

# Curt Henrichs

## Software Engineer

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### Aspiration

I am passionate about building real things for real people.  
My interests include human-robot interaction, embedded systems, software engineering, and mixed-reality interfaces.

### Skills

Python, ROS, Git, Atmel, C/C++, Linux, Javascript, React, Angular, Unity/C#, Keras, MATLAB, MoveIt/Relaxed-IK

### Education

(2018 - \* )

M.S. in Computer Science ~ Emphasis: HCI / HRI

GPA: 3.7 / 4.0

📍 University of Wisconsin - Madison, Madison, WI

Coursework: Human Computer Interaction      Artificial Intelligence      High Performance Computing  
+ Wearables      + Machine Learning      + Adv. Computer Architecture  
+ User Modeling      + Computer Vision  
+ Data Visualization

- Human Robot Interaction -

(2014 - 2018)

B.S. in Computer Engineering ~ Emphasis: Embedded Systems

GPA: 3.9 / 4.0

📍 Milwaukee School of Engineering, Milwaukee, WI

Coursework: Embedded Systems (I - IV)      Software Development      Business / Management  
+ Computer Architecture      + Operating Systems      + Servant Leadership  
+ Digital / Analog Circuits      + Data Structures      + Entrepreneurship  
+ Control Systems      + Computer Vision      + Ethics for Mgmt. and Eng.  
+ Digital Signal Processing      + Neural Networks  
+ Computer Networking      + Computer Graphics

- Engineering Practices -

### Experience

(2019 - \* )

Graduate Research Assistant ~ People and Robots Lab, Computer Sciences

📍 University of Wisconsin - Madison, Madison, WI

- Developed collaborative robot (cobot) authoring and training interfaces [Authr, Expert View Dashboard].
- Researched interactions with cobots for both supervision tasks [pRAD] and levels of task interdependence.
- Worked with several colleagues outside of lab (in Human Factors and Optimization) to investigate cobot effectiveness when deployed on a variety of manual work activities.
  - Contributed robot capability analysis as inputs into allocation algorithm.
- Contributed to lab infrastructure and processes.
  - Ex. Developed centralized robot description repository.
  - Ex. Device bringup and documentation (Universal Robots UR3e, Microsoft HoloLens 1 & 2).
  - Ex. Debugged and updated Robotiq gripper ROS drivers for colleague under paper deadline.
- Assisted colleagues with their user studies, technical development, and paper writing.



(2016 - 2018)

R&D Software Engineering Intern

📍 Dedicated Computing, Waukesha, WI

- Responsible for development of embedded firmware in C/C++.
- Prototype server hardware and software systems [Matrix Storage, Fan Controller].
- Integrate embedded devices into server control software with Python.
- Developed internal hardware testing infrastructure [Thermal Chamber] with NodeJS, Python, and MongoDB.
- Produce product life-cycle documents for design, implementation, and testing.



### Notable Projects

- 📁 Authr ~ Cobot authoring environment.
  - Developed an Angular web app with ROS backend.
  - Used MoveIt to compute motion plans and time-of-flight.
  - Custom domain language designed around Therbligs.
- 📁 Expert View Dashboard ~ Cobot training environment.
  - React web app with ROS backend and Unity simulation.
  - Operationalizes expert thinking into a checklist novices use to develop their programs with custom domain language.
  - Explored Microsoft HoloLens as an alternate XR interface.
- 📁 pRAD ~ Evaluation of cobot operator interfaces.
  - Applies predictive robot attention demand (pRAD) to cobots.
  - Developed two widgets (timeline and timer) evaluated for task and collaborative outcomes in human-subjects study.
  - Captured design suggestions from participant interviews informing future implementation.
- 📁 Automated Thermal Chamber Testing.
  - Developed several subsystems:
    - Unit-Under-Test state scraper captures CPU and GPU configuration / sensor values with NodeJS.
    - Thermal couple monitor running on NI cRIO.
    - Chamber control server with NodeJS issues low-level TCP byte commands.
  - Integrated subsystems into internal testing software.
- 📁 Matrix Storage ~ Server Backplane Controller.
  - Developed controller firmware with Atmel C.
    - Aggregates PSU, fan, and environment sensing and control for Linux node on I2C system bus.
  - Wrote Python interface between application and controller.
- 📁 Programmable Fan Controller.
  - USB UART with JSON API to configure programmable thermal profiles with individual fan control.
  - Firmware written in C for Atmel ARM microcontroller.