CS 182: Introduction to Machine Learning, Fall 2022 Homework 5

(Due on Wednesday, Dec. 20 at 11:59pm (CST))

Notice:

- Please submit your assignments via Gradescope. The entry code is <u>G2V63D</u>.
- Please make sure you select your answer to the corresponding question when submitting your assignments.
- Each person has a total of five days to be late without penalty for all the assignments. Each late delivery less than one day will be counted as one day.

1. [10 points] [Deep Learning Models]

- (a) Consider a 3D convolution layer. Suppose the input size is $32 \times 32 \times 3$ (width, height, depth) and we use ten 5×5 (width, height) kernels to convolve with it. Set stride = 1 and pad = 2. What is the output size? Let the bias for each kernel be a scalar, how many parameters do we have in this layer? [5 points]
- (b) The convolution layer is followed by a max pooling layer with 2×2 (width, height) filter and stride = 2. What is the output size of the pooling layer? How many parameters do we have in the pooling layer? [5 points]

- 2. [30 points] [Deep Learning Models] Principal component analysis (PCA) and autoencoders are popular tools for dimension reduction in machine learning. In this problem, we look into the relation between PCA and the linear autoencoders.
 - (a) Given a sample matrix $\mathbf{X} = [\mathbf{x}_1, ..., \mathbf{x}_M] \in \mathbb{R}^{d \times M}$ where each column denotes a d-dimensional zero-mean sample. The goal of PCA is to find an orthogonal matrix (transformation) $\mathbf{W} \in \mathbb{R}^{d \times r}$ $(r \leq d)$ which is the solution to

$$\underset{\mathbf{W}}{\text{maximize}} \text{ Tr}(\mathbf{W}^T \mathbf{X} \mathbf{X}^T \mathbf{W}) \quad \text{s.t. } \mathbf{W}^T \mathbf{W} = \mathbf{I}_r,$$

where $\text{Tr}(\cdot)$ denotes the trace and \mathbf{I}_r is an $r \times r$ identity matrix. Show that

- i. when r = 1, **W** is exactly the eigenvector of $\mathbf{X}\mathbf{X}^T$ corresponding to its largest eigenvalue. [7 points]
- ii. \mathbf{W} is also the solution to

$$\underset{\mathbf{W}}{\text{minimize}} \ \|\mathbf{X} - \mathbf{W}\mathbf{W}^T\mathbf{X}\|_F^2 \quad \text{s.t.} \ \mathbf{W}^T\mathbf{W} = \mathbf{I}_r,$$

where $\|\cdot\|_F$ is the Frobenius norm, i.e., $\|\mathbf{P}\|_F = \sqrt{\text{Tr}(\mathbf{P}^T\mathbf{P})}$. [7 points]

(b) Consider a linear autoencoder (as a neural network) with a single hidden layer structure:

$$\mathbf{H} = \mathbf{A}_1 \mathbf{X} + \mathbf{b}_1 \mathbf{1}^T$$
$$\hat{\mathbf{X}} = \mathbf{A}_2 \mathbf{H} + \mathbf{b}_2 \mathbf{1}^T,$$

where $\mathbf{A}_1 \in \mathbb{R}^{r \times d}$ ($\mathbf{A}_2 \in \mathbb{R}^{d \times r}$) and $\mathbf{b}_1 \in \mathbb{R}^{r \times 1}$ ($\mathbf{b}_2 \in \mathbb{R}^{d \times 1}$) are respectively the weight matrix and the bias vector of the layer in the encoder (decoder), and $\mathbf{1} = [1, ..., 1]^T \in \mathbb{R}^M$. One trains the linear autoencoder by minimizing the reconstruction error:

$$\{\mathbf{A}_1^\star, \mathbf{b}_1^\star, \mathbf{A}_2^\star, \mathbf{b}_2^\star\} = \underset{\mathbf{A}_1, \mathbf{b}_1, \mathbf{A}_2, \mathbf{b}_2}{\operatorname{argmin}} \quad \|\mathbf{X} - \hat{\mathbf{X}}\|_F^2.$$

Show that

i. \mathbf{A}_2^{\star} can be solved from:

$$\underset{\mathbf{A}_2}{\text{minimize}} \ \|\mathbf{X} - \mathbf{A}_2 \mathbf{A}_2^{\dagger} \mathbf{X}\|_F^2,$$

where $\mathbf{A}_2^{\dagger} = (\mathbf{A}_2^T \mathbf{A}_2)^{-1} \mathbf{A}_2^T$ is the Moore-Penrose pseudoinverse of \mathbf{A}_2 . [8 points] (*Hint*: use the derivative of Frobenius norm and the fact that $\mathbf{A}_2^{\dagger} = \underset{\mathbf{A}_1}{\operatorname{argmin}} \|\mathbf{X} - \mathbf{A}_2 \mathbf{A}_1 \mathbf{X}\|_F^2$)

ii. the solution **W** from (a) can be taken as the same as A_2^{\star} . [8 points] (*Hint:* you may prove it by showing the equivalence of the column spaces spanned by these two matrices)





