

# Curt Henrichs

## Software Engineer

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### Aspiration

I am passionate about building real things for real people.  
My interests include human-robot interaction, embedded systems, software engineering, and mixed-reality interfaces.

### Skills

Python, ROS, Git, Atmel, C/C++, Linux, Javascript, React, Angular, Unity/C#, Keras, MATLAB, MoveIt/Relaxed-IK

### Education

- (2018 - \* ) **M.S. in Computer Science ~ Emphasis: HCI / HRI** GPA: 3.7 / 4.0  
📍 University of Wisconsin - Madison, Madison, WI
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|-------------|--|--|--|
| Coursework: | Human Computer Interaction<br>+ Wearables<br>+ User Modeling<br>+ Data Visualization | Artificial Intelligence<br>+ Machine Learning<br>+ Computer Vision | High Performance Computing<br>+ Adv. Computer Architecture |
|-------------|--|--|--|
- Human Robot Interaction -
- (2014 - 2018) **B.S. in Computer Engineering ~ Emphasis: Embedded Systems** GPA: 3.9 / 4.0  
📍 Milwaukee School of Engineering, Milwaukee, WI
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|-------------|---|---|--|
| Coursework: | Embedded Systems<br>+ Computer Architecture<br>+ Digital / Analog Circuits<br>+ Control Systems<br>+ Digital Signal Processing<br>+ Computer Networking | Software Development<br>+ Operating Systems<br>+ Data Structures<br>+ Computer Vision<br>+ Neural Networks<br>+ Computer Graphics | Business / Management<br>+ Servant Leadership<br>+ Entrepreneurship<br>+ Ethics for Mgmt. and Eng. |
|-------------|---|---|--|
- Engineering Practices -

### Experience

- (2019 - \* ) **Graduate Research Assistant ~ People and Robots Lab, Computer Sciences**   
📍 University of Wisconsin - Madison, Madison, WI
- Developed collaborative robot (cobot) authoring and training interfaces [Authr, Expert View Dashboard].
  - Researched interactions with cobots for both attention management and levels of task interdependence.
  - Worked with several colleagues outside of lab (in Human Factors and Optimization) to investigate cobot effectiveness when deployed on a variety of manual work activities.
    - Contributed robot capability analysis as inputs into allocation algorithm.
  - Contributed to lab infrastructure and processes.
    - Ex. Maintained centralized robot description and configuration repository for lab.
    - Ex. Device bringup and documentation (Universal Robots UR3e, Microsoft HoloLens 1 & 2).
    - Ex. Debugged and updated Robotiq gripper ROS drivers for colleague under paper deadline.
  - Assisted colleagues with their user studies, technical development, and paper writing.
- (2016 - 2018) **R&D Software Engineering Intern**   
📍 Dedicated Computing, Waukesha, WI
- Responsible for development of embedded firmware in C/C++.
  - Prototyped server hardware and software systems [Matrix Storage, Fan Controller].
  - Integrated embedded devices into server control software with Python.
  - Developed internal hardware testing infrastructure [Thermal Chamber] with NodeJS, Python, and MongoDB.
  - Contributed to product life-cycle documentation for design, implementation, and testing.

### Notable Projects

- 🤖 **Authr ~ Cobot authoring environment.**
- Developed an Angular web app with ROS backend.
  - Used MoveIt to compute motion plans and time-of-flight.
  - Custom domain language designed around Therbligs.
- 🤖 **Expert View Dashboard ~ Cobot training environment.**
- React web app with ROS backend and Unity simulation.
  - Operationalizes expert thinking into a checklist novices use to develop their programs with custom domain language.
  - Explored Microsoft HoloLens as an alternate XR interface.
- 🤖 **pRAD ~ Evaluation of cobot operator interfaces.**
- Applies predictive robot attention demand (pRAD) to cobots.
  - Developed two widgets (timeline and timer) evaluated for task and collaborative outcomes in human-subjects study.
  - Captured design suggestions from participant interviews informing future implementation.
- 🔧 **Automated Thermal Chamber Testing.**
- Developed several subsystems:
    - Unit-Under-Test state scraper captures CPU and GPU configuration / sensor values with NodeJS.
    - Thermal couple monitor running on NI cRIO.
    - Chamber control server, with NodeJS, issues low-level TCP byte commands.
  - Integrated subsystems into internal testing software.
- 🔧 **Matrix Storage ~ Server Backplane Controller.**
- Developed controller firmware with Atmel C.
    - Aggregates PSU, fan, and environment sensing and control for Linux node on I2C system bus.
  - Interfaced firmware with python application.
- 🔧 **Programmable Fan Controller.**
- USB UART with JSON API to configure programmable thermal profiles with individual fan control.
  - Firmware written in C for Atmel ARM microcontroller.