Francisco Ramos

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Machine Learning Engineer UC Berkelev

Personal site: curroramos.github.io GitHub: curroramos LinkedIn: curro-ramos-perez

EDUCATION

Master of Engineering in Control of Robotics and Autonomous Systems - Computer Sciences, UC Berkeley

- Natural Language Processing, Deep Learning for Visual Data, Machine Learning for Modeling Processes, Control of UAVs

- Research: Sky Computing Lab: Finetuning LLMs using generalization metrics and correlational analysis.

Master of Science in Mechatronics, Robotics and Automation Engineering, Universidad Politécnica de Madrid, UPM 2022 - 2023

- Project manager: Autonomous UAV System: Drone for Autonomous Drone Racing Competition (12 team members)

Bachelor of Science in Mechatronics, Robotics and Automation Engineering Universidad de Sevilla, ETSI

2018 - 2022

2023 - 2024

- Top 1% in +300 students, 13 honors awards (with distinction) in different courses

- Awarded Best Final Project among +600 candidates. Final Project: "Charge demand and renewable generation forecasting with Deep Learning: application to electric vehicle station optimization." - Awarded with Honours

- Personal Project: Pan & Tilt servo system autonomously controlled using Facial, Hand and Color Detection

Additional Courses:

- TensorFlow Developer Specialization - Professional Certificate (4 courses), DeepLearning.AI

2022

- Internet of Things and Embedded Systems, University of California, Irvine

2020

- Deep Learning Specialization by Andrew NG (5 courses), DeepLearning.Al

2019

TECHNICAL EXPERIENCE

Software Engineer - Robotics

08/2023 — PRESENT

Al Racing Tech - Robot Open Autonomous Racing (ROAR) UC Berkeley

Berkeley, California

- Researched Autonomous Racing, focusing on software, hardware, and simulation tools promoting ai-racing competitions.
- Implemented End-to-End Self Driving car with Behavior Cloning using Neural Networks and Reinforcement Learning.
- Established Simulation Environments within the Carla platform, featuring sensor integration and control implementations.
- Fastened ROS2 communication -80% by optimizing message transmission with TCP, UDP and message serialization techniques.

Machine Learning Engineer

02/2022 - 08/2022

Advanced Center for Aerospace Technologies - CATEC

Seville, Spain

- Utilized High Altitude Platform Station (HAPS) and Computer Vision techniques to apply photogrammetry for crop monitoring, enhancing crop management efficiency and analysis accuracy, providing +5 different tools and use cases.
- Incorporated Object Detection algorithms into unmanned aerial vehicles (UAVs) to enhance aerial safety by enabling effective detect and avoid algorithms achieving +70% accuracy.
- Evaluated +10 state-of-the-art object detection models with Transformers, selecting the most efficient one resulting in a 15% decrease in inference time on embedded systems.
- Utilized unsupervised learning models for the implementation and training of an Anomaly Detection system in road inspections.
- Publication: Benchmark on real-time long-range aircraft detection for safe RPAS operations. DOI: 10.1007/978-3-031-21062-4_28

Machine Learning Engineer

09/2021 - 07/2022

Systems Engineering and Automation Department, University of Seville

Seville, Spain

- Developed an integrated system simulator for an Electric Vehicle (EV) charging station supplemented with renewable energies.
- Enhanced operational efficiency through the utilization of Time-Series deep learning models to forecast both the charging load and energy production, thus facilitating management optimization.
- Publications: Optimized Operation of an Electric Vehicle Charging Station with Photovoltaic Support and Vehicle-to-Grid Implementation. DOI:10.1007/978-3-031-10047-5_62 - DOI:10.17979

Electronics Engineer

09/2019 - 08/2021

US Racing - Electric Powertrain & Electronic systems department

Seville, Spain

- Analysis and description of the high and low voltage electrical systems pertaining to the electric motorbike.
- Design of key components such as the Battery Management System (BMS), inverter, motor, charger, and telemetry.

SKILLS

Research

Deep Learning, Natural Language Processing (NLP), Computer Vision, Time Series Analysis, Reinforcement Learning, Generative Adversarial Networks (GANs), Neural Architecture Search (NAS), Object Detection, Sentiment Analysis, Image Segmentation, Speech Recognition, Large Language Models (LLMs) fine-tuning, Machine Translation, Text Generation, Transformers, Difussion Models

Tools

Languages Python (TensorFlow, PyTorch, Keras, Scikit-learn, OpenCV, Pandas, NumPy), C, C++, MATLAB, R, SQL, Java, JavaScript, PySpark, Hugging Face Transformers, FastAI, ROS2, Git, Docker, Bash/Shell scripting, Jupyter Notebooks, AWS, Azure, Google Cloud Platform (GCP), Kubernetes, Django, HTML/CSS

Supervised Learning, Unsupervised Learning, Semi-supervised Learning, Active Learning, Ensemble Methods, Neural ML/AI Networks, Convolutional Neural Networks (CNN), Recurrent Neural Networks (RNN), Long Short-Term Memory (LSTM), Transformer Models, Attention Mechanism, Bayesian Methods, Convex Optimization