



Bayesian Machine Learning

03/05/21 - François HU

Outline

1

Bayesian statistics

- define a probabilistic model
- apply bayesian inference
- conjugate priors

2

Latent variable models

- define latent variable and apply them to simplify probabilistic model
- cluster data with latent models like GMM
- train probabilistic models with EM-algorithm

3

Variational Inference

- apply variational inference for probabilistic models
- understand variational interpretation of LDA
- application of LDA to text mining

4

Markov Chain Monte Carlo

- train / do inference almost any probabilistic model with MCMC
- pros and cons of MCMC / VI

5

Extensions and oral presentations

PREREQUISITE

THEORY

1. Notions of **probability & statistics**
2. **Statistical Learning :**
supervised & unsupervised learning
3. **Information theory :**
Entropy, KL-divergence, ...
4. **Monte Carlo & Markov Chain**

APPLICATION

Python (or at least R)

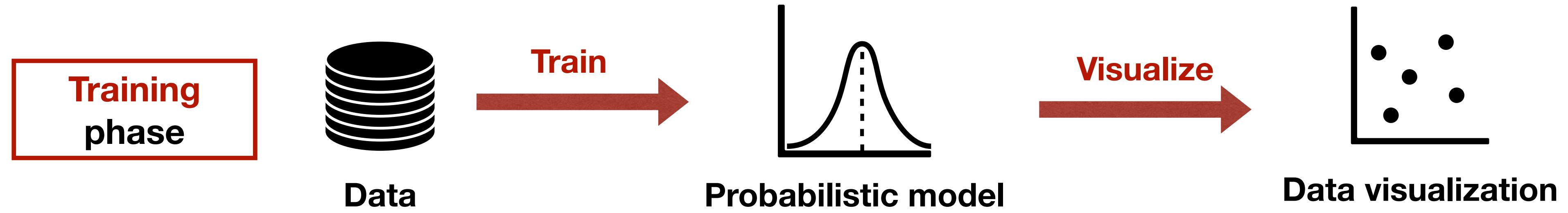
ALGORITHM

Some « classical » supervised & unsupervised models

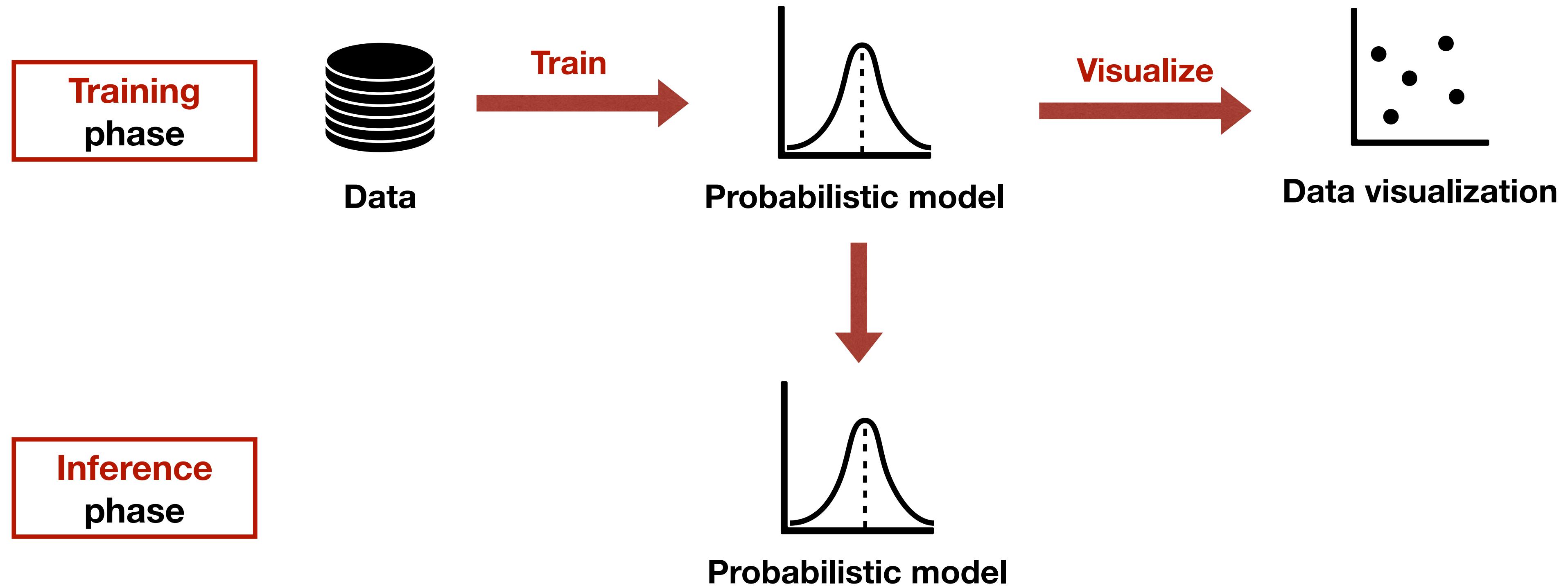
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Gentle introduction to statistical learning

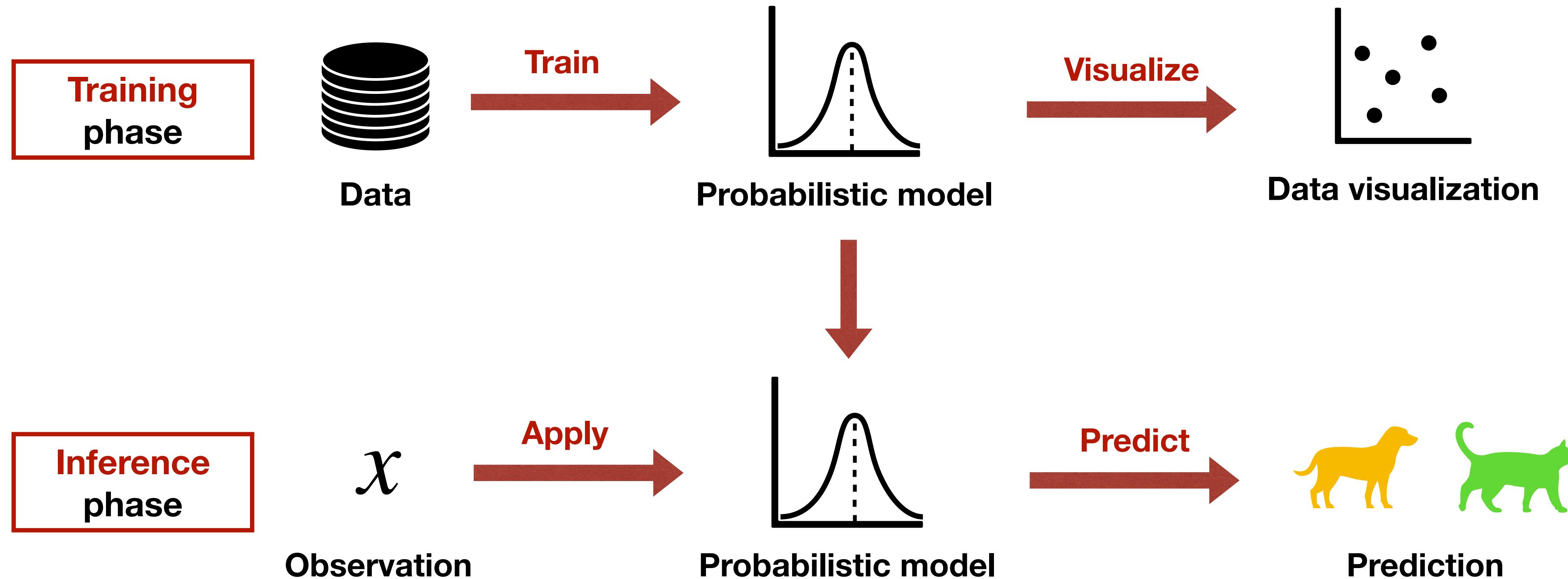
Simplified statistical learning process



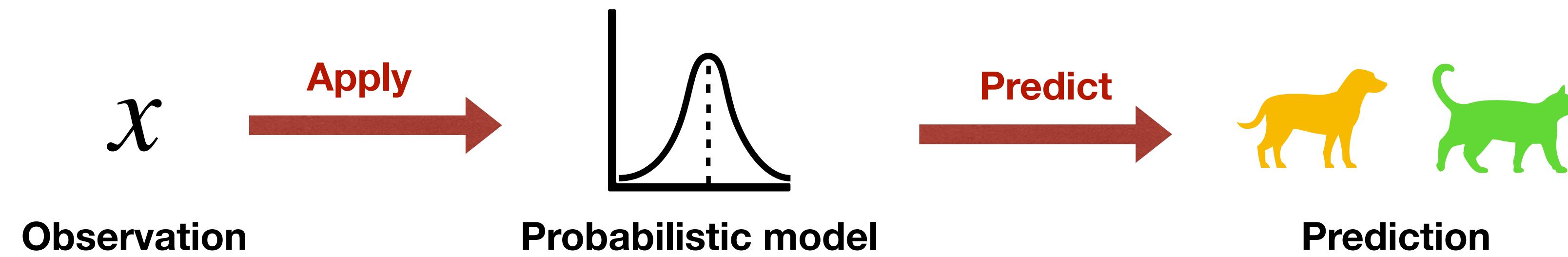
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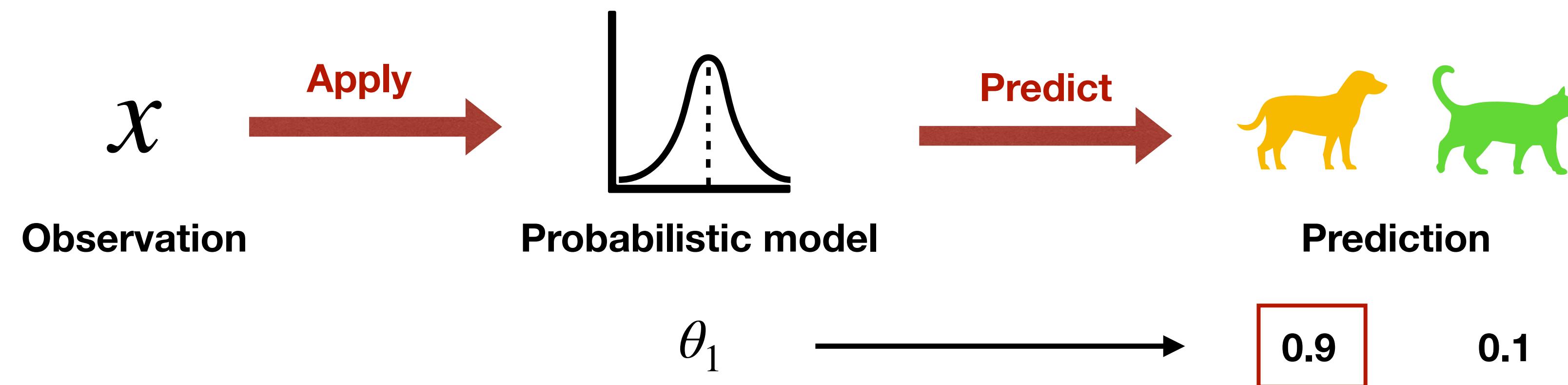
Simplified statistical learning process



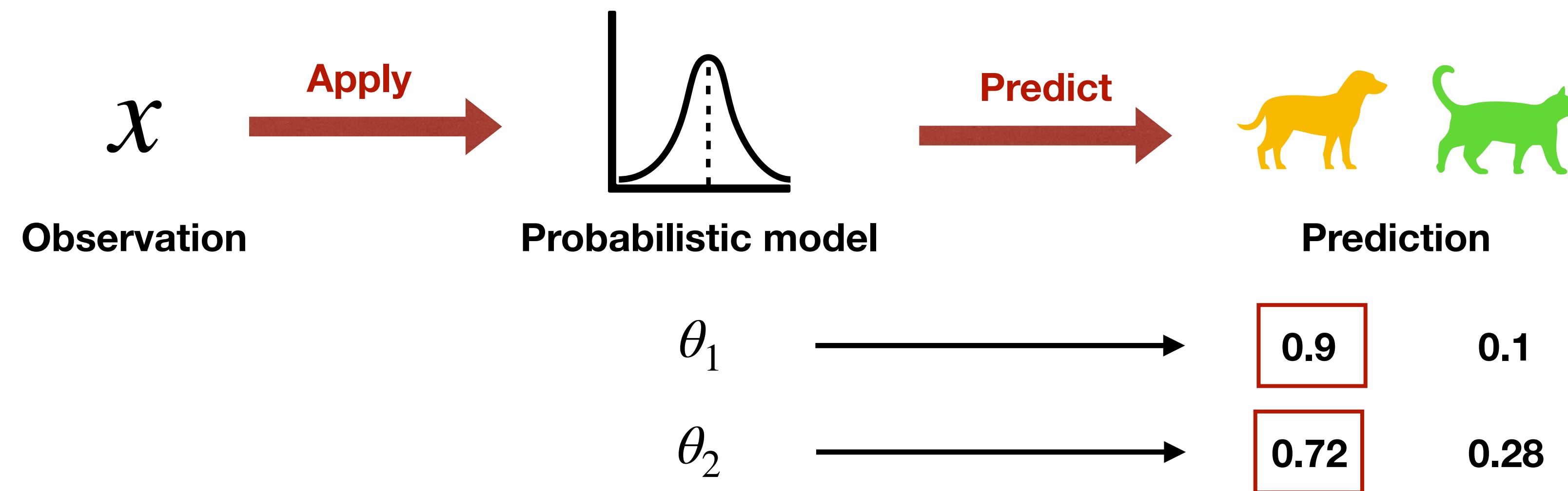
Inference phase



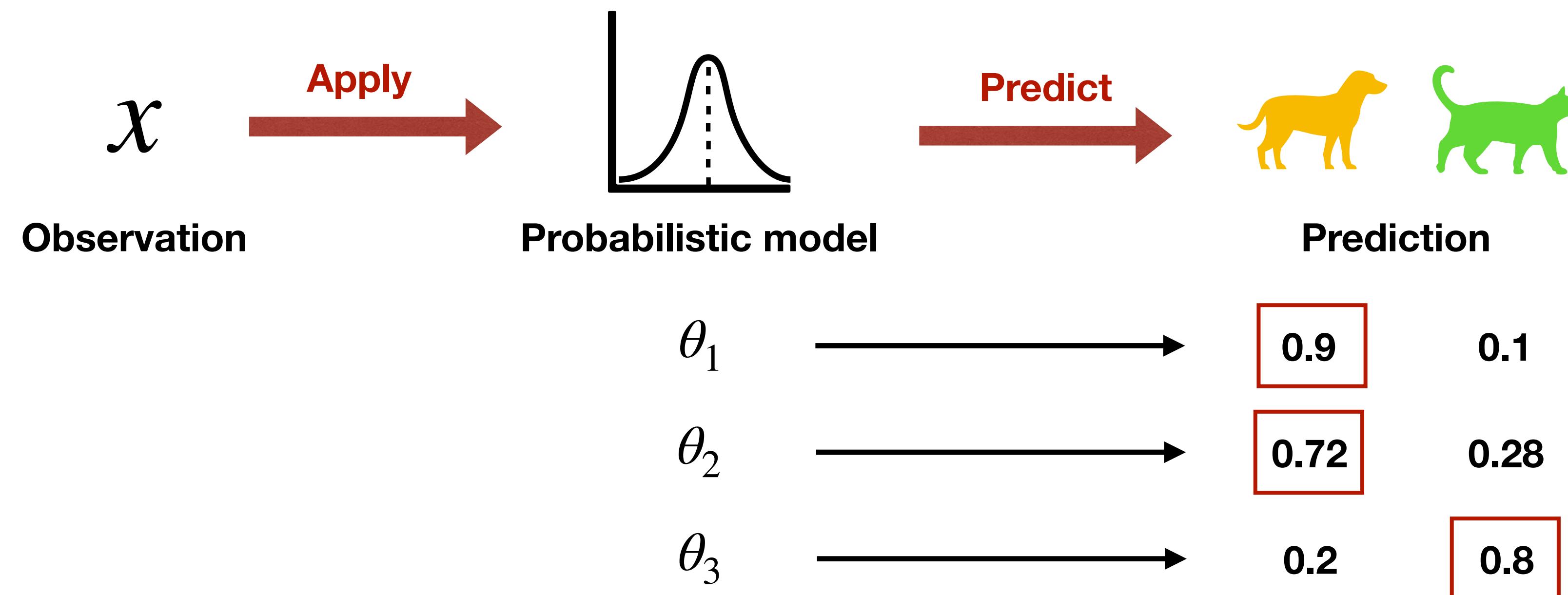
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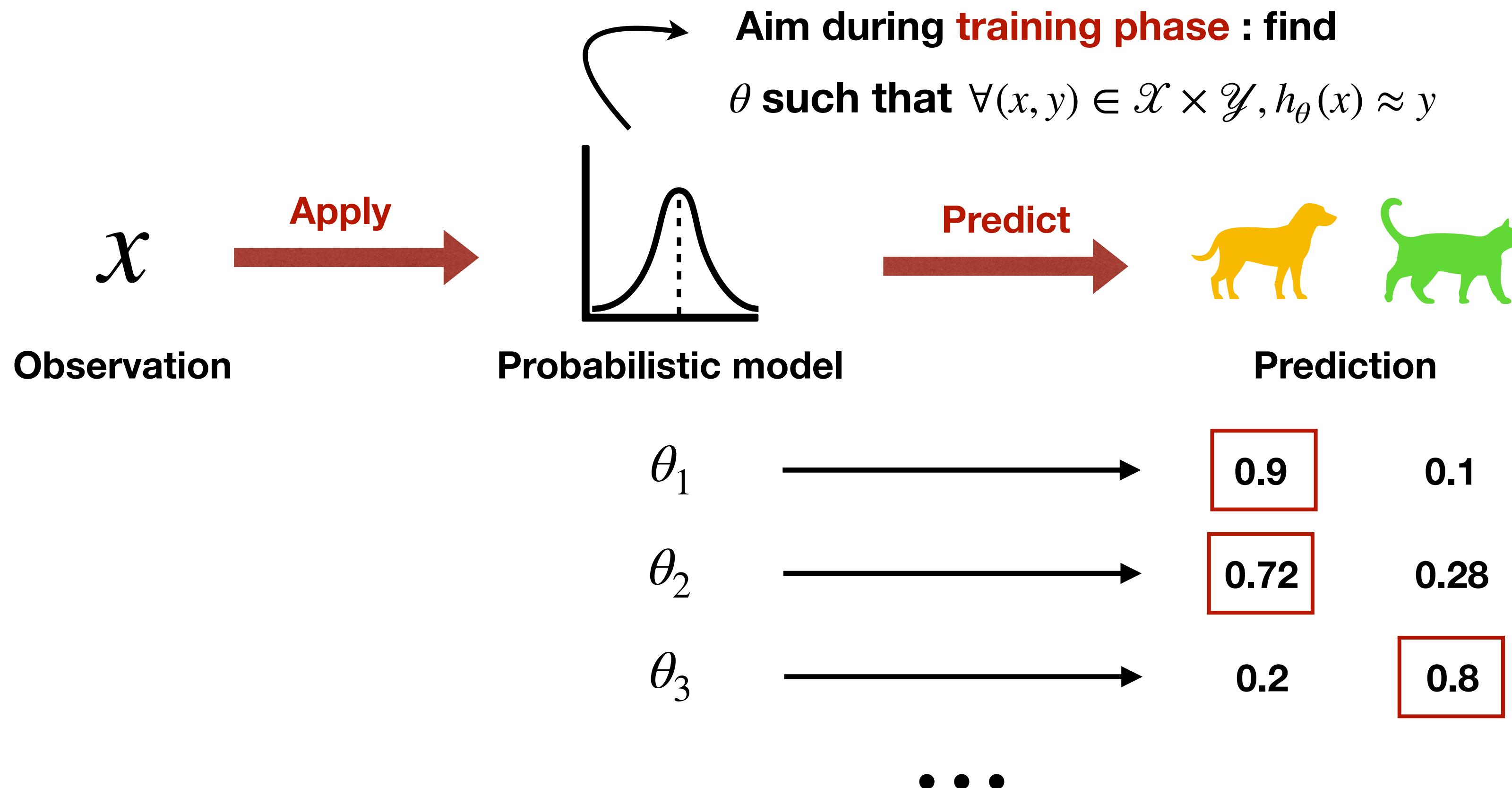
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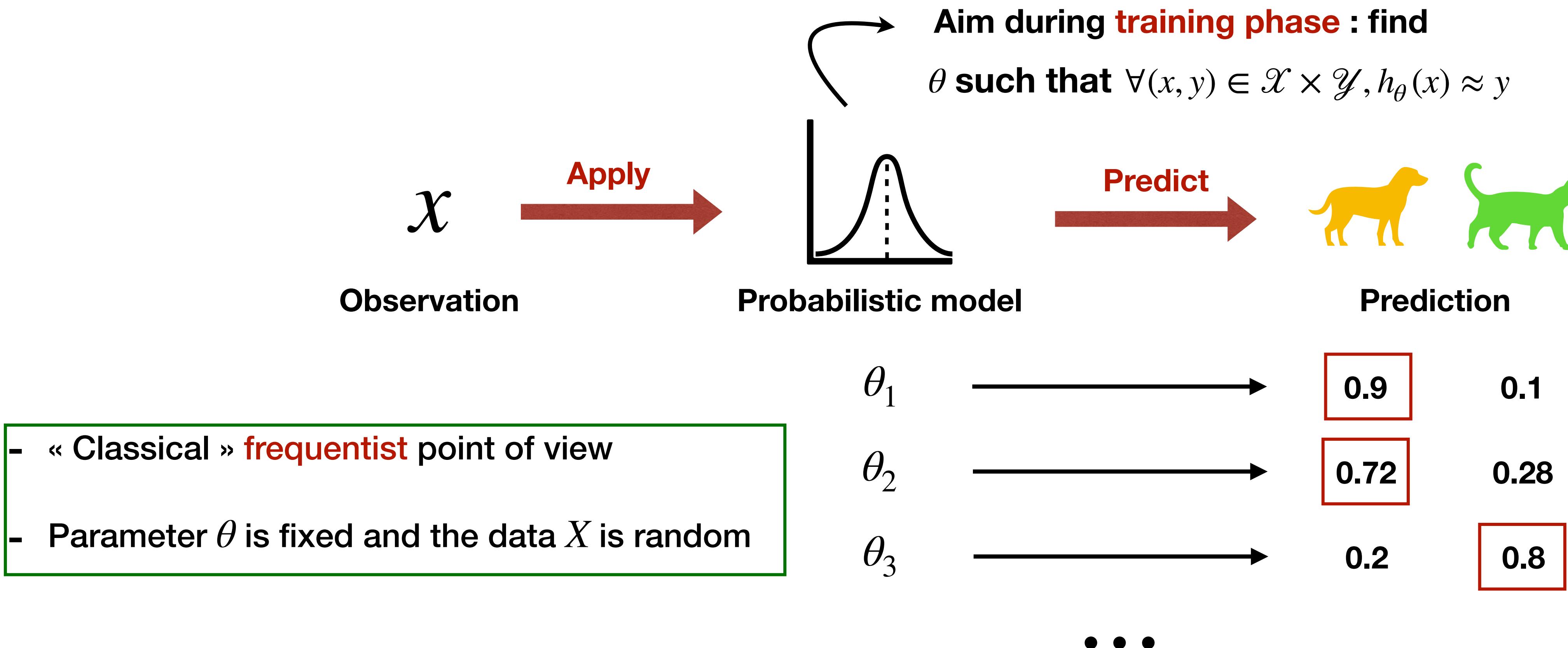
Inference phase



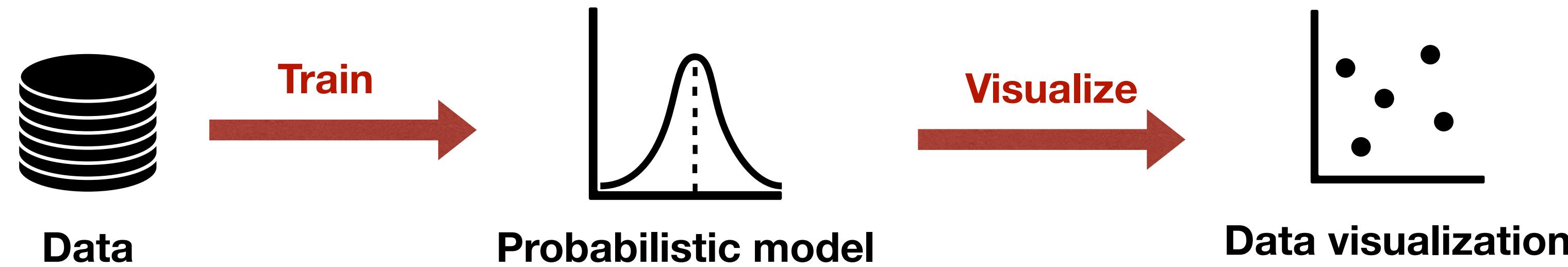
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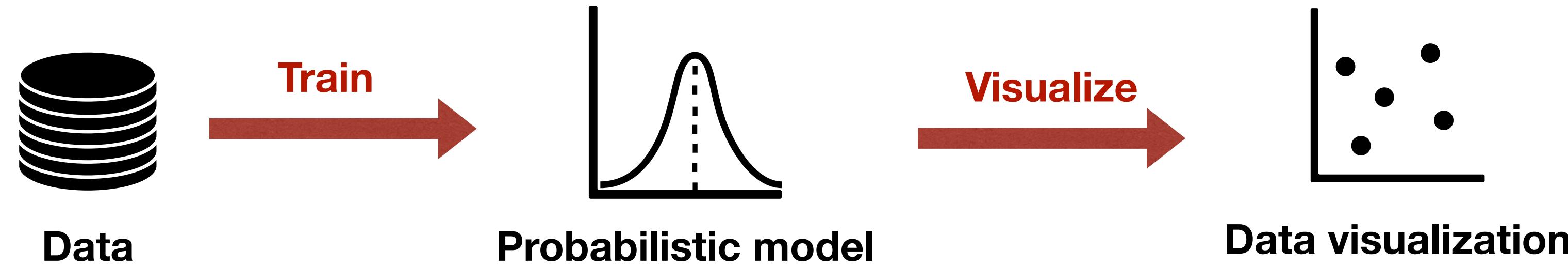
Training phase



Aim during **training phase** : find θ such that $\forall (x, y) \in \mathcal{X} \times \mathcal{Y}, h_\theta(x) \approx y$

Usually in frequentist statistics we use the MLE : **Maximum Likelihood Estimation** $\hat{\theta} = \arg \max_{\theta} P(X | \theta)$

Training phase



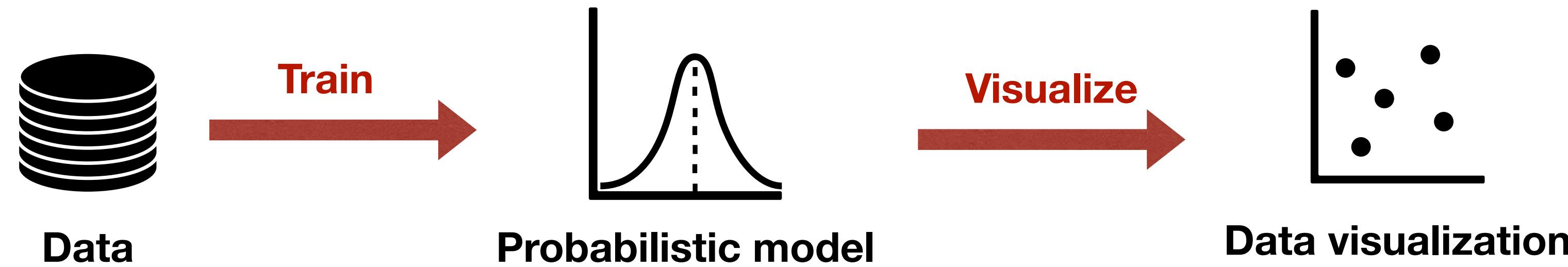
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- Cannot start with a « belief » hence not practical nor flexible
- Cannot express uncertainty of estimated model parameters and predictions

Training phase



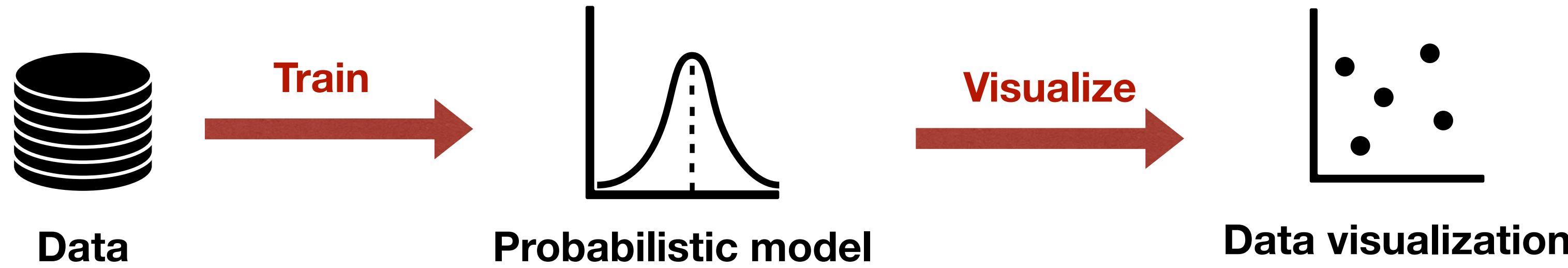
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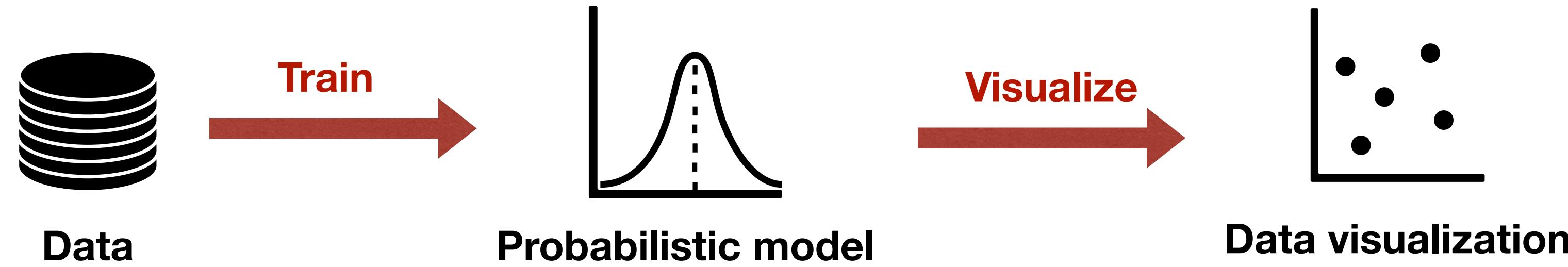
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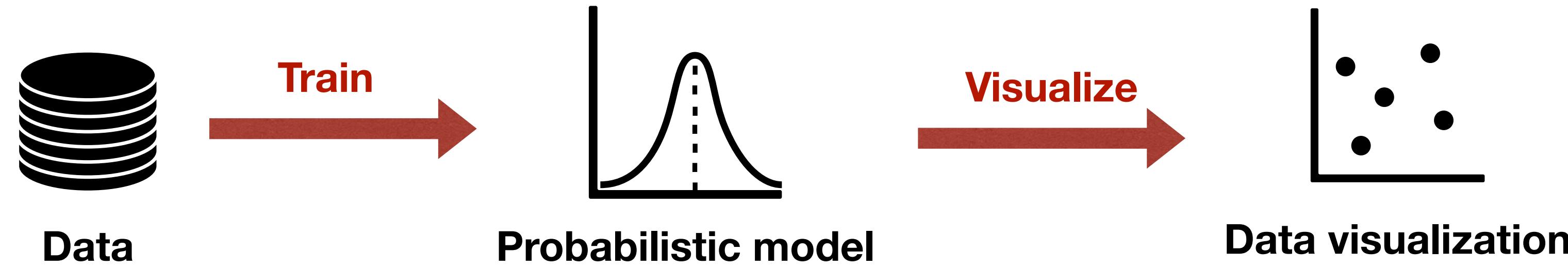
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Bayesian statistics

1

Introduction to bayesian statistics

1. Introduction to bayesian statistics

Probability & statistics : small review

Probability (non axiomatic definition) of an event : relative **frequency** of an event in an infinite trials

1. Introduction to bayesian statistics

Probability & statistics : small review

Probability (non axiomatic definition) of an event : relative **frequency** of an event in an infinite trials

Example : a deck of 52 playing cards

$$P(\text{King of Hearts}) = \frac{1}{52}$$

$$P(\text{Spade}) = \frac{1}{4}$$

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Probability & statistics : small review

Probability (non axiomatic definition) of an event : relative **frequency** of an event in an infinite trials

Random variable

1. Introduction to bayesian statistics

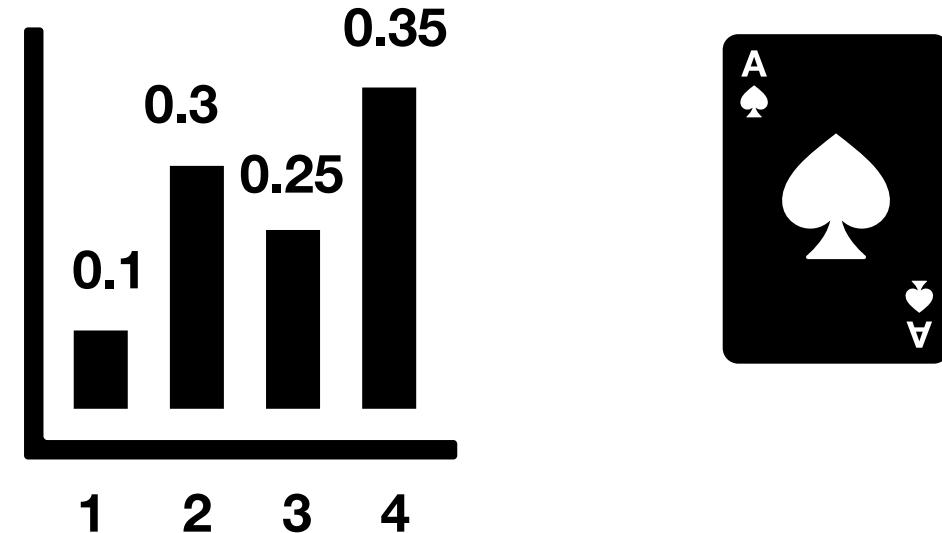
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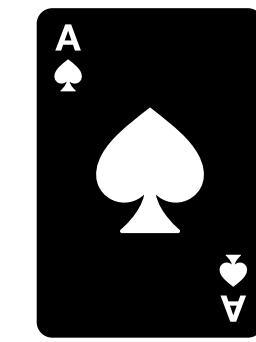
Random variable

- **Discrete** variable Example

Probability Mass Function
(PMF)



$P(X) = \begin{cases} 0.1 & \text{if } X = 1 \\ 0.3 & \text{if } X = 2 \\ 0.25 & \text{if } X = 3 \\ 0.35 & \text{if } X = 4 \end{cases}$



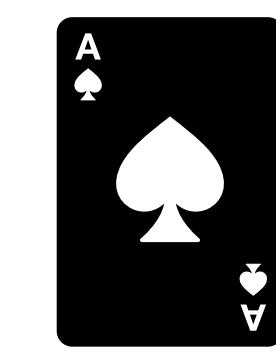
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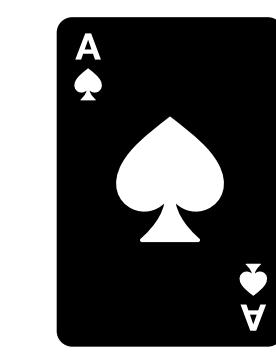
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- **Discrete** variable



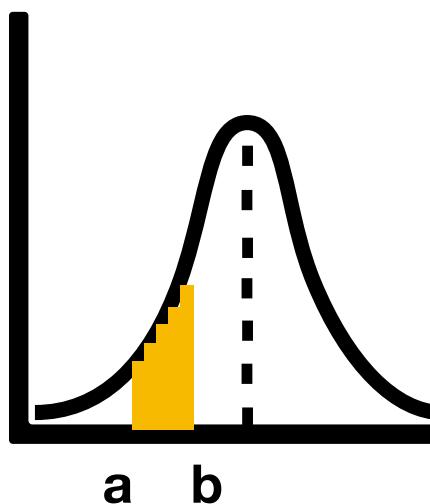
Example



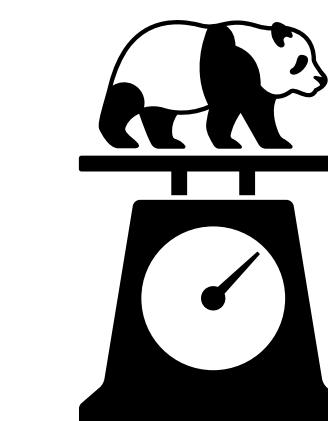
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- **Continuous** variable



Example



Probability Density function
(PDF)

$$P(X \in [a, b]) = \int_a^b p(s)ds$$

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Probability (non axiomatic definition) of an event : relative **frequency** of an event in an infinite trials

Random variable - **Discrete** variable - **Continuous** variable

Independence

1. Introduction to bayesian statistics

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Independence : two random variables X and Y are **independent** if

$$P(X, Y) = P(X)P(Y)$$

joint probability

marginals

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- **Discrete** variable

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Example :

joint probability

marginals

dependency : **one** deck of 52 playing cards

$$P(X_1 = \begin{array}{|c|}\hline \text{A} \\ \hline \text{H} \\ \hline\end{array}, X_2 = \begin{array}{|c|}\hline \text{A} \\ \hline \text{H} \\ \hline\end{array}) = 0$$

$$P(X_1 = \begin{array}{|c|}\hline \text{A} \\ \hline \text{H} \\ \hline\end{array}) \cdot P(X_2 = \begin{array}{|c|}\hline \text{A} \\ \hline \text{H} \\ \hline\end{array}) = \frac{1}{52^2}$$

independency : **two** dices

$$P(X_1 = \begin{array}{|c|c|}\hline \bullet & \bullet \\ \hline \bullet & \bullet \\ \hline\end{array}, X_2 = \begin{array}{|c|c|}\hline \bullet & \bullet \\ \hline \bullet & \bullet \\ \hline\end{array}) = \frac{1}{6^2}$$

$$P(X_1 = \begin{array}{|c|c|}\hline \bullet & \bullet \\ \hline \bullet & \bullet \\ \hline\end{array}) \cdot P(X_2 = \begin{array}{|c|c|}\hline \bullet & \bullet \\ \hline \bullet & \bullet \\ \hline\end{array}) = \frac{1}{6} \times \frac{1}{6} = \frac{1}{6^2}$$

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Conditional probability

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Conditional probability : probability of X **given that Y happened**

conditional

$$P(X | Y) = \frac{P(X, Y)}{P(Y)}$$

joint probability
marginal

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$$P(\begin{array}{|c|}\hline \text{A} \\ \hline \text{H} \\ \hline\end{array} | \begin{array}{|c|}\hline \text{A} \\ \hline \text{C} \\ \hline\end{array}) = \frac{P(\begin{array}{|c|}\hline \text{A} \\ \hline \text{H} \\ \hline\end{array}, \begin{array}{|c|}\hline \text{A} \\ \hline \text{C} \\ \hline\end{array})}{P(\begin{array}{|c|}\hline \text{A} \\ \hline \text{C} \\ \hline\end{array})}$$

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Rules :

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Chain rule $P(X_1, X_2) = P(X_1 | X_2) \times P(X_2)$

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Chain rule $P(X_1, X_2, X_3) = P(X_1 | X_2, X_3) \times P(X_2 | X_3) \times P(X_3)$

1. Introduction to bayesian statistics

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Sum rule $P(X) = \sum_{Y \in \mathcal{Y}} P(X, Y) \quad P(X) = \int_{Y \in \mathcal{Y}} P(X, Y) \cdot dY$

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Bayes theorem :

1. Introduction to bayesian statistics

Probability & statistics : small review

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Bayes theorem :

θ Parameters

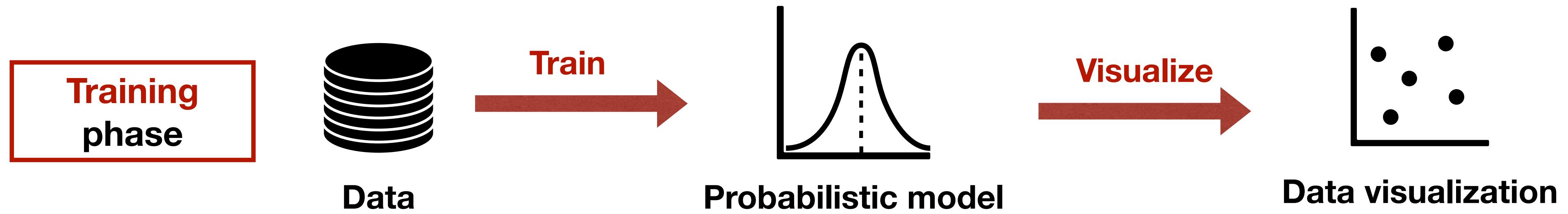
X Observations (data)

	Likelihood	Prior
Posterior	$P(X, \theta)$	$P(\theta) \times P(X)$
	Evidence	

$$P(\theta | X) = \frac{P(X, \theta)}{P(X)} = \frac{P(X | \theta) \times P(\theta)}{P(X)}$$

1. Introduction to bayesian statistics

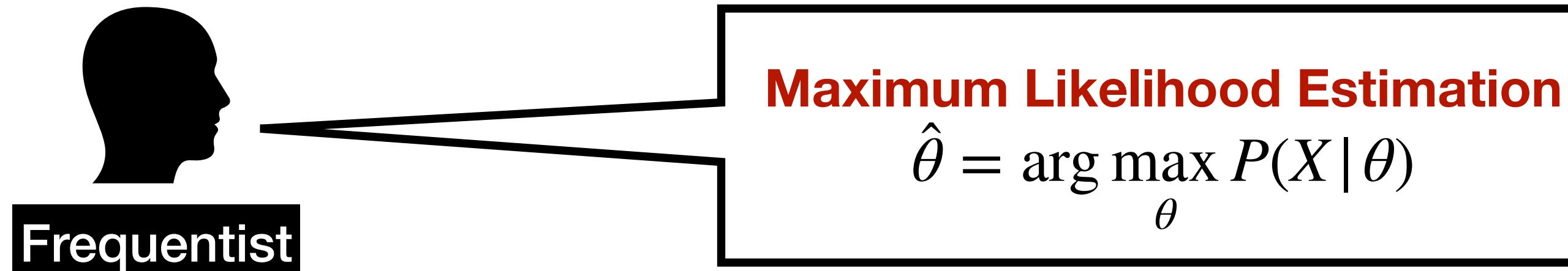
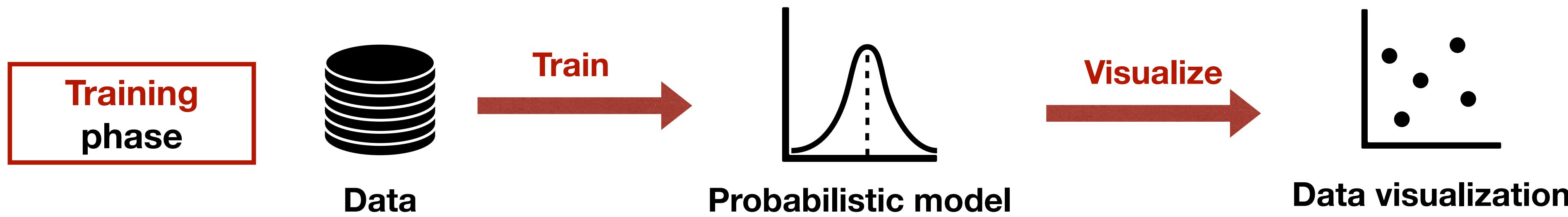
Frequentist VS Bayesian point of view



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1. Introduction to bayesian statistics

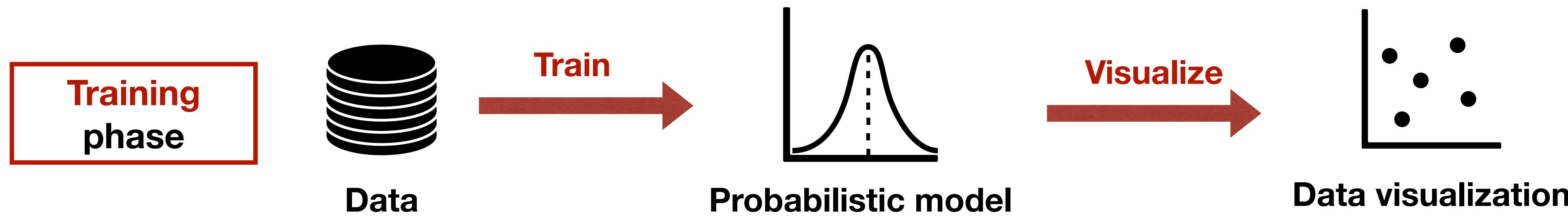
Frequentist VS Bayesian point of view



θ is fixed
 X is random

1. Introduction to bayesian statistics

Frequentist VS Bayesian point of view



Frequentist

Maximum Likelihood Estimation

$$\hat{\theta} = \arg \max_{\theta} P(X | \theta)$$

θ is fixed
 X is random

Bayes theorem

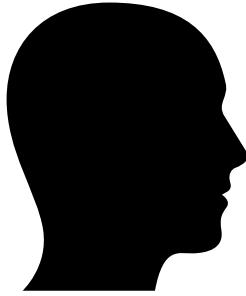
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Bayesian

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1. Introduction to bayesian statistics

Frequentist VS Bayesian point of view



Frequentist

Maximum Likelihood Estimation

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Bayesian

Bayes theorem

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1. Introduction to bayesian statistics

Frequentist VS Bayesian point of view



Frequentist

Maximum Likelihood Estimation

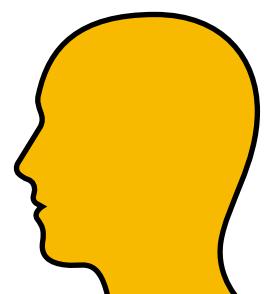
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Bayes theorem

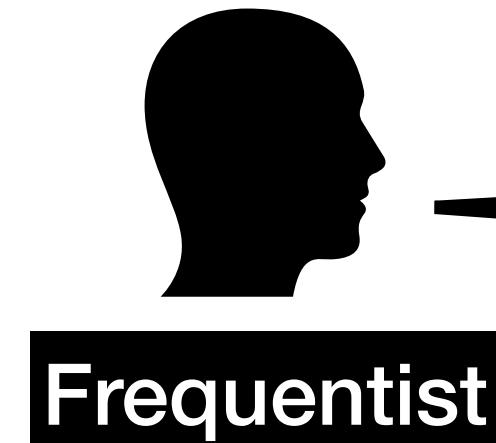
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Bayesian

1. Introduction to bayesian statistics

Frequentist VS Bayesian point of view

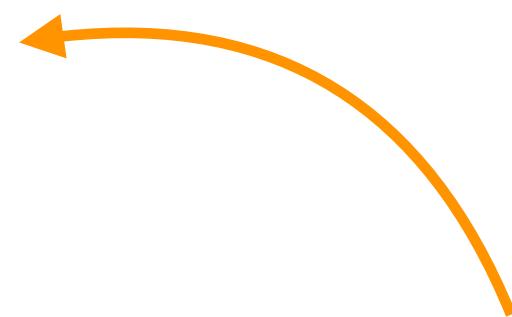


Maximum Likelihood Estimation

$$\hat{\theta} = \arg \max_{\theta} P(X | \theta)$$

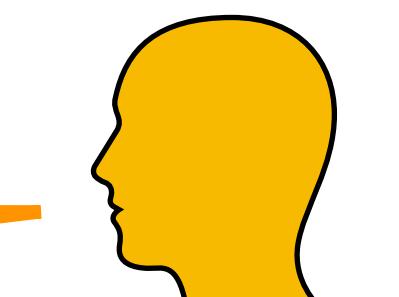
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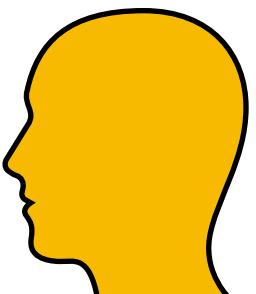
Bayesian

1. Introduction to bayesian statistics

Bayesian point of view : classification

Bayes theorem

$$P(\theta | X) = \frac{P(X | \theta) \times P(\theta)}{P(X)}$$



Bayesian

Training
phase

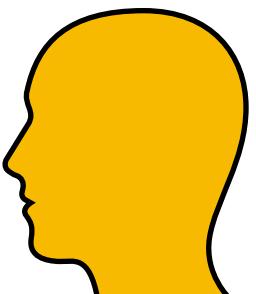
$$P(\theta | X_{train}, y_{train}) = \frac{P(y_{train} | X_{train}, \theta) \times P(\theta)}{P(y_{train} | X_{train})}$$

1. Introduction to bayesian statistics

Bayesian point of view : training

Bayes theorem

$$P(\theta | X) = \frac{P(X | \theta) \times P(\theta)}{P(X)}$$



Bayesian

Training
phase

$$P(\theta | X_{train}, y_{train}) = \frac{P(y_{train} | X_{train}, \theta) \times P(\theta)}{P(y_{train} | X_{train})}$$

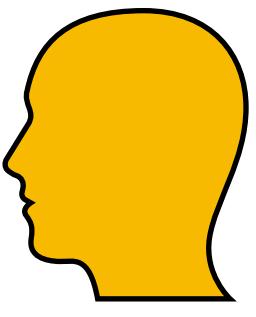
Can regularize your model when training on your data

1. Introduction to bayesian statistics

Bayesian point of view : inference

Bayes theorem

$$P(\theta | X) = \frac{P(X | \theta) \times P(\theta)}{P(X)}$$



Bayesian

Training phase

$$P(\theta | X_{train}, y_{train}) = \frac{P(y_{train} | X_{train}, \theta) \times P(\theta)}{P(y_{train} | X_{train})}$$

Can regularize your model when training on your data

Inference phase

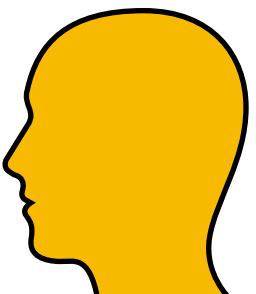
$$P(y_{new} | X_{new}, X_{train}, y_{train}) = \int P(y_{new} | X_{train}, \theta) \times P(\theta | X_{train}, y_{train}) d\theta$$

1. Introduction to bayesian statistics

Bayesian point of view : online learning

Bayes theorem

$$P(\theta | X) = \frac{P(X | \theta) \times P(\theta)}{P(X)}$$



Bayesian

Training phase

$$P(\theta | X_{train}, y_{train}) = \frac{P(y_{train} | X_{train}, \theta) \times P(\theta)}{P(y_{train} | X_{train})}$$

Can regularize your model when training on your data

Inference phase

$$P(y_{new} | X_{new}, X_{train}, y_{train}) = \int P(y_{new} | X_{train}, \theta) \times P(\theta | X_{train}, y_{train}) d\theta$$

Online learning

$$P_{new}(\theta) = P(\theta | x_{new}) = \frac{P(x_{new} | \theta) \times P_{old}(\theta)}{P(x_{new})}$$

New prior

Posterior



2

Probabilistic models

2. Probabilistic model

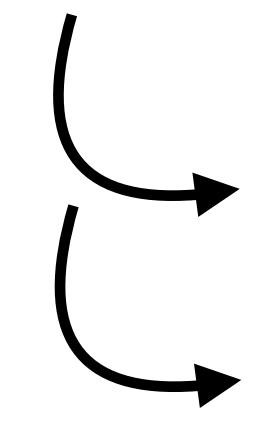
Probabilistic Graphical Model (PGM)

Probabilistic graphical models : analysis using **diagrammatic representations** of probability distributions

2. Probabilistic model

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Probabilistic graphical models : analysis using **diagrammatic representations** of probability distributions

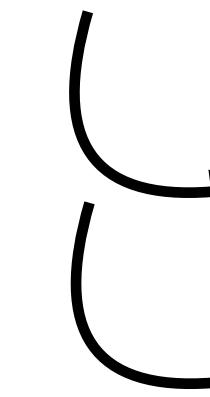
- 
- **Nodes** : random variables
 - **Links** : probabilistic relationships

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Probabilistic graphical models : analysis using **diagrammatic representations** of probability distributions

Bayesian networks
(Directed graphical models)



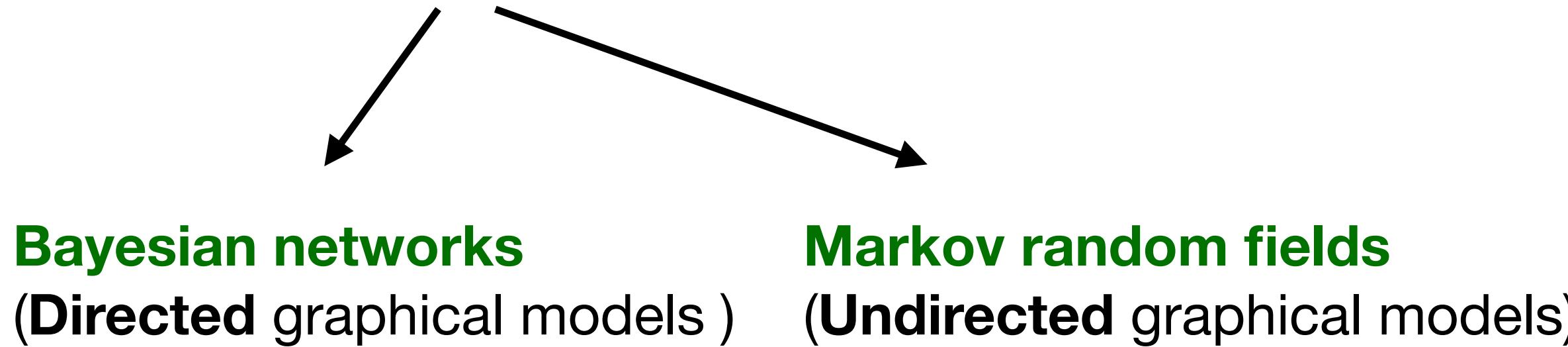
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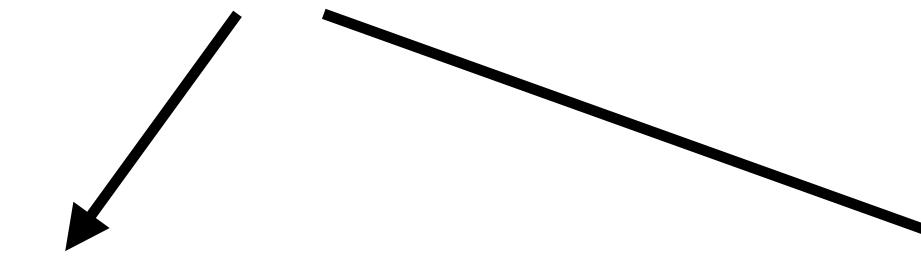
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Bayesian networks
(Directed graphical models)

Markov random fields
(Undirected graphical models)

The focus of our course !



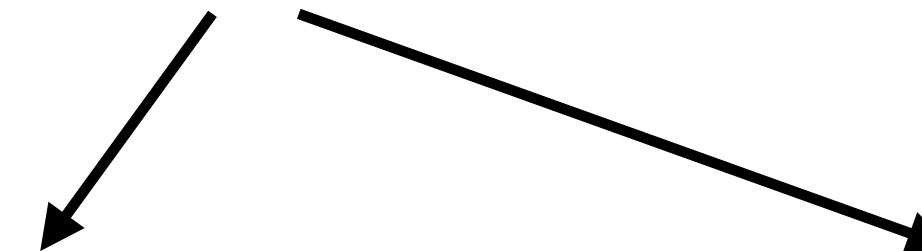
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Model : joint probability over all variables

$$P(X_1, \dots, X_N) = \dots$$

- **Nodes** : random variables
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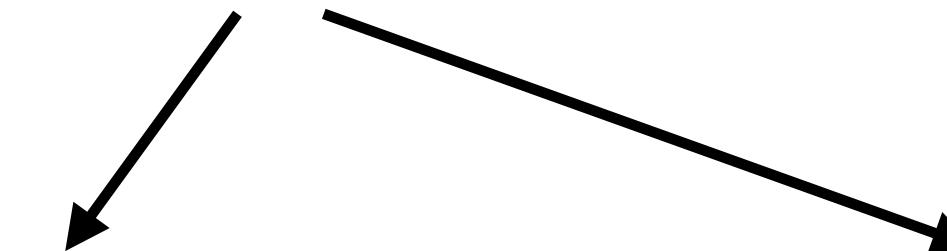
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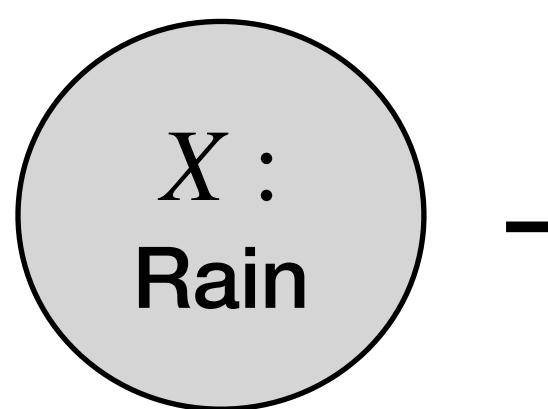
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Example :



$$P(X, Y) = \dots$$

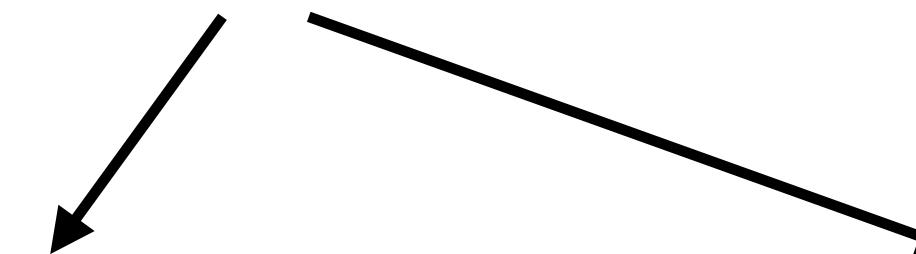
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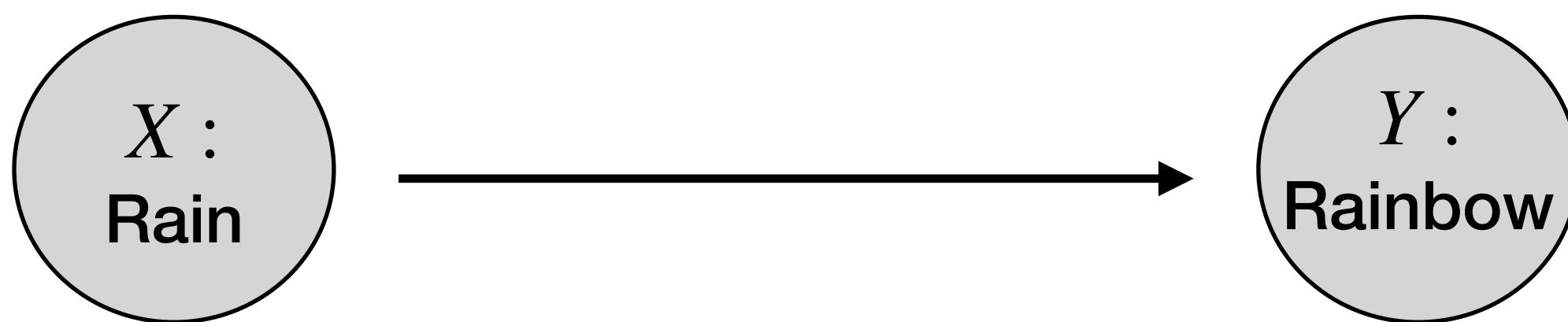
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Model : joint probability over all variables

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Example :



- **Nodes** : random variables
- **Links** : probabilistic relationships

$$P(X, Y) = P(Y|X) \times P(X)$$

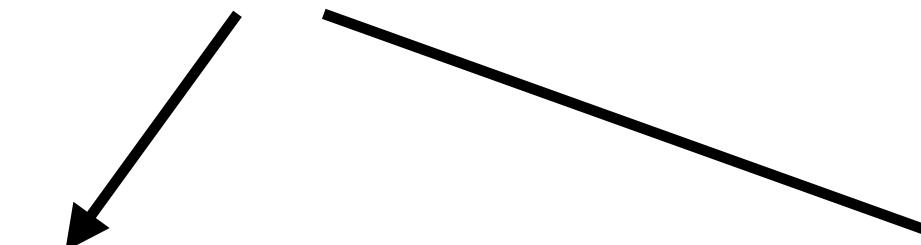
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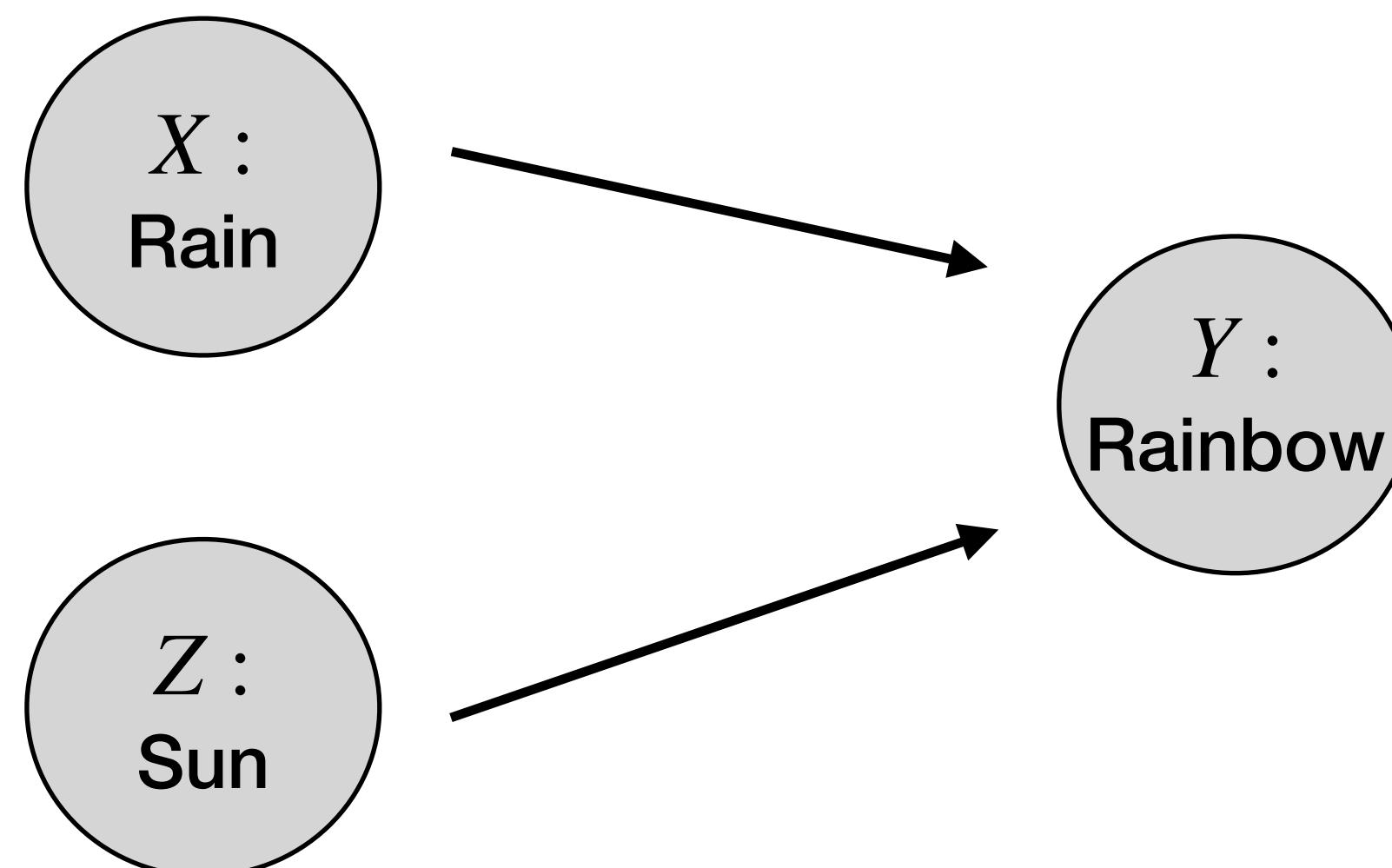
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Example :



$$P(X, Y, Z) = \dots$$

Features

X, Z conditionally
independent given Y

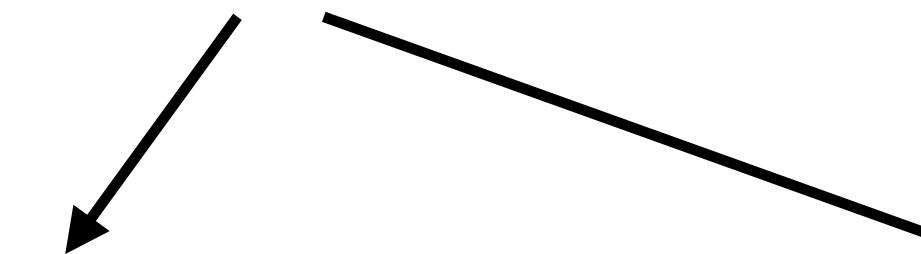
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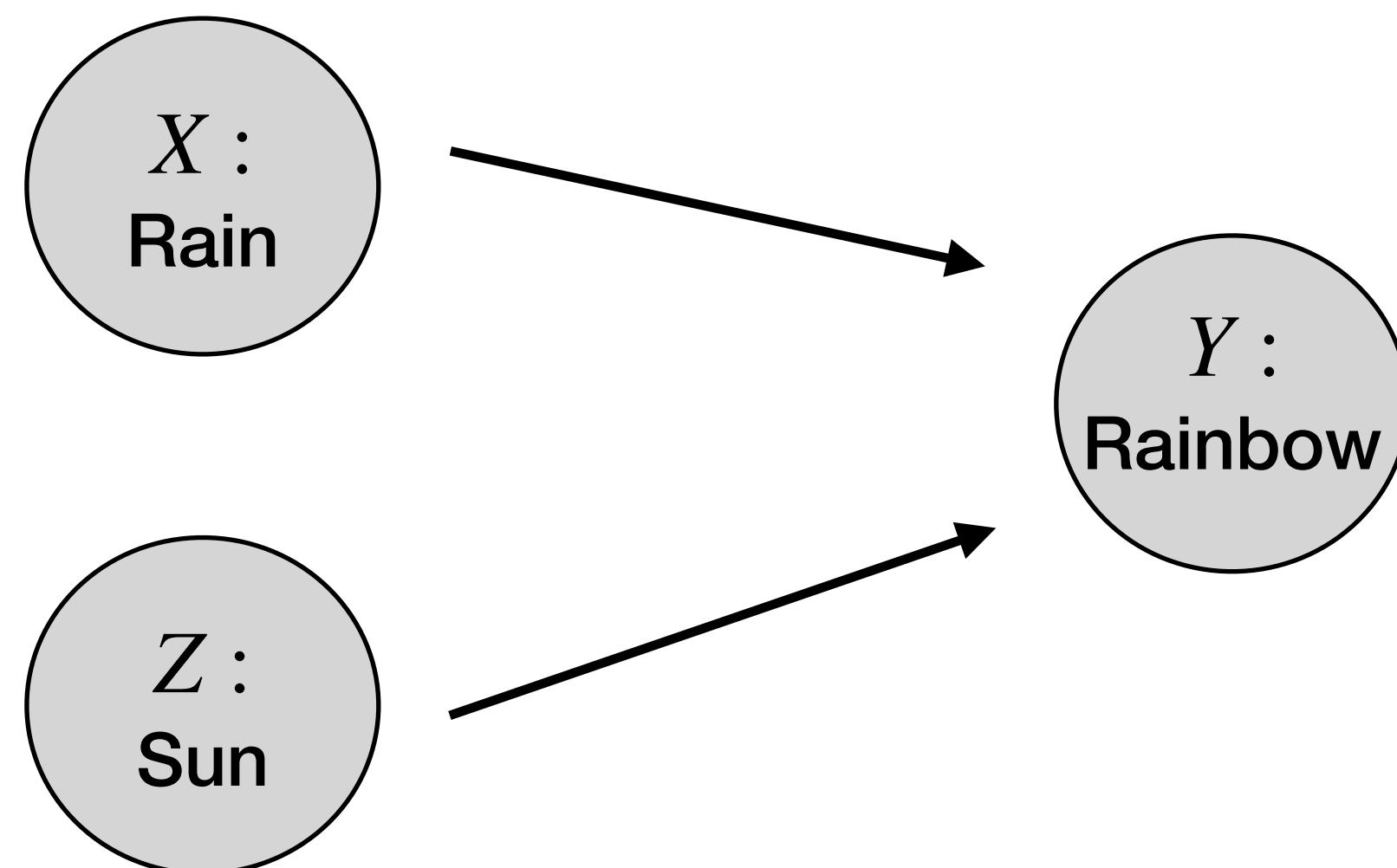
(Undirected graphical models)

The focus of our course !

Model : joint probability over all variables

$$P(X_1, \dots, X_N) = \dots$$

Example :



$$\begin{aligned} P(X, Y, Z) &= P(Y|X, Z) \times P(X, Z) \\ &= P(Y|X, Z) \times P(X) \times P(Z) \end{aligned}$$

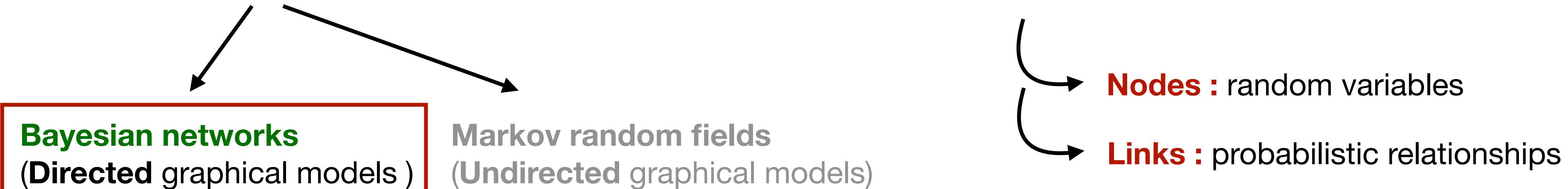
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X , Z conditionally
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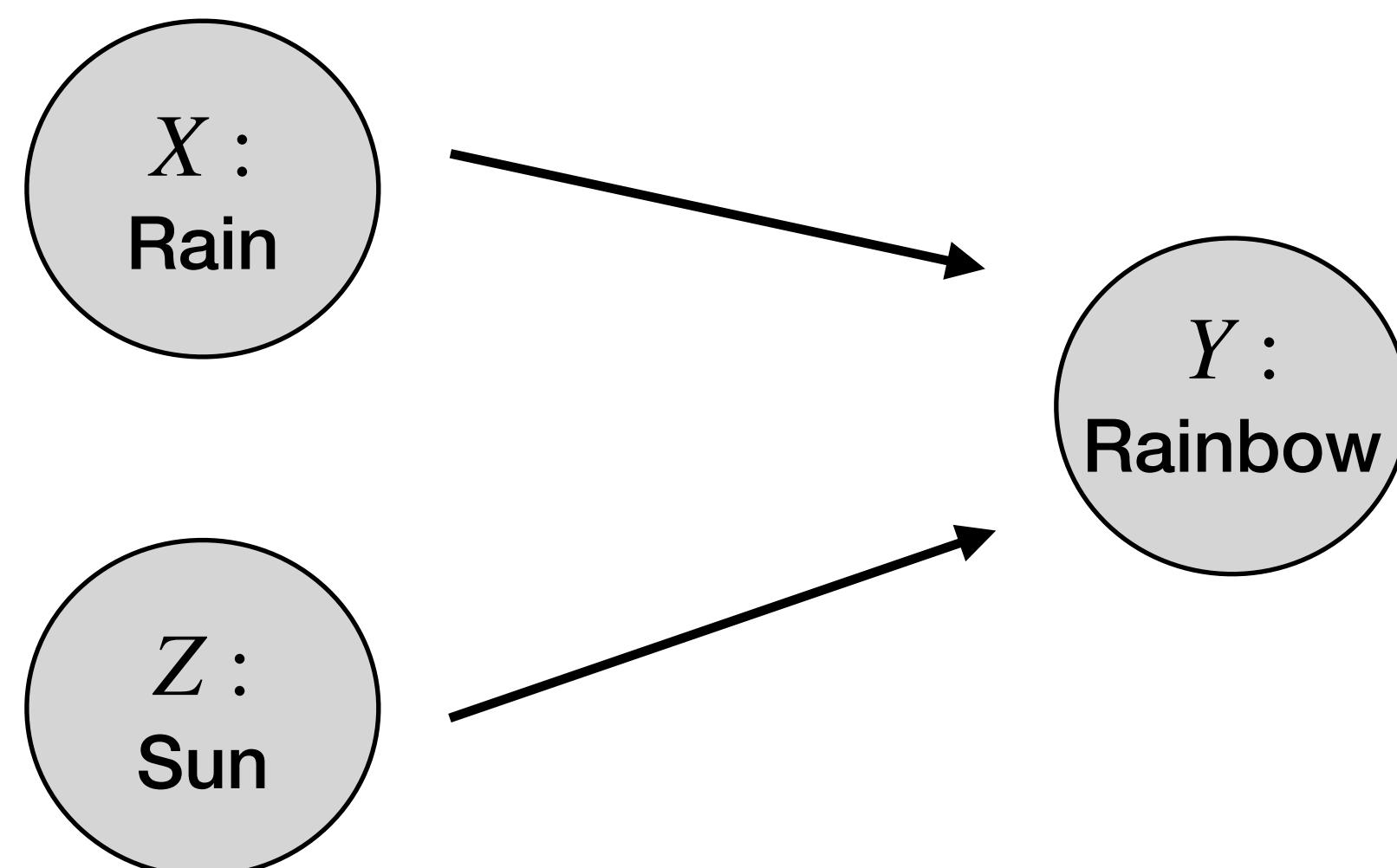


The focus of our course !

Model : joint probability over all variables

$$P(X_1, \dots, X_N) = \prod_{i=1, \dots, N} P(X_i \mid \text{parents}(X_i))$$

Example :



Features
X , Z conditionally
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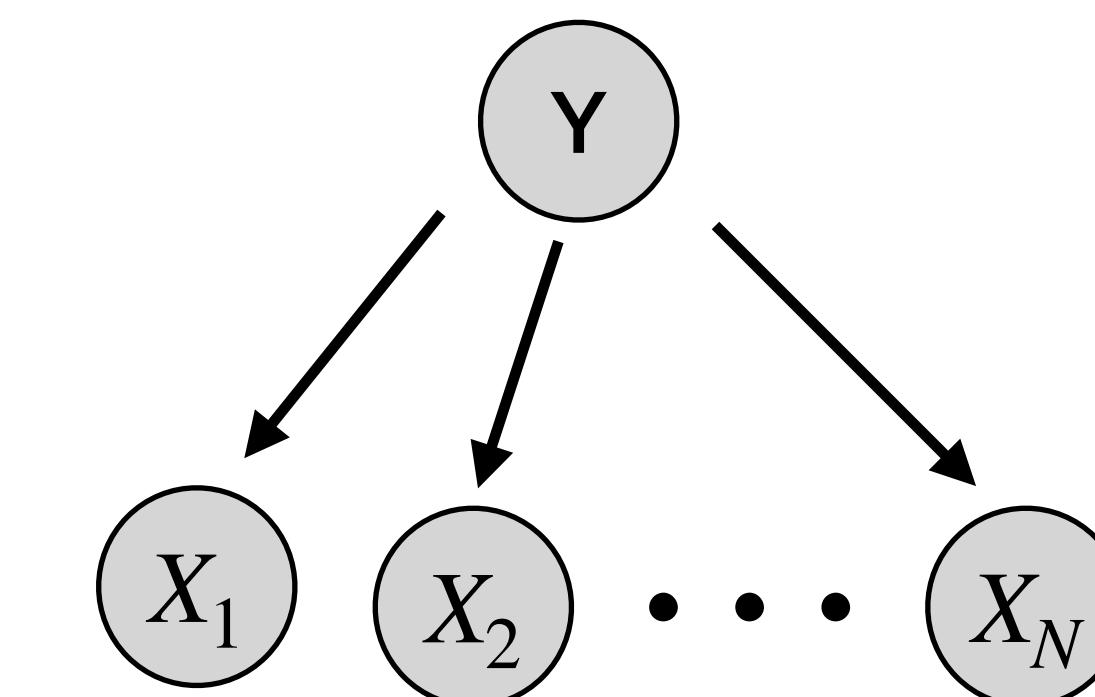
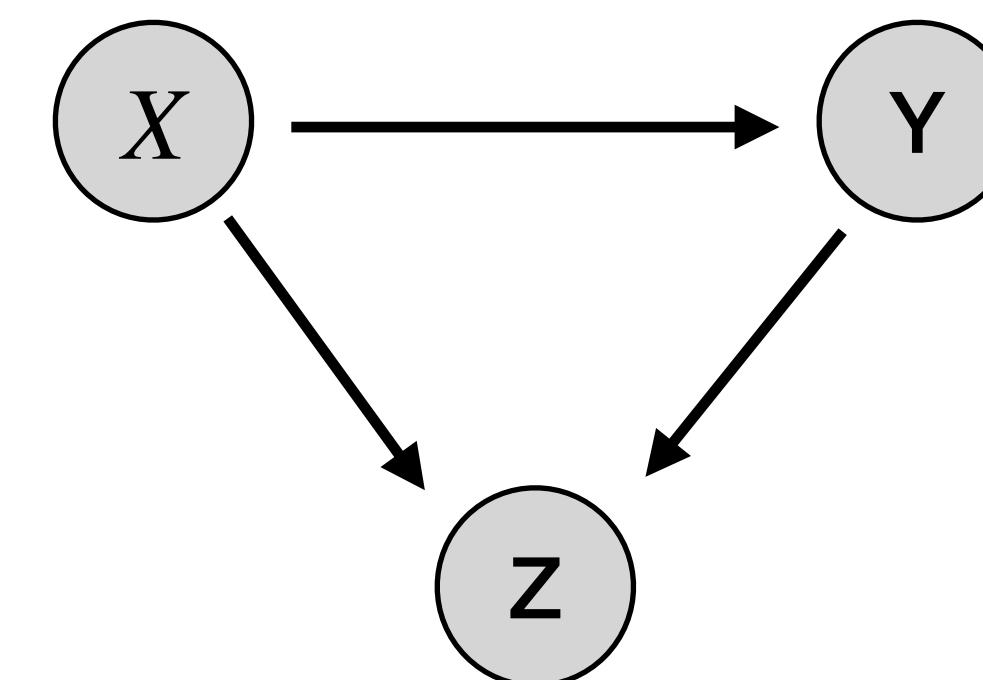
Markov random fields
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$$P(X, Y, Z) = \dots$$

$$P(Y, X_1, \dots, X_N) =$$

2. Probabilistic model

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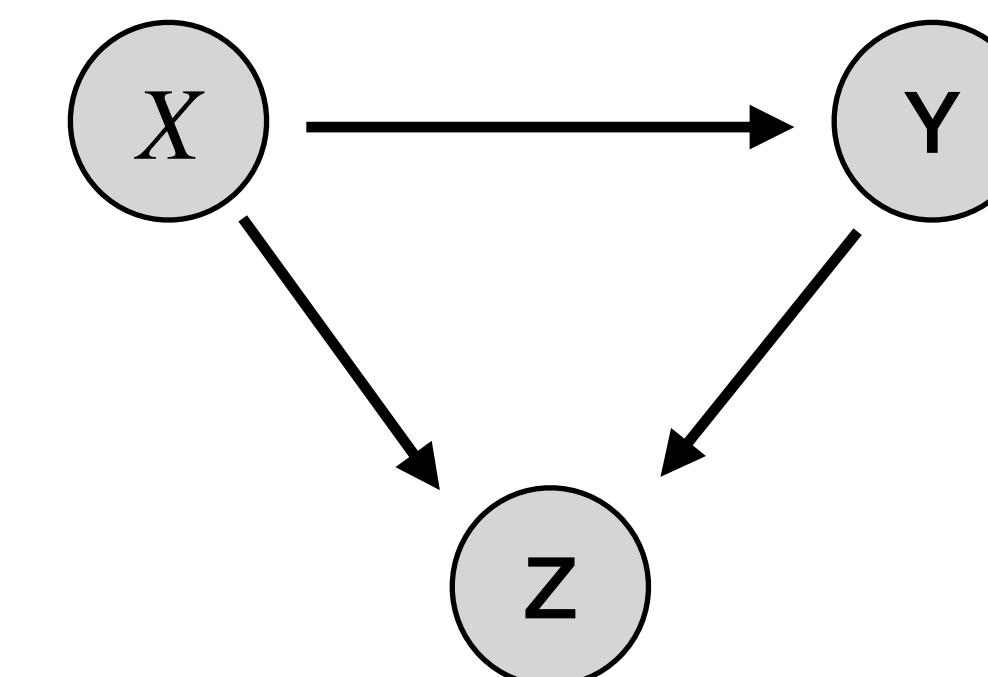
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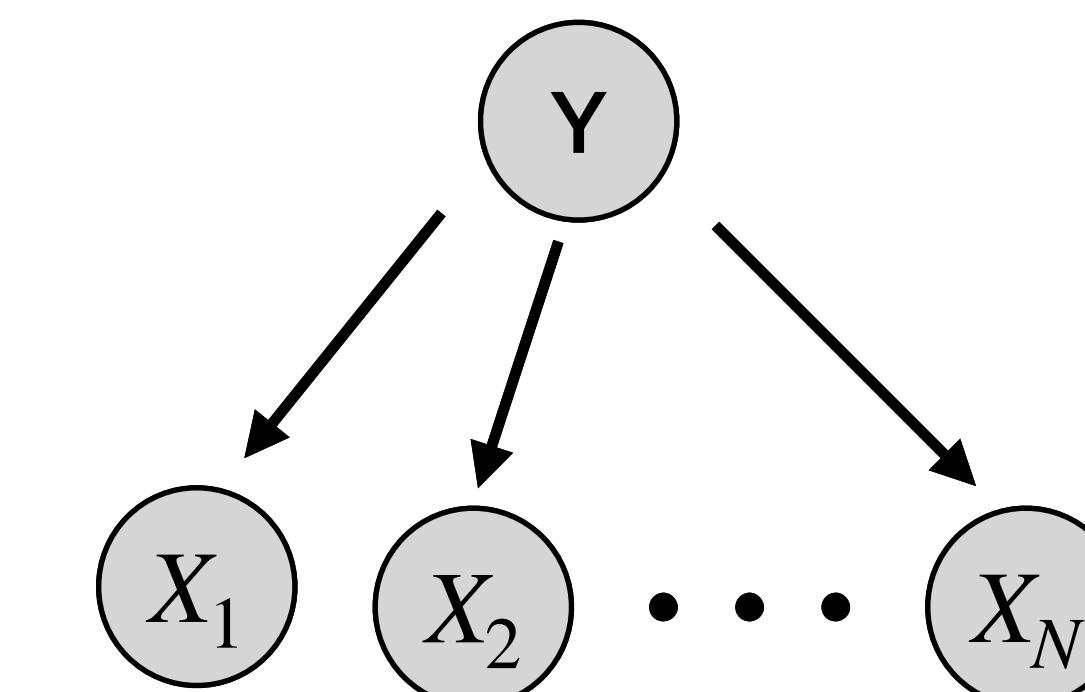


$$P(X, Y) = P(Y|X) \times P(X)$$



$$P(X, Y, Z) = P(Z|X, Y) \times P(X, Y)$$

$$= P(Z|X, Y) \times P(Y|X) \times P(X)$$



$$P(Y, X_1, \dots, X_N) = P(Y) \prod_{i=1, \dots, N} P(X_i | Y)$$

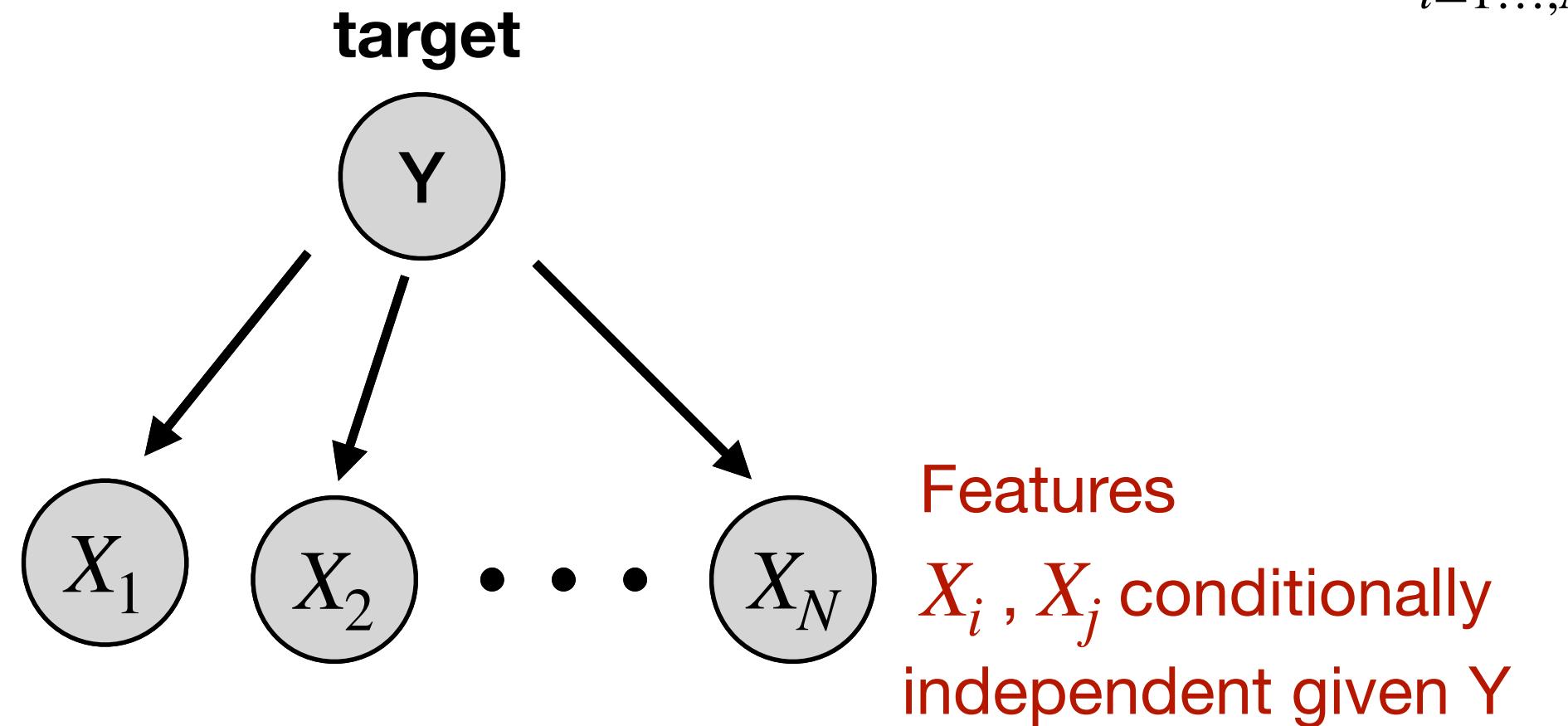
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2. Probabilistic model

Plates and examples of probabilistic model

Naive Bayes Classifier

$$P(Y, X_1, \dots, X_N) = P(Y) \prod_{i=1\dots,N} P(X_i | Y)$$

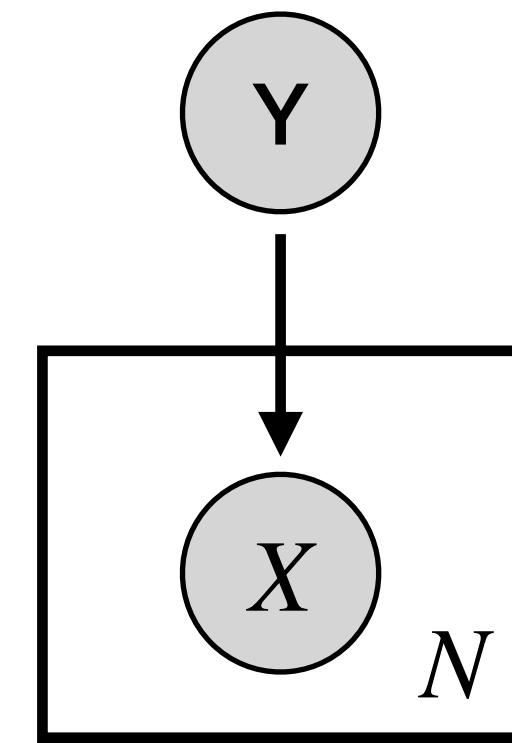
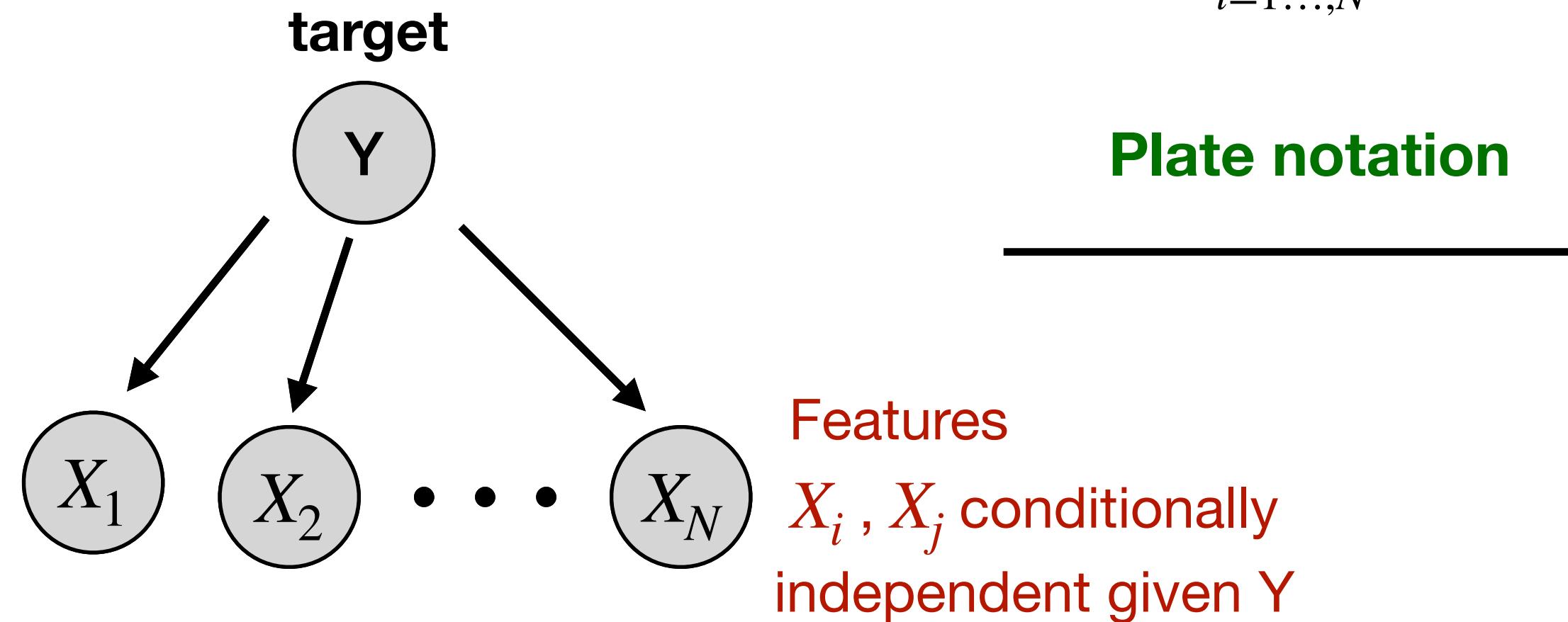


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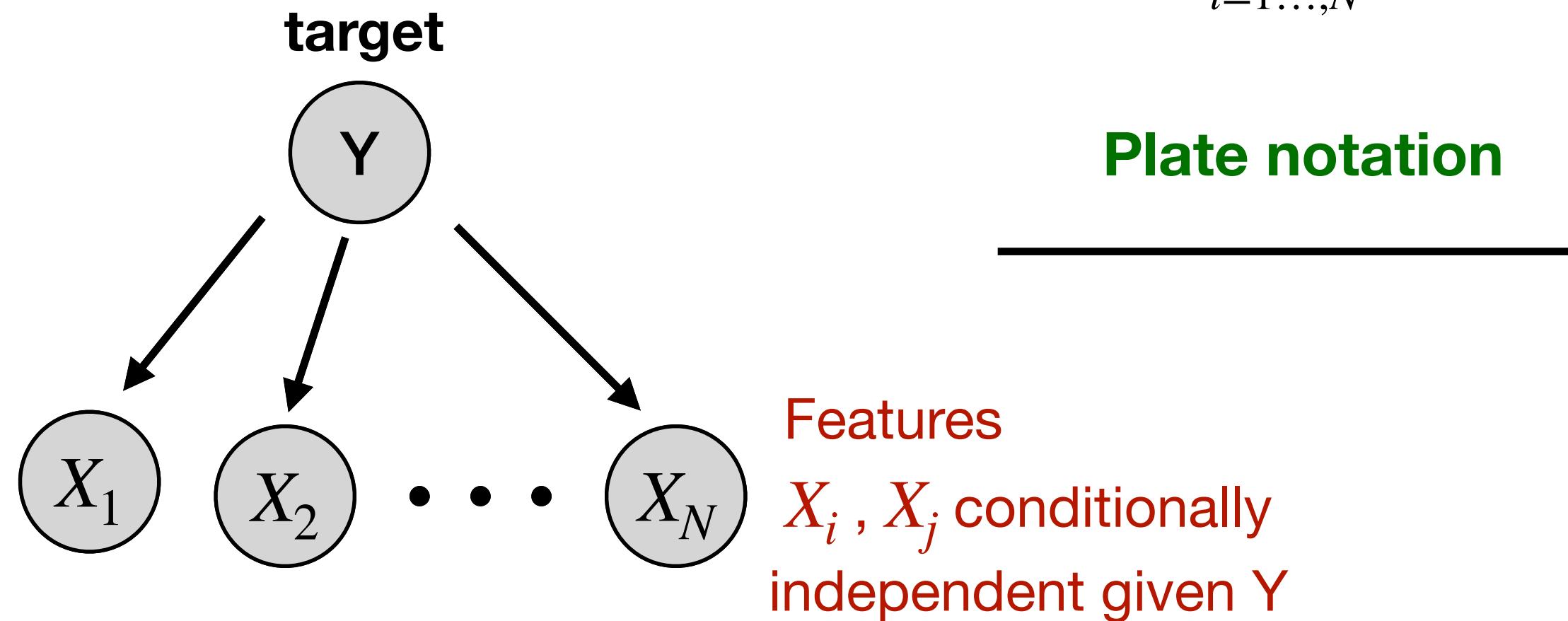


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$$P(Y, X_1, \dots, X_N) = P(Y) \prod_{i=1 \dots, N} P(X_i | Y)$$



Reminder : Frequentist linear regression $x_i \in \mathbb{R}^d$ $y_1 \in \mathbb{R}$

Scalar notation :

$$D = \{(x_1, y_1), \dots, (x_n, y_n)\}$$

$$y_i = x_i^T \theta + \epsilon_i$$

Matrix notation :

$$\mathbf{X} = (x_1, \dots, x_n) \text{ and } \mathbf{y} = (y_1, \dots, y_n)$$

$$y = \mathbf{X}^T \theta + \epsilon$$

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Plates and examples of probabilistic model

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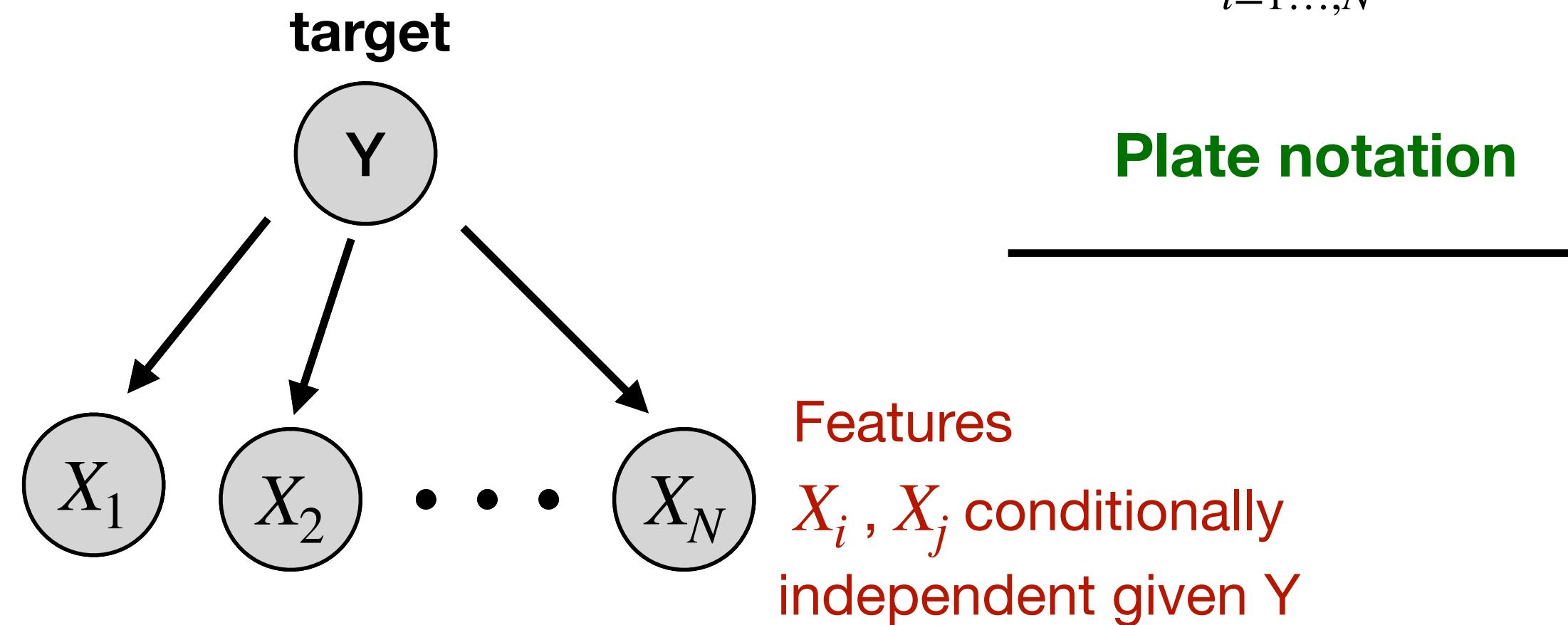
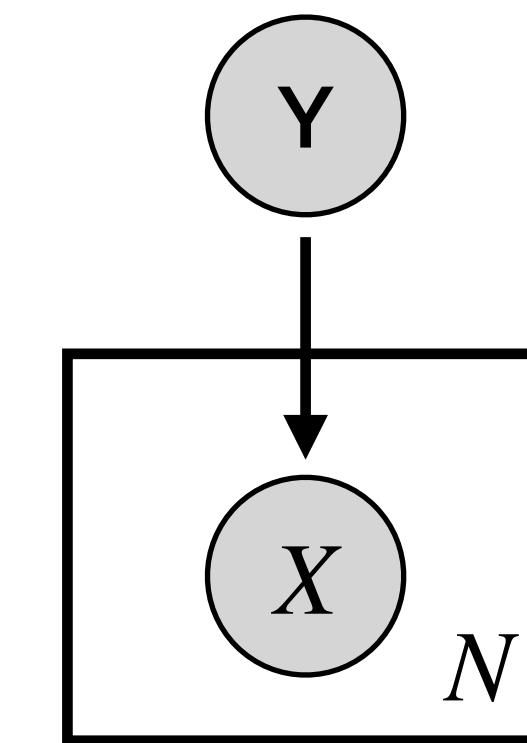


Plate notation



Reminder : Frequentist linear regression

$$x_i \in \mathbb{R}^d \quad y_i \in \mathbb{R}$$

Scalar notation :

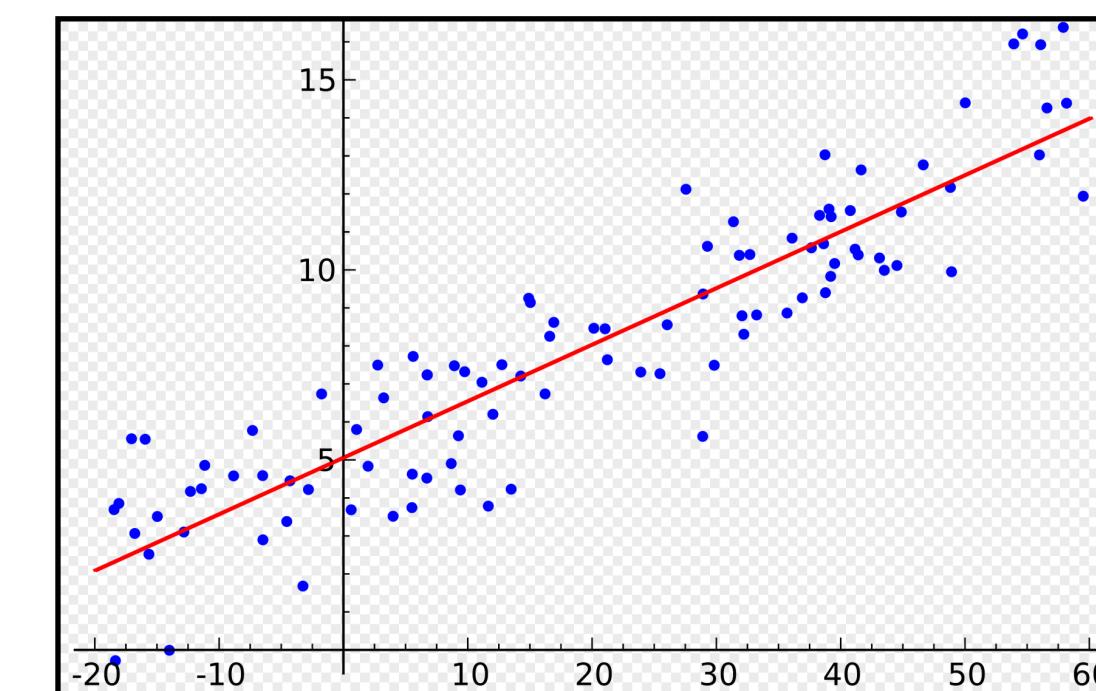
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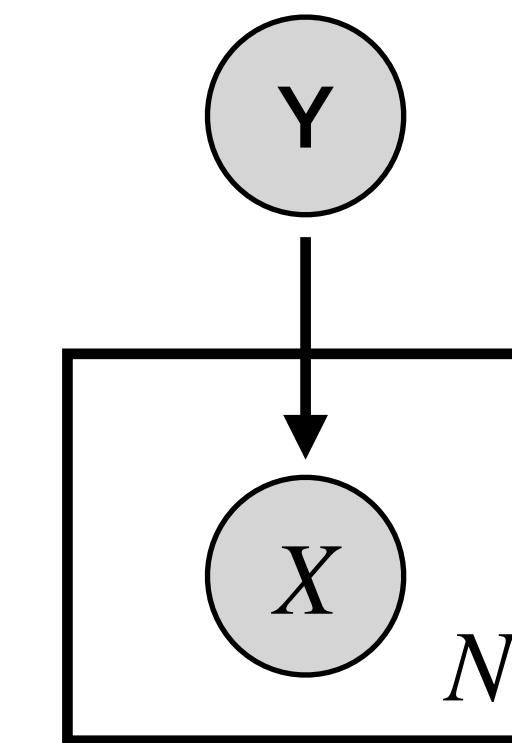
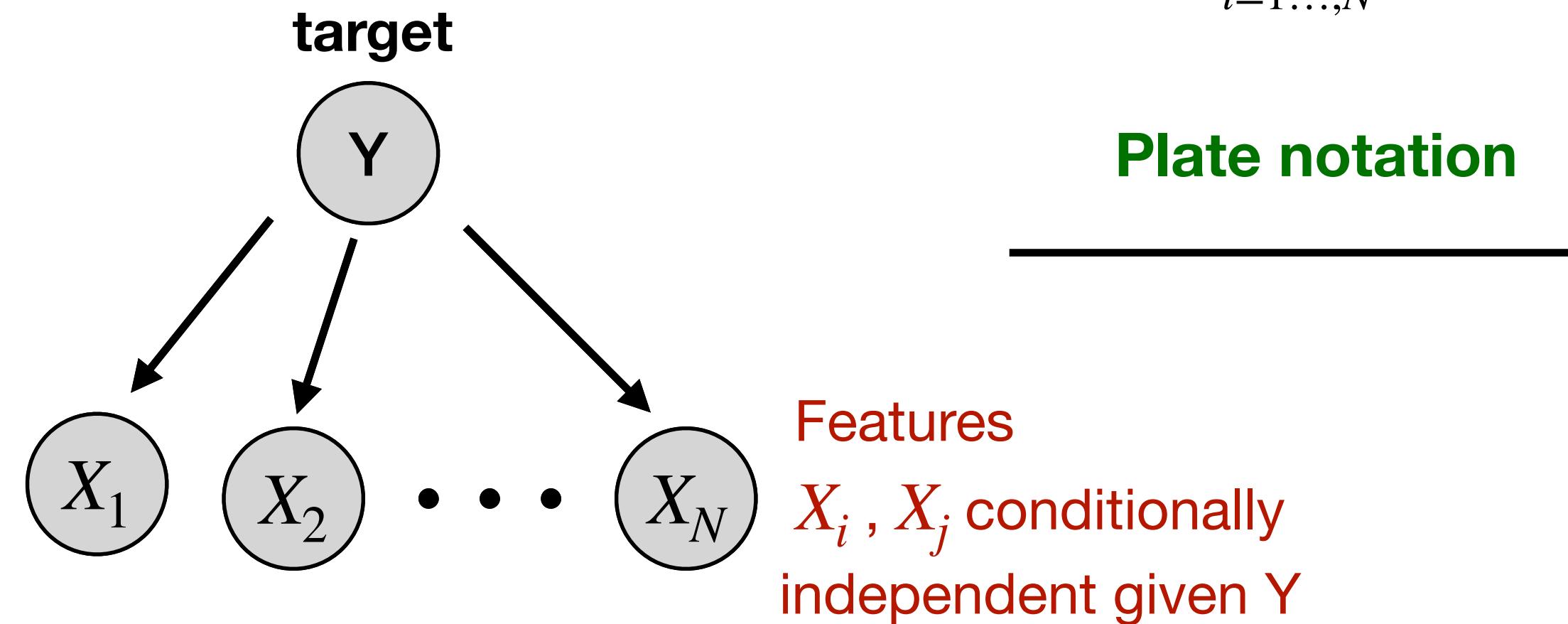
$$\min_{\theta} \|\theta^T \mathbf{X} - \mathbf{y}\|^2$$

2. Probabilistic model

Plates and examples of probabilistic model

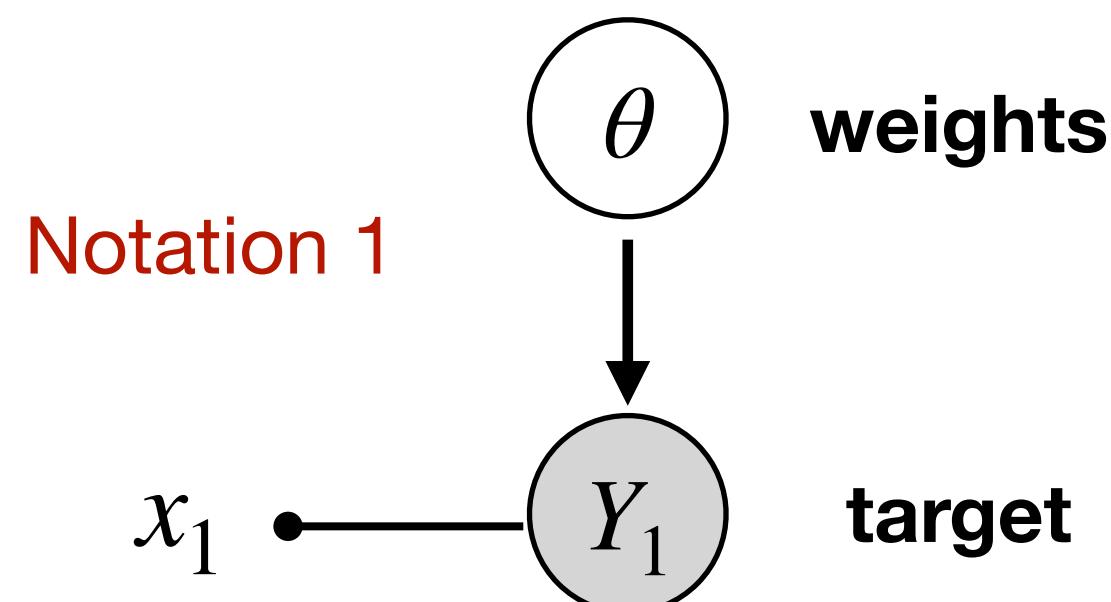
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$$P(Y, X_1, \dots, X_N) = P(Y) \prod_{i=1\dots,N} P(X_i | Y)$$



Bayesian Linear regression

$$(x_1, y_1) \text{ with } x_1 \in \mathbb{R}^d, y_1 \in \mathbb{R}$$



$$\begin{aligned} P(\theta, y_1 | x_1) &= P(y_1 | \theta, x_1) \times P(\theta) \\ P(y_1 | \theta, x_1) &= \dots \\ P(\theta) &= \dots \end{aligned}$$

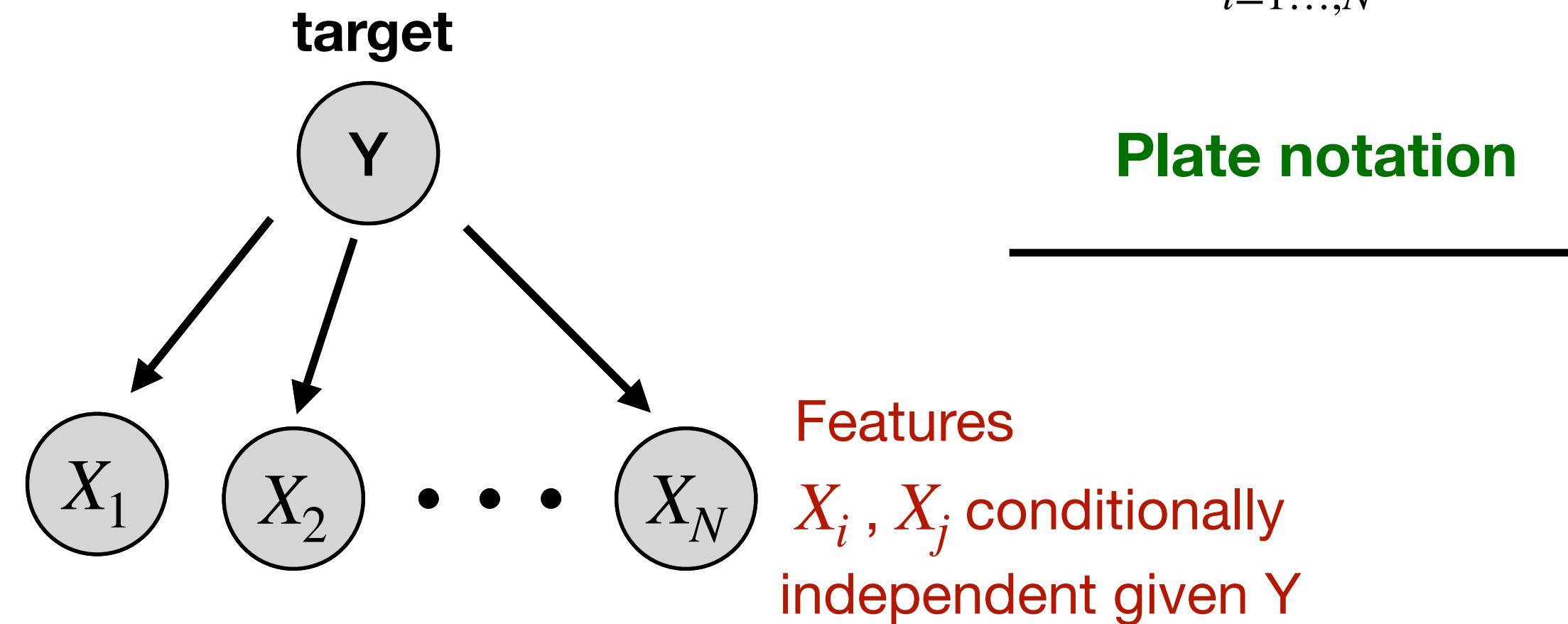


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Plates and examples of probabilistic model

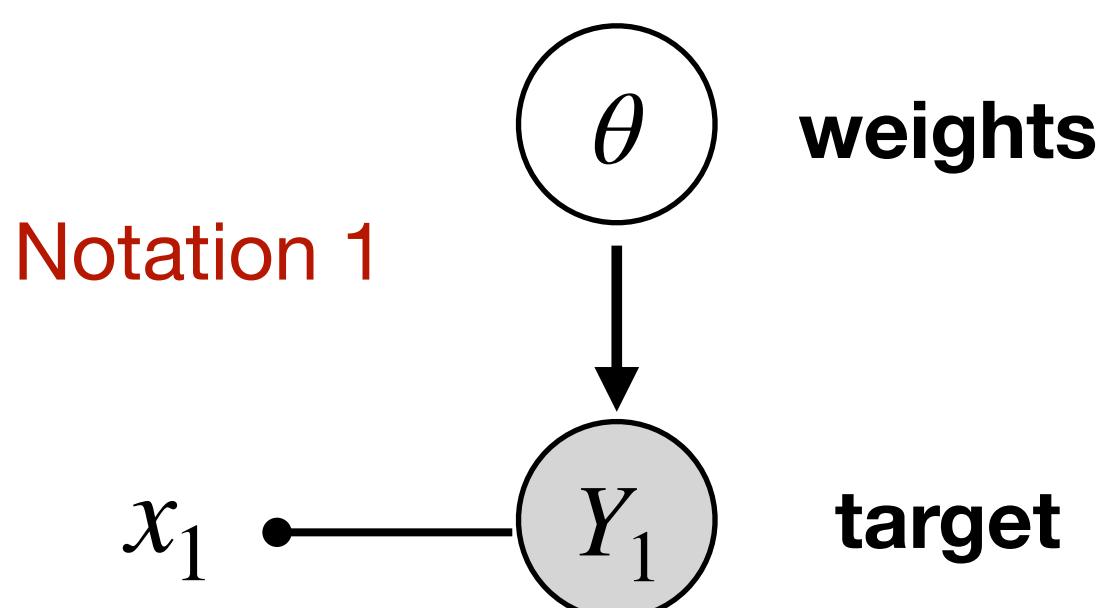
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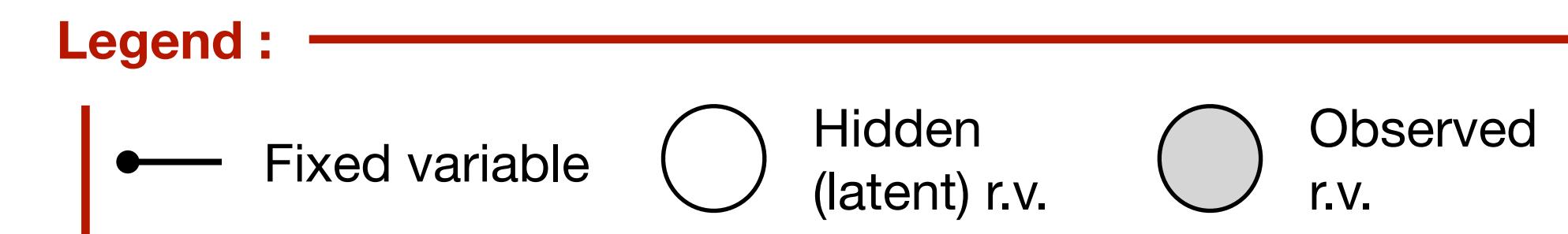


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$$(x_1, y_1) \text{ with } x_1 \in \mathbb{R}^d, y_1 \in \mathbb{R}$$



$$\begin{aligned} P(\theta, y_1 | x_1) &= P(y_1 | \theta, x_1) \times P(\theta) \\ P(y_1 | \theta, x_1) &= \mathcal{N}(y_1 | \theta^T x_1, \sigma^2) \\ P(\theta) &= \mathcal{N}(\theta | 0, \gamma^2) \end{aligned}$$

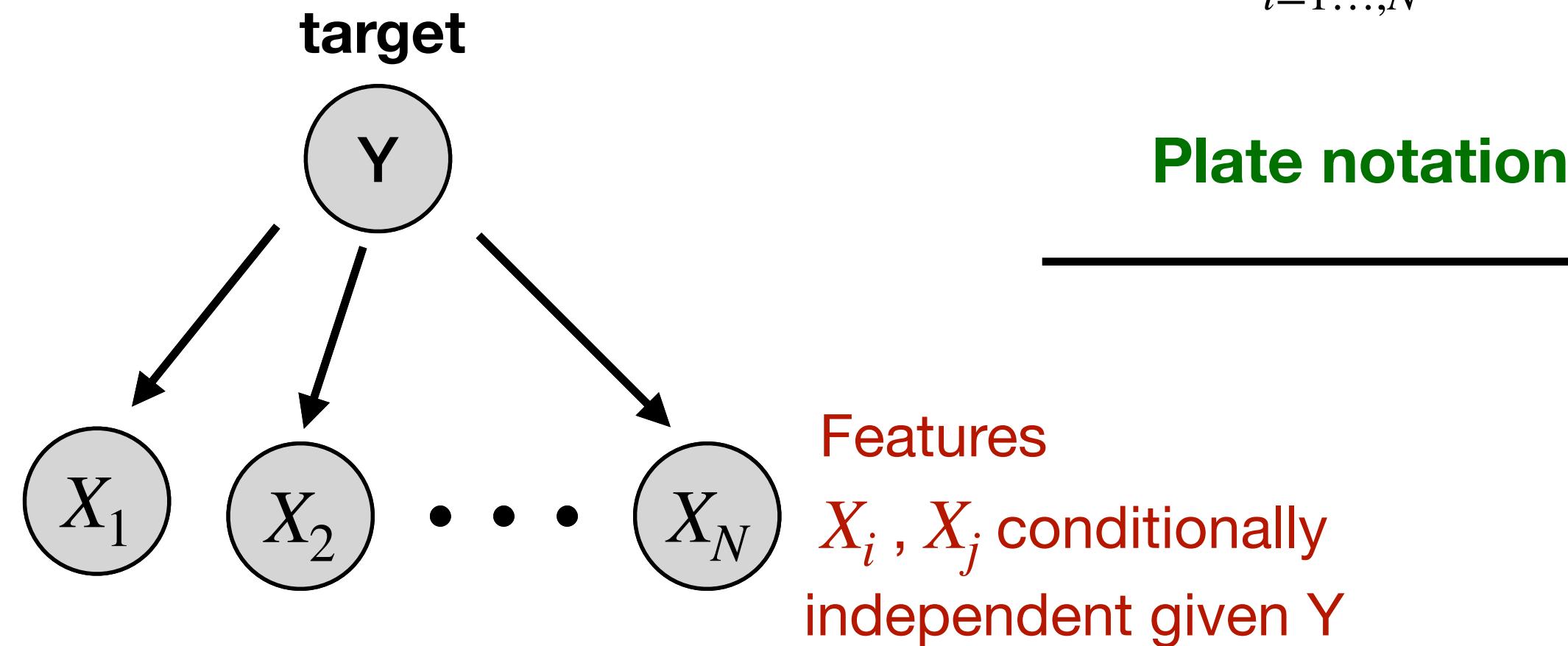


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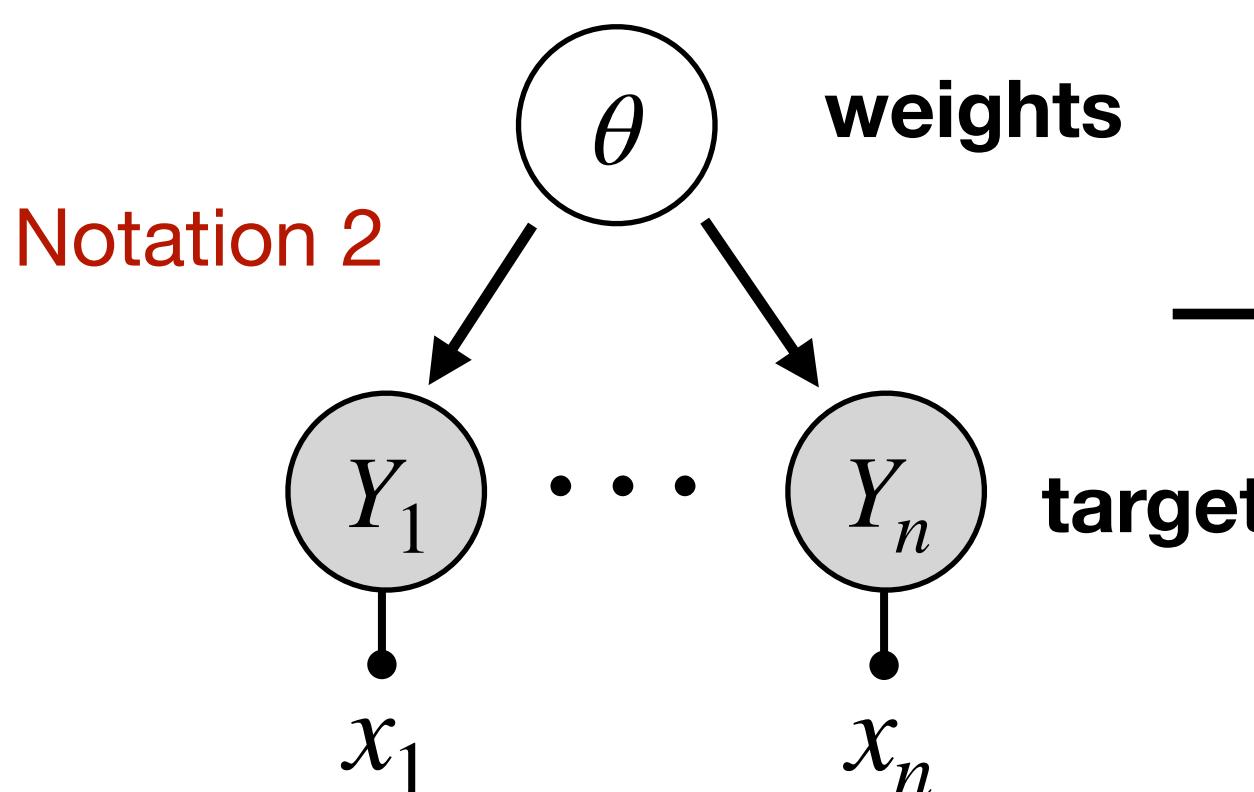
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Bayesian Linear regression



$$D = \{(x_1, y_1), \dots, (x_n, y_n)\} \quad \text{with} \quad x_i \in \mathbb{R}^d, y_i \in \mathbb{R}$$

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$$P(\theta) = \mathcal{N}(\theta | 0, \gamma^2)$$

Legend :

— Fixed variable

○ Hidden (latent) r.v.

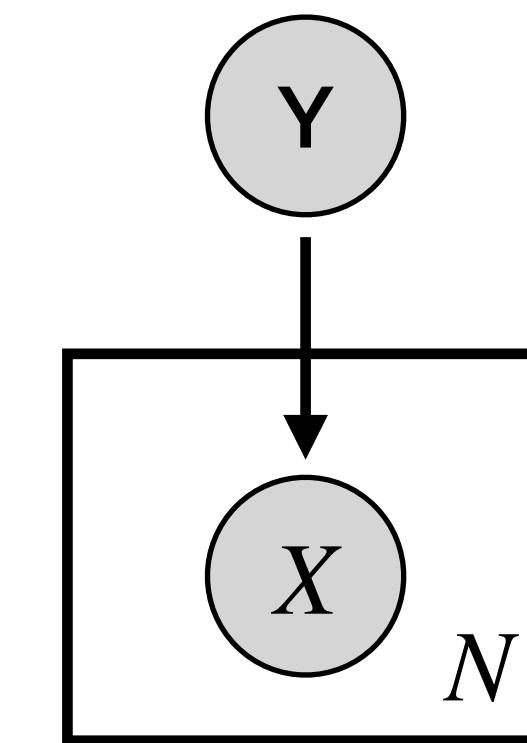
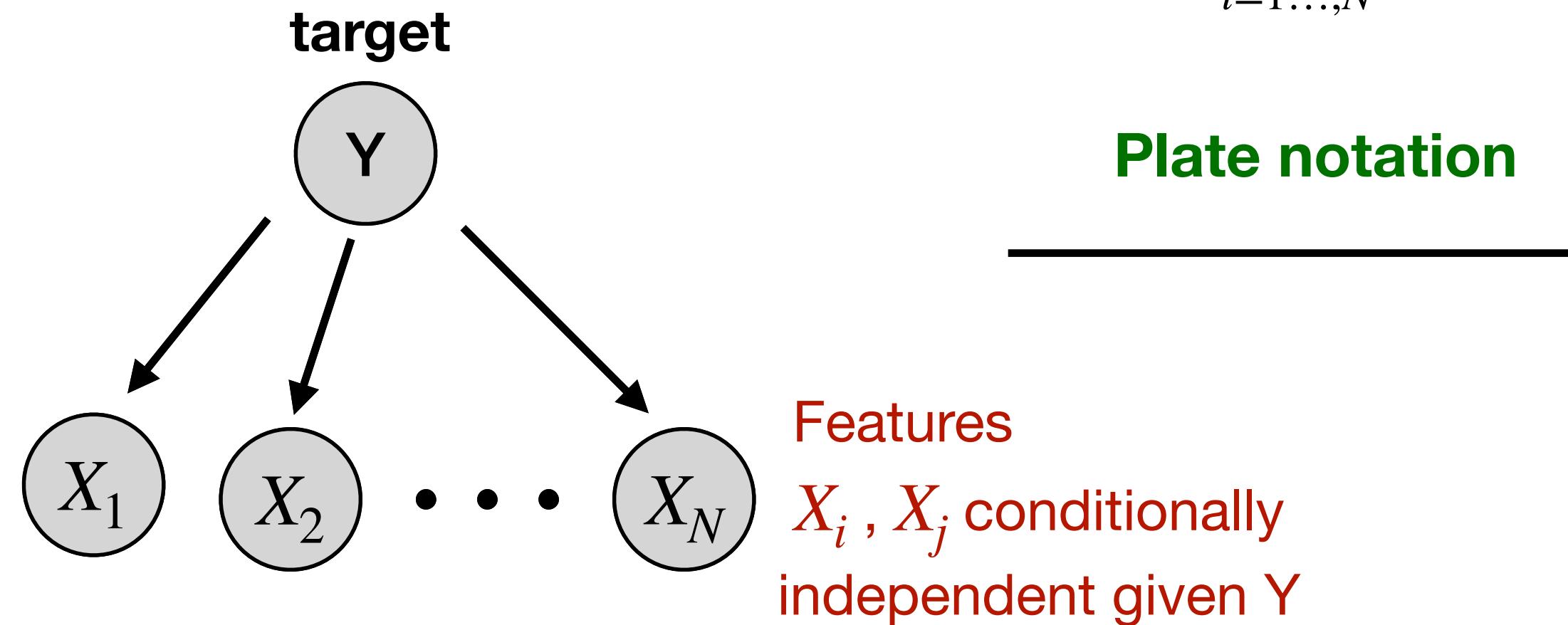
● Observed r.v.

2. Probabilistic model

Plates and examples of probabilistic model

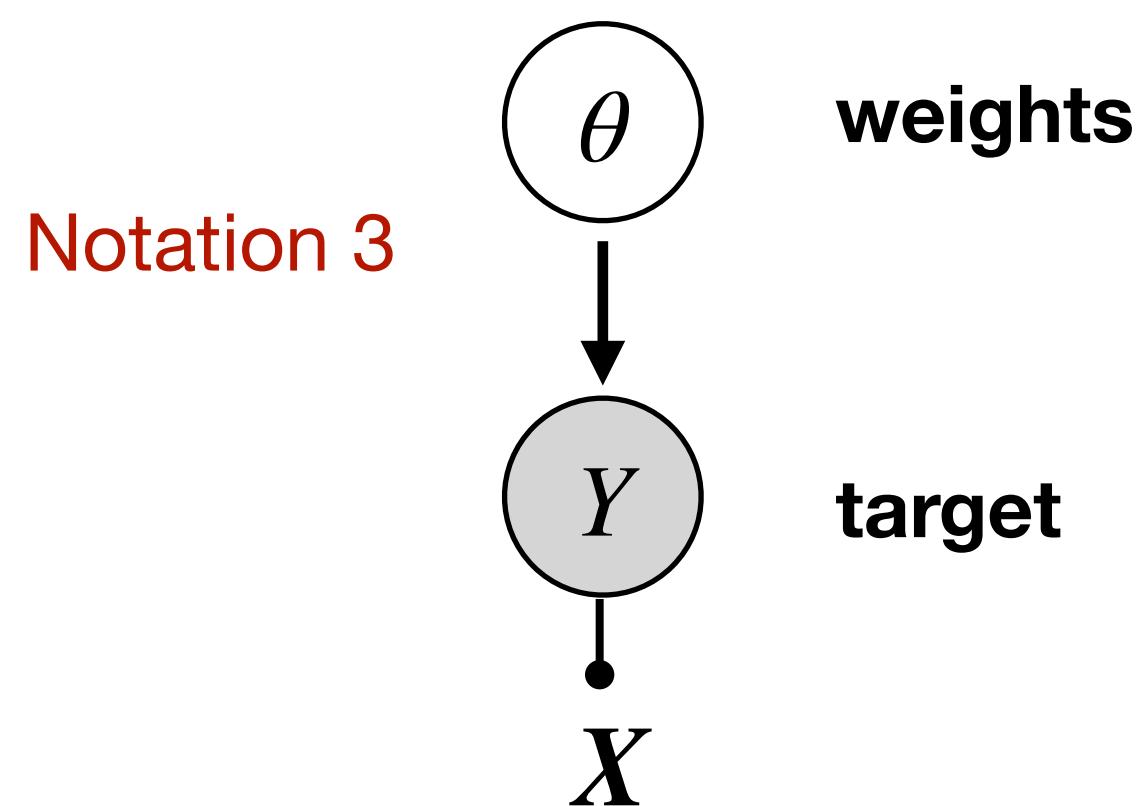
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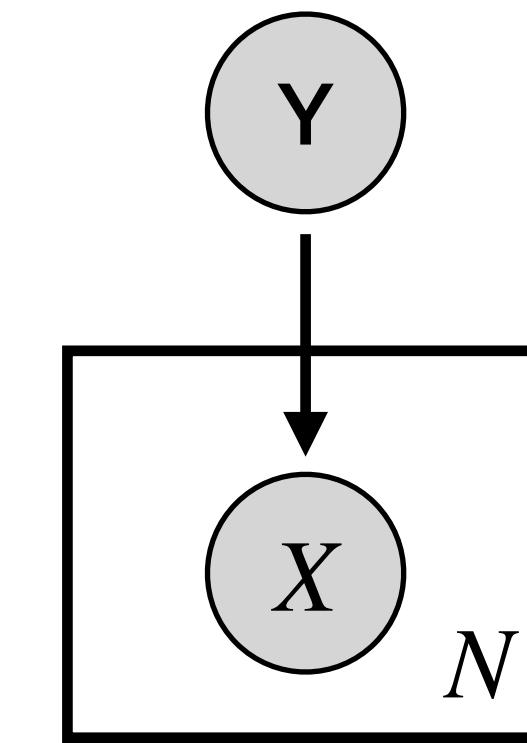
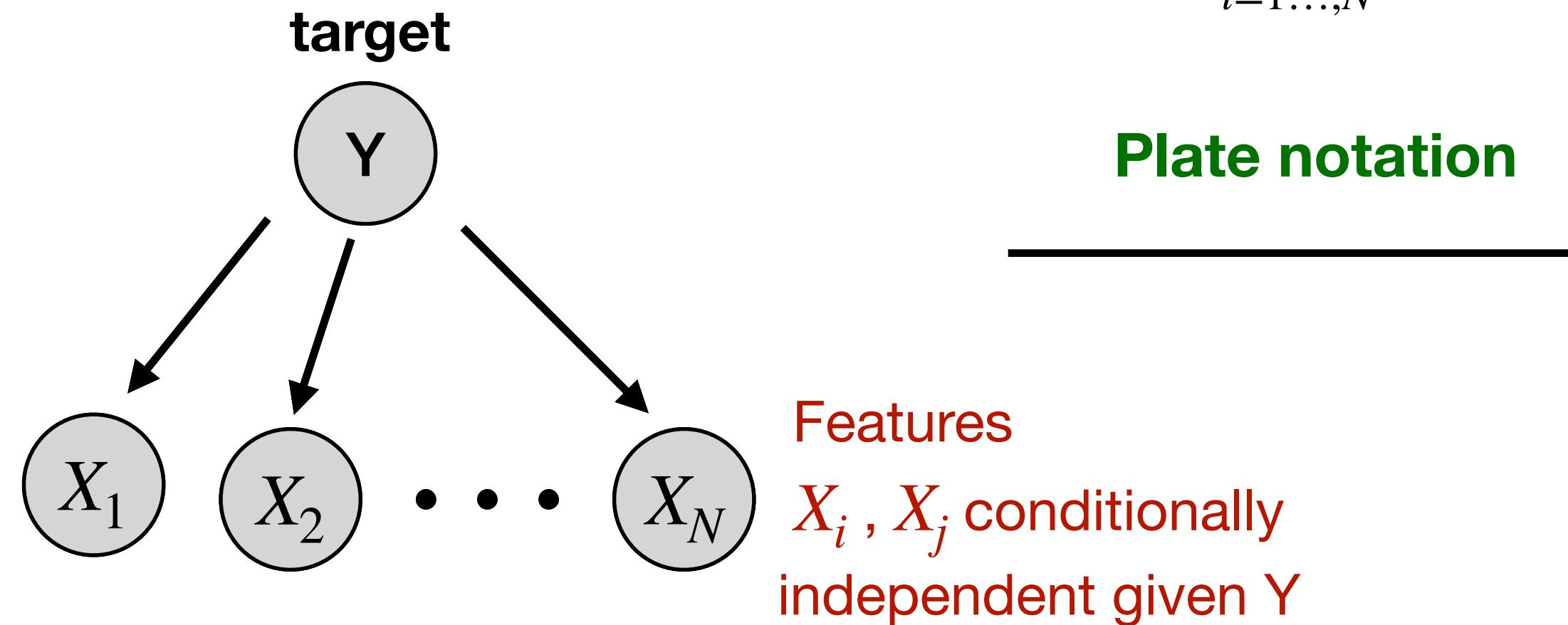


2. Probabilistic model

Plates and examples of probabilistic model

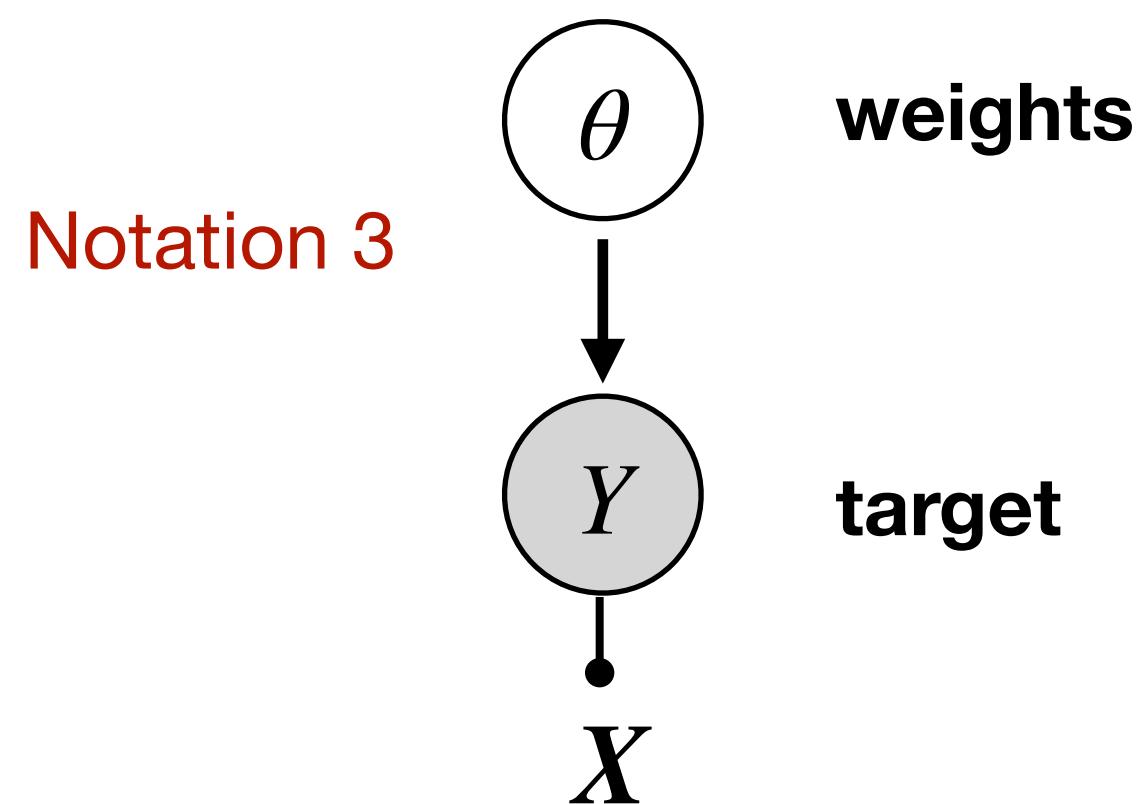
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$$P(y | \theta, x) = \mathcal{N}(y | \theta^T x, \sigma^2 I_n)$$

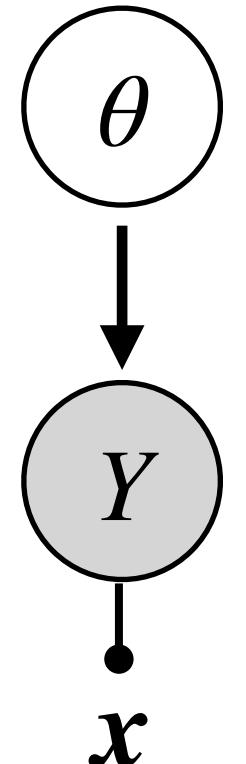
$$P(\theta) = \mathcal{N}(\theta | 0, \gamma^2 I_n)$$

Legend : — Fixed variable ○ Hidden (latent) r.v. ● Observed r.v.

2. Probabilistic model

Linear regression

Bayesian Linear regression



$$P(\theta, y | X) = P(y | \theta, X) \times P(\theta)$$

$$P(y | \theta, X) = \mathcal{N}(y | \theta^T X, \sigma^2 I_n)$$

$$P(\theta) = \mathcal{N}(\theta | 0, \gamma^2 I_n)$$

Objective :

Frequentist linear regression

Objective : $\min_{\theta} \mathcal{L}(\theta) = \min_{\theta} \|\theta^T X - y\|^2$

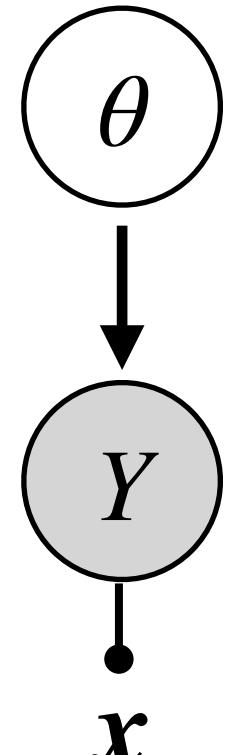
$$\hat{\theta} = \arg \min_{\theta} \mathcal{L}(\theta)$$

$$\hat{\theta} = (X^T X)^{-1} X^T y$$

2. Probabilistic model

Linear regression

Bayesian Linear regression



$$P(\theta, y | X) = P(y | \theta, X) \times P(\theta)$$

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$$P(\theta) = \mathcal{N}(\theta | 0, \gamma^2 I_n)$$

Objective : $\arg \max_{\theta} P(\theta | X, y) = \arg \max_{\theta} P(\theta, y | X)$

Frequentist linear regression

Objective : $\min_{\theta} \mathcal{L}(\theta) = \min_{\theta} \|\theta^T X - y\|^2$

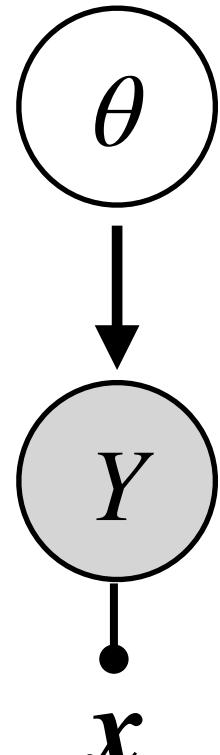
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Objective : $\arg \max_{\theta} P(\theta | X, y) = \arg \max_{\theta} P(\theta, y | X)$

Frequentist linear regression

Objective : $\min_{\theta} \mathcal{L}(\theta) = \min_{\theta} \|\theta^T X - y\|^2$

$$\hat{\theta} = \arg \min_{\theta} \mathcal{L}(\theta)$$

$$\hat{\theta} = (X^T X)^{-1} X^T y$$

Theorem :

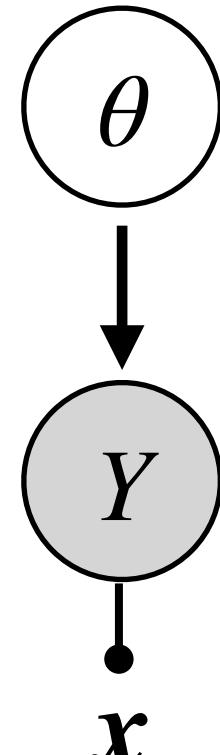
There exists $\lambda \in \mathbb{R}$ such that : $\arg \max_{\theta} P(\theta | X, y) = \arg \min_{\theta} \left\{ \|\theta^T X - y\|^2 + \lambda \|\theta\|^2 \right\}$

So by adding a normal prior on the weight we turned this problem into a L_2 regularised problem

2. Probabilistic model

Linear regression

Bayesian Linear regression



$$P(\theta, y | X) = P(y | \theta, X) \times P(\theta)$$

$$P(y | \theta, X) = \mathcal{N}(y | \theta^T X, \sigma^2 I_n)$$

$$P(\theta) = \mathcal{N}(\theta | 0, \gamma^2 I_n)$$

Objective : $\arg \max_{\theta} P(\theta | X, y) = \arg \max_{\theta} P(\theta, y | X)$

Frequentist linear regression

Objective : $\min_{\theta} \mathcal{L}(\theta) = \min_{\theta} \|\theta^T X - y\|^2$

$$\hat{\theta} = \arg \min_{\theta} \mathcal{L}(\theta)$$

$$\hat{\theta} = (X^T X)^{-1} X^T y$$

Theorem :

There exists $\lambda \in \mathbb{R}$ such that : $\arg \max_{\theta} P(\theta | X, y) = \arg \min_{\theta} \left\{ \|\theta^T X - y\|^2 + \lambda \|\theta\|^2 \right\}$

So by adding a normal prior on the weight we turned this problem into a L_2 regularised problem

Proof : see the whiteboard in class or left as an exercise



3

Analytical Inference

3. Analytical Inference

Reminder of posterior distribution

Posterior distribution

$$P(\theta | X) = \frac{P(X, \theta)}{P(X)} = \frac{\text{Likelihood} \times \text{Prior}}{\text{Evidence}}$$

3. Analytical Inference

Reminder of posterior distribution

Posterior distribution

The diagram illustrates the formula for the posterior distribution:

$$P(\theta | X) = \frac{P(X, \theta)}{P(X)} = \frac{P(X | \theta) \times P(\theta)}{P(X)}$$

The components are labeled as follows:

- Likelihood**: Fixed by model
- Prior**: Fixed by us
- Evidence**: Fixed by data
- Posterior**: The resulting distribution

3. Analytical Inference

Reminder of posterior distribution

Posterior distribution

$$P(\theta | X) = \frac{P(X, \theta)}{P(X)} = \frac{P(X | \theta) \times P(\theta)}{P(X)}$$

Posterior

Fixed by model Likelihood Prior Fixed by us

Evidence
HARD TO COMPUTE

$$P(X) = \int_{\theta} P(X | \theta) \cdot P(\theta) \cdot d\theta$$

Fixed by data

3. Analytical Inference

Maximum a posteriori (MAP) : definition & remarks

Posterior distribution

$$P(\theta | X) = \frac{P(X, \theta)}{P(X)} = \frac{P(X | \theta) \times P(\theta)}{P(X)}$$

Posterior

Fixed by model

Likelihood

Prior

Fixed by us

Evidence

HARD TO COMPUTE

Fixed by data

$$P(X) = \int_{\theta} P(X | \theta) \cdot P(\theta) \cdot d\theta$$

Remarks

- We have to **avoid computing** the evidence
- Naive approach : **maximum a posteriori** ,
$$\hat{\theta}_{MAP} = \arg \max_{\theta} \left\{ \frac{P(\theta | X) \cdot P(\theta)}{P(X)} \right\}$$
$$= \arg \max_{\theta} P(X | \theta) \cdot P(\theta)$$
- This maximization can be done with numerical **optimization** problem

3. Analytical Inference

Maximum a posteriori (MAP) : limitations

Posterior distribution

$$P(\theta | X) = \frac{P(X, \theta)}{P(X)} = \frac{P(X | \theta) \times P(\theta)}{P(X)}$$

Posterior

Likelihood **Prior**

Evidence
HARD TO COMPUTE

Fixed by model

Fixed by us

Fixed by data

$$P(X) = \int_{\theta} P(X | \theta) \cdot P(\theta) \cdot d\theta$$

Remarks

- We have to **avoid computing** the evidence
- Naive approach : **maximum a posteriori** ,
$$\hat{\theta}_{MAP} = \arg \max_{\theta} \left\{ \frac{P(\theta | X) \cdot P(\theta)}{P(X)} \right\}$$
$$= \arg \max_{\theta} P(X | \theta) \cdot P(\theta)$$
- This maximization can be done with numerical **optimization** problem

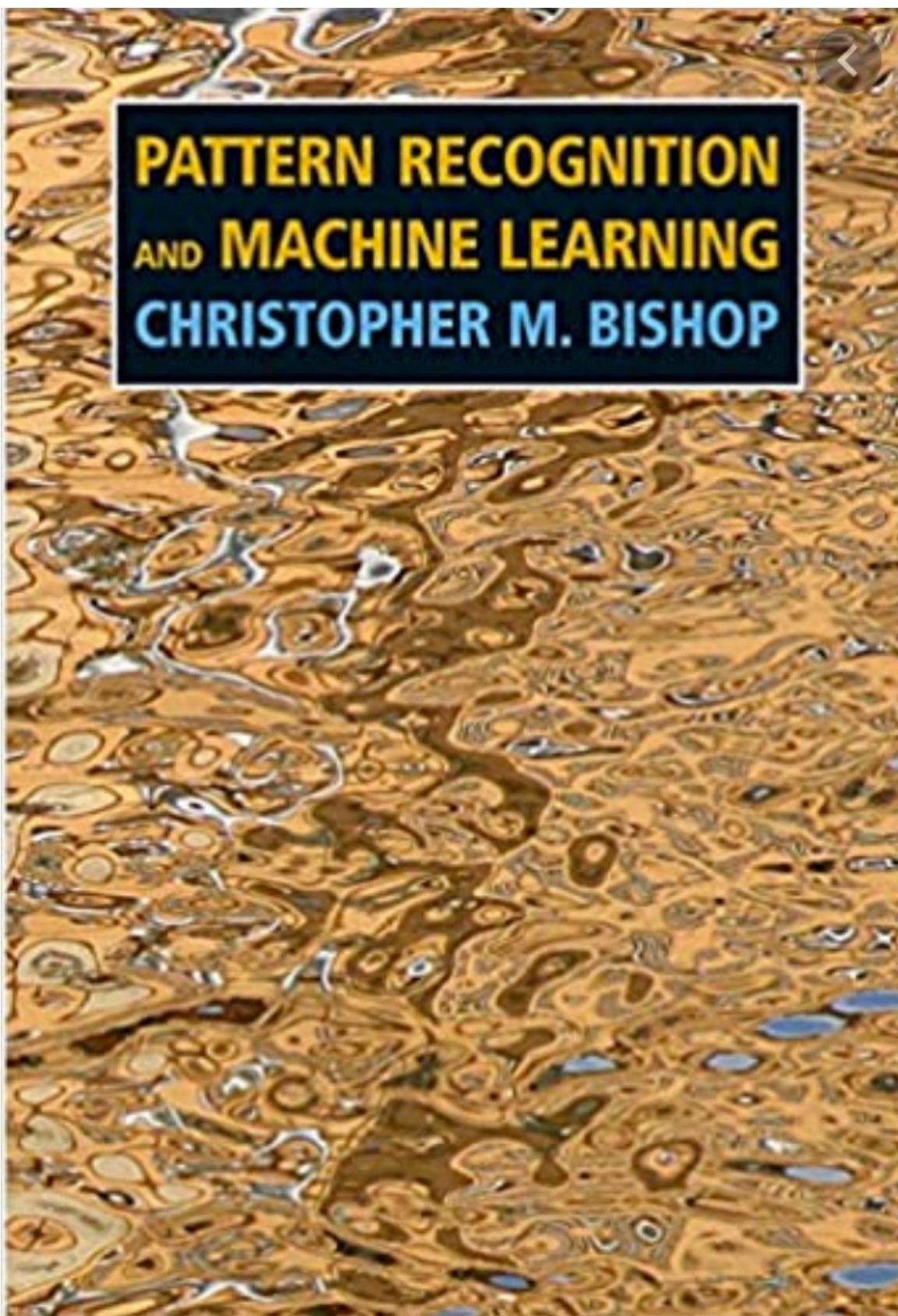
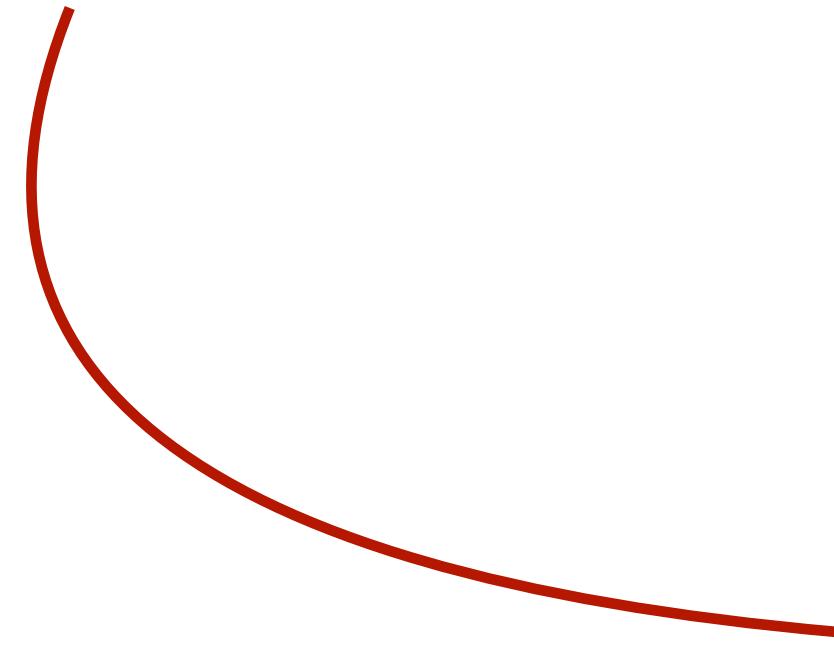
Limitations (among many others)

1. in general, **not representative of bayesian** methods : $\hat{\theta}_{MAP}$ is a point estimate like $\hat{\theta}_{MLE}$
 - can't compute **credible intervals** because it doesn't return a pdf/pmf (not a bayesian inference)
2. **can't use online learning** : the prior is not well updated

3. Analytical Inference

Maximum a posteriori (MAP) : book

For more theoretical details (and example on analytical inference) :



4

Conjugate distributions

4. Conjugate distributions

Conjugate distributions : avoid computing evidence

Posterior distribution

The diagram illustrates the formula for the posterior distribution:

$$P(\theta | X) = \frac{P(X, \theta)}{P(X)} = \frac{P(X | \theta) \times P(\theta)}{P(X)}$$

The components are labeled as follows:

- Likelihood**: Fixed by model
- Prior**: Fixed by us
- Evidence**: Fixed by data

4. Conjugate distributions

Conjugate distributions : avoid computing evidence

Posterior distribution

$$P(\theta | X) = \frac{P(X, \theta)}{P(X)} = \frac{P(X | \theta) \times P(\theta)}{P(X)}$$

Posterior

Fixed by model

Likelihood

Prior

Fixed by us

Evidence

Fixed by data

Remarks

- We have to **avoid computing** the evidence
- We can choose a **convenient prior** which enable us to compute the posterior :
Conjugate prior

4. Conjugate distributions

Conjugate distributions : avoid computing evidence

Posterior distribution

$$P(\theta | X) = \frac{P(X, \theta)}{P(X)} = \frac{P(X | \theta) \times P(\theta)}{P(X)}$$

Posterior

The diagram illustrates the components of the posterior distribution formula. The term $P(X, \theta)$ is labeled "Fixed by model". The term $P(\theta)$ is labeled "Fixed by us". The term $P(X)$ is labeled "Fixed by data". The terms $P(X | \theta)$ and $P(\theta)$ are grouped together and labeled "Likelihood" and "Prior" respectively, while the term $P(X)$ is labeled "Evidence".

Remarks

- We have to **avoid computing** the evidence
- We can choose a **convenient prior** which enable us to compute the **posterior** :
Conjugate prior

Conjugate prior

$P(\theta)$ is **conjugate** to $P(X | \theta)$ if the $P(\theta)$ and $P(X | \theta)$ lie in the same family of distributions (gaussian for example)

4. Conjugate distributions

Conjugate distributions : avoid computing evidence

Posterior distribution

$$P(\theta | X) = \frac{P(X, \theta)}{P(X)} = \frac{P(X|\theta) \times P(\theta)}{P(X)}$$

Posterior

Likelihood Prior

Evidence

Fixed by model Fixed by us Fixed by data

Remarks

- We have to **avoid computing** the evidence
- We can choose a **convenient prior** which enable us to compute the posterior :
Conjugate prior

Conjugate prior

$P(\theta)$ is **conjugate** to $P(X|\theta)$ if the $P(\theta)$ and $P(X|\theta)$ lie in the same family of distributions (gaussian for example)

Example

$$P(\theta | X) = \frac{\mathcal{N}(\theta | \mu_{prior}, \sigma^2_{prior})}{P(X)} \times P(\theta)$$

$\mathcal{N}(\theta | \mu_{posterior}, \sigma^2_{posterior})$

In the context of a gaussian, the prior for the mean is a gaussian !

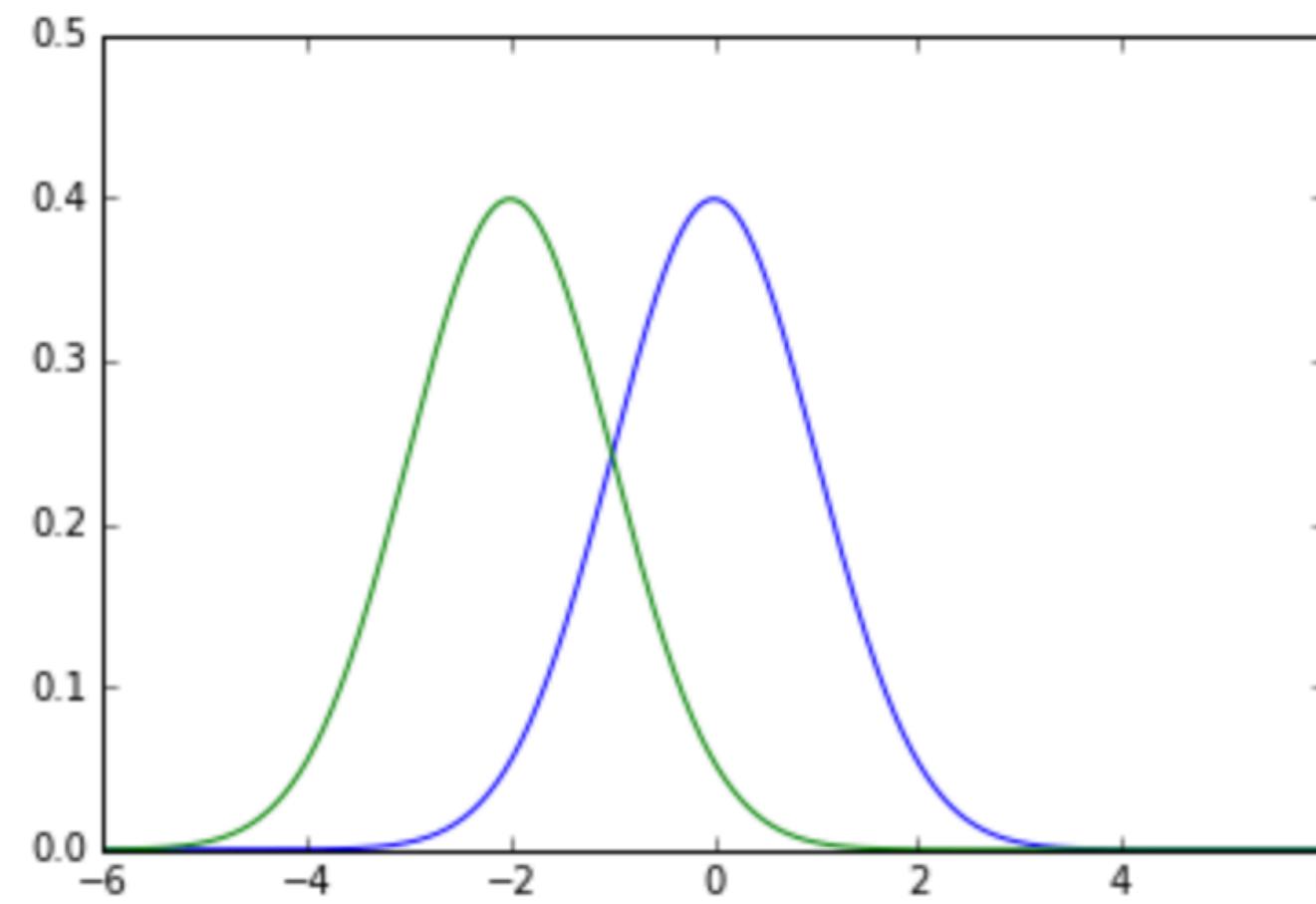
4. Conjugate distributions

Conjugate distributions : example

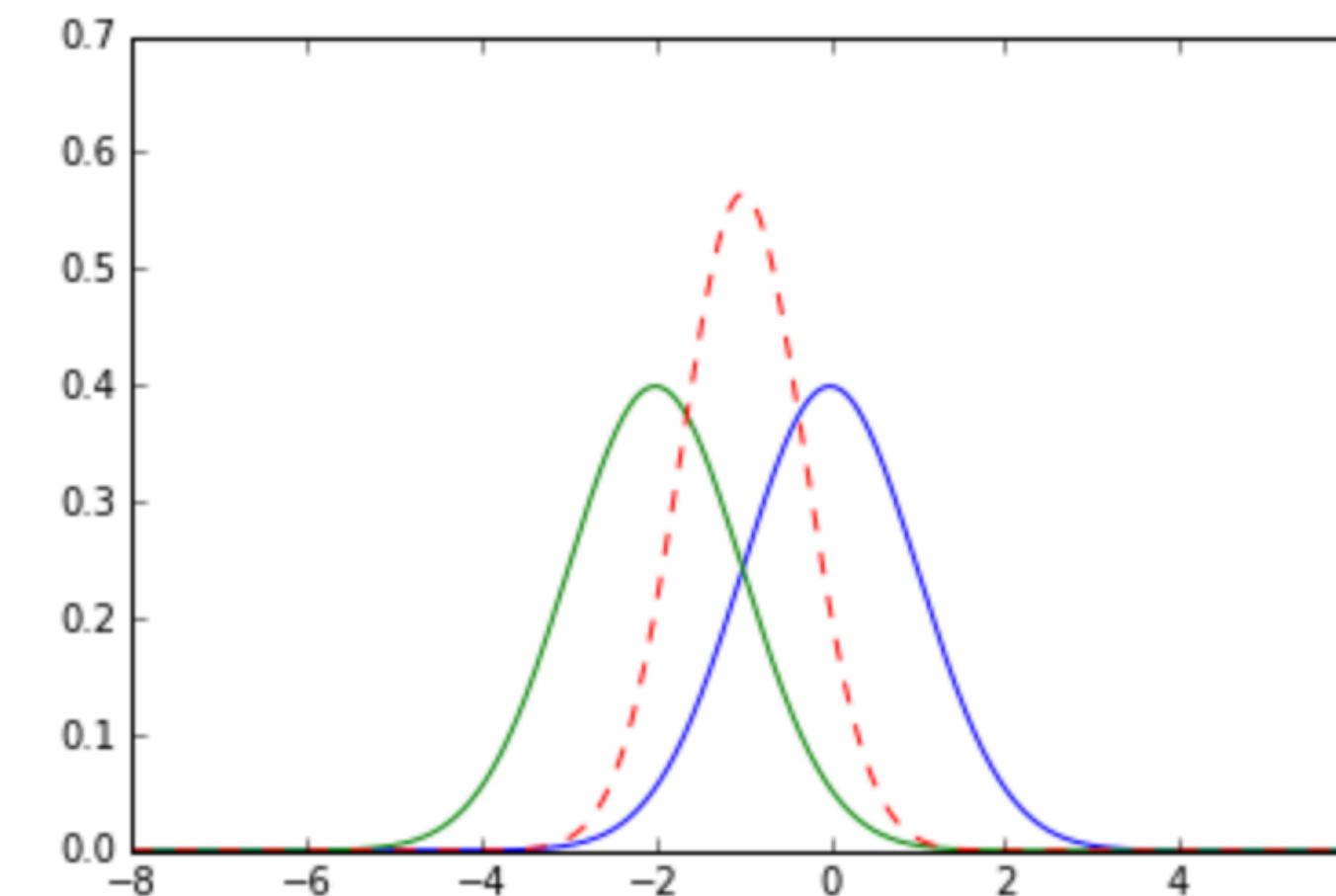
Example

$$P(\theta|X) = \frac{\mathcal{N}(X|\theta, \sigma^2) \times P(\theta)}{P(X)}$$

$\mathcal{N}(\theta|\mu_{prior}, \sigma^2_{prior})$



pointwise product



Exercice (left as an exercice, correction in the next lecture)

Show that $\mathcal{N}(\theta|x/2, 1/2) = \frac{\mathcal{N}(x|\theta, 1) \times \mathcal{N}(\theta|0, 1)}{P(x)}$

4. Conjugate distributions

Usual distributions : Gamma distribution

Gamma distribution

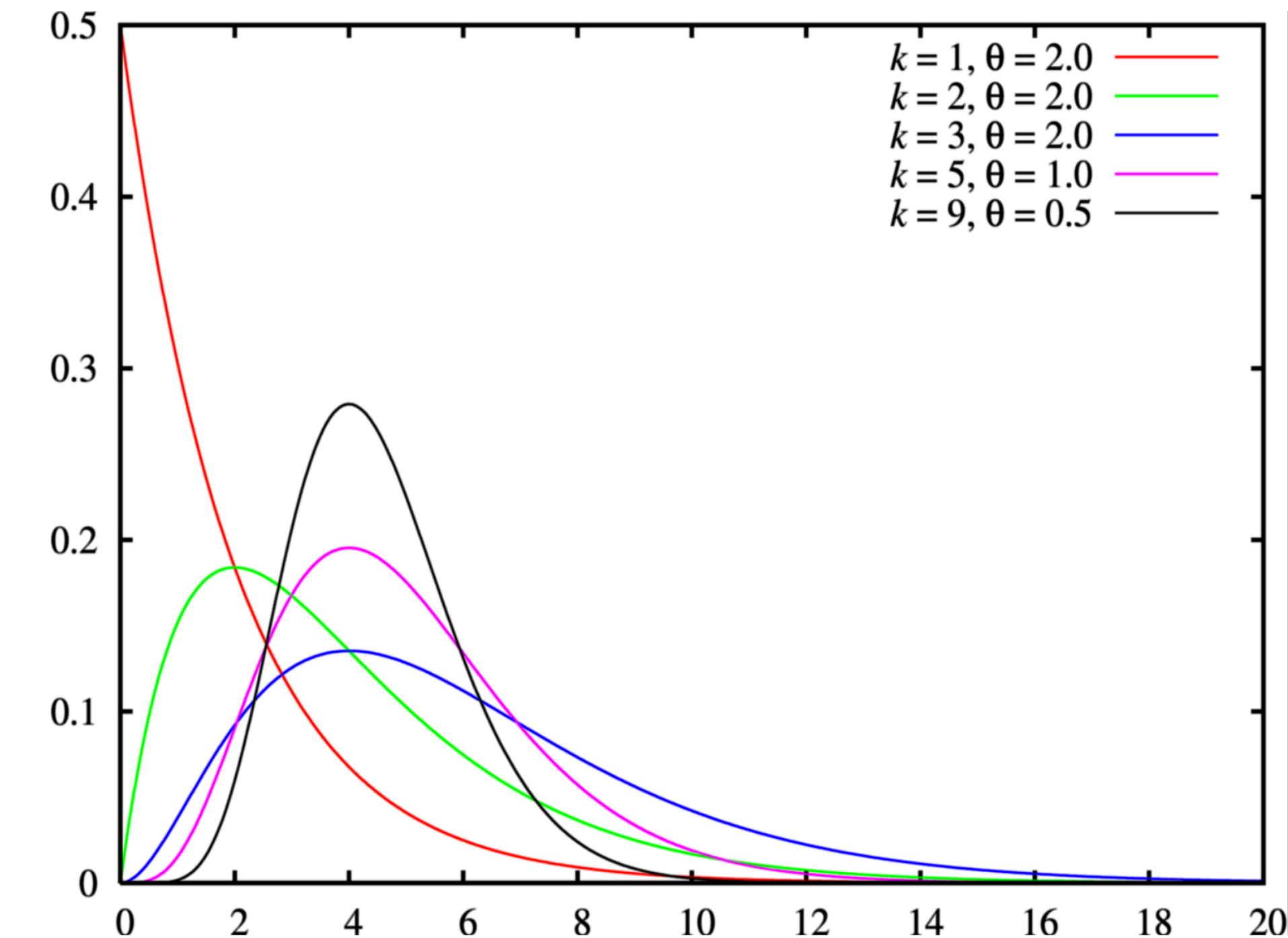
PDF : $\Gamma(x | \alpha, \beta) = \frac{\beta^\alpha}{\Gamma(\alpha)} x^{\alpha-1} e^{-\beta x}$ with $x, \alpha, \beta > 0$

$$\Gamma(\alpha) = (\alpha - 1)!$$

mean : $\mathbb{E}[x] = \frac{\alpha}{\beta}$

variance : $V(x) = \frac{\alpha}{\beta^2}$

mode : $Mode [x] = \frac{\alpha - 1}{\beta}$



Example

$$\Gamma(\gamma | \alpha_{posterior}, \beta_{posterior}) — P(\gamma | x) = \frac{\mathcal{N}(x | \mu, \gamma^{-1}) \times P(\gamma)}{P(x)} \longrightarrow \Gamma(\gamma | \alpha_{prior}, \beta_{prior})$$

In the context of a gaussian, the prior for the precision is a gamma !

4. Conjugate distributions

Usual distributions : Gamma distribution

Gamma distribution

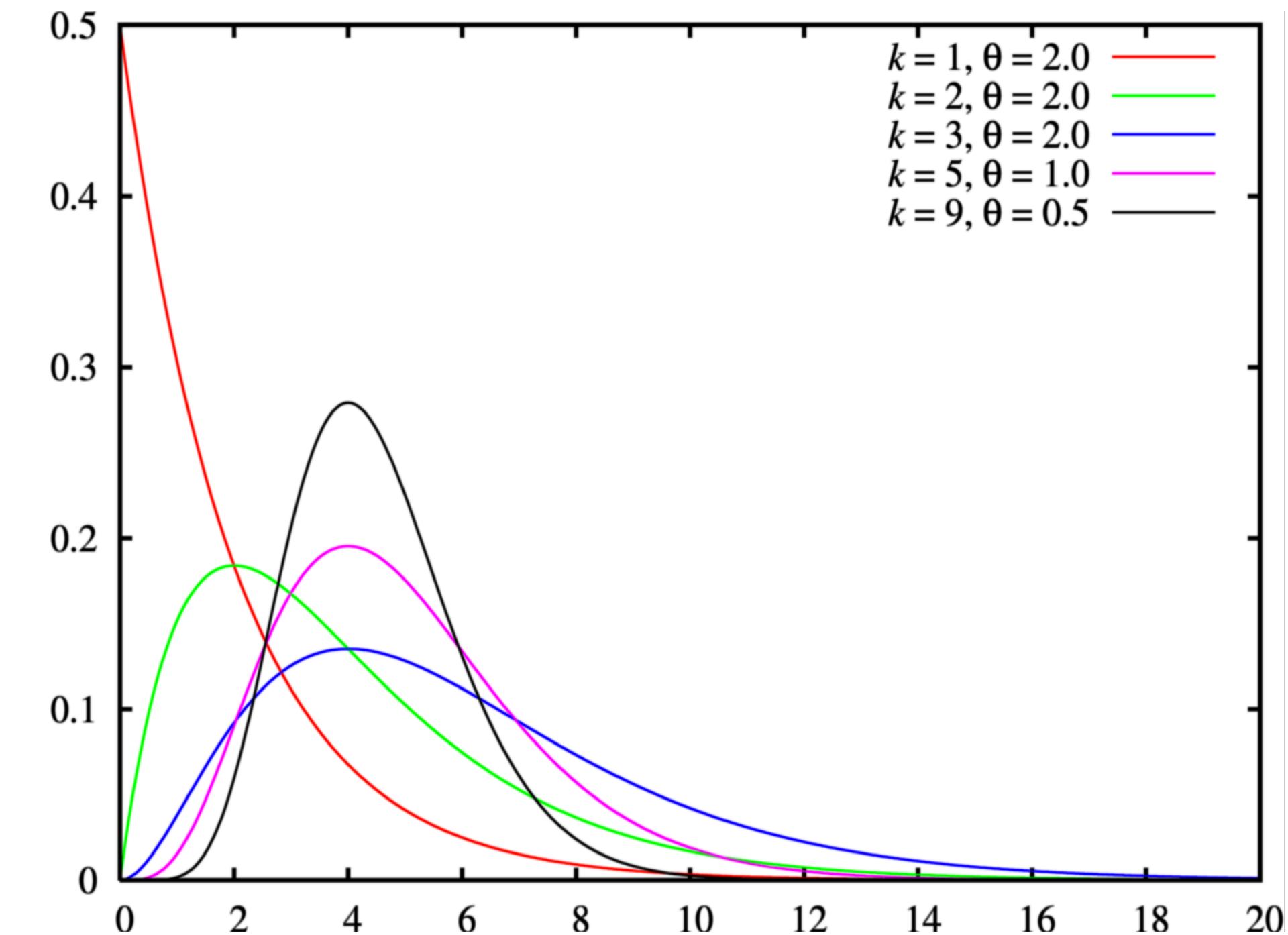
PDF : $\Gamma(x | \alpha, \beta) = \frac{\beta^\alpha}{\Gamma(\alpha)} x^{\alpha-1} e^{-\beta x}$ with $x, \alpha, \beta > 0$

$$\Gamma(\alpha) = (\alpha - 1)!$$

mean : $\mathbb{E}[x] = \frac{\alpha}{\beta}$

variance : $V(x) = \frac{\alpha}{\beta^2}$

mode : $Mode [x] = \frac{\alpha - 1}{\beta}$



Exercice (left as an exercice, correction in the next lecture)

$$P(\gamma | x) = \frac{\mathcal{N}(x | \mu, \gamma^{-1}) \times P(\gamma)}{P(x)}$$

$\Gamma(\gamma | \alpha_{prior}, \beta_{prior})$

$\Gamma(\gamma | \alpha_{posterior}, \beta_{posterior})$

$\Gamma(\gamma | \alpha_{prior} + 1/2, \beta_{prior} + (x - \mu)^2/2)$

In the context of a gaussian, the prior for the precision is a gamma !

4. Conjugate distributions

Usual distributions : Beta distribution

Beta distribution

PDF : $B(x | \alpha, \beta) = \frac{1}{B(\alpha, \beta)} x^{\alpha-1} (1-x)^{\beta-1}$ with $\alpha, \beta > 0$ and $x \in [0,1]$

$$B(\alpha, \beta) = \frac{\Gamma(\alpha) \cdot \Gamma(\beta)}{\Gamma(\alpha + \beta)}$$

mean : $\mathbb{E}[x] = \frac{\alpha}{\alpha + \beta}$

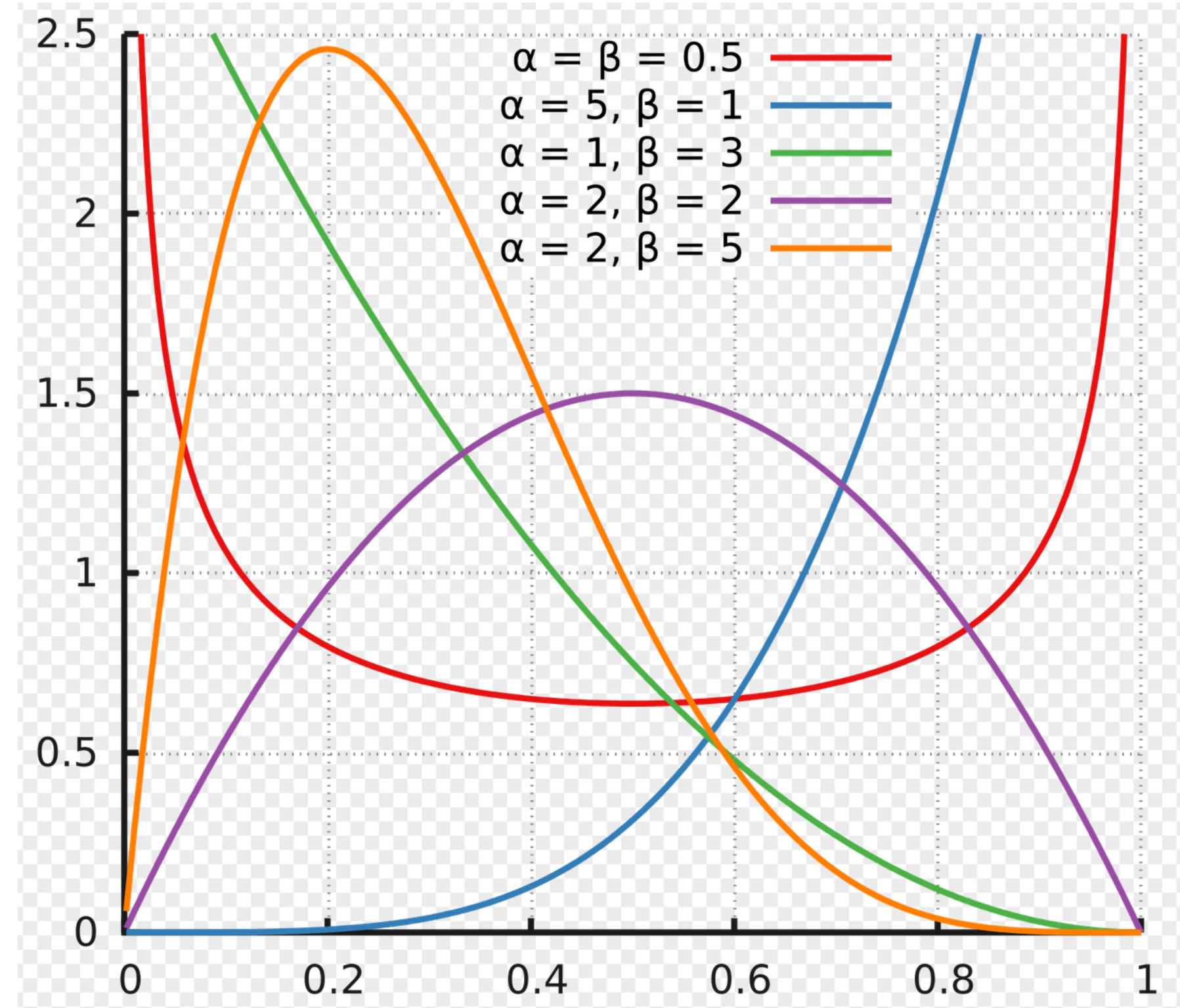
variance : $V(x) = \frac{\alpha\beta}{(\alpha + \beta)^2 \cdot (\alpha + \beta - 1)}$

mode : $Mode[x] = \frac{\alpha - 1}{\alpha + \beta - 2}$

Example

$$B(\theta | \alpha_{posterior}, \beta_{posterior}) — P(\theta | x) = \frac{Ber(x | \theta) \times P(\theta)}{P(x)} \longrightarrow B(\theta | \alpha_{prior}, \beta_{prior})$$

In the context of a Bernoulli distribution, the prior is a beta !



4. Conjugate distributions

Usual distributions : Beta distribution

Beta distribution

PDF : $B(x|\alpha, \beta) = \frac{1}{B(\alpha, \beta)} x^{\alpha-1} (1-x)^{\beta-1}$ with $\alpha, \beta > 0$ and $x \in [0,1]$

$$B(\alpha, \beta) = \frac{\Gamma(\alpha) \cdot \Gamma(\beta)}{\Gamma(\alpha + \beta)}$$

mean : $\mathbb{E}[x] = \frac{\alpha}{\alpha + \beta}$

variance : $V(x) = \frac{\alpha\beta}{(\alpha + \beta)^2 \cdot (\alpha + \beta - 1)}$

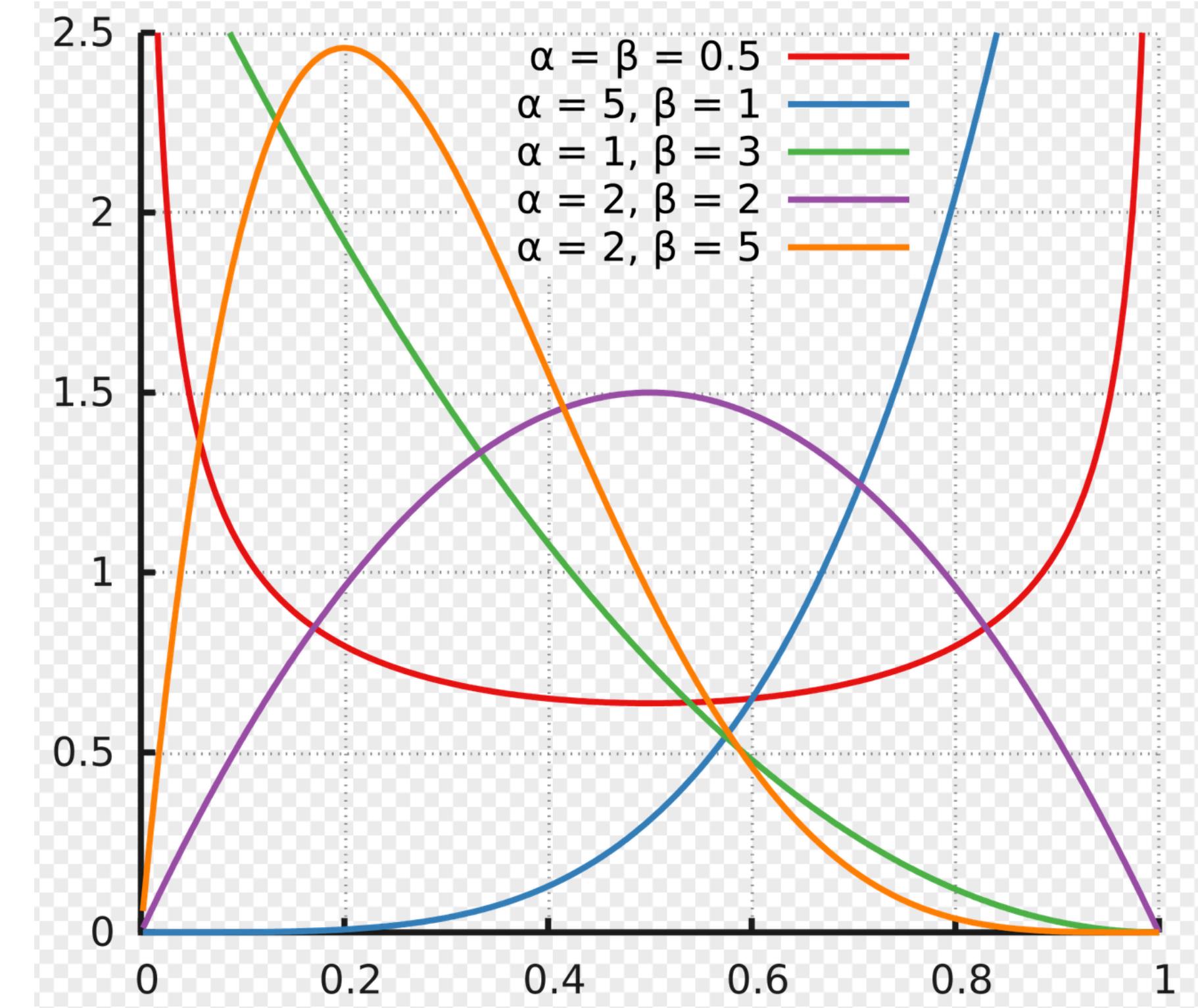
mode : $Mode[x] = \frac{\alpha - 1}{\alpha + \beta - 2}$

Exercice (left as an exercice, correction in the next lecture)

$$P(\theta|x) = \frac{Ber(x|\theta) \times P(\theta)}{P(x)}$$

$\theta^{n_1} \cdot (1 - \theta)^{n_0}$
 $B(\theta|\alpha_{prior}, \beta_{prior})$

$B(\theta|\alpha_{posterior}, \beta_{posterior})$
 $B(\theta|n_1 + \alpha_{prior}, n_0 + \beta_{prior})$



In the context of a Bernoulli distribution, the prior is a beta !

4. Conjugate distributions

Limitations

Posterior distribution

$$P(\theta | X) = \frac{P(X, \theta)}{P(X)} = \frac{P(X | \theta) \times P(\theta)}{\text{Evidence}}$$

Posterior

Fixed by model

Likelihood

Prior

Fixed by us

Evidence

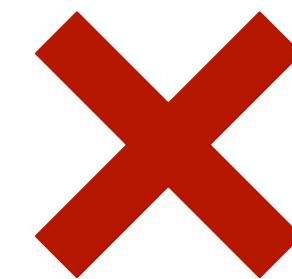
Fixed by data

Remarks

- We have to **avoid computing** the evidence
- We can choose a **convenient prior** which enable us to compute the posterior :
Conjugate prior



- It computes the **exact posterior**
- Easy for **online learning**

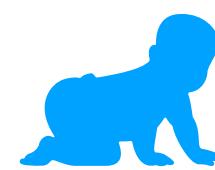


- For some (**complex**) models, the conjugate prior can be **inadequate (improper prior)**
- Can be **unrealistic (non-informative prior)**

!

Road map

Bayesian statistics (03/05/21)



1

Bayesian perspective :

$$P(\theta | X) = \frac{P(X, \theta)}{P(X)} = \frac{P(X | \theta) \cdot P(\theta)}{P(X)}$$

Likelihood
Posterior distribution

θ parameters

X observations

Exemple :
Naive Bayes classifier,
Linear regression,

Prior distribution

Evidence

Hard to compute !

MAP : $\arg \max_{\theta} P(X | \theta) \cdot P(\theta)$

Conjugate distribution

Pros :
- exact posterior

Cons :
- conjugate prior
maybe inadequate

Extensions (14/06/21)

5

Variational Inference (31/05/21)

3

Latent variable models (17/05/21)

2

Markov Chain Monte Carlo (07/06/21)

4