# Geometric and Graphics Programming Laboratory: Lecture 10

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# Outline: LAR2 (Dicarlo, Paoluzzi, and Shapiro 2014)

- LAR-CC library
- 2 LAR representation
- Facet extraction
- Boundary computation
- Extrusion
- 6 Cartesian product of complexes
- Skeletons
- References

# LAR-CC library

#### download from github

\$ git clone https@github.com:cvdlab/lar-cc.git

# download from github

```
$ git clone https@github.com:cvdlab/lar-cc.git
In your python files:
""" import modules from larlib """
from larlib import *
```

# LAR representation

# Input of a simplicial complex (brc2csr)

From BRC (Binary Row Compressed) to CSR (Compressed Sparse Row)

• LAR model: (V,FV,EV)

```
V = [[0, 0], [1, 0], [2, 0], [0, 1], [1, 1], [2, 1]]
FV = [[0, 1, 3], [1, 2, 4], [1, 3, 4], [2, 4, 5]]
EV = [[0,1],[0,3],[1,2],[1,3],[1,4],[2,4],[2,5],[3,4],[4,5]]

VIEW(STRUCT(MKPOLS((V,FV)))); VIEW(EXPLODE(1.2,1.2,1)(MKPOLS((V,FV))))
VIEW(STRUCT(MKPOLS((V,EV)))); VIEW(EXPLODE(1.2,1.2,1)(MKPOLS((V,EV))))
```

```
csrFV = csrCreate(FV)
csrEV = csrCreate(EV)

print "\ncsrCreate(FV) =\n", csrFV
print "\n>>> csr2DenseMatrix"
print "\nFV =\n", csr2DenseMatrix(csrFV)
print "\nEV =\n", csr2DenseMatrix(csrEV)
```

# Input of a simplicial complex (brc2csr)

From BRC (Binary Row Compressed) to CSR (Compressed Sparse Row)

LAR model: (V,FV,EV)

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FV = [[0, 1, 3], [1, 2, 4], [1, 3, 4], [2, 4, 5]]
EV = [[0,1],[0,3],[1,2],[1,3],[1,4],[2,4],[2,5],[3,4],[4,5]]
VIEW(STRUCT(MKPOLS((V,FV)))); VIEW(EXPLODE(1.2,1.2,1)(MKPOLS((V,FV))))
VIEW(STRUCT(MKPOLS((V,EV)))); VIEW(EXPLODE(1.2,1.2,1)(MKPOLS((V,EV))))
```

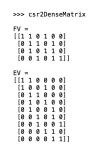
Lar representation: (CSR matrix)

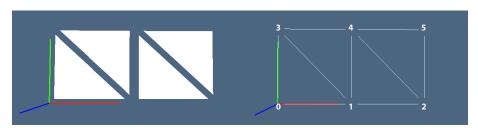
```
csrFV = csrCreate(FV)
csrEV = csrCreate(EV)

print "\ncsrCreate(FV) =\n", csrFV
print "\n>>> csr2DenseMatrix"
print "\nFV =\n", csr2DenseMatrix(csrFV)
print "\nEV =\n", csr2DenseMatrix(csrEV)
```

# Input of a simplicial complex (brc2csr)

csrCreate(FV)	=
(0, 0)	1
(0, 1)	1
(0, 3)	1
(1, 1)	1
(1, 2)	1
(1, 4)	1
(2, 1)	1
(2, 3)	1
(2, 4)	1
(3, 2)	1
(3, 4)	1
(3, 5)	1





Facet extraction

combinatorial approach

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- A (d-1)-face of a d-simplex

$$\sigma^d = \langle v_0, v_1, \dots, v_d \rangle$$

is also called a facet.

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• Each of the d+1 facets of  $\sigma^d$ , obtained by removing a vertex from  $\sigma^d$ , is a (d-1)-simplex.

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- A simplex may be oriented in two different ways according to the permutation class of its vertices.

#### combinatorial approach

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is also called a facet.

- Each of the d+1 facets of  $\sigma^d$ , obtained by removing a vertex from  $\sigma^d$ , is a (d-1)-simplex.
- A simplex may be oriented in two different ways according to the permutation class of its vertices.
- The simplex orientation is so changed by either multiplying the simplex by -1, or by executing an odd number of exchanges of its vertices.

combinatorial approach

The chain of oriented boundary facets of  $\sigma^d$ , usually denoted as  $\partial \sigma^d$ , is generated combinatorially as follows:

$$\partial \sigma^d = \sum_{k=0}^d (-1)^d \langle v_0, \dots, v_{k-1}, v_{k+1}, \dots, v_d \rangle$$

#### Implementation

# Test of implementation

```
>>>larSimplexFacets([[0]])
[[]]
>>>larSimplexFacets([[0,1]])
[[0],[1]]
>>>larSimplexFacets([[0,1,2]])
[[0,1],[0,2],[1,2]]
>>>larSimplexFacets([[0,1,2,3]])
[[0,1,2],[0,1,3],[0,2,3],[1,2,3]]
>>>larSimplexFacets([[0,1,2,3,4]])
[[0,1,2,3],[0,1,2,4],[0,1,3,4],[0,2,3,4],[1,2,3,4]]
```

# Test of implementation

```
>>>larSimplexFacets([[0]])
[[]]
>>>larSimplexFacets([[0,1]])
[[0],[1]]
>>>larSimplexFacets([[0,1,2]])
[[0,1],[0,2],[1,2]]
>>>larSimplexFacets([[0,1,2,3]])
[[0,1,2],[0,1,3],[0,2,3],[1,2,3]]
>>>larSimplexFacets([[0,1,2,3,4]])
[[0,1,2,3],[0,1,2,4],[0,1,3,4],[0,2,3,4],[1,2,3,4]]
```

Are such facets oriented?

# Examples of facet extraction from 3D simplicial cube

```
V,CV = larSimplexGrid1([1,1,1])
VIEW(EXPLODE(1.5,1.5,1.5)(MKPOLS((V,CV))))
SK2 = (V,larSimplexFacets(CV))
VIEW(EXPLODE(1.5,1.5,1.5)(MKPOLS(SK2)))
SK1 = (V,larSimplexFacets(SK2[1]))
VIEW(EXPLODE(1.5,1.5,1.5)(MKPOLS(SK1)))
look also at
V,CV = larSimplexGrid1([5,5,2])
```

### Assignment

Change the larSimplexFacets so that the extracted facets are coherently oriented

# Boundary computation

# From cells and facets to boundary operator

```
def boundary(cells,facets):
    csrCV = csrCreate(cells)
    csrFV = csrCreate(facets)
    csrFC = matrixProduct(csrFV, csrTranspose(csrCV))
    facetLengths = [csrCell.getnnz() for csrCell in csrCV]
    return csrBoundaryFilter(csrFC,facetLengths)

def coboundary(cells,facets):
    Boundary = boundary(cells,facets)
    return csrTranspose(Boundary)
```

# Oriented boundary example

```
V,CV = larSimplexGrid1([4,4,4])
VIEW(EXPLODE(1.5,1.5,1.5)(MKPOLS((V,CV))))
FV = larSimplexFacets(CV)
EV = larSimplexFacets(FV)
VIEW(EXPLODE(1.5,1.5,1.5)(MKPOLS((V,FV))))
csrSignedBoundaryMat = signedBoundary (V,CV,FV)
boundaryCells_2 = signedBoundaryCells(V,CV,FV)
def swap(1): return [1[1],1[0],1[2]]
boundaryFV = [FV[-k] if k<0 else swap(FV[k]) for k in boundaryCells_2]
boundary = (V,boundaryFV)
VIEW(EXPLODE(1.5,1.5,1.5)(MKPOLS(boundary)))
```

# Oriented boundary example

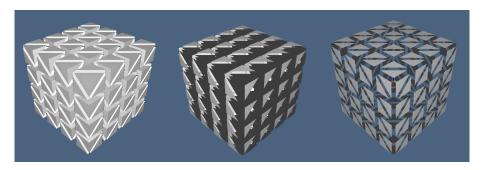


Figure 1: Simplicial complexes: (a) 3-complex  $S_3$ ; (b) 2-complex  $S_2 = K_2(S_3)$ ; (c) 2-complex  $T_2 = \partial S_3 \subset S_2$ )

#### Extrusion

### Simplicial extrusion

#### Computation

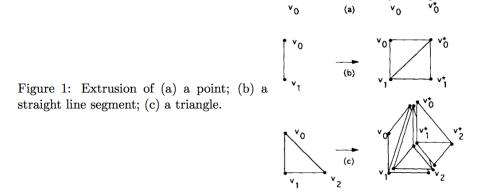


Figure 2: example caption

#### Simplicial extrusion

#### Computation

Let us concentrate on the generation of the simplex chain  $\gamma^{d+1}$  of dimension d+1 produced by combinatorial extrusion of a single simplex

$$\sigma^d = \langle v_0, v_1, \dots, v_d, \rangle.$$

Then we have, with  $|\gamma^{d+1}| = \sigma^d \times I$ , and I = [0,1]:

$$\gamma^{d+1} = \sum_{k=0}^{d} (-1)^{kd} \langle v_k, \dots v_d, v_0^*, \dots v_k^* \rangle$$

with  $v_k \in \sigma^d \times \{0\}$  and  $v_k^* \in \sigma^d \times \{1\}$ , and where the term  $(-1)^{kd}$  is used to generate a chain of coherently-oriented extruded simplices.

# Example of simplicial complex extrusion

```
V = [[0,0],[1,0],[2,0],[0,1],[1,1],[2,1],[0,2],[1,2],[2,2]]
FV = [[0,1,3],[1,2,4],[2,4,5],[3,4,6],[4,6,7],[5,7,8]]
model = larExtrude1((V,FV),4*[1,2,-3])
VIEW(EXPLODE(1,1,1.2)(MKPOLS(model)))
```

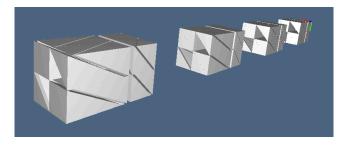


Figure 3: A simplicial complex providing a quite complex 3D assembly of tetrahedra.

### Multidimensional simplicial grids

The generation of simplicial grids of any dimension and shape is amazingly simple

The input parameter shape is either a tuple or a list of integers used to specify the shape of the created array

```
VOID = V0,CV0 = [[]],[[0]] # the empty simplicial model

def larSimplexGrid1(shape):
    model = V0ID
    for item in shape:
        model = larExtrude1(model,item*[1])
    return model
```

The returned model has integer vertices, to be scaled and/or translated and/or mapped

# Cartesian product of complexes

### Cartesian product of two LAR models

# Cartesian product of two LAR models

```
def larModelProduct(twoModels):
    (V. cells1). (W. cells2) = twoModels
   @< Cartesian product of vertices @>
   @< Topological product of cells</pre>
   model = [list(v) for v in vertices.keys()], cells
   return model
Cartesian product of vertices
vertices = collections.OrderedDict(): k = 0
for v in V:
   for w in W:
        id = tuple(v+w)
        if not vertices.has_key(id):
            vertices[id] = k
```

# Cartesian product of two LAR models

```
def larModelProduct(twoModels):
    (V. cells1). (W. cells2) = twoModels
   @< Cartesian product of vertices @>
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vertices = collections.OrderedDict(): k = 0
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```

#### Topological product of cells

#### Cuboidal grids

VIEW(EXPLODE(1.5,1.5,1.5) (MKPOLS(larCuboids([3,2,1]))))



Figure 4: Exploded views of 0-, 1-, 2-, and 3-dimensional skeletons.

#### Cuboidal grids

VIEW(EXPLODE(1.5,1.5,1.5) (MKPOLS(larCuboids([3,2,1]))))

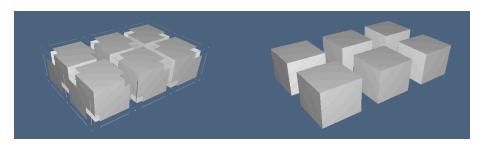


Figure 5: Exploded views of 0-, 1-, 2-, and 3-dimensional skeletons.

#### **Skeletons**

#### Cuboidal skeletons

A list of BRC characteristic matrices of cellular k-complexes ( $0 \le k \le d$ ) with dimension d, where d = len(shape), is returned by the function gridSkeletons in the macro below, where the input is given by the shape of the grid, i.e. by the list of cell items in each coordinate direction.

```
def gridSkeletons(shape):
    gridMap = larGridSkeleton(shape)
    skeletonIds = range(len(shape)+1)
    skeletons = [ gridMap(id) for id in skeletonIds ]
    return skeletons
```

#### Cuboidal skeletons

Just notice that the number of returned d-cells is equal to PROD(shape)

```
print "\ngridSkeletons([3]) =\n", gridSkeletons([3])
print "\ngridSkeletons([3,2]) =\n", gridSkeletons([3,2])
print "\ngridSkeletons([3,2,1]) =\n", gridSkeletons([3,2,1])
```

# Generation of grid boundary complex

```
def gridBoundaryMatrices(shape):
    skeletons = gridSkeletons(shape)
    boundaryMatrices = [boundary(skeletons[k+1],faces)
                         for k,faces in enumerate(skeletons[:-
    return boundaryMatrices
for k in range(1):
    print "\ngridBoundaryMatrices([3]) =\n", \
            csr2DenseMatrix(gridBoundaryMatrices([3])[k])
for k in range(2):
    print "\ngridBoundaryMatrices([3,2]) =\n", \
            csr2DenseMatrix(gridBoundaryMatrices([3,2])[k])
for k in range(3):
    print "\ngridBoundaryMatrices([3,2,1]) =\n", \
            csr2DenseMatrix(gridBoundaryMatrices([3,2,1])[k])
```

#### References

#### References

Dicarlo, Antonio, Alberto Paoluzzi, and Vadim Shapiro. 2014. "Linear Algebraic Representation for Topological Structures." Comput. Aided Des. 46 (January). Newton, MA, USA: Butterworth-Heinemann: 269–74. doi:10.1016/j.cad.2013.08.044.