

8. Turbulence Modelling

Objective

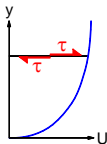
Model the Reynolds stresses

$-\overline{\rho uv}$, $-\overline{\rho uu}$, etc.

in order to close the mean-flow equations.

Eddy-Viscosity Models

Total stress
(in simple shear): $\tau = \underbrace{\mu \frac{\partial U}{\partial y}}_{\text{viscous}} - \overline{\rho uv}$



Eddy-viscosity model: $-\overline{\rho uv} = \mu_t \frac{\partial U}{\partial y}$

Total stress: $\tau = (\mu + \mu_t) \frac{\partial U}{\partial y}$

Effective viscosity: $\mu_{eff} = \mu + \mu_t$

Eddy-Viscosity Models

$$-\overline{\rho uv} = \mu_t \frac{\partial U}{\partial y}$$

- This is a **model**!
- μ is a **physical** property of the **fluid**
 μ_t is a **hypothetical** property of the **flow**
- μ_t varies with position
- At high Reynolds numbers, $\mu_t \gg \mu$

Eddy-Viscosity Models

For

- Easy to implement
- Extra viscosity aids stability
- Theoretical basis in simple flows

Against

- Little foundation in complex flows
- Turbulence modelling reduced to a single scalar, μ_t

Consistency With the Log Law

Logarithmic velocity profile: $\frac{\partial U}{\partial y} = \frac{u_\tau}{\kappa y}$

Total stress constant and dominated by turbulent stress:

$$\tau^{(turb)} = \tau_w \equiv \rho u_\tau^2$$

Definition of eddy viscosity: $\mu_t \equiv \frac{\tau^{(turb)}}{\partial U / \partial y} = \frac{\rho u_\tau^2}{u_\tau / \kappa y} = \rho(\kappa u_\tau y)$

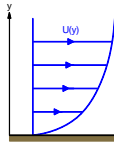
$$\mu_t = \rho(\kappa u_\tau y)$$

$$\nu_t = \kappa u_\tau y$$

General Stress-Strain Relationship

In **simple shear** $(U(y), 0, 0)$:

$$-\rho \overline{uv} = \mu_t \frac{\partial U}{\partial y}$$



In **arbitrary flow**:

$$-\rho \overline{uv} = \mu_t \left(\frac{\partial U}{\partial y} + \frac{\partial V}{\partial x} \right)$$

$$-\rho \overline{uu} = 2\mu_t \frac{\partial U}{\partial x} - \frac{2}{3} \rho k$$

$$-\rho u_i u_j = \mu_t \left(\frac{\partial U_i}{\partial x_j} + \frac{\partial U_j}{\partial x_i} \right) - \frac{2}{3} \rho k \delta_{ij}$$

Reynolds' Analogy

Similar **gradient-diffusion** model for other turbulent fluxes

$$-\rho v \overline{\phi} = \Gamma_t \frac{\partial \phi}{\partial y}$$

$$\Gamma_t = \frac{\mu_t}{\sigma_t}$$

eddy diffusivity

turbulent **Prandtl number**

The Eddy Viscosity

Kinematic eddy viscosity $\nu_t = \frac{\mu_t}{\rho}$

$$\nu_t = u_0 l_0 \quad u_0 \text{ is a typical turbulent velocity}$$
$$l_0 \text{ is a typical turbulent eddy size}$$

e.g. In the **log layer**: $\nu_t = \kappa u_\tau y = u_\tau \times (\kappa y)$

Types of Eddy-Viscosity Model

Based on the number of additional scalar-transport equations.

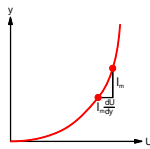
- **Zero-equation models:**
 - constant eddy-viscosity models
 - **mixing-length** models
- **One-equation models:**
 - l_0 specified algebraically; transport equation for u_0
- **Two-equation models:**
 - transport equations for 2 scales (k - ϵ , k - ω , ...)

Mixing-Length Models

Eddy viscosity: $\nu_t = u_0 l_m$

Mixing length l_m specified algebraically

Velocity scale $u_0 = l_m \left| \frac{\partial U}{\partial y} \right|$ from the **mean velocity gradient**



Turbulent shear stress: $\tau^{(turb)} = \mu_t \frac{\partial U}{\partial y} = \rho u_0 l_m \frac{\partial U}{\partial y} = \rho l_m^2 \left(\frac{\partial U}{\partial y} \right)^2$

Consistency With the Log Law

$$\tau^{(turb)} = \rho l_m^2 \left(\frac{\partial U}{\partial y} \right)^2$$

Log-law region: $\frac{\partial U}{\partial y} = \frac{u_\tau}{\kappa y}$

$$\tau^{(turb)} = \tau_w = \rho u_\tau^2$$

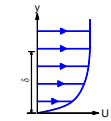
$$\rho u_\tau^2 = \rho l_m^2 \left(\frac{u_\tau}{\kappa y} \right)^2$$

$$l_m = \kappa y$$

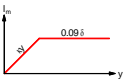
Mixing Length

Wall-bounded flows

l_m related to distance from the wall



$l_m = \min(\kappa y, 0.09\delta)$



Free shear flows

l_m proportional to width of layer



mixing layer

$l_m = 0.071\delta$



jet

$l_m = 0.098\delta$ (plane)

$l_m = 0.080\delta$ (round)



wake

$l_m = 0.180\delta$

The k - ϵ Model

1. Eddy-viscosity model: $\tau^{(turb)} = \mu_t \frac{\partial U}{\partial y}$

2. Formula for the eddy viscosity: $\mu_t = C_\mu \rho \frac{k^2}{\epsilon}$

$\nu_t = C_\mu \frac{k^2}{\epsilon}$

3. Scalar-transport equations for:
 k – turbulent kinetic energy
 ϵ – rate of dissipation of k

The k and ϵ Transport Equations

$\frac{\partial}{\partial t}(\rho k) + \frac{\partial}{\partial x_i}(\rho U_i k - \Gamma^{(k)} \frac{\partial k}{\partial x_i}) = \rho(P^{(k)} - \epsilon)$
 $\frac{\partial}{\partial t}(\rho \epsilon) + \frac{\partial}{\partial x_i}(\rho U_i \epsilon - \Gamma^{(\epsilon)} \frac{\partial \epsilon}{\partial x_i}) = \rho(C_{\epsilon 1} P^{(k)} - C_{\epsilon 2} \epsilon) \frac{\epsilon}{k}$
rate of change advection diffusion source

Diffusivities: $\Gamma^{(k)} = \mu + \frac{\mu_t}{\sigma_k}$, $\Gamma^{(\epsilon)} = \mu + \frac{\mu_t}{\sigma_\epsilon}$

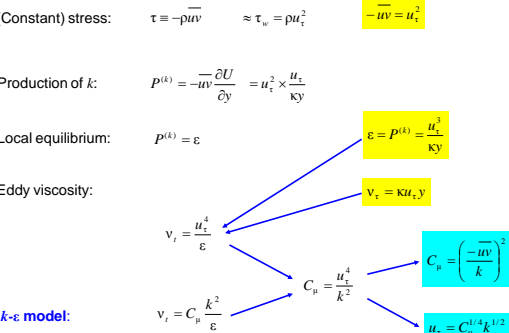
Production: $P^{(k)} = -u_i u_j \frac{\partial U_i}{\partial x_j}$

Constants: $C_\mu = 0.09$, $C_{\epsilon 1} = 1.44$, $C_{\epsilon 2} = 1.92$, $\sigma_k = 1.0$, $\sigma_\epsilon = 1.3$

The k and ε Transport Equations

- Heavily modelled (especially the ε equation)
- Source-dominated, with a balance between:
 - production** by mean flow: $P^{(k)} = -\overline{u_i u_j} \frac{\partial U_i}{\partial x_j}$
 - dissipation** by viscosity: $\varepsilon = \nu \sum_{i,j} \left(\frac{\partial u_i}{\partial x_j} \right)^2$
- Turbulence said to be in **local equilibrium** if $P^{(k)} = \varepsilon$
- Many variants, including low-Reynolds-number models
- Other choices of dimensional scales (e.g k - ω)

Consistency With the Log Law



Example

In the k - ε turbulence model, k is turbulent kinetic energy and ε is its dissipation rate. A (kinematic) eddy viscosity is defined by

$$\nu_t = C_\mu \frac{k^2}{\varepsilon}$$

where C_μ is a constant. A modeled scalar-transport equation for ε is

$$\frac{D\varepsilon}{Dt} = \frac{\partial}{\partial x_i} \left(\frac{\nu_t}{\sigma_\varepsilon} \frac{\partial \varepsilon}{\partial x_j} \right) + (C_{\varepsilon 1} P^{(k)} - C_{\varepsilon 2} \varepsilon) \frac{\varepsilon}{k}$$

where D/Dt is the derivative following the flow, $P^{(k)}$ is the rate of production of k and the summation convention is implied by the repeated index i . σ_ε , $C_{\varepsilon 1}$ and $C_{\varepsilon 2}$ are constants.

In the log-law region of a turbulent boundary layer,

$$P^{(k)} = \varepsilon = \frac{u_\tau^3}{\kappa y} \quad k = C_\mu^{-1/2} u_\tau^2$$

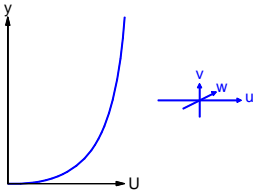
where κ is von Karman's constant, u_τ is the friction velocity and y is the distance from the boundary. Using the scalar-transport equation for ε and the eddy-viscosity formulation, show that this implies the following relationship between coefficients:

$$(C_{\varepsilon 2} - C_{\varepsilon 1}) \sigma_\varepsilon \sqrt{C_\mu} = \kappa^2$$

Limitations of Eddy-Viscosity Models

- For
- Simple to code
 - Extra viscosity aids stability
 - Supported theoretically in some simple but common types of flow
 - Effective in many engineering flows
- Against
- Only capable of predicting one Reynolds-stress component accurately
 - Lack justification in complex flows
 - Fail to predict common properties such as anisotropy

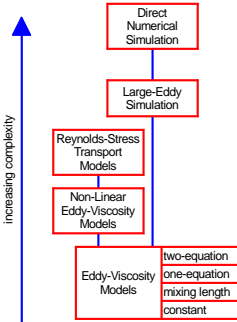
Turbulence Anisotropy



Experiment: $\overline{u^2} : \overline{v^2} : \overline{w^2} = 1.0 : 0.4 : 0.6$

Eddy-viscosity model: $\overline{u^2} = \overline{v^2} = \overline{w^2} = \frac{2}{3} k$

Advanced Turbulence Models



Reynolds-Stress Transport Models

- Solve **individual transport equations** for **each Reynolds stress**
– $\overline{\rho uv}$, – $\overline{\rho uu}$, etc.
- "Source" is a balance between:
 - **production** by mean-velocity gradients
 - **redistribution** by pressure fluctuations
 - **dissipation** by viscous action.

For

- Advection and production are exact and don't need modelling

Against

- Very complex: many terms need modelling
- Computational expense:
 - 6 extra transport equations
 - lack of a stabilising diffusion term

Non-Linear Eddy-Viscosity Models

Simple eddy-viscosity model:

$$\text{stress} \propto \text{velocity gradient} \quad \tau_{xy} = \mu_t \frac{\partial U}{\partial y}$$

Non-linear eddy-viscosity model:

$$\text{stress} = C_1(\text{velocity gradient}) + C_2(\text{velocity gradient})^2 + \dots$$

For

- Qualitatively correct response of turbulence to certain types of strain
- Little more computationally expensive than linear models

Against

- Doesn't accurately reflect the real physical processes
- Little justification in complex geometries

Wall Boundary Conditions

- Near a solid boundary:
 - there are very large flow gradients
 - wall-normal fluctuations are selectively damped
 - viscous and turbulent stresses are comparable
- Alternative approaches:
 - **low-Reynolds-number** turbulence models
 - **wall functions**

Wall Functions

Equilibrium (log law):

$$\frac{U_p}{u_\tau} = \frac{1}{\kappa} \ln(y_p^+) + B = \frac{1}{\kappa} \ln(E y_p^+)$$

$$y_p^+ = \frac{y_p u_\tau}{\nu}$$

$$u_\tau = C_\mu^{1/4} k_p^{1/2}$$

Non-equilibrium:

$$v_\tau = \kappa u_0 y$$

$$\tau_w = \rho(\kappa u_0 y) \frac{\partial U}{\partial y}$$

$$\frac{\partial U}{\partial y} = \frac{\tau_w / \rho}{\kappa u_0 y}$$

$$U = \frac{\tau_w / \rho}{\kappa u_0} \ln(Cy)$$

$$\tau_w = \rho \frac{\kappa u_0 U_p}{\ln(E \frac{y_p u_0}{\nu})}$$

Implemented via an **effective wall viscosity**:

$$\tau_w = \mu_w \frac{U_p}{y_p}$$

$$\mu_w = \frac{\rho(\kappa u_0 y_p)}{\ln(E \frac{y_p u_0}{\nu})}$$

Summary (1)

- A turbulence model or turbulence closure is a means of specifying Reynolds stresses (and other turbulent fluxes)
- The most popular type is an eddy-viscosity model
- The eddy viscosity may be specified:
 - geometrically (e.g. mixing-length models)
 - by solving transport equations (e.g. $k-\epsilon$ model)

Summary (2)

- Advanced turbulence models include:
 - Reynolds-stress transport models (RSTM)
 - non-linear eddy-viscosity models (NLEVM)
 - large-eddy simulation (LES)
- Wall boundary conditions require either:
 - low-Reynolds-number modifications (fine grid)
 - wall functions (coarse grid)
