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# Francisco Ramos

## Machine Learning Engineer



### SKILLS

<b>Tools and Languages</b>	C, C++, Python (Tensorflow, Pytorch, OpenCV, Pandas, Pyspark), R (GGPlot2), SQL, ROS2 , Matlab, Bash/Shell, Git, Docker, Web design
<b>Quantitative Research Communication</b>	Robotics, Control Systems, Electronics, Computer Vision, Deep Learning and AI English (TOEFL iBT: 102 & Advanced CAE - C1), French (A2), Spanish (Native)

### TECHNICAL EXPERIENCE

<b>Researcher / Robot Open Autonomous Racing (ROAR)</b> <i>AI Racing Tech - UC Berkeley</i>	<b>AUG 2023 — MAY 2023</b> <i>Berkeley, California</i>
<b>Robotics &amp; Machine Learning Engineer</b> <i>Advanced Center for Aerospace Technologies - CATEC</i>	<b>FEB 2022 — AUG 2022</b> <i>Seville, Spain</i>
<ul style="list-style-type: none"><li>Utilized High Altitude Platform Station (HAPS) and Computer Vision techniques to apply photogrammetry for crop monitoring, enhancing crop management efficiency and analysis accuracy.</li><li>Incorporated Object Detection algorithms into unmanned aerial vehicles (UAVs) to enhance aerial safety by enabling effective detect and avoid algorithms.</li><li>Explored and implemented state-of-the-art object detection models utilizing transformers, evaluating their performance on embedded systems. This process aided in selecting the most suitable model for integration into onboard systems.</li><li>Utilized unsupervised learning models for the implementation and training of an anomaly detection system in road inspections to enhance infrastructure monitoring and maintenance.</li><li>Publication: Benchmark on real-time long-range aircraft detection for safe RPAS operations. DOI: <a href="https://doi.org/10.1007/978-3-031-21062-4_28">10.1007/978-3-031-21062-4_28</a></li></ul>	
<b>Research intern / Application of ML and DL techniques for the optimization of an EV charging station</b> <i>Systems Engineering and Automation Department US</i>	<b>SEP 2021 — JUL 2022</b> <i>Seville, Spain</i>
<ul style="list-style-type: none"><li>Researched, developed models for, and executed the construction of an integrated system simulator for an Electric Vehicle (EV) charging station supplemented with renewable energy sources.</li><li>Enhanced operational efficiency through the utilization of time-series deep learning models to forecast both the charging load and energy production, thus facilitating management optimization.</li><li>Publication: Optimized Operation of an Electric Vehicle Charging Station with Photovoltaic Support and Vehicle-to-Grid Implementation. DOI: <a href="https://doi.org/10.1007/978-3-031-10047-5_62">10.1007/978-3-031-10047-5_62</a></li></ul>	
<b>Engineer / Electric Powertrain &amp; Electronic systems department.</b> <i>US Racing</i>	<b>SEP 2019 — AUG 2021</b> <i>Seville, Spain</i>
<ul style="list-style-type: none"><li>Analysis and description of the high and low voltage electrical systems pertaining to the electric motorbike.</li><li>Creation and specification of key components such as the Battery Management System (BMS), inverter, motor, charger, and telemetry in the overall design.</li></ul>	

### EDUCATION

<b>Master of Engineering in Control of Robotics and Autonomous Systems</b> , <i>University of California Berkeley</i>	<b>2023 — 2024</b>
- CS 288: Natural Language Processing, CS 198: Deep Learning for Visual Data, ME 249: Machine Learning Tools for Modeling Energy Transport and Conversion Processes, ME 236: Control of Unmanned Aerial Vehicles	
<b>Master of Science in Mechatronics, Robotics and Automation Engineering</b> , <i>Universidad Politécnica de Madrid, UPM</i>	<b>2022 — 2023</b>
- Project manager: Autonomous UAV System: Drone for Autonomous Drone Racing Competition (12 students)	
<b>Bachelor of Science in Mechatronics, Robotics and Automation Engineering</b> , <i>Universidad de Sevilla, ETSI</i>	<b>2018 — 2022</b>
- Top 1%, Cumulative GPA: 3.777, Major field GPA: 3.836, 13 honors (with distinction)	
- Final degree project: "Charge demand and renewable generation forecasting with Deep Learning: application to electric vehicle station optimization." (Awarded with Honours)	
- Other projects: Pan & Tilt servo system autonomously controlled using Facial, Hand and Color Detection	
<b>Additional Training Courses :</b>	
- TensorFlow Developer Specialization - Professional Certificate (4 courses), <i>DeepLearning.AI</i>	<b>2022</b>
- Introduction to the Internet of Things and Embedded Systems, <i>University of California, Irvine</i>	<b>2020</b>
- Deep Learning Specialization by Andrew NG (5 courses), <i>DeepLearning.AI</i>	<b>2019-2021</b>
<b>Internship</b> , <i>Rockbrook International - Dublin, Ireland</i>	<b>2012</b>

### ACTIVITIES AND ACHIEVEMENTS

Prize for the Best Final Degree Project awarded by the Endesa Chair - XVIII Edition	<b>2023</b>
Captain of the University football team of the School of Engineering of Seville	<b>2018 — 2022</b>