

# IT Technical Writing and Research Ethics

Hyeon Seong Jeon, *Student Member, SKKU*, Shin Sun Kim, *Engineer, SKKU*, Wayne Rooney, *Marketing, SE*, and Tae Yong Kuc, *Professor, SKKU*

**Abstract**—The abstract goes here.

**Index Terms**—Computer Society, IEEE, IEEEtran, journal, LATEX, paper, template.

## 1 INTRODUCTION

THIS demo file is intended to serve as a “starter file” for IEEE Computer Society journal papers produced under LATEX using IEEEtran.cls version 1.8b and later. As you can see (1),  $f = ma$ . I wish you the best of success.

$$f = ma \quad (1)$$

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$$p(x, y) = \sin(x + y) \quad (2)$$

$$p(x, y) = \sin x \cos y + \cos x \sin y \quad (3)$$

$$p(x_0, y_0) = \sin x_0 \cos y_0 + \cos x_0 \sin y_0 \quad (4)$$

$$q(x, y) = \cos(x + y) \quad (5)$$

$$= \cos x \cos y - \sin x \sin y$$

$$q(x_0, y_0) = \cos x_0 \cos y_0 - \sin x_0 \sin y_0 \quad (6)$$

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$$\begin{aligned} & \int_0^1 (f_n - \frac{n}{r} f_n)^2 r \, dr + 2n \int_0^1 f_n f_n \, dr \\ &= \int_0^1 (f_n - \frac{n}{r} f_n)^2 r \, dr + n f_n^2(1) \end{aligned} \quad (7)$$

$$\begin{aligned} \phi(x, y, z) &= (x^2 + y^2 + z^2)^{1/2} (x - y + z)(x + y - z)^2 \\ &\quad - [f(x, y, z) - 3x^2] \end{aligned} \quad (8)$$

mds

August 26, 2015

### 1.1 Subsection Heading Here

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#### 1.1.1 Subsubsection Heading Here

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## 2 CONCLUSION

The conclusion goes here.

## APPENDIX A

### PROOF OF THE FIRST ZONKLAR EQUATION

Appendix one text goes here.

## APPENDIX B

Appendix two text goes here.

- H. Jeon is with the Department of Artificial Intelligence, SungKyunKwan University, 16419, Suwon, South Korea (e-mail: cutz@skku.edu)
- S. Kim is with the Electrical and Electronic Engineering Department, SungKyunKwan University, 16419, Suwon, South Korea (e-mail: sunkim@skku.edu)
- W. Rooney is with Marketing Department, SamSung Electronics, 16419, Suwon, South Korea (e-mail: rooney@samsung.co.kr)
- T. Kuc is with the Electrical and Electronic Engineering Department, SungKyunKwan University, 16419, Suwon, South Korea (e-mail: tykuc@skku.edu).

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## REFERENCES

- [1] H. Kopka and P. W. Daly, *A Guide to L<sup>A</sup>T<sub>E</sub>X*, 3rd ed. Harlow, England: Addison-Wesley, 1999.



**Hyeon Seong Jeon** was born in Seoul, Korea in 1990. He received the B.E. degree in mass communication and journalism from Sungkyunkwan University (SKKU) Seoul, in 2017. In 2019, he joined the Department of Artificial Intelligence from Sungkyunkwan University, Suwon. His current research interests include A.I. and self-driving car using Deep learning.

**Tae Yong Kuc** was born in Seoul, Korea in 1956. He received the B.E. degree in electrical engineering from Koera Advanced Institute of Science and Technology (KAIST) in 1977, M.E. and Ph.D. degrees in electrical engineering from KAIST in 1979 and 1983 respectively. In 1983, he joined the Department of Electrical Engineering, SungKyunKwan University as a Lecturer. He has been with the Department of Electrical Engineering, SungKyunKwan University, Suwon, where he was an Assistant Professor, became an Associate Professor in 1994, and a Professor in 1997. His current research interests include power electronics, electrical machines and drives, active filters, flexible ac transmission systems, high-voltage dc, and power quality.