

**Q.1 Question 1**

- a) Describe the physical interpretation of the Grashof number for natural convection. Describe each of its terms and write down an equation for the temperature at which temperature-dependent terms in Gr should be evaluated. [5 marks]

**Solution:**

- [1] *The Grashof number is the analogue of the Reynolds number for natural convection*  
 [1] *and is the ratio of bouyancy and viscous forces in the fluid. It is defined as*

$$Gr = \frac{g \rho^2 \beta (T_w - T_\infty) L^3}{\mu^2},$$

*where  $g$  is the gravitational acceleration,*

*$\rho$  is the density of the fluid,*

- [1]  *$\beta$  is the thermal expansion coefficient of the fluid,*

*$T_w$  is the wall temperature,*

*$T_\infty$  is the fluid temperature a large distance from the wall (bulk),*

- [1]  *$L$  is a characterstic (and often vertical) length scale,*

*and  $\mu$  is the fluid viscosity.*

*The properties of the flow for the Grashof number should be evaluated at the so-called film temperature,*

$$T_f = (T_w + T_\infty) / 2$$

- [1]

- b) An electric heater of 0.032 m diameter and 0.85 m in length is used to heat a room. Calculate the electrical input (i.e. the sum of heat transferred by convection and radiation) to the heater when the bulk of the air in the room is at 24°C, the walls are at 12°C, and the surface of the heater is at 532°C. For convective heat transfer from the heater, assume the heater is a horizontal cylinder and the Nusselt number is given by

$$Nu = 0.38(Gr)^{0.25}$$

where all properties are evaluated at the film temperature. You may assume air is an ideal gas, giving  $\beta = T^{-1}$ . Take the emissivity of the heater surface as  $\epsilon = 0.62$  and assume that the surroundings are black. All other properties should be calculated using the steam tables provided. [10 marks]

**Solution:**

*Calculating the film temperature, we have*

$$T_f = \frac{532 + 24}{2} = 278^\circ \text{C} = 551 \text{ K}$$

- [1]

- [2] *From the tables at 551 K,  $\nu = 4.48 \times 10^{-5} \text{ m}^2 \text{ s}^{-1}$  and  $k = 0.04375 \text{ W m}^{-1} \text{ K}^{-1}$ . The*

[1] *expansion coefficient is  $\beta = 551^{-1} K^{-1}$ . Combining these we have:*

$$Gr = \frac{9.81 (532 - 24) 0.032^3}{551 (4.48 \times 10^{-5})^2} \approx 147\,700$$

[1] *Calculating the Nusselt number, we have*

$$Nu = 0.38 (147\,700)^{1/4} \approx 7.45$$

[1] *Calculating the convective coefficient we have*

$$h = \frac{k Nu}{L} = \frac{0.04375 \times 7.45}{0.032} \approx 10.19 W m^{-2} K^{-1}$$

[1] *Heat transfer via convection:*

$$Q_{conv} = h A \Delta T = 10.19 \times \pi \times 0.032 \times 0.85 (532 - 24) \approx 442 W$$

[1] *Heat transfer by radiation*

$$\begin{aligned} Q_{rad.} &= \sigma \epsilon A (T_w^4 - T_\infty^4) \\ &= 5.67 \times 10^{-8} \times 0.62 \times \pi \times 0.032 \times 0.85 (805^4 - 285^4) \\ &\approx 1242 \end{aligned}$$

[1] *Total energy input is*

$$Q_{total} = Q_{rad.} + Q_{conv} = 1242 + 442 = 1684 W$$

[1] c) Using index notation, prove the following vector calculus identity:

$$\nabla^2 f g = f \nabla^2 g + 2(\nabla f) \cdot (\nabla g) + g \nabla^2 f$$

[5 marks]

**Note:** You must treat  $f$  and  $g$  as functions of  $x, y, z$ .

**Solution:**

Converting to index notation in Cartesian coordinates  $(x, y, z)$ ,

$$\nabla^2 f g = \frac{\partial}{\partial r_i} \left( \frac{\partial}{\partial r_i} f g \right)$$

[1] *We can't use  $\partial^2 / \partial r_i^2$  as there is no repeated  $i$  index. Using the product rule on the term in parenthesis*

$$\frac{\partial}{\partial r_i} f g = f \frac{\partial g}{\partial r_i} + g \frac{\partial f}{\partial r_i}$$

[1] *Using the product rule again to apply the second derivative to both of these terms*

*gives*

$$\begin{aligned}\frac{\partial}{\partial r_i} \frac{\partial}{\partial r_i} f g &= \frac{\partial f}{\partial r_i} \frac{\partial g}{\partial r_i} + f \frac{\partial}{\partial r_i} \frac{\partial g}{\partial r_i} + \frac{\partial g}{\partial r_i} \frac{\partial f}{\partial r_i} + g \frac{\partial}{\partial r_i} \frac{\partial f}{\partial r_i} \\ &= f \frac{\partial}{\partial r_i} \frac{\partial g}{\partial r_i} + 2 \frac{\partial f}{\partial r_i} \frac{\partial g}{\partial r_i} + g \frac{\partial}{\partial r_i} \frac{\partial f}{\partial r_i}\end{aligned}$$

[2]

*Converting back to vector notation, yields the identity,*

$$\frac{\partial}{\partial r_i} \frac{\partial}{\partial r_i} f g = f \nabla^2 g + 2(\nabla f) \cdot (\nabla g) + g \nabla^2 f$$

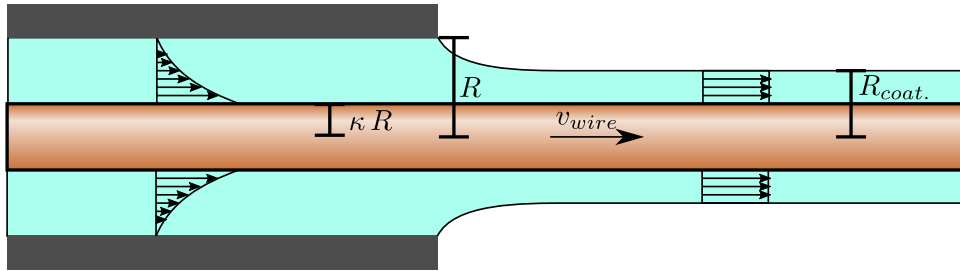
[1]

**Total Question Marks:20**

Q.2

**Question 2**

A wire-coating die consists of a cylindrical wire of radius,  $\kappa R$ , moving horizontally at a constant velocity,  $v_{wire}$ , along the axis of a cylindrical die of radius,  $R$ . You may assume the pressure is constant within the die (it is not pressure driven flow) but the flow is driven by the motion of the wire (it is “axial annular Couette flow”). Neglect end effects and assume an isothermal system.



**Figure 1:** *Diagram of a wire coating die.*

- a) State the two relevant boundary conditions for the flow within the die and how they arise. [2 marks]

**Solution:**

*Both conditions arise from non-slip conditions of the fluid with a solid boundary.*

- $v_z(r = R) = 0$ : *At the die wall interface.*
- $v_z(r = \kappa R) = v_{wire}$ : *At the wire interface.*

- b) The stress profile for an annular system is of the following form

$$\frac{1}{r} \frac{\partial}{\partial r} r \tau_{rz} = -\frac{\partial p}{\partial z} + \rho g_z.$$

Derive the following expression for the flow profile

$$v_z = \frac{v_{wire}}{\ln \kappa} \ln \left( \frac{r}{R} \right).$$

[9 marks]

**Solution:**

*There is no driving pressure gradient, and as the flow is horizontal, the two terms on the right hand side are zero*

$$\frac{1}{r} \frac{\partial}{\partial r} r \tau_{rz} = -\cancel{\frac{\partial p}{\partial z}}^0 + \rho \cancel{g_z}^0.$$

*Performing the integration of the stress profile expression from the previous question,*

$$\tau_{rz} = \frac{C_1}{r}.$$

[1]

*Assuming the fluid is Newtonian, we have*

$$-\mu \frac{\partial v_z}{\partial r} = \frac{C_1}{r}.$$

[1]

*Performing the integration*

$$v_z = -\mu^{-1} C_1 \ln r + C_2.$$

[1]

*Inserting the two boundary conditions yields the following*

$$\begin{aligned} 0 &= -\mu^{-1} C_1 \ln R + C_2. \\ v_{wire} &= -\mu^{-1} C_1 \ln \kappa R + C_2. \end{aligned}$$

[1]

*Solving both equations for the constants,*

$$\begin{aligned} C_2 &= \mu^{-1} C_1 \ln R \\ v_{wire} &= \mu^{-1} C_1 (\ln R - \ln \kappa R) \\ C_1 &= -\frac{\mu v_{wire}}{\ln \kappa}. \end{aligned}$$

[2]

*Inserting these back in gives the final expression*

$$v_z = \frac{v_{wire}}{\ln \kappa} \ln \left( \frac{r}{R} \right)$$

[1]

c) Derive the following expression for the volumetric flow-rate of liquid through the die

$$\dot{V}_z = -\pi R^2 v_{wire} \left( \kappa^2 + \frac{1 - \kappa^2}{2 \ln \kappa} \right).$$

[5 marks]

**Note:** You will need the integration identity

$$\int x \ln(x) dx = \frac{x^2}{2} \left( \ln(x) - \frac{1}{2} \right).$$

**Solution:**

To determine the volumetric flow rate, the following integration is performed

$$\dot{V}_z = 2\pi \int_{\kappa R}^R r v_z dr$$

[1]

Performing the integration

$$\begin{aligned}\dot{V}_z &= 2\pi R \frac{v_{wire}}{\ln \kappa} \int_{\kappa R}^R \frac{r}{R} \ln\left(\frac{r}{R}\right) dr \\ &= \frac{2\pi R^2 v_{wire}}{\ln \kappa} \int_{\kappa}^1 x \ln(x) dx \\ &= \frac{2\pi R^2 v_{wire}}{\ln \kappa} \left[ \frac{x^2}{2} \left( \ln x - \frac{1}{2} \right) \right]_{\kappa}^1 \\ &= -\frac{2\pi R^2 v_{wire}}{\ln \kappa} \left( \frac{\kappa^2}{2} \left( \ln \kappa - \frac{1}{2} \right) + \frac{1}{4} \right) \\ &= -\pi R^2 v_{wire} \left( \kappa^2 + \frac{1 - \kappa^2}{2 \ln \kappa} \right)\end{aligned}$$

[4]

- d) Derive an expression for the outer radius of the coating,  $R_{coat.}$ , far away from the die exit. [4 marks]

**Solution:**

Solving the stress balance again but for the film coating the wire, the following expression is found again for the stress

$$\tau_{rz} = \frac{C_1}{r}$$

At the exposed surface of the film ( $r \neq 0$ ), the stress is zero (assuming the air exerts close to zero drag). This implies that  $C_1 = 0$  as well, as it is the only possible way to set the RHS to zero at finite values of  $r$ . As the stress is zero, Newton's law of viscosity then implies the film has a constant velocity which will be the velocity of the wire (note, the diagram gives the student a strong hint that this is true).

[2]

The volumetric flowrate of the wire coating is related to the outer radius of the coating,  $R_{coat.}$

$$\dot{V}_{z, coating} = v_{wire} \pi (R_{coat.}^2 - \kappa^2 R^2)$$

[1]

This must be equal to the volumetric flowrate of coating through the die

$$v_{wire} \pi (R_{coat.}^2 - \kappa^2 R^2) = -\pi R^2 v_{wire} \left( \kappa^2 + \frac{1 - \kappa^2}{2 \ln \kappa} \right)$$

$$R_{coat.} = R \sqrt{\frac{\kappa^2 - 1}{2 \ln \kappa}}$$

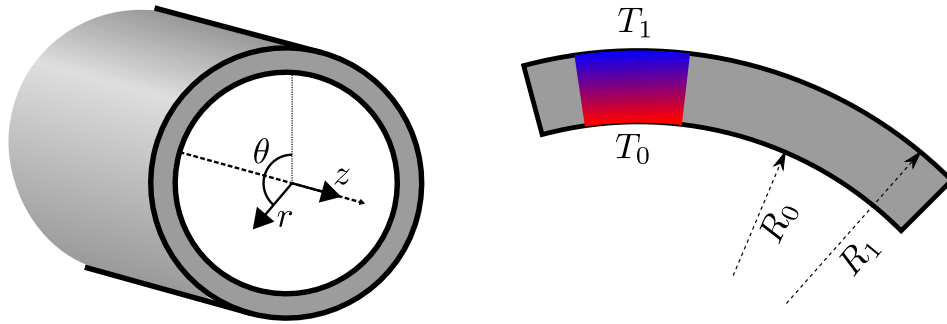
[1]

**Total Question Marks:20**

Q.3

**Question 3**

To explore the effect of using a temperature-dependent thermal conductivity, consider heat flowing through an annular (pipe) wall of inside radius  $R_0$  and an outside radius  $R_1$ . It is assumed that thermal conductivity varies linearly with temperature from  $k_0(T = T_0)$  to  $k_1(T = T_1)$  where  $T_0$  and  $T_1$  are the inner and outer wall temperatures respectively.



**Figure 2:** Conduction through an annular(pipe) wall.

a) Derive the following energy balance equation

$$\frac{\partial}{\partial r} r q_r = 0,$$

and state ALL assumptions required.

[7 marks]

**Solution:**

[1]

Assuming that the pressure dependency of the internal energy of the solid is small, Equation 4 can be used valid.

As this is heat transfer in solids, we can set the frame of reference to the wall and  $v = 0$ . This greatly simplifies the energy balance equation:

$$\begin{aligned} \rho C_p \frac{\partial T}{\partial t} &= - \cancel{\rho C_p v_j \nabla_j T}^0 - \nabla_i q_i - \cancel{\tau_{ji} \nabla_j v_i}^0 - \cancel{p \nabla_i v_i}^0 + \sigma_{energy} \\ \rho C_p \frac{\partial T}{\partial t} &= - \nabla_i q_i + \sigma_{energy} \end{aligned}$$

[1]

Assuming the wall does not generate heat:

$$\rho C_p \frac{\partial T}{\partial t} = - \nabla_i q_i + \cancel{\sigma_{energy}}^0$$

[1]

And steady state:

$$\begin{aligned} \cancel{\rho C_p \frac{\partial T}{\partial t}}^0 &= - \nabla_i q_i \\ \nabla_i q_i &= 0 \end{aligned}$$

[1]

Finally, inserting the cylindrical coordinate system definition of  $\nabla_i q_i$ :

$$\nabla_i q_i = \frac{1}{r} \frac{\partial}{\partial r} (r q_r) + \frac{1}{r} \frac{\partial q_\theta}{\partial \theta} + \frac{\partial q_z}{\partial z}$$

[2]

Assuming a symmetry of the system *ALONG* and *AROUND* the axis, the only remaining derivative is in the  $r$ -direction:

$$\begin{aligned} \nabla_i q_i &= \frac{1}{r} \frac{\partial}{\partial r} (r q_r) \\ &= \frac{\partial}{\partial r} (r q_r) = 0 \end{aligned}$$

[1]

As required.

b) Derive the following expression for the temperature profile

$$Q_r = \frac{2\pi L}{\ln\left(\frac{R_0}{R_1}\right)} \frac{k_1 + k_0}{2} (T_1 - T_0),$$

where  $L$  is the length of the pipe/annulus.

[10 marks]

**Note:** You will need the following identity:

$$T_1^2 - T_0^2 = (T_1 + T_0)(T_1 - T_0).$$

**Solution:**

Performing the integration, we have

$$\begin{aligned} r q_r &= C_1 \\ q_r &= \frac{C_1}{r} \end{aligned}$$

[1]

Inserting in Fourier's law, we have

$$-k \frac{\partial T}{\partial r} = \frac{C_1}{r}$$

We need to insert the temperature dependent thermal conductivity, which is given by the following linear relationship

$$k = k_0 + (T - T_0) \frac{k_1 - k_0}{T_1 - T_0}$$

[1]

Inserting this,

$$-\left(k_0 + (T - T_0) \frac{k_1 - k_0}{T_1 - T_0}\right) \frac{\partial T}{\partial r} = \frac{C_1}{r}$$

[1]

Integrating between the two limits,



$$\begin{aligned}
& - \int_{R_0}^{R_1} \left( k_0 + (T - T_0) \frac{k_1 - k_0}{T_1 - T_0} \right) \frac{\partial T}{\partial r} dr = \int_{R_0}^{R_1} \frac{C_1}{r} dr \\
& - \int_{T_0}^{T_1} \left( k_0 + (T - T_0) \frac{k_1 - k_0}{T_1 - T_0} \right) dT = C_1 \ln \left( \frac{R_1}{R_0} \right) \\
& - \left( k_0 (T_1 - T_0) + \left( \frac{T_1^2 - T_0^2}{2} - (T_1 - T_0) T_0 \right) \frac{k_1 - k_0}{T_1 - T_0} \right) = C_1 \ln \left( \frac{R_1}{R_0} \right)
\end{aligned}$$

[2] Using the identity  $T_1^2 - T_0^2 = (T_1 + T_0)(T_1 - T_0)$ ,

$$\begin{aligned}
& - \left( k_0 (T_1 - T_0) + \frac{T_1 + T_0}{2} (k_1 - k_0) - T_0 (k_1 - k_0) \right) = C_1 \ln \left( \frac{R_1}{R_0} \right) \\
& - \left( k_0 T_1 + \frac{T_1 + T_0}{2} (k_1 - k_0) - T_0 k_1 \right) = C_1 \ln \left( \frac{R_1}{R_0} \right)
\end{aligned}$$

[2] Simple cancellation and factorisation leads to the following

$$\frac{k_1 + k_0}{2 \ln \left( \frac{R_0}{R_1} \right)} (T_1 - T_0) = C_1$$

[1] Inserting this back into the expression for the flux, we have

$$\begin{aligned}
q_r &= \frac{C_1}{r} \\
&= \frac{k_1 + k_0}{2 r \ln \left( \frac{R_0}{R_1} \right)} (T_1 - T_0)
\end{aligned}$$

[1] The total flux is given by multiplying by the cylindrical area,  $2 \pi r L$ ,

$$Q_r = \frac{2 \pi L}{\ln \left( \frac{R_0}{R_1} \right)} \frac{k_1 + k_0}{2} (T_1 - T_0)$$

[1] c) Compare this expression to the standard expression for conduction in pipe walls (with constant thermal conductivity), what can you observe? [3 marks]

**Solution:**

The expression for pipes is available from the tables in the datasheet, and is as follows

$$Q = \frac{2 \pi L k}{\ln \left( \frac{R_1}{R_0} \right)} \Delta T.$$

[1] On comparison with the derived equation, the only change is to replace the constant thermal conductivity with the average of the thermal conductivity on the inner and outer surfaces.

[1] For small temperature differences (where a linear temperature dependence may be assumed) using the average thermal conductivity is a useful strategy.

**Total Question Marks:20**

**Q.4 Question 4**

Consider laminar flow within a pipe. The only prior knowledge you should assume is that the pressure drop must be a function of pipe diameter  $D$ , viscosity  $\mu$ , density  $\rho$ , and average velocity  $\langle v_z \rangle$ , i.e.,

$$\Delta p/l = f(D, \rho, \mu, \langle v_z \rangle).$$

- a) Perform dimensional analysis on the pressure drop per unit length,  $\Delta p/l$ , and determine the relevant dimensionless groups. [12 marks]

**Solution:**

*The first step is to make the units of each term explicit by dividing out the dimensions of each term*

$$\frac{\Delta p}{l} \frac{L^2 T^2}{M} = f\left(\frac{D}{L}, \frac{\rho L^3}{M}, \frac{\mu L T}{M}, \frac{\langle v_z \rangle T}{L}\right).$$

[5] *Students will receive FIVE marks for correctly identifying the units of each term in SI.*

[1] *A convenient length scale is the diameter,  $L = D$ , which gives:*

$$\frac{\Delta p}{l} \frac{D^2 T^2}{M} = f\left(1, \frac{\rho D^3}{M}, \frac{\mu D T}{M}, \frac{\langle v_z \rangle T}{D}\right)$$

[1]

[1] *A convenient mass scale is  $M = \rho D^3$ , which gives:*

$$\frac{\Delta p}{l} \frac{T^2}{\rho D} = f\left(1, 1, \frac{\mu T}{\rho D^2}, \frac{\langle v_z \rangle T}{D}\right)$$

[1]

[1] *Finally, a convenient time scale is  $T = D/\langle v_z \rangle$ , which gives:*

$$\frac{\Delta p}{l} \frac{D}{\rho \langle v_z \rangle^2} = f\left(1, 1, \frac{\mu}{\rho \langle v_z \rangle D}, 1\right)$$

[1] *Noticing that the dimensionless grouping on the right hand side is the Reynolds number, we have*

$$\begin{aligned} \frac{\Delta p}{l} \frac{D}{\rho \langle v_z \rangle^2} &= f(1, 1, Re^{-1}, 1) \\ &= f(Re) \end{aligned}$$

[1]

- b) Compare this to the exact solution, known as the Hagen-Poiseuille equation, as given below.

$$\dot{V}_z = \pi \left( \frac{-\Delta p}{l} + \rho g_z \right) \frac{R^4}{8\mu}.$$

Determine the form of the unknown function,  $f$ .

[5 marks]

**Solution:**

Noting that  $\langle v_z \rangle = \dot{V}_z/A$  and ignoring gravity, we have

$$\langle v_z \rangle = -\frac{\Delta p}{l} \frac{R^2}{8\mu}.$$

Rearranging the equation to make it identical to the LHS of the solution to the previous question, we have

$$\begin{aligned} \frac{\Delta p}{l} \frac{R}{\rho \langle v_z \rangle^2} &= -8 \frac{\mu}{\rho \langle v_z \rangle R} \\ \frac{\Delta p}{l} \frac{D}{\rho \langle v_z \rangle^2} &= -32 \frac{\mu}{\rho \langle v_z \rangle D} \\ &= -\frac{32}{Re} \end{aligned}$$

Thus the unknown function is  $f = -32 Re^{-1}$ .

- c) Comment on why dimensional analysis is so important. Also comment on why redundant dimensionless groups arise (as an example, consider the relationship between friction factor  $C_f$  and the Reynolds number). [3 marks]

**Solution:**

Dimensionless groups are important, and arise so often, as units themselves are an entirely artificial construct and natural phenomena must be independent of the choice of units. For our models/equations to correctly reflect this, units must cancel within expressions and thus our equations must be able to be rearranged into a composition of dimensionless groups.

Redundant dimensionless groups arise as dimensional analysis places no constraints on the functional form of equations, just on the possible groupings of dimensional terms. Thus dimensionless groups (such as the Reynolds number) may appear with arbitrary transformations applied. One example is the friction factor, which is a dimensionless grouping, but is simply a transformation of the Reynolds number dimensionless group,  $C_f = 16 Re^{-1}$  (and vice-versa).

**Total Question Marks:20**

**END OF PAPER**

**Sum of all question's marks:80**

**DATASHEET****General balance equations:**

$$\frac{\partial \rho}{\partial t} = -\nabla \cdot \rho \mathbf{v} \quad (\text{Mass/Continuity}) \quad (1)$$

$$\frac{\partial C_A}{\partial t} = -\nabla \cdot \mathbf{N}_A + \sigma_A \quad (\text{Species}) \quad (2)$$

$$\rho \frac{\partial \mathbf{v}}{\partial t} = -\rho \mathbf{v} \cdot \nabla \mathbf{v} - \nabla \cdot \boldsymbol{\tau} - \nabla p + \rho \mathbf{g} \quad (\text{Momentum}) \quad (3)$$

$$\rho C_p \frac{\partial T}{\partial t} = -\rho C_p \mathbf{v} \cdot \nabla T - \nabla \cdot \mathbf{q} - \boldsymbol{\tau} : \nabla \mathbf{v} - p \nabla \cdot \mathbf{v} + \sigma_{\text{energy}} \quad (\text{Heat/Energy}) \quad (4)$$

In Cartesian coordinate systems,  $\nabla$  can be treated as a vector of derivatives. In curve-linear coordinate systems, the directions  $\hat{r}$ ,  $\hat{\theta}$ , and  $\hat{\phi}$  depend on the position. For convenience in these systems, look-up tables are provided for common terms involving  $\nabla$ .

**Cartesian coordinates** (with index notation examples)

where  $s$  is a scalar,  $\mathbf{v}$  is a vector, and  $\boldsymbol{\tau}$  is a tensor.

$$\begin{aligned} \nabla s &= \nabla_i s = \left[ \frac{\partial s}{\partial x}, \frac{\partial s}{\partial y}, \frac{\partial s}{\partial z} \right] \\ \nabla^2 s &= \nabla_i \nabla_i s = \frac{\partial^2 s}{\partial x^2} + \frac{\partial^2 s}{\partial y^2} + \frac{\partial^2 s}{\partial z^2} \\ \nabla \cdot \mathbf{v} &= \nabla_i v_i = \frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z} \\ \nabla \cdot \boldsymbol{\tau} &= \nabla_i \tau_{ij} \\ [\nabla \cdot \boldsymbol{\tau}]_x &= \frac{\partial \tau_{xx}}{\partial x} + \frac{\partial \tau_{yx}}{\partial y} + \frac{\partial \tau_{zx}}{\partial z} \\ [\nabla \cdot \boldsymbol{\tau}]_y &= \frac{\partial \tau_{xy}}{\partial x} + \frac{\partial \tau_{yy}}{\partial y} + \frac{\partial \tau_{zy}}{\partial z} \\ [\nabla \cdot \boldsymbol{\tau}]_z &= \frac{\partial \tau_{xz}}{\partial x} + \frac{\partial \tau_{yz}}{\partial y} + \frac{\partial \tau_{zz}}{\partial z} \\ \mathbf{v} \cdot \nabla \mathbf{v} &= v_i \nabla_i v_j \\ [\mathbf{v} \cdot \nabla \mathbf{v}]_x &= v_x \frac{\partial v_x}{\partial x} + v_y \frac{\partial v_x}{\partial y} + v_z \frac{\partial v_x}{\partial z} \\ [\mathbf{v} \cdot \nabla \mathbf{v}]_y &= v_x \frac{\partial v_y}{\partial x} + v_y \frac{\partial v_y}{\partial y} + v_z \frac{\partial v_y}{\partial z} \\ [\mathbf{v} \cdot \nabla \mathbf{v}]_z &= v_x \frac{\partial v_z}{\partial x} + v_y \frac{\partial v_z}{\partial y} + v_z \frac{\partial v_z}{\partial z} \end{aligned}$$

**Cylindrical coordinates**

where  $s$  is a scalar,  $\mathbf{v}$  is a vector, and  $\boldsymbol{\tau}$  is a tensor. All expressions involving  $\boldsymbol{\tau}$  are for symmetrical  $\boldsymbol{\tau}$  only.

$$\begin{aligned}\nabla s &= \left[ \frac{\partial s}{\partial r}, \frac{1}{r} \frac{\partial s}{\partial \theta}, \frac{\partial s}{\partial z} \right] \\ \nabla^2 s &= \frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial s}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 s}{\partial \theta^2} + \frac{\partial^2 s}{\partial z^2} \\ \nabla \cdot \mathbf{v} &= \frac{1}{r} \frac{\partial}{\partial r} (r v_r) + \frac{1}{r} \frac{\partial v_\theta}{\partial \theta} + \frac{\partial v_z}{\partial z} \\ [\nabla \cdot \boldsymbol{\tau}]_r &= \frac{1}{r} \frac{\partial}{\partial r} (r \tau_{rr}) + \frac{1}{r} \frac{\partial \tau_{r\theta}}{\partial \theta} - \frac{1}{r} \tau_{\theta\theta} + \frac{\partial \tau_{rz}}{\partial z} \\ [\nabla \cdot \boldsymbol{\tau}]_\theta &= \frac{1}{r} \frac{\partial \tau_{\theta\theta}}{\partial \theta} + \frac{\partial \tau_{r\theta}}{\partial r} + \frac{2}{r} \tau_{r\theta} + \frac{\partial \tau_{\theta z}}{\partial z} \\ [\nabla \cdot \boldsymbol{\tau}]_z &= \frac{1}{r} \frac{\partial}{\partial r} (r \tau_{rz}) + \frac{1}{r} \frac{\partial \tau_{\theta z}}{\partial \theta} + \frac{\partial \tau_{zz}}{\partial z} \\ [\mathbf{v} \cdot \nabla \mathbf{v}]_r &= v_r \frac{\partial v_r}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_r}{\partial \theta} - \frac{v_\theta^2}{r} + v_z \frac{\partial v_r}{\partial z} \\ [\mathbf{v} \cdot \nabla \mathbf{v}]_\theta &= v_r \frac{\partial v_\theta}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_\theta}{\partial \theta} + \frac{v_r v_\theta}{r} + v_z \frac{\partial v_\theta}{\partial z} \\ [\mathbf{v} \cdot \nabla \mathbf{v}]_z &= v_r \frac{\partial v_z}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_z}{\partial \theta} + v_z \frac{\partial v_z}{\partial z}\end{aligned}$$

**Spherical coordinates**

where  $s$  is a scalar,  $\mathbf{v}$  is a vector, and  $\boldsymbol{\tau}$  is a tensor. All expressions involving  $\boldsymbol{\tau}$  are for symmetrical  $\boldsymbol{\tau}$  only.

$$\begin{aligned}\nabla s &= \left[ \frac{\partial s}{\partial r}, \frac{1}{r} \frac{\partial s}{\partial \theta}, \frac{1}{r \sin \theta} \frac{\partial s}{\partial \phi} \right] \\ \nabla^2 s &= \frac{1}{r^2} \frac{\partial}{\partial r} \left( r^2 \frac{\partial s}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left( \sin \theta \frac{\partial s}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 s}{\partial \phi^2} \\ \nabla \cdot \mathbf{v} &= \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 v_r) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (v_\theta \sin \theta) + \frac{1}{r \sin \theta} \frac{\partial v_\phi}{\partial \phi} \\ [\nabla \cdot \boldsymbol{\tau}]_r &= \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 \tau_{rr}) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\tau_{r\theta} \sin \theta) + \frac{1}{r \sin \theta} \frac{\partial \tau_{r\phi}}{\partial \phi} - \frac{\tau_{\theta\theta} + \tau_{\phi\phi}}{r} \\ [\nabla \cdot \boldsymbol{\tau}]_\theta &= \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 \tau_{r\theta}) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\tau_{\theta\theta} \sin \theta) + \frac{1}{r \sin \theta} \frac{\partial \tau_{\theta\phi}}{\partial \phi} + \frac{\tau_{r\theta}}{r} - \frac{\cot \theta}{r} \tau_{\phi\phi} \\ [\nabla \cdot \boldsymbol{\tau}]_\phi &= \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 \tau_{r\phi}) + \frac{1}{r} \frac{\partial \tau_{\theta\phi}}{\partial \theta} + \frac{1}{r \sin \theta} \frac{\partial \tau_{\phi\phi}}{\partial \phi} + \frac{\tau_{r\theta}}{r} + \frac{2 \cot \theta}{r} \tau_{\theta\phi} \\ [\mathbf{v} \cdot \nabla \mathbf{v}]_r &= v_r \frac{\partial v_r}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_r}{\partial \theta} + \frac{v_\phi}{r \sin \theta} \frac{\partial v_r}{\partial \phi} - \frac{v_\theta^2 + v_\phi^2}{r} \\ [\mathbf{v} \cdot \nabla \mathbf{v}]_\theta &= v_r \frac{\partial v_\theta}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_\theta}{\partial \theta} + \frac{v_\phi}{r \sin \theta} \frac{\partial v_\theta}{\partial \phi} + \frac{v_r v_\theta - v_\phi^2 \cot \theta}{r} \\ [\mathbf{v} \cdot \nabla \mathbf{v}]_\phi &= v_r \frac{\partial v_\phi}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_\phi}{\partial \theta} + \frac{v_\phi}{r \sin \theta} \frac{\partial v_\phi}{\partial \phi} + \frac{v_r v_\phi + v_\theta v_\phi \cot \theta}{r}\end{aligned}$$

Rectangular		Cylindrical		Spherical	
$q_x$	$-k \frac{\partial T}{\partial x}$	$q_r$	$-k \frac{\partial T}{\partial r}$	$q_r$	$-k \frac{\partial T}{\partial r}$
$q_y$	$-k \frac{\partial T}{\partial y}$	$q_\theta$	$-k \frac{1}{r} \frac{\partial T}{\partial \theta}$	$q_\theta$	$-k \frac{1}{r} \frac{\partial T}{\partial \theta}$
$q_z$	$-k \frac{\partial T}{\partial z}$	$q_z$	$-k \frac{\partial T}{\partial z}$	$q_\phi$	$-k \frac{1}{r \sin \theta} \frac{\partial T}{\partial \phi}$
$\tau_{xx}$	$-2\mu \frac{\partial v_x}{\partial x} + \mu^B \nabla \cdot \mathbf{v}$	$\tau_{rr}$	$-2\mu \frac{\partial v_r}{\partial r} + \mu^B \nabla \cdot \mathbf{v}$	$\tau_{rr}$	$-2\mu \frac{\partial v_r}{\partial r} + \mu^B \nabla \cdot \mathbf{v}$
$\tau_{yy}$	$-2\mu \frac{\partial v_y}{\partial y} + \mu^B \nabla \cdot \mathbf{v}$	$\tau_{\theta\theta}$	$-2\mu \left( \frac{1}{r} \frac{\partial v_\theta}{\partial \theta} + \frac{v_r}{r} \right) + \mu^B \nabla \cdot \mathbf{v}$	$\tau_{\theta\theta}$	$-2\mu \left( \frac{1}{r} \frac{\partial v_\theta}{\partial \theta} + \frac{v_r}{r} \right) + \mu^B \nabla \cdot \mathbf{v}$
$\tau_{zz}$	$-2\mu \frac{\partial v_z}{\partial z} + \mu^B \nabla \cdot \mathbf{v}$	$\tau_{zz}$	$-2\mu \frac{\partial v_z}{\partial z} + \mu^B \nabla \cdot \mathbf{v}$	$\tau_{\phi\phi}$	$-2\mu \left( \frac{1}{r \sin \theta} \frac{\partial v_\phi}{\partial \phi} + \frac{v_r + v_\theta \cot \theta}{r} \right) + \mu^B \nabla \cdot \mathbf{v}$
$\tau_{xy}$	$-\mu \left( \frac{\partial v_x}{\partial y} + \frac{\partial v_y}{\partial x} \right)$	$\tau_{r\theta}$	$-\mu \left( r \frac{\partial}{\partial r} \left( \frac{v_\theta}{r} \right) + \frac{1}{r} \frac{\partial v_r}{\partial \theta} \right)$	$\tau_{r\theta}$	$-\mu \left( r \frac{\partial}{\partial r} \left( \frac{v_\theta}{r} \right) + \frac{1}{r} \frac{\partial v_r}{\partial \theta} \right)$
$\tau_{yz}$	$-\mu \left( \frac{\partial v_y}{\partial z} + \frac{\partial v_z}{\partial y} \right)$	$\tau_{\theta z}$	$-\mu \left( \frac{1}{r} \frac{\partial v_z}{\partial \theta} + \frac{\partial v_\theta}{\partial z} \right)$	$\tau_{\theta\phi}$	$-\mu \left( \frac{\sin \theta}{r} \frac{\partial}{\partial \theta} \left( \frac{v_\phi}{\sin \theta} \right) + \frac{1}{r \sin \theta} \frac{\partial v_\theta}{\partial \phi} \right)$
$\tau_{xz}$	$-\mu \left( \frac{\partial v_x}{\partial z} + \frac{\partial v_z}{\partial x} \right)$	$\tau_{zr}$	$-\mu \left( \frac{\partial v_r}{\partial z} + \frac{\partial v_z}{\partial r} \right)$	$\tau_{\phi r}$	$-\mu \left( \frac{1}{r \sin \theta} \frac{\partial v_r}{\partial \phi} + r \frac{\partial}{\partial r} \left( \frac{v_\phi}{r} \right) \right)$

**Table 1:** Fourier's law for the heat flux and Newton's law for the stress in several coordinate systems. Please remember that the stress is symmetric, so  $\tau_{ij} = \tau_{ji}$ .

### Viscous models:

Power-Law Fluid:

$$|\tau_{xy}| = k \left| \frac{\partial v_x}{\partial y} \right|^n \quad (5)$$

Bingham-Plastic Fluid:

$$\frac{\partial v_x}{\partial y} = \begin{cases} -\mu^{-1} (\tau_{xy} - \tau_0) & \text{if } \tau_{xy} > \tau_0 \\ 0 & \text{if } \tau_{xy} \leq \tau_0 \end{cases}$$

### Dimensionless Numbers

$$\text{Re} = \frac{\rho \langle v \rangle D}{\mu} \quad \text{Re}_H = \frac{\rho \langle v \rangle D_H}{\mu} \quad \text{Re}_{MR} = -\frac{16 L \rho \langle v \rangle^2}{R \Delta p} \quad (6)$$

The hydraulic diameter is defined as  $D_H = 4A/P_w$ .

### Single phase pressure drop calculations in pipes:

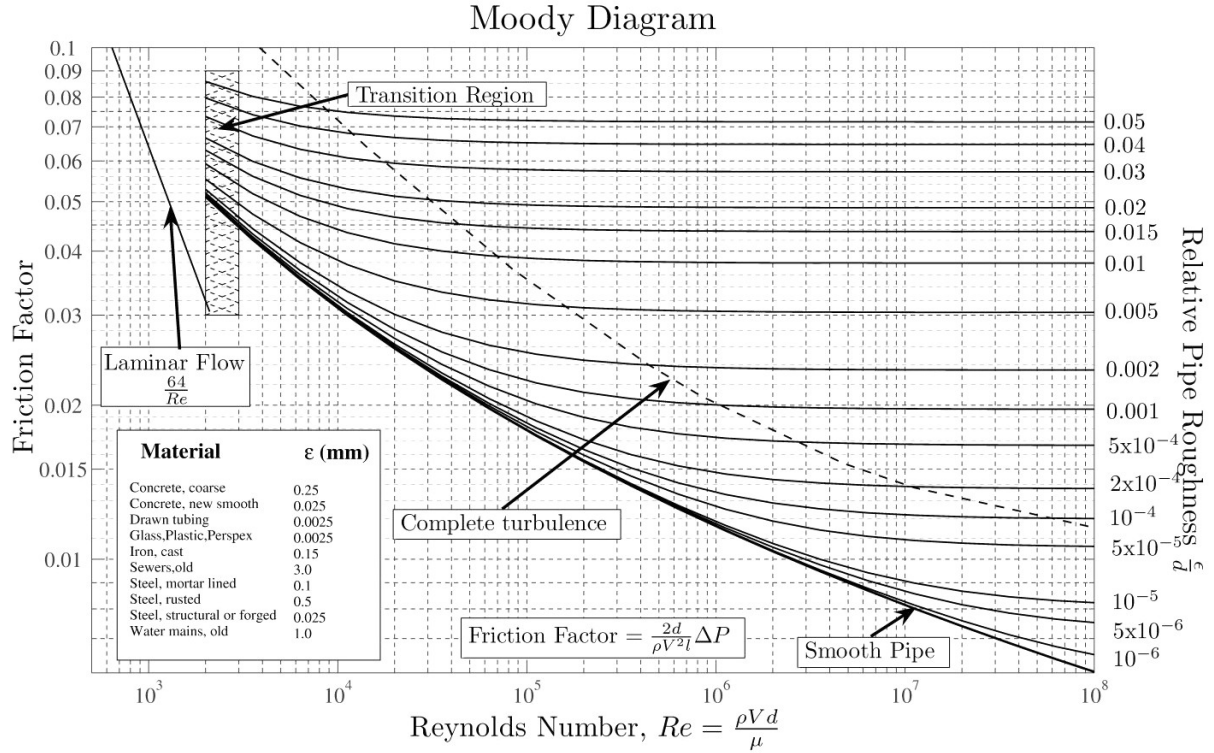
Darcy-Weisbach equation:

$$\frac{\Delta p}{L} = -\frac{C_f \rho \langle v \rangle^2}{R} \quad (7)$$

where  $C_f = 16/Re$  for laminar Newtonian flow. For turbulent flow of Newtonian fluids in smooth pipes, we have the Blasius correlation:

$$C_f = 0.079 Re^{-1/4} \quad \text{for } 2.5 \times 10^3 < Re < 10^5 \text{ and smooth pipes.}$$

Otherwise, you may refer to the Moody diagram.



Laminar Power-Law fluid:

$$\dot{V} = \frac{n \pi R^3}{3n + 1} \left( \frac{R}{2k} \right)^{\frac{1}{n}} \left( -\frac{\Delta p}{L} \right)^{\frac{1}{n}}$$

**Two-Phase Flow:**

Lockhart-Martinelli parameter:

$$X^2 = \frac{\Delta p_{liq.-only}}{\Delta p_{gas.-only}}$$

Pressure drop calculation:

$$\Delta p_{two-phase} = \Phi_{liq.}^2 \Delta p_{liq.-only} = \Phi_{gas}^2 \Delta p_{gas.-only}$$

Chisholm's relation:

$$\Phi_{gas}^2 = 1 + cX + X^2$$

$$\Phi_{liq.}^2 = 1 + \frac{c}{X} + \frac{1}{X^2}$$

$$c = \begin{cases} 20 & \text{turbulent liquid \& turbulent gas} \\ 12 & \text{laminar liquid \& turbulent gas} \\ 10 & \text{turbulent liquid \& laminar gas} \\ 5 & \text{laminar liquid \& laminar gas} \end{cases}$$

Farooqi and Richardson expression for liquid hold-up in co-current flows of Newtonian fluids and air in horizontal pipes:

$$h = \begin{cases} 0.186 + 0.0191 X & 1 < X < 5 \\ 0.143 X^{0.42} & 5 < X < 50 \\ 1/(0.97 + 19/X) & 50 < X < 500 \end{cases}$$

### Heat Transfer:

Stefan-Boltzmann constant  $\sigma = 5.6703 \times 10^{-8} \text{ W/m}^2 \text{ K}^4$

### Heat Transfer Dimensionless numbers:

$$\text{Nu} = \frac{h L}{k} \quad \text{Pr} = \frac{\mu C_p}{k} \quad \text{Gr} = \frac{g \beta (T_w - T_\infty) L^3}{\nu^2}$$

### Resistances

$$Q = U_T A_T \Delta T = R_T^{-1} \Delta T \quad Q_{rad.} = \sigma \varepsilon A (T_\infty^4 - T_w^4) = h_{rad.} A (T_\infty - T_w)$$

	Conduction Shell Resistances			Radiation
	Rect.	Cyl.	Sph.	
$R$	$\frac{X}{k A}$	$\frac{\ln(R_{outer}/R_{inner})}{2 \pi L k}$	$\frac{R_{inner}^{-1} - R_{outer}^{-1}}{4 \pi k}$	$[A \varepsilon \sigma (T_\infty^2 + T_w^2) (T_\infty + T_w)]^{-1}$

### Natural Convection

$Ra = Gr Pr$	$C$	$m$
$< 10^4$	1.36	1/5
$10^4 - 10^9$	0.59	1/4
$> 10^9$	0.13	1/3

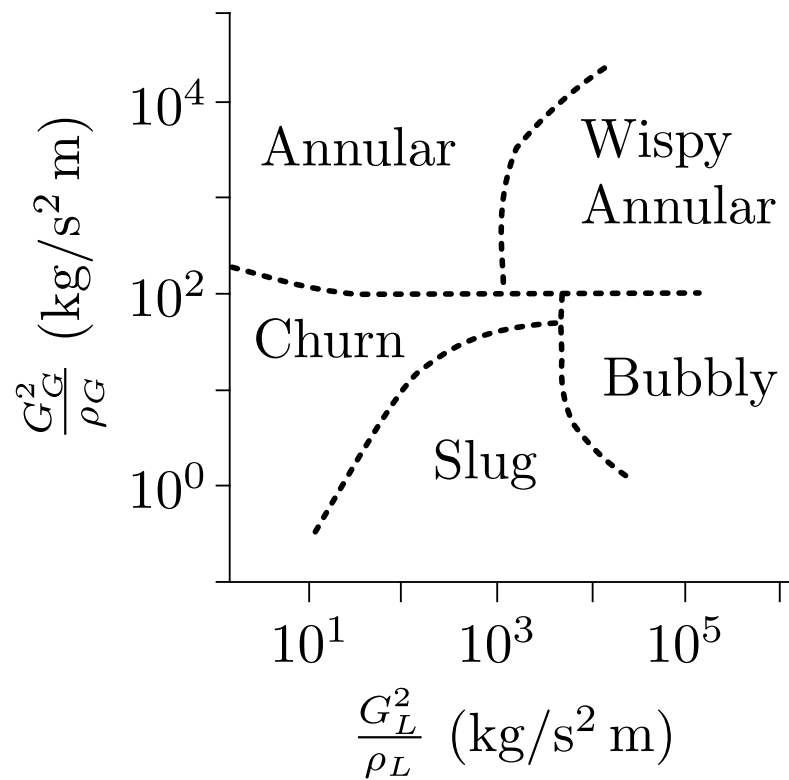
**Table 2:** Natural convection coefficients for isothermal vertical plates in the empirical relation  $Nu \approx C (Gr Pr)^m$ .

For isothermal vertical cylinders, the above expressions for isothermal vertical plates may be used but must be scaled by a factor,  $F$ :

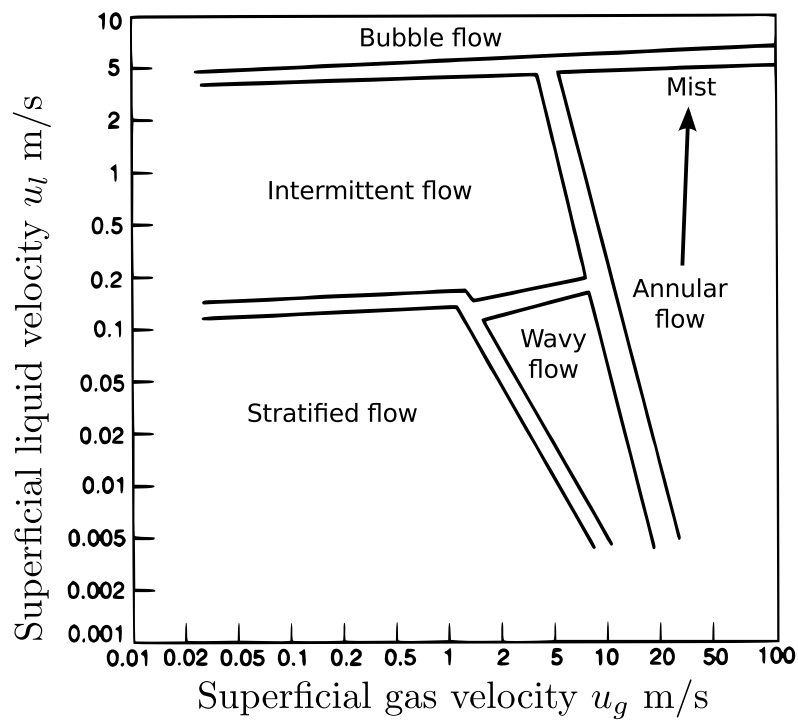
$$F = \begin{cases} 1 & \text{for } (D/H) < 35 Gr_H^{-1/4} \\ 1.3 [H D^{-1} Gr_D^{-1}]^{1/4} + 1 & \text{for } (D/H) \geq 35 Gr_H^{-1/4} \end{cases}$$

where  $D$  is the diameter and  $H$  is the height of the cylinder. The subscript on  $Gr$  indicates which length is to be used as the critical length to calculate the Grashof number.





**Figure 3:** Hewitt-Taylor flow pattern map for multiphase flows in vertical pipes.



**Figure 4:** Chhabra and Richardson flow pattern map for horizontal pipes.

Churchill and Chu expression for natural convection from a horizontal pipe:

$$\text{Nu}^{1/2} = 0.6 + 0.387 \left\{ \frac{\text{Gr Pr}}{\left[ 1 + (0.559/\text{Pr})^{9/16} \right]^{16/9}} \right\}^{1/6} \quad \text{for } 10^{-5} < \text{Gr Pr} < 10^{12}$$

### Forced Convection:

Laminar flows:

$$\text{Nu} \approx 0.332 \text{Re}^{1/2} \text{Pr}^{1/3}$$

Well-Developed turbulent flows in smooth pipes:

$$\text{Nu} \approx \frac{(C_f/2)\text{Re Pr}}{1.07 + 12.7(C_f/2)^{1/2} (\text{Pr}^{2/3} - 1)} \left( \frac{\mu_b}{\mu_w} \right)^{0.14}$$

### Boiling:

Forster-Zuber pool-boiling coefficient:

$$h_{nb} = 0.00122 \frac{k_L^{0.79} C_{p,L}^{0.45} \rho_L^{0.49}}{\gamma^{0.5} \mu_L^{0.29} h_{fg}^{0.24} \rho_G^{0.24}} (T_w - T_{sat})^{0.24} (p_w - p_{sat})^{0.75}$$

Mostinski correlations:

$$h_{nb} = 0.104 p_c^{0.69} q^{0.7} \left[ 1.8 \left( \frac{p}{p_c} \right)^{0.17} + 4 \left( \frac{p}{p_c} \right)^{1.2} + 10 \left( \frac{p}{p_c} \right)^{10} \right]$$

$$q_c = 3.67 \times 10^4 p_c \left( \frac{p}{p_c} \right)^{0.35} \left[ 1 - \frac{p}{p_c} \right]^{0.9}$$

(Note: for the Mostinski correlations, the pressures are in units of bar)

### Condensing:

Horizontal pipes

$$h = 0.72 \left( \frac{k^3 \rho^2 g_x E_{latent}}{D \mu (T_w - T_\infty)} \right)^{1/4}$$

### NTU method:

$$\text{NTU} = \frac{U A}{C_{min}} = \frac{t_{C1} - t_{C2}}{\Delta t_{ln}} \quad R = \frac{C_{min}}{C_{max}}$$

For counter-current flow:

$$E = \frac{1 - \exp[-\text{NTU}(1 - R)]}{1 - R \exp[-\text{NTU}(1 - R)]}$$

For co-current flow:

$$E = \frac{1 - \exp[-NTU(1 - R)]}{1 + R}$$

**Lumped capacitance method:**

$$\text{Bi} = \frac{h L_c}{k}$$

$$L_c = V/A \quad \text{for Bi} < 0.1$$

$$\frac{\theta}{\theta_i} = \frac{T - T_\infty}{T_i - T_\infty} = \exp\left[-\frac{h A_s}{\rho V C_p} t\right]$$

**Diffusion Dimensionless Numbers**

$$\text{Sc} = \frac{\mu}{\rho D_{AB}} \quad \text{Le} = \frac{k}{\rho C_p D_{AB}}$$

**Diffusion**

General expression for the flux:

$$\mathbf{N}_A = \mathbf{J}_A + x_A \sum_B \mathbf{N}_B$$

Fick's law:

$$\mathbf{J}_A = -D_{AB} \nabla C_A$$

Stefan's law:

$$N_{s,r} = -D \frac{c}{1-x} \frac{\partial x}{\partial r}$$

**Misc**

$$PV = nRT \quad R \approx 8.314598 \text{ J K}^{-1} \text{ mol}^{-1}$$