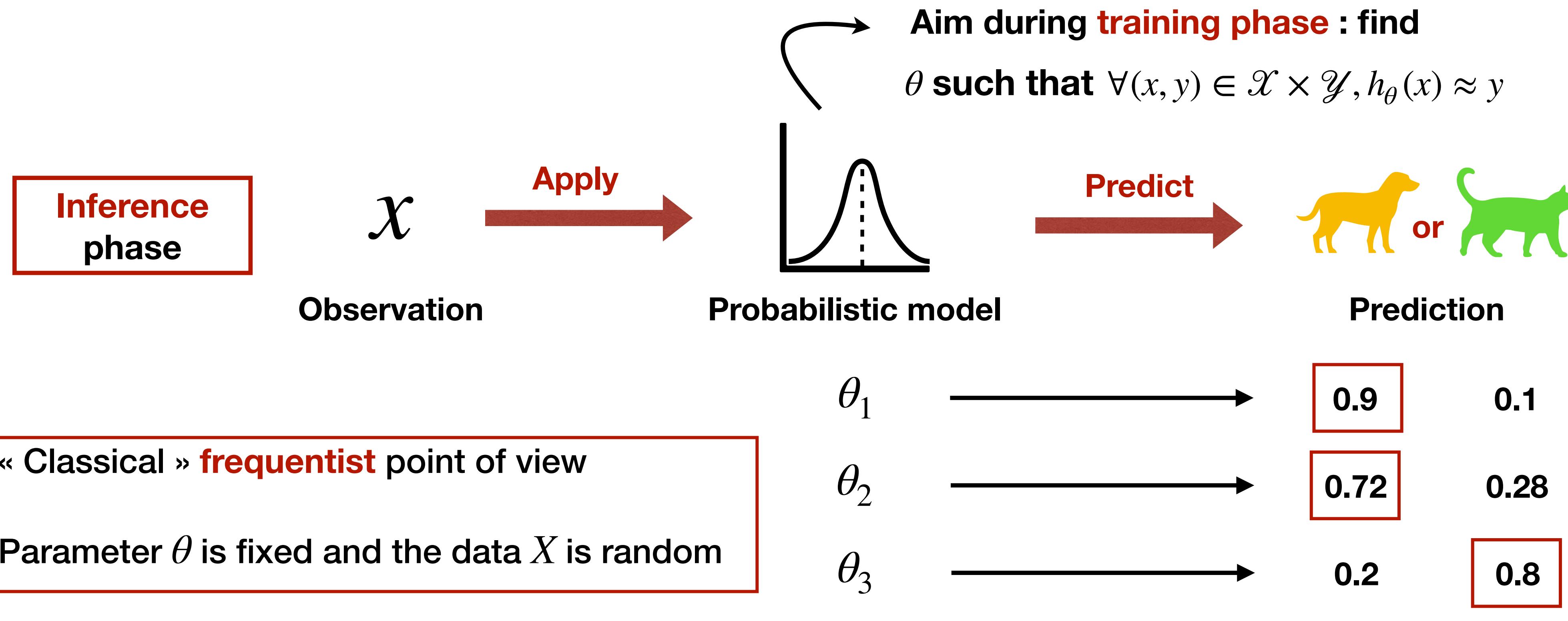
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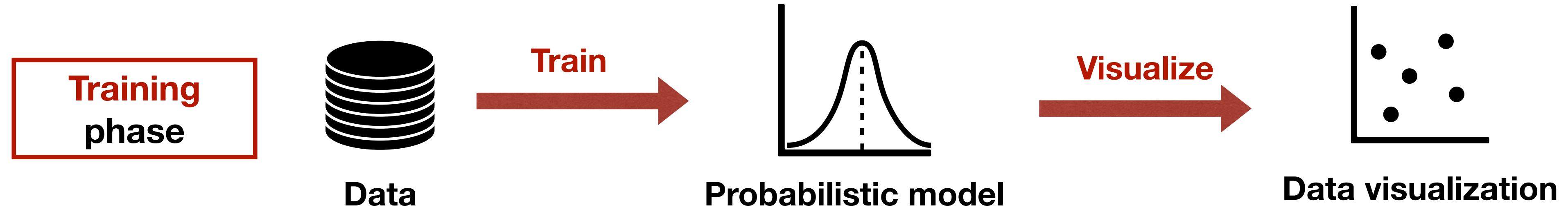
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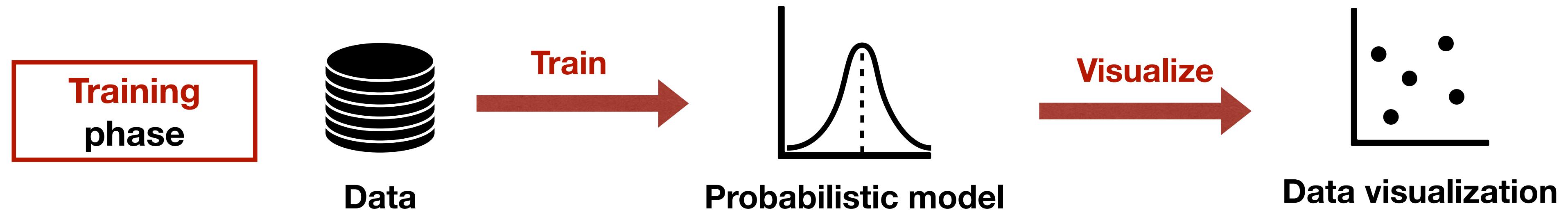
# Training phase



Aim during **training phase** : find  $\theta$  such that  $\forall (x, y) \in \mathcal{X} \times \mathcal{Y}, h_\theta(x) \approx y$

Usually in frequentist statistics we use the MLE : **Maximum Likelihood Estimation**  $\hat{\theta}_{MLE} = \arg \max_{\theta} P(X | \theta)$

# Training phase

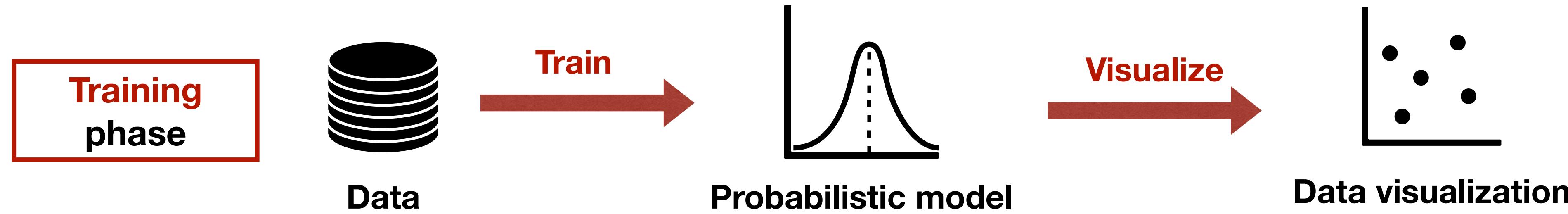


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**Example :** Linear regression example (proof later in the course if needed)

# Training phase



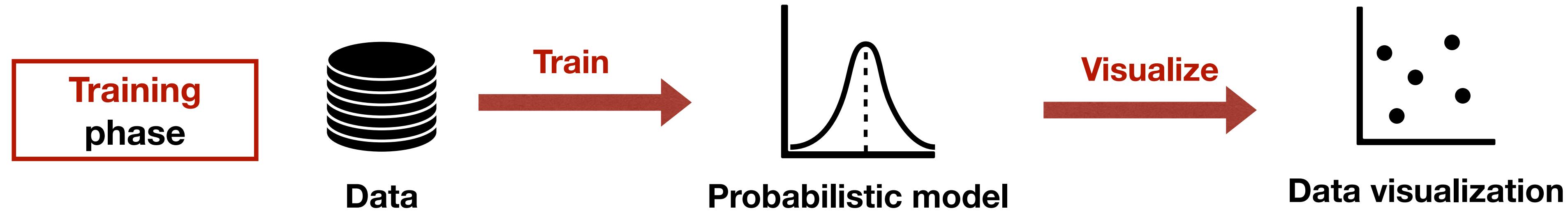
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## Problems :

- Only works well if we have big data :  $|X| \gg |\theta|$
- Cannot start with a « belief » hence not practical nor flexible
- Cannot express uncertainty of estimated model parameters and predictions

# Training phase



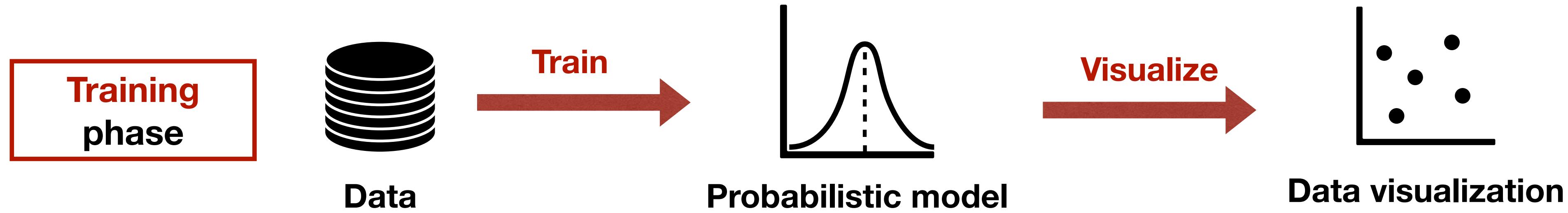
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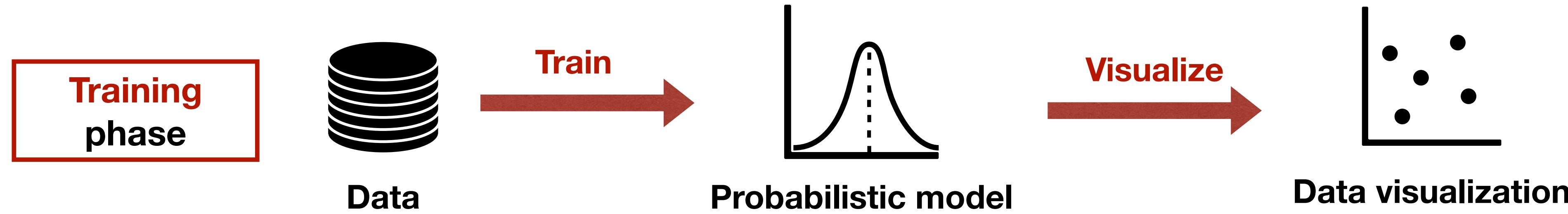
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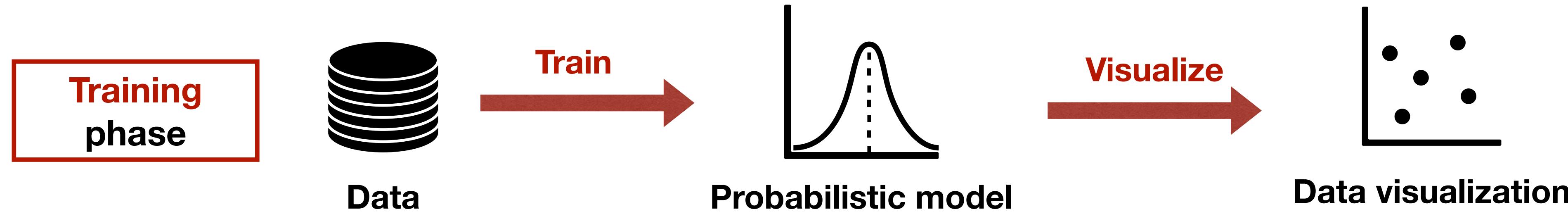
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*SOLUTION : Bayesian statistics*

# Why Bayesian methods ?

## Examples of application of Bayesian Machine Learning

Credit card default detection  
Bayes theorem



Medical diagnosis  
Bayes theorem

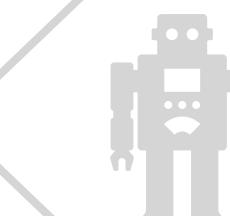


Spam filtering  
Bayesian Neural Network



Patterns in customer dataset  
Bayesian Non parametric Clustering (BNC)

Help robots make decision  
Bayesian Reinforcement Learning (BRL)



Reconstructing images from noisy images  
Bayes theorem + MCMC

Speech emotion recognition  
Nonparametric hierarchical neural network (NHNN)



Optimal character recognition (OCR)



Supervised machine learning

Unsupervised machine learning

Others

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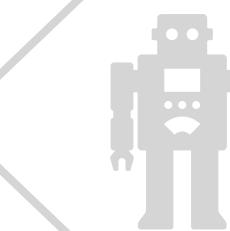
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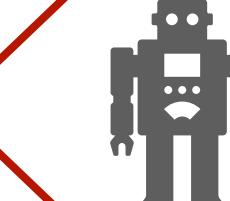
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Optimal character recognition (OCR)



Supervised machine learning

Unsupervised machine learning

Others using more advanced techniques

1

# Introduction to bayesian statistics

# 1. Introduction to bayesian statistics

## Probability & statistics : basic definitions

### Probability

Relative **frequency** of an event in an infinite trials



$$P(\text{ } \begin{array}{c} \text{K} \\ \text{ } \\ \text{ } \end{array} \text{ } ) = \frac{1}{52}$$
$$P(\text{ } \begin{array}{c} \spadesuit \\ \text{ } \end{array} \text{ } ) = \frac{1}{4}$$

# 1. Introduction to bayesian statistics

## Probability & statistics : basic definitions

### Probability

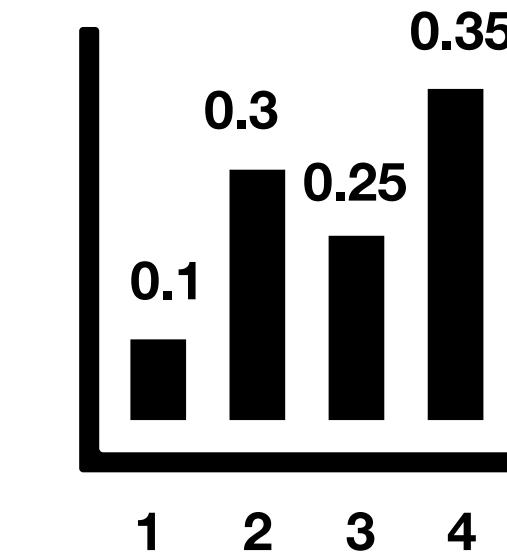
Relative **frequency** of an event in an infinite trials



$$P(\text{King of Hearts}) = \frac{1}{52}$$
$$P(\text{Spade}) = \frac{1}{4}$$

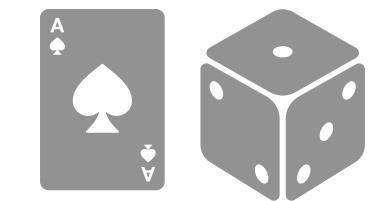
### Random variable

#### Discrete variable

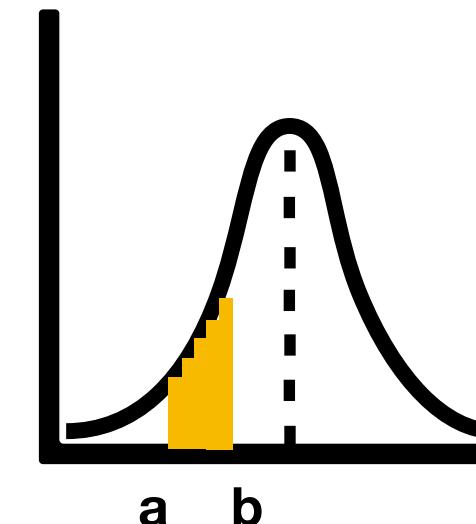


#### Probability Mass Function (PMF)

$$P(X) = \begin{cases} 0.1 & \text{if } X = 1 \\ 0.3 & \text{if } X = 2 \\ 0.25 & \text{if } X = 3 \\ 0.35 & \text{if } X = 4 \end{cases}$$

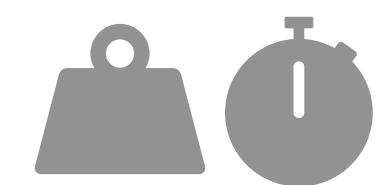


#### Continuous variable



#### Probability Density function (PDF)

$$P(X \in [a, b]) = \int_a^b p(s)ds$$



# 1. Introduction to bayesian statistics

## Probability & statistics : basic definitions

### Probability

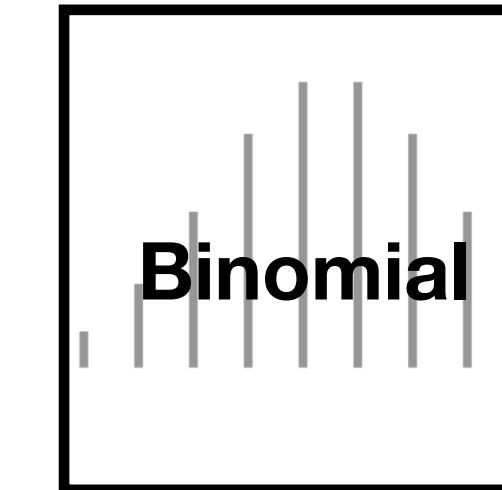
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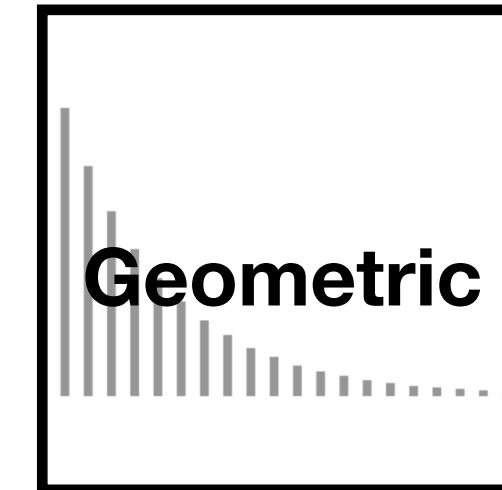
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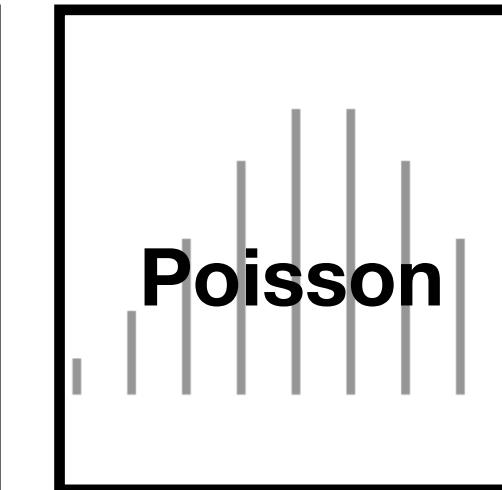
**Discrete** variable



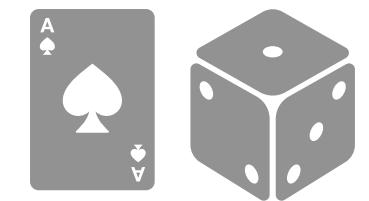
Binomial



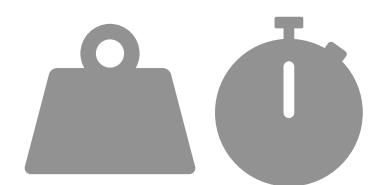
Geometric



Poisson

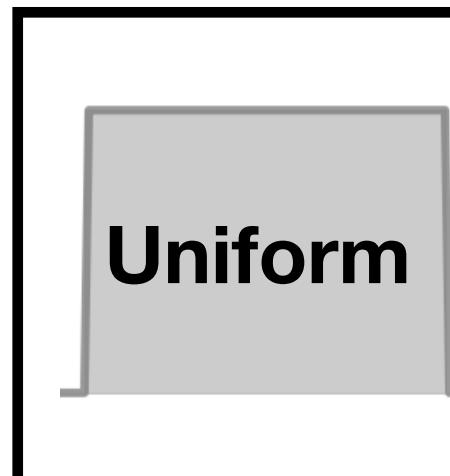


Usual distributions

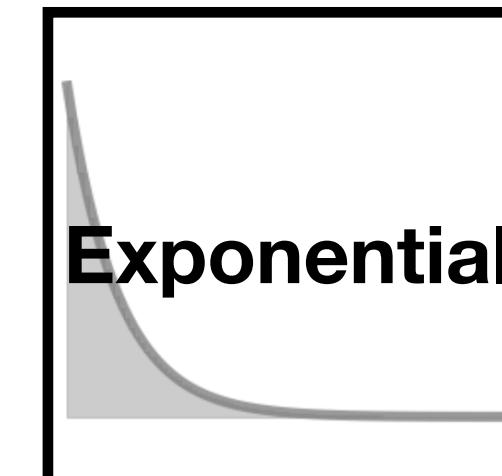


Usual distributions

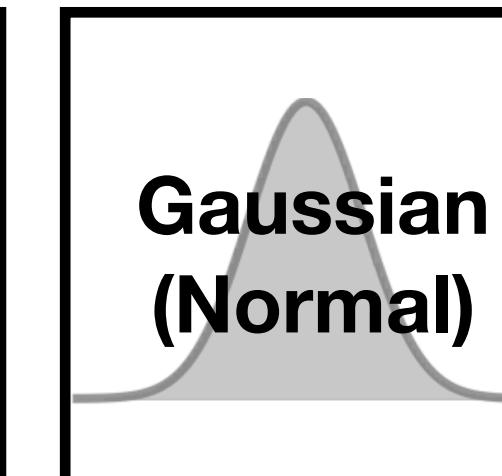
**Continuous** variable



Uniform



Exponential



Gaussian  
(Normal)

# 1. Introduction to bayesian statistics

## Probability & statistics : basic definitions

### Probability

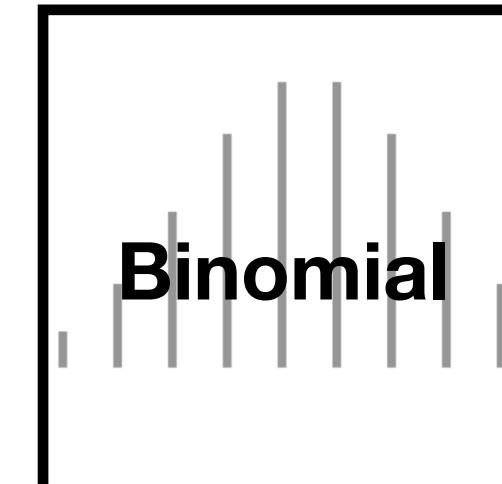
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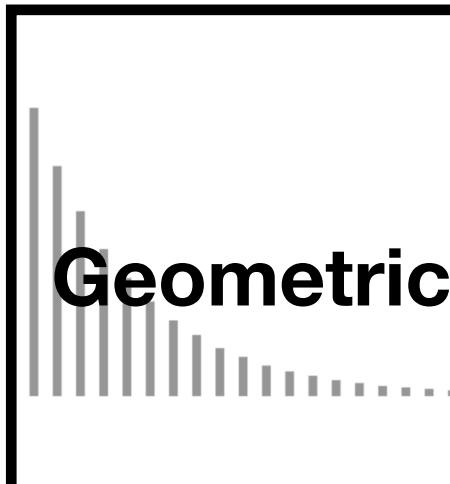
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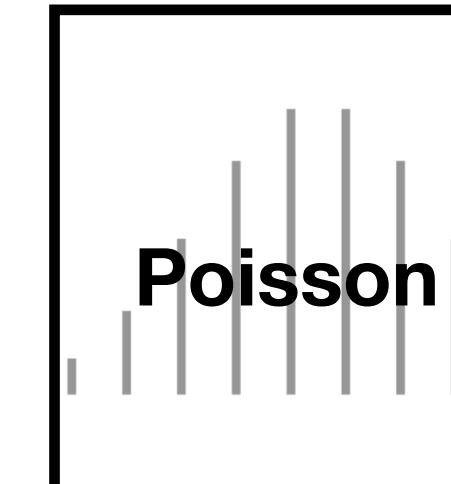
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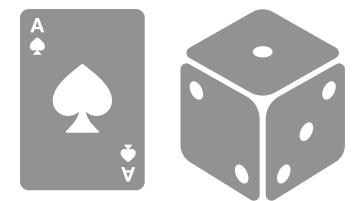
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Usual distributions



Usual distributions

### Independence

Two random variables X and Y are **independent** if

$$P(X, Y) = P(X)P(Y)$$

joint probability

marginals

**dependency** : one dice

$$P(\begin{array}{|c|c|}\hline \bullet & \bullet \\ \hline \bullet & \bullet \\ \hline \end{array}, \begin{array}{|c|c|}\hline \bullet & \bullet \\ \hline \bullet & \bullet \\ \hline \end{array}) = 0 \neq P(\begin{array}{|c|c|}\hline \bullet & \bullet \\ \hline \bullet & \bullet \\ \hline \end{array})P(\begin{array}{|c|c|}\hline \bullet & \bullet \\ \hline \bullet & \bullet \\ \hline \end{array}) = 1/6^2$$

**independency** : two dices

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# 1. Introduction to bayesian statistics

## Probability & statistics : basic definitions

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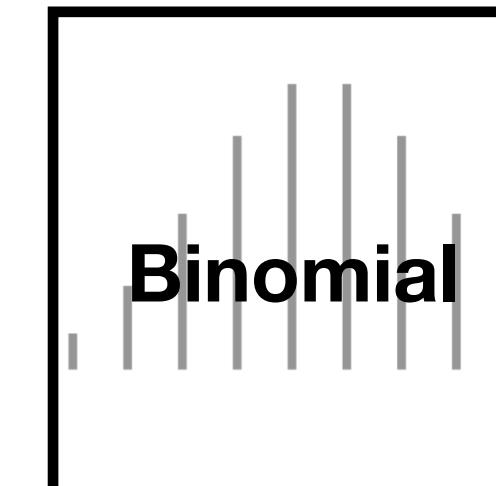
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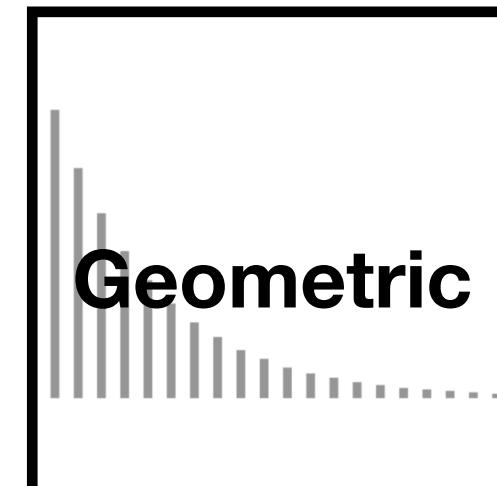
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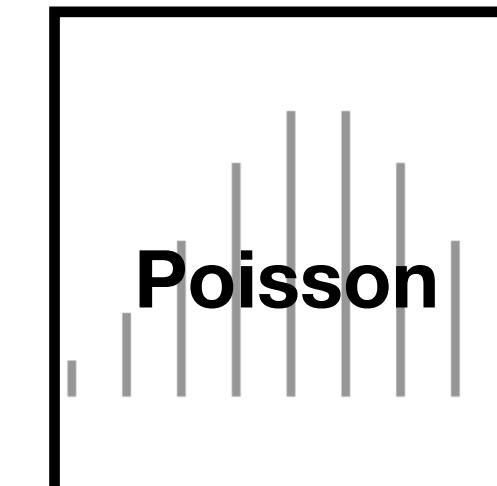
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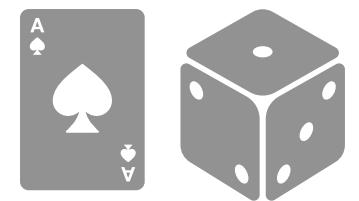
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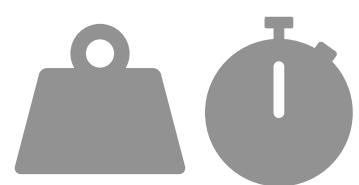
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Usual distributions

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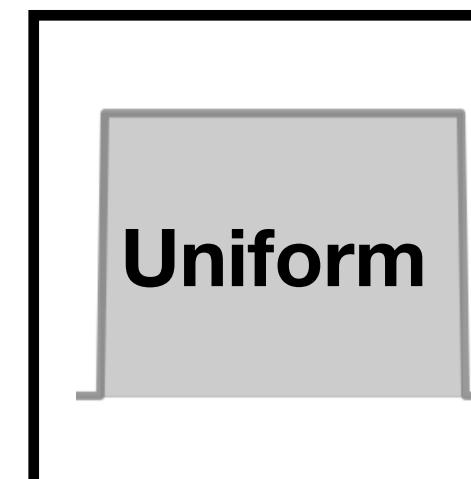
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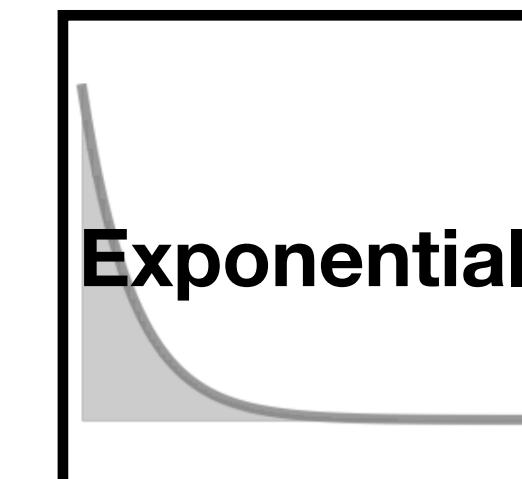
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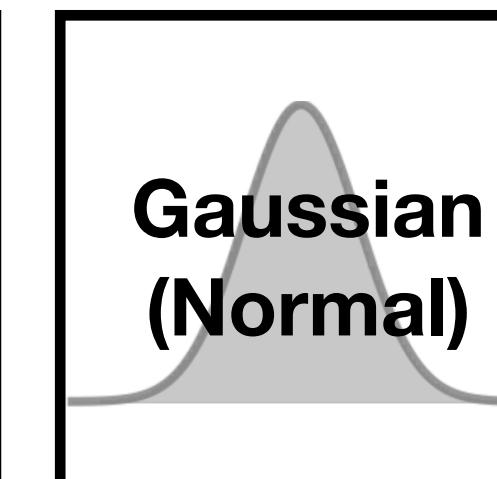
**Continuous** variable



Uniform



Exponential



Gaussian (Normal)

### Conditional probability

probability of X **given that** Y happened

$$P(X | Y) = \frac{P(X, Y)}{P(Y)}$$

conditionaljoint probabilitymarginal

$$P(\begin{smallmatrix} \bullet & \bullet \\ \bullet & \bullet \end{smallmatrix} | \begin{smallmatrix} \bullet & \bullet \\ \bullet & \bullet \end{smallmatrix}) = \frac{P(\begin{smallmatrix} \bullet & \bullet \\ \bullet & \bullet \end{smallmatrix}, \begin{smallmatrix} \bullet & \bullet \\ \bullet & \bullet \end{smallmatrix})}{P(\begin{smallmatrix} \bullet & \bullet \\ \bullet & \bullet \end{smallmatrix})}$$

# 1. Introduction to bayesian statistics

# Probability & statistics : Bayes theorem

# Conditional probability

# probability of X given that Y happened

$$P(X | Y) = \frac{P(X, Y)}{P(Y)}$$

Joint probability  
Marginal

## Chain rule

$$P(X_1, X_2) = \dots$$

$$P(X_1, X_2, X_3) = \dots$$

$$P(X_1, \dots, X_n) = \dots$$

# Sum rule

# discrete

$$P(X) = \dots$$

# continuous

$$P(X) = \dots$$

# 1. Introduction to bayesian statistics

## Probability & statistics : Bayes theorem

### Conditional probability

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$$P(X | Y) = \frac{P(X, Y)}{P(Y)}$$

**Conditional**                            **Joint probability**  
    **Marginal**

### Chain rule

$$P(X_1, X_2) = P(X_1 | X_2) \times P(X_2)$$

$$P(X_1, X_2, X_3) = \dots$$

$$P(X_1, \dots, X_n) = \dots$$

### Sum rule

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## Probability & statistics : Bayes theorem

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## Probability & statistics : Bayes theorem

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**Conditional**                            **Marginal**

Joint probability

### Chain rule

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$$P(X_1, X_2, X_3) = P(X_1 | X_2, X_3) \times P(X_2 | X_3) \times P(X_3)$$

$$P(X_1, \dots, X_n) = \prod_{k=1, \dots, n} P(X_k | X_1, \dots, X_{k-1})$$

### Sum rule

discrete

$$P(X) = \dots$$

continuous

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## Probability & statistics : Bayes theorem

### Conditional probability

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**Conditional**                            **Marginal**

Joint probability

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$$P(X_1, \dots, X_n) = \prod_{k=1, \dots, n} P(X_k | X_1, \dots, X_{k-1})$$

### Sum rule

discrete

$$P(X) = \sum_{Y \in \mathcal{Y}} P(X, Y)$$

continuous

$$P(X) = \dots$$

# 1. Introduction to bayesian statistics

## Probability & statistics : Bayes theorem

### Conditional probability

probability of X given that Y happened

$$P(X | Y) = \frac{P(X, Y)}{P(Y)}$$

**Conditional**                            **Marginal**

**Joint probability**

### Chain rule

$$P(X_1, X_2) = P(X_1 | X_2) \times P(X_2)$$

$$P(X_1, X_2, X_3) = P(X_1 | X_2, X_3) \times P(X_2 | X_3) \times P(X_3)$$

$$P(X_1, \dots, X_n) = \prod_{k=1, \dots, n} P(X_k | X_1, \dots, X_{k-1})$$

### Sum rule

#### discrete

$$P(X) = \sum_{Y \in \mathcal{Y}} P(X, Y)$$

#### continuous

$$P(X) = \int_{Y \in \mathcal{Y}} P(X, Y) \cdot dY$$

# 1. Introduction to bayesian statistics

## Probability & statistics : Bayes theorem

### Conditional probability

probability of X given that Y happened

$$P(X | Y) = \frac{P(X, Y)}{P(Y)}$$

ConditionalJoint probabilityMarginal

### Chain rule

$$P(X_1, X_2) = P(X_1 | X_2) \times P(X_2)$$

$$P(X_1, X_2, X_3) = P(X_1 | X_2, X_3) \times P(X_2 | X_3) \times P(X_3)$$

$$P(X_1, \dots, X_n) = \prod_{k=1, \dots, n} P(X_k | X_1, \dots, X_{k-1})$$

### Sum rule

discrete

$$P(X) = \sum_{Y \in \mathcal{Y}} P(X, Y)$$

continuous

$$P(X) = \int_{Y \in \mathcal{Y}} P(X, Y) \cdot dY$$

### Bayes theorem

$\theta$  Parameters

X Data

Likelihood      Prior

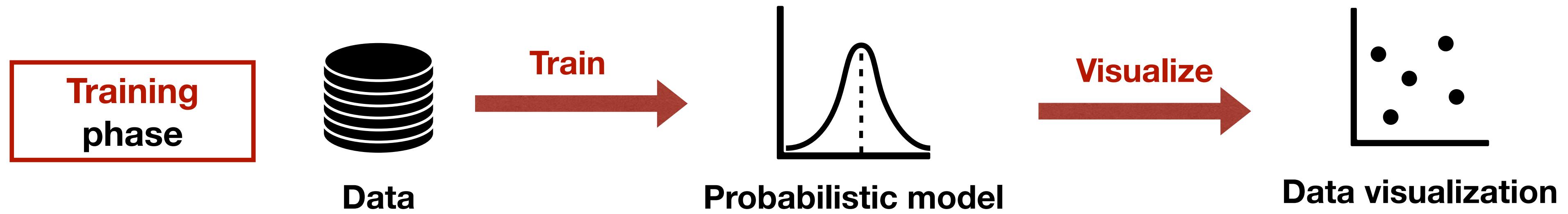
$$P(\theta | X) = \frac{P(X, \theta)}{P(X)} = \frac{P(X | \theta) \times P(\theta)}{P(X)}$$

Posterior

Evidence

# 1. Introduction to bayesian statistics

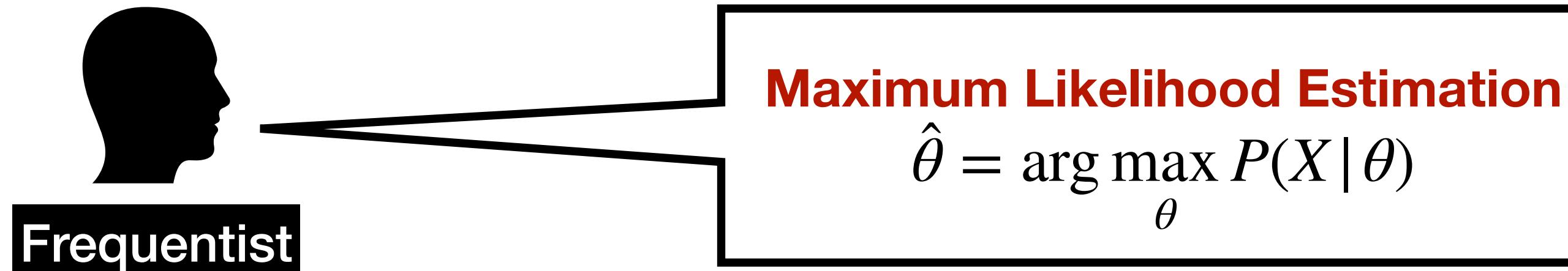
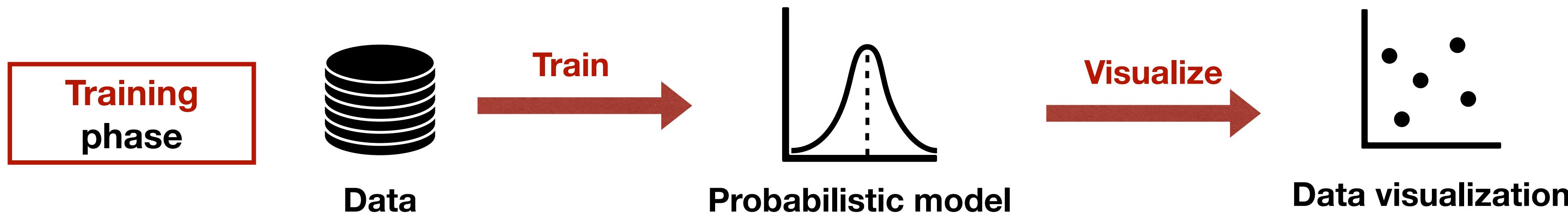
Frequentist VS Bayesian point of view



find  $\theta$  such that  $\forall (x, y) \in \mathcal{X} \times \mathcal{Y}, h_\theta(x) \approx y$

# 1. Introduction to bayesian statistics

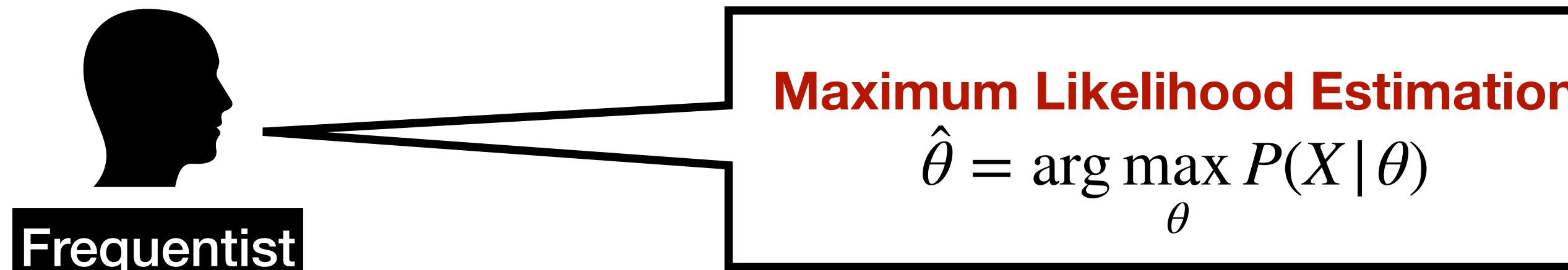
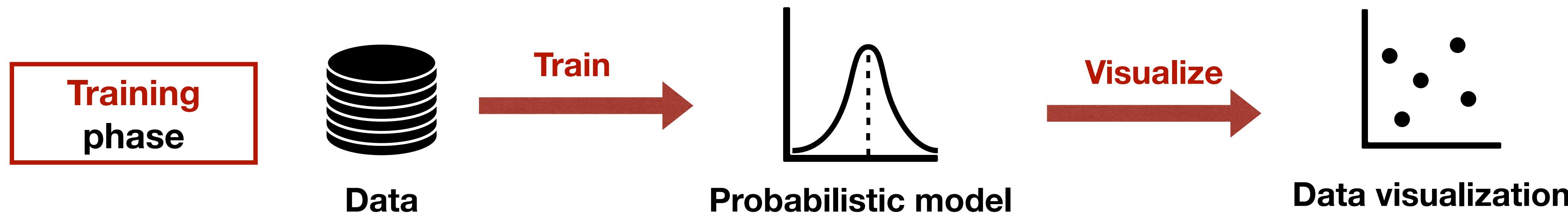
Frequentist VS Bayesian point of view



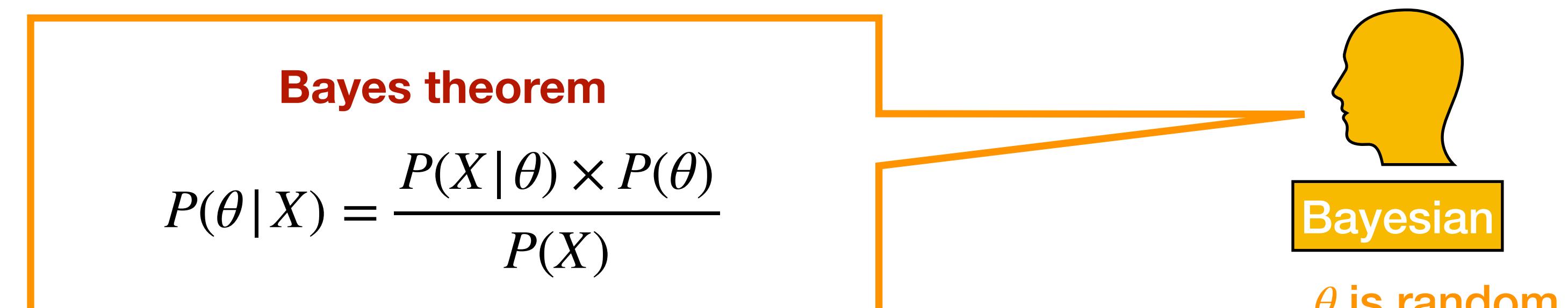
$\theta$  is fixed  
 $X$  is random

# 1. Introduction to bayesian statistics

## Frequentist VS Bayesian point of view



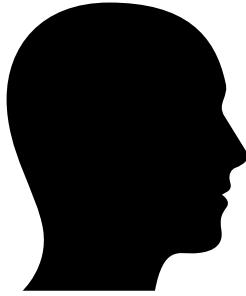
$\theta$  is fixed  
 $X$  is random



$\theta$  is random  
 $X$  is fixed

# 1. Introduction to bayesian statistics

## Frequentist VS Bayesian point of view



Frequentist

**Maximum Likelihood Estimation**

$$\hat{\theta} = \arg \max_{\theta} P(X | \theta)$$



Bayesian

**Bayes theorem**

$$P(\theta | X) = \frac{P(X | \theta) \times P(\theta)}{P(X)}$$

# 1. Introduction to bayesian statistics

## Frequentist VS Bayesian point of view



Frequentist

**Maximum Likelihood Estimation**

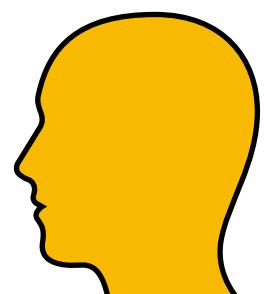
$$\hat{\theta} = \arg \max_{\theta} P(X | \theta)$$

**Problems in frequentist estimation :**

- Only works well if we have big data :  $|X| \gg |\theta|$
- Cannot start with a « belief » hence not practical nor flexible
- Cannot express uncertainty of estimated model parameters and predictions

**Bayes theorem**

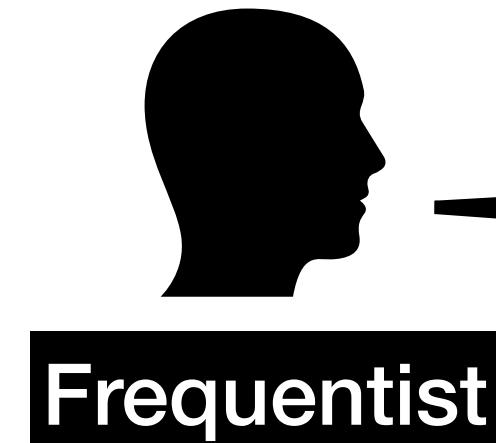
$$P(\theta | X) = \frac{P(X | \theta) \times P(\theta)}{P(X)}$$



Bayesian

# 1. Introduction to bayesian statistics

## Frequentist VS Bayesian point of view



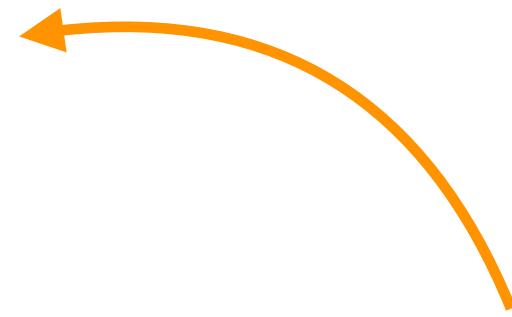
Frequentist

**Maximum Likelihood Estimation**

$$\hat{\theta} = \arg \max_{\theta} P(X | \theta)$$

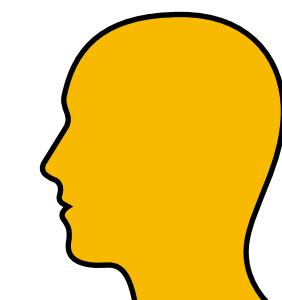
**Problems in frequentist estimation :**

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- ~~Cannot express uncertainty of estimated model parameters and predictions~~



**Bayes theorem**

$$P(\theta | X) = \frac{P(X | \theta) \times P(\theta)}{P(X)}$$



Bayesian

# 1. Introduction to bayesian statistics

## Bayesian point of view : classification

Bayes theorem

$$P(\theta | X) = \frac{P(X | \theta) \times P(\theta)}{P(X)}$$

Training phase

$$P(\theta | X_{train}, y_{train}) = \frac{P(y_{train} | X_{train}, \theta) \times P(\theta)}{P(y_{train} | X_{train})}$$



# 1. Introduction to bayesian statistics

## Bayesian point of view : training

Bayes theorem

$$P(\theta | X) = \frac{P(X | \theta) \times P(\theta)}{P(X)}$$

Training phase

$$P(\theta | X_{train}, y_{train}) = \frac{P(y_{train} | X_{train}, \theta) \times P(\theta)}{P(y_{train} | X_{train})}$$

Can regularize your model when training on your data

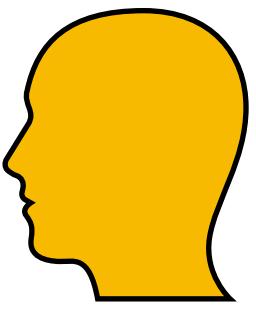


# 1. Introduction to bayesian statistics

## Bayesian point of view : inference

Bayes theorem

$$P(\theta | X) = \frac{P(X | \theta) \times P(\theta)}{P(X)}$$



Bayesian

Training phase

$$P(\theta | X_{train}, y_{train}) = \frac{P(y_{train} | X_{train}, \theta) \times P(\theta)}{P(y_{train} | X_{train})}$$

Can regularize your model when training on your data

Inference phase

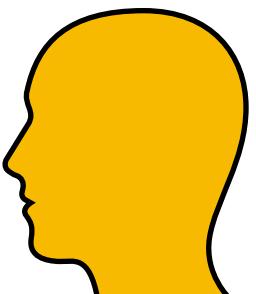
$$P(y_{new} | X_{new}, X_{train}, y_{train}) = \int P(y_{new} | X_{train}, \theta) \times P(\theta | X_{train}, y_{train}) d\theta$$

# 1. Introduction to bayesian statistics

Bayesian point of view : online learning

Bayes theorem

$$P(\theta | X) = \frac{P(X | \theta) \times P(\theta)}{P(X)}$$



Bayesian

Training phase

$$P(\theta | X_{train}, y_{train}) = \frac{P(y_{train} | X_{train}, \theta) \times P(\theta)}{P(y_{train} | X_{train})}$$

Can regularize your model when training on your data

Inference phase

$$P(y_{new} | X_{new}, X_{train}, y_{train}) = \int P(y_{new} | X_{train}, \theta) \times P(\theta | X_{train}, y_{train}) d\theta$$

Online learning

$$P_{new}(\theta) = P(\theta | x_{new}) = \frac{P(x_{new} | \theta) \times P_{old}(\theta)}{P(x_{new})}$$

New prior

Posterior



2

## Probabilistic models

## 2. Probabilistic model

### Probabilistic Graphical Model (PGM)

**Probabilistic graphical models** : analysis using **diagrammatic representations** of probability distributions

## 2. Probabilistic model

### Probabilistic Graphical Model (PGM)

**Probabilistic graphical models** : analysis using **diagrammatic representations** of probability distributions

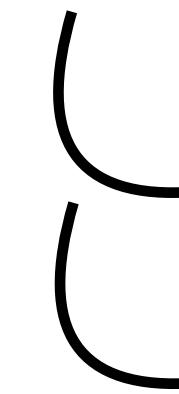
- **Nodes** : random variables
- **Links** : probabilistic relationships

## 2. Probabilistic model

### Probabilistic Graphical Model (PGM)

**Probabilistic graphical models** : analysis using **diagrammatic representations** of probability distributions

**Bayesian networks**  
(Directed graphical models )



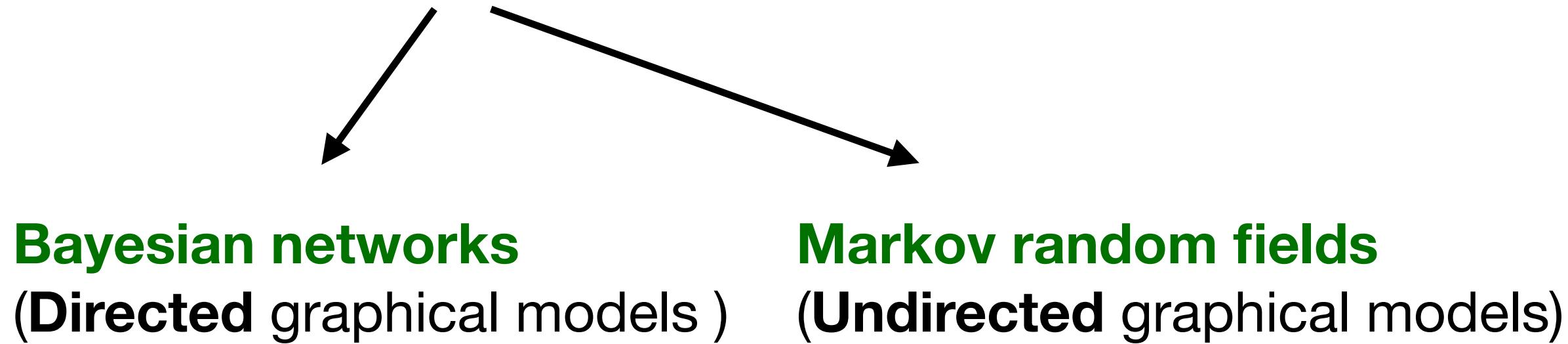
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## 2. Probabilistic model

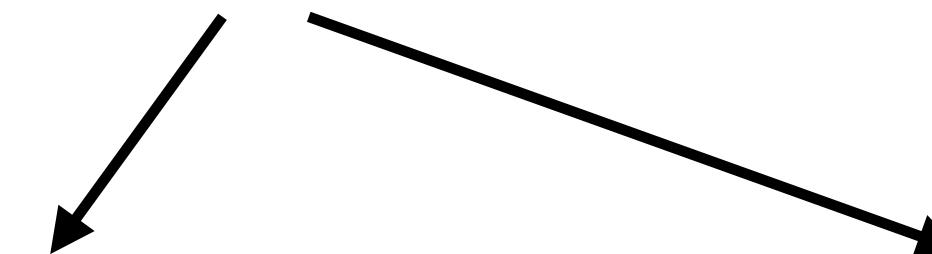
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**Probabilistic graphical models** : analysis using **diagrammatic representations** of probability distributions

**Bayesian networks**  
(Directed graphical models )

Markov random fields  
(Undirected graphical models)

The focus of our course !



- **Nodes** : random variables
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## 2. Probabilistic model

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**Probabilistic graphical models** : analysis using **diagrammatic representations** of probability distributions

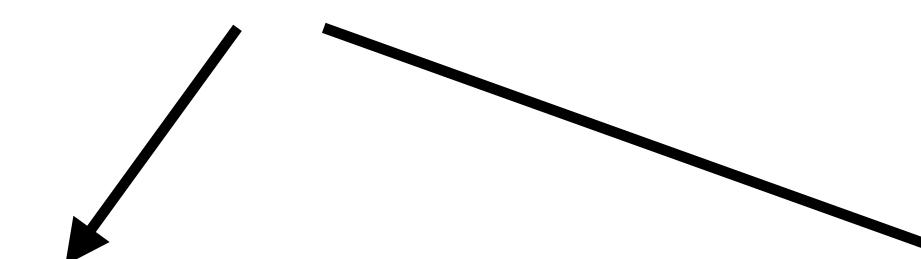
**Bayesian networks**  
(Directed graphical models )

Markov random fields  
(Undirected graphical models)

**The focus of our course !**

**Model** : joint probability over all variables

$$P(X_1, \dots, X_N) = \dots$$

- 
- **Nodes** : random variables
  - **Links** : probabilistic relationships

## 2. Probabilistic model

### Probabilistic Graphical Model (PGM)

**Probabilistic graphical models** : analysis using **diagrammatic representations** of probability distributions

**Bayesian networks**

(Directed graphical models )

Markov random fields

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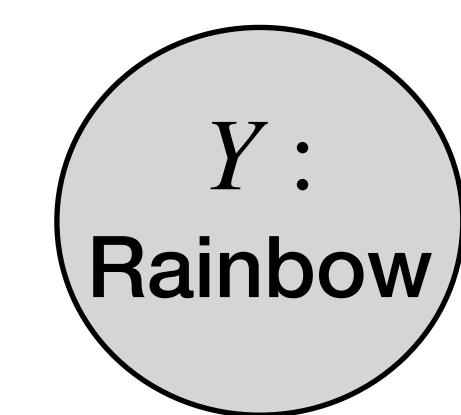
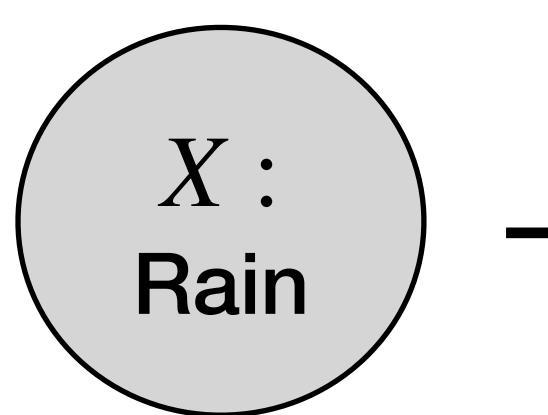
The focus of our course !

**Model** : joint probability over all variables

$$P(X_1, \dots, X_N) = \dots$$

- **Nodes** : random variables
- **Links** : probabilistic relationships

**Example :**



$$P(X, Y) = \dots$$

## 2. Probabilistic model

### Probabilistic Graphical Model (PGM)

**Probabilistic graphical models** : analysis using **diagrammatic representations** of probability distributions

**Bayesian networks**

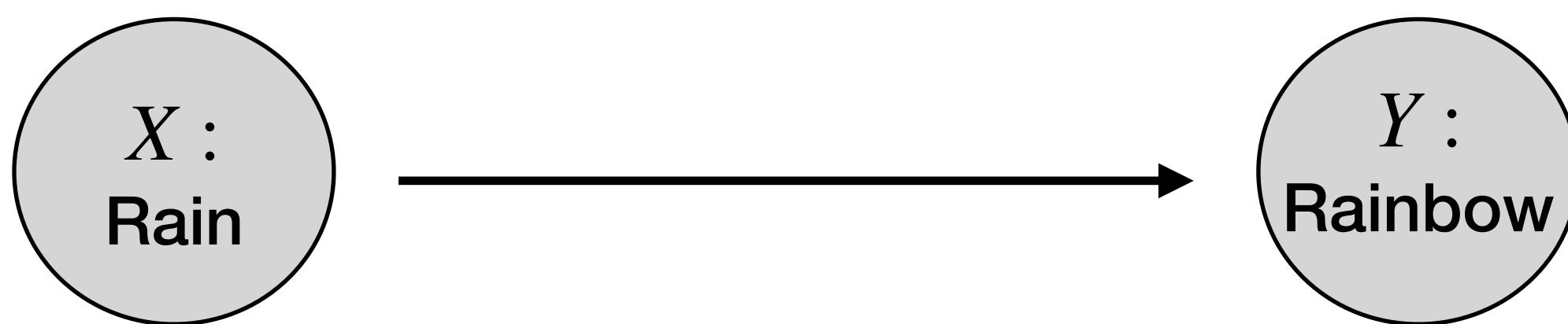
(Directed graphical models )

The focus of our course !

**Model** : joint probability over all variables

$$P(X_1, \dots, X_N) = \dots$$

**Example :**



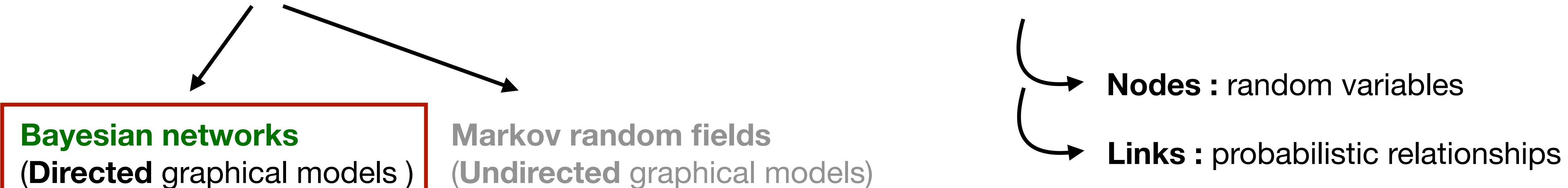
$$P(X, Y) = P(Y | X) \times P(X)$$

- **Nodes** : random variables
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## 2. Probabilistic model

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Probabilistic graphical models : analysis using diagrammatic representations of probability distributions

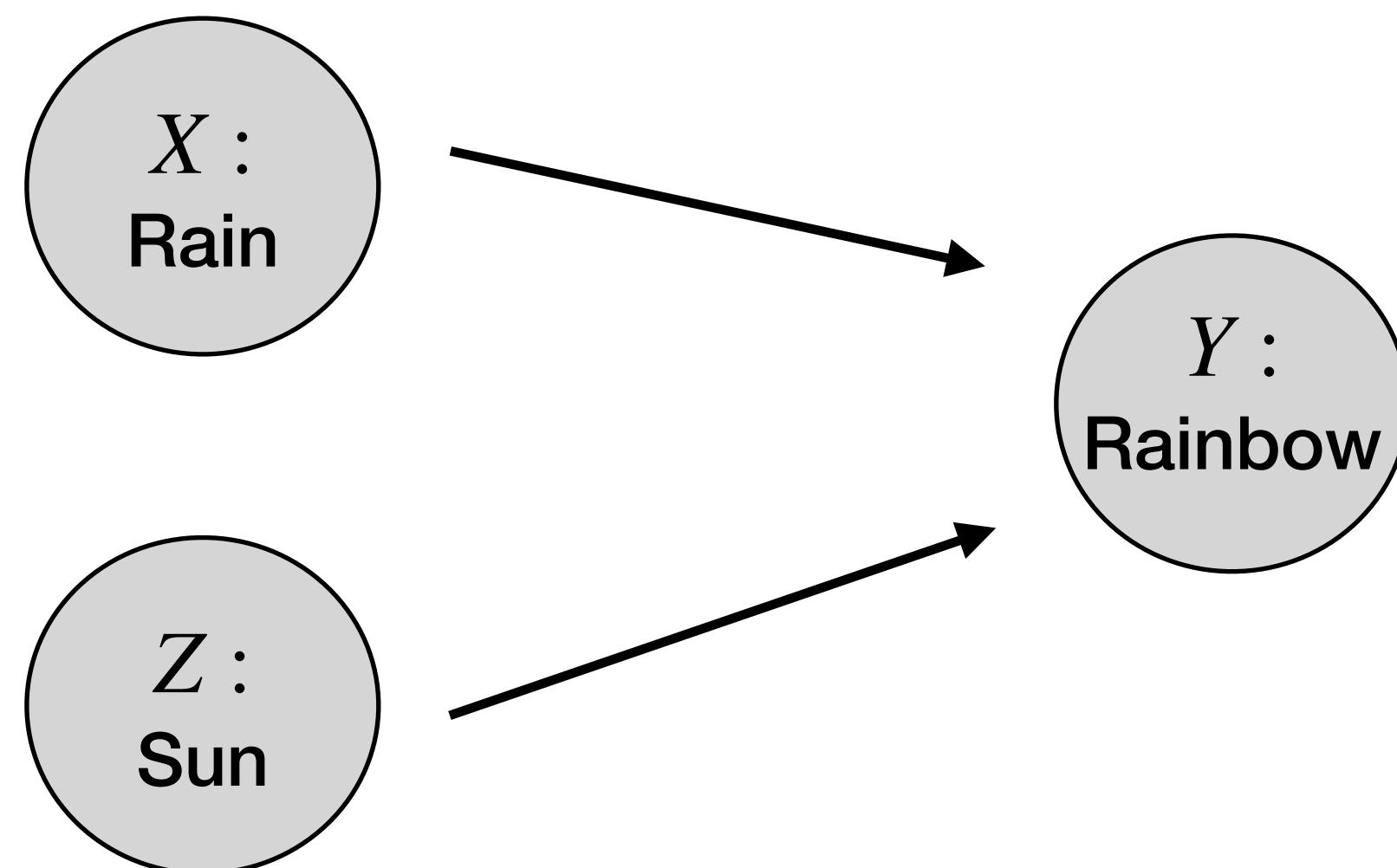


**The focus of our course !**

**Model** : joint probability over all variables

$$P(X_1, \dots, X_N) = \dots$$

**Example :**



$$P(X, Y, Z) = \dots$$

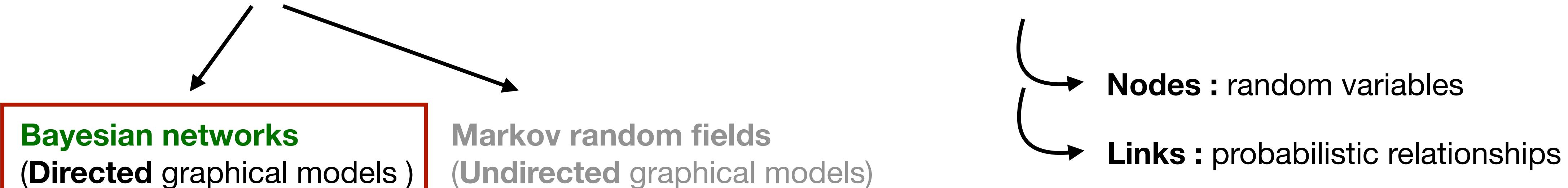
Features

X , Z conditionally  
independent given Y

## 2. Probabilistic model

### Probabilistic Graphical Model (PGM)

**Probabilistic graphical models** : analysis using **diagrammatic representations** of probability distributions

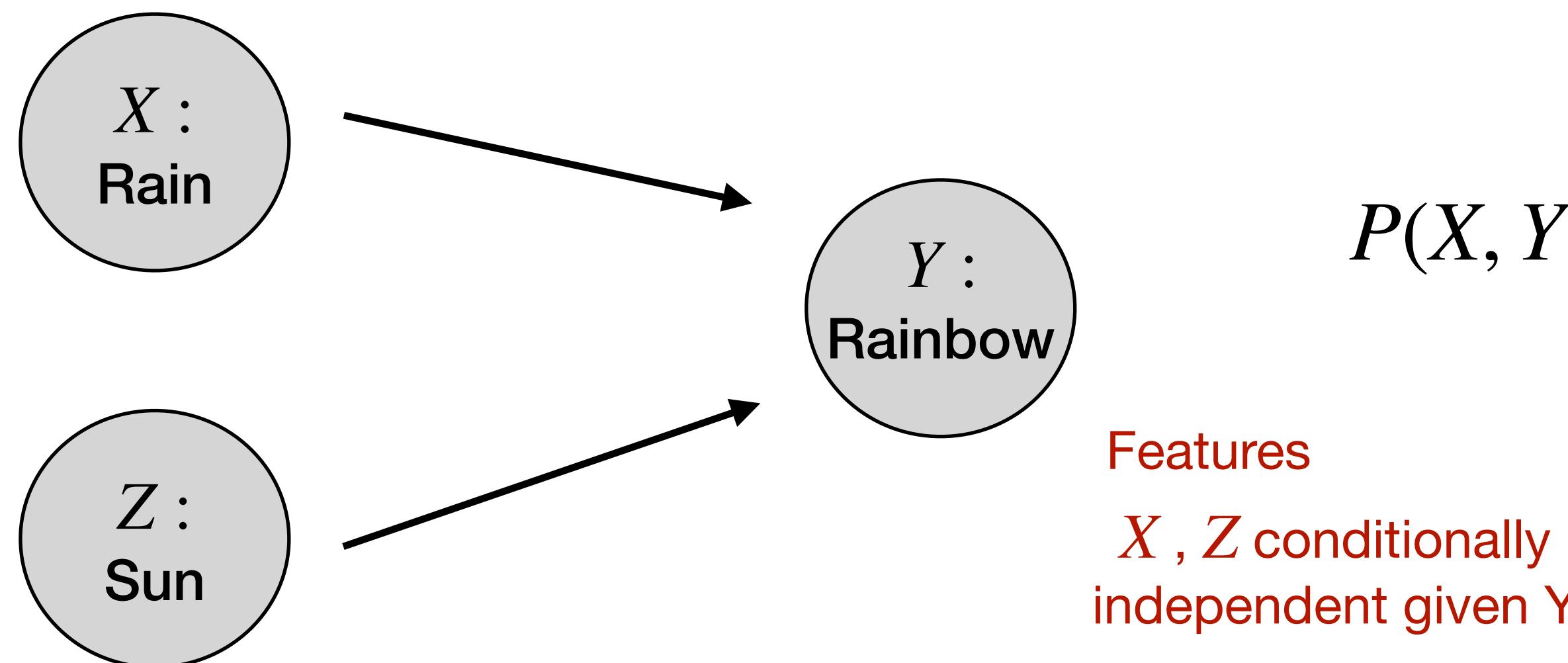


**The focus of our course !**

**Model** : joint probability over all variables

$$P(X_1, \dots, X_N) = \dots$$

**Example :**



Features

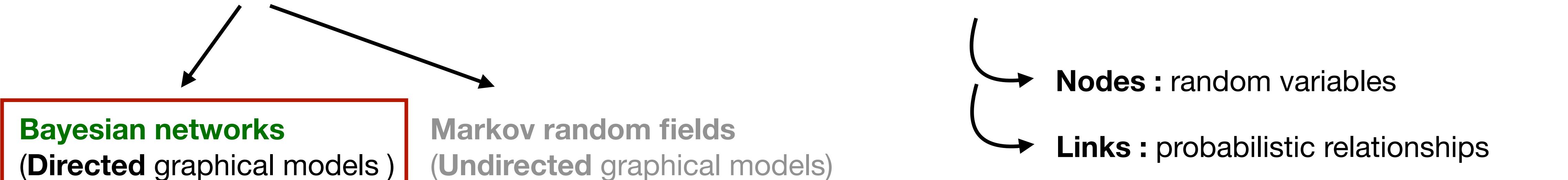
X , Z conditionally  
independent given Y

$$\begin{aligned} P(X, Y, Z) &= P(Y|X, Z) \times P(X, Z) \\ &= P(Y|X, Z) \times P(X) \times P(Z) \end{aligned}$$

## 2. Probabilistic model

### Probabilistic Graphical Model (PGM)

Probabilistic graphical models : analysis using **diagrammatic representations** of probability distributions

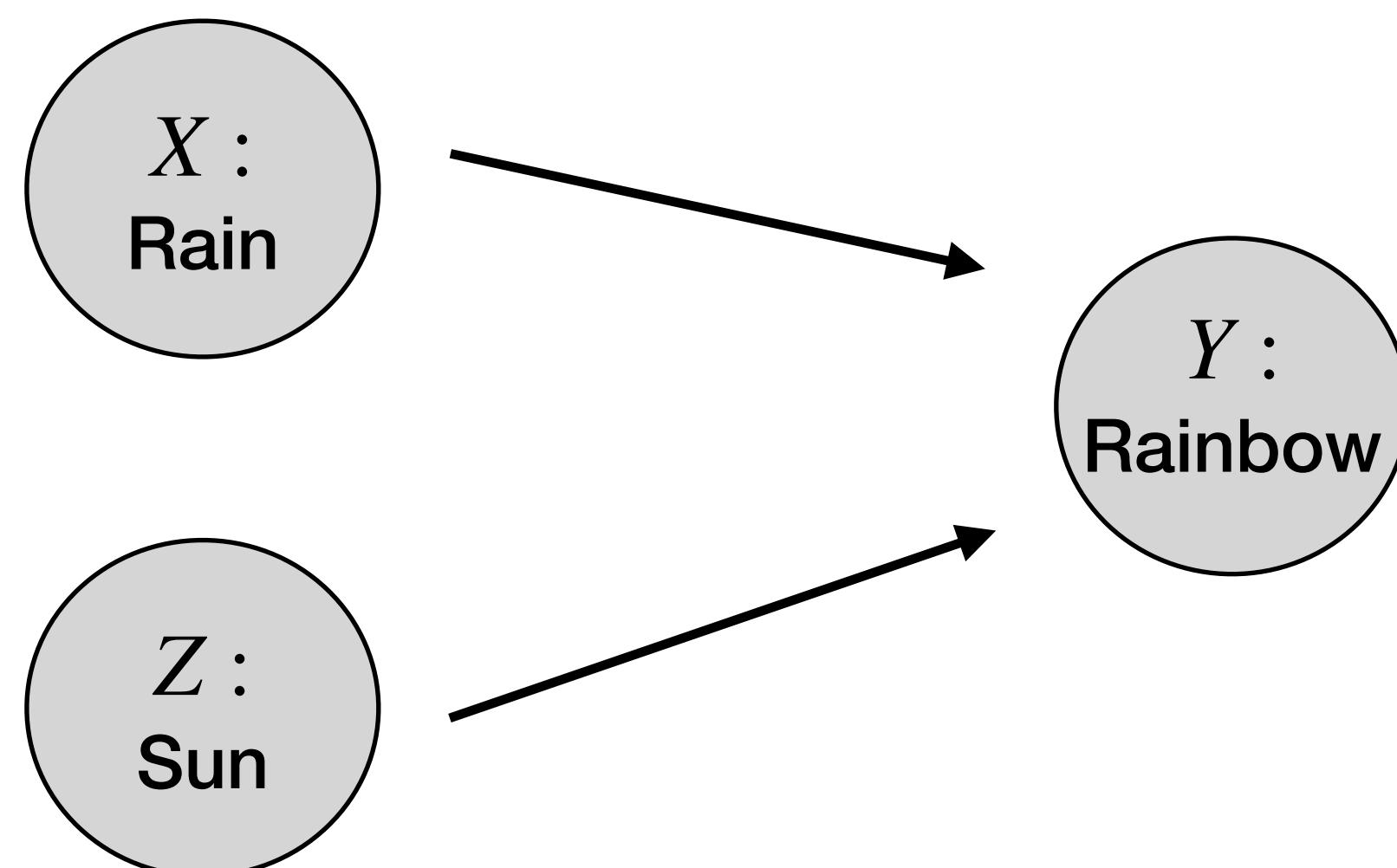


**The focus of our course !**

**Model** : joint probability over all variables

$$P(X_1, \dots, X_N) = \prod_{i=1, \dots, N} P(X_i \mid \text{parents}(X_i))$$

**Example :**



Features  
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## 2. Probabilistic model

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Probabilistic graphical models : analysis using **diagrammatic representations** of probability distributions

Bayesian networks  
(Directed graphical models )

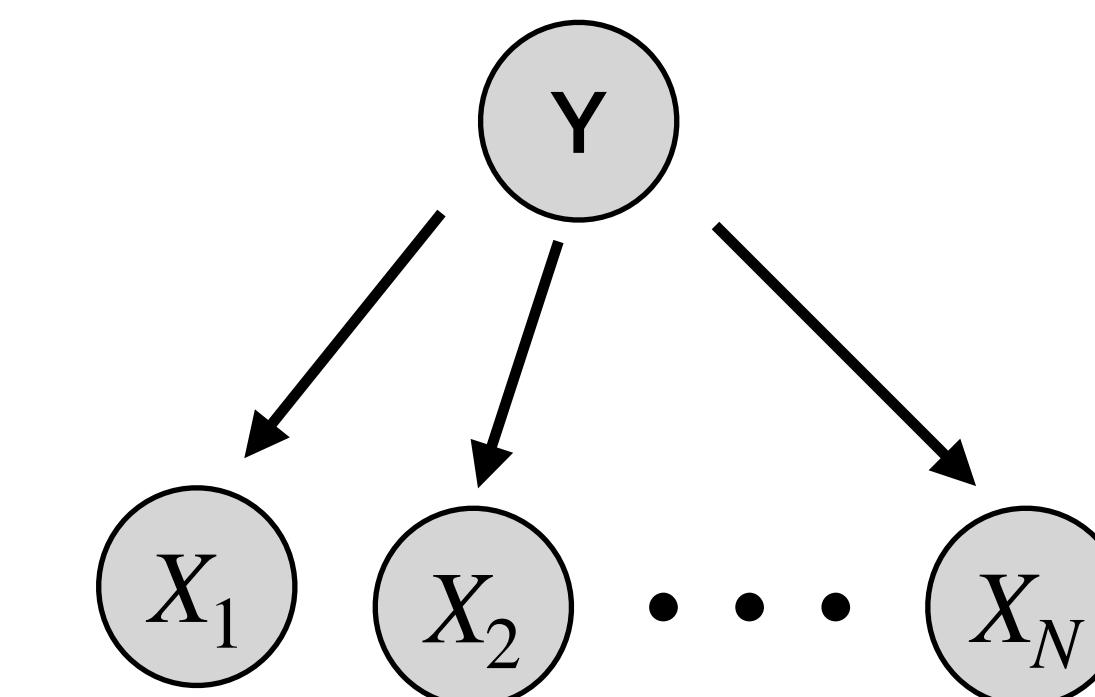
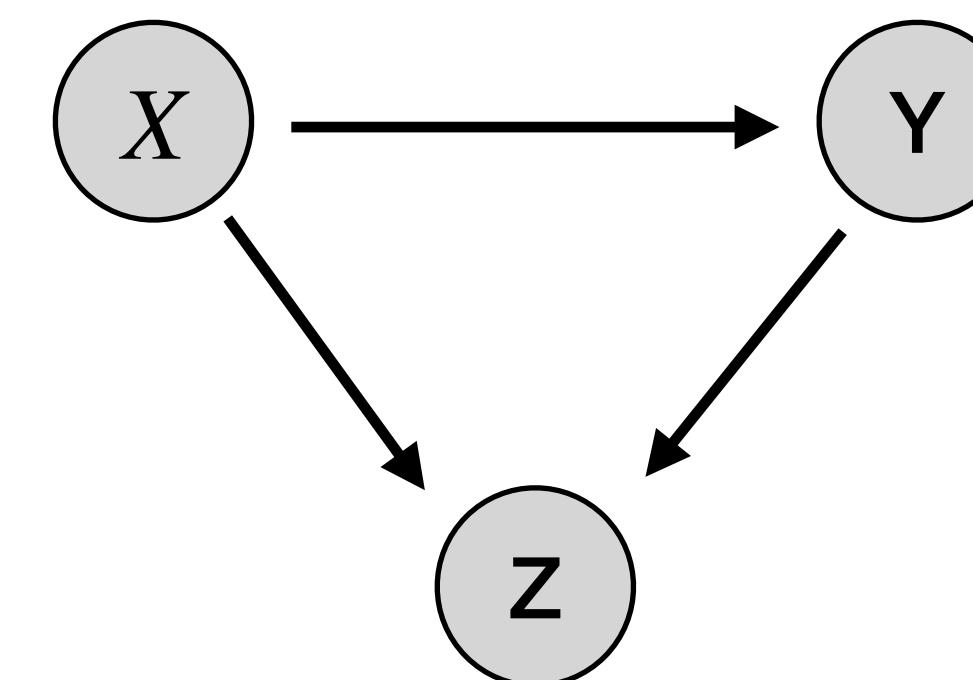
Markov random fields  
(Undirected graphical models)

The focus of our course !

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**Example :**



$$P(X, Y) = P(Y|X) \times P(X)$$

$$P(X, Y, Z) = \dots$$

$$P(Y, X_1, \dots, X_N) =$$

- Nodes : random variables
- Links : probabilistic relationships

## 2. Probabilistic model

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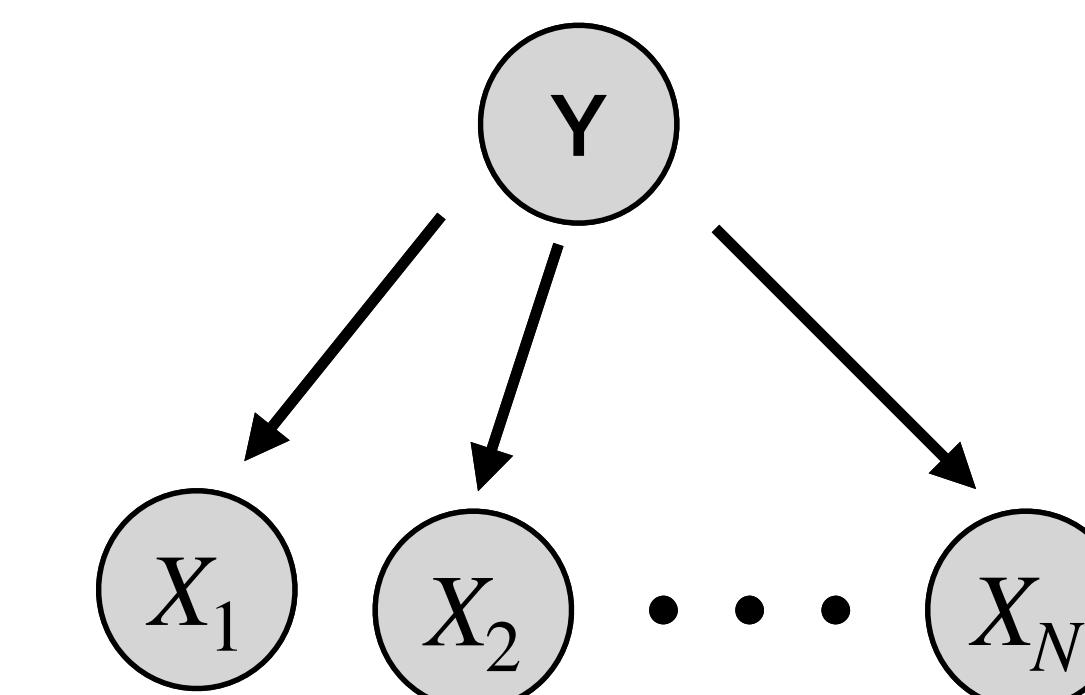
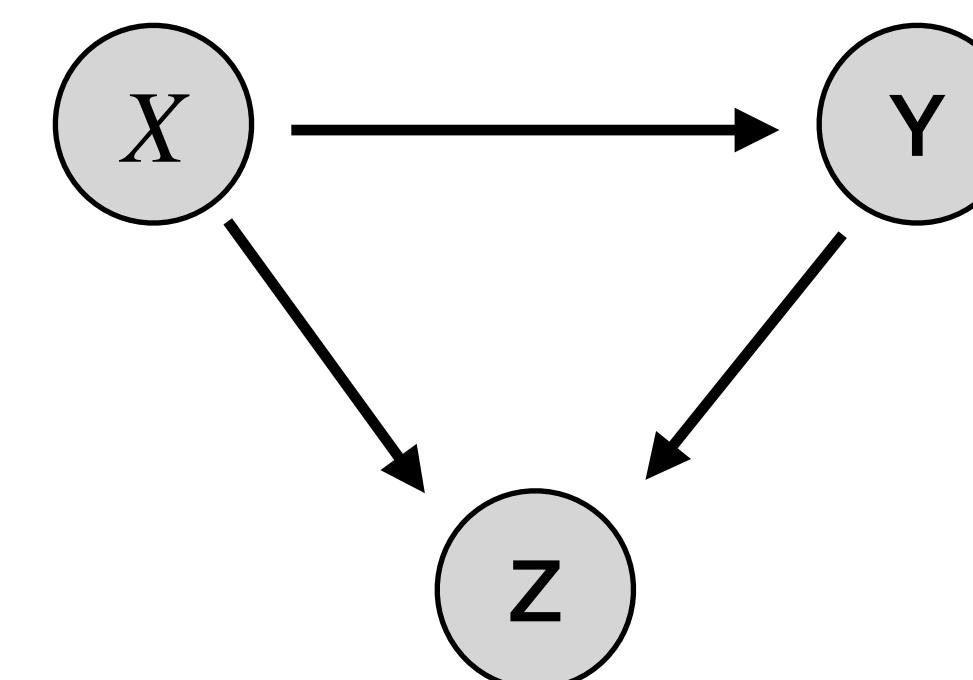
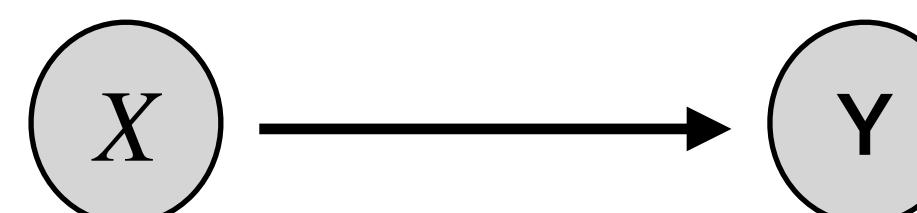
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**Example :**



$$P(X, Y) = P(Y|X) \times P(X)$$

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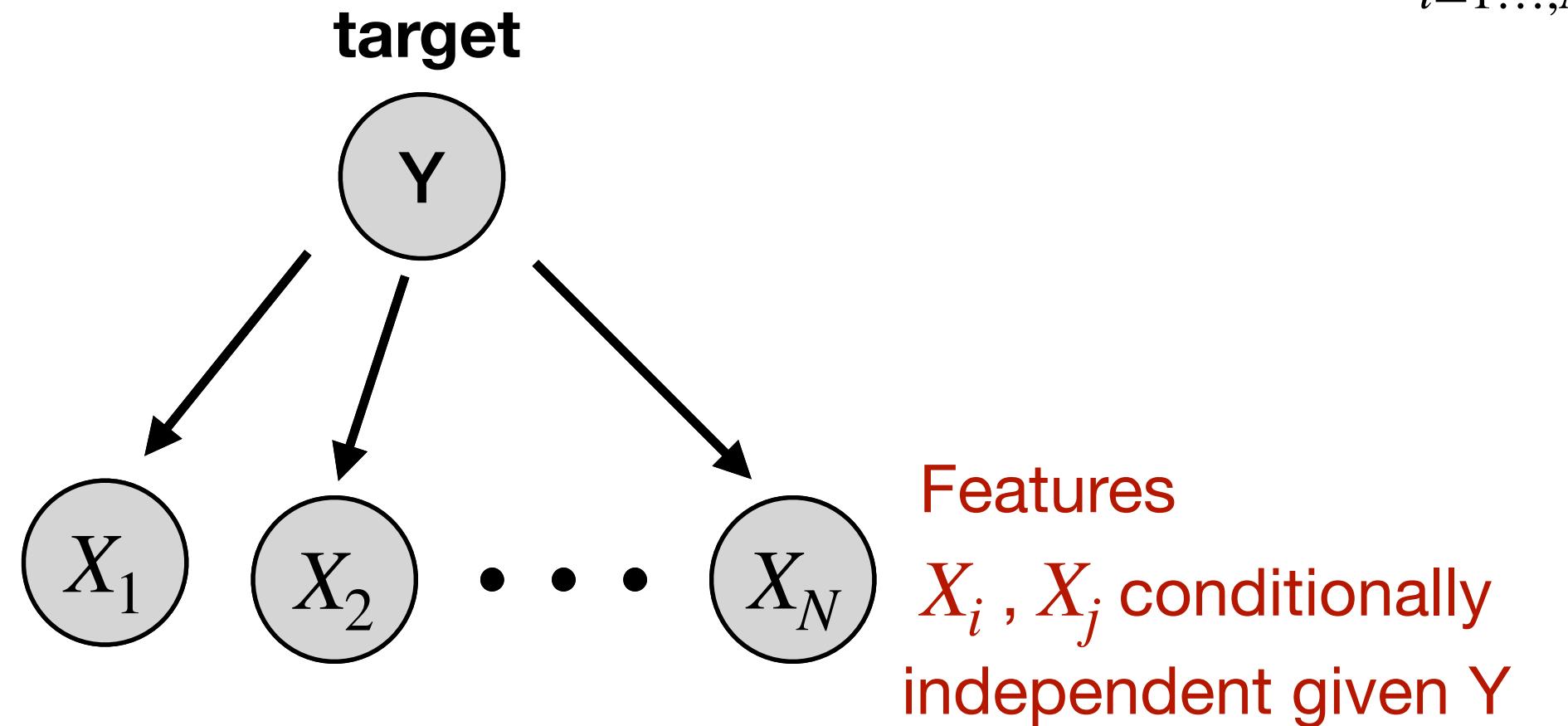
$$P(Y, X_1, \dots, X_N) = P(Y) \prod_{i=1, \dots, N} P(X_i | Y)$$

## 2. Probabilistic model

### Plates and examples of probabilistic model

#### Naive Bayes Classifier

$$P(Y, X_1, \dots, X_N) = P(Y) \prod_{i=1\dots,N} P(X_i | Y)$$

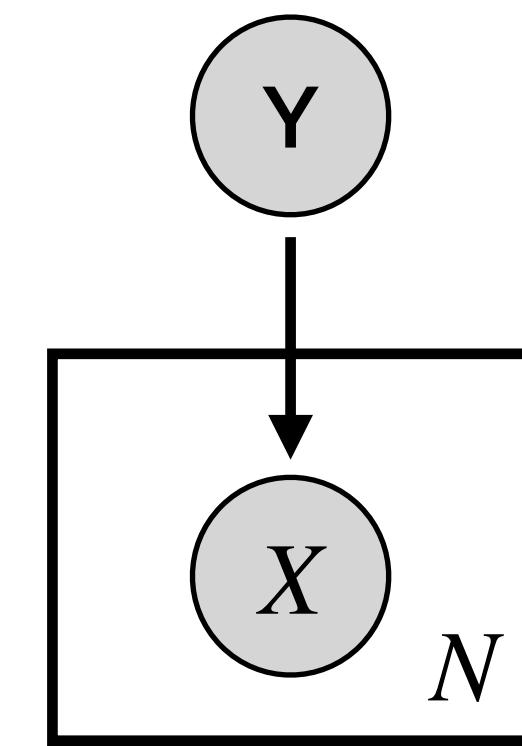
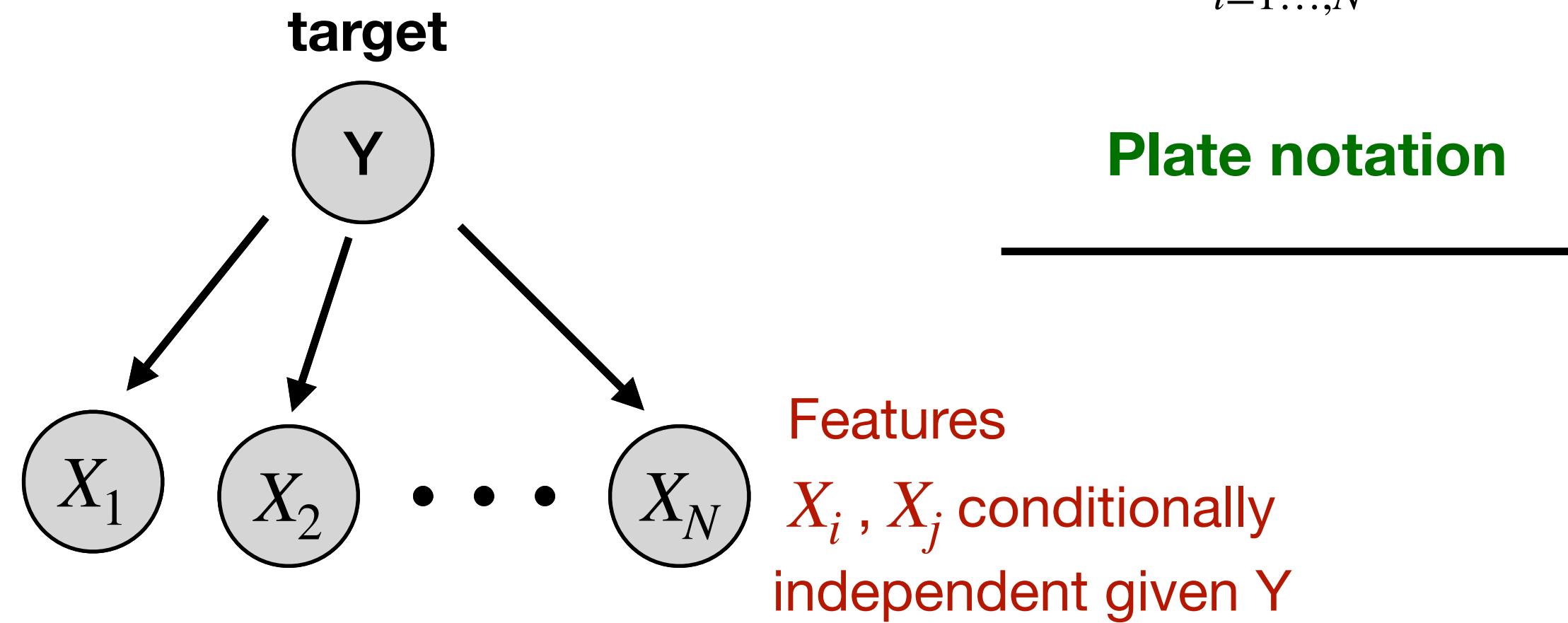


## 2. Probabilistic model

### Plates and examples of probabilistic model

#### Naive Bayes Classifier

$$P(Y, X_1, \dots, X_N) = P(Y) \prod_{i=1 \dots, N} P(X_i | Y)$$



## 2. Probabilistic model

### Frequentist linear regression

**Reminder : Frequentist linear regression**

$$x_i \in \mathbb{R}^d \quad y_i \in \mathbb{R}$$

**Scalar notation :**

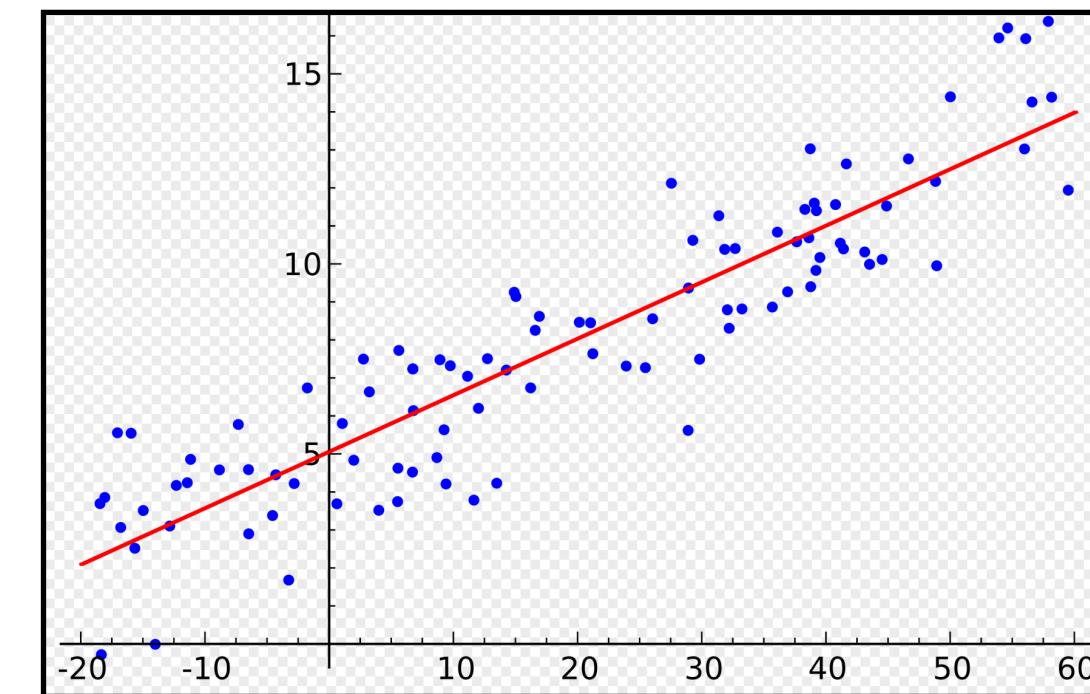
$$D = \{(x_1, y_1), \dots, (x_n, y_n)\}$$

$$y_i = x_i^T \theta + \epsilon_i$$

**Matrix notation :**

$$\mathbf{X} = (x_1, \dots, x_n) \text{ and } \mathbf{y} = (y_1, \dots, y_n)$$

$$y = \mathbf{X}^T \theta + \epsilon$$



$$\min_{\theta} \|\theta^T \mathbf{X} - \mathbf{y}\|^2$$

## 2. Probabilistic model

### Frequentist linear regression

**Reminder : Frequentist linear regression**

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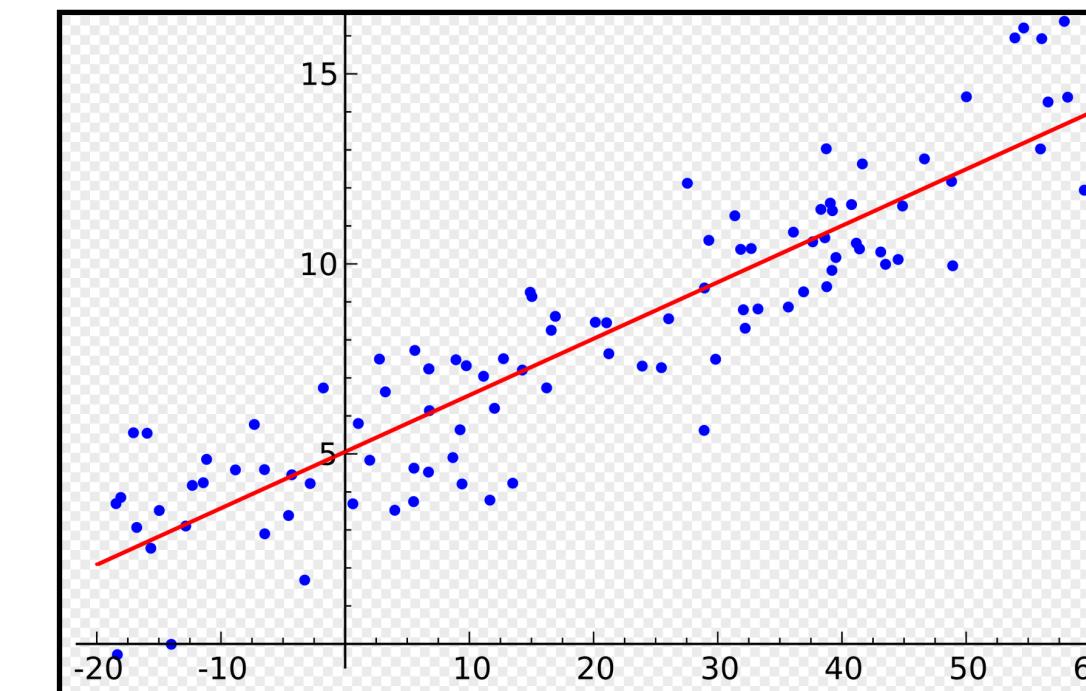
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**Matrix notation :**

$$\mathbf{X} = (x_1, \dots, x_n) \text{ and } \mathbf{y} = (y_1, \dots, y_n)$$

$$\mathbf{y} = \mathbf{X}^T \theta + \boldsymbol{\epsilon}$$



$$\min_{\theta} \|\theta^T \mathbf{X} - \mathbf{y}\|^2$$

**Proof : MLE for linear regression**

$$\mathbf{x} = (x_1, \dots, x_n), \mathbf{y} = (y_1, \dots, y_n), x_i \in \mathbb{R}^d, y_i \in \mathbb{R}$$

$$\mathbf{y} \sim N(\mathbf{w}^T \mathbf{x}, \sigma^2)$$

$\theta = \mathbf{w}$  we suppose that  $\sigma^2$  is known

$$y_1, \dots, y_n \text{ indep, } y_i \sim N(w^T x_i, \sigma^2) \text{ OR } y_i = w^T x_i + \varepsilon \text{ with } \varepsilon \sim N(0, \sigma^2)$$

$$\hat{\theta}_{MLE} = \underset{\theta \in \mathbb{R}^d}{\operatorname{argmax}} p(y | x, \theta)$$

$$p(y | x, \theta) = p(y_1, \dots, y_n | x_1, \dots, x_n, \theta) = \prod_{i=1}^n p(y_i | x_i, \theta)$$

$$= \prod_{i=1}^n \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{1}{2\sigma^2}(y_i - x_i^T \theta)^2\right)$$

$$= \left(\frac{1}{\sqrt{2\pi\sigma^2}}\right)^n \exp\left(-\frac{1}{2\sigma^2} \sum_{i=1}^n (y_i - x_i^T \theta)^2\right)$$

"vector  
matrix  
way"

$$\frac{1}{(2\pi\sigma^2)^{n/2}} \exp\left(-\frac{1}{2\sigma^2} (\mathbf{y} - \mathbf{x}^T \theta)^T (\mathbf{y} - \mathbf{x}^T \theta)\right)$$

$$l(\theta) = \log p(y | x, \theta) = -\frac{n}{2} \log(2\pi\sigma^2) - \frac{1}{2\sigma^2} (\mathbf{y} - \mathbf{x}^T \theta)^T (\mathbf{y} - \mathbf{x}^T \theta)$$

$$\frac{\partial l(\theta)}{\partial \theta} = 0 - \frac{1}{2\sigma^2} [\mathbf{0} - 2\mathbf{x}^T \mathbf{y} + 2\mathbf{x}^T \mathbf{x} \theta]$$

$$\frac{\partial l(\theta)}{\partial \theta} = 0 \Rightarrow \hat{\theta}_{MLE} = \theta = (\mathbf{x}^T \mathbf{x})^{-1} \mathbf{x}^T \mathbf{y}$$

## 2. Probabilistic model

### Bayesian linear regression

#### Bayesian Linear regression

**Scalar notation**  $D = \{(x_1, y_1), \dots, (x_n, y_n)\}$  with  $x_i \in \mathbb{R}^d, y_i \in \mathbb{R}$

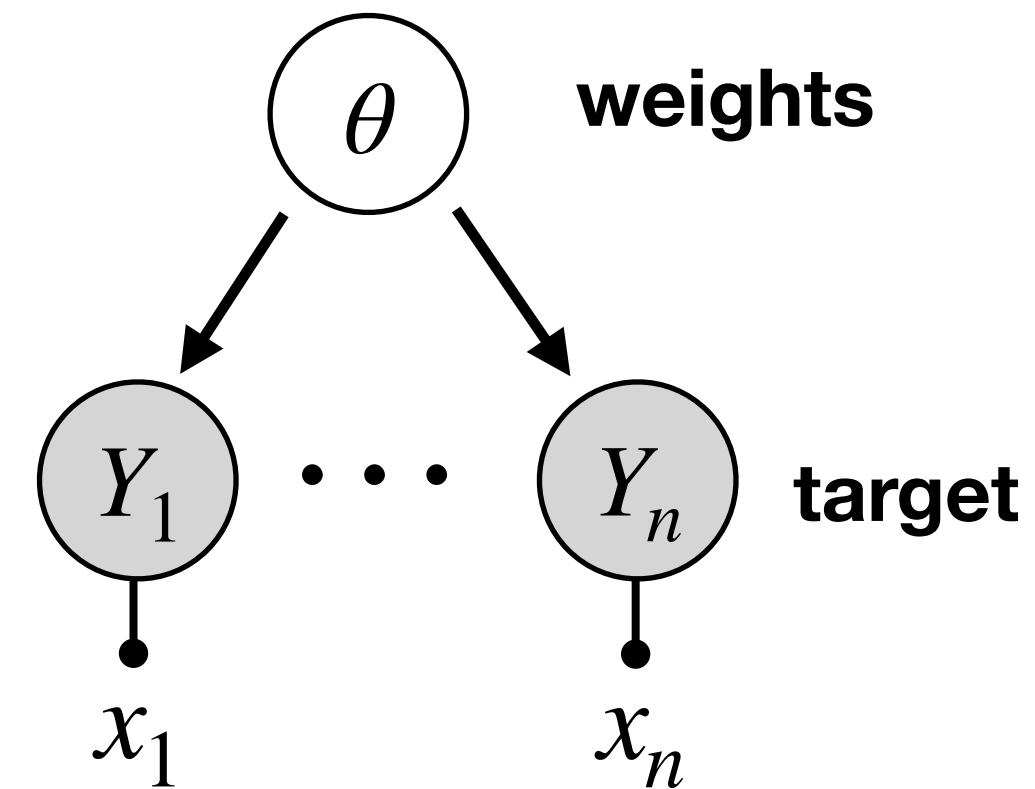
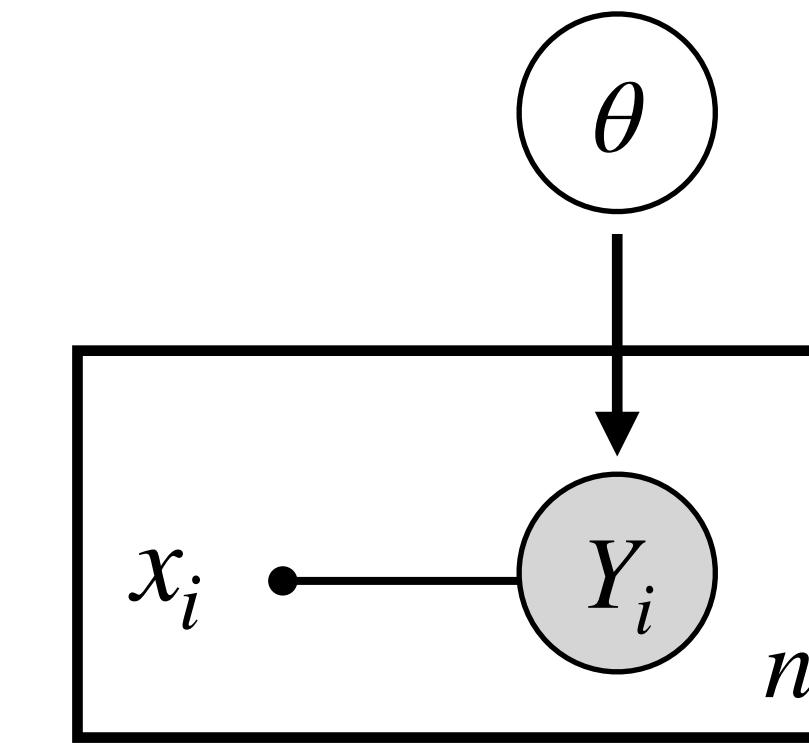
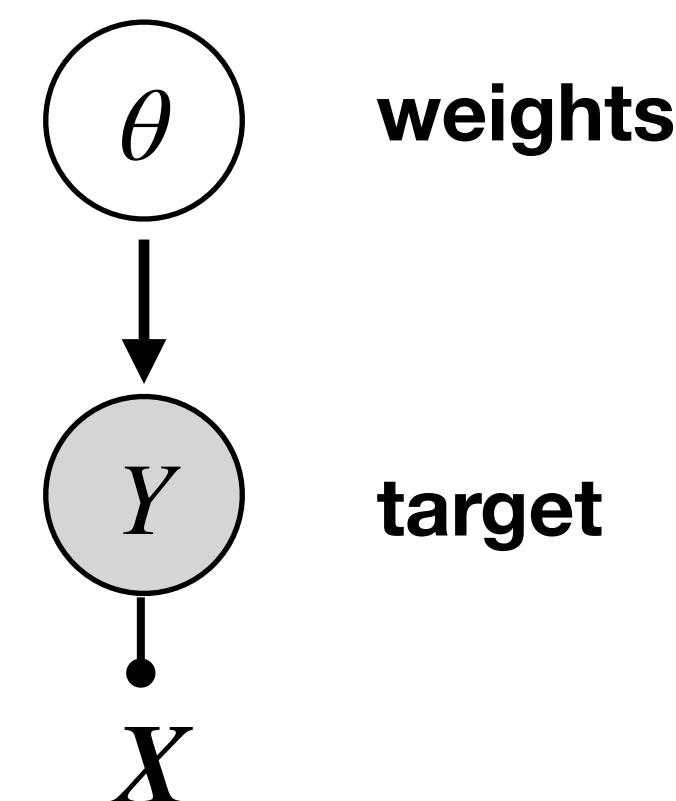


Plate notation  
→



$$P(\theta, y_i | x_i) = P(y_i | \theta, x_i) \times P(\theta)$$
$$P(y_i | \theta, x_i) = \dots$$
$$P(\theta) = \dots$$

**Matrix notation**  $\mathbf{X} = (x_1, \dots, x_n)$  and  $\mathbf{y} = (y_1, \dots, y_n)$  with  $x_i \in \mathbb{R}^d, y_i \in \mathbb{R}$



$$P(\theta, y | x) = P(y | \theta, x) \times P(\theta)$$
$$P(y | \theta, x) = \dots$$
$$P(\theta) = \dots$$

Legend :

— Fixed variable

○ Hidden (latent) r.v.

● Observed r.v.

## 2. Probabilistic model

### Bayesian linear regression

#### Bayesian Linear regression

**Scalar notation**  $D = \{(x_1, y_1), \dots, (x_n, y_n)\}$  with  $x_i \in \mathbb{R}^d, y_i \in \mathbb{R}$

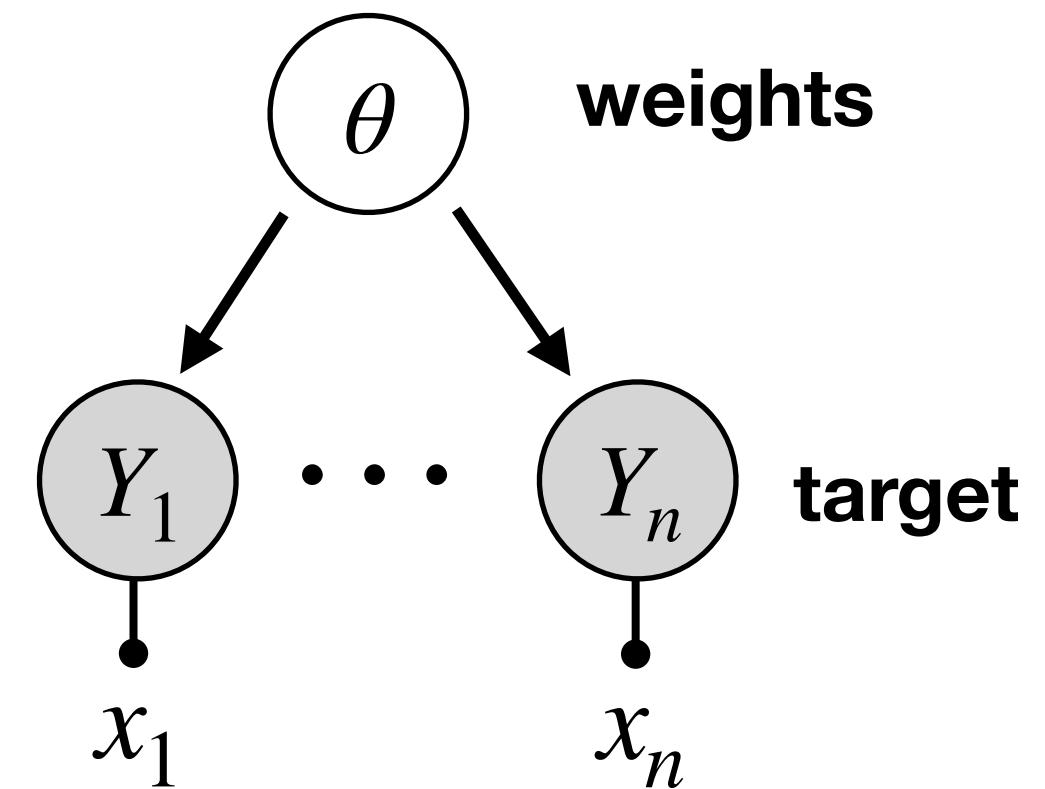
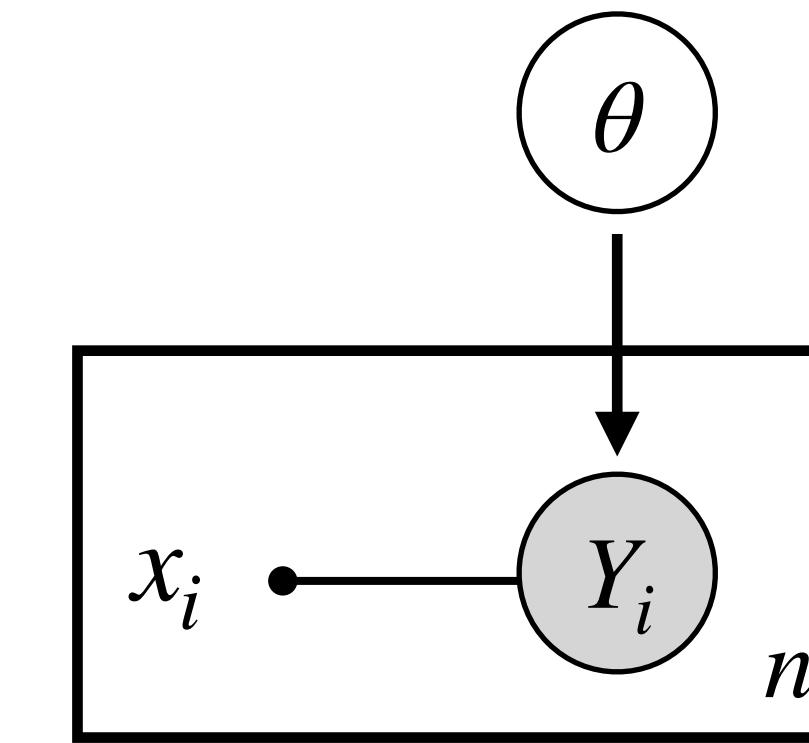


Plate notation

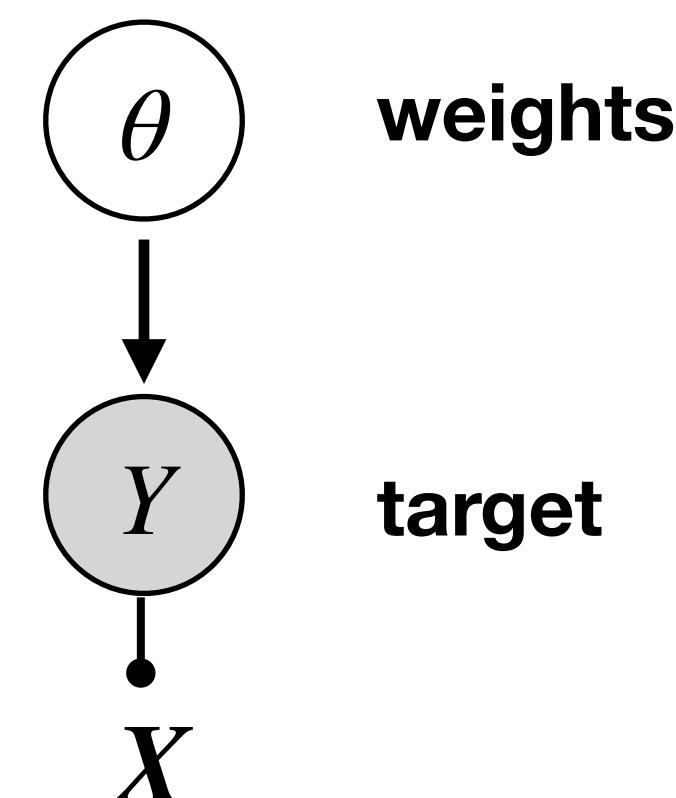


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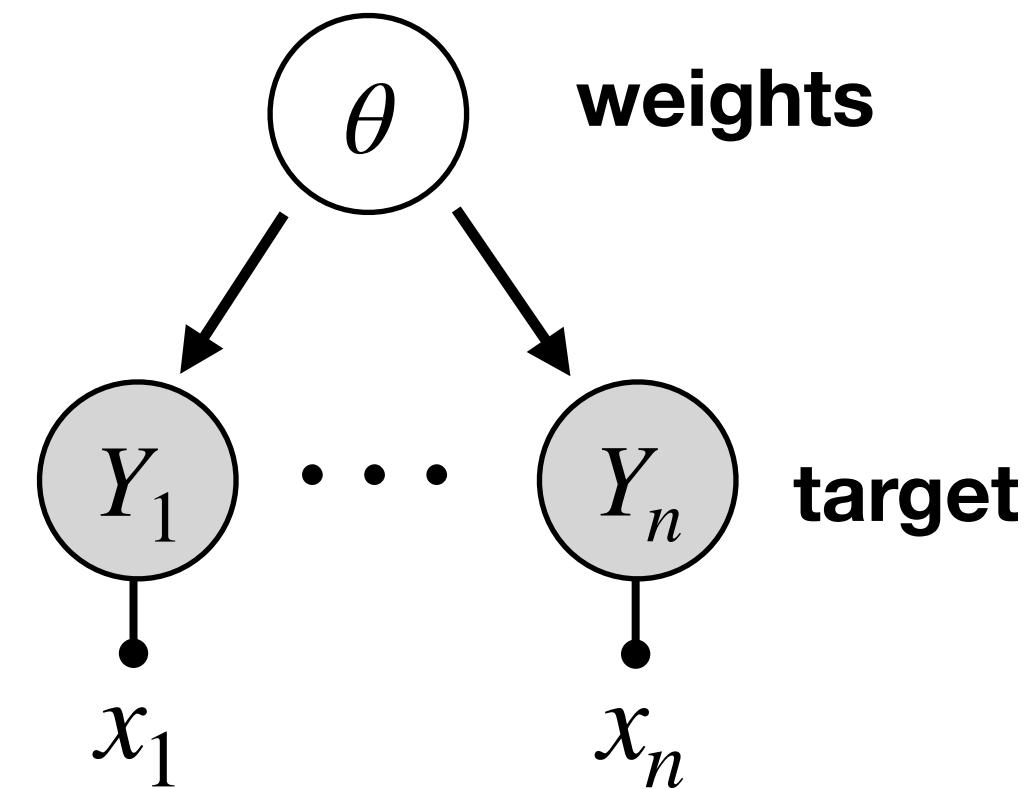
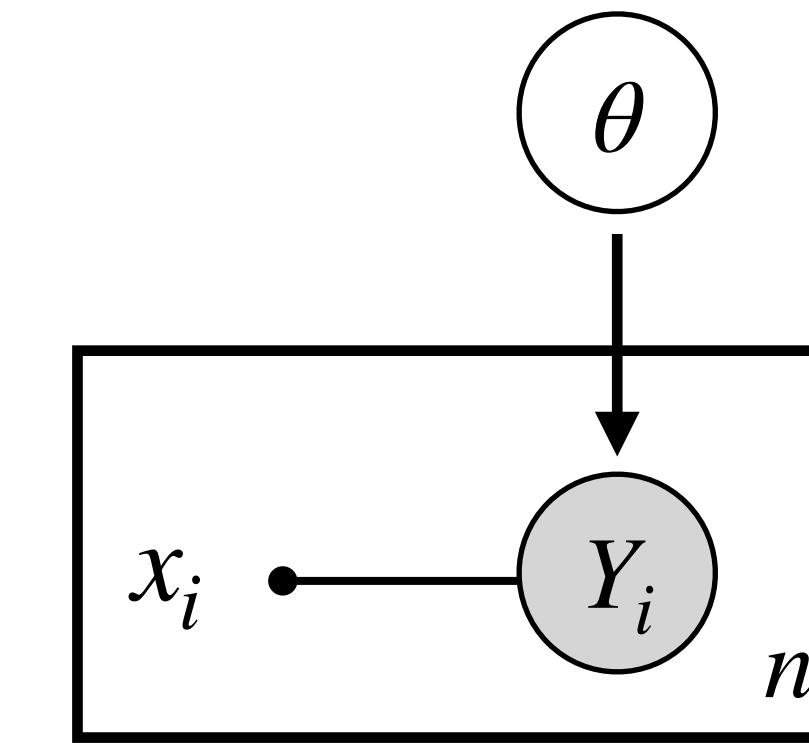


Plate notation

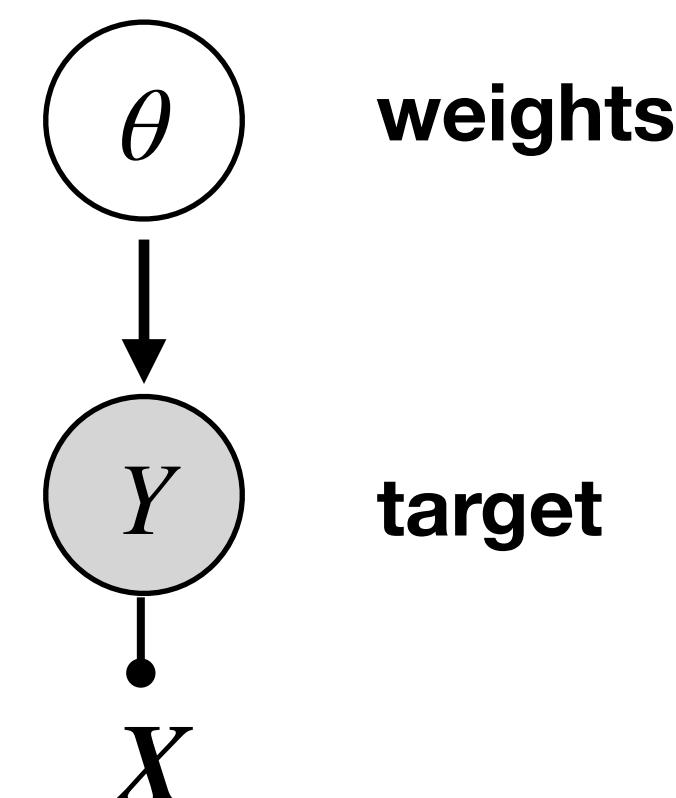


$$P(\theta, y_i | x_i) = P(y_i | \theta, x_i) \times P(\theta)$$

$$P(y_i | \theta, x_i) = \mathcal{N}(y_i | \theta^T x_i, \sigma^2)$$

$$P(\theta) = \mathcal{N}(\theta | 0, \gamma^2)$$

**Matrix notation**  $\mathbf{X} = (x_1, \dots, x_n)$  and  $\mathbf{y} = (y_1, \dots, y_n)$  with  $x_i \in \mathbb{R}^d, y_i \in \mathbb{R}$



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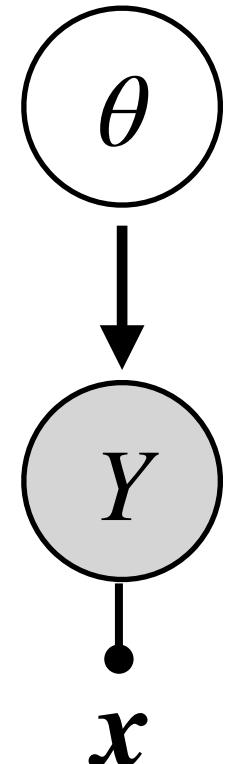
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## 2. Probabilistic model

### Linear regression

#### Bayesian Linear regression



$$P(\theta, y | X) = P(y | \theta, X) \times P(\theta)$$

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$$P(\theta) = \mathcal{N}(\theta | 0, \gamma^2 I_n)$$

**Objective :**

#### Frequentist linear regression

**Objective :**  $\min_{\theta} \mathcal{L}(\theta) = \min_{\theta} \|\theta^T X - y\|^2$

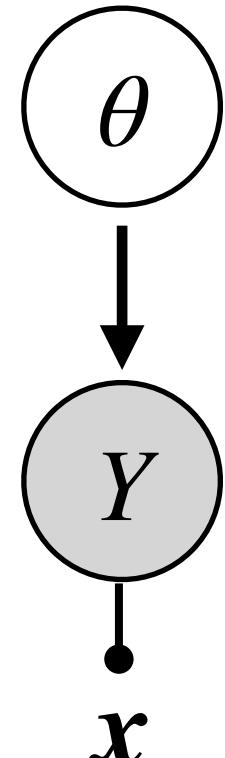
$$\hat{\theta} = \arg \min_{\theta} \mathcal{L}(\theta)$$

$$\hat{\theta} = (X^T X)^{-1} X^T y$$

## 2. Probabilistic model

### Linear regression

#### Bayesian Linear regression



$$P(\theta, y | X) = P(y | \theta, X) \times P(\theta)$$

$$P(y | \theta, X) = \mathcal{N}(y | \theta^T X, \sigma^2 I_n)$$

$$P(\theta) = \mathcal{N}(\theta | 0, \gamma^2 I_n)$$

**Objective :**  $\arg \max_{\theta} P(\theta | X, y) = \arg \max_{\theta} P(\theta, y | X)$

#### Frequentist linear regression

**Objective :**  $\min_{\theta} \mathcal{L}(\theta) = \min_{\theta} \|\theta^T X - y\|^2$

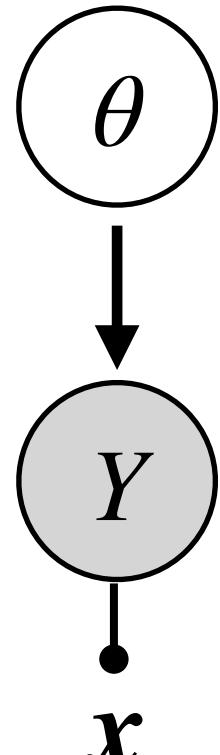
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## 2. Probabilistic model

### Linear regression

#### Bayesian Linear regression



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$$\hat{\theta} = \arg \min_{\theta} \mathcal{L}(\theta)$$

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#### Theorem :

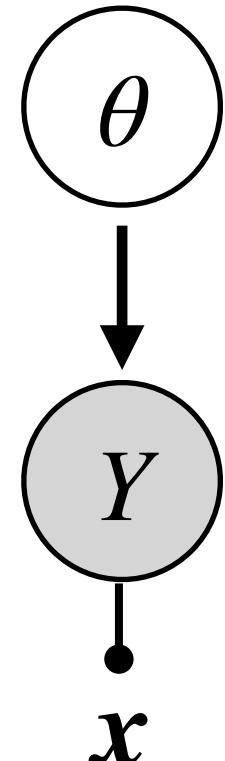
There exists  $\lambda \in \mathbb{R}$  such that :  $\arg \max_{\theta} P(\theta | X, y) = \arg \min_{\theta} \left\{ \|\theta^T X - y\|^2 + \lambda \|\theta\|^2 \right\}$

So by adding a normal prior on the weight we turned this problem into a  $L_2$  regularised problem

## 2. Probabilistic model

### Linear regression

#### Bayesian Linear regression



$$P(\theta, y | X) = P(y | \theta, X) \times P(\theta)$$

$$P(y | \theta, X) = \mathcal{N}(y | \theta^T X, \sigma^2 I_n)$$

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**Objective :**  $\arg \max_{\theta} P(\theta | X, y) = \arg \max_{\theta} P(\theta, y | X)$

#### Frequentist linear regression

**Objective :**  $\min_{\theta} \mathcal{L}(\theta) = \min_{\theta} \|\theta^T X - y\|^2$

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So by adding a normal prior on the weight we turned this problem into a  $L_2$  regularised problem

**Proof :** left as an exercise



3

## Analytical Inference

### 3. Analytical Inference

#### Reminder of posterior distribution

##### Posterior distribution

$$P(\theta | X) = \frac{P(X, \theta)}{P(X)} = \frac{\text{Likelihood} \times \text{Prior}}{\text{Evidence}}$$

### 3. Analytical Inference

#### Reminder of posterior distribution

##### Posterior distribution

The diagram illustrates the formula for the posterior distribution:

$$P(\theta | X) = \frac{P(X, \theta)}{P(X)} = \frac{P(X | \theta) \times P(\theta)}{P(X)}$$

The components are labeled as follows:

- Likelihood**: Fixed by model
- Prior**: Fixed by us
- Evidence**: Fixed by data
- Posterior**: The resulting distribution

### 3. Analytical Inference

#### Reminder of posterior distribution

##### Posterior distribution

$$P(\theta | X) = \frac{P(X, \theta)}{P(X)} = \frac{P(X | \theta) \times P(\theta)}{P(X)}$$

Posterior

Fixed by model      Likelihood      Prior      Fixed by us

Evidence  
HARD TO COMPUTE

$$P(X) = \int_{\theta} P(X | \theta) \cdot P(\theta) \cdot d\theta$$

Fixed by data

### 3. Analytical Inference

#### Maximum a posteriori (MAP) : definition & remarks

##### Posterior distribution

$$P(\theta | X) = \frac{P(X, \theta)}{P(X)} = \frac{P(X | \theta) \times P(\theta)}{P(X)}$$

**Posterior**

**Fixed by model**

**Likelihood**

**Prior**

**Fixed by us**

**Evidence**

**HARD TO COMPUTE**

**Fixed by data**

$$P(X) = \int_{\theta} P(X | \theta) \cdot P(\theta) \cdot d\theta$$

##### Remarks

- We have to **avoid computing** the evidence
- Naive approach : **maximum a posteriori** ,  
$$\hat{\theta}_{MAP} = \arg \max_{\theta} \left\{ \frac{P(\theta | X) \cdot P(\theta)}{P(X)} \right\}$$
$$= \arg \max_{\theta} P(X | \theta) \cdot P(\theta)$$
- This maximization can be done with numerical **optimization** problem

# 3. Analytical Inference

## Maximum a posteriori (MAP) : limitations

### Posterior distribution

$$P(\theta | X) = \frac{P(X, \theta)}{P(X)} = \frac{P(X | \theta) \times P(\theta)}{P(X)}$$

**Posterior**

**Likelihood**      **Prior**

**Evidence**  
**HARD TO COMPUTE**

**Fixed by model**

**Fixed by us**

**Fixed by data**

$$P(X) = \int_{\theta} P(X | \theta) \cdot P(\theta) \cdot d\theta$$

### Remarks

- We have to **avoid computing** the evidence
- Naive approach : **maximum a posteriori** ,  
$$\hat{\theta}_{MAP} = \arg \max_{\theta} \left\{ \frac{P(\theta | X) \cdot P(\theta)}{P(X)} \right\}$$
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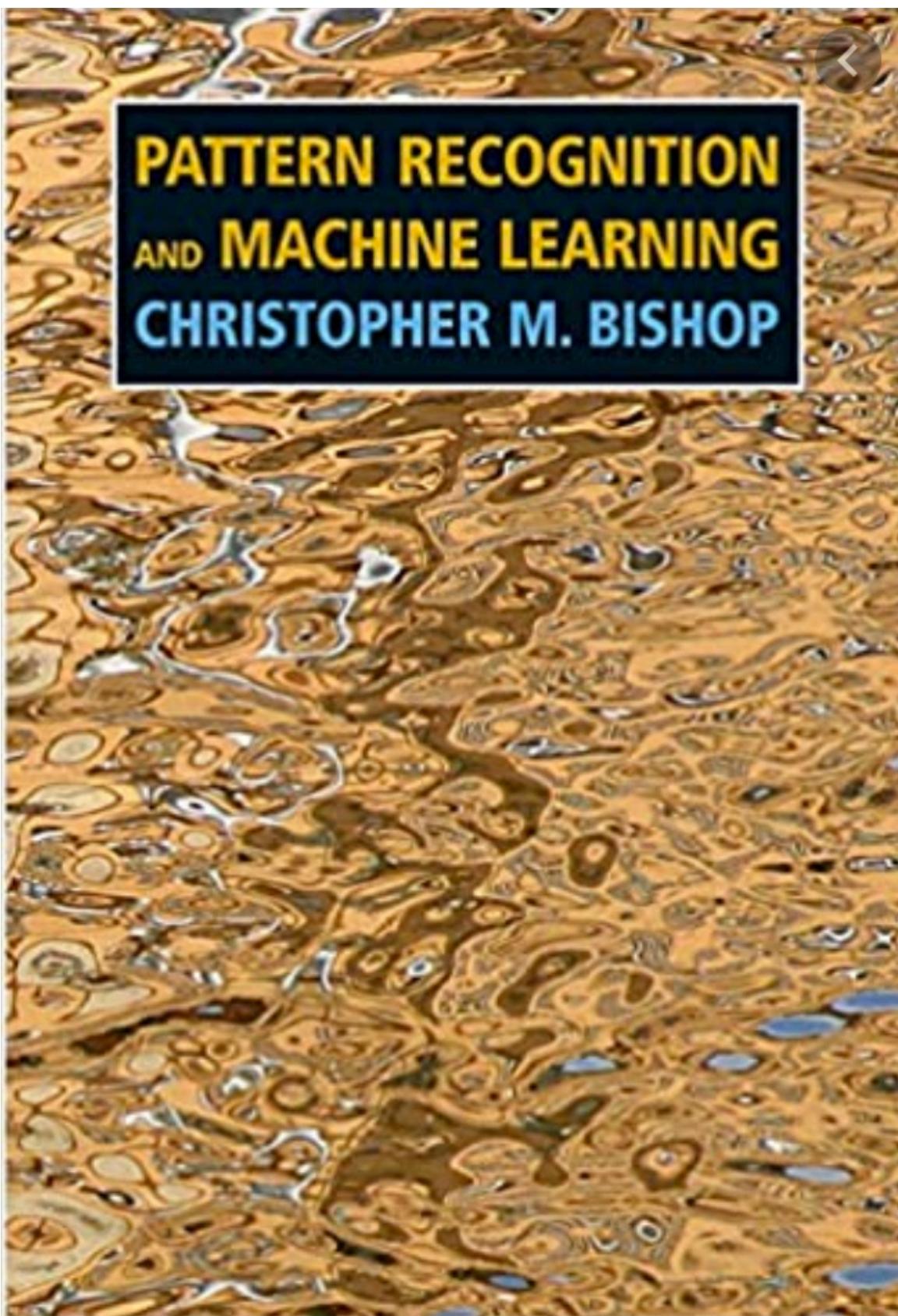
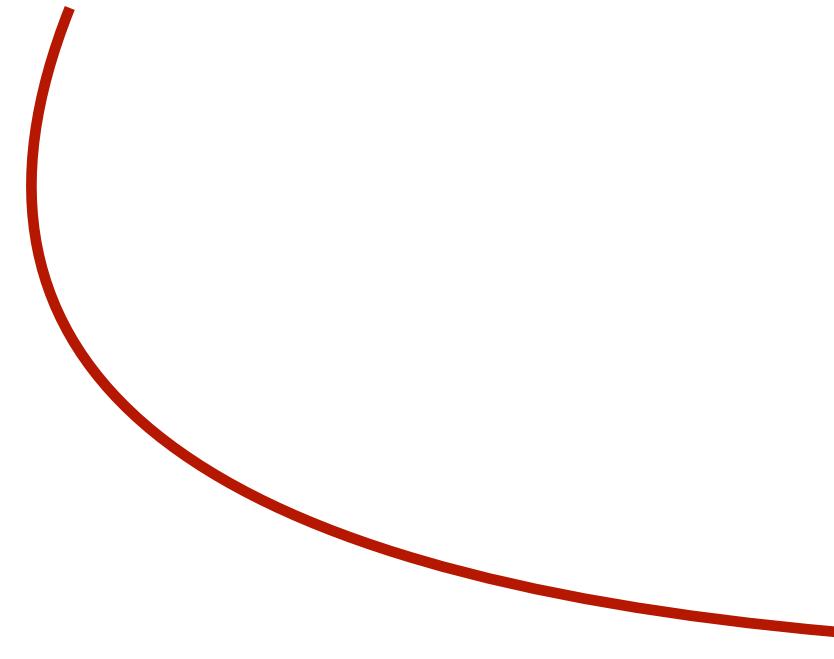
### Limitations (among many others)

1. in general, **not representative of bayesian** methods :  $\hat{\theta}_{MAP}$  is a point estimate like  $\hat{\theta}_{MLE}$ 
  - can't compute **credible intervals** because it doesn't return a pdf/pmf (not a bayesian inference)
2. **can't use online learning** : the prior is not well updated

### 3. Analytical Inference

#### Maximum a posteriori (MAP) : book

For more theoretical details (and example on analytical inference) :



4

## Conjugate distributions

# 4. Conjugate distributions

Conjugate distributions : avoid computing evidence

Posterior distribution

The diagram illustrates the formula for the posterior distribution:

$$P(\theta | X) = \frac{P(X, \theta)}{P(X)} = \frac{P(X | \theta) \times P(\theta)}{P(X)}$$

The components are labeled as follows:

- Likelihood**: Fixed by model
- Prior**: Fixed by us
- Evidence**: Fixed by data

# 4. Conjugate distributions

## Conjugate distributions : avoid computing evidence

### Posterior distribution

$$P(\theta | X) = \frac{P(X, \theta)}{P(X)} = \frac{P(X | \theta) \times P(\theta)}{\text{Evidence}}$$

Posterior

Fixed by model

Likelihood

Prior

Fixed by us

Evidence

Fixed by data

The diagram illustrates the formula for the posterior distribution,  $P(\theta | X)$ , as a fraction. The numerator is  $P(X, \theta)$ , which is factored into  $P(X | \theta) \times P(\theta)$ . The term  $P(X | \theta)$  is labeled 'Likelihood' and 'Fixed by model'. The term  $P(\theta)$  is labeled 'Prior' and 'Fixed by us'. The denominator is labeled 'Evidence' and 'Fixed by data'.

### Remarks

- We have to **avoid computing** the evidence
- We can choose a **convenient prior** which enable us to compute the posterior : **Conjugate prior**

# 4. Conjugate distributions

## Conjugate distributions : avoid computing evidence

### Posterior distribution

$$P(\theta | X) = \frac{P(X, \theta)}{P(X)} = \frac{P(X | \theta) \times P(\theta)}{P(X)}$$

Posterior

Fixed by model

Likelihood

Prior

Fixed by us

Evidence

Fixed by data

### Remarks

- We have to **avoid computing** the evidence
- We can choose a **convenient prior** which enable us to compute the posterior :  
**Conjugate prior**

### Conjugate prior

$P(\theta)$  is **conjugate** to  $P(X | \theta)$  if the  $P(\theta)$  and  $P(\theta | X)$  lie in the same family of distributions ( gaussian for example )

# 4. Conjugate distributions

## Conjugate distributions : avoid computing evidence

### Posterior distribution

$$P(\theta | X) = \frac{P(X, \theta)}{P(X)} = \frac{P(X|\theta) \times P(\theta)}{P(X)}$$

Posterior

Likelihood      Prior

Evidence

Fixed by model      Fixed by us      Fixed by data

### Remarks

- We have to **avoid computing** the evidence
- We can choose a **convenient prior** which enable us to compute the posterior :  
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### Conjugate prior

$P(\theta)$  is **conjugate** to  $P(X|\theta)$  if the  $P(\theta)$  and  $P(\theta|X)$  lie in the same family of distributions ( gaussian for example )

### Example

$$P(\theta | X) = \frac{\mathcal{N}(X|\theta, \sigma^2) \times P(\theta)}{P(X)}$$

$\mathcal{N}(\theta | \mu_{posterior}, \sigma^2_{posterior})$

$\mathcal{N}(\theta | \mu_{prior}, \sigma^2_{prior})$

In the context of a gaussian, the prior for the mean is a gaussian !

# 4. Conjugate distributions

## Limitations

### Posterior distribution

$$P(\theta | X) = \frac{P(X, \theta)}{P(X)} = \frac{P(X | \theta) \times P(\theta)}{\text{Evidence}}$$

Posterior

Fixed by model

Likelihood

Prior

Fixed by us

Evidence

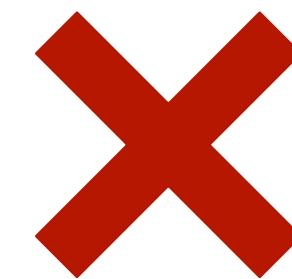
Fixed by data

### Remarks

- We have to **avoid computing** the evidence
- We can choose a **convenient prior** which enable us to compute the posterior :  
**Conjugate prior**



- It computes the **exact posterior**
- Easy for **online learning**



- For some (**complex**) models, the conjugate prior can be **inadequate (improper prior)**
- Can be **unrealistic (non-informative prior)**

5

## Conjugate distributions : Exercices

# 5. Conjugate distributions

## Exercices

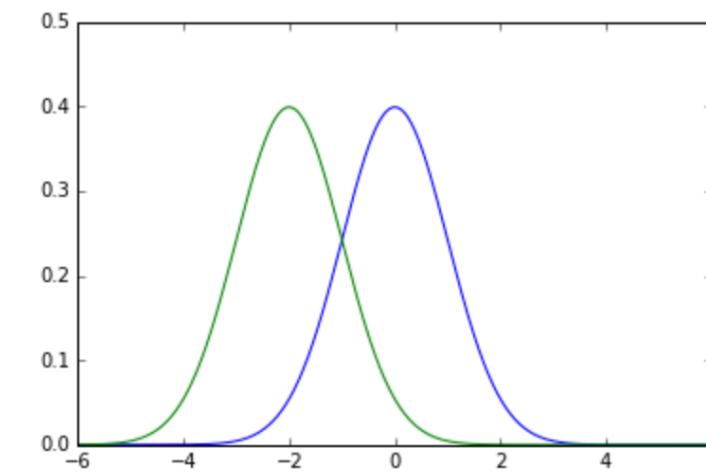


If you do these exercices before the next lecture,  
you'll have **bonus points**:

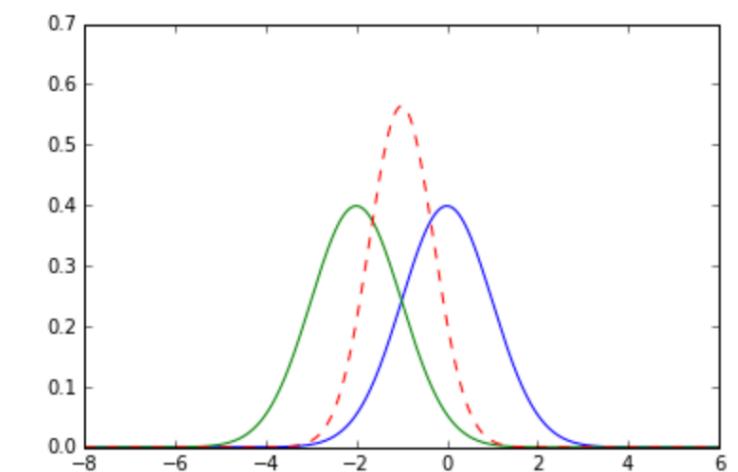
- 0.25 pts if only the reasoning is good
- 0.5 pts if only some of them are correct
- 0.75 pts if most of them are correct
- 1 pts if all of them are correct

**Exercice** (left as an exercice, correction in the next lecture)

Show that  $\mathcal{N}(\theta | x/2, 1/2) = \frac{\mathcal{N}(x | \theta, 1) \times \mathcal{N}(\theta | 0, 1)}{P(x)}$



→ **pointwise product**



**Exercice** (left as an exercice, correction in the next lecture)

show the following equation

$$\Gamma(\gamma | \alpha_{posterior}, \beta_{posterior}) = P(\gamma | x) = \frac{\mathcal{N}(x | \mu, \gamma^{-1}) \times P(\gamma)}{P(x)} \quad \Gamma(\gamma | \alpha_{prior}, \beta_{prior})$$
$$\Gamma(\gamma | \alpha_{prior} + 1/2, \beta_{prior} + (x - \mu)^2/2)$$

In the context of a gaussian, the prior for the precision is a gamma !

**Exercice** (left as an exercice, correction in the next lecture)

show the following equation

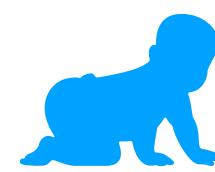
$$B(\theta | \alpha_{posterior}, \beta_{posterior}) = P(\theta | x) = \frac{Ber(x | \theta) \times P(\theta)}{P(x)} \quad B(\theta | \alpha_{prior}, \beta_{prior})$$
$$B(\theta | n_1 + \alpha_{prior}, n_0 + \beta_{prior})$$

In the context of a Bernoulli distribution, the prior is a beta !

!

## Road map

## Bayesian statistics



1

**Bayesian perspective :**

$$P(\theta | X) = \frac{P(X, \theta)}{P(X)} = \frac{P(X | \theta) \cdot P(\theta)}{P(X)}$$

Posterior distribution

$\theta$  parameters

$X$  observations

**Exemple :**  
Naive Bayes classifier,  
Linear regression, ....

Likelihood Prior distribution

Evidence

Hard to compute !

MAP :  $\arg \max_{\theta} P(X | \theta) \cdot P(\theta)$

Conjugate distribution

**Pros :**  
- exact posterior

**Cons :**  
- conjugate prior  
maybe inadequate

## Latent variable models

2

## Variational Inference

3

## Causal Inference

4

## Oral presentations

5