

Geometric & Graphics Programming Lab: Lecture 14

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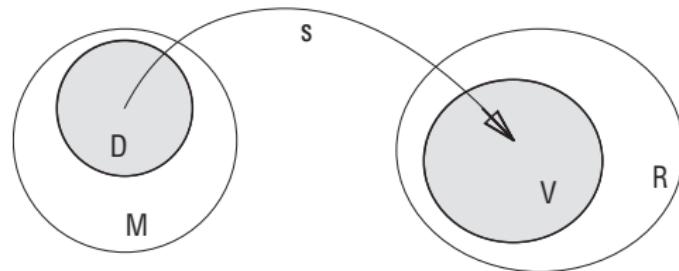
Outline: Cell complexes (LAR)

- 1 Solid Modeling
- 2 Linear Algebraic Representation (LAR)
- 3 LAR: computer representation
- 4 Operations

Solid Modeling

Representation scheme: definition

mapping $s : M \rightarrow R$ from a space M of mathematical models to a space R of computer representations



- ① The M set contains the mathematical models of the class of solid objects the scheme aims to represent
- ② The R set contains the symbolic representations, i.e. the proper data structures, built according to a suitable grammar

A. Requicha, [Representations for Rigid Solids: Theory, Methods, and Systems, ACM Comput. Surv.](#), 1980.

V. Shapiro, [Solid Modeling](#), In [Handbook of Computer Aided Geometric Design](#), 2001

Representation schemes

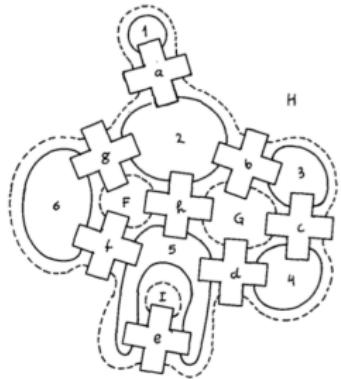
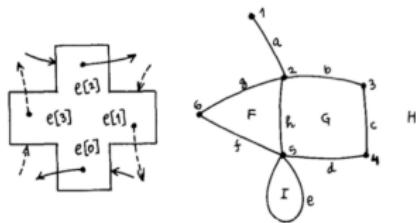
Most of such papers introduce or discuss one or more representation schemes . . .

- 1 Requicha, ACM Comput. Surv., 1980, [?]
- 2 Requicha & Voelcker, PEP TM-25, 1977, [?]
- 3 Rossignac & Requicha, Comput. Aided Des., 1991, [?]
- 4 Bowyer, SVLIS, 1994, [?]
- 5 Baumgart, Stan-CS-320, 1972, [?]
- 6 Braid, Commun. ACM, 1975, [?]
- 7 Dobkin & Laszlo, ACM SCG, 1987, [?]
- 8 Guibas & Stolfi, ACM Trans. Graph., 1985, [?]
- 9 Woo, IEEE Comp. Graph. & Appl., 1985, [?]
- 10 Yamaguchi & Kimura, Comp. Graph. & Appl., 1995, [?]
- 11 Gursoz & Choi & Prinz, Geom.Mod., 1990, [?]
- 12 S.S.Lee & K.Lee, ACM SMA, 2001, [?]
- 13 Rossignac & O'Connor, IFIP WG 5.2, 1988, [?]
- 14 Weiler, IEEE Comp. Graph. & Appl., 1985, [?]
- 15 Silva, Rochester, PEP TM-36, 1981, [?]
- 16 Shapiro, Cornell Ph.D Th., 1991, [?]
- 17 Paoluzzi et al., ACM Trans. Graph., 1993, [?]
- 18 Pratt & Anderson, ICAP, 1994, [?]
- 19 Bowyer, Djinn, 1995, [?]
- 20 Gomes et al., ACM SMA, 1999, [?]
- 21 Raghothama & Shapiro, ACM Trans. Graph., 1998, [?]
- 22 Shapiro & Vossler, ACM SMA, 1995, [?]
- 23 Hoffmann & Kim, Comput. Aided Des., 2001, [?]
- 24 Raghothama & Shapiro, ACM SMA, 1999, [?]
- 25 DiCarlo et al., IEEE TASE, 2008, [?]
- 26 Bajaj et al., CAD&A, 2006, [?]
- 27 Pascucci et al., ACM SMA, 1995, [?]
- 28 Paoluzzi et al., ACM Trans. Graph., 1995, [?]
- 29 Paoluzzi et al., Comput. Aided Des., 1989, [?]
- 30 Ala, IEEE Comput. Graph. Appl., 1992, [?]

and much more . . .

Representation scheme: Quad-Edge data structure

(Guibas & Stolfi, ACM Transactions on Graphics, 1985)



- (a) Edge record showing Next links.
- (b) A subdivision of the sphere.
- (c) Data structure for the subdivision

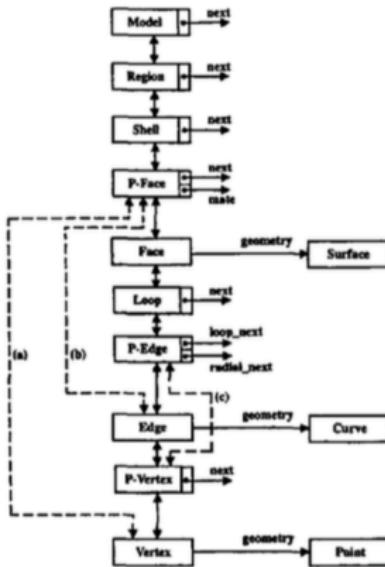
Primitives for the Manipulation
of General Subdivisions and
the Computation of Voronoi
Diagrams

largely used in computational
geometry algorithms and in
geometric libraries

Representation scheme: Partial-Entity data structure

(Sang Hun Lee & Kunwoo Lee, ACM Solid Modeling, 2001)

Compact Non-Manifold Boundary Representation Based on Partial Topological Entities



```

class Entity {
    int _id;
    Attribute *_attribute;
};

class Model : public Entity {
    Model *_next; // next model
    Region *_region; // list of regions
};

class Region : public Entity {
    Region *_next; // link field of the region list of a model
    Model *_model; // parent model
    Shell *_shell; // peripheral shell
};

class Shell : public Entity {
    Shell *_next; // next void shell
    Region *_region; // parent region
    Pface *_pface; // partial face
};

class Pface : public Entity { // partial face (p-face) class
    Pface *_next; // next p-face
    Shell *_shell; // parent shell
    Entity *_child; // child entity: a face, an edge, or a vertex
    Orient *_orient; // orientation flag w.r.t. the face normal
    Pface *_mate; // mate p-face
};

class Face : public Entity {
    Pface *_pface; // one of two incident p-faces
    Loop *_loop; // peripheral loop
    Surface *_geometry; // surface
};

class Loop : public Entity { // next hole loop
    Loop *_next; // next hole loop
    Face *_face; // parent face
    Pedge *_pedge; // a p-edge in a loop
};

class Pedge : public Entity { // partial edge (p-edge) class
    Pedge *_loop; // parent loop
    Entity *_child; // child entity: an edge or a p-vertex
    Orient *_orient; // orientation flag w.r.t. the edge direction
    Pvertex *_pvertices; // start p-vertex
    Pedge *_looped_prev; // previous p-edge in the loop cycle
    Pedge *_looped_next; // next p-edge in the loop cycle
    Pedge *_radial_prev; // previous p-edge in the radial cycle
    Pedge *_radial_next; // next p-edge in the radial cycle
};

class Pvertex : public Entity { // partial vertex (p-vertex) class
    Pvertex *_next; // another p-vertex associated with _vertex
    Entity *_parent; // parent entity: an edge or a p-edge
    Vertex *_vertex; // mother vertex
};

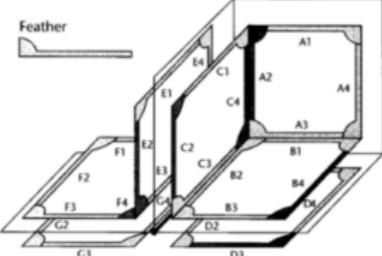
class Edge : public Entity { // parent entity: a p-edge or a p-face
    Pvertex *_pvertices[2]; // two end p-vertices
    Curve *_geometry; // curve
};

class Vertex : public Entity { // parent entity: a p-vertex or a p-face
    Entity *_parent; // parent entity: a p-vertex or a p-face
    Point *_geometry; // position
};

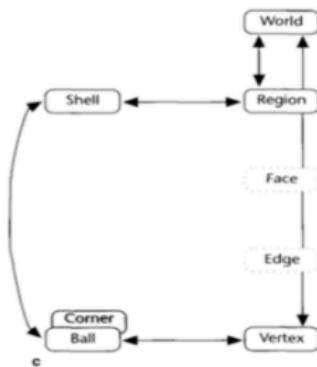
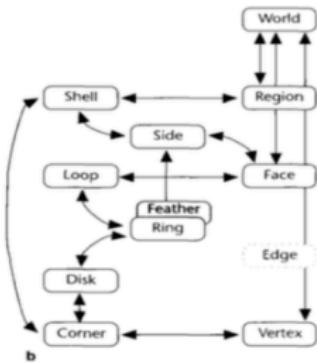
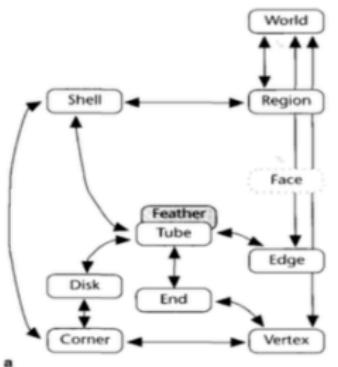
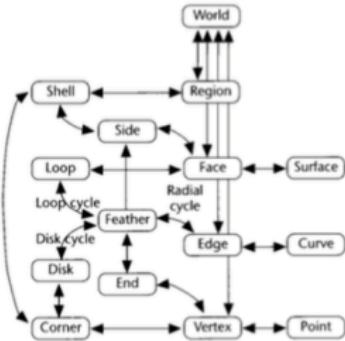
```

Representation scheme: Coupling Entities data structure

(Yamaguchi & Kimura, IEEE Computer Graphics and Applications, 1995)



Fan	$B_4 \& D_3$	$:D_3 = FM(B_4), B_4 = FM(D_3)$
Blade	$C_2 \& E_2$	$:E_2 = BM(C_2), C_2 = BM(E_2)$
Wedge	$A_2 \& C_4$	$:C_4 = WM(A_2), A_2 = WM(C_4)$
Loop cycle	$A_1 >> A_2 >> A_3 >> A_4$	$:A_2 = CCL(A_1), A_3 = CCL(A_2)$
	$A_4 >> A_3 >> A_2 >> A_1$	$:A_1 = CL(A_2), A_2 = CL(A_3)$
Radial cycle	$D_2 >> C_3 >> F_4$	$:C_3 = CCR(D_2), F_4 = CCR(C_3)$
	$F_4 >> C_3 >> D_2$	$:D_2 = CR(C_3), C_3 = CR(F_4)$
Disk cycle	$A_3 >> C_4 >> B_2$	$:C_4 = CCD(A_3), B_2 = CCD(C_4)$
	$B_2 >> C_4 >> A_3$	$:A_3 = CD(C_4), C_4 = CD(B_2)$



Linear Algebraic Representation (LAR)

LAR: Mathematical models

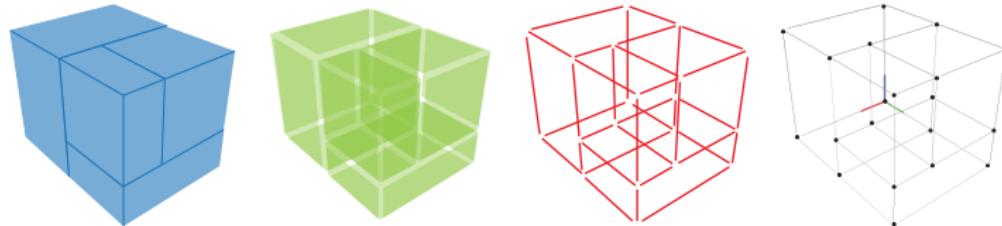
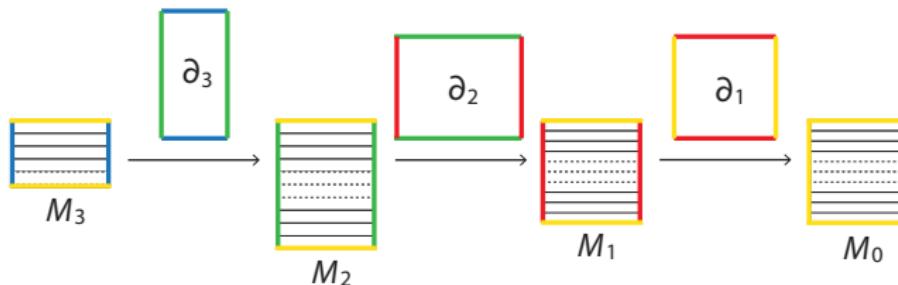
Space of CW-complexes (cellular complexes)

Chain complex (of chain spaces)

Sequence of linear spaces (over \mathbb{Z}_2) of d -cell subsets

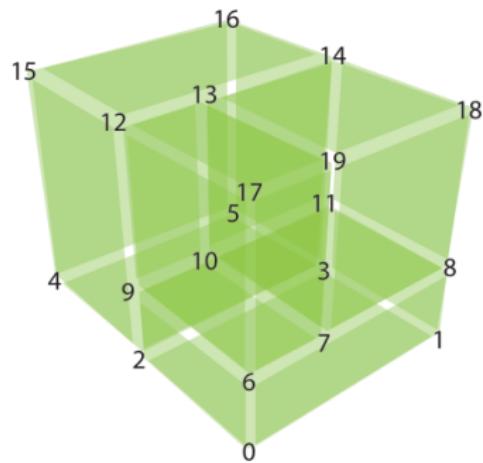
A **chain complex C** is a complex of **chain spaces** and **boundary maps**:

Unit d -chains (single d -cell subsets), give the **standard bases** (M_d rows) of d -chain spaces



Characteristic matrices of d -chain spaces

Matrix representation of the basis — d -cells as subsets of vertices



$$M_3 = \begin{pmatrix} 0 & 0 & 1 & 1 & 1 & 1 & 0 & 0 & 0 & 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 & 0 & 0 \\ 1 & 1 & 1 & 1 & 0 & 0 & 1 & 1 & 1 & 1 & 1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 1 & 0 & 1 & 1 & 0 & 1 & 1 & 0 & 0 & 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 & 0 & 1 & 1 & 0 & 1 & 1 & 0 & 0 & 0 & 1 & 1 \end{pmatrix}$$

$$M_2 = \begin{pmatrix} 1 & 1 & 1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 1 & 0 & 0 & 0 & 0 & 1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 & 1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 & 0 & 0 & 0 & 0 & 0 & 1 & 1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 & 1 & 1 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 & 0 & 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 & 0 & 0 & 0 & 1 \end{pmatrix}$$

LAR: computer representation

Sparse matrix representations

Basic representations

A few basic representation of topology are used in LARCC.

They include some common sparse matrix representations:

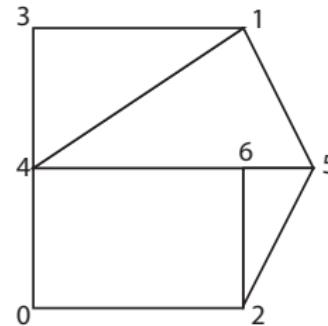
- CSR (Compressed Sparse Row),
- CSC (Compressed Sparse Column),
- COO (Coordinate Representation),
- and BRC (Binary Row Compressed)

Data definition

- We can identify each cell with its set of vertices.
- Thus, to define S , we start from the vertex set V , and specify the vertex subsets which correspond to the cells, and the rank of each cell.
- The partial order is induced by set inclusion.

Characteristic matrix $M_2 : C_0 \rightarrow C_2$

$$M_2 = \begin{pmatrix} 1 & 0 & 1 & 0 & 1 & 0 & 1 \\ 0 & 1 & 0 & 0 & 1 & 1 & 1 \\ 0 & 1 & 0 & 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 1 & 1 \end{pmatrix}$$



BRC (Binary Row Compressed) representation

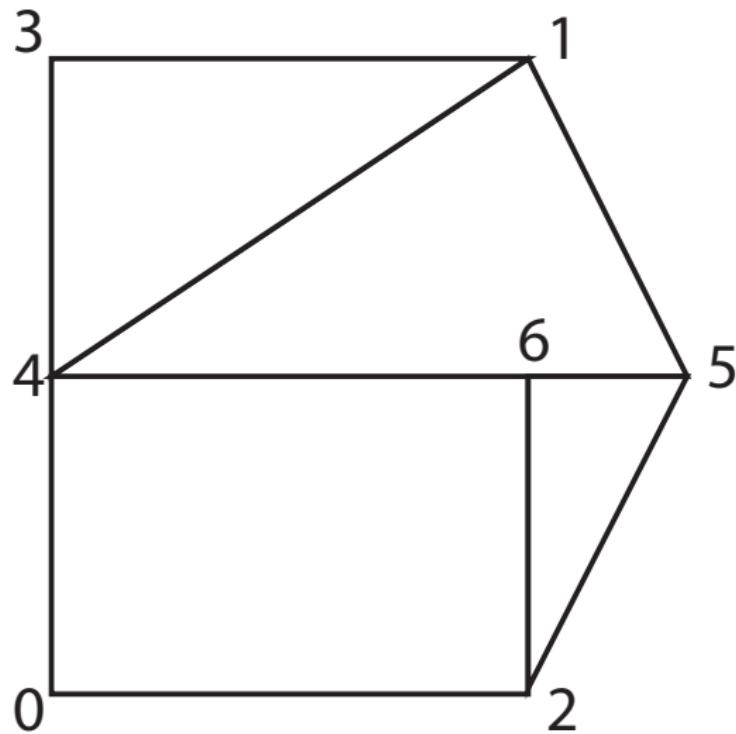
List of list of integer

typically used for input of cell complexes

Let $A = (a_{i,j} \in \{0, 1\})$ be a characteristic matrix.

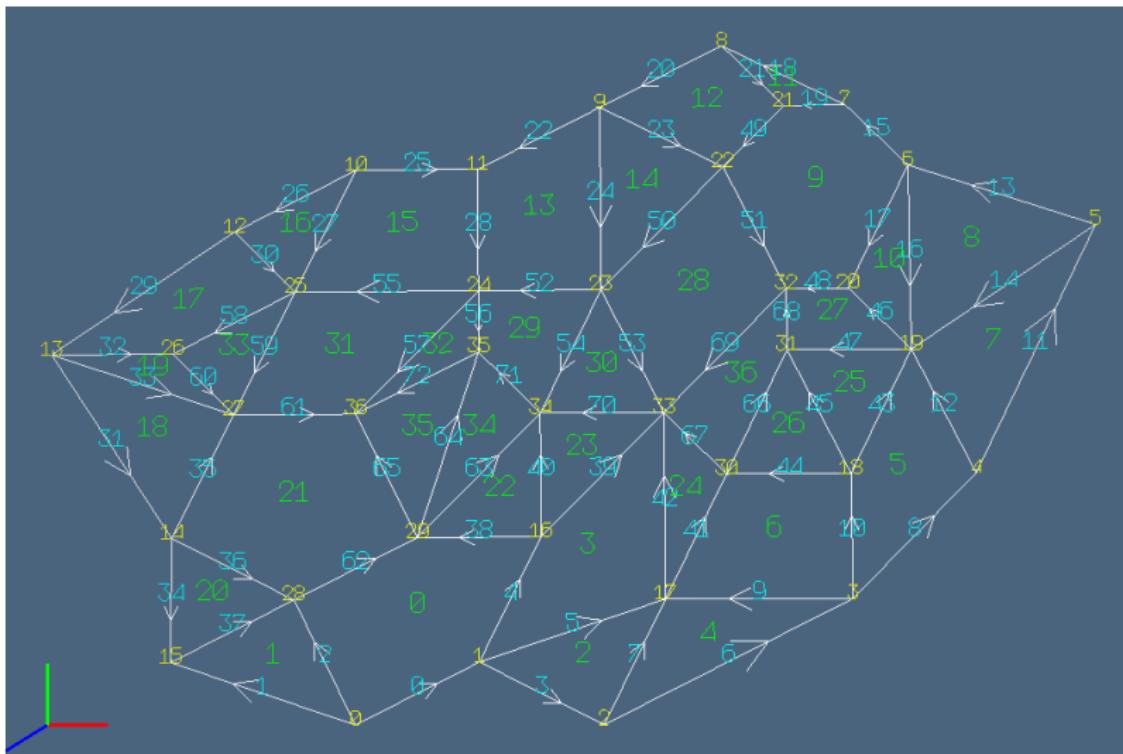
$$A = \left(\begin{array}{ccccccccc} 0, 1, 0, 0, 0, 0, 0, 1, 0, 0 \\ 0, 0, 1, 0, 0, 0, 0, 0, 0, 0 \\ 1, 0, 0, 1, 0, 0, 0, 0, 0, 1 \\ 1, 0, 0, 0, 0, 0, 1, 0, 0, 0 \\ 0, 0, 0, 0, 0, 1, 1, 1, 0, 0 \\ 0, 0, 1, 0, 1, 0, 0, 0, 1, 0 \\ 0, 0, 0, 0, 0, 0, 0, 0, 0, 0 \\ 0, 1, 0, 0, 0, 0, 0, 1, 0, 1 \\ 0, 0, 0, 1, 0, 0, 0, 0, 1, 0 \\ 0, 1, 1, 0, 1, 0, 0, 0, 0, 0 \end{array} \right) \mapsto \text{BRC}(A) = [[1, 7], [2], [0, 3, 9], [0, 6], [5, 6, 7], [2, 4, 8], [], [1, 7, 9], [3, 8], [1, 2, 4]]$$

The idea: generalisation of abstract simplicial sets



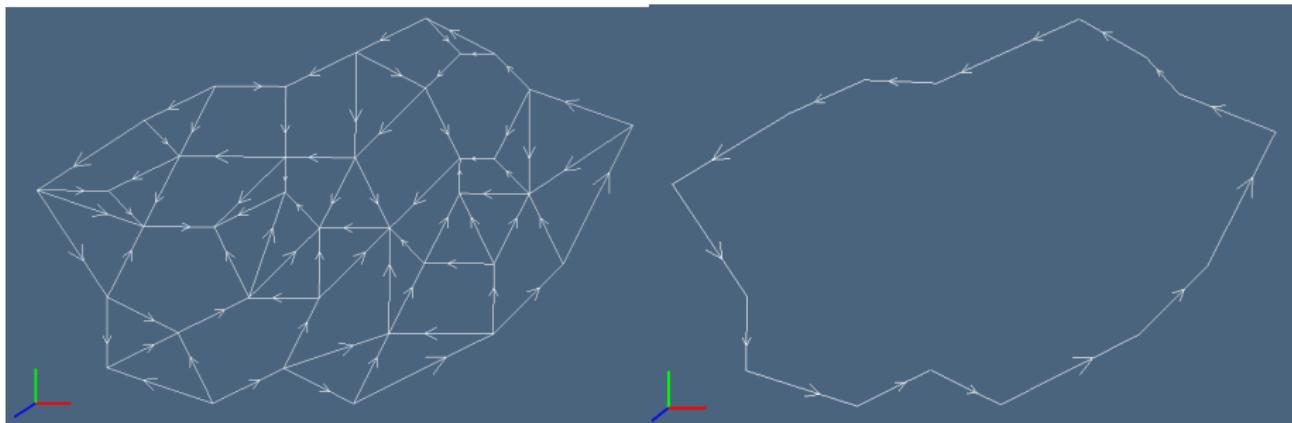
n -cells by
their vertices:

$[[0, 2, 4, 6],$
 $[1, 4, 5, 6],$
 $[1, 5, 6],$
 $[2, 5, 6]]$



The bare minimum data

with full awareness of topology



```
V = [[5,0],[7,1],[9,0],[13,2],[15,4],[17,8],[14,9],[13,10],[11,11],[9,10],[5,9],[7,9],[3,8],[0,6],[2,3],[2,1],[8,3],[10,2],[13,4],[14,6],[13,7],[12,10],[11,9],[9,7],[7,7],[4,7],[2,6],[3,5],[4,2],[6,3],[11,4],[12,6],[12,7],[10,5],[8,5],[7,6],[5,5]]
```

```
FV = [[0,1,16,28,29],[0,15,28],[1,2,17],[1,16,17,33],[2,3,17],[3,4,18,19],[3,17,18,30],[4,5,19],[5,6,19],[6,7,20,21,22,32],[6,19,20],[7,8,21],[8,9,21,22],[9,11,23,24],[9,22,23],[10,11,24,25],[10,12,25],[12,13,25,26],[13,14,27],[13,26,27],[14,15,28],[14,27,28,29,36],[16,29,34],[16,33,34],[17,30,33],[18,19,31],[18,30,31],[19,20,31,32],[22,23,32,33],[23,24,34,35],[23,33,34],[24,25,27,36],[24,35,36],[25,26,27],[29,34,35],[29,35,36],[30,31,32,33]]
```

Compressed Sparse Row (CSR) matrix storage

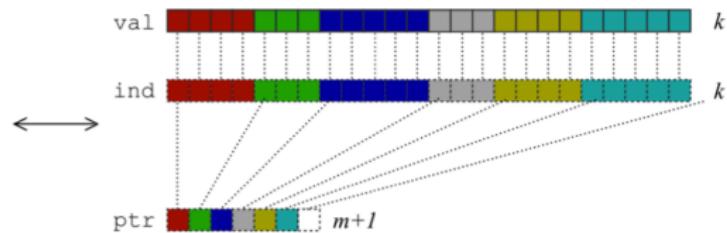
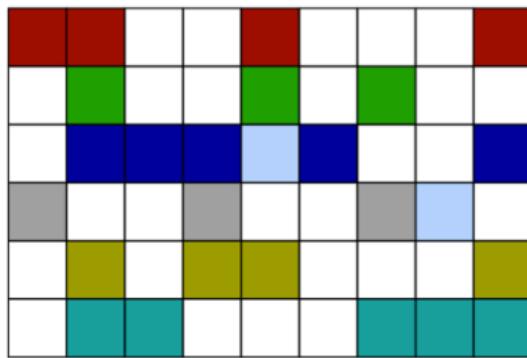
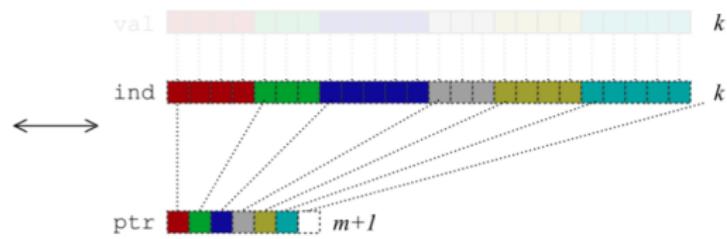
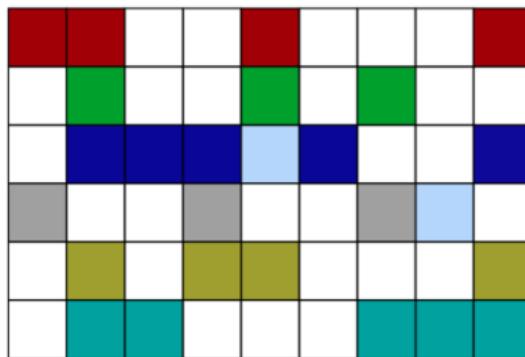


image from

Samuel Williams, Leonid Oliker, Richard Vuduc, John Shalf, Katherine Yelick, and James Demmel, [Optimization of sparse matrix-vector multiplication on emerging multicore platforms](#), Proceedings of the 2007 ACM/IEEE conference on Supercomputing (New York, NY, USA), SC '07, ACM, 2007, pp. 38:1–38:12.

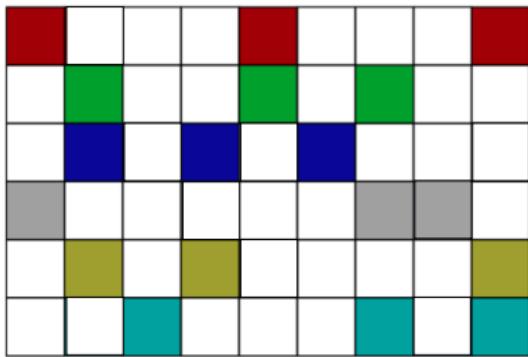
CSR storage of a **BINARY** matrix



of course, **non-zero values (all ones)** do not require storage

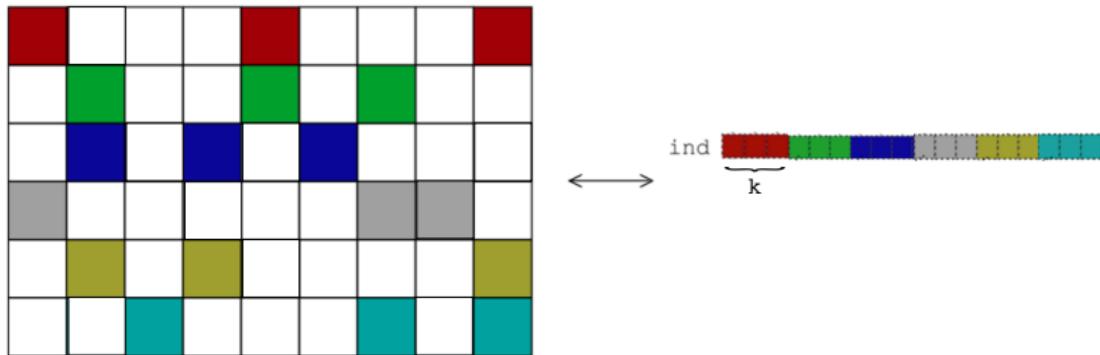
CSR storage of a binary matrix M_d such that

$$M_d \mathbf{1} = \mathbf{k}$$



CSR storage of a binary matrix M_d such that

$$M_d \mathbf{1} = \mathbf{k}$$



important cases:

- regular **simplicial** d -complexes: $k = d + 1$
- regular **cuboidal** d -complexes: $k = 2^d$

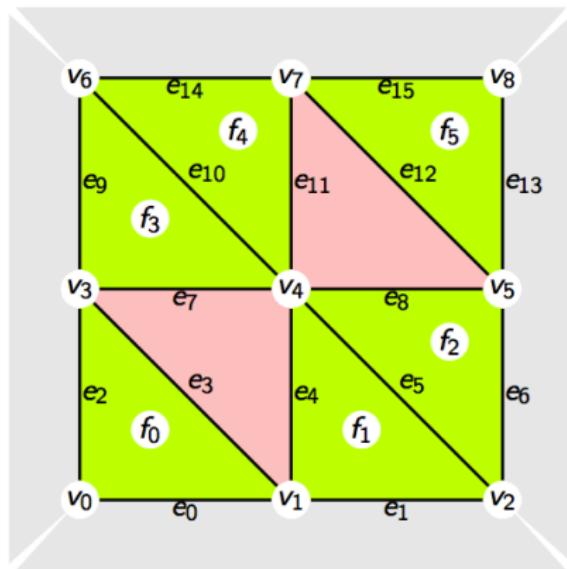
Operations

Facet extraction (1/5)

use the characteristic matrix M_d of a cellular partition Λ_d of \mathbb{E}^d , empty cells included

$$2D \Rightarrow d = 2$$

$$M_2 = \left(\begin{array}{ccccccc} 1 & 1 & 0 & 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 & 1 & 0 & 1 \\ 0 & 0 & 0 & 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 1 & 0 \\ 1 & 1 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 1 \\ 1 & 0 & 0 & 1 & 0 & 0 & 0 \end{array} \right)$$

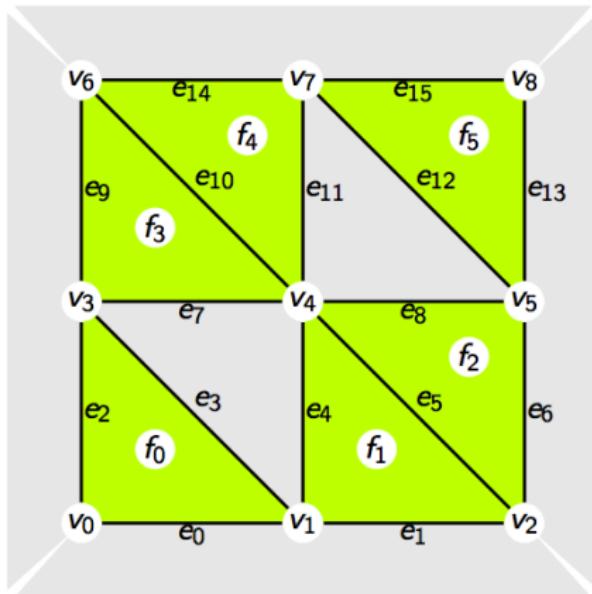


Facet extraction (2/5)

use the characteristic matrix M_d of a cellular partition Λ_d of \mathbb{E}^d , empty cells included

$$2D \Rightarrow d = 2$$

$$M_2 = \left(\begin{array}{ccccccc} 1 & 1 & 0 & 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 & 1 & 0 & 1 \\ 0 & 0 & 0 & 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 1 & 1 \\ 0 & 1 & 0 & 1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 1 & 0 \\ 1 & 1 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 1 \\ 1 & 0 & 0 & 1 & 0 & 0 & 0 \end{array} \right)$$



Facet extraction (3/5)

use the characteristic matrix M_d of a cellular partition Λ_d of \mathbb{E}^d , empty cells included

$$A = M_2 M_2^t = \left(\begin{array}{cccccccccc} 3 & 1 & 0 & 1 & 0 & 0 & 2 & 0 & 0 & 2 & 2 & 0 \\ 3 & & 2 & 1 & 1 & 0 & 2 & 1 & 0 & 0 & 2 & 1 \\ & 3 & 1 & 1 & 1 & 1 & 2 & 0 & 0 & 1 & 1 & 2 \\ & & 3 & 2 & 0 & 0 & 0 & 1 & 2 & 2 & 2 & 1 \\ & & & 3 & 1 & 0 & 0 & 2 & 1 & 1 & 2 & 2 \\ & & & & 3 & 0 & 2 & 2 & 0 & 0 & 2 & 1 \\ & & & & & 3 & 1 & 0 & 1 & 1 & 0 & 0 \\ & & & & & & 3 & 1 & 0 & 0 & 1 & 1 \\ & & & & & & & 3 & 1 & 0 & 0 & 1 \\ & & & & & & & & 3 & 1 & 0 \\ & & & & & & & & & 3 & 1 \\ & & & & & & & & & & 3 \end{array} \right)$$

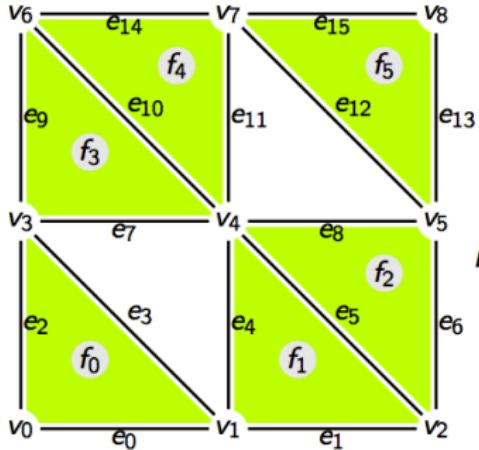
sym

$$\#(\lambda_d^i \cap \lambda_d^j) = A(i,j) \geq d \quad (i \neq j) \Rightarrow \exists \lambda_{d-1} = M_d(i) \wedge M_d(j)$$

Facet extraction (4/5)

use the characteristic matrix M_d of a cellular partition Λ_d of \mathbb{E}^d , empty cells included

$$A(0, 6) = 2 \Rightarrow (\text{110100000}) \wedge (\text{010110000}) = (\text{010100000}) \Rightarrow e = (v_1, v_3)$$

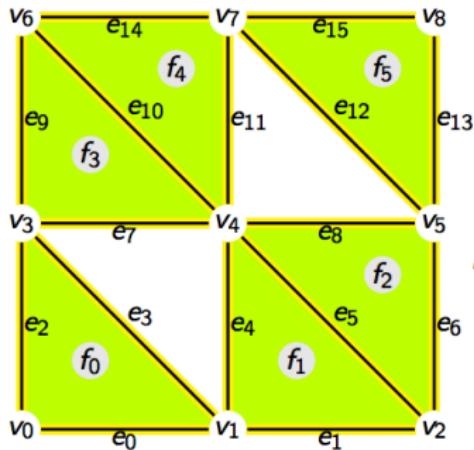


$$M_2 = \left(\begin{array}{c} \text{110100000} \\ \text{011010000} \\ \text{001011100} \\ \text{000110100} \\ \text{000010110} \\ \text{000001011} \\ \text{010110000} \\ \text{000011010} \\ \text{111000000} \\ \text{001001001} \\ \text{000000111} \\ \text{100100100} \end{array} \right) \Rightarrow M_1 = \left(\begin{array}{c} \text{110000000} \\ \text{100100000} \\ \text{011000000} \\ \text{010100000} \\ \text{010010000} \\ \text{001010000} \\ \text{001001000} \\ \text{000110000} \\ \text{000100100} \\ \text{000011000} \\ \text{000010100} \\ \text{000010010} \\ \text{000001010} \\ \text{000001001} \\ \text{000000110} \\ \text{000000011} \end{array} \right)$$

Facet extraction (5/5)

use the characteristic matrix M_d of a cellular partition Λ_d of \mathbb{E}^d , empty cells included

$$A(0, 6) = 2 \Rightarrow (\textcolor{blue}{110100000}) \wedge (\textcolor{gray}{010110000}) = (\textcolor{yellow}{010100000}) \Rightarrow e = (v_1, v_3)$$



$$M_2 = \left(\begin{array}{cccccc} 1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \end{array} \right) \Rightarrow M_1 = \left(\begin{array}{cccccc} 1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \end{array} \right)$$

Simplicial extrusion (1/3)

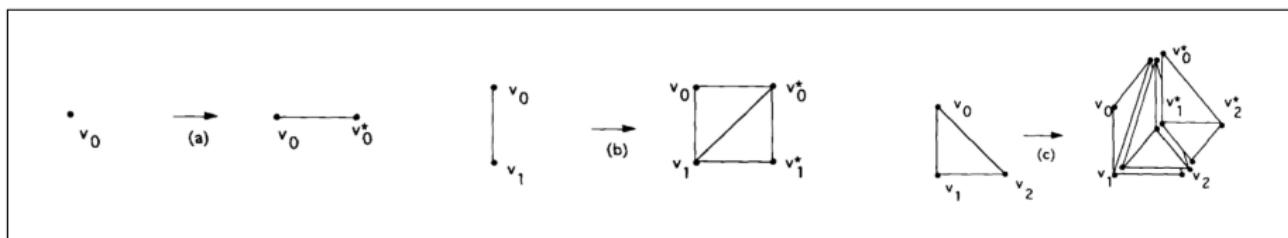
Optimal combinatorial algorithm

[Ferrucci & Paoluzzi, CAD, 1991]

for each d-simplex

$$\sigma^d = (v_0, v_1, \dots, v_d)$$

in the input complex $S(d)$, we generate combinatorially a chain of $d + 1$ **coherently-oriented** simplexes of dimension $d + 1$:



So we have, with $|\gamma^{d+1}| = \sigma^d \times I$, and $I = [0, 1]$:

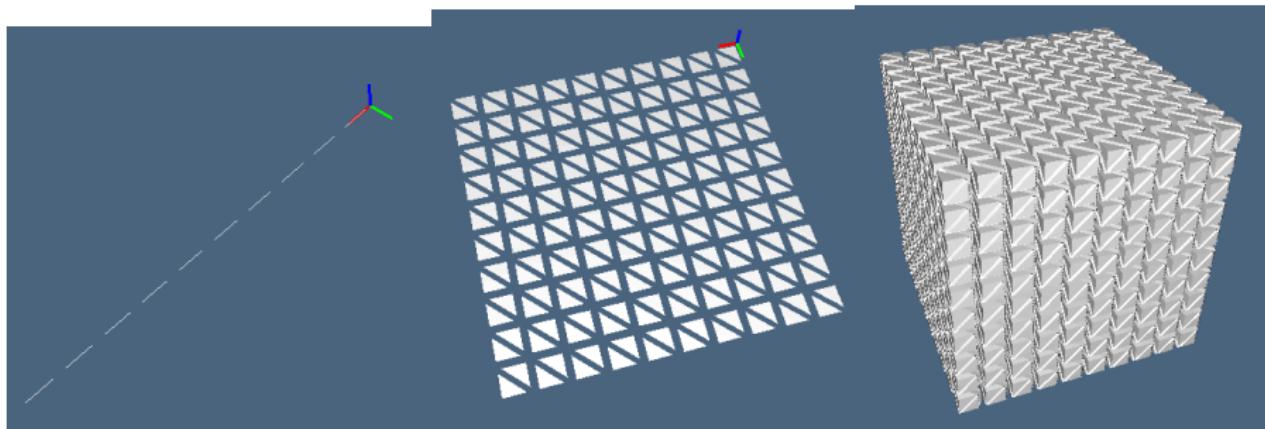
$$\gamma^{d+1} = \sum_{k=0}^d (-1)^{kd} \langle v_k, \dots, v_d, v_0^*, \dots, v_k^* \rangle$$

with $v_k \in \sigma^d \times \{0\}$ and $v_k^* \in \sigma^d \times \{1\}$,

Simplicial extrusion (2/3)

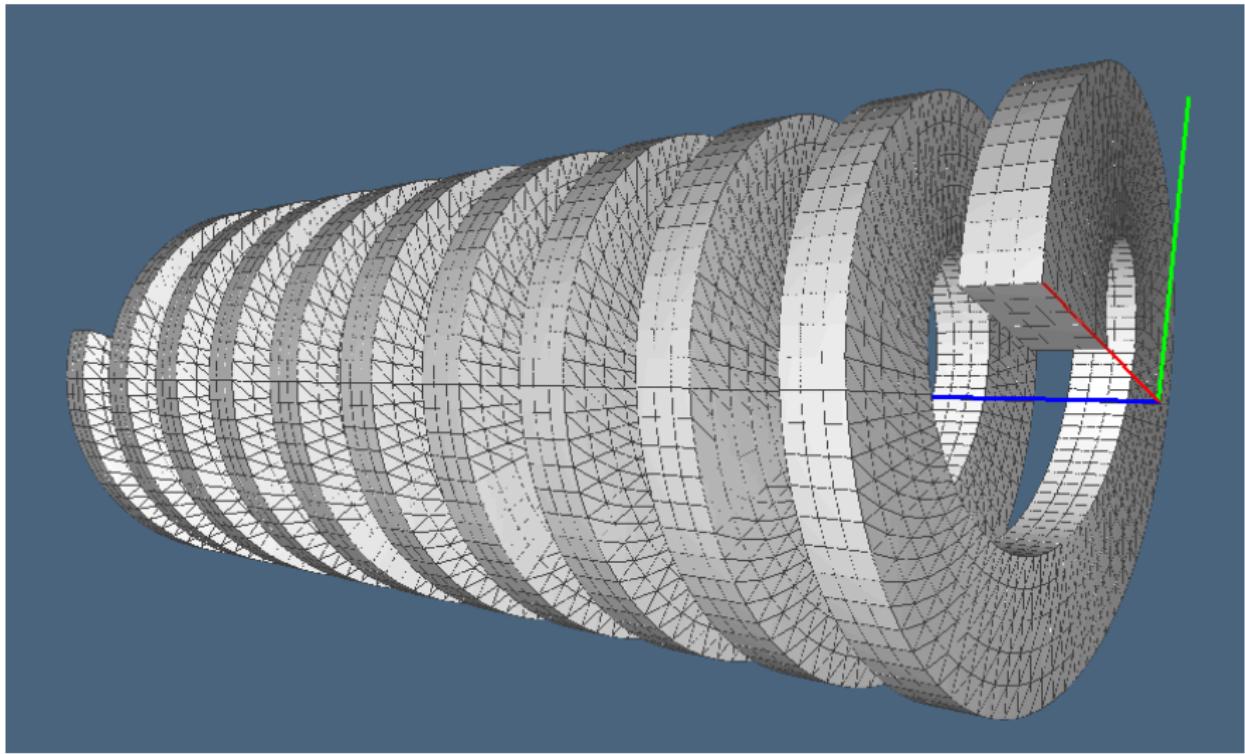
Let \mathfrak{S} be the set of simplicial c.c.c., and $S_d, S_1 \in \mathfrak{S}$:

$$S_d \times S_1 =: S_{d+1} \in \mathfrak{S}$$



```
model1 = larExtrude( VOID, 10*[1] )
model2 = larExtrude( model1, 10*[1] )
model3 = larExtrude( model2, 10*[1] )
```

Simplicial extrusion (3/3)



Cartesian product of complexes (1/4)

Let \mathfrak{C} be the set of c.c.c's. $X, Y \in \mathfrak{C} \Rightarrow X \times Y \in \mathfrak{C}$ [Basak, Geom. dedicata, 2010]

Let

$$X = S(m) \in \mathfrak{S}, \quad \text{and} \quad Y = S(n) \in \mathfrak{S};$$

Then

$$X \times Y = S(X \times Y) \in \mathfrak{S}$$

with

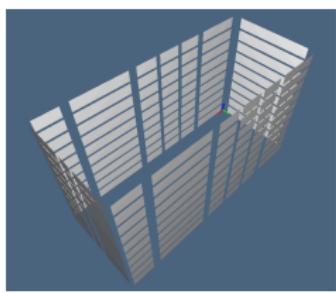
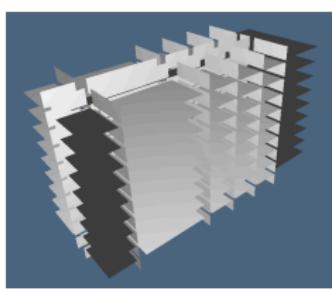
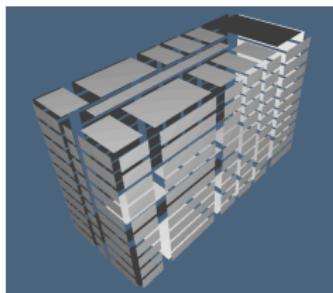
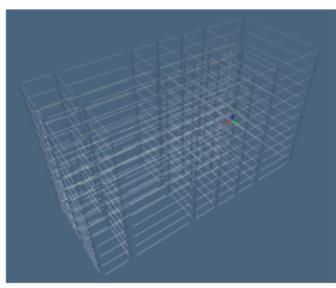
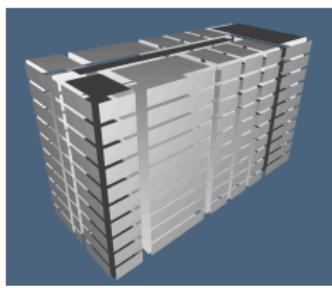
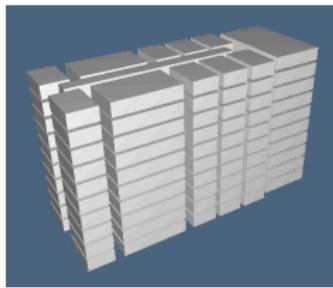
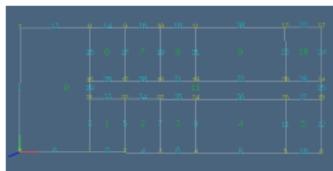
$$x \times y = (x_1y_1, \dots, x_1y_n, \dots, x_my_1, \dots, x_my_n) \in S(m+n).$$

Cartesian product of complexes (2/4)

Implementation

```
def larModelProduct(twoModels):
    (V, cells1), (W, cells2) = twoModels
    vertices = collections.OrderedDict(); k = 0
    for v in V:
        for w in W:
            id = tuple(v+w)
            if not vertices.has_key(id):
                vertices[id] = k
                k += 1
    cells = [ [vertices[tuple(V[v] + W[w])] for v in c1 for w in c2 ]
              for c1 in cells1 for c2 in cells2]
    model = [list(v) for v in vertices.keys()], cells
    return model
```

Cartesian product of complexes (4/4)



Larlib Examples ()

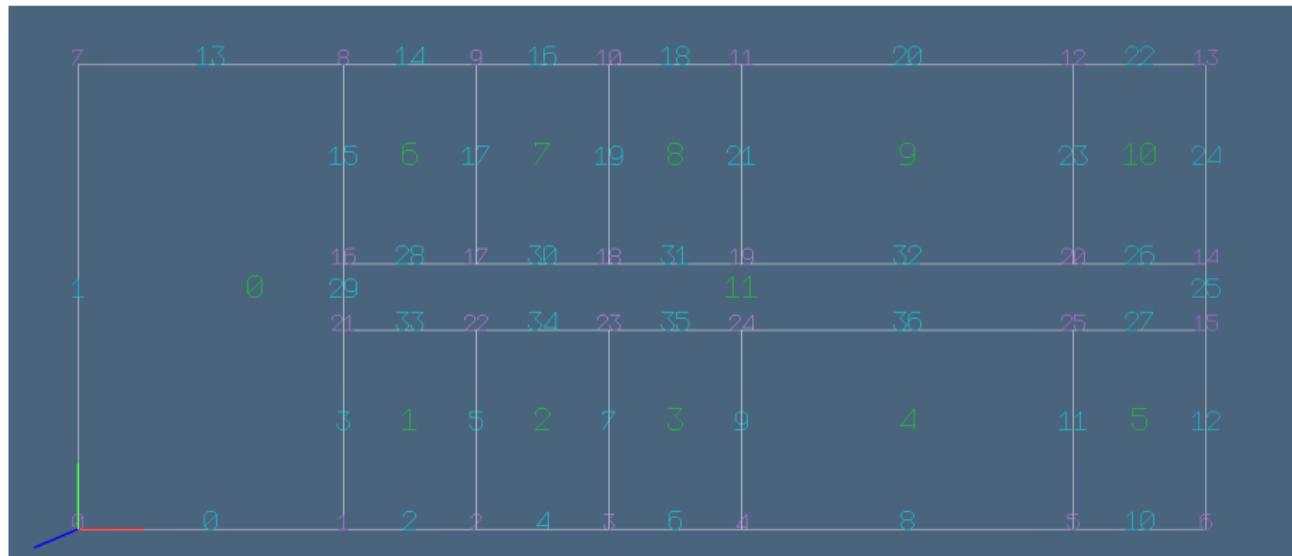
```
from larlib import *

V = [[0,0],[4,0],[6,0],[8,0],[10,0],[15,0],[17,0],[0,7],[4,7],[6,7],[8,7],[15,7],[17,7],[17,4],[17,3],[4,4],[6,4],[8,4],[10,4],[15,4],[4,3],[6,3],[8,10],[10,3],[15,3]]

FV = [[0,1,7,8,16,21],[1,2,21,22],[2,3,22,23],[3,4,23,24],[4,5,24,25],[5,6,25,26],[6,7,27,28],[7,8,29,30],[8,9,16,17],[9,10,17,18],[10,11,18,19],[11,12,19,20],[12,13,14,20],range(14),range(7),range(7,14),[0,7],[6,13,14,15]]
```

Larlib Examples (1/8)

```
submodel = SKEL_1(STRUCT(MKPOLS((V,FV))))  
V, EV = larFacets((V,FV),2,4)  
VV = AA(LIST)(range(len(V)))  
VIEW(larModelNumbering(1,1,1)(V,[VV,EV,FV[:-4]],submodel,3))
```



Larlib Examples (2/8)

```
VIEW(EXPLODE(1.2,1.2,1.2)(MKPOLS((V,FV[:-4]))+MKPOLS((V,EV))+AA(MK)(V)))
```

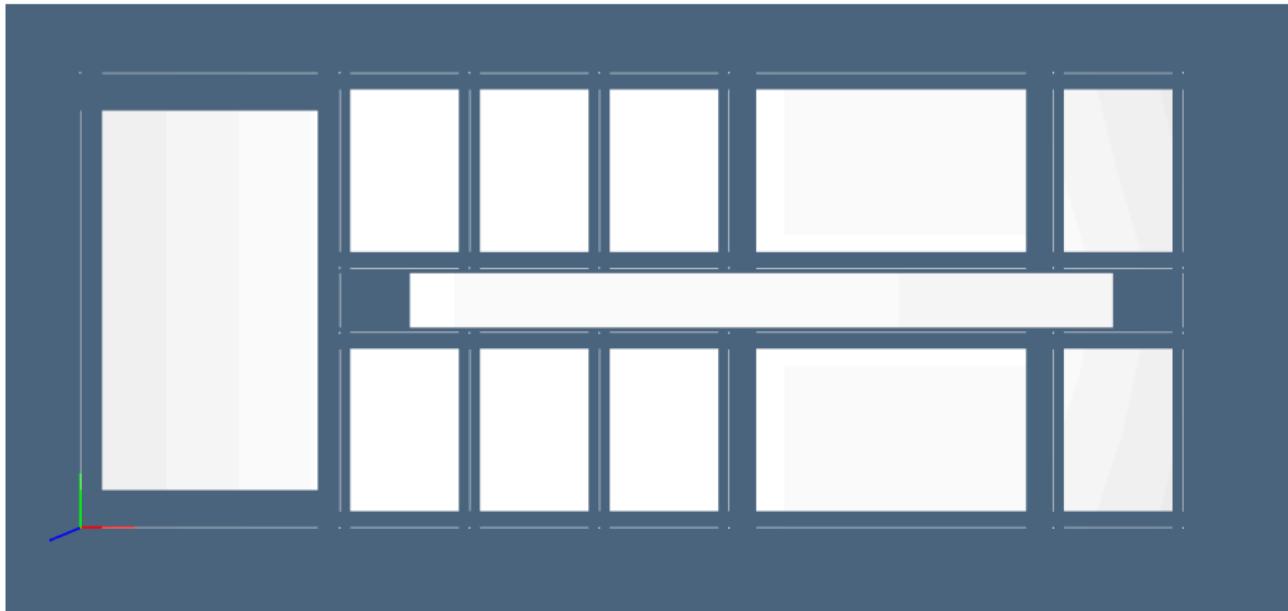


Figure 2:

Larlib Examples (3/8)

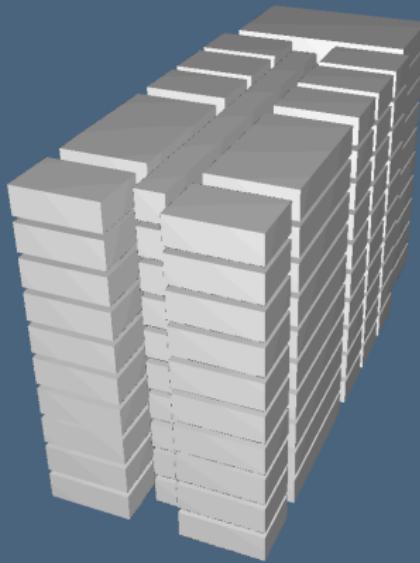
```
BE = boundaryCells(FV[:-4],EV)
VIEW(EXPLODE(1.2,1.2,1)(MKPOL((V,[EV[e] for e in BE]))))
```



Figure 3:

Larlib Examples (4/8)

```
C1 = larCuboids([10])
V3,CV = larModelProduct([(V,FV[:-4]),C1])
VIEW(EXPLODE(1.2,1.2,1.2)(MKPOLS((V3,CV))))
```



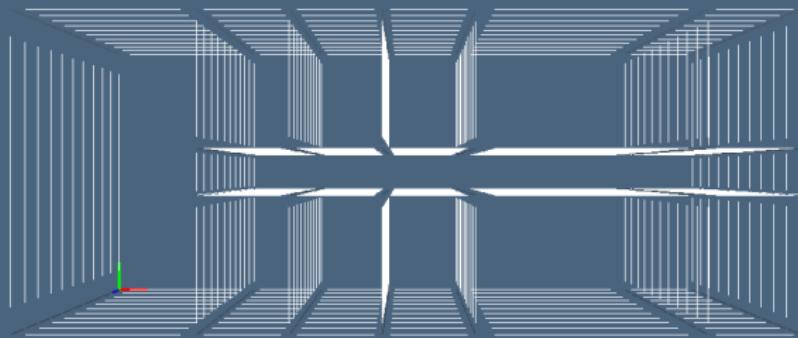
Larlib Examples (5/8)

```
full3D = CV + exteriorCells((V3,CV))
V3,FV3 = larFacets((V3,full3D),3,6)
VIEW(EXPLODE(1.2,1.2,1.2)(MKPOLS((V3,FV3))))
```



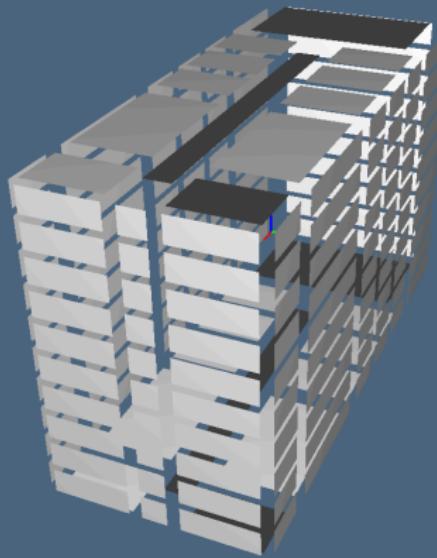
Larlib Examples (6/8)

```
V3,EV3 = larFacets((V3,FV3),2)
VIEW(EXPLODE(1.2,1.2,1.2)(MKPOLS((V3,EV3))))
```



Larlib Examples (7/8)

```
VV3 = AA(LIST)(range(len(V3)))
boundary3D = boundaryCells(CV,FV3)
VIEW(EXPLODE(1.25,1.25,1.25)(MKPOL((V3,[FV3[f] for f in boundary3D]))))
```



Larlib Examples (8/8)

```
V3,F3 = larFacets((V3,CV))
VIEW(EXplode(1.2,1.2,1.2)(MKPOLS((V3,F3))))
```

