```
clear all;
clc;
clf.
close all;
filetype='.jpg';
% problem 1
%______%
%----%
% part 1 %
%----%
%%construct 3x3 normalized gauss mask
%default response to mimic matlab's built in function
dimensions = 3;
sigma = 0.5;
h = gaussfilter(dimensions, sigma)
%----%
% part 2 %
%----%
%%built in matlab function, compare to my function
H = fspecial('gaussian',dimensions,sigma)
sprintf('comapring my gauss filter vs builtin: h-H:')
gauss_difference = H-h %proves my mask and built in masks are identical
                     %because it = 0
%----%
% part 3 %
%----%
%%construct a 300x300 gauss mask
h2=fspecial('gaussian',300,sigma);
%----%
% part 4 %
%----%
%%plot frequency respons of said mask
figure('name', 'frequency response of gaauss mask');
freqz2(h2)
title('frequency response of gauss mask');
%----%
% part 5 %
%----%
%%display magnitude of FFT of gauss mask with DC component in the center
h2 = fft2(h2);
h2=fftshift(h2);
%h2 = sqrt(shifted);
figure('name','shifted fourier');
imshow(h2);
title('shiftedfft');
```

```
% problem 2
8----8
% part 1 %
%%read image (i develop on both windows and linux so this command
%%automatically determines what filepath to use)
image = './Carl_Friedrich_Gauss.jpg';
baseimage = imread(image);
I = imresize(baseimage, [400,400]);
I = rqb2qray(I);
figure('name', 'original image')
imshow(I);
title('original image');
%----%
% part 2 %
%----%
%%add gauss noise to image, call it image2
image2 = imnoise(I, 'gaussian', 0, .05);
figure('name', 'gauss noise added to img');
imshow(image2);
title('gauss noise added to img');
8----8
% part 3 %
%%add salt/pepper noise to image, call it image3
image3 = imnoise(I ,'salt & pepper',.05);
figure('name', 'salt & pepper added to img');
imshow(image3);
title('salt & pepper added to img');
%----%
% part 4 %
8----8
%%apply filtering in space domain (convolution)
%see convolution.m
%----%
% part 5 %
%%apply median filtering operation
%see medianfilter.m
8----8
% part 6 %
%%use convolution code to perform gauss filter on image2
FI = convolution(image2, h);
figure('name', 'gauss filtered image2');
```

```
imshow(FI);
title('gauss filtered image2');
% figure('name', 'gauss filter using builtin convolv');
% builtin = conv2(double(I),double(h));
% imshow(builtin);
%----%
% part 7 %
%----%
%%use convolution code to perform gauss filter on image3
G3 = convolution(image3, h);
figure('name', 'gauss filtered img3');
imshow(G3);
title('gauss filtered image3');
%----%
% part 8 %
%----%
%%use code to perform median filter on image2
med1= medianfilter(image2);
figure('name','median filtered image2');
imshow(med1);
title('median filtered image3');
%----%
% part 9 %
%----%
%%use code to perform median filter on image3
med2 = medianfilter(image3);
figure('name','median filtered image3');
imshow(med2);
title('median filtered image3');
%----%
% part 10 %
%----%
%%show and discuss results
        h =
            0.0113
                     0.0838
                               0.0113
            0.0838
                     0.6193
                               0.0838
            0.0113
                     0.0838
                               0.0113
       H =
            0.0113
                     0.0838
                               0.0113
            0.0838
                     0.6193
                               0.0838
            0.0113
                     0.0838
                               0.0113
```

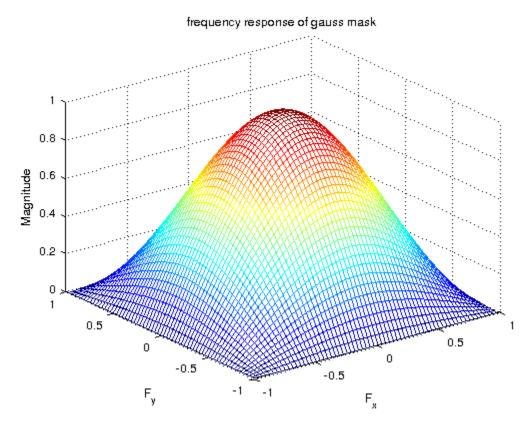
ans =

comapring my gauss filter vs builtin: h-H:

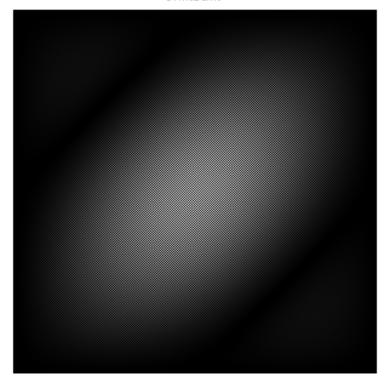
gauss_difference =

0	0	0
0	0	0
0	0	0

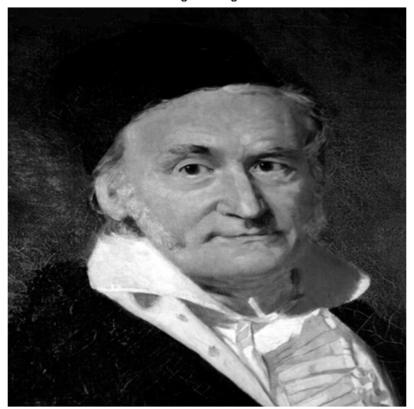
Warning: Displaying real part of complex input.







original image



gauss noise added to img



salt & pepper added to img



gauss filtered image2



gauss filtered image3



median filtered image3



median filtered image3



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