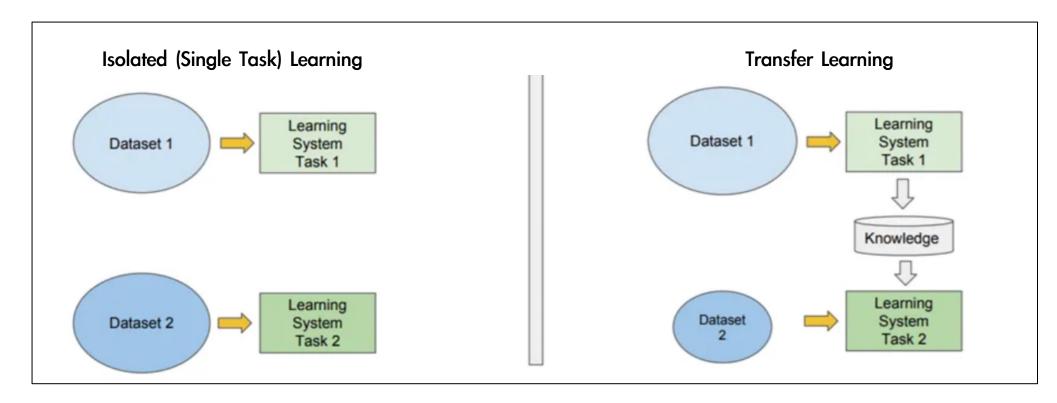


December 2023

http://link.koreatech.ac.kr

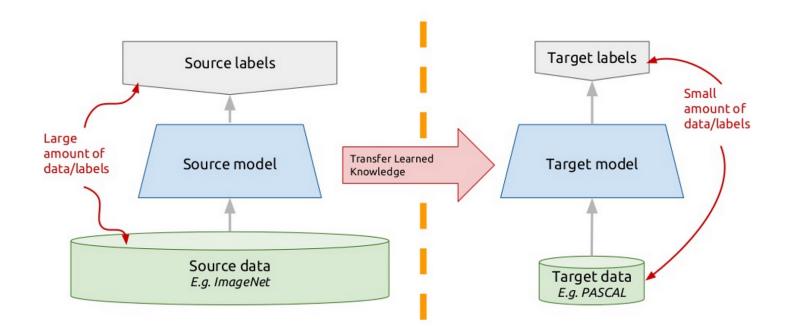
#### **♦**What is Transfer Learning?

- Transfering the knowledge of one model to perform a new task
- Reuse of a pre-trained model on a new task
- a.k.a "Domain Adaptation"

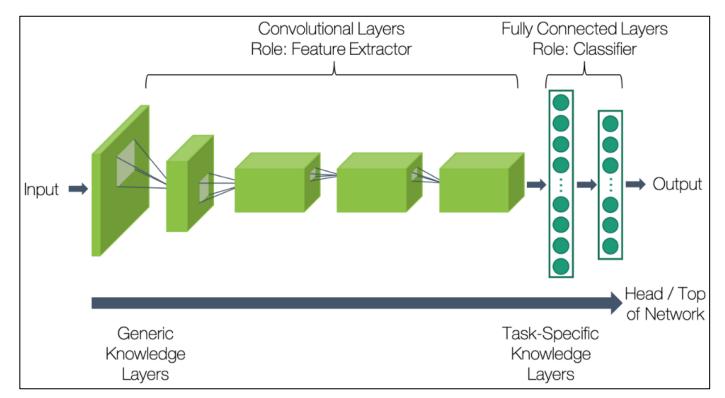


#### **♦** Motivation of Transfer Learning

- Lots of data, time, resources needed to train and tune a neural network from scratch
  - An ImageNet deep neural network can take weeks to train and fine-tune from scratch
  - Unless you have 256 GPUs, it is not possible to achieve in 1 hour
- Cheaper & faster way of adapting a neural network by <u>exploiting their generalization</u>
   <u>properties</u>
   <u>Transfer learning: idea</u>



- Neural Network Layers: General to Specific
  - Bottom/first/earlier layers: general learners
    - Low-level notions of edges, visual shapes
  - Top/last/later layers: specific learners
    - High-level features such as eyes, feathers

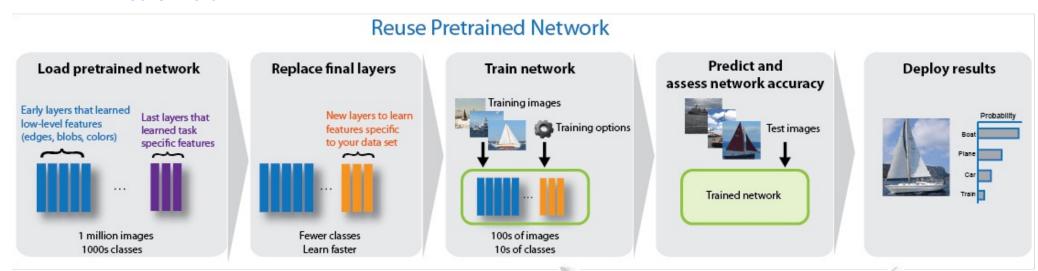


conv2 1: a few of the 128 filters conv3 1: a few of the 256 filters conv4\_1: a few of the 512 filters conv5\_1: a few of the 512 filters

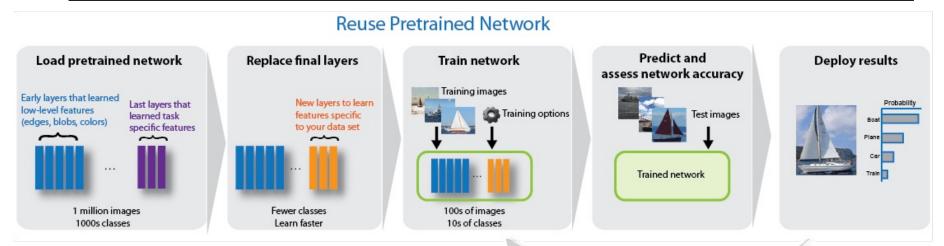
conv1\_1: a few of the 64 filters

Example: VGG 16 Filters

- **♦**Transfer Learning Process (1/2)
  - 1. Start with a pre-trained network
  - 2. Partition network into:
    - Featurizers: identify which layers to keep (feature extraction layers)
    - Classifiers: identify which layers to replace
      - In many cases, we replace the old layers with new ones (with different numbers of outputs) on top of featurizers



- **♦**Transfer Learning Process (2/2)
  - 3. Two major transfer learning methods
    - 1) Frozen the featurizers and Train the classifiers (including new layers) with new data
      - It is common to pretrain a ConvNet on a very large dataset (e.g. ImageNet, which contains 1.2 million images with 1000 categories), and then use the ConvNet as a featurizers for the task of interest
    - 2) Fine-tune the whole model with new data
      - > Unfreeze weights and fine-tune the whole network with smaller learning rate
      - It is not common method because it is relatively rare to have a dataset of sufficient size



### **Data Preparation**

#### **♦** Data Preparation

- We will use torchvision and torch.utils.data packages for loading the data
- The problem we're going to solve today is to train a model to classify ants and bees
  - There are about 120 training images each for ants and bees
  - There are 75 validation images each for ants and bees
- Usually, this is a very small dataset to generalize upon, if trained from scratch.
- Since we are using transfer learning, we should be able to generalize reasonably well
- Download the data from here and extract it to the predefined folder
  - <a href="https://download.pytorch.org/tutorial/hymenoptera\_data.zip">https://download.pytorch.org/tutorial/hymenoptera\_data.zip</a>
  - Make "\_00\_data/l\_transfer\_learning\_data" and store the unzipped files into the new folder



#### Preparation

```
import torch
import torch.nn as nn
import torch.optim as optim
from torch.optim import lr_scheduler
import numpy as np
from torchvision import datasets, models, transforms
import matplotlib.pyplot as plt
import time, os, sys
from pathlib import Path
BASE_PATH = str(Path(__file__).resolve().parent.parent.parent) # BASE_PATH: /Users/yhhan/git/link_dl
sys.path.append(BASE_PATH)
CURRENT_FILE_PATH = os.path.dirname(os.path.abspath(__file__))
CHECKPOINT FILE PATH = os.path.join(CURRENT FILE PATH, "checkpoints")
if not os.path.isdir(CHECKPOINT_FILE_PATH):
 os.makedirs(os.path.join(CURRENT FILE PATH, "checkpoints"))
```

#### **♦** Data Transforms

```
data_transforms = {
  'train': transforms.Compose([
    transforms.RandomResizedCrop(224),
    transforms.RandomHorizontalFlip(),
    transforms.ToTensor(),
    transforms.Normalize([0.485, 0.456, 0.406], [0.229, 0.224, 0.225])
  ]),
  'val': transforms.Compose([
    transforms.Resize(256),
    transforms.CenterCrop(224),
    transforms.ToTensor(),
   transforms.Normalize([0.485, 0.456, 0.406], [0.229, 0.224, 0.225])
  ])
```

#### **♦**Get New Data

```
def get new data():
  new_data_path = os.path.join(BASE_PATH, "_00_data", "l_transfer_learning_data")
  image datasets = {
    x: datasets.ImageFolder(os.path.join(new_data_path, x), data_transforms[x])
    for x in ['train', 'val']
                                                                                         I_transfer_learning_data

✓ Image: Train

                                                                                             > ants
 dataset sizes = {
                                                                                             > bees
    x: len(image_datasets[x]) for x in ['train', 'val']

✓ I val

                                                                                             > ants
                                                                                             > bees
 dataloaders = {
    x: torch.utils.data.DataLoader(image_datasets[x], batch_size=4, shuffle=True, num_workers=0)
    for x in ['train', 'val']
 class_names = image_datasets['train'].classes
  return image_datasets, dataset_sizes, dataloaders, class_names
```

```
def train_model(
 dataloaders, dataset_sizes, model, loss_fn, optimizer, scheduler, num_epochs=25, device=torch.device("cpu")
 since = time.time()
 best_model_params_path = os.path.join(CHECKPOINT_FILE_PATH, 'best_model_params.pt')
 best acc = 0.0
 for epoch in range(num epochs):
    print(f'Epoch {epoch}/{num_epochs - 1}')
    print('-' * 10)
    # Each epoch has a training and validation phase
    for phase in ['train', 'val']:
      if phase == 'train':
       model.train() # Set model to training mode
      else:
       model.eval() # Set model to evaluate mode
```

```
def train_model(
  dataloaders, dataset_sizes, model, loss_fn, optimizer, scheduler, num_epochs=25, device=torch.device("cpu")
):
  for epoch in range(num_epochs):
    for phase in ['train', 'val']:
      running loss = 0.0
      running_corrects = 0
      # Iterate over data
      for inputs, labels in dataloaders[phase]:
        inputs = inputs.to(device)
        labels = labels.to(device)
        # zero the parameter gradients
        optimizer.zero_grad()
```

```
def train_model(
  dataloaders, dataset_sizes, model, loss_fn, optimizer, scheduler, num_epochs=25, device=torch.device("cpu")
):
  . . .
  for epoch in range(num_epochs):
    for phase in ['train', 'val']:
      for inputs, labels in dataloaders[phase]:
        # track history if only in train
        with torch.set_grad_enabled(phase == 'train'):
          outputs = model(inputs)
          _, preds = torch.max(outputs, 1)
          loss = criterion(outputs, labels)
          # backward + optimize only if in training phase
          if phase == 'train':
            loss.backward()
            optimizer.step()
```

```
def train_model(
 dataloaders, dataset_sizes, model, loss_fn, optimizer, scheduler, num_epochs=25, device=torch.device("cpu")
):
  for epoch in range(num epochs):
    for phase in ['train', 'val']:
      for inputs, labels in dataloaders[phase]:
        # statistics
        running_loss += loss.item() * inputs.size(0)
        running_corrects += torch.sum(preds == labels.data)
      if phase == 'train':
        scheduler.step() # Scheduling the learning rate
      epoch_loss = running_loss / dataset_sizes[phase]
      epoch_acc = running_corrects.double() / dataset_sizes[phase]
```

```
def train_model(
 dataloaders, dataset_sizes, model, loss_fn, optimizer, scheduler, num_epochs=25, device=torch.device("cpu")
):
  for epoch in range(num epochs):
    for phase in ['train', 'val']:
      print(f'{phase} Loss: {epoch loss:.4f} Acc: {epoch acc:.4f}')
      # deep copy the model
      if phase == 'val' and epoch_acc > best_acc:
        best acc = epoch acc
        torch.save(model.state_dict(), best_model_params_path)
    print()
  time elapsed = time.time() - since
  print(f'Training complete in {time_elapsed // 60:.0f}m {time_elapsed % 60:.0f}s')
  print(f'Best val Acc: {best_acc:4f}\n')
```

```
def train_model(
 dataloaders, dataset_sizes, model, loss_fn, optimizer, scheduler, num_epochs=25, device=torch.device("cpu")
):
 # load best model weights
 model.load_state_dict(torch.load(best_model_params_path))
  return model
```

#### **♦** Visualization

```
def imshow(input, label=None):
  """Display image for Tensor."""
  input = input.numpy().transpose((1, 2, 0))
 mean = np.array([0.485, 0.456, 0.406])
  std = np.array([0.229, 0.224, 0.225])
  input = std * input + mean
  input = np.clip(input, 0, 1)
 plt.imshow(input)
 if label is not None:
    plt.title(label)
 plt.show()
```

#### **♦** Visualization

```
def visualize_model(dataloaders, class_names, model, num_images=6):
 model.eval()
  images_so_far = 0
 for i, (inputs, labels) in enumerate(dataloaders['val']):
    outputs = model(inputs)
    _, preds = torch.max(outputs, dim=1)
    for j in range(inputs.size()[0]):
      imshow(
        inputs.data[j], label="Prediction: {0} - Label: {1}".format(
          class_names[preds[j].item()], class_names[labels[j].item()]
      images_so_far += 1
      if images_so_far == num_images:
        return
```

#### **♦**Get Model

```
def get_model(method, device=torch.device("cpu")):
  model ft = models.resnet18(weights='IMAGENET1K V1')
 if method == "frozen and train new classifier":
                                                            We need to freeze all the network except the final layer.
    for param in model_ft.parameters():
                                                            We need to set requires grad = False to freeze the parameters
      param.requires grad = False
                                                            so that the gradients are not computed in backward()
  print(model ft)
  print("#" * 100)
  # Here the size of each output sample is set to 2
  num_ftrs = model_ft.fc.in_features
  model_ft.fc = nn.Linear(in_features=num_ftrs, out_features=2)
  print(model ft)
  print("#" * 100)
  model ft = model ft.to(device)
  return model_ft
```

#### **♦**Main

```
def main(method):
 device = torch.device("cuda:0" if torch.cuda.is available() else "cpu")
  image_datasets, dataset_sizes, dataloaders, class_names = get_new_data()
 model ft = get model(method, device)
 loss_fn = nn.CrossEntropyLoss()
 # Observe that all parameters are being optimized
 optimizer_ft = optim.Adam(model_ft.parameters(), lr=0.001)
 # Decay LR by a factor of 0.1 every 7 epochs
 exp_lr_scheduler = lr_scheduler.StepLR(optimizer_ft, step_size=7, gamma=0.1)
 model_ft = train_model(
    dataloaders, dataset_sizes, model_ft, loss_fn, optimizer_ft, exp_lr_scheduler,
    num epochs=25, device=device
 visualize_model(dataloaders, class_names, model_ft)
```

#### **♦** Main

```
if __name__ == "__main__":
    method_idx = 0
    methods = [
        "frozen_and_train_new_classifier",
        "fine_tune_the_whole_model"
    ]
    main(methods[method_idx])
```

```
Epoch 24/24
-----
train Loss: 0.4411 Acc: 0.7951
val Loss: 0.2509 Acc: 0.9346

Training complete in 2m 28s
Best val Acc: 0.941176
```

```
if __name__ == "__main__":
    method_idx = 1
    methods = [
        "frozen_and_train_new_classifier",
        "fine_tune_the_whole_model"
    ]
    main(methods[method_idx])
```

```
Epoch 24/24
-----
train Loss: 0.6055 Acc: 0.6721
val Loss: 0.5691 Acc: 0.6732

Training complete in 5m 26s
Best val Acc: 0.699346
```