

# Programming Assignment 2: PoseRAC

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## Abstract

*In this assignment, I explored the state-of-the-art repeat action counting algorithm **PoseRAC** and tried to reproduce the results in the original paper. Then I proved the necessity of Transformer encoder by canceling the encoder part and using Fully-Connected Layer only. Moreover, I also tried to explore the relationship between counting performance and the number of encoder layers together with number of heads in the multi-head attention module. The results show that the performance of PoseRAC barely improves when the number of encoder layers increases from 1 to 8, but the model will crush when the number of encoder layers is larger than 8 in my training setting. Besides, the performance of PoseRAC is not sensitive to the number of heads in the multi-head attention module. Finally, I replaced the triplet margin loss with **contrastive loss** and **circle loss**, the results show that circle loss significantly boosts the model within 20 epoch, the evaluation metrics MAE and OBO improved from 0.2540 and 0.5395 to 0.2083 and 0.6053.*

## 1. Introduction

**PoseRAC** is the state-of-the-art repeat action counting algorithm proposed by [1]. This model achieves tremendous success in the repeat action counting task and improves the performance of the previous state-of-the-art model by a large margin. The novelty of PoseRAC is the new annotation method. The traditional method will annotate the start and the end frame of an action, models are forced to regress the locations or indices of an action. However, PoseRAC turns the annotation into two salient frames which indicates the most representative points of an action. Then PoseRAC utilizes a keypoint extractor to transform the salient frames into a series of keypoint with 3D coordinates. This operation enormously reduces the amount of data need to process and improves the effectiveness of information because it only uses transformer encoder layer to get the embedding information and a single FC layer to classify the embedding.

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## References

- [1] Ziyu Yao, Xuxin Cheng, and Yuexian Zou. Poserac: Pose saliency transformer for repetitive action counting. *arXiv preprint arXiv:2303.08450*, 2023. 1