

# Linear Regression

## STOCHASTIC Gradient Descent

- picks random instances
- update the weights using only one training example at a time

$$\text{Model: } y = mx + b$$

$$\text{Residual} = y - \hat{y}_{\text{pred}}$$

$$\text{MSE} = \frac{1}{n} (\text{Residual} \times \times 2)$$

$$w = w - (l_r \times dL/dw)$$

$$b = b - (l_r \times dL/db)$$

where,

$$\frac{dL}{dw} = (y - \hat{y}_{\text{pred}}) \cdot x$$

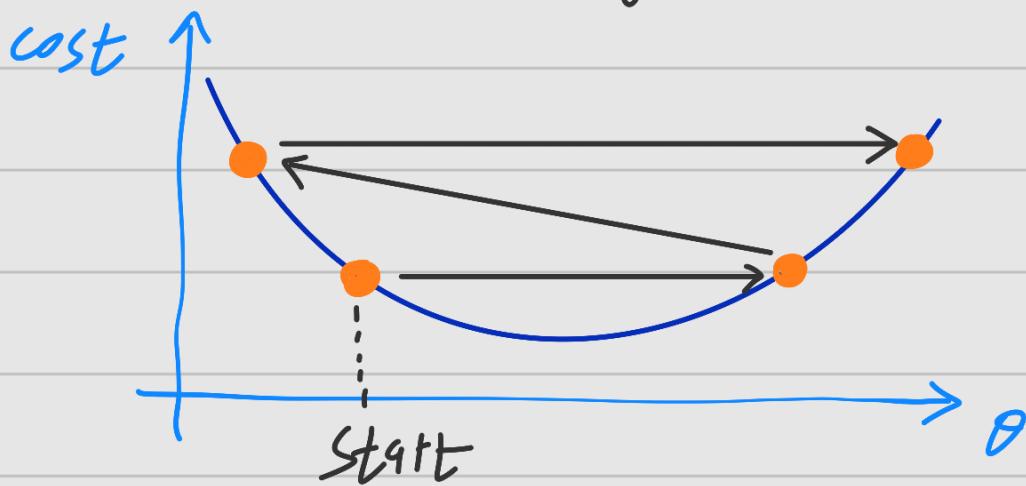
$$\frac{dL}{db} = (y - \hat{y}_{\text{pred}}) \cdot 1$$

## Learning Schedule Parameters:

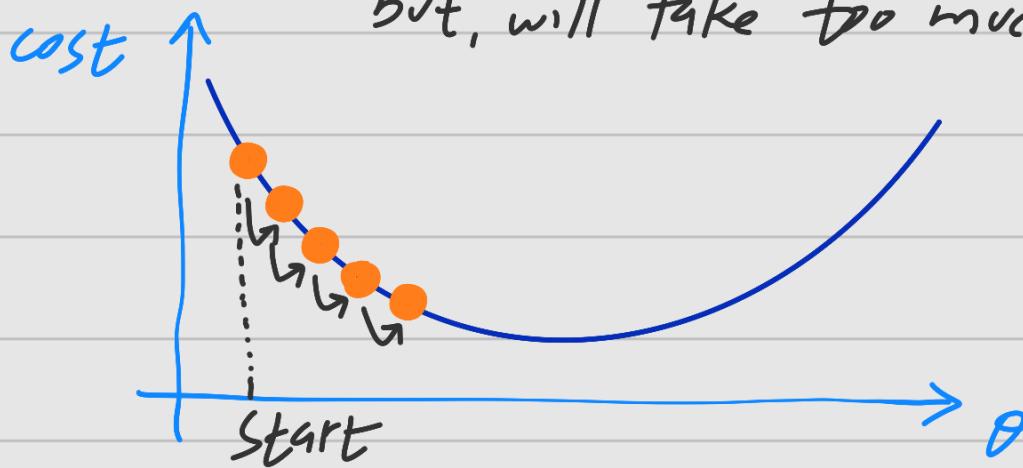
↳ Controls learning rate behaviour during training, directly affecting speed and accuracy.

→ Initial learning rate

Too high: Algorithm diverges, jumping all over the place & getting further from solution.



Too low: Algorithm will reach the solution but, will take too much time



$$\eta(t) = \frac{t_0}{t + t_1} \quad \left\{ \begin{array}{l} t_0, t_1 \text{ controls how} \\ \text{fast learning rate decays} \end{array} \right\}$$

$\downarrow$   
learning  
rate

- Slow down the updates to converge smoothly.
- helps escape local minima

$$\text{new lr} = \underline{\text{old lr}}$$

$$(1 + \text{decay rate} \cdot \text{step})$$

$$\begin{array}{c|c} x_i \rightarrow x[i] & | \\ y_i \rightarrow y[i] & | \\ m, n \rightarrow x.\text{shape} & ; \end{array} \quad \begin{array}{c} | \\ | \\ | \end{array} \quad \begin{array}{l} y_{-\text{pred}} = [x_i][\text{weights}] \\ \text{weights} = [\text{zeros}] \\ \hookrightarrow \text{size}(1) \end{array}$$

## Finding Gradient:

$$\hat{y} = w_0 + w_1 x_1 + w_2 x_2 + \dots + w_n x_n$$

$$w \rightarrow [w_0, w_1, w_2, \dots w_n] \quad \{ \text{weights} \}$$

$$x \rightarrow [x_1, x_2, \dots x_n] \quad \{ \text{input features with bias} \}$$

$\hat{y}_i \rightarrow$  predicted for  $i^{\text{th}}$  sample

$y_i \rightarrow$  Actual value

Loss  $f^n$ : MSE

$$\begin{aligned} J(w) &= \frac{1}{2} (\hat{y}_i - y_i)^2 \\ &= \frac{1}{2} (w^T x_i - y_i)^2 \end{aligned}$$

Actual  
predicted

To minimize loss, we take derivative of loss  $f^n$  wrt. weights

$$\begin{aligned} \frac{d}{dw_j} \left[ \frac{1}{2} (w^T x_i - y_i)^2 \right] \\ = \frac{1}{2} \cancel{x^2} (w^T x_i - y_i) \cdot \frac{d}{dw_j} (w^T x_i - \cancel{y_i}) \end{aligned}$$

constant

$$\text{Gradient} = (w^T x_i - y_i) \cdot x_i$$

$$\begin{aligned} \text{Gradient} &= (\hat{y}_i - y_i) \cdot x_i \\ &= \text{residual} \cdot \text{Input vector} \end{aligned}$$

## Algorithm

↳ parameters: X, y, steps, initial lr, decay

m, n → X.shape

weights → zeros array (n)

loss-list = []

for loop (steps):

for loops (m):

$x_i \rightarrow x[i]$

$y_i \rightarrow y[i]$

$y\text{-pred} \rightarrow [x_i] \cdot [\text{weights}]$

loss =  $y - y\text{-pred}$

gradient = loss · inputvector( $x_i$ )

update learning rate

update weight

append the errors

return weights, loss History.

