

libcin

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# Chapter 1

## FastCCD Communication Library (libcin)

### Introduction

This library, based in C is designed to control the FastCCD detector from Lawrence Berkeley National Laboratory. It controls both camera control functions and data acquisition (frame acquisition). It is separated into two distinct parts, the control part ,`cin_ctl`, and the data (image) part named `cin_data`. It was written in part for use with `areaDetector`.

### Prerequisites

The library relies on the following:

- `libbsd` (Used for string manipulation)
- `libconfig` (Used for nice config files)
- `libpthread` (Used for threading)
- `librt` (Used for time functions)

### Installation

Installation of the library is like most unix based source packages:

```
./make
./make doc
./make test
./make install
```

## TCP/IP Stack Tuning

In order for the CIN data to operate efficiently, the 10G interface on the host computer needs to be tuned. This needs to be done by adding the following to the file `/etc/sysctl.conf`.

```
# Increase the maximum buffer that user programs can request
# 2147483647 = 2048 Mb
net.core.rmem_max=2147483647
net.core.wmem_max=2147483647
# Set a default value 10 times bigger
net.core.rmem_default=1000000
net.core.wmem_default=1000000
# increase the length of the processor input queue
net.core.netdev_max_backlog = 250000
# recommended for hosts with jumbo frames enabled
net.ipv4.tcp_mt看u_probing=1
```

These can be reread by the system without rebooting by entering the command:

```
$sudo sysctl --system
```

## Versioning

For the versions available, see the [tags on this repository](#).

## Authors

- **Stuart B. Wilkins** - [stuwilkins](#)

See also the list of [contributors](#) who participated in this project.

## License

This project is licensed under the BSD License - see the [LICENSE](#) file for details

## Acknowledgments

A huge thanks to Peter Dennes, John Joseph and the detector team at LBNL and the team at Sydor Instruments.

## Chapter 2

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### 2.1 Modules

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## Chapter 3

# Class Index

### 3.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

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<a href="#">cin_ctl</a>	26
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# File Index

### 4.1 File List

Here is a list of all documented files with brief descriptions:

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src/ <a href="#">cin_register_map.h</a> . . . . .	<a href="#">39</a>
src/ <b>cinregisters.h</b> . . . . .	??
src/ <b>common.h</b> . . . . .	??
src/ <b>config.h</b> . . . . .	??
src/ <b>control.h</b> . . . . .	??
src/ <b>data.h</b> . . . . .	??
src/ <b>descramble.h</b> . . . . .	??
src/ <b>descramble_map.h</b> . . . . .	??
src/ <b>fifo.h</b> . . . . .	??
src/ <b>report.h</b> . . . . .	??





# Chapter 5

## Module Documentation

### 5.1 Cin Control Initialization Routines

#### Functions

- int [cin\\_ctl\\_init](#) ([cin\\_ctl\\_t](#) \*cin, char \*addr, uint16\_t port, uint16\_t sport, char \*bind\_addr, uint16\_t bind\_port, uint16\_t bind\_sport)
- int [cin\\_ctl\\_destroy](#) ([cin\\_ctl\\_t](#) \*cin)
- int [cin\\_data\\_send\\_magic](#) ([cin\\_data\\_t](#) \*cin)

#### 5.1.1 Detailed Description

#### 5.1.2 Function Documentation

##### 5.1.2.1 [cin\\_ctl\\_destroy\(\)](#)

```
int cin_ctl_destroy (  
    cin\_ctl\_t * cin )
```

Destroy (close) the cin control library

Close connections, free memory and exit library

#### Parameters

<i>cin</i>	handle to cin library
------------	-----------------------

#### Returns

Returns 0 on success non-zero if error

### 5.1.2.2 cin\_ctl\_init()

```
int cin_ctl_init (
    cin_ctl_t * cin,
    char * addr,
    uint16_t port,
    uint16_t sport,
    char * bind_addr,
    uint16_t bind_port,
    uint16_t bind_sport )
```

Initialize the cin control library

Initialize the control structures and communications with the CIN via the control interface. This function opens the UDP ports and starts a listening thread to receive packets from the CIN.

#### Parameters

<i>cin</i>	handle to cin library
<i>addr</i>	ip address of CIN base address
<i>port</i>	UDP port of cin
<i>sport</i>	stream output UDP port of cin
<i>bind_addr</i>	ip address to bind to
<i>bind_port</i>	input udp port of cin
<i>bind_sport</i>	stream input udp port of cin

#### Returns

Returns 0 on success non-zero if error

### 5.1.2.3 cin\_data\_send\_magic()

```
int cin_data_send_magic (
    cin_data_t * cin )
```

Send a magic packet to the CIN to initialize data

#### Parameters

<i>cin</i>	handle to cin library
------------	-----------------------

#### Returns

Returns 0 on success non-zero if error

## 5.2 Cin Control Read/Rwrite Routines

### Functions

- int `cin_ctl_read` (`cin_ctl_t` \*cin, uint16\_t reg, uint16\_t \*val, int wait)
- int `cin_ctl_write` (`cin_ctl_t` \*cin, uint16\_t reg, uint16\_t val, int wait)
- int `cin_ctl_stream_write` (`cin_ctl_t` \*cin, unsigned char \*val, int size)
- int `cin_ctl_write_with_readback` (`cin_ctl_t` \*cin, uint16\_t reg, uint16\_t val)
- int `cin_ctl_pwr` (`cin_ctl_t` \*cin, int pwr)
- int `cin_ctl_fp_pwr` (`cin_ctl_t` \*cin, int pwr)
- int `cin_ctl_fo_test_pattern` (`cin_ctl_t` \*cin, int on\_off)

### 5.2.1 Detailed Description

### 5.2.2 Function Documentation

#### 5.2.2.1 cin\_ctl\_read()

```
int cin_ctl_read (
    cin_ctl_t * cin,
    uint16_t reg,
    uint16_t * val,
    int wait )
```

Read register from CIN

#### Parameters

<i>cin</i>	handle to cin library
<i>reg</i>	register to read
<i>val</i>	variable to read value of register to
<i>wait</i>	if non-zero, wait a predefined time before read command (for i2c)

#### Returns

Returns 0 on success non-zero if error

#### 5.2.2.2 cin\_ctl\_stream\_write()

```
int cin_ctl_stream_write (
    cin_ctl_t * cin,
    unsigned char * val,
    int size )
```

Write stream data to CIN

**Parameters**

<i>cin</i>	handle to cin library
<i>val</i>	array of values to write
<i>size</i>	size of array pointed to by val

Write stream data to cin in form of 16 bit array.

**Returns**

Returns 0 on success non-zero if error

**5.2.2.3 cin\_ctl\_write()**

```
int cin_ctl_write (
    cin_ctl_t * cin,
    uint16_t reg,
    uint16_t val,
    int wait )
```

Write register to CIN

**Parameters**

<i>cin</i>	handle to cin library
<i>reg</i>	register to write to
<i>val</i>	value to write to register
<i>wait</i>	if non-zero

Write register value to CIN. If wait is non-zero then wait a sleep time of i CIN\_CTL\_WRITE\_SLEEP before releasing the mutex to add flow control to the cin.

**Returns**

Returns 0 on success non-zero if error

**5.2.2.4 cin\_ctl\_write\_with\_readback()**

```
int cin_ctl_write_with_readback (
    cin_ctl_t * cin,
    uint16_t reg,
    uint16_t val )
```

Write register to CIN with readback verification

**Parameters**

<i>cin</i>	handle to cin library
<i>reg</i>	register to write to
<i>val</i>	value to write to register

Write register value to CIN. Follow write with read of register and compare value. CIN\_CTL\_WRITE\_SLEEP before releasing the mutex to add flow control to the cin.

**Returns**

Returns 0 on success non-zero if error

## 5.3 CIN Firmware Upload Routines

### Functions

- int **cin\_ctl\_load\_config** ([cin\\_ctl\\_t](#) \*cin, char \*filename)
- int **cin\_ctl\_load\_firmware** ([cin\\_ctl\\_t](#) \*cin)
- int **cin\_ctl\_load\_firmware\_file** ([cin\\_ctl\\_t](#) \*cin, char \*filename)
- int **cin\_ctl\_load\_firmware\_data** ([cin\\_ctl\\_t](#) \*cin, unsigned char \*data, int data\_len)

### 5.3.1 Detailed Description

Firmware upload routines

## 5.4 CIN FCLK Configuration Routines

### Functions

- int **cin\_ctl\_get\_fclk** (cin\_ctl\_t \*cin, int \*clkfreq)
- int **cin\_ctl\_set\_fclk** (cin\_ctl\_t \*cin, int clkfreq)
- int **cin\_ctl\_set\_fclk\_regs** (cin\_ctl\_t \*cin, int clkfreq)

### 5.4.1 Detailed Description

Firmware upload routines

## 5.5 CIN Status Routines

### Functions

- int **cin\_ctl\_get\_cfg\_fpga\_status** ([cin\\_ctl\\_t](#) \*cin, uint16\_t \*\_val)
- int **cin\_ctl\_get\_id** ([cin\\_ctl\\_t](#) \*cin, [cin\\_ctl\\_id\\_t](#) \*\_val)
- int **cin\_ctl\_get\_dcm\_status** ([cin\\_ctl\\_t](#) \*cin, uint16\_t \*\_val)
- int **cin\_ctl\_get\_power\_status** ([cin\\_ctl\\_t](#) \*cin, int full, int \*pwr, [cin\\_ctl\\_pwr\\_mon\\_t](#) \*values)

### 5.5.1 Detailed Description

Status Routines



## 5.6 CIN Control Bias Routines

### Functions

- int **cin\_ctl\_set\_bias** ([cin\\_ctl\\_t](#) \*cin, int val)
- int **cin\_ctl\_get\_bias** ([cin\\_ctl\\_t](#) \*cin, int \*val)
- int **cin\_ctl\_set\_bias\_regs** ([cin\\_ctl\\_t](#) \*cin, uint16\_t \*vals, int verify)
- int **cin\_ctl\_get\_bias\_regs** ([cin\\_ctl\\_t](#) \*cin, uint16\_t \*vals)
- int **cin\_ctl\_set\_bias\_voltages** ([cin\\_ctl\\_t](#) \*cin, float \*voltage, int verify)
- int **cin\_ctl\_get\_bias\_voltages** ([cin\\_ctl\\_t](#) \*cin, float \*voltage)

### 5.6.1 Detailed Description

Initialization group

## 5.7 CIN Control Timing Routines

### Functions

- int **cin\_ctl\_set\_timing\_regs** ([cin\\_ctl\\_t](#) \*cin, uint16\_t \*vals, int vals\_len)
- int **cin\_ctl\_get\_timing\_regs** ([cin\\_ctl\\_t](#) \*cin, uint16\_t \*vals)

### 5.7.1 Detailed Description

Timing setup group

## 5.8 CIN Data Initialization Routines

### Functions

- int `cin_data_init` (`cin_data_t` \*cin, char \*addr, uint16\_t port, char \*bind\_addr, uint16\_t bind\_port, int rcvbuf, int packet\_buffer\_len, int frame\_buffer\_len, cin\_data\_callback push\_callback, cin\_data\_callback pop\_callback, void \*usr\_ptr)
- void `cin_data_destroy` (`cin_data_t` \*cin)

### 5.8.1 Detailed Description

Initialization group

### 5.8.2 Function Documentation

#### 5.8.2.1 `cin_data_destroy()`

```
void cin_data_destroy (
    cin_data_t * cin )
```

Close the cin data library and cleanup

Stop all the processing threads and join them to the main thread. This function blocks until all threads have joined the main thread (program). This should be called to clean up the library before the program is exited

#### Parameters

<code>cin</code>	Handle to cin data library
------------------	----------------------------

#### 5.8.2.2 `cin_data_init()`

```
int cin_data_init (
    cin_data_t * cin,
    char * addr,
    uint16_t port,
    char * bind_addr,
    uint16_t bind_port,
    int rcvbuf,
    int packet_buffer_len,
    int frame_buffer_len,
    cin_data_callback push_callback,
    cin_data_callback pop_callback,
    void * usr_ptr )
```

Initialize the cin data library

Initialize the data handling routines and start the threads for listening.

## Parameters

<i>cin</i>	Handle to cin data library
<i>addr</i>	IP-Address of cin (if NULL defaults to standard)
<i>port</i>	UDP Port of CIN
<i>bind_addr</i>	IP-Address to bind to (if NULL binds to 0.0.0.0)
<i>bind_port</i>	UDP Port of host
<i>rcvbuf</i>	TCP/IP Kernel receive buffer size
<i>packet_buffer_len</i>	Length of packet buffer fifo (in units number of packets)
<i>frame_buffer_len</i>	Length of frame (assembler) buffer fifo (in units of number of frames)
<i>push_callback</i>	This function is called when a data structure is needed
<i>pop_callback</i>	This function is called when an image has been processed
<i>usr_ptr</i>	Pointer passed to callback functions

## 5.9 CIN Data Framestore Functions

### Functions

- void `cin_data_framestore_trigger` (`cin_data_t` \*cin, int count)
- void `cin_data_framestore_skip` (`cin_data_t` \*cin, int count)
- int `cin_data_get_framestore_counter` (`cin_data_t` \*cin)
- void `cin_data_framestore_disable` (`cin_data_t` \*cin)
- void `cin_data_framestore_trigger_enable` (`cin_data_t` \*cin)

### 5.9.1 Detailed Description

Framestore Group

### 5.9.2 Function Documentation

#### 5.9.2.1 `cin_data_framestore_disable()`

```
void cin_data_framestore_disable (  
    cin_data_t * cin )
```

Disable the framestore modes

This function disables the framestore modes (software trigger and skip). If the camera is hardware triggering then the images will start to be processed.

#### Parameters

<code>cin</code>	Handle to the cin library
------------------	---------------------------

#### 5.9.2.2 `cin_data_framestore_skip()`

```
void cin_data_framestore_skip (  
    cin_data_t * cin,  
    int count )
```

Enable framestore skip mode

Enable the framestore skip mode. This function should be called before hardware triggering the camera. This causes the data processing to skip

## Parameters

<i>count</i>	frames from the first images to be read. This is usually done to stop the first few frames from being over exposed.
<i>cin</i>	handle to the <a href="#">cin_data</a> library

5.9.2.3 `cin_data_framestore_trigger()`

```
void cin_data_framestore_trigger (
    cin_data_t * cin,
    int count )
```

Send a framestore (software) trigger

Send a software trigger to the CIN by timestamping the request time and allow images to be processed when recieved after this time. The count option sets the number of frames to trigger. A value of -1 indicated that the trigger should not count images but run indefinitely after the trigger has occurred.

## Parameters

<i>cin</i>	handle to the <a href="#">cin_data</a> library
<i>count</i>	number of frames to trigger

5.9.2.4 `cin_data_framestore_trigger_enable()`

```
void cin_data_framestore_trigger_enable (
    cin_data_t * cin )
```

Enable the framestore trigger mode

This function enables the framestore trigger mode. It cases the images to not be processed pending a call to the function to (software) trigger the camera.

## Parameters

<i>cin</i>	Handle to the cin library
------------	---------------------------

5.9.2.5 `cin_data_get_framestore_counter()`

```
int cin_data_get_framestore_counter (
    cin_data_t * cin )
```

Get the value of the framestore counter

Return the number of frames in the framestore counter. In trigger mode, this returns the number of frames to go. In skip mode, this returns the number of frames that have to be skipped.

#### Parameters

<i>cin</i>	handle to the <a href="#">cin_data</a> library
------------	--

#### Returns

Number of frames to go in trigger



## Chapter 6

# Class Documentation

### 6.1 cin\_config\_timing Struct Reference

#### Public Attributes

- uint16\_t \* [data](#)
- int [data\\_len](#)
- char [name](#) [40]
- int [rows](#)
- int [cols](#)
- int [overscan](#)
- int [fclk\\_freq](#)

#### 6.1.1 Member Data Documentation

##### 6.1.1.1 cols

```
int cin_config_timing::cols
```

Cols for this timing setup

##### 6.1.1.2 data

```
uint16_t* cin_config_timing::data
```

Pointer to timing data

##### 6.1.1.3 data\_len

```
int cin_config_timing::data_len
```

timing data length

#### 6.1.1.4 fclk\_freq

```
int cin_config_timing::fclk_freq
```

FCLK Frequency to use

#### 6.1.1.5 name

```
char cin_config_timing::name[40]
```

String for config name

#### 6.1.1.6 overscan

```
int cin_config_timing::overscan
```

Number of overscan cols for this setup

#### 6.1.1.7 rows

```
int cin_config_timing::rows
```

Rows for this timing setup

The documentation for this struct was generated from the following file:

- [src/cin.h](#)

## 6.2 cin\_ctl Struct Reference

### Public Attributes

- char \* **addr**
- char \* **bind\_addr**
- int **port**
- int **bind\_port**
- int **sport**
- int **bind\_sport**
- [cin\\_port\\_t](#) **ctl\_port**
- [cin\\_port\\_t](#) **stream\_port**
- [cin\\_config\\_timing\\_t](#) **timing** [[CIN\\_CONFIG\\_MAX\\_TIMING\\_MODES](#)]
- int **timing\_num**
- [cin\\_config\\_timing\\_t](#) \* **current\_timing**
- int **folk\_time\_tick**
- [cin\\_ctl\\_listener\\_t](#) \* **listener**
- pthread\_mutex\_t **access**
- pthread\_mutexattr\_t **access\_attr**

## 6.2.1 Member Data Documentation

### 6.2.1.1 fclk\_time\_tick

```
int cin_ctl::fclk_time_tick
```

In micro seconds

The documentation for this struct was generated from the following file:

- src/[cin.h](#)

## 6.3 cin\_ctl\_id Struct Reference

### Public Attributes

- uint16\_t **base\_board\_id**
- uint16\_t **base\_serial\_no**
- uint16\_t **base\_fpga\_ver**
- uint16\_t **fabric\_board\_id**
- uint16\_t **fabric\_serial\_no**
- uint16\_t **fabric\_fpga\_ver**

The documentation for this struct was generated from the following file:

- src/[cin.h](#)

## 6.4 cin\_ctl\_listener Struct Reference

### Public Attributes

- struct [cin\\_port](#) \* **cp**
- [fifo](#) **ctl\_fifo**
- pthread\_t **thread\_id**
- pthread\_barrier\_t **barrier**

The documentation for this struct was generated from the following file:

- src/[cin.h](#)

## 6.5 cin\_ctl\_pwr\_mon\_t Struct Reference

### Public Attributes

- [cin\\_ctl\\_pwr\\_val\\_t](#) **bus\_12v0**
- [cin\\_ctl\\_pwr\\_val\\_t](#) **mgmt\_3v3**
- [cin\\_ctl\\_pwr\\_val\\_t](#) **mgmt\_2v5**
- [cin\\_ctl\\_pwr\\_val\\_t](#) **mgmt\_1v2**
- [cin\\_ctl\\_pwr\\_val\\_t](#) **enet\_1v0**
- [cin\\_ctl\\_pwr\\_val\\_t](#) **s3e\_3v3**
- [cin\\_ctl\\_pwr\\_val\\_t](#) **gen\_3v3**
- [cin\\_ctl\\_pwr\\_val\\_t](#) **gen\_2v5**
- [cin\\_ctl\\_pwr\\_val\\_t](#) **v6\_0v9**
- [cin\\_ctl\\_pwr\\_val\\_t](#) **v6\_1v0**
- [cin\\_ctl\\_pwr\\_val\\_t](#) **v6\_2v5**
- [cin\\_ctl\\_pwr\\_val\\_t](#) **fp**

The documentation for this struct was generated from the following file:

- [src/cin.h](#)

## 6.6 cin\_ctl\_pwr\_val Struct Reference

### Public Attributes

- double **i**
- double **v**

The documentation for this struct was generated from the following file:

- [src/cin.h](#)

## 6.7 cin\_data Struct Reference

### Public Attributes

- [fifo](#) \* **packet\_fifo**
- [fifo](#) \* **frame\_fifo**
- [cin\\_data\\_threads\\_t](#) **listen\_thread**
- [cin\\_data\\_threads\\_t](#) **assembler\_thread**
- [cin\\_data\\_threads\\_t](#) **descramble\_thread**
- [pthread\\_mutex\\_t](#) **descramble\_mutex**
- [pthread\\_mutex\\_t](#) **stats\_mutex**
- [pthread\\_mutex\\_t](#) **framestore\_mutex**
- [cin\\_data\\_callbacks\\_t](#) **callbacks**
- char \* **addr**
- char \* **bind\_addr**
- int **port**

- int **bind\_port**
- int **recv\_buf**
- [cin\\_port\\_t](#) **dp**
- struct timespec **framerate**
- unsigned long int **dropped\_packets**
- unsigned long int **malformed\_packets**
- uint16\_t **last\_frame**
- [descramble\\_map\\_t](#) **map**
- int **framestore\_mode**
- struct timespec **framestore\_trigger**
- int **framestore\_counter**

The documentation for this struct was generated from the following file:

- [src/cin.h](#)

## 6.8 cin\_data\_callbacks Struct Reference

### Public Attributes

- void **\***(**\* push**)([cin\\_data\\_frame\\_t](#) **\***)
- void **\***(**\* pop**)([cin\\_data\\_frame\\_t](#) **\***)
- [cin\\_data\\_frame\\_t](#) **\*** **frame**

The documentation for this struct was generated from the following file:

- [src/cin.h](#)

## 6.9 cin\_data\_frame Struct Reference

### Public Attributes

- uint16\_t **\*** **data**
- uint16\_t **number**
- struct timespec **timestamp**
- int **size\_x**
- int **size\_y**
- void **\*** **usr\_ptr**

The documentation for this struct was generated from the following file:

- [src/cin.h](#)

## 6.10 cin\_data\_packet Struct Reference

### Public Attributes

- unsigned char \* **data**
- int **size**
- struct timespec **timestamp**

The documentation for this struct was generated from the following file:

- [src/data.h](#)

## 6.11 cin\_data\_proc Struct Reference

### Public Attributes

- void \*(\* **input\_get** )(void \*, int)
- void \*(\* **input\_put** )(void \*, int)
- void \* **input\_args**
- int **reader**
- void \*(\* **output\_put** )(void \*)
- void \*(\* **output\_get** )(void \*)
- void \* **output\_args**
- [cin\\_data\\_t](#) \* **parent**

The documentation for this struct was generated from the following file:

- [src/data.h](#)

## 6.12 cin\_data\_stats Struct Reference

### Public Attributes

- int **last\_frame**
- double **framerate**
- double **datarate**
- double **packet\_percent\_full**
- double **frame\_percent\_full**
- double **image\_percent\_full**
- long int **packet\_overruns**
- long int **frame\_overruns**
- long int **image\_overruns**
- long int **packet\_used**
- long int **frame\_used**
- long int **image\_used**
- long int **dropped\_packets**
- long int **malformed\_packets**

The documentation for this struct was generated from the following file:

- [src/cin.h](#)

## 6.13 cin\_data\_threads Struct Reference

### Public Attributes

- pthread\_t **thread\_id**
- int **started**

The documentation for this struct was generated from the following file:

- src/[cin.h](#)

## 6.14 cin\_map\_t Struct Reference

### Public Attributes

- char \* **name**
- uint16\_t **reg**

The documentation for this struct was generated from the following file:

- src/cinregisters.h

## 6.15 cin\_port Struct Reference

### Public Attributes

- int **sockfd**
- struct timeval **tv**
- struct sockaddr\_in **sin\_srv**
- struct sockaddr\_in **sin\_cli**
- socklen\_t **slen**

The documentation for this struct was generated from the following file:

- src/[cin.h](#)

## 6.16 descramble\_map\_t Struct Reference

### Public Attributes

- uint32\_t \* **map**
- int **size\_x**
- int **size\_y**
- int **overscan**
- int **rows**

The documentation for this struct was generated from the following file:

- src/[cin.h](#)

## 6.17 fifo Struct Reference

### Public Attributes

- void \* **data**
- void \* **head**
- void \* **tail** [FIFO\_MAX\_READERS]
- void \* **end**
- int **readers**
- long int **size**
- int **elem\_size**
- int **full**
- long int **overruns**
- pthread\_mutex\_t **mutex**
- pthread\_cond\_t **signal**

The documentation for this struct was generated from the following file:

- [src/cin.h](#)



# Chapter 7

## File Documentation

### 7.1 src/cin.h File Reference

```
#include <stdint.h>
#include <stdio.h>
#include <sys/socket.h>
#include <netinet/in.h>
#include <netinet/ip.h>
#include <sys/time.h>
#include <pthread.h>
```

#### Classes

- struct [fifo](#)
- struct [cin\\_ctl\\_listener](#)
- struct [cin\\_port](#)
- struct [cin\\_config\\_timing](#)
- struct [cin\\_ctl](#)
- struct [cin\\_data\\_frame](#)
- struct [cin\\_data\\_stats](#)
- struct [cin\\_data\\_threads](#)
- struct [cin\\_data\\_callbacks](#)
- struct [descramble\\_map\\_t](#)
- struct [cin\\_data](#)
- struct [cin\\_ctl\\_id](#)
- struct [cin\\_ctl\\_pwr\\_val](#)
- struct [cin\\_ctl\\_pwr\\_mon\\_t](#)

#### Macros

- #define **CIN\_OK** 0
- #define **CIN\_ERROR** -1
- #define **CIN\_CTL\_IP** "192.168.1.207"
- #define **CIN\_CTL\_CIN\_PORT** 49200
- #define **CIN\_CTL\_BIND\_PORT** 50200

- #define **CIN\_CTL\_FRMW\_CIN\_PORT** 49202
- #define **CIN\_CTL\_FRMW\_BIND\_PORT** 50202
- #define **CIN\_CTL\_RCVBUF** 10
- #define **CIN\_CTL\_MAX\_READ\_TRIES** 10
- #define **CIN\_CTL\_MAX\_WRITE\_TRIES** 5
- #define **CIN\_CTL\_WRITE\_SLEEP** 100
- #define **CIN\_CTL\_STREAM\_CHUNK** 256
- #define **CIN\_CTL\_STREAM\_SLEEP** 15
- #define **CIN\_CTL\_POWER\_ENABLE** 0x001F
- #define **CIN\_CTL\_POWER\_DISABLE** 0x0000
- #define **CIN\_CTL\_FP\_POWER\_ENABLE** 0x0020
- #define **CIN\_CTL\_DCM\_LOCKED** 0x0001
- #define **CIN\_CTL\_DCM\_PSDONE** 0x0002
- #define **CIN\_CTL\_DCM\_STATUS0** 0x0004
- #define **CIN\_CTL\_DCM\_STATUS1** 0x0008
- #define **CIN\_CTL\_DCM\_STATUS2** 0x0010
- #define **CIN\_CTL\_DCM\_TX1\_READY** 0x0020
- #define **CIN\_CTL\_DCM\_TX2\_READY** 0x0040
- #define **CIN\_CTL\_DCM\_ATCA\_ALARM** 0x0080
- #define **CIN\_CTL\_TRIG\_INTERNAL** 0x0000
- #define **CIN\_CTL\_TRIG\_EXTERNAL\_1** 0x0001
- #define **CIN\_CTL\_TRIG\_EXTERNAL\_2** 0x0002
- #define **CIN\_CTL\_TRIG\_EXTERNAL\_BOTH** 0x0003
- #define **CIN\_CTL\_FOCUS\_BIT** 0x0002
- #define **CIN\_CTL\_FCLK\_125** 0x0000
- #define **CIN\_CTL\_FCLK\_200** 0x0001
- #define **CIN\_CTL\_FCLK\_250** 0x0002
- #define **CIN\_CTL\_FCLK\_125\_C** 0x0003
- #define **CIN\_CTL\_FCLK\_200\_C** 0x0004
- #define **CIN\_CTL\_FCLK\_250\_C** 0x0005
- #define **CIN\_CTL\_FCLK\_156\_C** 0x0006
- #define **CIN\_CTL\_FPGA\_STS\_CFG** 0x8000
- #define **CIN\_CTL\_FPGA\_STS\_FP\_PWR** 0x0008
- #define **CIN\_CTL\_DCM\_STS\_ATCA** 0x0080
- #define **CIN\_CTL\_DCM\_STS\_LOCKED** 0x0001
- #define **CIN\_CTL\_DCM\_STS\_OVERRIDE** 0x0800
- #define **CIN\_CTL\_MUX1\_VCLK1** 0x0001
- #define **CIN\_CTL\_MUX1\_VCLK2** 0x0002
- #define **CIN\_CTL\_MUX1\_VCLK3** 0x0003
- #define **CIN\_CTL\_MUX1\_ATG** 0x0004
- #define **CIN\_CTL\_MUX1\_VFCLK1** 0x0005
- #define **CIN\_CTL\_MUX1\_VFCLK2** 0x0006
- #define **CIN\_CTL\_MUX1\_VFCLK3** 0x0007
- #define **CIN\_CTL\_MUX1\_HCLK1** 0x0008
- #define **CIN\_CTL\_MUX1\_HCLK2** 0x0009
- #define **CIN\_CTL\_MUX1\_OSW** 0x000A
- #define **CIN\_CTL\_MUX1\_RST** 0x000B
- #define **CIN\_CTL\_MUX1\_CONVERT** 0x000C
- #define **CIN\_CTL\_MUX1\_SHUTTER** 0x000D
- #define **CIN\_CTL\_MUX1\_SWTRIGGER** 0x000E
- #define **CIN\_CTL\_MUX1\_TRIGMON** 0x000F
- #define **CIN\_CTL\_MUX1\_EXPOSE** 0x0000
- #define **CIN\_CTL\_MUX2\_VCLK1** 0x0010
- #define **CIN\_CTL\_MUX2\_VCLK2** 0x0020
- #define **CIN\_CTL\_MUX2\_VCLK3** 0x0030

- `#define CIN_CTL_MUX2_ATG 0x0040`
- `#define CIN_CTL_MUX2_VFCLK1 0x0050`
- `#define CIN_CTL_MUX2_VFCLK2 0x0060`
- `#define CIN_CTL_MUX2_VFCLK3 0x0070`
- `#define CIN_CTL_MUX2_HCLK1 0x0080`
- `#define CIN_CTL_MUX2_HCLK2 0x0090`
- `#define CIN_CTL_MUX2_HCLK3 0x00A0`
- `#define CIN_CTL_MUX2_OSW 0x00B0`
- `#define CIN_CTL_MUX2_RST 0x00C0`
- `#define CIN_CTL_MUX2_CONVERT 0x00D0`
- `#define CIN_CTL_MUX2_SAVE 0x00E0`
- `#define CIN_CTL_MUX2_HWTRIG 0x00F0`
- `#define CIN_CTL_MUX2_EXPOSE 0x0000`
- `#define CIN_CTL_FO_REG1 0x821D`
- `#define CIN_CTL_FO_REG2 0x821E`
- `#define CIN_CTL_FO_REG3 0x821F`
- `#define CIN_CTL_FO_REG4 0x8001`
- `#define CIN_CTL_FO_REG5 0x8211`
- `#define CIN_CTL_FO_REG6 0x8212`
- `#define CIN_CTL_FO_REG7 0x8213`
- `#define CIN_DATA_IP "10.0.5.207"`
- `#define CIN_DATA_BIND_PORT 49201`
- `#define CIN_DATA_CIN_PORT 49203`
- `#define CIN_DATA_MAX_MTU 9000`
- `#define CIN_DATA_UDP_HEADER 8`
- `#define CIN_DATA_MAGIC_PACKET UINT64_C(0x0000F4F3F2F1F000)`
- `#define CIN_DATA_MAGIC_PACKET_MASK UINT64_C(0x0000FFFFFFFFFFFF00)`
- `#define CIN_DATA_TAIL_MAGIC_PACKET UINT64_C(0x010DF0ADDEF2F1F0)`
- `#define CIN_DATA_TAIL_MAGIC_PACKET_MASK UINT64_C(0xFFFFFFFFFFFFFFFF)`
- `#define CIN_DATA_DROPPED_PACKET_VAL 0x2000`
- `#define CIN_DATA_DATA_MASK 0x1FFF`
- `#define CIN_DATA_CTRL_MASK 0xE000`
- `#define CIN_DATA_SIGN_MASK 0x1000`
- `#define CIN_DATA_GAIN_8 0xC000`
- `#define CIN_DATA_GAIN_4 0x4000`
- `#define CIN_DATA_PACKET_LEN 8184`
- `#define CIN_DATA_MAX_PACKETS 542`
- `#define CIN_DATA_RCVBUF (100*1024*1024)`
- `#define CIN_DATA_MAX_FRAME_X 1152`
- `#define CIN_DATA_MAX_FRAME_Y 2050`
- `#define CIN_DATA_MAX_STREAM 2400000`
- `#define CIN_DATA_CCD_COLS 96`
- `#define CIN_DATA_CCD_COLS_PER_CHAN 10`
- `#define CIN_DATA_PIPELINE_FLUSH 1344`
- `#define CIN_CTL_NUM_BIAS_VOLTAGE 20`
- `#define CIN_CTL_BIAS_POSH 0`
- `#define CIN_CTL_BIAS_NEGH 1`
- `#define CIN_CTL_BIAS_POSRG 2`
- `#define CIN_CTL_BIAS_NEGRG 3`
- `#define CIN_CTL_BIAS_POSSW 4`
- `#define CIN_CTL_BIAS_NEGSW 5`
- `#define CIN_CTL_BIAS_POSV 6`
- `#define CIN_CTL_BIAS_NEGV 7`
- `#define CIN_CTL_BIAS_POSTG 8`
- `#define CIN_CTL_BIAS_NEGTG 9`

- `#define CIN_CTL_BIAS_POSVF 10`
- `#define CIN_CTL_BIAS_NEGVF 11`
- `#define CIN_CTL_BIAS_NEDGE 12`
- `#define CIN_CTL_BIAS_OTG 13`
- `#define CIN_CTL_BIAS_VDDR 14`
- `#define CIN_CTL_BIAS_VDD_OUT 15`
- `#define CIN_CTL_BIAS_BUF_BASE 16`
- `#define CIN_CTL_BIAS_BUF_DELTA 17`
- `#define CIN_CTL_BIAS_SPARE1 18`
- `#define CIN_CTL_BIAS_SPARE2 19`
- `#define DEBUG_PRINT(fmt, ...) if(_debug_print_flag) { fprintf(stderr, "%s:%d:%s(): " fmt, __FILE__, __LINE__, __func__, __VA_ARGS__); }`
- `#define DEBUG_COMMENT(fmt) if(_debug_print_flag) { fprintf(stderr, "%s:%d:%s(): " fmt, __FILE__, __LINE__, __func__); }`
- `#define ERROR_COMMENT(fmt) if(_error_print_flag) { fprintf(stderr, "%s:%d:%s(): " fmt, __FILE__, __LINE__, __func__); }`
- `#define ERROR_PRINT(fmt, ...) if(_error_print_flag) { fprintf(stderr, "%s:%d:%s(): " fmt, __FILE__, __LINE__, __func__, __VA_ARGS__); }`
- `#define CIN_CONFIG_MAX_STRING 40`
- `#define FIFO_MAX_READERS 10`
- `#define CIN_CONFIG_MAX_TIMING_DATA 880`
- `#define CIN_CONFIG_MAX_TIMING_MODES 20`

## Typedefs

- `typedef struct cin_ctl_listener cin_ctl_listener_t`
- `typedef struct cin_port cin_port_t`
- `typedef struct cin_config_timing cin_config_timing_t`
- `typedef struct cin_ctl cin_ctl_t`
- `typedef struct cin_data_frame cin_data_frame_t`
- `typedef struct cin_data_stats cin_data_stats_t`
- `typedef struct cin_data_threads cin_data_threads_t`
- `typedef struct cin_data_callbacks cin_data_callbacks_t`
- `typedef struct cin_data cin_data_t`
- `typedef void(* cin_data_callback) (cin_data_frame_t *)`
- `typedef struct cin_ctl_id cin_ctl_id_t`
- `typedef struct cin_ctl_pwr_val cin_ctl_pwr_val_t`

## Functions

- `void cin_set_debug_print (int debug)`
- `void cin_set_error_print (int error)`
- `void cin_report (FILE *fp, int details)`
- `int cin_ctl_init (cin_ctl_t *cin, char *addr, uint16_t port, uint16_t sport, char *bind_addr, uint16_t bind_port, uint16_t bind_sport)`
- `int cin_ctl_destroy (cin_ctl_t *cin)`
- `int cin_data_send_magic (cin_data_t *cin)`
- `int cin_ctl_read (cin_ctl_t *cin, uint16_t reg, uint16_t *val, int wait)`
- `int cin_ctl_write (cin_ctl_t *cin, uint16_t reg, uint16_t val, int wait)`
- `int cin_ctl_stream_write (cin_ctl_t *cin, unsigned char *val, int size)`
- `int cin_ctl_write_with_readback (cin_ctl_t *cin, uint16_t reg, uint16_t val)`
- `int cin_ctl_pwr (cin_ctl_t *cin, int pwr)`
- `int cin_ctl_fp_pwr (cin_ctl_t *cin, int pwr)`

- int [cin\\_ctl\\_fo\\_test\\_pattern](#) ([cin\\_ctl\\_t](#) \*cin, int on\_off)
- int [cin\\_ctl\\_load\\_config](#) ([cin\\_ctl\\_t](#) \*cin, char \*filename)
- int [cin\\_ctl\\_load\\_firmware](#) ([cin\\_ctl\\_t](#) \*cin)
- int [cin\\_ctl\\_load\\_firmware\\_file](#) ([cin\\_ctl\\_t](#) \*cin, char \*filename)
- int [cin\\_ctl\\_load\\_firmware\\_data](#) ([cin\\_ctl\\_t](#) \*cin, unsigned char \*data, int data\_len)
- int [cin\\_ctl\\_get\\_fclk](#) ([cin\\_ctl\\_t](#) \*cin, int \*clkfreq)
- int [cin\\_ctl\\_set\\_fclk](#) ([cin\\_ctl\\_t](#) \*cin, int clkfreq)
- int [cin\\_ctl\\_set\\_fclk\\_regs](#) ([cin\\_ctl\\_t](#) \*cin, int clkfreq)
- int [cin\\_ctl\\_get\\_cfg\\_fpga\\_status](#) ([cin\\_ctl\\_t](#) \*cin, uint16\_t \*\_val)
- int [cin\\_ctl\\_get\\_id](#) ([cin\\_ctl\\_t](#) \*cin, [cin\\_ctl\\_id\\_t](#) \*\_val)
- int [cin\\_ctl\\_get\\_dcm\\_status](#) ([cin\\_ctl\\_t](#) \*cin, uint16\_t \*\_val)
- int [cin\\_ctl\\_get\\_power\\_status](#) ([cin\\_ctl\\_t](#) \*cin, int full, int \*pwr, [cin\\_ctl\\_pwr\\_mon\\_t](#) \*values)
- int [cin\\_ctl\\_set\\_bias](#) ([cin\\_ctl\\_t](#) \*cin, int val)
- int [cin\\_ctl\\_get\\_bias](#) ([cin\\_ctl\\_t](#) \*cin, int \*val)
- int [cin\\_ctl\\_set\\_bias\\_regs](#) ([cin\\_ctl\\_t](#) \*cin, uint16\_t \*vals, int verify)
- int [cin\\_ctl\\_get\\_bias\\_regs](#) ([cin\\_ctl\\_t](#) \*cin, uint16\_t \*vals)
- int [cin\\_ctl\\_set\\_bias\\_voltages](#) ([cin\\_ctl\\_t](#) \*cin, float \*voltage, int verify)
- int [cin\\_ctl\\_get\\_bias\\_voltages](#) ([cin\\_ctl\\_t](#) \*cin, float \*voltage)
- int [cin\\_ctl\\_set\\_timing\\_regs](#) ([cin\\_ctl\\_t](#) \*cin, uint16\_t \*vals, int vals\_len)
- int [cin\\_ctl\\_get\\_timing\\_regs](#) ([cin\\_ctl\\_t](#) \*cin, uint16\_t \*vals)
- int [cin\\_ctl\\_get\\_camera\\_pwr](#) ([cin\\_ctl\\_t](#) \*cin, int \*val)
- int [cin\\_ctl\\_set\\_camera\\_pwr](#) ([cin\\_ctl\\_t](#) \*cin, int val)
- int [cin\\_ctl\\_set\\_clocks](#) ([cin\\_ctl\\_t](#) \*cin, int val)
- int [cin\\_ctl\\_get\\_clocks](#) ([cin\\_ctl\\_t](#) \*cin, int \*val)
- int [cin\\_ctl\\_set\\_trigger](#) ([cin\\_ctl\\_t](#) \*cin, int val)
- int [cin\\_ctl\\_get\\_trigger](#) ([cin\\_ctl\\_t](#) \*cin, int \*val)
- int [cin\\_ctl\\_set\\_focus](#) ([cin\\_ctl\\_t](#) \*cin, int val)
- int [cin\\_ctl\\_get\\_focus](#) ([cin\\_ctl\\_t](#) \*cin, int \*val)
- int [cin\\_ctl\\_get\\_triggering](#) ([cin\\_ctl\\_t](#) \*cin, int \*trigger)
- int [cin\\_ctl\\_int\\_trigger\\_start](#) ([cin\\_ctl\\_t](#) \*cin, int nimages)
- int [cin\\_ctl\\_int\\_trigger\\_stop](#) ([cin\\_ctl\\_t](#) \*cin)
- int [cin\\_ctl\\_ext\\_trigger\\_start](#) ([cin\\_ctl\\_t](#) \*cin, int trigger\_mode)
- int [cin\\_ctl\\_ext\\_trigger\\_stop](#) ([cin\\_ctl\\_t](#) \*cin)
- int [cin\\_ctl\\_set\\_exposure\\_time](#) ([cin\\_ctl\\_t](#) \*cin, float e\_time)
- int [cin\\_ctl\\_set\\_trigger\\_delay](#) ([cin\\_ctl\\_t](#) \*cin, float t\_time)
- int [cin\\_ctl\\_set\\_cycle\\_time](#) ([cin\\_ctl\\_t](#) \*cin, float ftime)
- int [cin\\_ctl\\_frame\\_count\\_reset](#) ([cin\\_ctl\\_t](#) \*cin)
- int [cin\\_ctl\\_set\\_mux](#) ([cin\\_ctl\\_t](#) \*cin, int setting)
- int [cin\\_ctl\\_get\\_mux](#) ([cin\\_ctl\\_t](#) \*cin, int \*setting)
- int [cin\\_ctl\\_set\\_fcric\\_clamp](#) ([cin\\_ctl\\_t](#) \*cin, int clamp)
- int [cin\\_ctl\\_set\\_fcric\\_gain](#) ([cin\\_ctl\\_t](#) \*cin, int gain)
- int [cin\\_ctl\\_set\\_fabric\\_address](#) ([cin\\_ctl\\_t](#) \*cin, char \*ip)
- int [cin\\_ctl\\_reg\\_dump](#) ([cin\\_ctl\\_t](#) \*cin, FILE \*fp)
- int [cin\\_config\\_read\\_file](#) ([cin\\_ctl\\_t](#) \*cin, const char \*file)
- int [cin\\_data\\_init](#) ([cin\\_data\\_t](#) \*cin, char \*addr, uint16\_t port, char \*bind\_addr, uint16\_t bind\_port, int rcvbuf, int packet\_buffer\_len, int frame\_buffer\_len, cin\_data\_callback push\_callback, cin\_data\_callback pop\_callback, void \*usr\_ptr)
- void [cin\\_data\\_destroy](#) ([cin\\_data\\_t](#) \*cin)
- void [cin\\_data\\_framestore\\_trigger](#) ([cin\\_data\\_t](#) \*cin, int count)
- void [cin\\_data\\_framestore\\_skip](#) ([cin\\_data\\_t](#) \*cin, int count)
- int [cin\\_data\\_get\\_framestore\\_counter](#) ([cin\\_data\\_t](#) \*cin)
- void [cin\\_data\\_framestore\\_disable](#) ([cin\\_data\\_t](#) \*cin)
- void [cin\\_data\\_framestore\\_trigger\\_enable](#) ([cin\\_data\\_t](#) \*cin)
- struct [cin\\_data\\_frame](#) \* [cin\\_data\\_get\\_next\\_frame](#) ([cin\\_data\\_t](#) \*cin)
- void [cin\\_data\\_release\\_frame](#) ([cin\\_data\\_t](#) \*cin, int free\_mem)

- struct `cin_data_frame` \* `cin_data_get_buffered_frame` (void)
- void `cin_data_release_buffered_frame` (void)
- void `cin_data_compute_stats` (`cin_data_t` \*cin, `cin_data_stats_t` \*stats)
- void `cin_data_show_stats` (FILE \*fp, `cin_data_stats_t` stats)
- void `cin_data_reset_stats` (`cin_data_t` \*cin)
- int `cin_data_set_descramble_params` (`cin_data_t` \*cin, int rows, int overscan)
- void `cin_data_get_descramble_params` (`cin_data_t` \*cin, int \*rows, int \*overscan, int \*xsize, int \*ysize)
- int `cin_com_boot` (`cin_ctl_t` \*cin\_ctl, `cin_data_t` \*cin\_data, char \*mode)

## Variables

- const char \* `cin_build_git_time`
- const char \* `cin_build_git_sha`
- const char \* `cin_build_version`
- int `_debug_print_flag`
- int `_error_print_flag`
- uint16\_t `cin_config_timing` []
- int `cin_config_timing_len`
- unsigned char `cin_config_firmware` []
- unsigned `cin_config_firmware_len`
- uint16\_t `cin_config_bias` []
- int `cin_config_bias_len`
- uint16\_t `cin_config_fcric_200` []
- int `cin_config_fcric_200_len`

### 7.1.1 Detailed Description

#### Author

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### 7.1.3 DESCRIPTION

header file for CIN communications

### 7.1.4 Macro Definition Documentation

#### 7.1.4.1 CIN\_CONFIG\_MAX\_TIMING\_DATA

```
#define CIN_CONFIG_MAX_TIMING_DATA 880
```

Max = 55 per state, 16 states

#### 7.1.4.2 CIN\_CONFIG\_MAX\_TIMING\_MODES

```
#define CIN_CONFIG_MAX_TIMING_MODES 20
```

20 states max

## 7.2 src/cin\_register\_map.h File Reference

### Macros

- #define [REG\\_COMMAND](#) 0x0001
- #define **REG\_READ\_ADDRESS** 0x0002
- #define [REG\\_STREAM\\_TYPE](#) 0x0003
- #define **CMD\_FCLK\_125** 0xB000
- #define **CMD\_FCLK\_200** 0x7000
- #define [CMD\\_FCLK\\_250](#) 0x3000
- #define **REG\_IF\_MAC0** 0x0010
- #define **REG\_IF\_MAC1** 0x0011
- #define **REG\_IF\_MAC2** 0x0012
- #define **REG\_IF\_IP0** 0x0013
- #define **REG\_IF\_IP1** 0x0014
- #define **REG\_IF\_CMD\_PORT\_NUM** 0x001A
- #define **REG\_IF\_STREAM\_IN\_PORT\_NUM** 0x001C
- #define **REG\_IF\_STREAM\_OUT\_PORT\_NUM** 0x001D
- #define [REG\\_ETH\\_RESET](#) 0x0020
- #define [REG\\_ETH\\_ENABLE](#) 0x0021
- #define [REG\\_PHY1\\_MDIO\\_CMD](#) 0x0022
- #define **REG\_PHY1\_MDIO\_CMD\_DATA** 0x0023
- #define **REG\_PHY1\_MDIO\_STATUS** 0x0024
- #define **REG\_PHY1\_MDIO\_RD\_ADDR** 0x0025
- #define **REG\_PHY1\_MDIO\_RD\_DATA** 0x0026
- #define [REG\\_MAC\\_CFG\\_VECTOR1](#) 0x0027
- #define **REG\_PHY2\_MDIO\_CMD** 0x0028
- #define **REG\_PHY2\_MDIO\_CMD\_DATA** 0x0029

- #define **REG\_PHY2\_MDIO\_STATUS** 0x002A
- #define **REG\_PHY2\_MDIO\_RD\_ADDR** 0x002B
- #define **REG\_PHY2\_MDIO\_RD\_DATA** 0x002C
- #define **REG\_MAC\_CFG\_VECTOR2** 0x002D
- #define **CMD\_PS\_ENABLE** 0x0021
- #define **CMD\_PS\_POWERDOWN** 0x0022
- #define **REG\_PS\_ENABLE** 0x0030
- #define **REG\_PS\_SYNC\_DIV0** 0x0031
- #define **REG\_PS\_SYNC\_DIV1** 0x0032
- #define **REG\_PS\_SYNC\_DIV2** 0x0033
- #define **REG\_PS\_SYNC\_DIV3** 0x0034
- #define **REG\_PS\_SYNC\_DIV4** 0x0035
- #define **CMD\_PROGRAM\_FRAME** 0x0041
- #define **REG\_FRM\_RESET** 0x0036
- #define **REG\_FRM\_10GbE\_SEL** 0x0037;
- #define **CMD\_ENABLE\_CLKS** 0x0031
- #define **CMD\_DISABLE\_CLKS** 0x0032
- #define **REG\_CLOCK\_EN\_REG** 0x0038
- #define **REG\_SI570\_REG0** 0x0039
- #define **REG\_SI570\_REG1** 0x003A
- #define **REG\_SI570\_REG2** 0x003B
- #define **REG\_SI570\_REG3** 0x003C
- #define **CMD\_MON\_STOP** 0x0011
- #define **CMD\_MON\_START** 0x0012
- #define **REG\_VMON\_ADC1\_CH1** 0x0040 /\* V12P\_BUS Voltage Monitor \*/
- #define **REG\_IMON\_ADC1\_CH0** 0x0041 /\* V12P\_BUS Current Monitor \*/
- #define **REG\_VMON\_ADC0\_CH5** 0x0042 /\* V3P3\_MGMT Voltage Monitor \*/
- #define **REG\_IMON\_ADC0\_CH5** 0x0043 /\* V3P3\_MGMT Current Monitor \*/
- #define **REG\_VMON\_ADC0\_CH4** 0x0044 /\* V3P3\_S3E Voltage Monitor \*/
- #define **REG\_IMON\_ADC0\_CH4** 0x0045 /\* V3P3\_S3E Current Monitor \*/
- #define **REG\_VMON\_ADC0\_CH7** 0x0046 /\* V2P5\_MGMT Voltage Monitor \*/
- #define **REG\_IMON\_ADC0\_CH7** 0x0047 /\* V2P5\_MGMT Current Monitor \*/
- #define **REG\_VMON\_ADC0\_CH6** 0x0048 /\* V1P8\_MGMT Voltage Monitor \*/
- #define **REG\_IMON\_ADC0\_CH6** 0x0049 /\* V1P8\_MGMT Current Monitor \*/
- #define **REG\_VMON\_ADC0\_CH2** 0x004A /\* V1P2\_MGMT Voltage Monitor \*/
- #define **REG\_IMON\_ADC0\_CH2** 0x004B /\* V1P2\_MGMT Current Monitor \*/
- #define **REG\_VMON\_ADC0\_CH3** 0x004C /\* V1P0\_ENET Voltage Monitor \*/
- #define **REG\_IMON\_ADC0\_CH3** 0x004D /\* V1P0\_ENET Current Monitor \*/
- #define **REG\_VMON\_ADC0\_CH8** 0x004E /\* V3P3\_GEN Voltage Monitor \*/
- #define **REG\_IMON\_ADC0\_CH8** 0x004F /\* V3P3\_GEN Current Monitor \*/
- #define **REG\_VMON\_ADC0\_CH9** 0x0050 /\* V2P5\_GEN Voltage Monitor \*/
- #define **REG\_IMON\_ADC0\_CH9** 0x0051 /\* V2P5\_GEN Current Monitor \*/
- #define **REG\_VMON\_ADC0\_CHE** 0x0052 /\* V0P9\_V6 Voltage Monitor \*/
- #define **REG\_IMON\_ADC0\_CHE** 0x0053 /\* V0P9\_V6 Current Monitor \*/
- #define **REG\_VMON\_ADC0\_CHD** 0x0054 /\* V2P5\_V6 Voltage Monitor \*/
- #define **REG\_IMON\_ADC0\_CHD** 0x0055 /\* V2P5\_V6 Current Monitor \*/
- #define **REG\_VMON\_ADC0\_CHB** 0x0056 /\* V1P0\_V6 Voltage Monitor \*/
- #define **REG\_IMON\_ADC0\_CHB** 0x0057 /\* V1P0\_V6 Current Monitor \*/
- #define **REG\_VMON\_ADC0\_CHC** 0x0058 /\* V1P2\_V6 Voltage Monitor \*/
- #define **REG\_IMON\_ADC0\_CHC** 0x0059 /\* V1P2\_V6 Current Monitor \*/
- #define **REG\_VMON\_ADC0\_CHF** 0x005A /\* V5P0\_FP Voltage Monitor (1/2) \*/
- #define **REG\_IMON\_ADC0\_CHF** 0x005B /\* V5P0\_FP Current Monitor (1/2) \*/
- #define **REG\_DCM\_STATUS** 0x0080
- #define **REG\_FPGA\_STATUS** 0x0081
- #define **REG\_BOARD\_ID** 0x008D



- #define **REG\_HW\_SERIAL\_NUM** 0x008E
- #define **REG\_FPGA\_VERSION** 0x008F
- #define **REG\_SANDBOX\_REG00** 0x00F0
- #define **REG\_SANDBOX\_REG01** 0x00F1
- #define **REG\_SANDBOX\_REG02** 0x00F2
- #define **REG\_SANDBOX\_REG03** 0x00F3
- #define **REG\_SANDBOX\_REG04** 0x00F4
- #define **REG\_SANDBOX\_REG05** 0x00F5
- #define **REG\_SANDBOX\_REG06** 0x00F6
- #define **REG\_SANDBOX\_REG07** 0x00F7
- #define **REG\_SANDBOX\_REG08** 0x00F8
- #define **REG\_SANDBOX\_REG09** 0x00F9
- #define **REG\_SANDBOX\_REG0A** 0x00FA
- #define **REG\_SANDBOX\_REG0B** 0x00FB
- #define **REG\_SANDBOX\_REG0C** 0x00FC
- #define **REG\_SANDBOX\_REG0D** 0x00FD
- #define **REG\_SANDBOX\_REG0E** 0x00FE
- #define **REG\_SANDBOX\_REG0F** 0x00FF
- #define **REG\_FRM\_COMMAND** 0x8001
- #define **REG\_FRM\_READ\_ADDRESS** 0x8002
- #define **REG\_FRM\_STREAM\_TYPE** 0x8003
- #define **CMD\_SEND\_SYNC\_PULSE** 0x0100
- #define **CMD\_SYNC\_DETECTOR2READOUT** 0x0101
- #define **CMD\_WR\_CCD\_BIAS\_REG** 0x0102
- #define **CMD\_WR\_CCD\_CLOCK\_REG** 0x0103
- #define **CMD\_SEND\_FCRIC\_CONFIG** 0x0105
- #define **CMD\_RESET\_FRAME\_COUNT** 0x0106
- #define **REG\_IF\_MAC\_FAB1B0** 0x8010
- #define **REG\_IF\_MAC\_FAB1B1** 0x8011
- #define **REG\_IF\_MAC\_FAB1B2** 0x8012
- #define **REG\_IF\_IP\_FAB1B0** 0x8013
- #define **REG\_IF\_IP\_FAB1B1** 0x8014
- #define **REG\_IF\_CMD\_PORT\_NUM\_FAB1B** 0x8015
- #define **REG\_IF\_STREAM\_IN\_PORT\_NUM\_FAB1B** 0x8016
- #define **REG\_IF\_STREAM\_OUT\_PORT\_NUM\_FAB1B** 0x8017
- #define **REG\_XAUI\_FAB1B** 0x8018
- #define **REG\_MAC\_CONFIG\_VEC\_FAB1B0** 0x8019
- #define **REG\_MAC\_CONFIG\_VEC\_FAB1B1** 0x801A
- #define **REG\_MAC\_STATS1\_FAB1B0** 0x801B
- #define **REG\_MAC\_STATS1\_FAB1B1** 0x801C
- #define **REG\_MAC\_STATS2\_FAB1B0** 0x801D
- #define **REG\_MAC\_STATS2\_FAB1B1** 0x801E
- #define **REG\_IF\_MAC\_FAB2B0** 0x8020
- #define **REG\_IF\_MAC\_FAB2B1** 0x8021
- #define **REG\_IF\_MAC\_FAB2B2** 0x8022
- #define **REG\_IF\_IP\_FAB2B0** 0x8023
- #define **REG\_IF\_IP\_FAB2B1** 0x8024
- #define **REG\_IF\_CMD\_PORT\_NUM\_FAB2B** 0x8025
- #define **REG\_IF\_STREAM\_IN\_PORT\_NUM\_FAB2B** 0x8026
- #define **REG\_IF\_STREAM\_OUT\_PORT\_NUM\_FAB2B** 0x8027
- #define **REG\_XAUI\_FAB2B** 0x8028
- #define **REG\_MAC\_CONFIG\_VEC\_FAB2B0** 0x8029
- #define **REG\_MAC\_CONFIG\_VEC\_FAB2B1** 0x802A
- #define **REG\_MAC\_STATS1\_FAB2B0** 0x802B
- #define **REG\_MAC\_STATS1\_FAB2B1** 0x802C

- #define **REG\_MAC\_STATS2\_FAB2B0** 0x802D
- #define **REG\_MAC\_STATS2\_FAB2B1** 0x802E
- #define **REG\_SRAM\_COMMAND** 0x8030
- #define **REG\_SRAM\_START\_ADDR1** 0x8031
- #define **REG\_SRAM\_START\_ADDR0** 0x8032
- #define **REG\_SRAM\_STOP\_ADDR1** 0x8033
- #define **REG\_SRAM\_STOP\_ADDR0** 0x8034
- #define **REG\_SRAM\_FRAME\_DATA\_OUT1** 0x8035
- #define **REG\_SRAM\_FRAME\_DATA\_OUT0** 0x8036
- #define **REG\_SRAM\_FRAME\_DATA\_IN1** 0x8037
- #define **REG\_SRAM\_FRAME\_DATA\_IN0** 0x8038
- #define **REG\_SRAM\_FRAME\_DV** 0x8039
- #define **REG\_SRAM\_STATUS1** 0x803A
- #define **REG\_SRAM\_STATUS0** 0x803B
- #define **CMD\_FCLK\_COMMIT** 0x0012
- #define **REG\_FCLK\_I2C\_ADDRESS** 0x8040
- #define **REG\_FCLK\_I2C\_DATA\_WR** 0x8041
- #define **REG\_FCLK\_I2C\_DATA\_RD** 0x8042
- #define **REG\_TRIGGERSELECT\_REG** 0x8050
- #define **REG\_TRIGGERMASK\_REG** 0x8051
- #define **REG\_CCDCLKSELECT\_REG** 0x8052
- #define **REG\_CDCLKDISABLE\_REG** 0x8053
- #define **REG\_FCLK\_SET0** 0xB007
- #define **REG\_FCLK\_SET1** 0xB008
- #define **REG\_FCLK\_SET2** 0xB009
- #define **REG\_FCLK\_SET3** 0xB00A
- #define **REG\_FCLK\_SET4** 0xB00B
- #define **REG\_FCLK\_SET5** 0xB00C
- #define **REG\_FRM\_DCM\_STATUS** 0x8080
- #define **REG\_FRM\_FPGA\_STATUS** 0x8081
- #define **REG\_FRM\_BOARD\_ID** 0x808D
- #define **REG\_FRM\_HW\_SERIAL\_NUM** 0x808E
- #define **REG\_FRM\_FPGA\_VERSION** 0x808F
- #define **REG\_FRM\_SANDBOX\_REG00** 0x80F0
- #define **REG\_FRM\_SANDBOX\_REG01** 0x80F1
- #define **REG\_FRM\_SANDBOX\_REG02** 0x80F2
- #define **REG\_FRM\_SANDBOX\_REG03** 0x80F3
- #define **REG\_FRM\_SANDBOX\_REG04** 0x80F4
- #define **REG\_FRM\_SANDBOX\_REG05** 0x80F5
- #define **REG\_FRM\_SANDBOX\_REG06** 0x80F6
- #define **REG\_FRM\_SANDBOX\_REG07** 0x80F7
- #define **REG\_FRM\_SANDBOX\_REG08** 0x80F8
- #define **REG\_FRM\_SANDBOX\_REG09** 0x80F9
- #define **REG\_FRM\_SANDBOX\_REG0A** 0x80FA
- #define **REG\_FRM\_SANDBOX\_REG0B** 0x80FB
- #define **REG\_FRM\_SANDBOX\_REG0C** 0x80FC
- #define **REG\_FRM\_SANDBOX\_REG0D** 0x80FD
- #define **REG\_FRM\_SANDBOX\_REG0E** 0x80FE
- #define **REG\_FRM\_SANDBOX\_REG0F** 0x80FF
- #define **REG\_DETECTOR\_REVISION\_REG** 0x8100
- #define **REG\_DETECTOR\_CONFIG\_REG1** 0x8101
- #define **REG\_DETECTOR\_CONFIG\_REG2** 0x8102
- #define **REG\_DETECTOR\_CONFIG\_REG3** 0x8103
- #define **REG\_DETECTOR\_CONFIG\_REG4** 0x8104
- #define **REG\_DETECTOR\_CONFIG\_REG5** 0x8105

- `#define REG_DETECTOR_CONFIG_REG6 0x8106`
- `#define REG_DETECTOR_CONFIG_REG7 0x8107`
- `#define REG_DETECTOR_CONFIG_REG8 0x8108`
- `#define REG_IMG_PROC_REVISION_REG 0x8120`
- `#define REG_IMG_PROC_CONFIG_REG1 0x8121`
- `#define REG_IMG_PROC_CONFIG_REG2 0x8122`
- `#define REG_IMG_PROC_CONFIG_REG3 0x8123`
- `#define REG_IMG_PROC_CONFIG_REG4 0x8124`
- `#define REG_IMG_PROC_CONFIG_REG5 0x8125`
- `#define REG_IMG_PROC_CONFIG_REG6 0x8126`
- `#define REG_IMG_PROC_CONFIG_REG7 0x8127`
- `#define REG_IMG_PROC_CONFIG_REG8 0x8128`
- `#define REG_BIASANDCLOCKREGISTERADDRESS 0x8200`
- `#define REG_BIASANDCLOCKREGISTERDATA 0x8201`
- `#define REG_CLOCKREGISTERDATAOUT 0x8202`
- `#define REG_BIASREGISTERDATAOUT 0x8203`
- `#define REG_BIASCONFIGREGISTER0_REG 0x8204`
- `#define REG_CLOCKCONFIGREGISTER0_REG 0x8205`
- `#define REG_BIASPARAM_READ_START 0x3000`
- `#define REG_EXPOSURETIMEMSB_REG 0x8206`
- `#define REG_EXPOSURETIMELSB_REG 0x8207`
- `#define REG_ALTEXPOSURETIMEMSB_REG 0x8306`
- `#define REG_ALTEXPOSURETIMELSB_REG 0x8307`
- `#define REG_TRIGGERREPETITIONTIMEMSB_REG 0x8208`
- `#define REG_TRIGGERREPETITIONTIMELSB_REG 0x8209`
- `#define REG_DELAYTOEXPOSUREMSB_REG 0x820A`
- `#define REG_DELAYTOEXPOSURELSB_REG 0x820B`
- `#define REG_NUMBEROFEXPOSURE_REG 0x820C`
- `#define REG_SHUTTERTIMEMSB_REG 0x820D`
- `#define REG_SHUTTERTIMELSB_REG 0x820E`
- `#define REG_DELAYTOSHUTTERMSB_REG 0x820F`
- `#define REG_DELAYTOSHUTTERLSB_REG 0x8210`
- `#define REG_FCRIC_MASK_REG1 0x8211`
- `#define REG_FCRIC_MASK_REG2 0x8212`
- `#define REG_FCRIC_MASK_REG3 0x8213`
- `#define REG_LVDS_OVERFLOW_ERROR_REG1 0x8214`
- `#define REG_LVDS_OVERFLOW_ERROR_REG2 0x8215`
- `#define REG_LVDS_OVERFLOW_ERROR_REG3 0x8216`
- `#define REG_LVDS_PARITY_ERROR_REG1 0x8217`
- `#define REG_LVDS_PARITY_ERROR_REG2 0x8218`
- `#define REG_LVDS_PARITY_ERROR_REG3 0x8219`
- `#define REG_LVDS_STOP_BIT_ERROR_REG1 0x821A`
- `#define REG_LVDS_STOP_BIT_ERROR_REG2 0x821B`
- `#define REG_LVDS_STOP_BIT_ERROR_REG3 0x821C`
- `#define REG_FCRIC_WRITE0_REG 0x821D`
- `#define REG_FCRIC_WRITE1_REG 0x821E`
- `#define REG_FCRIC_WRITE2_REG 0x821F`
- `#define REG_FCRIC_READ0_REG 0x8220`
- `#define REG_FCRIC_READ1_REG 0x8221`
- `#define REG_FCRIC_READ2_REG 0x8222`
- `#define REG_DEBUGVIDEO0_REG 0x8223`
- `#define REG_DEBUGVIDEO1_REG 0x8224`
- `#define REG_DEBUGVIDEO2_REG 0x8225`
- `#define REG_DEBUGVIDEO3_REG 0x8226`
- `#define REG_DEBUGVIDEO4_REG 0x8227`

- #define **REG\_DEBUGVIDEO5\_REG** 0x8228
- #define **REG\_DEBUGVIDEO6\_REG** 0x8229
- #define **REG\_DEBUGVIDEO7\_REG** 0x822A
- #define **REG\_DEBUGVIDEO8\_REG** 0x822B
- #define **REG\_DEBUGVIDEO9\_REG** 0x822C
- #define **REG\_DEBUGVIDEO10\_REG** 0x822D
- #define **REG\_DEBUGVIDEO11\_REG** 0x822E
- #define **REG\_DEBUGCOUNTER00\_REG** 0x822F
- #define **REG\_DEBUGCOUNTER01\_REG** 0x8230
- #define **REG\_DEBUGCOUNTER02\_REG** 0x8231
- #define **REG\_DEBUGCOUNTER03\_REG** 0x8232
- #define **REG\_DEBUGCOUNTER04\_REG** 0x8233
- #define **CMD\_READ\_REG** 0x0001

### 7.2.1 Detailed Description

<vim: set ts=2 sw=2 tw=0 noet : <

#### Author

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### 7.2.3 DESCRIPTION

Control and Frame FPGA Register Map

## 7.2.4 Macro Definition Documentation

### 7.2.4.1 CMD\_DISABLE\_CLKS

```
#define CMD_DISABLE_CLKS 0x0032
```

Disable Frame FPGA clock crystals

### 7.2.4.2 CMD\_ENABLE\_CLKS

```
#define CMD_ENABLE_CLKS 0x0031
```

Enable selected Frame FPGA clock crystals

### 7.2.4.3 CMD\_FCLK\_250

```
#define CMD_FCLK_250 0x3000
```

Ethernet Interface

### 7.2.4.4 CMD\_FCLK\_COMMIT

```
#define CMD_FCLK_COMMIT 0x0012
```

Start I2C Write/Read

### 7.2.4.5 CMD\_MON\_START

```
#define CMD_MON_START 0x0012
```

Start voltage and current monitor

### 7.2.4.6 CMD\_MON\_STOP

```
#define CMD_MON_STOP 0x0011
```

Stop voltage and current monitor

### 7.2.4.7 CMD\_PS\_ENABLE

```
#define CMD_PS_ENABLE 0x0021
```

Enable Selected Power Modules

#### 7.2.4.8 CMD\_PS\_POWERDOWN

```
#define CMD_PS_POWERDOWN 0x0022
```

Start power down sequence

#### 7.2.4.9 CMD\_READ\_REG

```
#define CMD_READ_REG 0x0001
```

Read Register CIN\_REGISTER\_MAP\_H

#### 7.2.4.10 CMD\_RESET\_FRAME\_COUNT

```
#define CMD_RESET_FRAME_COUNT 0x0106
```

RESET STATISTICS/DEBUG COUNTERS Ethernet Interface

#### 7.2.4.11 CMD\_SEND\_FCRIC\_CONFIG

```
#define CMD_SEND_FCRIC_CONFIG 0x0105
```

SEND CONFIG DATA TO FRIC

#### 7.2.4.12 CMD\_SEND\_SYNC\_PULSE

```
#define CMD_SEND_SYNC_PULSE 0x0100
```

ISSUES A SYNC PULSE

#### 7.2.4.13 CMD\_SYNC\_DETECTOR2READOUT

```
#define CMD_SYNC_DETECTOR2READOUT 0x0101
```

COMMAND TO SYNC DETECTOR AND READOUT (SEE IMAGE PROCESSING)

#### 7.2.4.14 CMD\_WR\_CCD\_BIAS\_REG

```
#define CMD_WR_CCD_BIAS_REG 0x0102
```

WRITE CCD BIAS REGISTERS

#### 7.2.4.15 CMD\_WR\_CCD\_CLOCK\_REG

```
#define CMD_WR_CCD_CLOCK_REG 0x0103
```

WRITE CCD CLOCK REGISTER

**7.2.4.16 REG\_BIASCONFIGREGISTER0\_REG**

```
#define REG_BIASCONFIGREGISTER0_REG 0x8204
```

Clock Static Registers

**7.2.4.17 REG\_BIASREGISTERDATAOUT**

```
#define REG_BIASREGISTERDATAOUT 0x8203
```

Bias Static Registers

**7.2.4.18 REG\_CLOCK\_EN\_REG**

```
#define REG_CLOCK_EN_REG 0x0038
```

Clock Enable Register Programmable Si570 Clock Registers

**7.2.4.19 REG\_CLOCKCONFIGREGISTER0\_REG**

```
#define REG_CLOCKCONFIGREGISTER0_REG 0x8205
```

Bias Voltage

**7.2.4.20 REG\_COMMAND**

```
#define REG_COMMAND 0x0001
```

<Command Registers

**7.2.4.21 REG\_DEBUGCOUNTER04\_REG**

```
#define REG_DEBUGCOUNTER04_REG 0x8233
```

```
=====
```

**CIN Commands**

Common Commands

**7.2.4.22 REG\_DELAYTOSHUTTERLSB\_REG**

```
#define REG_DELAYTOSHUTTERLSB_REG 0x8210
```

Digitizer Registers

#### 7.2.4.23 REG\_ETH\_ENABLE

```
#define REG_ETH_ENABLE 0x0021
```

Enable Eth Hardware 1=Rx, 2=Tx, 3=Both

#### 7.2.4.24 REG\_ETH\_RESET

```
#define REG_ETH_RESET 0x0020
```

Reset Eth Hardware 1=Rx, 2=Tx, 3=Both

#### 7.2.4.25 REG\_FCLK\_I2C\_ADDRESS

```
#define REG_FCLK_I2C_ADDRESS 0x8040
```

[ Slave Address(7), RD/WRn(1), Reg Address(8) ] Slave address Hx58 -> HxB when shifted up by 1

#### 7.2.4.26 REG\_FCLK\_I2C\_DATA\_RD

```
#define REG_FCLK_I2C_DATA_RD 0x8042
```

[ Read Failed (1), Write Failed(1), Toggle bit(1), 0(5), Read Data (8) ]

#### 7.2.4.27 REG\_FCLK\_I2C\_DATA\_WR

```
#define REG_FCLK_I2C_DATA_WR 0x8041
```

[ Clock Select(2), Clock Enable (1), 0(5), Write Data (8) ] Clock Select: (00): 250 MHz (01): 200 MHz (10): FPGA FCRIC Clk (11): Si570 Programmable

#### 7.2.4.28 REG\_FCLK\_SET5

```
#define REG_FCLK_SET5 0xB00C
```

FRM Status

#### 7.2.4.29 REG\_FPGA\_VERSION

```
#define REG_FPGA_VERSION 0x008F
```

Sandbox Registers



#### 7.2.4.30 REG\_FRM\_10GbE\_SEL

```
#define REG_FRM_10GbE_SEL 0x0037;
```

10GbE Link Select Clock Enables

#### 7.2.4.31 REG\_FRM\_FPGA\_VERSION

```
#define REG_FRM_FPGA_VERSION 0x808F
```

Sandbox Registers

#### 7.2.4.32 REG\_FRM\_RESET

```
#define REG_FRM_RESET 0x0036
```

Frame Reset

#### 7.2.4.33 REG\_FRM\_SANDBOX\_REG0F

```
#define REG_FRM_SANDBOX_REG0F 0x80FF
```

Image Processing Registers

#### 7.2.4.34 REG\_FRM\_STREAM\_TYPE

```
#define REG_FRM_STREAM_TYPE 0x8003
```

List of Commands

#### 7.2.4.35 REG\_IMON\_ADC0\_CHF

```
#define REG_IMON_ADC0_CHF 0x005B /* V5P0_FP Current Monitor (1/2) */
```

Status Registers

#### 7.2.4.36 REG\_MAC\_CFG\_VECTOR1

```
#define REG_MAC_CFG_VECTOR1 0x0027
```

Ethernet Hardware Conf

#### 7.2.4.37 REG\_MAC\_CFG\_VECTOR2

```
#define REG_MAC_CFG_VECTOR2 0x002D
```

Ethernet Hardware Conf Power Supply Control

#### 7.2.4.38 REG\_MAC\_STATS2\_FAB2B1

```
#define REG_MAC_STATS2_FAB2B1 0x802E
```

SRAM Test Interface

#### 7.2.4.39 REG\_PHY1\_MDIO\_CMD

```
#define REG_PHY1_MDIO_CMD 0x0022
```

Start(1), RnW(1), WDRd(1), PHY Addr(5), REG Addr(5)

#### 7.2.4.40 REG\_PS\_ENABLE

```
#define REG_PS_ENABLE 0x0030
```

Power Supply Enable:

#### 7.2.4.41 REG\_PS\_SYNC\_DIV0

```
#define REG_PS_SYNC_DIV0 0x0031
```

2.5V Gen

#### 7.2.4.42 REG\_PS\_SYNC\_DIV1

```
#define REG_PS_SYNC_DIV1 0x0032
```

3.3V Gen

#### 7.2.4.43 REG\_PS\_SYNC\_DIV2

```
#define REG_PS_SYNC_DIV2 0x0033
```

2.5V Frame

#### 7.2.4.44 REG\_PS\_SYNC\_DIV3

```
#define REG_PS_SYNC_DIV3 0x0034
```

0.9V Frame

#### 7.2.4.45 REG\_PS\_SYNC\_DIV4

```
#define REG_PS_SYNC_DIV4 0x0035
```

5.0V FP Frame FPGA Control

#### 7.2.4.46 REG\_SANDBOX\_REG0F

```
#define REG_SANDBOX_REG0F 0x00FF
```

-----< Frame FPGA Registers > Command Registers

#### 7.2.4.47 REG\_SI570\_REG3

```
#define REG_SI570_REG3 0x003C
```

Power Monitor Registers

#### 7.2.4.48 REG\_SRAM\_COMMAND

```
#define REG_SRAM_COMMAND 0x8030
```

1 bit [0] >> Read NOT Write 2 bits [3:2] >> Modes: – Single RW 0x00 – Burst RW 0x01 – Test/Diagnostic 10 – Sleep 11 1 bit [4] >> start/stop

#### 7.2.4.49 REG\_SRAM\_STATUS0

```
#define REG_SRAM_STATUS0 0x803B
```

Programmable Clock

#### 7.2.4.50 REG\_STREAM\_TYPE

```
#define REG_STREAM_TYPE 0x0003
```

FCLK Values

#### 7.2.4.51 REG\_TRIGGERMASK\_REG

```
#define REG_TRIGGERMASK_REG 0x8051
```

[00]==SW Trigger, [01]==FP TrigIn2, [10]==FP TrigIn1, [11]==FP TrigIn1OR2



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