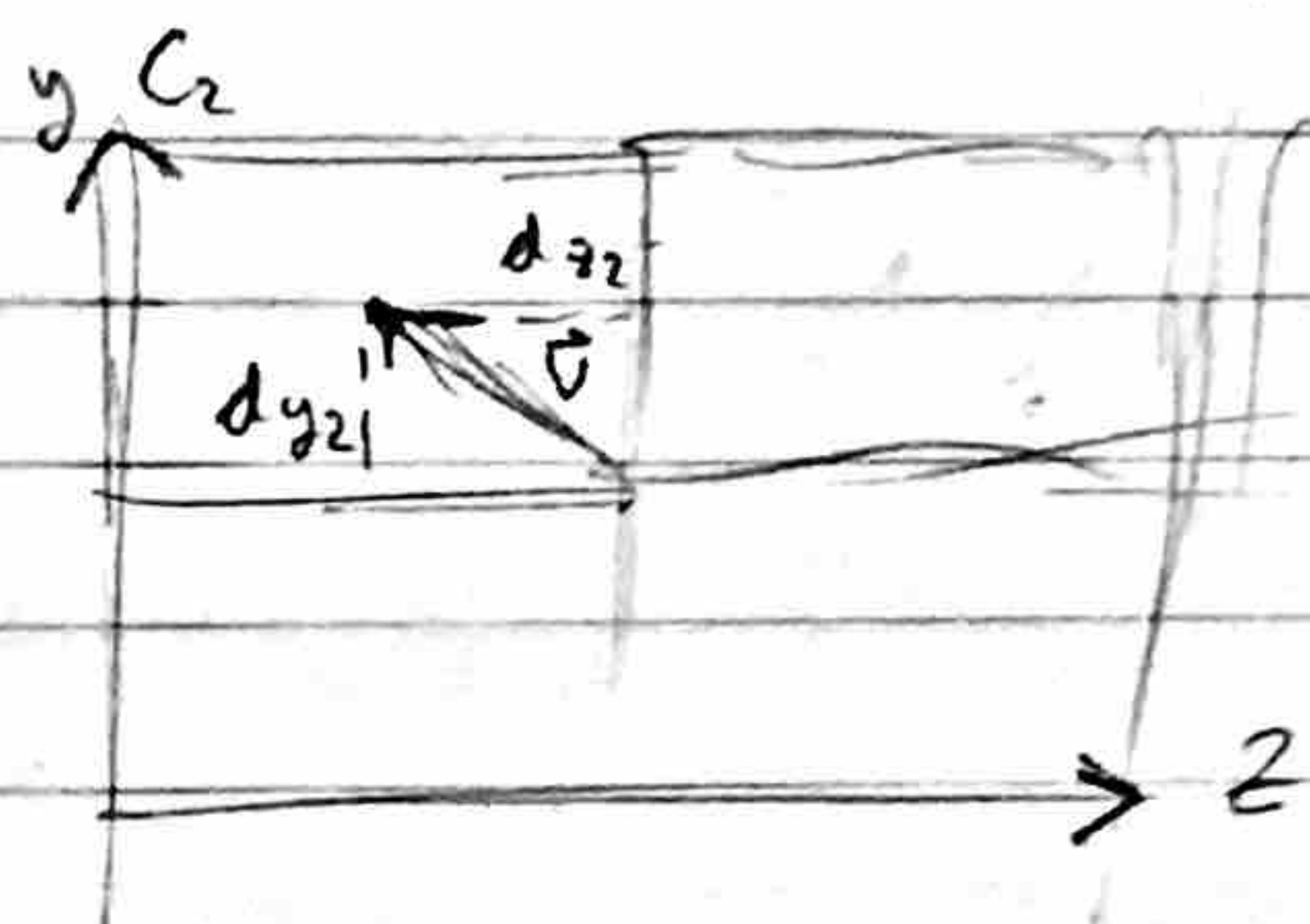
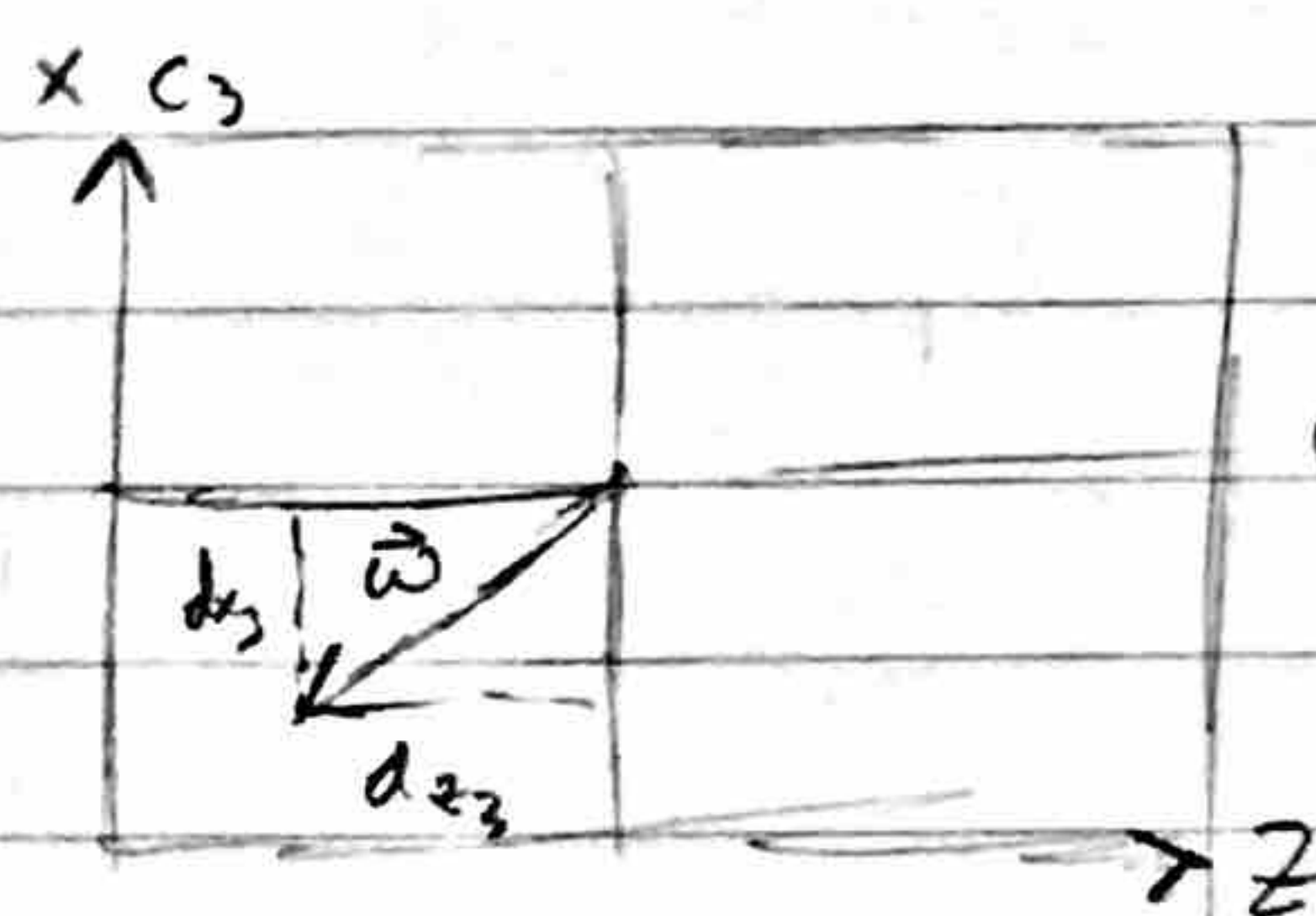
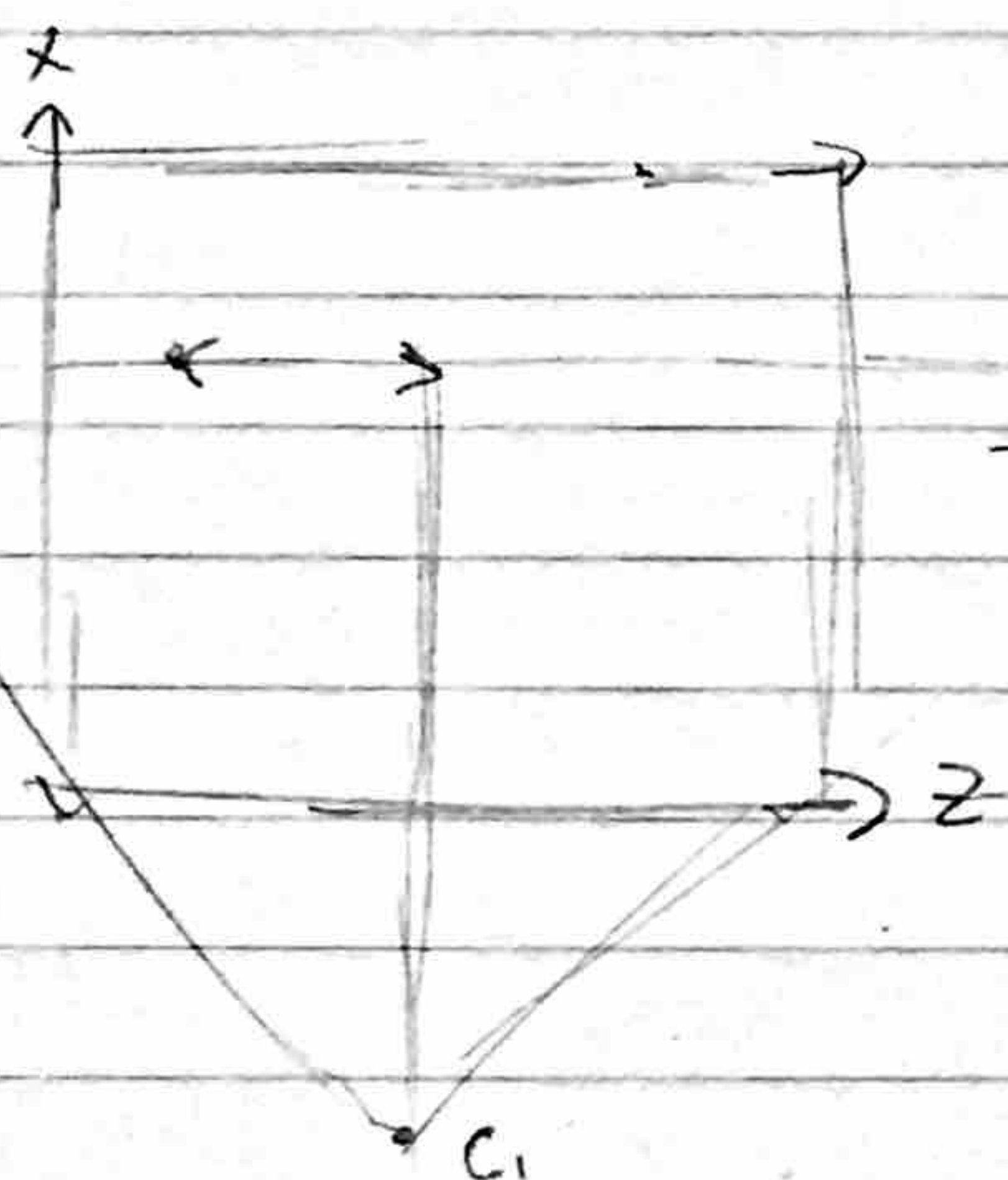


$$\vec{u} = \begin{bmatrix} dx_1 \\ dy_1 \\ 0 \end{bmatrix} t + \begin{bmatrix} x_{c1} \\ 0 \\ z_{c1} \end{bmatrix}$$

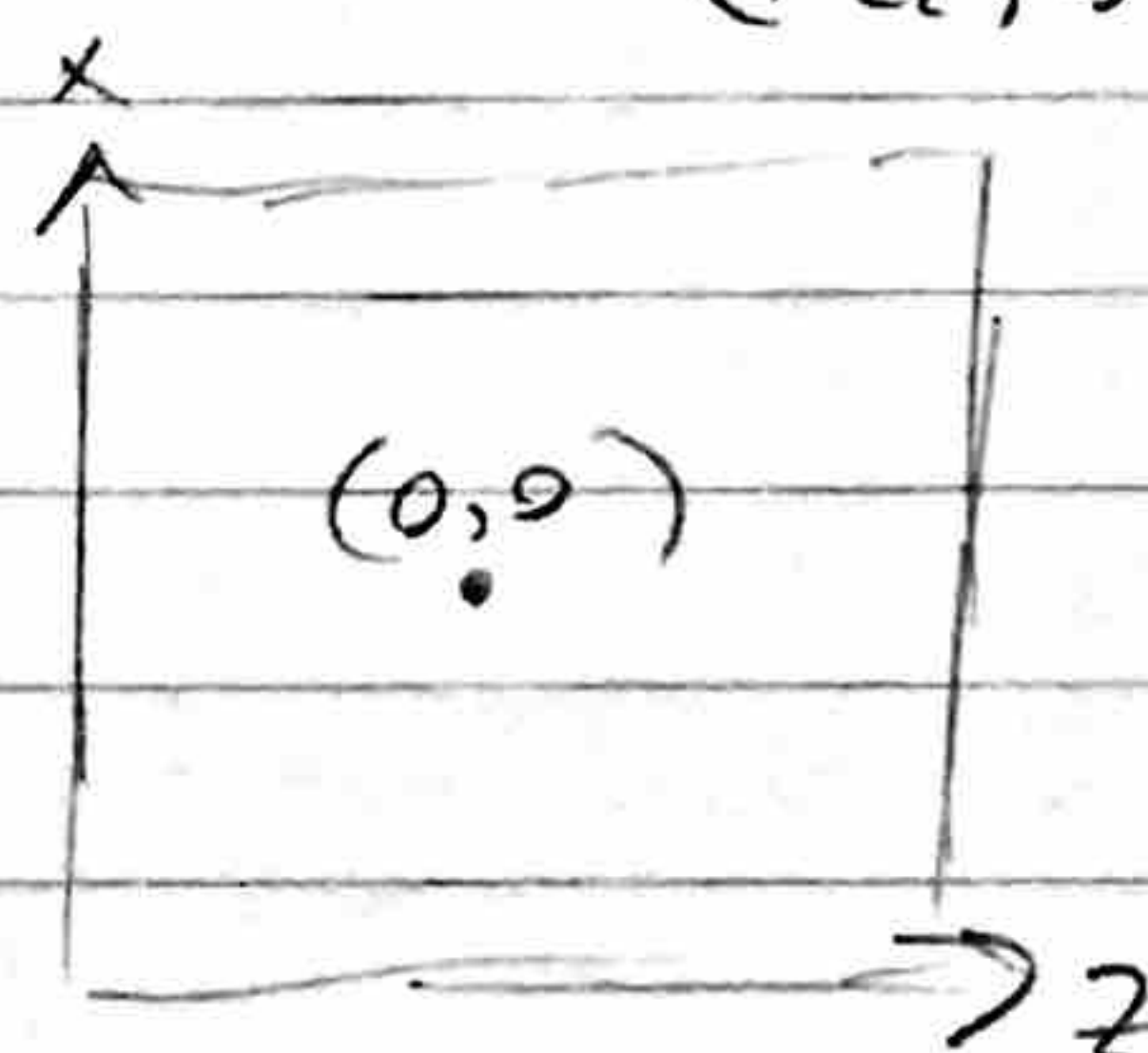


$$\vec{v} = \begin{bmatrix} 0 \\ dy_2 \\ dz_2 \end{bmatrix} l + \begin{bmatrix} x_{c2} \\ 0 \\ z_{c2} \end{bmatrix}$$



$$\vec{w} = \begin{bmatrix} dx_3 \\ 0 \\ dz_3 \end{bmatrix} m + \begin{bmatrix} 0 \\ y_{c3} \\ 0 \end{bmatrix}$$

$$\bullet (x_{c1}, 0, z_{c1})$$



$$\bullet (x_{c1}, 0, z_{c1})$$

