

UNIVERSITY OF ABERDEEN SESSION 2016–17

EX3030

Degree Examination in EX3030 Heat, Mass, & Momentum Transfer

13th December 2016

2 pm – 5 pm

PLEASE NOTE THE FOLLOWING

- (i) You **must not** have in your possession any material other than that expressly permitted in the rules appropriate to this examination. Where this is permitted, such material **must not** be amended, annotated or modified in any way.
- (ii) You **must not** have in your possession any material that could be determined as giving you an advantage in the examination.
- (iii) You **must not** attempt to communicate with any candidate during the exam, either orally or by passing written material, or by showing material to another candidate, nor must you attempt to view another candidate's work.
- (iv) You **must not** take to your examination desk any electronic devices such as mobile phones or other smart devices. The only exception to this rule is an approved calculator.

Failure to comply with the above will be regarded as cheating and may lead to disciplinary action as indicated in the Academic Quality Handbook Section 7 and particularly Appendix 7.1

Notes:

- (i) Candidates ARE permitted to use an approved calculator.*
- (ii) Candidates ARE permitted to use the Engineering Mathematics Handbook.*
- (iii) Data sheets are attached to the paper.*

Candidates should attempt *all* questions.

Question 1

- a) Describe the physical interpretation of the Grashof number for natural convection. Describe each of its terms and write down an equation for the temperature at which temperature-dependent terms in Gr should be evaluated. [5 marks]
- b) An electric heater of 0.032 m diameter and 0.85 m in length is used to heat a room. Calculate the electrical input (i.e. the sum of heat transferred by convection and radiation) to the heater when the bulk of the air in the room is at 24°C, the walls are at 12°C, and the surface of the heater is at 532°C. For convective heat transfer from the heater, assume the heater is a horizontal cylinder and the Nusselt number is given by

$$\text{Nu} = 0.38(\text{Gr})^{0.25}$$

where all properties are evaluated at the film temperature. You may assume air is an ideal gas, giving $\beta = T^{-1}$. Take the emissivity of the heater surface as $\epsilon = 0.62$ and assume that the surroundings are black. All other properties should be calculated using the steam tables provided. [10 marks]

- c) Using index notation, prove the following vector calculus identity:

$$\nabla^2 f g = f \nabla^2 g + 2(\nabla f) \cdot (\nabla g) + g \nabla^2 f$$

[5 marks]

Note: You must treat f and g as functions of x, y, z .

Question 2

A wire-coating die consists of a cylindrical wire of radius, κR , moving horizontally at a constant velocity, v_{wire} , along the axis of a cylindrical die of radius, R . You may assume the pressure is constant within the die (it is not pressure driven flow) but the flow is driven by the motion of the wire (it is “axial annular Couette flow”). Neglect end effects and assume an isothermal system.

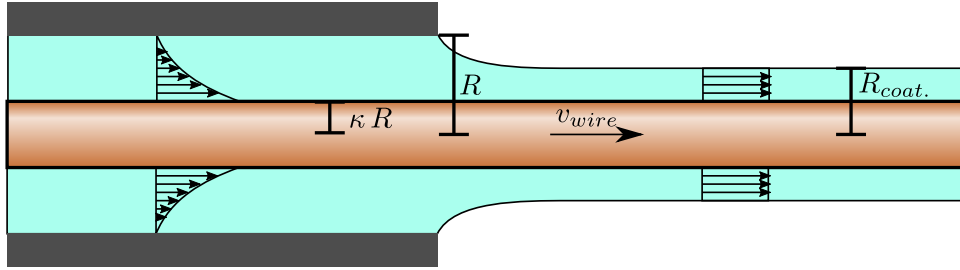


Figure 1: Diagram of a wire coating die.

- State the two relevant boundary conditions for the flow within the die and how they arise. [2 marks]
- The stress profile for an annular system is of the following form

$$\frac{1}{r} \frac{\partial}{\partial r} r \tau_{rz} = -\frac{\partial p}{\partial z} + \rho g_z.$$

Derive the following expression for the flow profile

$$v_z = \frac{v_{wire}}{\ln \kappa} \ln \left(\frac{r}{R} \right).$$

[9 marks]

- Derive the following expression for the volumetric flow-rate of liquid through the die

$$\dot{V}_z = -\pi R^2 v_{wire} \left(\kappa^2 + \frac{1 - \kappa^2}{2 \ln \kappa} \right).$$

[5 marks]

Note: You will need the integration identity

$$\int x \ln(x) dx = \frac{x^2}{2} \left(\ln(x) - \frac{1}{2} \right).$$

- Derive an expression for the outer radius of the coating, $R_{coat.}$, far away from the die exit. [4 marks]

Question 3

To explore the effect of using a temperature-dependent thermal conductivity, consider heat flowing through an annular (pipe) wall of inside radius R_0 and an outside radius R_1 . It is assumed that thermal conductivity varies linearly with temperature from $k_0(T = T_0)$ to $k_1(T = T_1)$ where T_0 and T_1 are the inner and outer wall temperatures respectively.

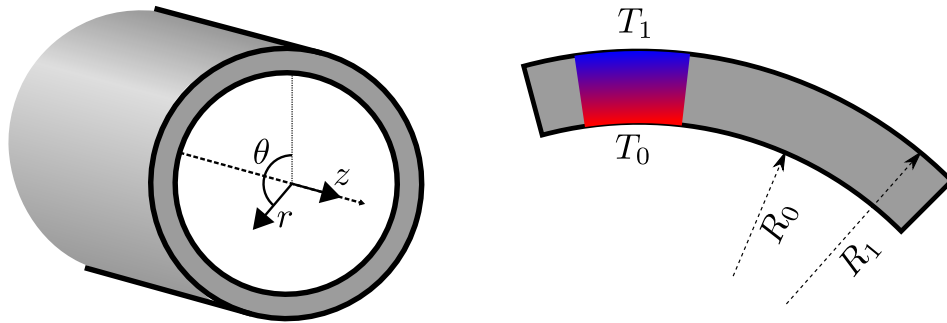


Figure 2: Conduction through an annular(pipe) wall.

- a) Derive the following energy balance equation

$$\frac{\partial}{\partial r} r q_r = 0,$$

and state ALL assumptions required.

[7 marks]

- b) Derive the following expression for the temperature profile

$$Q_r = \frac{2\pi L}{\ln\left(\frac{R_0}{R_1}\right)} \frac{k_1 + k_0}{2} (T_1 - T_0),$$

where L is the length of the pipe/annulus.

[10 marks]

Note: You will need the following identity:

$$T_1^2 - T_0^2 = (T_1 + T_0)(T_1 - T_0).$$

- c) Compare this expression to the standard expression for conduction in pipe walls (with constant thermal conductivity), what can you observe? [3 marks]

Question 4

To maintain a pressure close to 1 atm, an industrial pipeline containing ammonia gas is vented to ambient air. Venting is achieved by tapping the pipe and inserting a 3 mm diameter tube, which extends for 20 m into the atmosphere. With the entire system operating at 25°C and 1 bar, the ideal gas equation of state predicts a total molar concentration of 40.9 mol/m³. Equimolar counter-diffusion can be assumed, and both the concentration of air in the pipeline and the concentration of ammonia in the atmosphere can be considered negligible. The diffusion coefficient of ammonia through air is approximately 2×10^{-5} m²/s.

- a) Determine the mass rate of ammonia lost in to the atmosphere N_A in kg/h and the mass rate of contamination of the pipe with air N_B in the same units. [12 marks]
- b) A new high-tech membrane, which is impermeable to air, is installed at the bottom of the pipe to prevent air polluting the pipeline. The *air* within the tube is now **stationary** and the mole fraction of ammonia at the surface of the membrane is $x_A(z = 0) = 0.9$. Resolve the problem again to determine the flux of ammonia.
Note: Stefan's law (in mole fractions for ideal gases) is given by the following

$$N_{A,z} = -D_{AB} \frac{C_T}{1 - x_A} \frac{\partial x_A}{\partial z}$$

[8 marks]

END OF PAPER

DATASHEET

General balance equations:

$$\frac{\partial \rho}{\partial t} = -\nabla \cdot \rho \mathbf{v} \quad (\text{Mass/Continuity}) \quad (1)$$

$$\frac{\partial C_A}{\partial t} = -\nabla \cdot \mathbf{N}_A + \sigma_A \quad (\text{Species}) \quad (2)$$

$$\rho \frac{\partial \mathbf{v}}{\partial t} = -\rho \mathbf{v} \cdot \nabla \mathbf{v} - \nabla \cdot \boldsymbol{\tau} - \nabla p + \rho \mathbf{g} \quad (\text{Momentum}) \quad (3)$$

$$\rho C_p \frac{\partial T}{\partial t} = -\rho C_p \mathbf{v} \cdot \nabla T - \nabla \cdot \mathbf{q} - \boldsymbol{\tau} : \nabla \mathbf{v} - p \nabla \cdot \mathbf{v} + \sigma_{\text{energy}} \quad (\text{Heat/Energy}) \quad (4)$$

In Cartesian coordinate systems, ∇ can be treated as a vector of derivatives. In curve-linear coordinate systems, the directions \hat{r} , $\hat{\theta}$, and $\hat{\phi}$ depend on the position. For convenience in these systems, look-up tables are provided for common terms involving ∇ .

Cartesian coordinates (with index notation examples)

where s is a scalar, \mathbf{v} is a vector, and $\boldsymbol{\tau}$ is a tensor.

$$\begin{aligned} \nabla s &= \nabla_i s = \left[\frac{\partial s}{\partial x}, \frac{\partial s}{\partial y}, \frac{\partial s}{\partial z} \right] \\ \nabla^2 s &= \nabla_i \nabla_i s = \frac{\partial^2 s}{\partial x^2} + \frac{\partial^2 s}{\partial y^2} + \frac{\partial^2 s}{\partial z^2} \\ \nabla \cdot \mathbf{v} &= \nabla_i v_i = \frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z} \\ \nabla \cdot \boldsymbol{\tau} &= \nabla_i \tau_{ij} \\ [\nabla \cdot \boldsymbol{\tau}]_x &= \frac{\partial \tau_{xx}}{\partial x} + \frac{\partial \tau_{yx}}{\partial y} + \frac{\partial \tau_{zx}}{\partial z} \\ [\nabla \cdot \boldsymbol{\tau}]_y &= \frac{\partial \tau_{xy}}{\partial x} + \frac{\partial \tau_{yy}}{\partial y} + \frac{\partial \tau_{zy}}{\partial z} \\ [\nabla \cdot \boldsymbol{\tau}]_z &= \frac{\partial \tau_{xz}}{\partial x} + \frac{\partial \tau_{yz}}{\partial y} + \frac{\partial \tau_{zz}}{\partial z} \\ \mathbf{v} \cdot \nabla \mathbf{v} &= v_i \nabla_i v_j \\ [\mathbf{v} \cdot \nabla \mathbf{v}]_x &= v_x \frac{\partial v_x}{\partial x} + v_y \frac{\partial v_x}{\partial y} + v_z \frac{\partial v_x}{\partial z} \\ [\mathbf{v} \cdot \nabla \mathbf{v}]_y &= v_x \frac{\partial v_y}{\partial x} + v_y \frac{\partial v_y}{\partial y} + v_z \frac{\partial v_y}{\partial z} \\ [\mathbf{v} \cdot \nabla \mathbf{v}]_z &= v_x \frac{\partial v_z}{\partial x} + v_y \frac{\partial v_z}{\partial y} + v_z \frac{\partial v_z}{\partial z} \end{aligned}$$

Cylindrical coordinates

where s is a scalar, \mathbf{v} is a vector, and $\boldsymbol{\tau}$ is a tensor. All expressions involving $\boldsymbol{\tau}$ are for symmetrical $\boldsymbol{\tau}$ only.

$$\begin{aligned}
 \nabla s &= \left[\frac{\partial s}{\partial r}, \frac{1}{r} \frac{\partial s}{\partial \theta}, \frac{\partial s}{\partial z} \right] \\
 \nabla^2 s &= \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial s}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 s}{\partial \theta^2} + \frac{\partial^2 s}{\partial z^2} \\
 \nabla \cdot \mathbf{v} &= \frac{1}{r} \frac{\partial}{\partial r} (r v_r) + \frac{1}{r} \frac{\partial v_\theta}{\partial \theta} + \frac{\partial v_z}{\partial z} \\
 [\nabla \cdot \boldsymbol{\tau}]_r &= \frac{1}{r} \frac{\partial}{\partial r} (r \tau_{rr}) + \frac{1}{r} \frac{\partial \tau_{r\theta}}{\partial \theta} - \frac{1}{r} \tau_{\theta\theta} + \frac{\partial \tau_{rz}}{\partial z} \\
 [\nabla \cdot \boldsymbol{\tau}]_\theta &= \frac{1}{r} \frac{\partial \tau_{\theta\theta}}{\partial \theta} + \frac{\partial \tau_{r\theta}}{\partial r} + \frac{2}{r} \tau_{r\theta} + \frac{\partial \tau_{\theta z}}{\partial z} \\
 [\nabla \cdot \boldsymbol{\tau}]_z &= \frac{1}{r} \frac{\partial}{\partial r} (r \tau_{rz}) + \frac{1}{r} \frac{\partial \tau_{\theta z}}{\partial \theta} + \frac{\partial \tau_{zz}}{\partial z} \\
 [\mathbf{v} \cdot \nabla \mathbf{v}]_r &= v_r \frac{\partial v_r}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_r}{\partial \theta} - \frac{v_\theta^2}{r} + v_z \frac{\partial v_r}{\partial z} \\
 [\mathbf{v} \cdot \nabla \mathbf{v}]_\theta &= v_r \frac{\partial v_\theta}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_\theta}{\partial \theta} + \frac{v_r v_\theta}{r} + v_z \frac{\partial v_\theta}{\partial z} \\
 [\mathbf{v} \cdot \nabla \mathbf{v}]_z &= v_r \frac{\partial v_z}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_z}{\partial \theta} + v_z \frac{\partial v_z}{\partial z}
 \end{aligned}$$

Spherical coordinates

where s is a scalar, \mathbf{v} is a vector, and $\boldsymbol{\tau}$ is a tensor. All expressions involving $\boldsymbol{\tau}$ are for symmetrical $\boldsymbol{\tau}$ only.

$$\begin{aligned}
 \nabla s &= \left[\frac{\partial s}{\partial r}, \frac{1}{r} \frac{\partial s}{\partial \theta}, \frac{1}{r \sin \theta} \frac{\partial s}{\partial \phi} \right] \\
 \nabla^2 s &= \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial s}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial s}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 s}{\partial \phi^2} \\
 \nabla \cdot \mathbf{v} &= \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 v_r) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (v_\theta \sin \theta) + \frac{1}{r \sin \theta} \frac{\partial v_\phi}{\partial \phi} \\
 [\nabla \cdot \boldsymbol{\tau}]_r &= \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 \tau_{rr}) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\tau_{r\theta} \sin \theta) + \frac{1}{r \sin \theta} \frac{\partial \tau_{r\phi}}{\partial \phi} - \frac{\tau_{\theta\theta} + \tau_{\phi\phi}}{r} \\
 [\nabla \cdot \boldsymbol{\tau}]_\theta &= \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 \tau_{r\theta}) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\tau_{\theta\theta} \sin \theta) + \frac{1}{r \sin \theta} \frac{\partial \tau_{\theta\phi}}{\partial \phi} + \frac{\tau_{r\theta}}{r} - \frac{\cot \theta}{r} \tau_{\phi\phi} \\
 [\nabla \cdot \boldsymbol{\tau}]_\phi &= \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 \tau_{r\phi}) + \frac{1}{r} \frac{\partial \tau_{\theta\phi}}{\partial \theta} + \frac{1}{r \sin \theta} \frac{\partial \tau_{\phi\phi}}{\partial \phi} + \frac{\tau_{r\theta}}{r} + \frac{2 \cot \theta}{r} \tau_{\theta\phi} \\
 [\mathbf{v} \cdot \nabla \mathbf{v}]_r &= v_r \frac{\partial v_r}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_r}{\partial \theta} + \frac{v_\phi}{r \sin \theta} \frac{\partial v_r}{\partial \phi} - \frac{v_\theta^2 + v_\phi^2}{r} \\
 [\mathbf{v} \cdot \nabla \mathbf{v}]_\theta &= v_r \frac{\partial v_\theta}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_\theta}{\partial \theta} + \frac{v_\phi}{r \sin \theta} \frac{\partial v_\theta}{\partial \phi} + \frac{v_r v_\theta - v_\phi^2 \cot \theta}{r} \\
 [\mathbf{v} \cdot \nabla \mathbf{v}]_\phi &= v_r \frac{\partial v_\phi}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_\phi}{\partial \theta} + \frac{v_\phi}{r \sin \theta} \frac{\partial v_\phi}{\partial \phi} + \frac{v_r v_\phi + v_\theta v_\phi \cot \theta}{r}
 \end{aligned}$$

Rectangular		Cylindrical		Spherical	
q_x	$-k \frac{\partial T}{\partial x}$	q_r	$-k \frac{\partial T}{\partial r}$	q_r	$-k \frac{\partial T}{\partial r}$
q_y	$-k \frac{\partial T}{\partial y}$	q_θ	$-k \frac{1}{r} \frac{\partial T}{\partial \theta}$	q_θ	$-k \frac{1}{r} \frac{\partial T}{\partial \theta}$
q_z	$-k \frac{\partial T}{\partial z}$	q_z	$-k \frac{\partial T}{\partial z}$	q_ϕ	$-k \frac{1}{r \sin \theta} \frac{\partial T}{\partial \phi}$
τ_{xx}	$-2\mu \frac{\partial v_x}{\partial x} + \mu^B \nabla \cdot \mathbf{v}$	τ_{rr}	$-2\mu \frac{\partial v_r}{\partial r} + \mu^B \nabla \cdot \mathbf{v}$	τ_{rr}	$-2\mu \frac{\partial v_r}{\partial r} + \mu^B \nabla \cdot \mathbf{v}$
τ_{yy}	$-2\mu \frac{\partial v_y}{\partial y} + \mu^B \nabla \cdot \mathbf{v}$	$\tau_{\theta\theta}$	$-2\mu \left(\frac{1}{r} \frac{\partial v_\theta}{\partial \theta} + \frac{v_r}{r} \right) + \mu^B \nabla \cdot \mathbf{v}$	$\tau_{\theta\theta}$	$-2\mu \left(\frac{1}{r} \frac{\partial v_\theta}{\partial \theta} + \frac{v_r}{r} \right) + \mu^B \nabla \cdot \mathbf{v}$
τ_{zz}	$-2\mu \frac{\partial v_z}{\partial z} + \mu^B \nabla \cdot \mathbf{v}$	τ_{zz}	$-2\mu \frac{\partial v_z}{\partial z} + \mu^B \nabla \cdot \mathbf{v}$	$\tau_{\phi\phi}$	$-2\mu \left(\frac{1}{r \sin \theta} \frac{\partial v_\phi}{\partial \phi} + \frac{v_r + v_\theta \cot \theta}{r} \right) + \mu^B \nabla \cdot \mathbf{v}$
τ_{xy}	$-\mu \left(\frac{\partial v_x}{\partial y} + \frac{\partial v_y}{\partial x} \right)$	$\tau_{r\theta}$	$-\mu \left(r \frac{\partial}{\partial r} \left(\frac{v_\theta}{r} \right) + \frac{1}{r} \frac{\partial v_r}{\partial \theta} \right)$	$\tau_{r\theta}$	$-\mu \left(r \frac{\partial}{\partial r} \left(\frac{v_\theta}{r} \right) + \frac{1}{r} \frac{\partial v_r}{\partial \theta} \right)$
τ_{yz}	$-\mu \left(\frac{\partial v_y}{\partial z} + \frac{\partial v_z}{\partial y} \right)$	$\tau_{\theta z}$	$-\mu \left(\frac{1}{r} \frac{\partial v_z}{\partial \theta} + \frac{\partial v_\theta}{\partial z} \right)$	$\tau_{\theta\phi}$	$-\mu \left(\frac{\sin \theta}{r} \frac{\partial}{\partial \theta} \left(\frac{v_\phi}{\sin \theta} \right) + \frac{1}{r \sin \theta} \frac{\partial v_\theta}{\partial \phi} \right)$
τ_{xz}	$-\mu \left(\frac{\partial v_x}{\partial z} + \frac{\partial v_z}{\partial x} \right)$	τ_{zr}	$-\mu \left(\frac{\partial v_r}{\partial z} + \frac{\partial v_z}{\partial r} \right)$	$\tau_{\phi r}$	$-\mu \left(\frac{1}{r \sin \theta} \frac{\partial v_r}{\partial \phi} + r \frac{\partial}{\partial r} \left(\frac{v_\phi}{r} \right) \right)$

Table 1: Fourier's law for the heat flux and Newton's law for the stress in several coordinate systems. Please remember that the stress is symmetric, so $\tau_{ij} = \tau_{ji}$.

Viscous models:

Power-Law Fluid:

$$|\tau_{xy}| = k \left| \frac{\partial v_x}{\partial y} \right|^n \quad (5)$$

Bingham-Plastic Fluid:

$$\frac{\partial v_x}{\partial y} = \begin{cases} -\mu^{-1} (\tau_{xy} - \tau_0) & \text{if } \tau_{xy} > \tau_0 \\ 0 & \text{if } \tau_{xy} \leq \tau_0 \end{cases}$$

Dimensionless Numbers

$$\text{Re} = \frac{\rho \langle v \rangle D}{\mu} \quad \text{Re}_H = \frac{\rho \langle v \rangle D_H}{\mu} \quad \text{Re}_{MR} = -\frac{16 L \rho \langle v \rangle^2}{R \Delta p} \quad (6)$$

The hydraulic diameter is defined as $D_H = 4 A / P_w$.

Single phase pressure drop calculations in pipes:

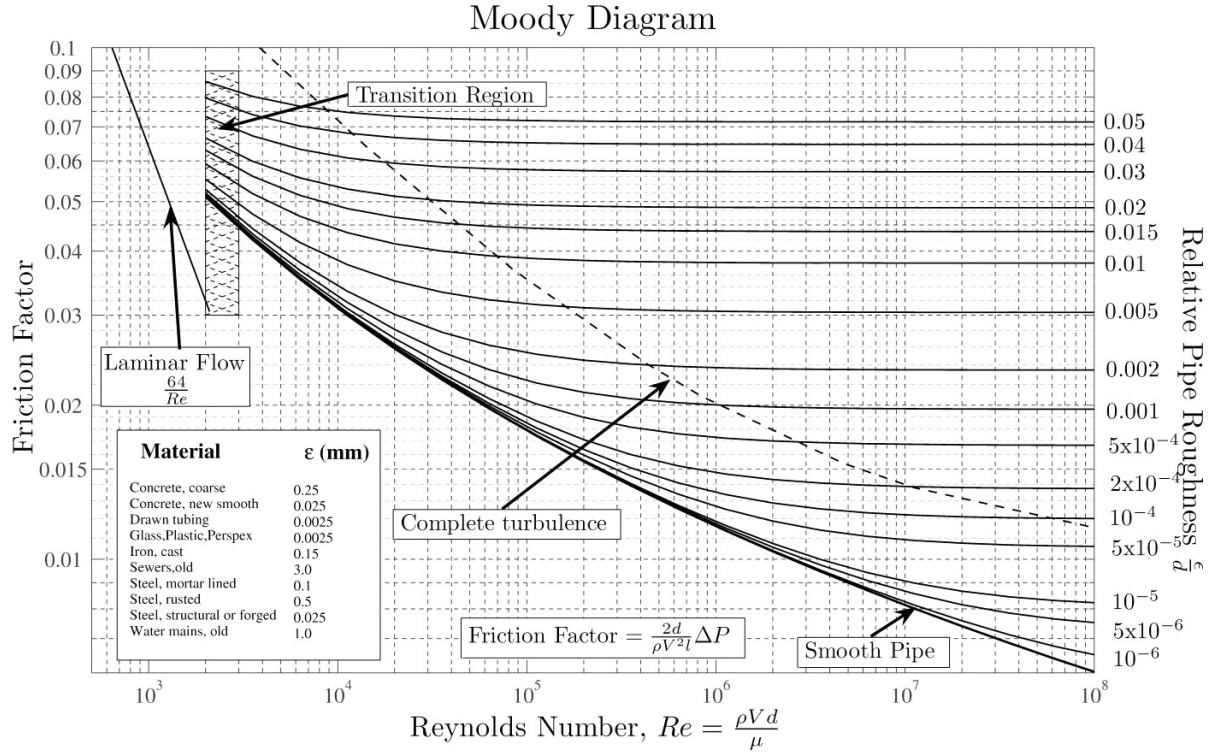
Darcy-Weisbach equation:

$$\frac{\Delta p}{L} = -\frac{C_f \rho \langle v \rangle^2}{R} \quad (7)$$

where $C_f = 16/Re$ for laminar Newtonian flow. For turbulent flow of Newtonian fluids in smooth pipes, we have the Blasius correlation:

$$C_f = 0.079 Re^{-1/4} \quad \text{for } 2.5 \times 10^3 < Re < 10^5 \text{ and smooth pipes.}$$

Otherwise, you may refer to the Moody diagram.



Laminar Power-Law fluid:

$$\dot{V} = \frac{n \pi R^3}{3n + 1} \left(\frac{R}{2k} \right)^{\frac{1}{n}} \left(-\frac{\Delta p}{L} \right)^{\frac{1}{n}}$$

Two-Phase Flow:

Lockhart-Martinelli parameter:

$$X^2 = \frac{\Delta p_{liq.-only}}{\Delta p_{gas.-only}}$$

Pressure drop calculation:

$$\Delta p_{two-phase} = \Phi_{liq.}^2 \Delta p_{liq.-only} = \Phi_{gas.}^2 \Delta p_{gas.-only}$$

Chisholm's relation:

$$\Phi_{gas.}^2 = 1 + cX + X^2$$

$$\Phi_{liq.}^2 = 1 + \frac{c}{X} + \frac{1}{X^2} \quad c = \begin{cases} 20 & \text{turbulent liquid \& turbulent gas} \\ 12 & \text{laminar liquid \& turbulent gas} \\ 10 & \text{turbulent liquid \& laminar gas} \\ 5 & \text{laminar liquid \& laminar gas} \end{cases}$$

Farooqi and Richardson expression for liquid hold-up in co-current flows of Newtonian fluids and air in horizontal pipes:

$$h = \begin{cases} 0.186 + 0.0191 X & 1 < X < 5 \\ 0.143 X^{0.42} & 5 < X < 50 \\ 1/(0.97 + 19/X) & 50 < X < 500 \end{cases}$$

Heat Transfer:

Stefan-Boltzmann constant $\sigma = 5.6703 \times 10^{-8} \text{ W/m}^2 \text{ K}^4$

Heat Transfer Dimensionless numbers:

$$\text{Nu} = \frac{h L}{k} \quad \text{Pr} = \frac{\mu C_p}{k} \quad \text{Gr} = \frac{g \beta (T_w - T_\infty) L^3}{\nu^2}$$

Resistances

$$Q = U_T A_T \Delta T = R_T^{-1} \Delta T \quad Q_{rad.} = \sigma \varepsilon A (T_\infty^4 - T_w^4) = h_{rad.} A (T_\infty - T_w)$$

	Conduction Shell Resistances			Radiation
	Rect.	Cyl.	Sph.	
R	$\frac{X}{k A}$	$\frac{\ln(R_{outer}/R_{inner})}{2 \pi L k}$	$\frac{R_{inner}^{-1} - R_{outer}^{-1}}{4 \pi k}$	$[A \varepsilon \sigma (T_\infty^2 + T_w^2) (T_\infty + T_w)]^{-1}$

Natural Convection

$Ra = Gr Pr$	C	m
$< 10^4$	1.36	1/5
$10^4 - 10^9$	0.59	1/4
$> 10^9$	0.13	1/3

Table 2: Natural convection coefficients for isothermal vertical plates in the empirical relation $Nu \approx C (Gr Pr)^m$.

For isothermal vertical cylinders, the above expressions for isothermal vertical plates may be used but must be scaled by a factor, F :

$$F = \begin{cases} 1 & \text{for } (D/H) < 35 Gr_H^{-1/4} \\ 1.3 [H D^{-1} Gr_D^{-1}]^{1/4} + 1 & \text{for } (D/H) \geq 35 Gr_H^{-1/4} \end{cases}$$

where D is the diameter and H is the height of the cylinder. The subscript on Gr indicates which length is to be used as the critical length to calculate the Grashof number.

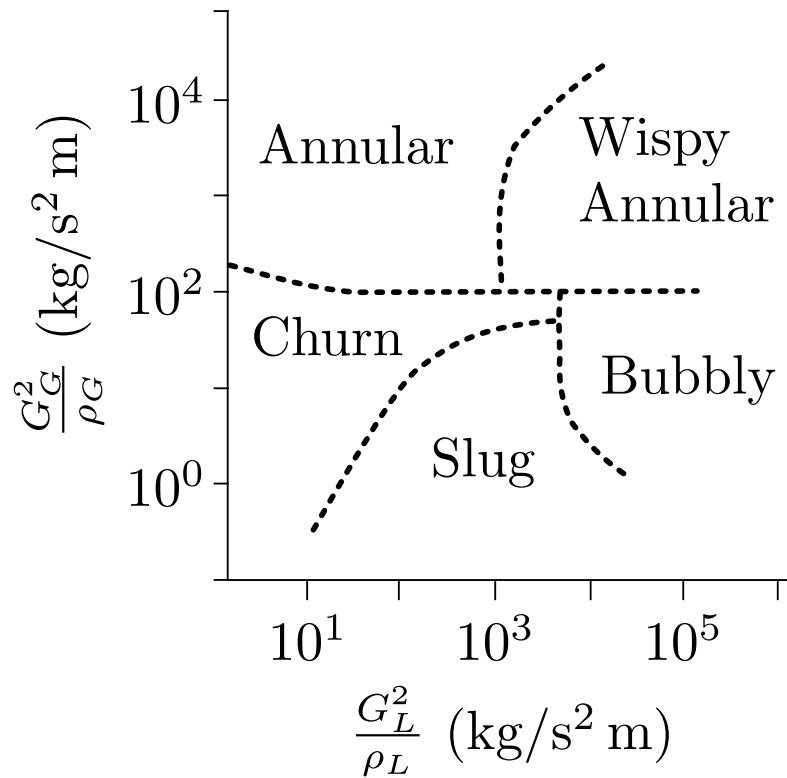


Figure 3: *Hewitt-Taylor flow pattern map for multiphase flows in vertical pipes.*

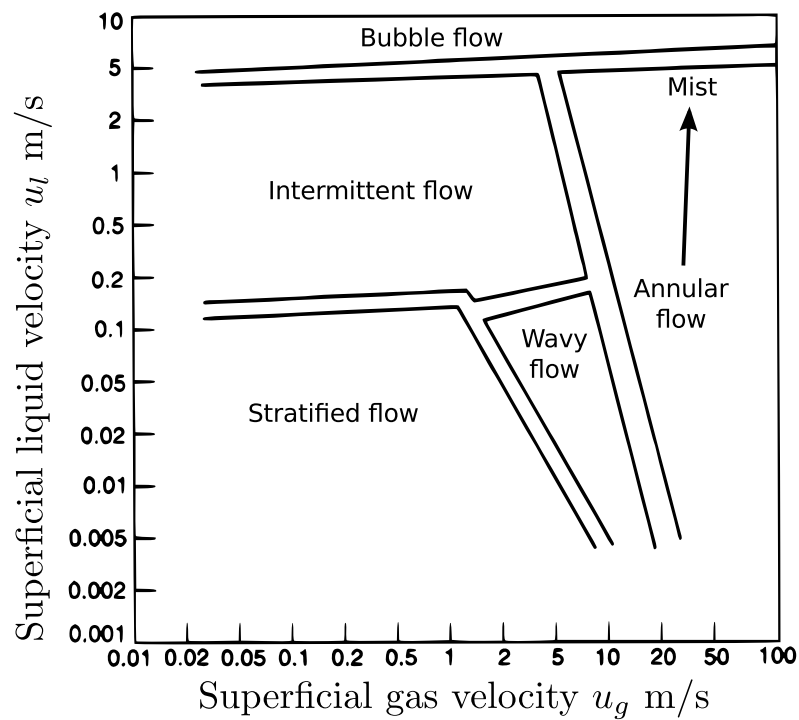


Figure 4: *Chhabra and Richardson flow pattern map for horizontal pipes.*

Churchill and Chu expression for natural convection from a horizontal pipe:

$$\text{Nu}^{1/2} = 0.6 + 0.387 \left\{ \frac{\text{Gr Pr}}{\left[1 + (0.559/\text{Pr})^{9/16} \right]^{16/9}} \right\}^{1/6} \quad \text{for } 10^{-5} < \text{Gr Pr} < 10^{12}$$

Forced Convection:

Laminar flows:

$$\text{Nu} \approx 0.332 \text{Re}^{1/2} \text{Pr}^{1/3}$$

Well-Developed turbulent flows in smooth pipes:

$$\text{Nu} \approx \frac{(C_f/2)\text{Re Pr}}{1.07 + 12.7(C_f/2)^{1/2} (\text{Pr}^{2/3} - 1)} \left(\frac{\mu_b}{\mu_w} \right)^{0.14}$$

Boiling:

Forster-Zuber pool-boiling coefficient:

$$h_{nb} = 0.00122 \frac{k_L^{0.79} C_{p,L}^{0.45} \rho_L^{0.49}}{\gamma^{0.5} \mu_L^{0.29} h_{fg}^{0.24} \rho_G^{0.24}} (T_w - T_{sat})^{0.24} (p_w - p_{sat})^{0.75}$$

Mostinski correlations:

$$h_{nb} = 0.104 p_c^{0.69} q^{0.7} \left[1.8 \left(\frac{p}{p_c} \right)^{0.17} + 4 \left(\frac{p}{p_c} \right)^{1.2} + 10 \left(\frac{p}{p_c} \right)^{10} \right]$$

$$q_c = 3.67 \times 10^4 p_c \left(\frac{p}{p_c} \right)^{0.35} \left[1 - \frac{p}{p_c} \right]^{0.9}$$

(Note: for the Mostinski correlations, the pressures are in units of bar)

Condensing:

Horizontal pipes

$$h = 0.72 \left(\frac{k^3 \rho^2 g_x E_{latent}}{D \mu (T_w - T_\infty)} \right)^{1/4}$$

NTU method:

$$\text{NTU} = \frac{U A}{C_{min}} = \frac{t_{C1} - t_{C2}}{\Delta t_{ln}} \quad R = \frac{C_{min}}{C_{max}}$$

For counter-current flow:

$$E = \frac{1 - \exp[-\text{NTU}(1 - R)]}{1 - R \exp[-\text{NTU}(1 - R)]}$$

For co-current flow:

$$E = \frac{1 - \exp[-NTU(1 - R)]}{1 + R}$$

Lumped capacitance method:

$$\text{Bi} = \frac{h L_c}{k}$$

$$L_c = V/A \quad \text{for Bi} < 0.1$$

$$\frac{\theta}{\theta_i} = \frac{T - T_\infty}{T_i - T_\infty} = \exp \left[-\frac{h A_s}{\rho V C_p} t \right]$$

Diffusion Dimensionless Numbers

$$\text{Sc} = \frac{\mu}{\rho D_{AB}} \quad \text{Le} = \frac{k}{\rho C_p D_{AB}}$$

Diffusion

General expression for the flux:

$$N_A = J_A + x_A \sum_B N_B$$

Fick's law:

$$J_A = -D_{AB} \nabla C_A$$

Stefan's law:

$$N_{s,r} = -D \frac{c}{1-x} \frac{\partial x}{\partial r}$$

Misc

$$PV = nRT \quad R \approx 8.314598 \text{ J K}^{-1} \text{ mol}^{-1}$$