

libcin

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# Chapter 1

## Module Index

### 1.1 Modules

Here is a list of all modules:

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## Chapter 2

# Class Index

### 2.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

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## Chapter 3

# File Index

### 3.1 File List

Here is a list of all documented files with brief descriptions:

src/ <a href="#">cin.h</a> . . . . .	19
src/ <b>cin_register_map.h</b> . . . . .	??
src/ <b>cinregisters.h</b> . . . . .	??
src/ <b>common.h</b> . . . . .	??
src/ <b>config.h</b> . . . . .	??
src/ <b>control.h</b> . . . . .	??
src/ <b>data.h</b> . . . . .	??
src/ <b>descramble.h</b> . . . . .	??
src/ <b>descramble_map.h</b> . . . . .	??
src/ <b>fclk_program.h</b> . . . . .	??
src/ <b>fifo.h</b> . . . . .	??
src/ <b>report.h</b> . . . . .	??
src/ <b>version.h</b> . . . . .	??



## Chapter 4

# Module Documentation

### 4.1 Cin Control Routines

#### Functions

- int [cin\\_ctl\\_init](#) ([cin\\_ctl\\_t](#) \*cin, const char \*ipaddr, uint16\_t oport, uint16\_t iport, uint16\_t soport, uint16\_t siport)
- int [cin\\_ctl\\_destroy](#) ([cin\\_ctl\\_t](#) \*cin)
- int [cin\\_ctl\\_read](#) ([cin\\_ctl\\_t](#) \*cin, uint16\_t reg, uint16\_t \*val)
- int [cin\\_ctl\\_write](#) ([cin\\_ctl\\_t](#) \*cin, uint16\_t reg, uint16\_t val, int wait)
- int [cin\\_ctl\\_stream\\_write](#) ([cin\\_ctl\\_t](#) \*cin, char \*val, int size)
- int [cin\\_ctl\\_write\\_with\\_readback](#) ([cin\\_ctl\\_t](#) \*cin, uint16\_t reg, uint16\_t val)
- int [cin\\_ctl\\_pwr](#) ([cin\\_ctl\\_t](#) \*cin, int pwr)
- int [cin\\_ctl\\_fp\\_pwr](#) ([cin\\_ctl\\_t](#) \*cin, int pwr)
- int [cin\\_ctl\\_fo\\_test\\_pattern](#) ([cin\\_ctl\\_t](#) \*cin, int on\_off)
- int [cin\\_ctl\\_load\\_config](#) ([cin\\_ctl\\_t](#) \*cin, char \*filename)
- int [cin\\_ctl\\_load\\_firmware](#) ([cin\\_ctl\\_t](#) \*cin, char \*filename)
- int [cin\\_ctl\\_set\\_fclk](#) ([cin\\_ctl\\_t](#) \*cin, int clkfreq)
- int [cin\\_ctl\\_get\\_fclk](#) ([cin\\_ctl\\_t](#) \*cin, int \*clkfreq)
- int [cin\\_ctl\\_freeze\\_dco](#) ([cin\\_ctl\\_t](#) \*cin, int freeze)
- int [cin\\_ctl\\_get\\_cfg\\_fpga\\_status](#) ([cin\\_ctl\\_t](#) \*cin, uint16\_t \*\_val)
- int [cin\\_ctl\\_get\\_id](#) ([cin\\_ctl\\_t](#) \*cin, [cin\\_ctl\\_id\\_t](#) \*\_val)
- void [cin\\_ctl\\_display\\_id](#) (FILE \*out, [cin\\_ctl\\_id\\_t](#) val)
- void [cin\\_ctl\\_display\\_fpga\\_status](#) (FILE \*out, uint16\_t val)
- int [cin\\_ctl\\_get\\_dcm\\_status](#) ([cin\\_ctl\\_t](#) \*cin, uint16\_t \*\_val)
- void [cin\\_ctl\\_display\\_dcm\\_status](#) (FILE \*out, uint16\_t \*\_val)
- double [cin\\_ctl\\_current\\_calc](#) (uint16\_t val)
- int [cin\\_ctl\\_get\\_power\\_status](#) ([cin\\_ctl\\_t](#) \*cin, int full, int \*pwr, [cin\\_ctl\\_pwr\\_mon\\_t](#) \*values)
- void [cin\\_ctl\\_display\\_pwr](#) (FILE \*out, [cin\\_ctl\\_pwr\\_mon\\_t](#) \*values)
- void [cin\\_ctl\\_display\\_pwr\\_line](#) (FILE \*out, const char \*msg, [cin\\_ctl\\_pwr\\_val\\_t](#) val)
- int [cin\\_ctl\\_calc\\_vi\\_status](#) ([cin\\_ctl\\_t](#) \*cin, uint16\_t vreg, uint16\_t ireg, double vfact, [cin\\_ctl\\_pwr\\_val\\_t](#) \*vi)
- int [cin\\_ctl\\_get\\_camera\\_pwr](#) ([cin\\_ctl\\_t](#) \*cin, int \*val)
- int [cin\\_ctl\\_set\\_camera\\_pwr](#) ([cin\\_ctl\\_t](#) \*cin, int val)
- int [cin\\_ctl\\_set\\_bias](#) ([cin\\_ctl\\_t](#) \*cin, int val)
- int [cin\\_ctl\\_get\\_bias](#) ([cin\\_ctl\\_t](#) \*cin, int \*val)
- int [cin\\_ctl\\_set\\_clocks](#) ([cin\\_ctl\\_t](#) \*cin, int val)
- int [cin\\_ctl\\_get\\_clocks](#) ([cin\\_ctl\\_t](#) \*cin, int \*val)
- int [cin\\_ctl\\_set\\_trigger](#) ([cin\\_ctl\\_t](#) \*cin, int val)
- int [cin\\_ctl\\_get\\_trigger](#) ([cin\\_ctl\\_t](#) \*cin, int \*val)
- int [cin\\_ctl\\_set\\_focus](#) ([cin\\_ctl\\_t](#) \*cin, int val)

- int **cin\_ctl\_get\_focus** ([cin\\_ctl\\_t](#) \*cin, int \*val)
- int **cin\_ctl\_get\_triggering** ([cin\\_ctl\\_t](#) \*cin, int \*trigger)
- int **cin\_ctl\_int\_trigger\_start** ([cin\\_ctl\\_t](#) \*cin, int nimages)
- int **cin\_ctl\_int\_trigger\_stop** ([cin\\_ctl\\_t](#) \*cin)
- int **cin\_ctl\_ext\_trigger\_start** ([cin\\_ctl\\_t](#) \*cin, int trigger\_mode)
- int **cin\_ctl\_ext\_trigger\_stop** ([cin\\_ctl\\_t](#) \*cin)
- int **cin\_ctl\_set\_exposure\_time** ([cin\\_ctl\\_t](#) \*cin, float e\_time)
- int **cin\_ctl\_set\_trigger\_delay** ([cin\\_ctl\\_t](#) \*cin, float t\_time)
- int **cin\_ctl\_set\_cycle\_time** ([cin\\_ctl\\_t](#) \*cin, float ftime)
- int **cin\_ctl\_frame\_count\_reset** ([cin\\_ctl\\_t](#) \*cin)
- int **cin\_ctl\_set\_mux** ([cin\\_ctl\\_t](#) \*cin, int setting)
- int **cin\_ctl\_get\_mux** ([cin\\_ctl\\_t](#) \*cin, int \*setting)
- int **cin\_ctl\_set\_fcric\_gain** ([cin\\_ctl\\_t](#) \*cin, int gain)
- int **cin\_ctl\_set\_fabric\_address** ([cin\\_ctl\\_t](#) \*cin, char \*ip)
- int **cin\_ctl\_reg\_dump** ([cin\\_ctl\\_t](#) \*cin, FILE \*fp)
- int **cin\_ctl\_get\_bias\_voltages** ([cin\\_ctl\\_t](#) \*cin, float \*voltage)
- int **cin\_ctl\_set\_bias\_voltages** ([cin\\_ctl\\_t](#) \*cin, float \*voltage)
- int **cin\_ctl\_set\_fcric\_clamp** ([cin\\_ctl\\_t](#) \*cin, int clamp)

#### 4.1.1 Detailed Description

#### 4.1.2 Function Documentation

##### 4.1.2.1 int cin\_ctl\_destroy ( [cin\\_ctl\\_t](#) \* cin )

Destroy (close) the cin control library

Close connections, free memory and exit library

Parameters

<i>cin</i>	handle to cin library
------------	-----------------------

Returns

Returns 0 on success non-zero if error

##### 4.1.2.2 int cin\_ctl\_init ( [cin\\_ctl\\_t](#) \* cin, const char \* *ipaddr*, [uint16\\_t](#) *oport*, [uint16\\_t](#) *iport*, [uint16\\_t](#) *soport*, [uint16\\_t](#) *siport* )

Initialize the cin control library

Initialize the control structures and communications with the CIN via the control interface. This function opens the UDP ports and starts a listening thread to receive packets from the CIN.

Parameters

<i>cin</i>	handle to cin library
<i>ipaddr</i>	ip address of CIN base address
<i>oport</i>	output udp port of cin
<i>iport</i>	input udp port of cin
<i>soport</i>	stream output udp port of cin
<i>siport</i>	stream input udp port of cin

Returns

Returns 0 on success non-zero if error

4.1.2.3 `int cin_ctl_read ( cin_ctl_t * cin, uint16_t reg, uint16_t * val )`

Read register from CIN

**Parameters**

<i>cin</i>	handle to cin library
<i>reg</i>	register to read
<i>val</i>	variable to read value of register to

**Returns**

Returns 0 on success non-zero if error

**4.1.2.4 int cin\_ctl\_stream\_write ( cin\_ctl\_t \* cin, char \* val, int size )**

Write stream data to CIN

**Parameters**

<i>cin</i>	handle to cin library
<i>val</i>	array of values to write
<i>size</i>	size of array pointed to by val

Write stream data to cin in form of 16 bit array.

**Returns**

Returns 0 on success non-zero if error

**4.1.2.5 int cin\_ctl\_write ( cin\_ctl\_t \* cin, uint16\_t reg, uint16\_t val, int wait )**

Write register to CIN

**Parameters**

<i>cin</i>	handle to cin library
<i>reg</i>	register to write to
<i>val</i>	value to write to register
<i>wait</i>	if non-zero

Write register value to CIN. If wait is non-zero then wait a sleep time of i CIN\_CTL\_WRITE\_SLEEP before releasing the mutex to add flow control to the cin.

**Returns**

Returns 0 on success non-zero if error

**4.1.2.6 int cin\_ctl\_write\_with\_readback ( cin\_ctl\_t \* cin, uint16\_t reg, uint16\_t val )**

Write register to CIN with readback verification

**Parameters**

<i>cin</i>	handle to cin library
<i>reg</i>	register to write to
<i>val</i>	value to write to register

Write register value to CIN. Follow write with read of register and compare value. CIN\_CTL\_WRITE\_SLEEP before releasing the mutex to add flow control to the cin.

**Returns**

Returns 0 on success non-zero if error

## 4.2 CIN Data Framestore Functions

### Functions

- void [cin\\_data\\_framestore\\_trigger](#) ([cin\\_data\\_t](#) \*cin, int count)
- void [cin\\_data\\_framestore\\_skip](#) ([cin\\_data\\_t](#) \*cin, int count)
- int [cin\\_data\\_get\\_framestore\\_counter](#) ([cin\\_data\\_t](#) \*cin)
- void [cin\\_data\\_framestore\\_disable](#) ([cin\\_data\\_t](#) \*cin)
- void [cin\\_data\\_framestore\\_trigger\\_enable](#) ([cin\\_data\\_t](#) \*cin)

### 4.2.1 Detailed Description

Framestore Group

### 4.2.2 Function Documentation

#### 4.2.2.1 void [cin\\_data\\_framestore\\_disable](#) ( [cin\\_data\\_t](#) \* *cin* )

Disable the framestore modes

This function disables the framestore modes (software trigger and skip). If the camera is hardware triggering then the images will start to be processed.

Parameters

<i>cin</i>	Handle to the cin library
------------	---------------------------

#### 4.2.2.2 void [cin\\_data\\_framestore\\_skip](#) ( [cin\\_data\\_t](#) \* *cin*, int *count* )

Enable framestore skip mode

Enable the framestore skip mode. This function should be called before hardware triggering the camera. This causes the data processing to skip

Parameters

<i>count</i>	frames from the first images to be read. This is usually done to stop the first few frames from being over exposed.
<i>cin</i>	handle to the <a href="#">cin_data</a> library

#### 4.2.2.3 void [cin\\_data\\_framestore\\_trigger](#) ( [cin\\_data\\_t](#) \* *cin*, int *count* )

Send a framestore (software) trigger

Send a software trigger to the CIN by timestamping the request time and allow images to be processed when recieved after this time. The count option sets the number of frames to trigger. A value of -1 indicated that the trigger should not count images but run indefinately after the trigger has occurred.

Parameters

<i>cin</i>	handle to the <a href="#">cin_data</a> library
<i>count</i>	number of frames to trigger

#### 4.2.2.4 void [cin\\_data\\_framestore\\_trigger\\_enable](#) ( [cin\\_data\\_t](#) \* *cin* )

Enable the framestore trigger mode

This function enables the framestore trigger mode. It cases the images to not be processed pending a call to the function to (software) trigger the camera.

**Parameters**

<i>cin</i>	Handle to the cin library
------------	---------------------------

**4.2.2.5 int cin\_data\_get\_framestore\_counter ( cin\_data\_t \* cin )**

Get the value of the framestore counter

Return the number of frames in the framestore counter. In trigger mode, this returns the number of frames to go. In skip mode, this returns the number of frames that have to be skipped.

**Parameters**

<i>cin</i>	handle to the <a href="#">cin_data</a> library
------------	--

**Returns**

Number of frames to go in trigger



## Chapter 5

# Class Documentation

### 5.1 cin\_ctl Struct Reference

#### Public Attributes

- [cin\\_port\\_t](#) **ctl\_port**
- [cin\\_port\\_t](#) **stream\_port**
- [cin\\_ctl\\_config\\_t](#) **config**
- [cin\\_ctl\\_listener\\_t](#) \* **listener**
- [pthread\\_mutex\\_t](#) **access**
- [pthread\\_mutexattr\\_t](#) **access\_attr**

The documentation for this struct was generated from the following file:

- [src/cin.h](#)

### 5.2 cin\_ctl\_config Struct Reference

#### Public Attributes

- char **name** [CIN\_CONFIG\_MAX\_STRING]
- char **firmware\_filename** [CIN\_CONFIG\_MAX\_STRING]
- int **overscan**
- int **columns**
- int **fclk**
- uint16\_t **timing** [CIN\_CONFIG\_MAX\_DATA][2]
- int **timing\_len**
- uint16\_t **fcric** [CIN\_CONFIG\_MAX\_DATA][2]
- int **fcric\_len**
- uint16\_t **bias** [CIN\_CONFIG\_MAX\_DATA][2]
- int **bias\_len**

The documentation for this struct was generated from the following file:

- [src/cin.h](#)

## 5.3 cin\_ctl\_id Struct Reference

### Public Attributes

- uint16\_t **board\_id**
- uint16\_t **serial\_no**
- uint16\_t **fpga\_ver**

The documentation for this struct was generated from the following file:

- src/[cin.h](#)

## 5.4 cin\_ctl\_listener Struct Reference

### Public Attributes

- struct [cin\\_port](#) \* **cp**
- [fifo](#) **ctl\_fifo**
- pthread\_t **thread\_id**

The documentation for this struct was generated from the following file:

- src/[cin.h](#)

## 5.5 cin\_ctl\_pwr\_mon\_t Struct Reference

### Public Attributes

- [cin\\_ctl\\_pwr\\_val\\_t](#) **bus\_12v0**
- [cin\\_ctl\\_pwr\\_val\\_t](#) **mgmt\_3v3**
- [cin\\_ctl\\_pwr\\_val\\_t](#) **mgmt\_2v5**
- [cin\\_ctl\\_pwr\\_val\\_t](#) **mgmt\_1v2**
- [cin\\_ctl\\_pwr\\_val\\_t](#) **enet\_1v0**
- [cin\\_ctl\\_pwr\\_val\\_t](#) **s3e\_3v3**
- [cin\\_ctl\\_pwr\\_val\\_t](#) **gen\_3v3**
- [cin\\_ctl\\_pwr\\_val\\_t](#) **gen\_2v5**
- [cin\\_ctl\\_pwr\\_val\\_t](#) **v6\_0v9**
- [cin\\_ctl\\_pwr\\_val\\_t](#) **v6\_1v0**
- [cin\\_ctl\\_pwr\\_val\\_t](#) **v6\_2v5**
- [cin\\_ctl\\_pwr\\_val\\_t](#) **fp**

The documentation for this struct was generated from the following file:

- src/[cin.h](#)

## 5.6 cin\_ctl\_pwr\_val Struct Reference

### Public Attributes

- double **i**

- double **v**

The documentation for this struct was generated from the following file:

- [src/cin.h](#)

## 5.7 cin\_data Struct Reference

### Public Attributes

- [fifo](#) \* **packet\_fifo**
- [fifo](#) \* **frame\_fifo**
- [fifo](#) \* **image\_fifo**
- [cin\\_data\\_threads\\_t](#) **listen\_thread**
- [cin\\_data\\_threads\\_t](#) **assembler\_thread**
- [cin\\_data\\_threads\\_t](#) **descramble\_thread**
- pthread\_mutex\_t **listen\_mutex**
- pthread\_mutex\_t **assembler\_mutex**
- pthread\_mutex\_t **descramble\_mutex**
- pthread\_mutex\_t **stats\_mutex**
- pthread\_mutex\_t **framestore\_mutex**
- [cin\\_data\\_callbacks\\_t](#) **callbacks**
- [cin\\_port\\_t](#) **dp**
- struct timespec **framerate**
- unsigned long int **dropped\_packets**
- unsigned long int **malformed\_packets**
- uint16\_t **last\_frame**
- [descramble\\_map\\_t](#) **map**
- int **framestore\_mode**
- struct timespec **framestore\_trigger**
- int **framestore\_counter**

The documentation for this struct was generated from the following file:

- [src/cin.h](#)

## 5.8 cin\_data\_callbacks Struct Reference

### Public Attributes

- void (\*)(**push**)([cin\\_data\\_frame\\_t](#) \*)
- void (\*)(**pop**)([cin\\_data\\_frame\\_t](#) \*)
- [cin\\_data\\_frame\\_t](#) \* **frame**

The documentation for this struct was generated from the following file:

- [src/cin.h](#)

## 5.9 cin\_data\_frame Struct Reference

### Public Attributes

- uint16\_t \* **data**
- uint16\_t **number**
- struct timespec **timestamp**
- int **size\_x**
- int **size\_y**
- void \* **usr\_ptr**

The documentation for this struct was generated from the following file:

- [src/cin.h](#)

## 5.10 cin\_data\_packet Struct Reference

### Public Attributes

- unsigned char \* **data**
- int **size**
- struct timespec **timestamp**

The documentation for this struct was generated from the following file:

- [src/data.h](#)

## 5.11 cin\_data\_proc Struct Reference

### Public Attributes

- void \*(\* **input\_get** )(void \*, int)
- void \*(\* **input\_put** )(void \*, int)
- void \* **input\_args**
- int **reader**
- void \*(\* **output\_put** )(void \*)
- void \*(\* **output\_get** )(void \*)
- void \* **output\_args**
- [cin\\_data\\_t](#) \* **parent**

The documentation for this struct was generated from the following file:

- [src/data.h](#)

## 5.12 cin\_data\_stats Struct Reference

### Public Attributes

- int **last\_frame**
- double **framerate**

- double **datarate**
- double **packet\_percent\_full**
- double **frame\_percent\_full**
- double **image\_percent\_full**
- long int **packet\_overruns**
- long int **frame\_overruns**
- long int **image\_overruns**
- long int **packet\_used**
- long int **frame\_used**
- long int **image\_used**
- long int **dropped\_packets**
- long int **mallformed\_packets**

The documentation for this struct was generated from the following file:

- [src/cin.h](#)

## 5.13 cin\_data\_threads Struct Reference

### Public Attributes

- pthread\_t **thread\_id**
- int **started**

The documentation for this struct was generated from the following file:

- [src/cin.h](#)

## 5.14 cin\_map\_t Struct Reference

### Public Attributes

- char \* **name**
- uint16\_t **reg**

The documentation for this struct was generated from the following file:

- [src/cinregisters.h](#)

## 5.15 cin\_port Struct Reference

### Public Attributes

- char \* **srvaddr**
- char \* **cliaddr**
- uint16\_t **srvport**
- uint16\_t **cliport**
- int **sockfd**
- struct timeval **tv**
- struct sockaddr\_in **sin\_srv**
- struct sockaddr\_in **sin\_cli**

- socklen\_t **slen**
- int **rcvbuf**
- int **rcvbuf\_rb**

The documentation for this struct was generated from the following file:

- src/[cin.h](#)

## 5.16 descramble\_map\_t Struct Reference

### Public Attributes

- uint32\_t \* **map**
- int **size\_x**
- int **size\_y**
- int **overscan**
- int **rows**

The documentation for this struct was generated from the following file:

- src/[cin.h](#)

## 5.17 fifo Struct Reference

### Public Attributes

- void \* **data**
- void \* **head**
- void \* **tail** [FIFO\_MAX\_READERS]
- void \* **end**
- int **readers**
- long int **size**
- int **elem\_size**
- int **full**
- long int **overruns**
- pthread\_mutex\_t **mutex**
- pthread\_cond\_t **signal**

The documentation for this struct was generated from the following file:

- src/[cin.h](#)

## Chapter 6

# File Documentation

### 6.1 src/cin.h File Reference

```
#include <stdint.h>
#include <stdio.h>
#include <sys/socket.h>
#include <netinet/in.h>
#include <netinet/ip.h>
#include <sys/time.h>
#include <pthread.h>
```

#### Classes

- struct [cin\\_ctl\\_config](#)
- struct [fifo](#)
- struct [cin\\_ctl\\_listener](#)
- struct [cin\\_port](#)
- struct [cin\\_ctl](#)
- struct [cin\\_data\\_frame](#)
- struct [cin\\_data\\_stats](#)
- struct [cin\\_data\\_threads](#)
- struct [cin\\_data\\_callbacks](#)
- struct [descramble\\_map\\_t](#)
- struct [cin\\_data](#)
- struct [cin\\_ctl\\_id](#)
- struct [cin\\_ctl\\_pwr\\_val](#)
- struct [cin\\_ctl\\_pwr\\_mon\\_t](#)

#### Macros

- `#define CIN_CTL_IP "192.168.1.207"`
- `#define CIN_CTL_SVR_PORT 49200`
- `#define CIN_CTL_CLI_PORT 50200`
- `#define CIN_CTL_SVR_FRMW_PORT 49202`
- `#define CIN_CTL_CLI_FRMW_PORT 50202`
- `#define CIN_CTL_MAX_READ_TRIES 10`
- `#define CIN_CTL_MAX_WRITE_TRIES 5`
- `#define CIN_CTL_WRITE_SLEEP 2000`

- #define **CIN\_CTL\_POWER\_ENABLE** 0x001F
- #define **CIN\_CTL\_POWER\_DISABLE** 0x0000
- #define **CIN\_CTL\_FP\_POWER\_ENABLE** 0x0020
- #define **CIN\_CTL\_DCM\_LOCKED** 0x0001
- #define **CIN\_CTL\_DCM\_PSDONE** 0x0002
- #define **CIN\_CTL\_DCM\_STATUS0** 0x0004
- #define **CIN\_CTL\_DCM\_STATUS1** 0x0008
- #define **CIN\_CTL\_DCM\_STATUS2** 0x0010
- #define **CIN\_CTL\_DCM\_TX1\_READY** 0x0020
- #define **CIN\_CTL\_DCM\_TX2\_READY** 0x0040
- #define **CIN\_CTL\_DCM\_ATCA\_ALARM** 0x0080
- #define **CIN\_CTL\_TRIG\_INTERNAL** 0x0000
- #define **CIN\_CTL\_TRIG\_EXTERNAL\_1** 0x0001
- #define **CIN\_CTL\_TRIG\_EXTERNAL\_2** 0x0002
- #define **CIN\_CTL\_TRIG\_EXTERNAL\_BOTH** 0x0003
- #define **CIN\_CTL\_FOCUS\_BIT** 0x0002
- #define **CIN\_CTL\_FCLK\_125** 0x0000
- #define **CIN\_CTL\_FCLK\_200** 0x0001
- #define **CIN\_CTL\_FCLK\_250** 0x0002
- #define **CIN\_CTL\_FCLK\_125\_C** 0x0003
- #define **CIN\_CTL\_FCLK\_200\_C** 0x0004
- #define **CIN\_CTL\_FCLK\_250\_C** 0x0005
- #define **CIN\_CTL\_FCLK\_156\_C** 0x0006
- #define **CIN\_CTL\_FPGA\_STS\_CFG** 0x8000
- #define **CIN\_CTL\_FPGA\_STS\_FP\_PWR** 0x0008
- #define **CIN\_CTL\_DCM\_STS\_ATCA** 0x0080
- #define **CIN\_CTL\_DCM\_STS\_LOCKED** 0x0001
- #define **CIN\_CTL\_DCM\_STS\_OVERRIDE** 0x0800
- #define **CIN\_CTL\_MUX1\_VCLK1** 0x0001
- #define **CIN\_CTL\_MUX1\_VCLK2** 0x0002
- #define **CIN\_CTL\_MUX1\_VCLK3** 0x0003
- #define **CIN\_CTL\_MUX1\_ATG** 0x0004
- #define **CIN\_CTL\_MUX1\_VFCLK1** 0x0005
- #define **CIN\_CTL\_MUX1\_VFCLK2** 0x0006
- #define **CIN\_CTL\_MUX1\_VFCLK3** 0x0007
- #define **CIN\_CTL\_MUX1\_HCLK1** 0x0008
- #define **CIN\_CTL\_MUX1\_HCLK2** 0x0009
- #define **CIN\_CTL\_MUX1\_OSW** 0x000A
- #define **CIN\_CTL\_MUX1\_RST** 0x000B
- #define **CIN\_CTL\_MUX1\_CONVERT** 0x000C
- #define **CIN\_CTL\_MUX1\_SHUTTER** 0x000D
- #define **CIN\_CTL\_MUX1\_SWTRIGGER** 0x000E
- #define **CIN\_CTL\_MUX1\_TRIGMON** 0x000F
- #define **CIN\_CTL\_MUX1\_EXPOSE** 0x0000
- #define **CIN\_CTL\_MUX2\_VCLK1** 0x0010
- #define **CIN\_CTL\_MUX2\_VCLK2** 0x0020
- #define **CIN\_CTL\_MUX2\_VCLK3** 0x0030
- #define **CIN\_CTL\_MUX2\_ATG** 0x0040
- #define **CIN\_CTL\_MUX2\_VFCLK1** 0x0050
- #define **CIN\_CTL\_MUX2\_VFCLK2** 0x0060
- #define **CIN\_CTL\_MUX2\_VFCLK3** 0x0070
- #define **CIN\_CTL\_MUX2\_HCLK1** 0x0080
- #define **CIN\_CTL\_MUX2\_HCLK2** 0x0090
- #define **CIN\_CTL\_MUX2\_HCLK3** 0x00A0
- #define **CIN\_CTL\_MUX2\_OSW** 0x00B0



- #define **CIN\_CTL\_MUX2\_RST** 0x00C0
- #define **CIN\_CTL\_MUX2\_CONVERT** 0x00D0
- #define **CIN\_CTL\_MUX2\_SAVE** 0x00E0
- #define **CIN\_CTL\_MUX2\_HWTRIG** 0x00F0
- #define **CIN\_CTL\_MUX2\_EXPOSE** 0x0000
- #define **CIN\_CTL\_FO\_REG1** 0x821D
- #define **CIN\_CTL\_FO\_REG2** 0x821E
- #define **CIN\_CTL\_FO\_REG3** 0x821F
- #define **CIN\_CTL\_FO\_REG4** 0x8001
- #define **CIN\_CTL\_FO\_REG5** 0x8211
- #define **CIN\_CTL\_FO\_REG6** 0x8212
- #define **CIN\_CTL\_FO\_REG7** 0x8213
- #define **CIN\_DATA\_IP** "10.0.5.207"
- #define **CIN\_DATA\_PORT** 49201
- #define **CIN\_DATA\_CTL\_PORT** 49203
- #define **CIN\_DATA\_MAX\_MTU** 9000
- #define **CIN\_DATA\_UDP\_HEADER** 8
- #define **CIN\_DATA\_MAGIC\_PACKET** UINT64\_C(0x0000F4F3F2F1F000)
- #define **CIN\_DATA\_MAGIC\_PACKET\_MASK** UINT64\_C(0x0000FFFFFFFFFFFF00)
- #define **CIN\_DATA\_TAIL\_MAGIC\_PACKET** UINT64\_C(0x010DF0ADDEF2F1F0)
- #define **CIN\_DATA\_TAIL\_MAGIC\_PACKET\_MASK** UINT64\_C(0xFFFFFFFFFFFFFFF0)
- #define **CIN\_DATA\_DROPPED\_PACKET\_VAL** 0x2000
- #define **CIN\_DATA\_DATA\_MASK** 0x1FFF
- #define **CIN\_DATA\_CTRL\_MASK** 0xE000
- #define **CIN\_DATA\_SIGN\_MASK** 0x1000
- #define **CIN\_DATA\_GAIN\_8** 0xC000
- #define **CIN\_DATA\_GAIN\_4** 0x4000
- #define **CIN\_DATA\_PACKET\_LEN** 8184
- #define **CIN\_DATA\_MAX\_PACKETS** 542
- #define **CIN\_DATA\_RCVBUF** 100
- #define **CIN\_DATA\_MAX\_FRAME\_X** 1152
- #define **CIN\_DATA\_MAX\_FRAME\_Y** 2050
- #define **CIN\_DATA\_MAX\_STREAM** 2400000
- #define **CIN\_DATA\_CCD\_COLS** 96
- #define **CIN\_DATA\_CCD\_COLS\_PER\_CHAN** 10
- #define **CIN\_DATA\_PIPELINE\_FLUSH** 1344
- #define **CIN\_DATA\_MODE\_CALLBACK** 0x01
- #define **NUM\_BIAS\_VOLTAGE** 20
- #define **pt\_posH** 0
- #define **pt\_negH** 1
- #define **pt\_posRG** 2
- #define **pt\_negRG** 3
- #define **pt\_posSW** 4
- #define **pt\_negSW** 5
- #define **pt\_posV** 6
- #define **pt\_negV** 7
- #define **pt\_posTG** 8
- #define **pt\_negTG** 9
- #define **pt\_posVF** 10
- #define **pt\_negVF** 11
- #define **pt\_NEDGE** 12
- #define **pt\_OTG** 13
- #define **pt\_VDDR** 14
- #define **pt\_VDD\_OUT** 15
- #define **pt\_BUF\_Base** 16

- `#define pt_BUF_Delta 17`
- `#define pt_Spare1 18`
- `#define pt_Spare2 19`
- `#define DEBUG_PRINT(fmt,...) if(_debug_print_flag) { fprintf(stderr, "%s:%d:%s(): " fmt, __FILE__, __LINE__, __func__, __VA_ARGS__); }`
- `#define DEBUG_COMMENT(fmt) if(_debug_print_flag) { fprintf(stderr, "%s:%d:%s(): " fmt, __FILE__, __LINE__, __func__); }`
- `#define ERROR_COMMENT(fmt) if(_error_print_flag) { fprintf(stderr, "%s:%d:%s(): " fmt, __FILE__, __LINE__, __func__); }`
- `#define ERROR_PRINT(fmt,...) if(_error_print_flag) { fprintf(stderr, "%s:%d:%s(): " fmt, __FILE__, __LINE__, __func__, __VA_ARGS__); }`
- `#define CIN_CONFIG_MAX_STRING 256`
- `#define CIN_CONFIG_MAX_DATA 5000`
- `#define FIFO_MAX_READERS 10`

## Typedefs

- typedef struct [cin\\_ctl\\_config](#) [cin\\_ctl\\_config\\_t](#)
- typedef struct [cin\\_ctl\\_listener](#) [cin\\_ctl\\_listener\\_t](#)
- typedef struct [cin\\_port](#) [cin\\_port\\_t](#)
- typedef struct [cin\\_ctl](#) [cin\\_ctl\\_t](#)
- typedef struct [cin\\_data\\_frame](#) [cin\\_data\\_frame\\_t](#)
- typedef struct [cin\\_data\\_stats](#) [cin\\_data\\_stats\\_t](#)
- typedef struct [cin\\_data\\_threads](#) [cin\\_data\\_threads\\_t](#)
- typedef struct [cin\\_data\\_callbacks](#) [cin\\_data\\_callbacks\\_t](#)
- typedef struct [cin\\_data](#) [cin\\_data\\_t](#)
- typedef void(\* [cin\\_data\\_callback](#))([cin\\_data\\_frame\\_t](#) \*)
- typedef struct [cin\\_ctl\\_id](#) [cin\\_ctl\\_id\\_t](#)
- typedef struct [cin\\_ctl\\_pwr\\_val](#) [cin\\_ctl\\_pwr\\_val\\_t](#)

## Functions

- void [cin\\_set\\_debug\\_print](#) (int debug)
- void [cin\\_set\\_error\\_print](#) (int error)
- void [cin\\_report](#) (FILE \*fp, int details)
- int [cin\\_ctl\\_init](#) ([cin\\_ctl\\_t](#) \*cin, const char \*ipaddr, uint16\_t oport, uint16\_t iport, uint16\_t soport, uint16\_t siport)
- int [cin\\_ctl\\_destroy](#) ([cin\\_ctl\\_t](#) \*cin)
- int [cin\\_ctl\\_read](#) ([cin\\_ctl\\_t](#) \*cin, uint16\_t reg, uint16\_t \*val)
- int [cin\\_ctl\\_write](#) ([cin\\_ctl\\_t](#) \*cin, uint16\_t reg, uint16\_t val, int wait)
- int [cin\\_ctl\\_stream\\_write](#) ([cin\\_ctl\\_t](#) \*cin, char \*val, int size)
- int [cin\\_ctl\\_write\\_with\\_readback](#) ([cin\\_ctl\\_t](#) \*cin, uint16\_t reg, uint16\_t val)
- int [cin\\_ctl\\_pwr](#) ([cin\\_ctl\\_t](#) \*cin, int pwr)
- int [cin\\_ctl\\_fp\\_pwr](#) ([cin\\_ctl\\_t](#) \*cin, int pwr)
- int [cin\\_ctl\\_fo\\_test\\_pattern](#) ([cin\\_ctl\\_t](#) \*cin, int on\_off)
- int [cin\\_ctl\\_load\\_config](#) ([cin\\_ctl\\_t](#) \*cin, char \*filename)
- int [cin\\_ctl\\_load\\_firmware](#) ([cin\\_ctl\\_t](#) \*cin, char \*filename)
- int [cin\\_ctl\\_set\\_fclk](#) ([cin\\_ctl\\_t](#) \*cin, int clkfreq)
- int [cin\\_ctl\\_get\\_fclk](#) ([cin\\_ctl\\_t](#) \*cin, int \*clkfreq)
- int [cin\\_ctl\\_freeze\\_dco](#) ([cin\\_ctl\\_t](#) \*cin, int freeze)
- int [cin\\_ctl\\_get\\_cfg\\_fpga\\_status](#) ([cin\\_ctl\\_t](#) \*cin, uint16\_t \* \_val)
- int [cin\\_ctl\\_get\\_id](#) ([cin\\_ctl\\_t](#) \*cin, [cin\\_ctl\\_id\\_t](#) \* \_val)
- void [cin\\_ctl\\_display\\_id](#) (FILE \*out, [cin\\_ctl\\_id\\_t](#) val)
- void [cin\\_ctl\\_display\\_fpga\\_status](#) (FILE \*out, uint16\_t val)

- int **cin\_ctl\_get\_dcm\_status** ([cin\\_ctl\\_t](#) \*cin, uint16\_t \*\_val)
- void **cin\_ctl\_display\_dcm\_status** (FILE \*out, uint16\_t \*\_val)
- double **cin\_ctl\_current\_calc** (uint16\_t val)
- int **cin\_ctl\_get\_power\_status** ([cin\\_ctl\\_t](#) \*cin, int full, int \*pwr, [cin\\_ctl\\_pwr\\_mon\\_t](#) \*values)
- void **cin\_ctl\_display\_pwr** (FILE \*out, [cin\\_ctl\\_pwr\\_mon\\_t](#) \*values)
- void **cin\_ctl\_display\_pwr\_line** (FILE \*out, const char \*msg, [cin\\_ctl\\_pwr\\_val\\_t](#) val)
- int **cin\_ctl\_calc\_vi\_status** ([cin\\_ctl\\_t](#) \*cin, uint16\_t vreg, uint16\_t ireg, double vfact, [cin\\_ctl\\_pwr\\_val\\_t](#) \*vi)
- int **cin\_ctl\_get\_camera\_pwr** ([cin\\_ctl\\_t](#) \*cin, int \*val)
- int **cin\_ctl\_set\_camera\_pwr** ([cin\\_ctl\\_t](#) \*cin, int val)
- int **cin\_ctl\_set\_bias** ([cin\\_ctl\\_t](#) \*cin, int val)
- int **cin\_ctl\_get\_bias** ([cin\\_ctl\\_t](#) \*cin, int \*val)
- int **cin\_ctl\_set\_clocks** ([cin\\_ctl\\_t](#) \*cin, int val)
- int **cin\_ctl\_get\_clocks** ([cin\\_ctl\\_t](#) \*cin, int \*val)
- int **cin\_ctl\_set\_trigger** ([cin\\_ctl\\_t](#) \*cin, int val)
- int **cin\_ctl\_get\_trigger** ([cin\\_ctl\\_t](#) \*cin, int \*val)
- int **cin\_ctl\_set\_focus** ([cin\\_ctl\\_t](#) \*cin, int val)
- int **cin\_ctl\_get\_focus** ([cin\\_ctl\\_t](#) \*cin, int \*val)
- int **cin\_ctl\_get\_triggering** ([cin\\_ctl\\_t](#) \*cin, int \*trigger)
- int **cin\_ctl\_int\_trigger\_start** ([cin\\_ctl\\_t](#) \*cin, int nimages)
- int **cin\_ctl\_int\_trigger\_stop** ([cin\\_ctl\\_t](#) \*cin)
- int **cin\_ctl\_ext\_trigger\_start** ([cin\\_ctl\\_t](#) \*cin, int trigger\_mode)
- int **cin\_ctl\_ext\_trigger\_stop** ([cin\\_ctl\\_t](#) \*cin)
- int **cin\_ctl\_set\_exposure\_time** ([cin\\_ctl\\_t](#) \*cin, float e\_time)
- int **cin\_ctl\_set\_trigger\_delay** ([cin\\_ctl\\_t](#) \*cin, float t\_time)
- int **cin\_ctl\_set\_cycle\_time** ([cin\\_ctl\\_t](#) \*cin, float ftime)
- int **cin\_ctl\_frame\_count\_reset** ([cin\\_ctl\\_t](#) \*cin)
- int **cin\_ctl\_set\_mux** ([cin\\_ctl\\_t](#) \*cin, int setting)
- int **cin\_ctl\_get\_mux** ([cin\\_ctl\\_t](#) \*cin, int \*setting)
- int **cin\_ctl\_set\_fcric\_gain** ([cin\\_ctl\\_t](#) \*cin, int gain)
- int **cin\_ctl\_set\_fabric\_address** ([cin\\_ctl\\_t](#) \*cin, char \*ip)
- int **cin\_ctl\_reg\_dump** ([cin\\_ctl\\_t](#) \*cin, FILE \*fp)
- int **cin\_ctl\_get\_bias\_voltages** ([cin\\_ctl\\_t](#) \*cin, float \*voltage)
- int **cin\_ctl\_set\_bias\_voltages** ([cin\\_ctl\\_t](#) \*cin, float \*voltage)
- int **cin\_ctl\_set\_fcric\_clamp** ([cin\\_ctl\\_t](#) \*cin, int clamp)
- int **cin\_config\_read\_file** ([cin\\_ctl\\_t](#) \*cin, const char \*file)
- int **cin\_data\_init** ([cin\\_data\\_t](#) \*cin, int mode, int packet\_buffer\_len, int frame\_buffer\_len, char \*ipaddr, uint16\_t port, char \*cin\_ipaddr, uint16\_t [cin\\_port](#), int rcvbuf, cin\_data\_callback push\_callback, cin\_data\_callback pop\_callback, void \*usr\_ptr)
- void **cin\_data\_wait\_for\_threads** ([cin\\_data\\_t](#) \*cin)
- void **cin\_data\_stop\_threads** ([cin\\_data\\_t](#) \*cin)
- void **cin\_data\_framestore\_trigger** ([cin\\_data\\_t](#) \*cin, int count)
- void **cin\_data\_framestore\_skip** ([cin\\_data\\_t](#) \*cin, int count)
- int **cin\_data\_get\_framestore\_counter** ([cin\\_data\\_t](#) \*cin)
- void **cin\_data\_framestore\_disable** ([cin\\_data\\_t](#) \*cin)
- void **cin\_data\_framestore\_trigger\_enable** ([cin\\_data\\_t](#) \*cin)
- struct [cin\\_data\\_frame](#) \* **cin\_data\_get\_next\_frame** ([cin\\_data\\_t](#) \*cin)
- void **cin\_data\_release\_frame** ([cin\\_data\\_t](#) \*cin, int free\_mem)
- struct [cin\\_data\\_frame](#) \* **cin\_data\_get\_buffered\_frame** (void)
- void **cin\_data\_release\_buffered\_frame** (void)
- void **cin\_data\_compute\_stats** ([cin\\_data\\_t](#) \*cin, [cin\\_data\\_stats\\_t](#) \*stats)
- void **cin\_data\_show\_stats** (FILE \*fp, [cin\\_data\\_stats\\_t](#) stats)
- void **cin\_data\_reset\_stats** ([cin\\_data\\_t](#) \*cin)
- int **cin\_data\_set\_descramble\_params** ([cin\\_data\\_t](#) \*cin, int rows, int overscan)
- void **cin\_data\_get\_descramble\_params** ([cin\\_data\\_t](#) \*cin, int \*rows, int \*overscan, int \*xsize, int \*ysize)

## Variables

- const char \* **cin\_build\_git\_time**
- const char \* **cin\_build\_git\_sha**
- const char \* **cin\_build\_version**
- int **\_debug\_print\_flag**
- int **\_error\_print\_flag**

### 6.1.1 Detailed Description

#### Author

Stuart B. Wilkins [swilkins@bnl.gov](mailto:swilkins@bnl.gov)

### 6.1.2 LICENSE

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### 6.1.3 DESCRIPTION

header file for CIN communications

### 6.1.4 Function Documentation

**6.1.4.1** `int cin_data_init ( cin_data_t * cin, int mode, int packet_buffer_len, int frame_buffer_len, char * ipaddr, uint16_t port, char * cin_ipaddr, uint16_t cin_port, int rcvbuf, cin_data_callback push_callback, cin_data_callback pop_callback, void * usr_ptr )`

Initialize the cin data library

Initialize the data handling routines and start the threads for listening. mode should be set for the desired output. The packet\_buffer\_len is the length of the packet FIFO in number of packets. The frame\_buffer\_len is the number of data frames to buffer.

## Parameters

<i>cin</i>	Handle to cin data library
------------	----------------------------

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