# 

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## 1. [Deep Learning Models]

(a) Consider a 3D convolution layer. Suppose the input size is  $32 \times 32 \times 3$  (width, height) and we use ten  $5 \times 5$  (width, height) kernels to convolve with it. Set stride = 1 and pad = 2. What is the output size? Let the bias for each kernel be a scalar, how many parameters do we have in this layer?

# Solution:

The input data shape is

$$[C_{in}, D_{in}, H_{in}, W_{in}] = [1, 3, 32, 32]$$

and the kernel size is

$$[C_{out}, D_{kernel}, H_{kernel}, w_{kernel}] = [10, 3, 5, 5]$$

Then by the formula, we have output data with a shape

$$[C_{out}, D_{out}, H_{out}, W_{out}]$$

and

$$D_{out} = \frac{D_{in} + 2 \times pad - (D_{kernel} - 1) - 1}{stride} + 1 = 1$$

$$H_{out} = \frac{H_{in} + 2 \times pad - (H_{kernel} - 1) - 1}{stride} + 1 = 32$$

$$W_{out} = \frac{W_{in} + 2 \times pad - (W_{kernel} - 1) - 1}{stride} + 1 = 32$$

Thus, the output size is  $[C_{out}, D_{out}, H_{out}, W_{out}] = [10, 1, 32, 32]$ Moreover, the total number of parameters is

$$\#\{parameters\} = \#\{parameters\ in\ kernel\} + \#\{biases\} = 5 \times 5 \times 1 \times 10 + 10 = 260$$

(b) The convolution layer is followed by a max pooling layer with  $2 \times 2$  (width, height) filter and stride = 2. What is the output size of the pooling layer? How many parameters do we have in the pooling layer?

### Solution:

The input data shape is

$$[C_{in}, D_{in}, H_{in}, W_{in}] = [10, 1, 32, 32]$$

and the kernel shape is

$$[C_{out}, D_{kernel}, H_{kernel}, W_{kernel}] = [10, 1, 2, 2]$$

Then by the formula, we have output data with a shape

$$[C_{out}, D_{out}, H_{out}, W_{out}]$$

and

$$\begin{split} D_{out} &= \frac{D_{in} + 2 \times pad - (D_{kernel} - 1) - 1}{stride} + 1 = 1 \\ H_{out} &= \frac{H_{in} + 2 \times pad - (H_{kernel} - 1) - 1}{stride} + 1 = 16 \\ W_{out} &= \frac{W_{in} + 2 \times pad - (W_{kernel} - 1) - 1}{stride} + 1 = 16 \end{split}$$

Thus, the output size is  $[C_{out}, D_{out}, H_{out}, W_{out}] = [10, 1, 16, 16].$ 

Moreover, given that the max pooling layer only performs maximizing, there are no parameters in the pooling layer. Thus, the total number of parameters of the pooling layer is 0.

- 2. [Deep Learning Models]
  - (a) (i.) When r = 1, W is exactly the eigenvector of  $XX^T$  corresponding to its largest eigenvalue. **Proof:**

When r = 1, we know that  $\mathbf{W}^T \mathbf{X} \mathbf{X}^T \mathbf{W}$  is a scalar, which means

$$Tr(\mathbf{W}^T \mathbf{X} \mathbf{X}^T \mathbf{W}) = \mathbf{W}^T \mathbf{X} \mathbf{X}^T \mathbf{W}$$

Hence, the optimization problem can be rewritten as follows:

Then, the Lagrangian is:

$$\mathcal{L}(\boldsymbol{W}, \lambda) = \boldsymbol{W}^T \boldsymbol{X} \boldsymbol{X}^T \boldsymbol{W} - \lambda \boldsymbol{W}^T \boldsymbol{W}$$

Taking the derivative of  $\mathcal{L}$  w.r.t W and setting it to 0, we get

$$2XX^{T}W^{*} - 2\lambda^{*}W^{*} = 0$$

$$\Rightarrow$$

$$XX^{T}W^{*} = \lambda^{*}W^{*}$$

Thus,  $\lambda^*$  is eigenvalue of  $XX^T$  and  $W^*$  is the corresponding eigenvector. Moreover, since

$$\mathbf{W}^{\star T} \mathbf{X} \mathbf{X}^T \mathbf{W}^{\star} = \lambda^{\star}$$

Therefore, we need to get the largest eigenvalue  $\lambda^*$  to maximize  $W^T X X^T W$ , which means  $W^*$  is the eigenvector corresponding to the largest eigenvalue.

(ii.)  $\boldsymbol{W}$  is also the solution to

$$\begin{array}{ll} \text{minimize} & ||\boldsymbol{X} - \boldsymbol{W} \boldsymbol{W}^T \boldsymbol{X}||_F^2 \quad s.t. \quad \boldsymbol{W}^T \boldsymbol{W} = \boldsymbol{I}_r \\ \end{array}$$

Proof:

Given that 
$$|\mathbf{P}|_F = \sqrt{Tr(\mathbf{P}^T\mathbf{P})}$$
, we get

$$\begin{aligned} ||\boldsymbol{X} - \boldsymbol{W} \boldsymbol{W}^T \boldsymbol{X}||_F^2 &= Tr[(\boldsymbol{X} - \boldsymbol{W} \boldsymbol{W}^T \boldsymbol{X})^T (\boldsymbol{X} - \boldsymbol{W} \boldsymbol{W}^T \boldsymbol{X})] \\ &= Tr[\boldsymbol{X}^T \boldsymbol{X} - \boldsymbol{X}^T \boldsymbol{W} \boldsymbol{W}^T \boldsymbol{X} - \boldsymbol{X}^T \boldsymbol{W} \boldsymbol{W}^T \boldsymbol{X} + \boldsymbol{X}^T \boldsymbol{W} \boldsymbol{W}^T \boldsymbol{W} \boldsymbol{W}^T \boldsymbol{X}] \\ &= Tr[\boldsymbol{X}^T \boldsymbol{X} - \boldsymbol{X}^T \boldsymbol{W} \boldsymbol{W}^T \boldsymbol{X}] \\ &= Tr(\boldsymbol{X}^T \boldsymbol{X}) - Tr(\boldsymbol{X}^T \boldsymbol{W} \boldsymbol{W}^T \boldsymbol{X}) \\ &= Tr(\boldsymbol{X}^T \boldsymbol{X}) - Tr(\boldsymbol{W}^T \boldsymbol{X} \boldsymbol{X}^T \boldsymbol{W}) \end{aligned}$$

Since the first term of the equation has nothing to do with W, the optimization problem can be rewritten as follows:

$$\begin{array}{ll}
\text{minimize} & -Tr(\boldsymbol{W}^T \boldsymbol{X} \boldsymbol{X}^T \boldsymbol{W}) & s.t. \ \boldsymbol{W}^T \boldsymbol{W} = \boldsymbol{I}_r
\end{array}$$

which is equivalent to the PCA problem.

(b) (i.)  $\boldsymbol{A}_2^{\star}$  can be solved from:

$$egin{aligned} & ext{minimize} & ||oldsymbol{X} - oldsymbol{A}_2 oldsymbol{A}_2^\dagger oldsymbol{X}||_F^2 \end{aligned}$$

- (ii.) The solution W from (a) can be taken as the same as  $A_2^{\star}$ .
- 3. [Ensemble Learning] Suppose there are L independent two-class classifiers used for simple voting and the output of classifier j ( $j = 1 \cdots L$ ) is denoted as  $d_j$ . From the point of view that the mean squared error of an estimator can be decomposed into the bias part and the variance part, explain why increasing L can lead to an increase in classification accuracy.

#### **Proof:**

By the definition of MSE, we get

$$\begin{split} MSE(\hat{y}) &= \mathbb{E}[(\hat{y} - y)^2] = \mathbb{E}[(\hat{y} - \mathbb{E}[\hat{y}] + \mathbb{E}[\hat{y}] - y)^2] \\ &= \mathbb{E}[(\hat{y} - \mathbb{E}[\hat{y}])^2 + 2(\hat{y} - \mathbb{E}[\hat{y}])(\mathbb{E}[\hat{y}] - y) + (\mathbb{E}[\hat{y}] - y)^2] \\ &= \mathbb{E}[(\hat{y} - \mathbb{E}[\hat{y}])^2] + 2\mathbb{E}[(\hat{y} - \mathbb{E}[\hat{y}])]\mathbb{E}[(\mathbb{E}[\hat{y}] - y)] + \mathbb{E}[(\mathbb{E}[\hat{y}] - y)^2] \\ &= \mathbb{E}[(\hat{y} - \mathbb{E}[\hat{y}])^2] + 2(\mathbb{E}[\hat{y}] - \mathbb{E}[\hat{y}])\mathbb{E}[(\mathbb{E}[\hat{y}] - y)] + (\mathbb{E}[\hat{y}] - y)^2 \\ &= \mathbb{E}[(\hat{y} - \mathbb{E}[\hat{y}])^2] + (\mathbb{E}[\hat{y}] - y)^2 \\ &= \mathrm{Var}(\hat{y}) + \mathrm{Bias}^2(\hat{y}, y) \end{split}$$

Then, for the second term of the equation above, we get

$$\begin{aligned} \operatorname{Bias}^2(\hat{y}, y) &\propto \operatorname{Bias}(\hat{y}, y) \\ &= \mathbb{E}[\hat{y}] - y \\ &\propto \mathbb{E}[\hat{y}] \\ &= \mathbb{E}\left[\frac{1}{L}\sum_j d_j\right] \\ &\geq \frac{1}{L} \times L \min_j \{\mathbb{E}[d_j]\} \\ &= \min_j \{\mathbb{E}[d_j]\} \end{aligned}$$

which means that the Bias term won't change as L gets larger.

As for the first term, we get

$$\operatorname{Var}(\hat{y}) = \operatorname{Var}\left(\frac{1}{L}\sum_{j}d_{j}\right)$$

$$= \frac{1}{L^{2}}\operatorname{Var}\left(\sum_{j}d_{j}\right)$$

$$\leq \frac{1}{L^{2}} \times L \max_{j}\left(\operatorname{Var}(d_{j})\right)$$

$$= \frac{1}{L}\max_{j}\left\{\operatorname{Var}(d_{j})\right\}$$

which means that the Variance term will get smaller when L gets larger.

In conclusion,  $MSE(\hat{y})$  will get smaller as L gets larger, so the classification will be more accurate.

4. [Model Assessment and Selection] Suppose we carry out a K-fold cross-validation on a dataset and obtain the classification error rates  $\{p_i\}_{i=1}^K$ , describe the steps of a one-sided t test on testing the null hypothesis  $H_0$  that the classifier has error percentage  $p_0$  or less at a significance level  $\alpha$ .